

4

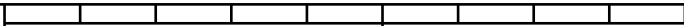
3

2

1

H

G



B

A

4

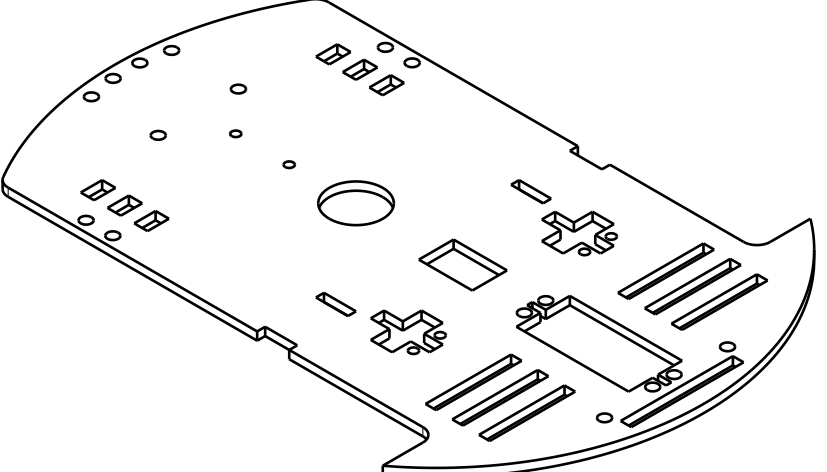
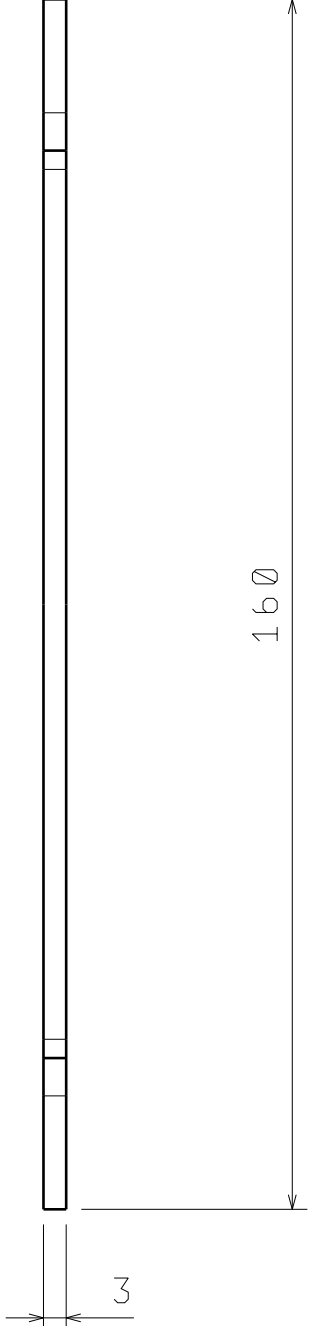
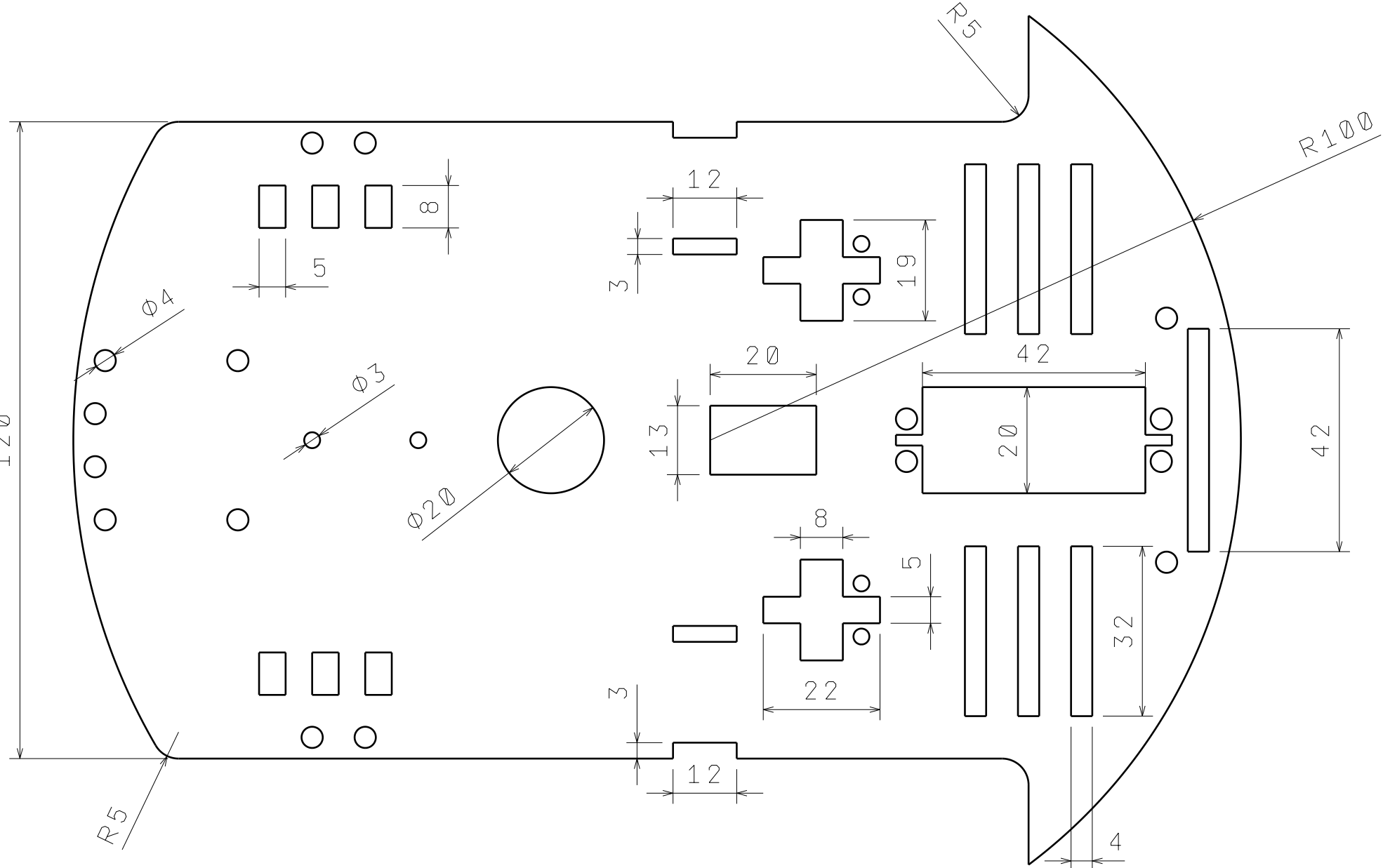
3

2

1

B

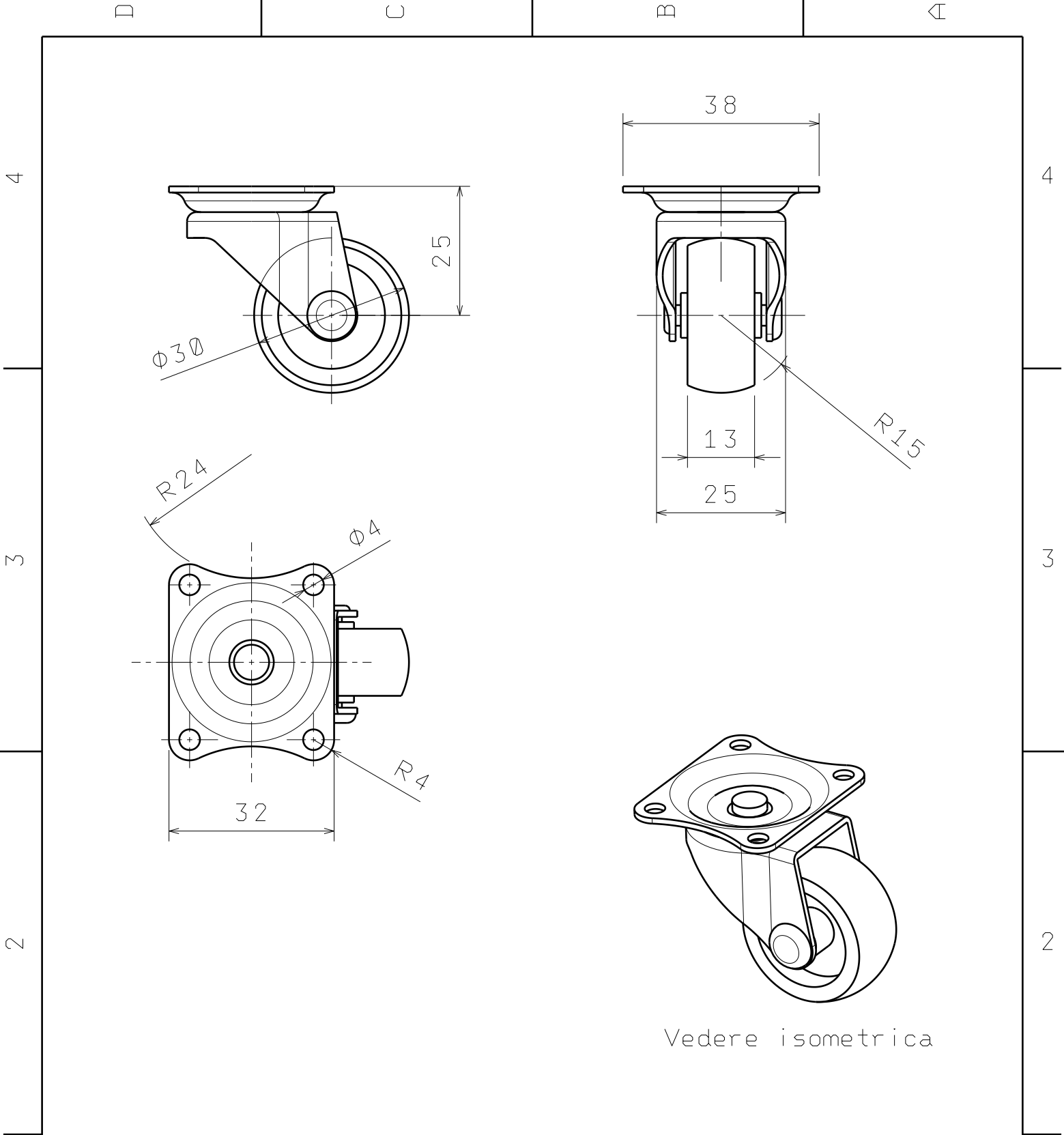
A



vedere isometrica
scara 1:2

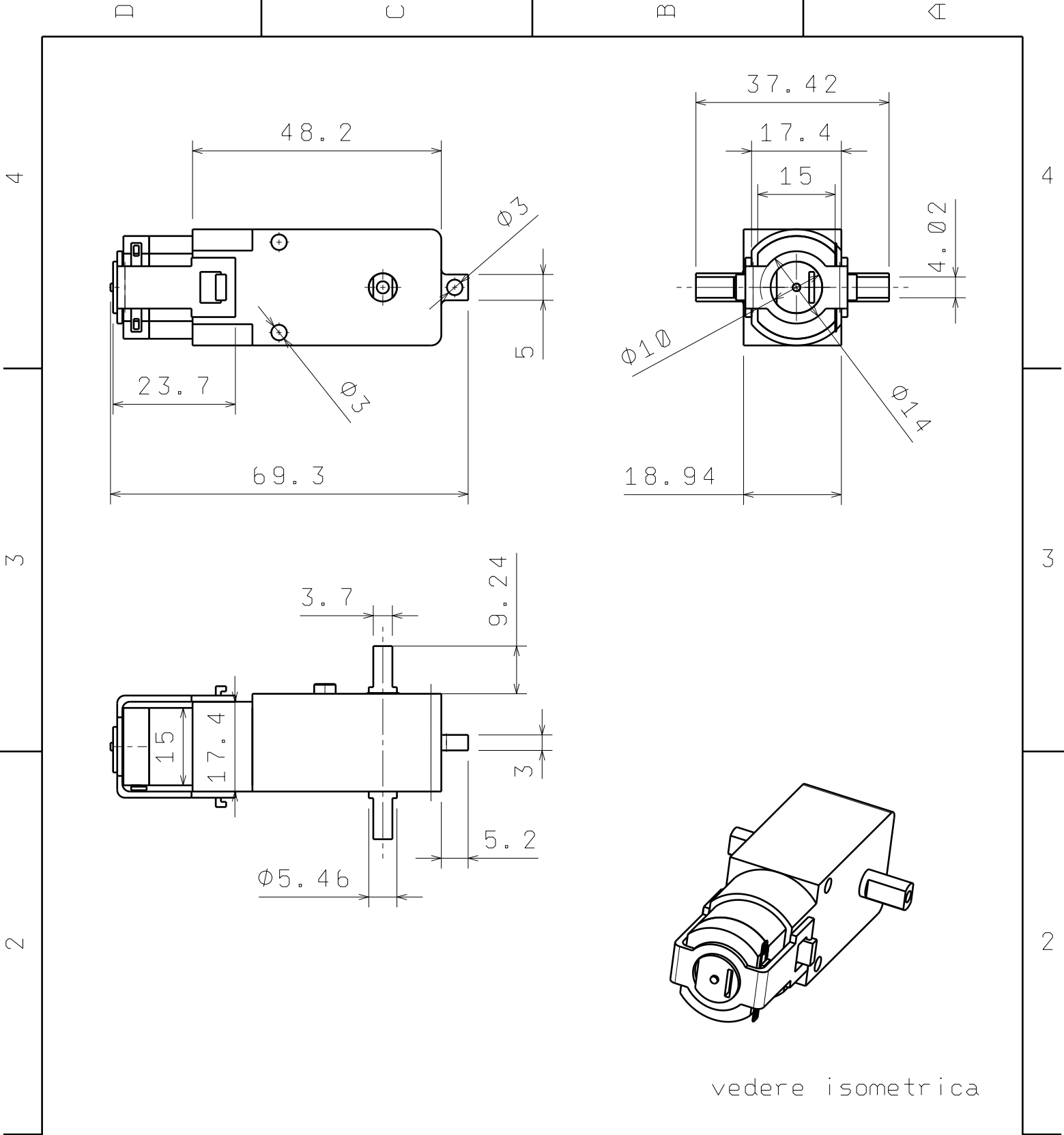
DESENAT		UNIVERSITATEA TEHNICA "GHEORGHE ASACI" DIN IASI FACULTATEA DE MECANICA	I	-
CRISTEA PETRU CORNEL			H	-
GRUPA	8408 MECATRONICA		G	-
			F	-
SIZE		E	-	
A3		D	-	
SCALE		C	-	
1: 1	1/5	B	-	
		A	-	

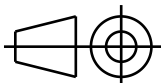
This drawing is our property; it can't be reproduced or communicated without our written agreement.

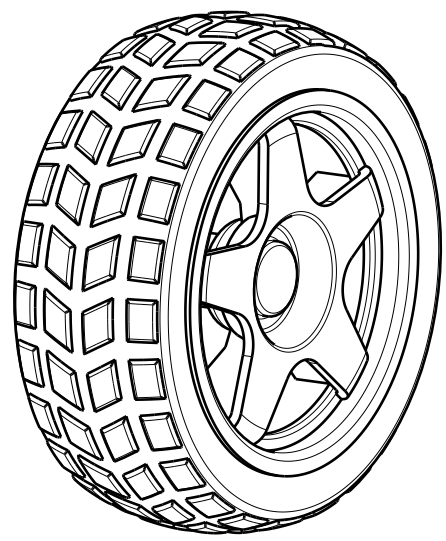
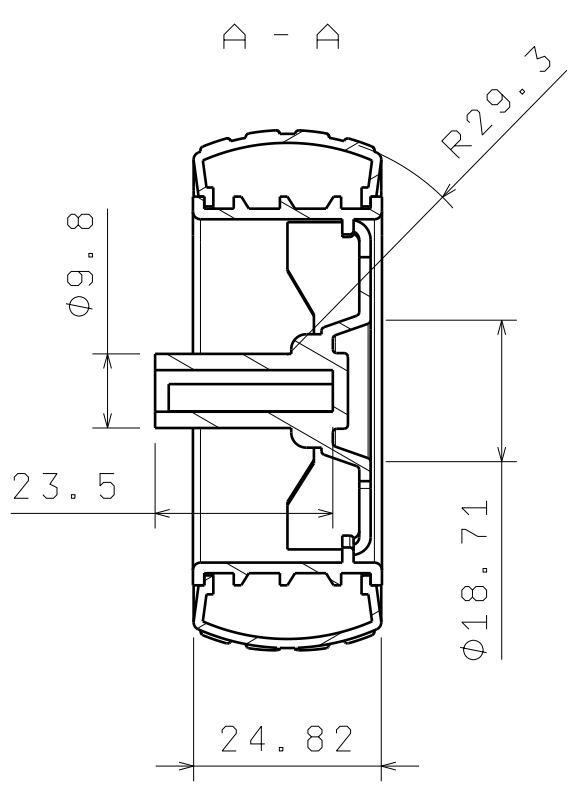
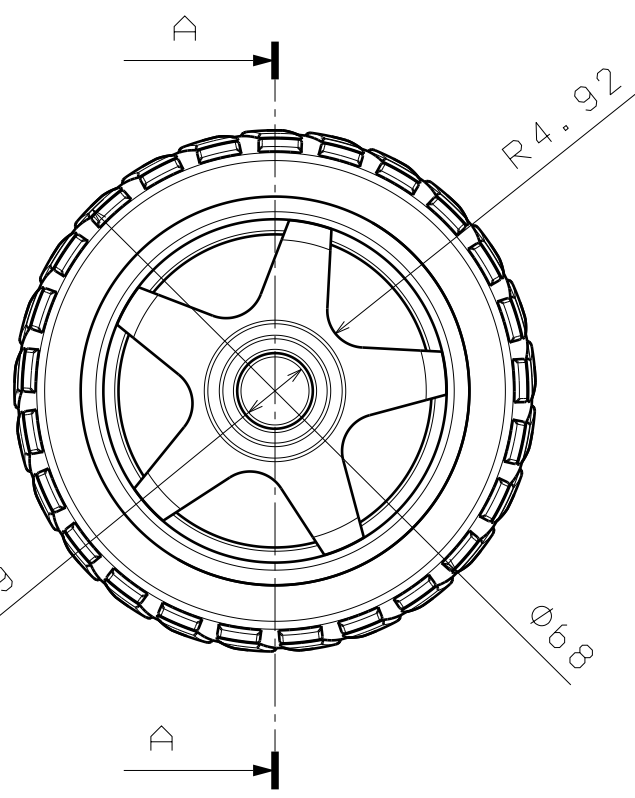


Vedere isometrica

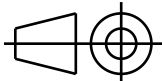
DESENAT		UNIVERSITATEA TEHNICA "GHEORGHE ASACHO" DIN IASI FACULTATEA DE MECANICA	I	-
CRISTEA PETRU CORNEL			H	-
GRUPA			G	-
8408 MECATRONICA			F	-
SIZE		ROBOT MOBIL CONTROLAT PRIN GESTURI	E	-
A4			D	-
SCALE	PLANSĂ	Roata pivotanta	C	-
1 : 1	2 / 5		B	-
			A	-
This drawing is our property; it can't be reproduced or communicated without our written agreement.				



DESENAT		UNIVERSITATEA TEHNICA "GHEORGHE ASACHO" DIN IASI FACULTATEA DE MECANICA	I	-
CRISTEA PETRU CORNEL			H	-
GRUPA			G	-
8408 MECATRONICA			F	-
SIZE		ROBOT MOBIL CONTROLAT PRIN GESTURI	E	-
A4			D	-
SCALE		PLANSĂ	C	-
1 : 1	3/5	Motor de curent continuu	B	-
This drawing is our property; it can't be reproduced or communicated without our written agreement.			A	-

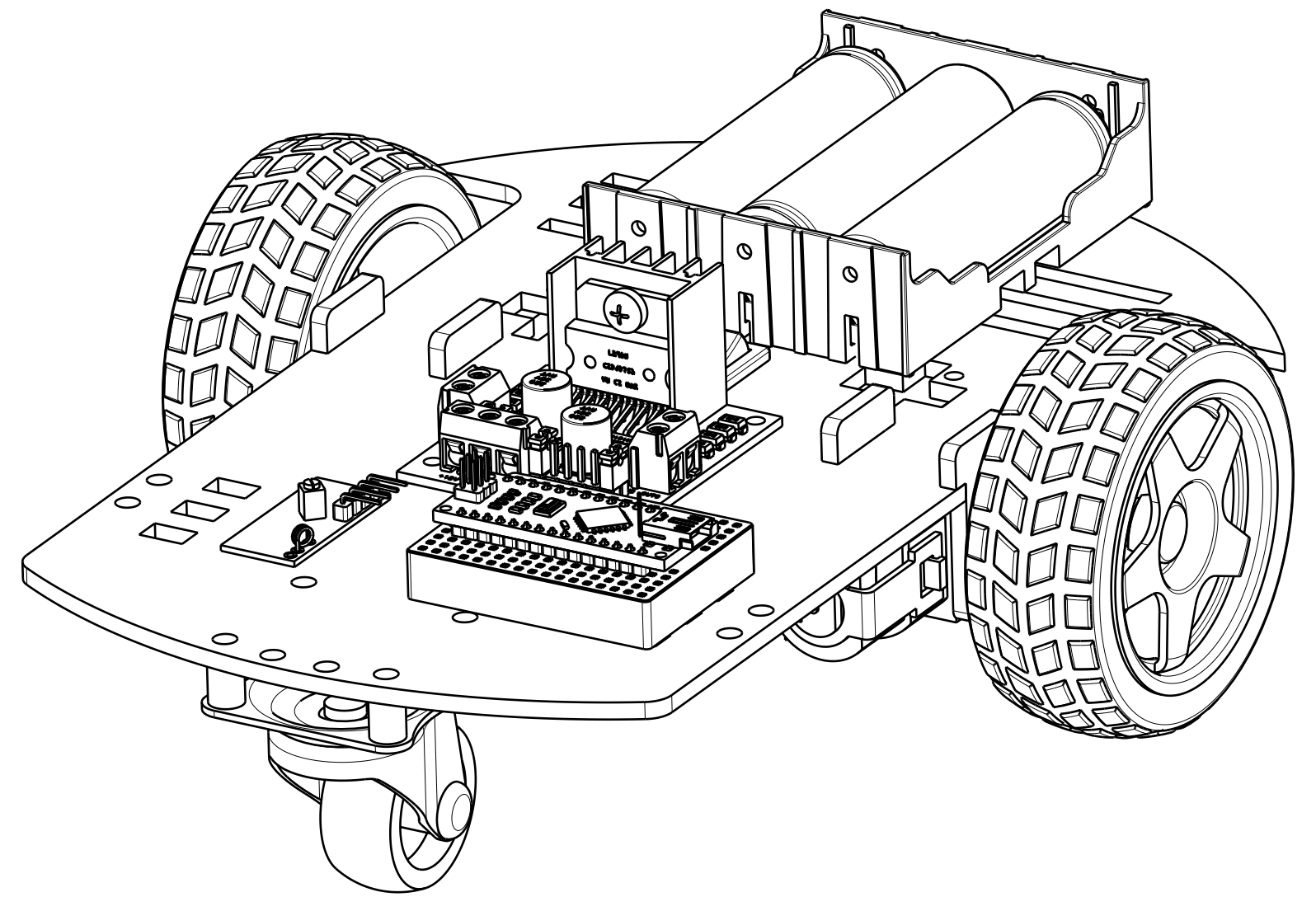
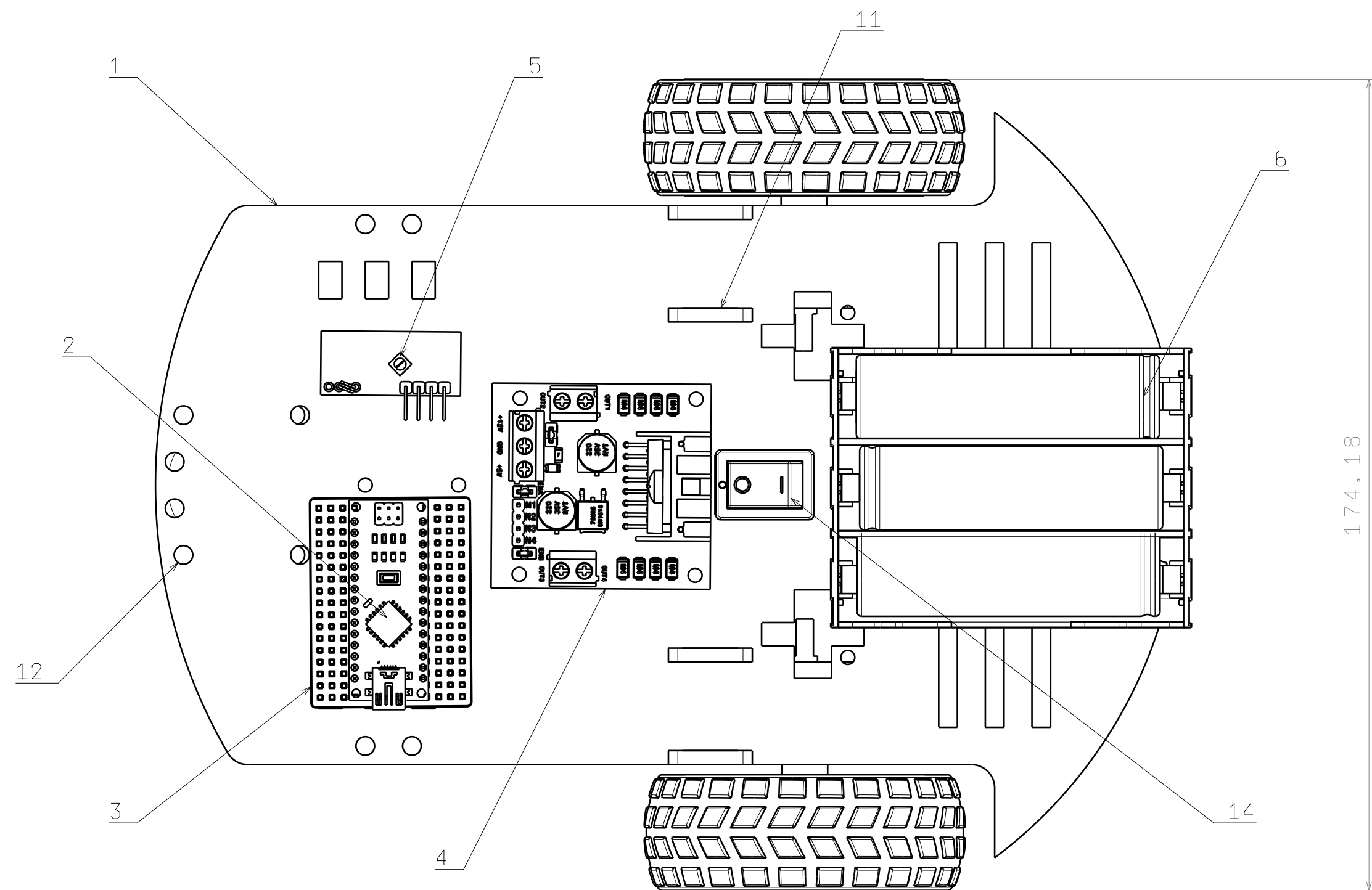
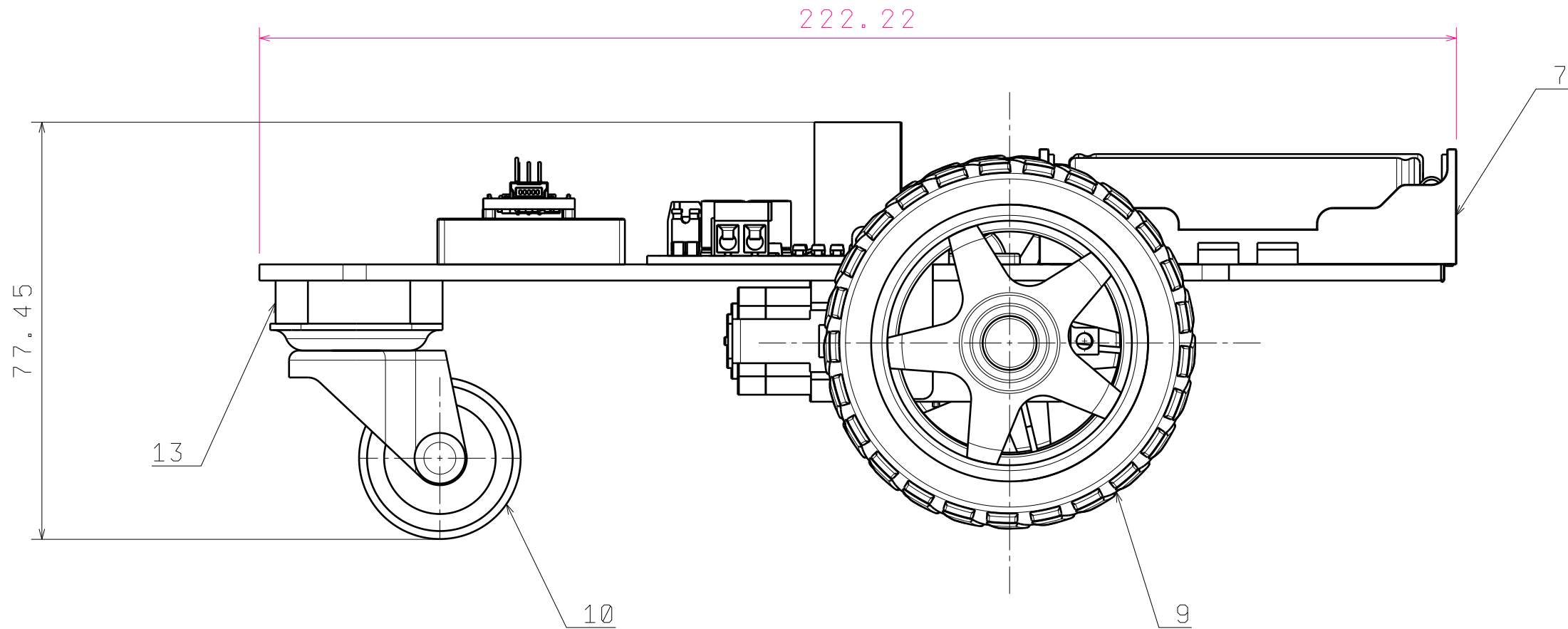


vedere isometrica

DESENAT		UNIVERSITATEA TEHNICA "GHEORGHE ASACHO" DIN IASI FACULTATEA DE MECANICA	I	-
CRISTEA PETRU CORNEL			H	-
GRUPA			G	-
8408 MECATRONICA		F	-	
SIZE		E	-	
A4		D	-	
SCALE	PLANSĂ	C	-	
1 : 1	4 / 5	B	-	
Roata motoare		A	-	
This drawing is our property; it can't be reproduced or communicated without our written agreement.				

D

A



Vedere isometrica

NR. CRT.	DENUMIRE COMPONENTA	NR. BUC.
1	Caroserie robot	1
2	Placa Arduino Nano	1
3	Placa de circuit Breadboard	1
4	Driver Motor L298N - Punte H	1
5	Receptor Radio 433MHz	1
6	Acumulator 18650 3.7V	3
7	Suport acumulatori	1
8	Motor de curent continuu cu reductor	2
9	Roata motoare	2
10	Roata pivotanta	1
11	Suport motor	4
12	Suruburi de fixare	10
13	Distantier	4
14	Comutator doua pozitii (ON-OFF)	1

DESENAT	CRISTEA PETRU CORNEL	UNIVERSITATEA TEHNICA "GHEORGHE ASACHI" DIN IASI FACULTATEA DE MECANICA	I	-
GRUPA	8408 MECATRONICA		H	-
SIZE	A2		G	-
SCALE	1:1		F	-
PLANSA	5/5		E	-
ROBOT MOBIL CONTROLAT PRIN GESTURI			D	-
Desen de ansamblu			C	-
This drawing is our property; it can't be reproduced or communicated without our written agreement.			B	-
			A	-