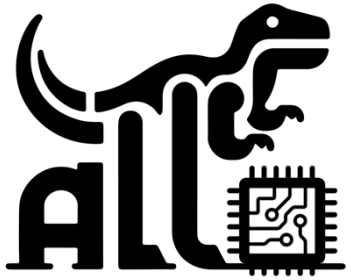


Python-Based Accelerator Design and Programming

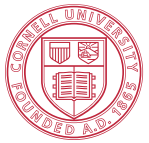
Hongzheng Chen, Niansong Zhang, Shaojie Xiang, Zhiru Zhang

Cornell University

ECE 8893 – Parallel Programming for FPGAs

Georgia Tech

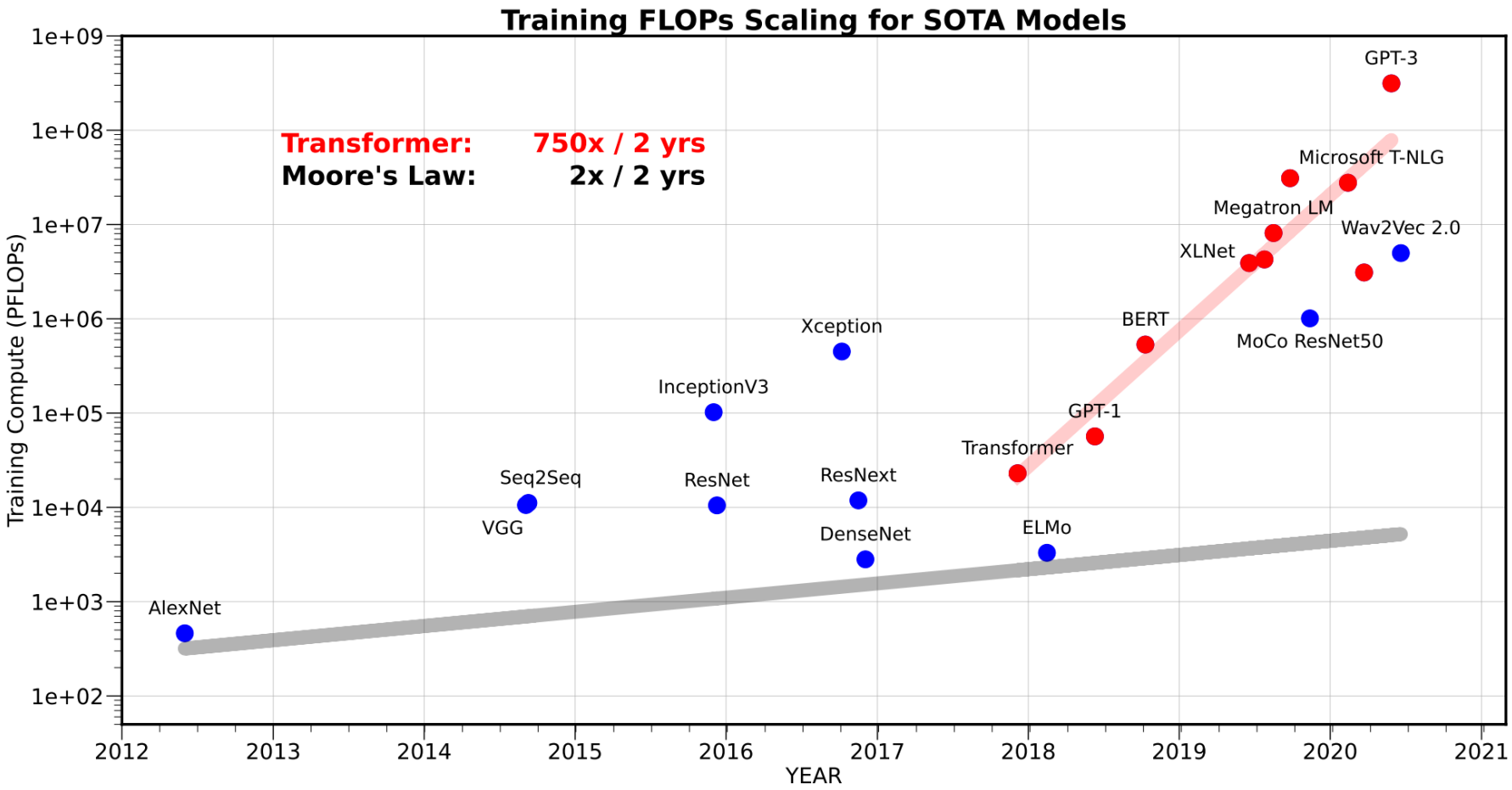
March 11, 2025



Cornell University

ZHANG

Deep Learning Models Become Larger and Larger…

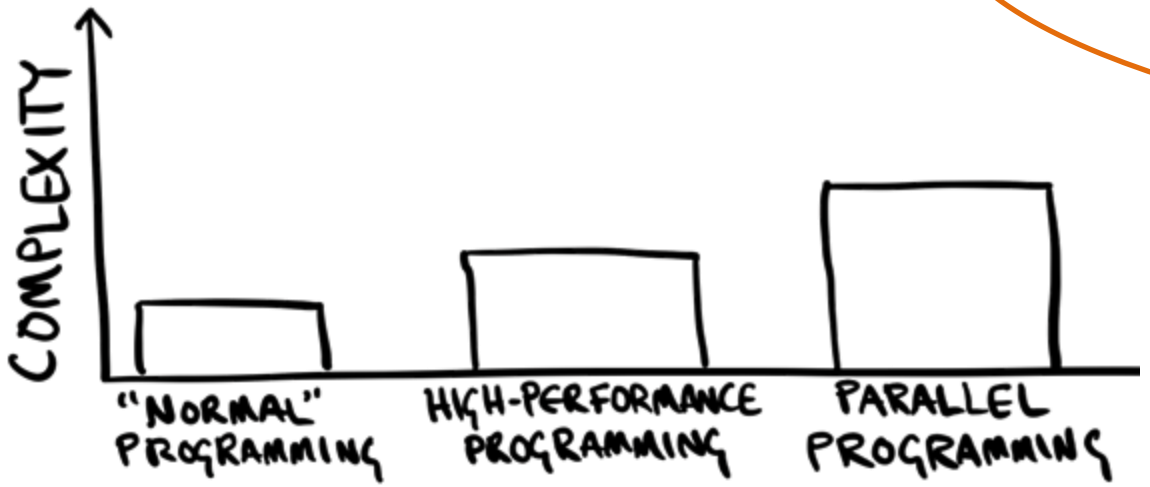


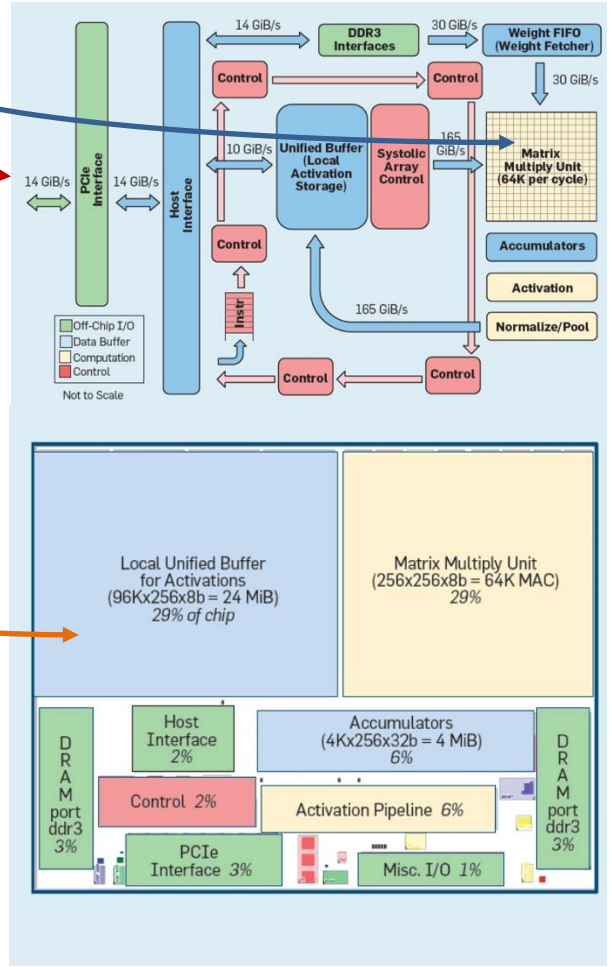
- The computational demands of large models have outgrown the capabilities of existing hardware
- Specialized accelerators are essential for speeding up model training and inference

Image source: Amir Gholami, Zhewei Yao, Sehoon Kim, Coleman Hooper, Michael W. Mahoney, Kurt Keutzer, “AI and Memory Wall”, IEEE MICRO, 2024.

Complexity in Specialized Accelerator Design

- Accelerator design is different from programming on general processors
  - Custom processing engines (PEs)
  - Custom data communication
  - Custom memory hierarchy





An AI accelerator example

Fig credit: Adrian Sampson, "From Hardware Description Languages to Accelerator Design Languages"

Challenge: Balancing Manual Control & Compiler Optimization

```
void systolic_tile(int8_t A_tile[2][768],
 int8_t B_tile[768][2],
 int8_t C_tile[2][2]) {
 #pragma dataflow
 hls::stream<int8_t> A_fifo[2][3], B_fifo[2][3];
 #pragma stream variable=A/B_fifo depth=3
 #pragma partition variable=A/B/C_tile complete dim=1
 for (int k4 = 0; k4 < 768; k4++) {
  for (int m = 0; m < 2; m++) {
   int8_t v105 = A_tile[m][k4];
   A_fifo[m][0].write(v105);}
   // ... write B_fifo
  }}
  for (int Ti = 0; Ti < 2; ++Ti) {
  #pragma HLS unroll
   for (int Tj = 0; Tj < 2; ++Tj) {
   #pragma HLS unroll
    // ... load A/B_fifo
    PE_kernel(A_in, A_out, B_in, B_out, C, Ti, Tj);
}}}

void matmul(int8_t A[512][768], int8_t B[768][768],
 int8_t C[512][768]
) {
 int8_t local_A[2][768], local_B[768][2], local_C[2][2];
 for (int mi = 0; mi < 256; mi++) {
  for (int ni = 0; ni < 384; ni++) {
   // ... load A, B
   systolic_tile(local_A, local_B, local_C);
}}}
```

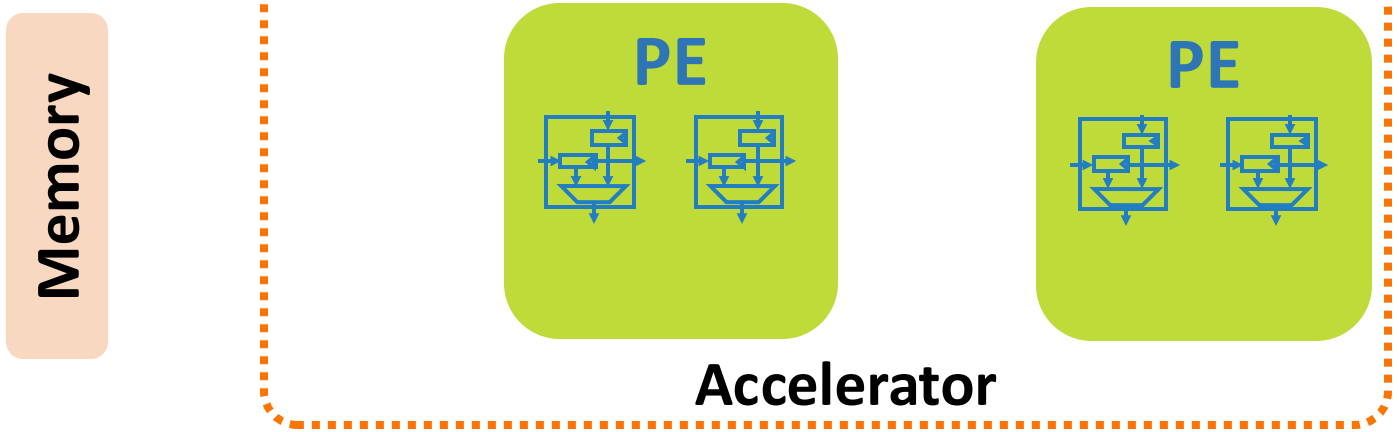
Compute Customization

Vanilla Matmul (1% theoretical peak perf.)

\+ Compute customization (~30% peak)

- \+ Loop tiling
- \+ Loop unrolling
- \+ Loop & function pipelining

Increasing programming effort



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   int8_t v105 = A_tile[m][k4];
   A_fifo[m][0].write(v105);}
   // ... write B_fifo
  }}
 for (int Ti = 0; Ti < 2; ++Ti) {
 #pragma HLS unroll
  for (int Tj = 0; Tj < 2; ++Tj) {
  #pragma HLS unroll
   // ... load A/B_fifo
   PE_kernel(A_in, A_out, B_in, B_out, C, Ti, Tj);
}}}

void matmul(int8_t A[512][768], int8_t B[768][768],
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 int8_t local_A[2][768], local_B[768][2], local_C[2][2];
 for (int mi = 0; mi < 256; mi++) {
  for (int ni = 0; ni < 384; ni++) {
   // ... load A, B
   systolic_tile(local_A, local_B, local_C);
}}}
```

Memory Customization

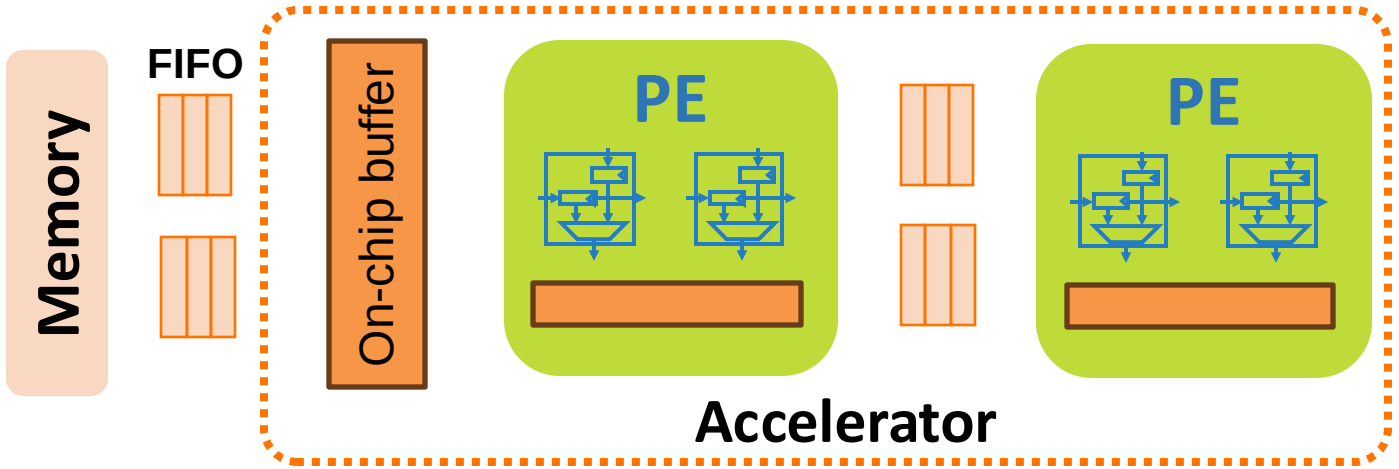
Compute Customization

Vanilla Matmul (1% theoretical peak perf.)

+ Compute customization (~30% peak)
  + Loop tiling
  + Loop unrolling
  + Loop & function pipelining

+ Custom memory hierarchy (~50% peak)
  + Tiling & data reuse buffers
  + Memory banking/partitioning

Increasing programming effort



Challenge: Balancing Manual Control & Compiler Optimization

```
void systolic_tile(int8_t A_tile[2][768],
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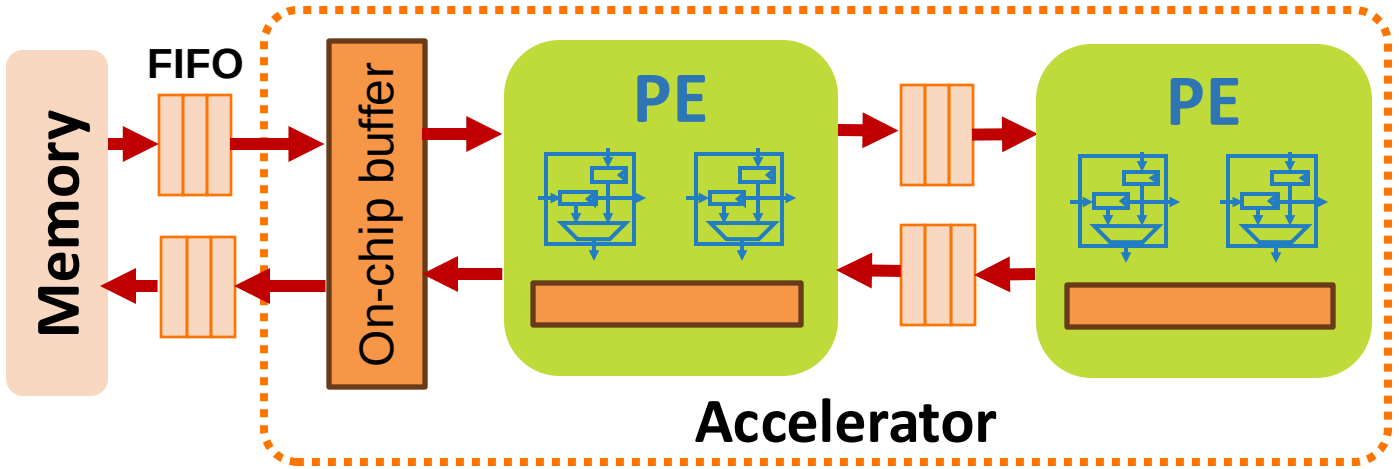
 #pragma dataflow
 hls::stream<int8_t> A_fifo[2][3], B_fifo[2][3];
 #pragma stream variable=A/B_fifo depth=3
 #pragma partition variable=A/B/C_tile complete dim=1
 for (int k4 = 0; k4 < 768; k4++) {
  for (int m = 0; m < 2; m++) {
   int8_t v105 = A_tile[m][k4];
   A_fifo[m][0].write(v105);}
   // ... write B_fifo
  }}
 for (int Ti = 0; Ti < 2; ++Ti) {
 #pragma HLS unroll
  for (int Tj = 0; Tj < 2; ++Tj) {
  #pragma HLS unroll
   // ... load A/B_fifo
   PE_kernel(A_in, A_out, B_in, B_out, C, Ti, Tj);
}}}

void matmul(int8_t A[512][768], int8_t B[768][768],
 int8_t C[512][768]
) {
 int8_t local_A[2][768], local_B[768][2], local_C[2][2];
 for (int mi = 0; mi < 256; mi++) {
  for (int ni = 0; ni < 384; ni++) {
   // ... load A, B
   systolic_tile(local_A, local_B, local_C);
}}}
```

Communication Customization

Memory Customization

Compute Customization



Vanilla Matmul (1% theoretical peak perf.)

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  + Loop tiling
  + Loop unrolling
  + Loop & function pipelining

+ Custom memory hierarchy (~50% peak)
  + Tiling & data reuse buffers
  + Memory banking/partitioning

+ Data movement optimization (~95% peak)
  + Data streaming
  + Data packing (vectorization)
  + Memory coalescing
  + Systolic communication

Increasing programming effort

Challenge: Balancing Manual Control & Compiler Optimization

```
void systolic_tile(int8_t A_tile[2][768],
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 hls::stream<int8_t> A_fifo[2][3], B_fifo[2][3];
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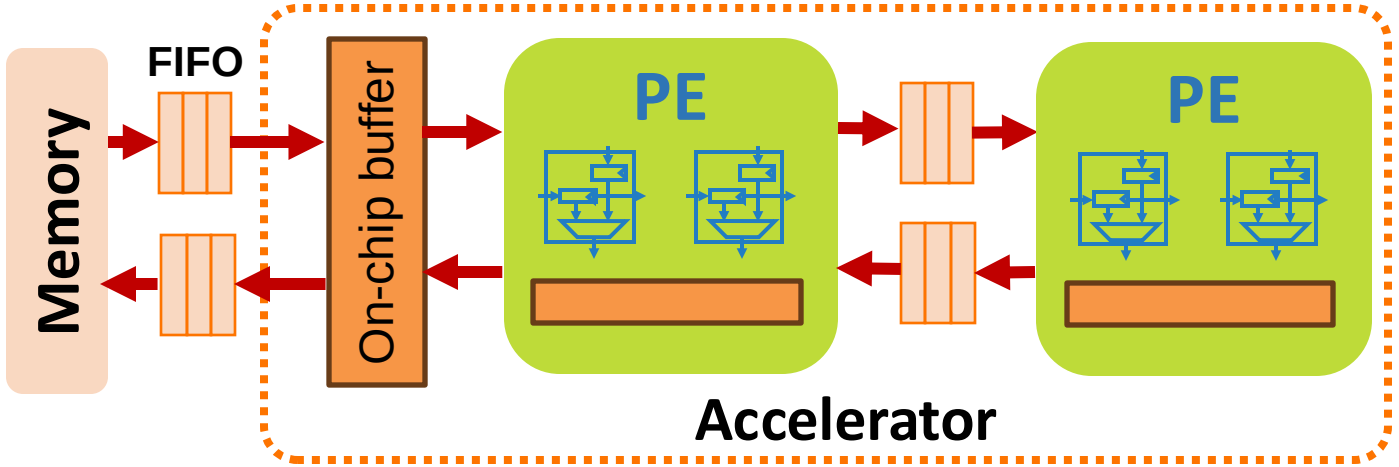
 for (int k4 = 0; k4 < 768; k4++) {
  for (int m = 0; m < 2; m++) {
   int8_t v105 = A_tile[m][k4];
   A_fifo[m][0].write(v105);}
   // ... write B_fifo
  }}
 for (int Ti = 0; Ti < 2; ++Ti) {
 #pragma HLS unroll
  for (int Tj = 0; Tj < 2; ++Tj) {
  #pragma HLS unroll
   // ... load A/B_fifo
   PE_kernel(A_in, A_out, B_in, B_out, C, Ti, Tj);
}}}

void matmul(int8_t A[512][768], int8_t B[768][768],
 int8_t C[512][768]
) {
 int8_t local_A[2][768], local_B[768][2], local_C[2][2];
 for (int mi = 0; mi < 256; mi++) {
  for (int ni = 0; ni < 384; ni++) {
   // ... load A, B
   systolic_tile(local_A, local_B, local_C);
}}}
```

Communication Customization

Memory Customization

Compute Customization



Vanilla Matmul (1% theoretical peak perf.)

+ Compute customization (~30% peak)
  + Loop tiling
  + Loop unrolling
  + Loop & function pipelining

Existing HLS compiler e.g., ScaleHLS [HPCA'22]

+ Custom memory hierarchy (~50% peak)
  + Tiling & data reuse buffers
  + Memory banking/partitioning

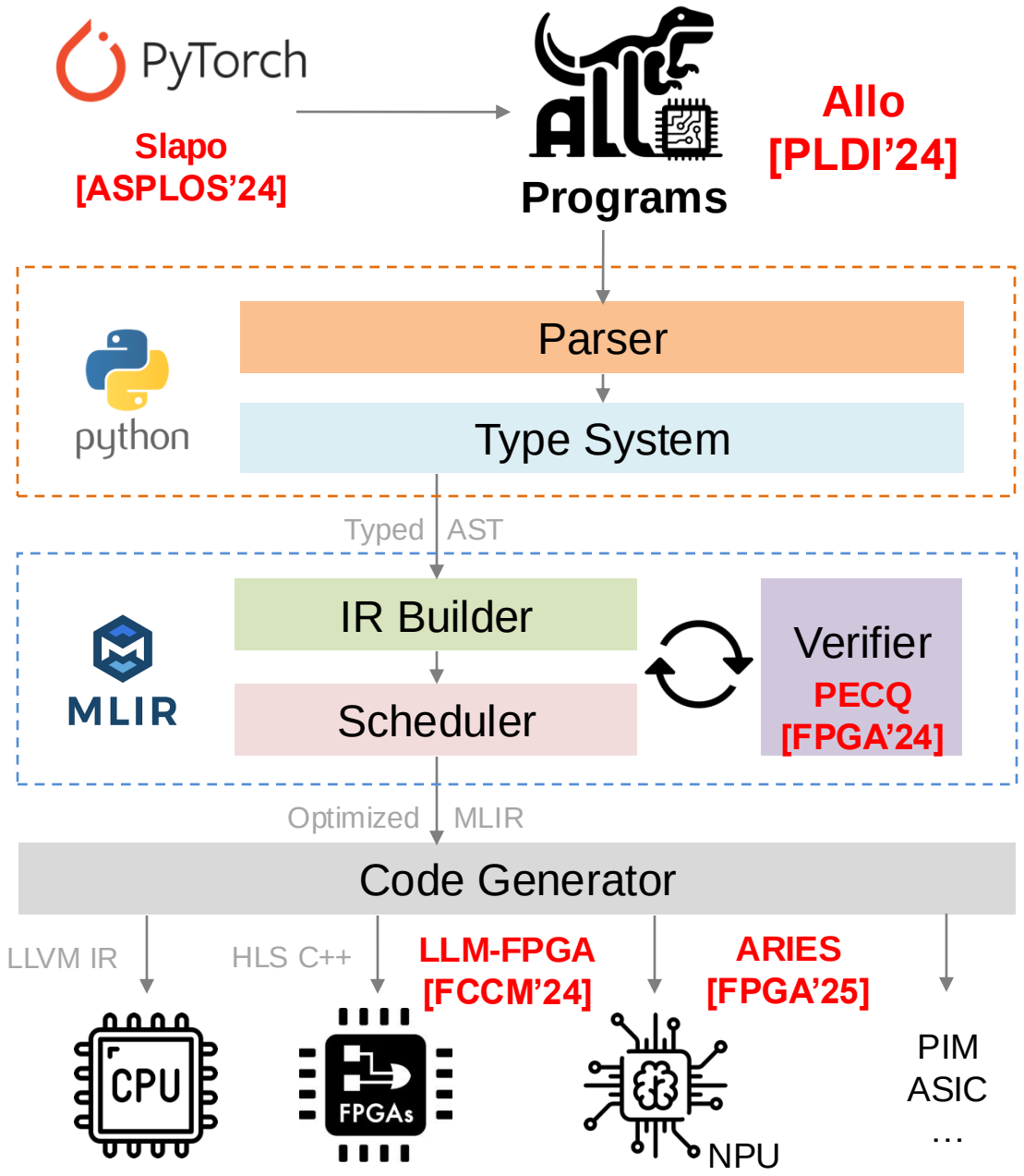
+ Data movement optimization (~95% peak)
  + Data streaming
  + Data packing (vectorization)
  + Memory coalescing
  + Systolic communication

Increasing programming effort

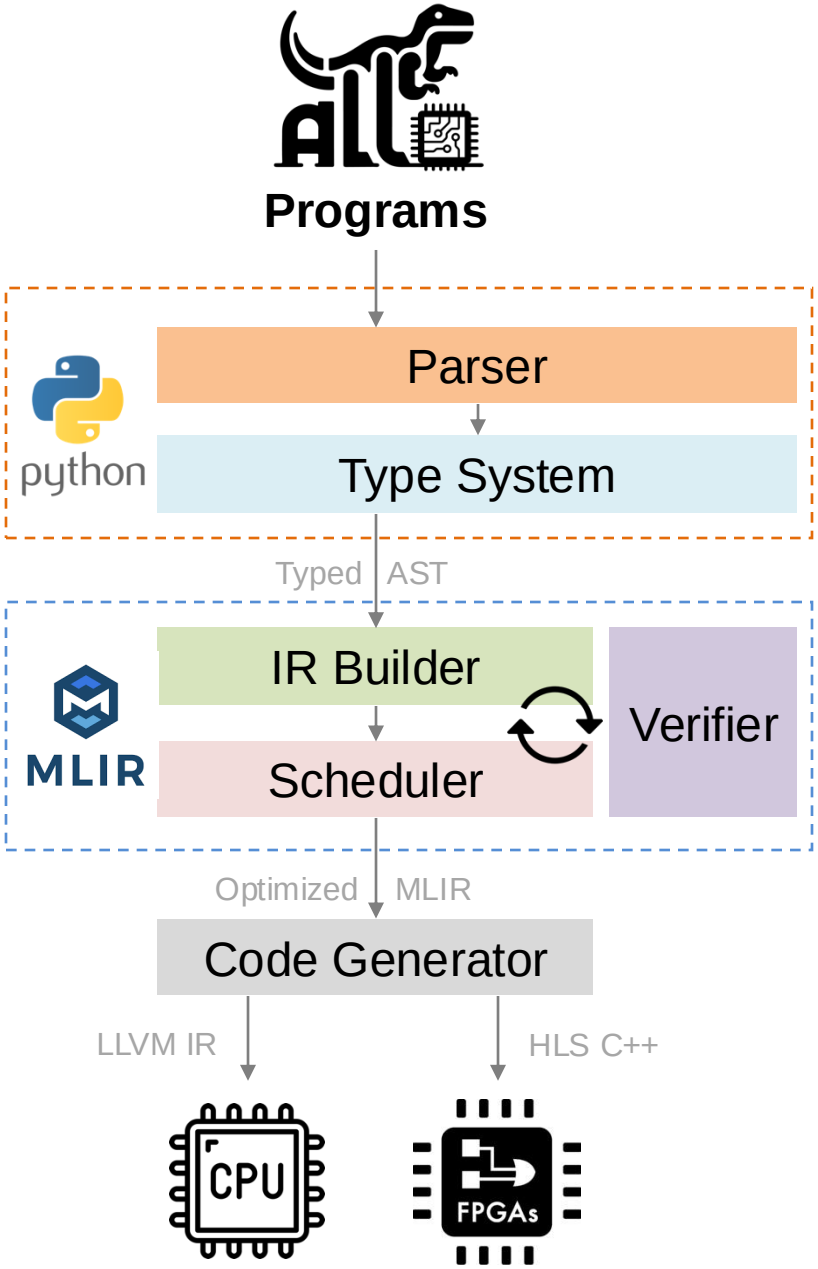
~500 lines of HLS code for a GEMM systolic array

vendor-specific, hard to maintain & reuse

Allo Accelerator Design Language (ADL) and Compiler



Allo Accelerator Design Language (ADL) and Compiler



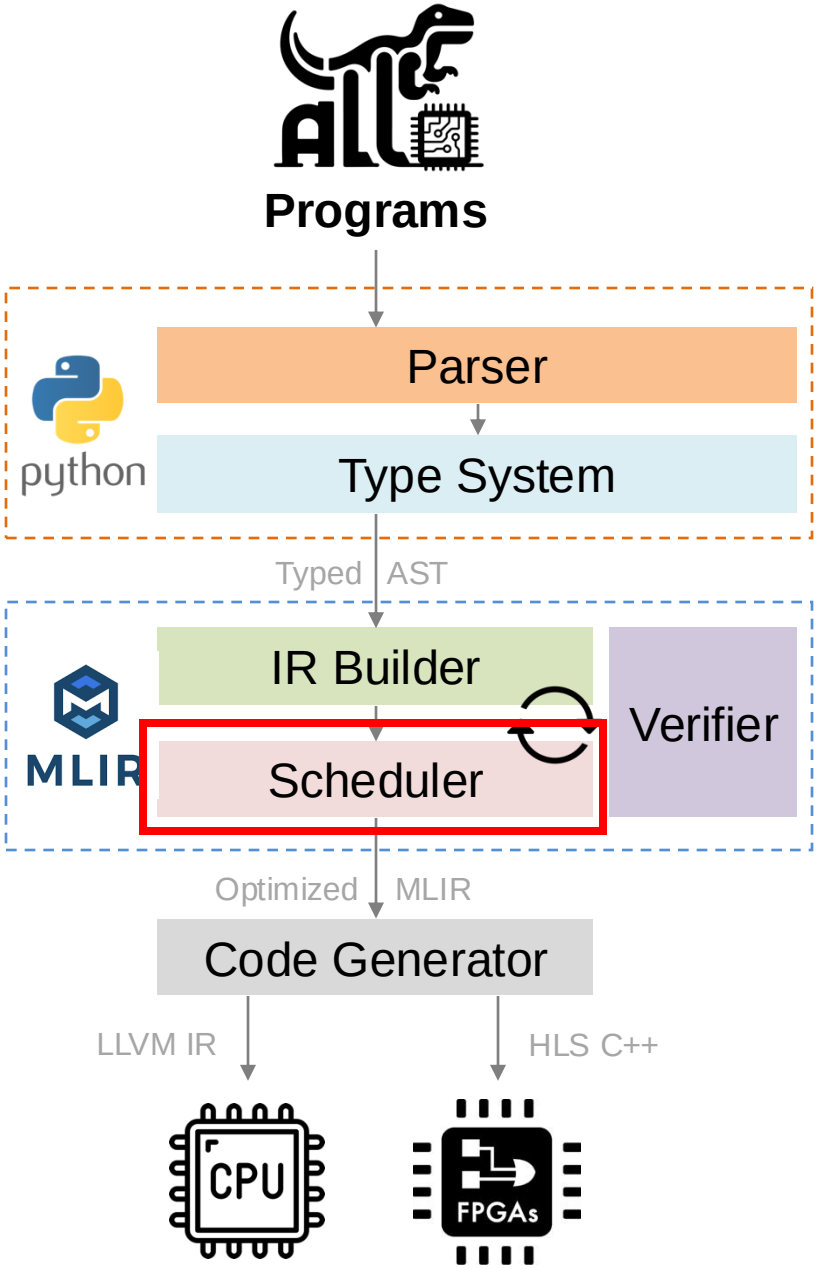
Pythonic: No need to learn a new DSL!

Algorithm Specification

```
def matmul(A: float32[M, K],
           B: float32[K, N])
           -> float32[M, N]:
  C: float32[M, N] = 0.0
  for i, j, k in allo.grid(M, N, K):
    C[i, j] += A[i, k] * B[k, j]
  return C
```

- Free-form imperative programming
- Strong type system

Allo Accelerator Design Language (ADL) and Compiler



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    C[i, j] += A[i, k] * B[k, j]
  return C
```
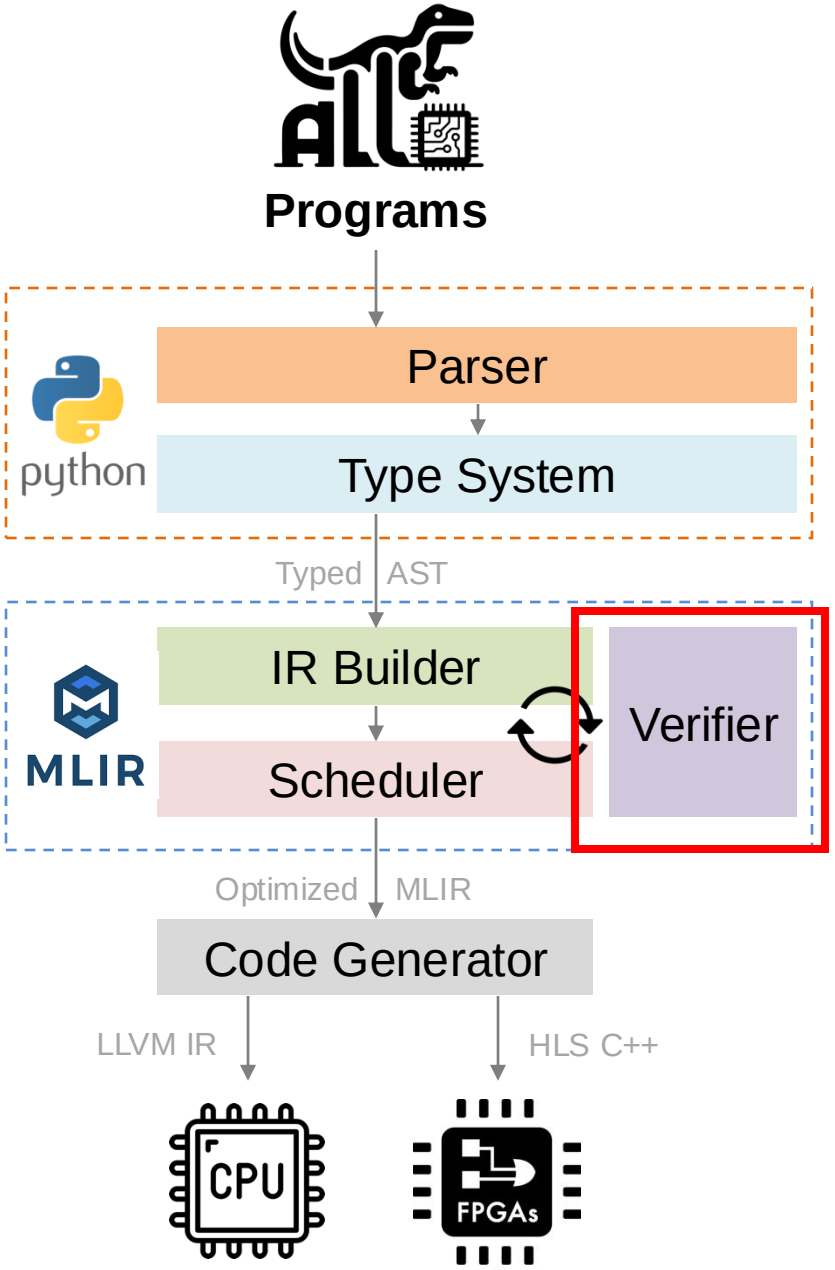

Decoupled customization

Compute Cust.
Memory Cust.
Comm. Cust.

```
s = allo.customize(matmul)
s.reorder("k", "j")
s.buffer_at(s.C, axis="i")
s.pipeline("j")
```

Allo Accelerator Design Language (ADL) and Compiler



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Algorithm Specification

```
def matmul(A: float32[M, K],
           B: float32[K, N])
           -> float32[M, N]:
  C: float32[M, N] = 0.0
  for i, j, k in allo.grid(M, N, K):
    C[i, j] += A[i, k] * B[k, j]
  return C
```

Stepwise verifiable rewrites

```
s = allo.customize(gemm)
s.reorder("k", "j")
print(s.module)
```

```
module {
 func.func @gemm(%arg0: memref<1024x1024xf32>, %arg1: memref<1024x1024xf32>) ->
 memref<1024x1024xf32> {
  %alloc = memref.alloc() {name = "C"} : memref<1024x1024xf32>
  affine.for %arg2 = 0 to 1024 {
   affine.for %arg3 = 0 to 1024 {
    affine.for %arg4 = 0 to 1024 {
     ...
    } {loop_name = "k"}
   } {loop_name = "j"}
  } {loop_name = "i", op_name = "S_i_j_0"}
  return %alloc : memref<1024x1024xf32>
 }}
```

```
s.buffer_at(s.C, axis="i")
print(s.module)
```

MLIR

```
module {
 func.func @gemm(%arg0: memref<1024x1024xf32>, %arg1: memref<1024x1024xf32>) ->
 memref<1024x1024xf32> {
  %alloc = memref.alloc() {name = "C"} : memref<1024x1024xf32>
  affine.for %arg2 = 0 to 1024 {
   %alloc_0 = memref.alloc() : memref<1024xf32>
   affine.for %arg3 = 0 to 1024 {
    ...
   } {buffer, loop_name = "j_init", pipeline_ii = 1 : i32}
   affine.for %arg3 = 0 to 1024 {
    affine.for %arg4 = 0 to 1024 {
     ...
    } {loop_name = "j"}
   } {loop_name = "k", op_name = "S_k_0", reduction}
   affine.for %arg3 = 0 to 1024 {
    ...
   } {buffer, loop_name = "j_back", pipeline_ii = 1 : i32}
  } {loop_name = "i", op_name = "S_i_j_0"}
  return %alloc : memref<1024x1024xf32>
 }}
```

```
s.pipeline("j")
print(s.module)
```

```
module {
 func.func @gemm(%arg0, %arg1) -> memref<1024x1024xf32> {
  %alloc = memref.alloc() {name = "C"} : memref<1024x1024xf32>
  affine.for %arg2 = 0 to 1024 {
   affine.for %arg3 = 0 to 1024 {
    affine.for %arg4 = 0 to 1024 {
     ...
    } {loop_name = "j", pipeline}
   } {loop_name = "k", op_name = "S_k_0", reduction}
   ...
  } {loop_name = "i", op_name = "S_i_j_0"}
  return %alloc : memref<1024x1024xf32>
 }}
```

Transforming GEMM to Systolic Array

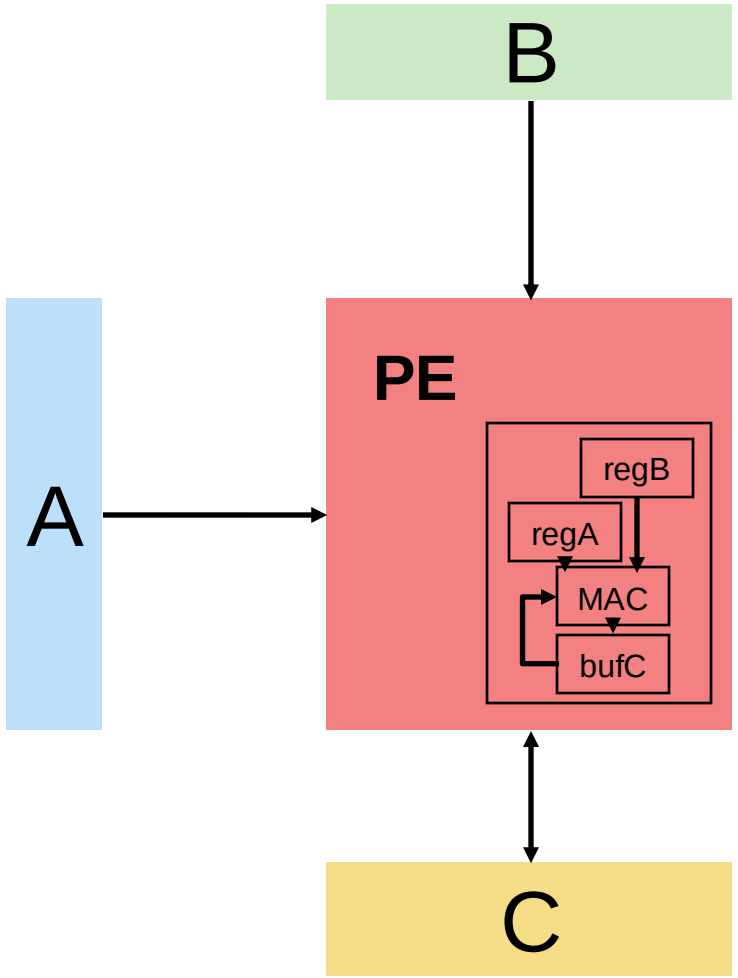
➔ Algorithm specification

```
def matmul(A: int8[M, K],
           B: int8[K, N],
           C: int16[M, N]):
  for i, j in allo.grid(M, N, "PE"):
    for k in range(K):
      C[i, j] += A[i, k] * B[k, j]
```

➔ Schedule construction

```
s = allo.customize(matmul)
```

➔ Architectural Diagram



* Schedule: A sequence of customization primitives

Transforming GEMM to Systolic Array

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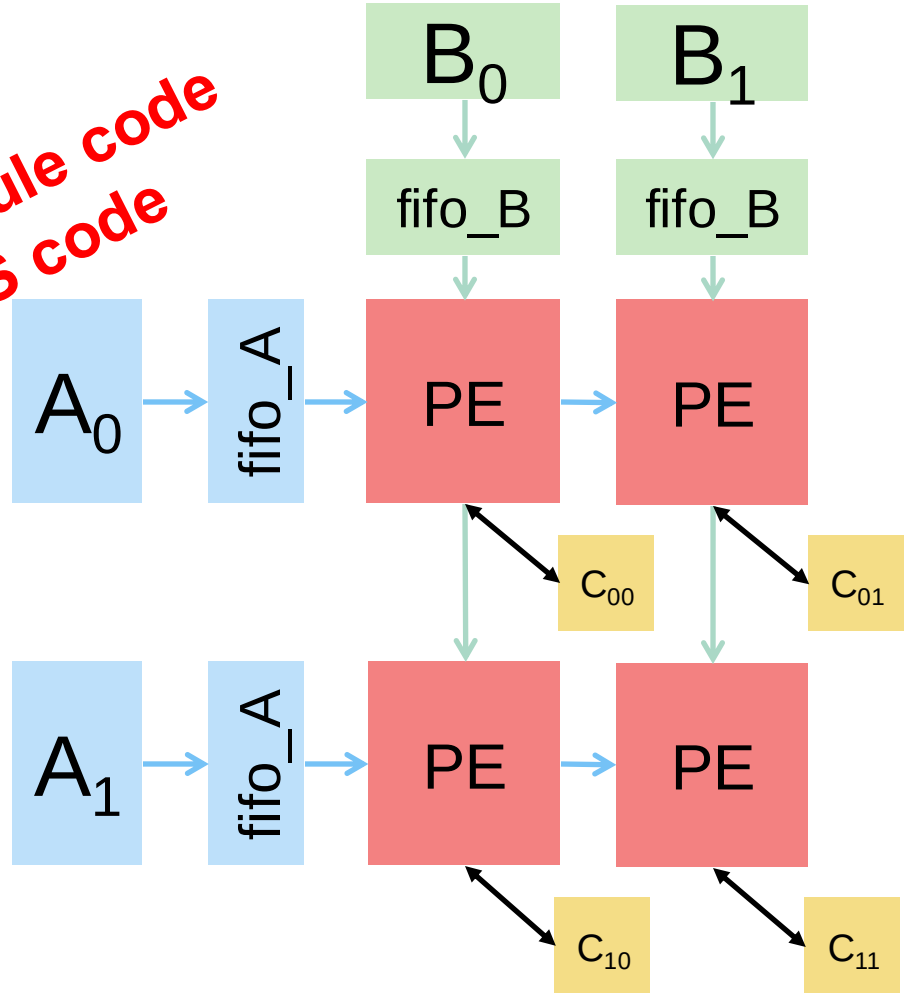
      C[i, j] += A[i, k] * B[k, j]
```

➔ Schedule construction

```
s = allo.customize(matmul)
buf_A = s.buffer_at(s.A, "j")
buf_B = s.buffer_at(s.B, "j")
pe = s.unfold("PE", axis=[0, 1],
              factor=[M, N])
s.partition(s.A, dim=0)
s.partition(s.B, dim=1)
s.partition(s.C, dim=[0, 1])
s.to(buf_A, pe, axis=0, depth=M + 1)
s.to(buf_B, pe, axis=1, depth=N + 1)
```

Only 8 lines of schedule code vs ~500 lines HLS code

➔ Architectural Diagram



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              factor=[M, N])
s.partition(s.A, dim=0)
s.partition(s.B, dim=1)
s.partition(s.C, dim=[0, 1])
s.to(buf_A, pe, axis=0, depth=M + 1)
s.to(buf_B, pe, axis=1, depth=N + 1)
```
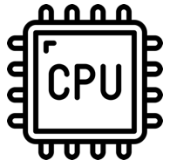
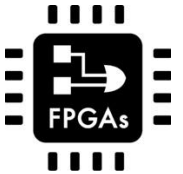

➔ CPU Simulation




```
mod = s.build(target="llvm")

A = np.random.randint(-8, 8, size=(M, K)) \
    .astype(np.int8)
B = np.random.randint(-8, 8, size=(K, N)) \
    .astype(np.int8)
C = np.zeros((M, N), dtype=np.int16)
mod(A, B, C)
np.testing.assert_allclose(C, A @ B, atol=1e-3)
```

➔ Bitstream generation




```
mod = s.build(target="vitis_hls",
              mode="hw",
              project="systolic.prj")

# Automatically invoke the HLS toolchain
mod(A, B, C)
```

Transforming GEMM to Systolic Array

➔ Algorithm specification

```
def matmul(A: int8[M, K],
           B: int8[K, N],
           C: int16[M, N]):
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      C[i, j] += A[i, k] * B[k, j]
```
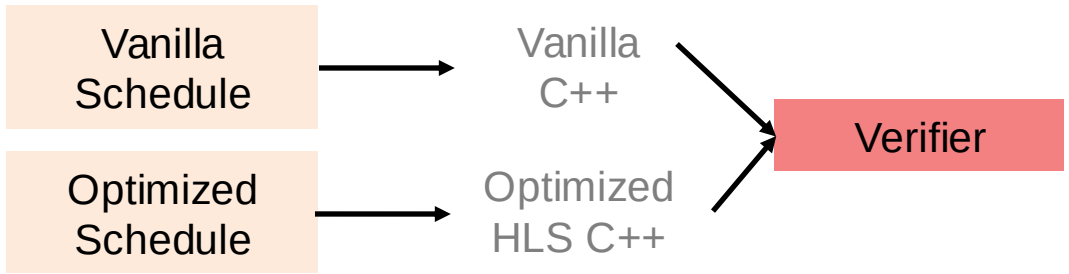

➔ Schedule construction

```
s = allo.customize(matmul)
buf_A = s.buffer_at(s.A, "j")
buf_B = s.buffer_at(s.B, "j")
pe = s.unfold("PE", axis=[0, 1],
              factor=[M, N])
s.partition(s.A, dim=0)
s.partition(s.B, dim=1)
s.partition(s.C, dim=[0, 1])
s.to(buf_A, pe, axis=0, depth=M + 1)
s.to(buf_B, pe, axis=1, depth=N + 1)
```

➔ Formal Verification [FPGA'24 Best Paper*]

```
mod = s.verify()
```



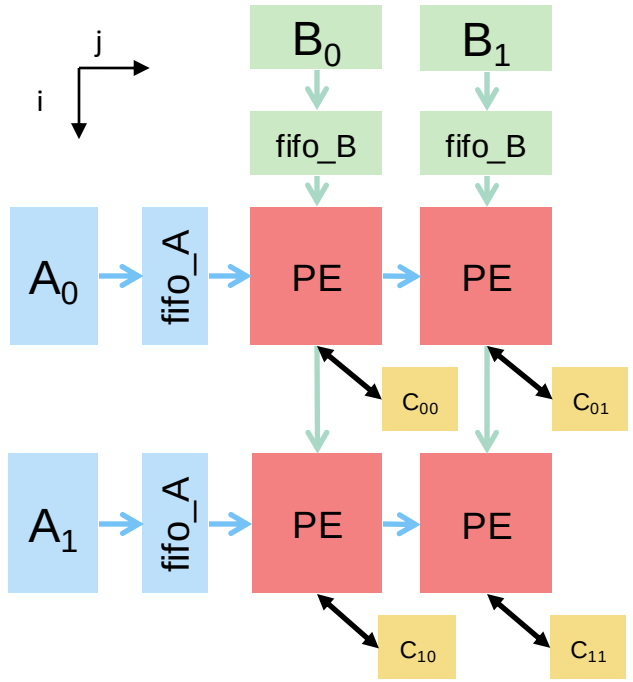
- A **formal equivalence checker** of source-to-source HLS transformations via symbolic execution
  - Support statically interpretable control-flow (SICF)
- Verification in time/space linear w.r.t. OPs executed
  - ~500K Ops/sec in verification throughput
  - A complex **64x64 systolic array verified in 16 minutes**

* L.-N. Pouchet et al., "Formal Verification of Source-to-Source Transformation for HLS", FPGA 2024 (Best Paper Award)

Transforming GEMM to Systolic Array

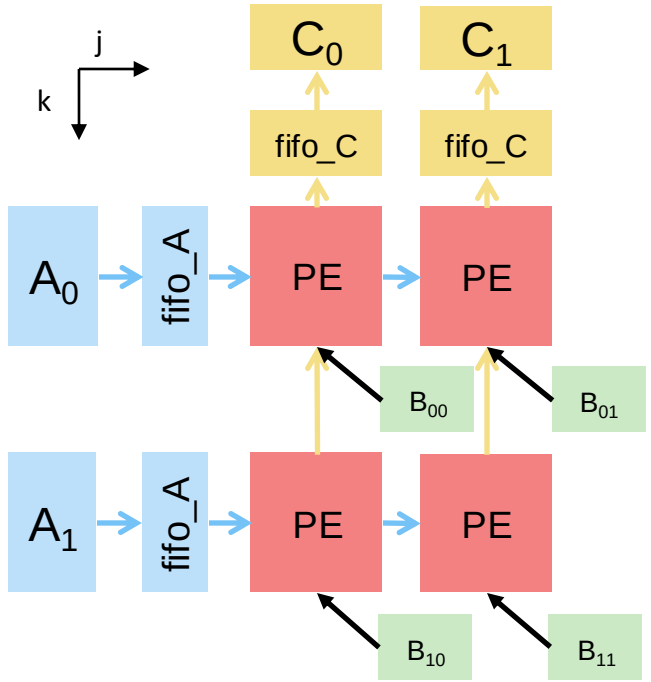
➔ Spatial loop: i, j

```
s = allo.customize(matmul)
buf_A = s.buffer_at(s.A, "j")
buf_B = s.buffer_at(s.B, "j")
pe = s.unfold("PE", axis=[0, 1],
              factor=[M, N])
s.partition(s.A, dim=0)
s.partition(s.B, dim=1)
s.partition(s.C, dim=[0, 1])
s.to(buf_A, pe, axis=0, depth=M + 1)
s.to(buf_B, pe, axis=1, depth=N + 1)
```



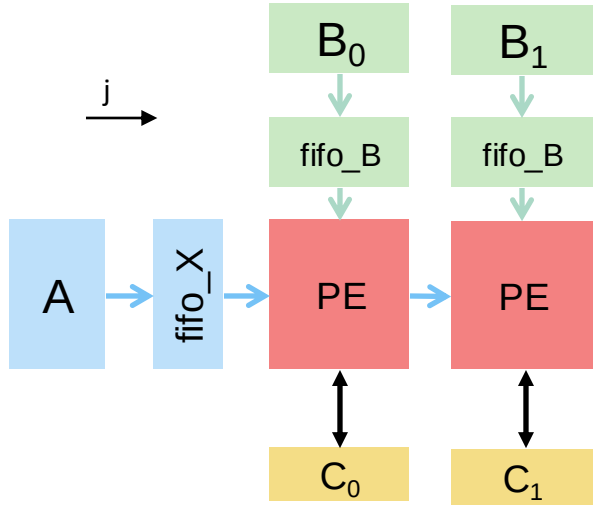
➔ Spatial loop: k, j

```
s = allo.customize(matmul)
s.reorder("k", "j", "i")
buf_A = s.buffer_at(s.A, "j")
buf_C = s.buffer_at(s.C, "j")
pe = s.unfold("PE", axis=[0, 1],
              factor=[K, N])
s.partition(s.A, dim=0)
s.partition(s.B, dim=[0, 1])
s.partition(s.C, dim=1)
s.to(buf_A, pe, axis=0)
s.to(buf_B, pe, axis=1)
```



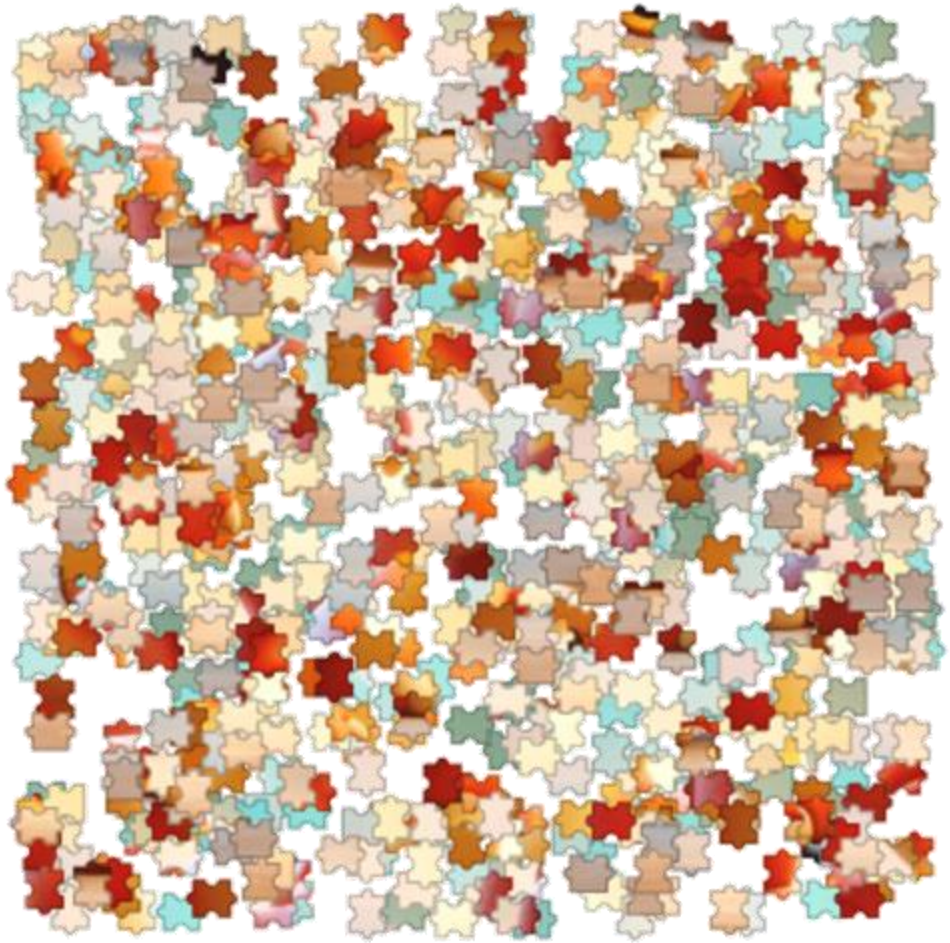
➔ Spatial loop: j

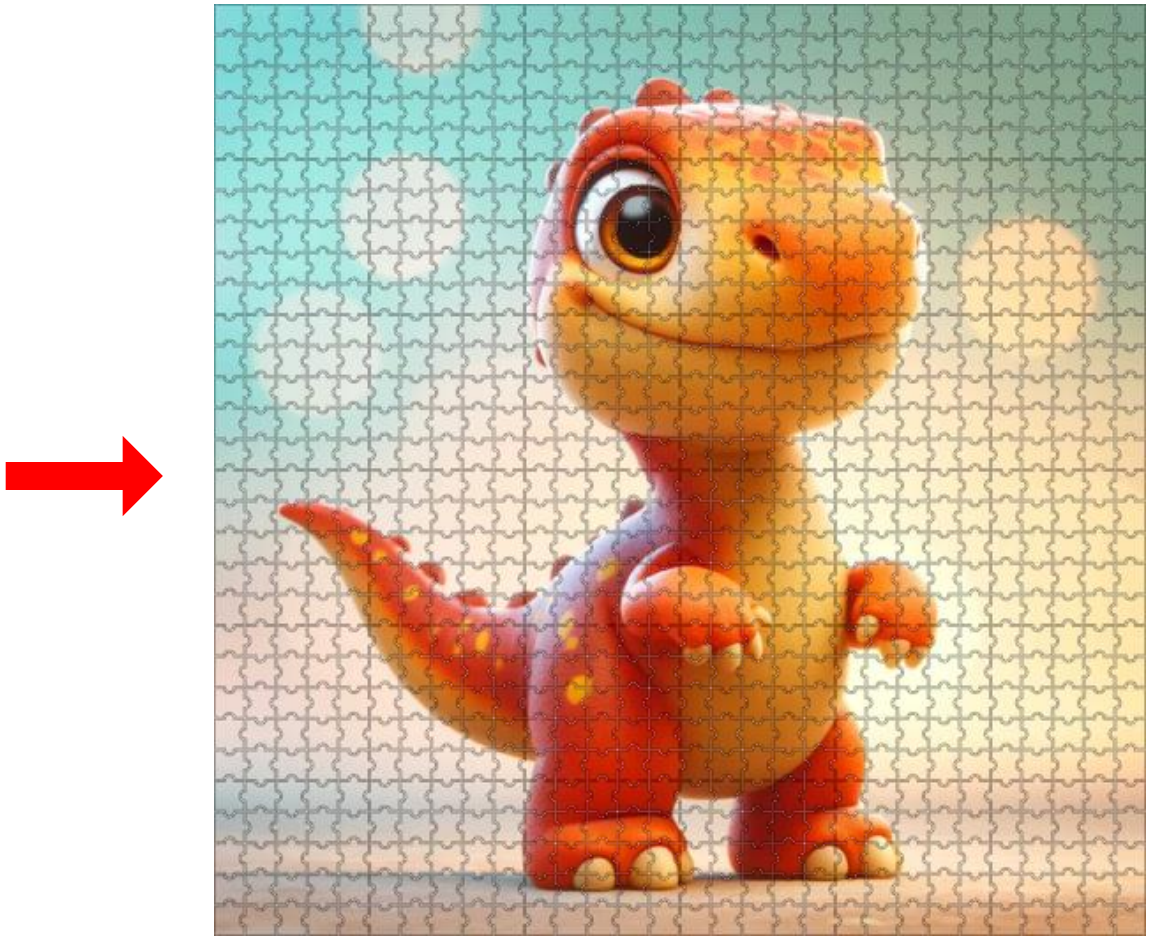
```
s = allo.customize(matmul)
buf_A = s.buffer_at(s.A, "j")
buf_B = s.buffer_at(s.B, "j")
pe = s.unfold("PE", axis=1,
              factor=M)
s.partition(s.B, dim=1)
s.partition(s.C, dim=1)
s.to(buf_A, pe, axis=0)
s.to(buf_B, pe, axis=1)
```



Realize different dataflows with minimal schedule code

How to Compose Optimized Kernels into Complete Accelerator?





Optimized Kernels

High-performance Accelerator

Composable Schedules

➔ Given different optimized kernel implementations

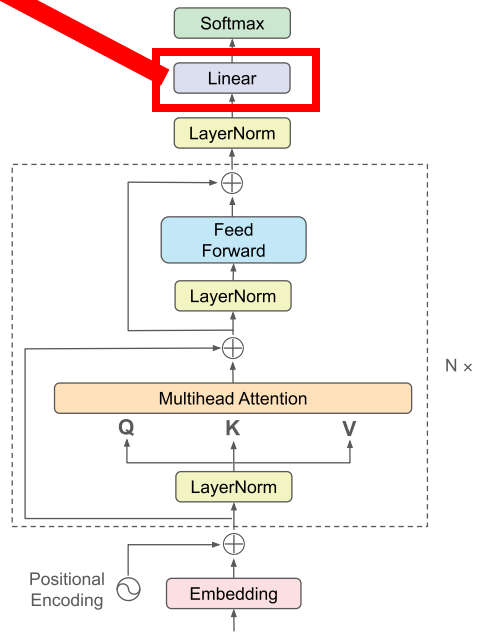
```
def matmul(A: int8[M, K],
           B: int8[K, N],
           C: int16[M, N])
```

➔ Algorithm specification (Hierarchical)

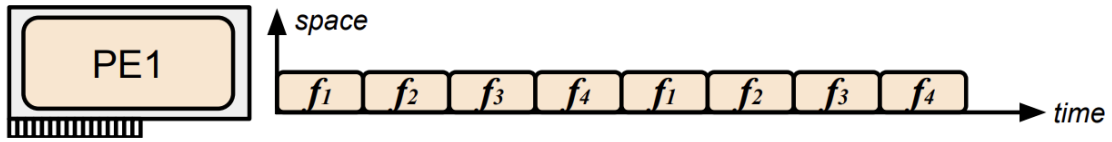
```
def top(X: int8[M, K],
        W_A: int8[K, N],
        W_B: int8[N, K]):
  Y: int8[M, N] = 0
  Z: int8[M, K] = 0
  matmul(X, W_A, Y)
  matmul(Y, W_B, Z)
  return Z
```

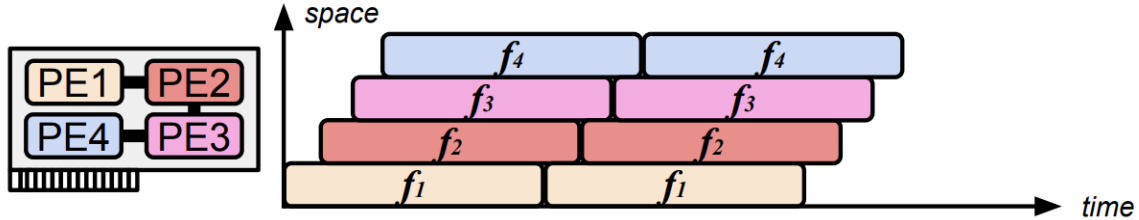
➔ Schedule composition

```
# Previous customizations for matmul
s_matmul = allo.customize(matmul)
# ...

s_top = allo.customize(top)
s_top.compose(s_matmul)
```



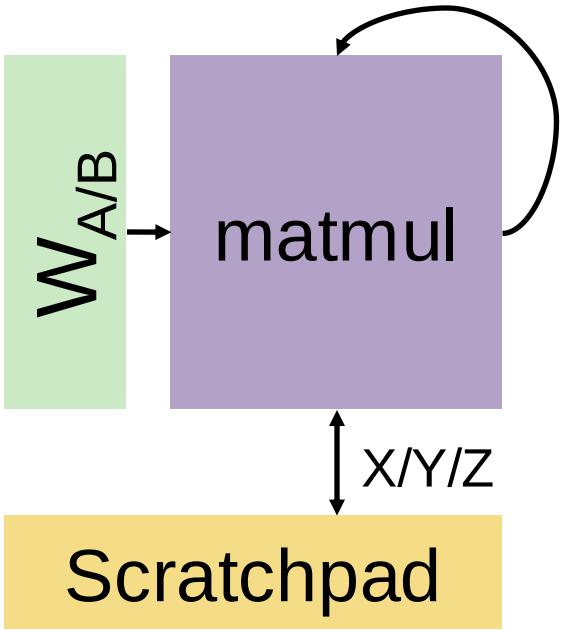
Interconnection between Kernels



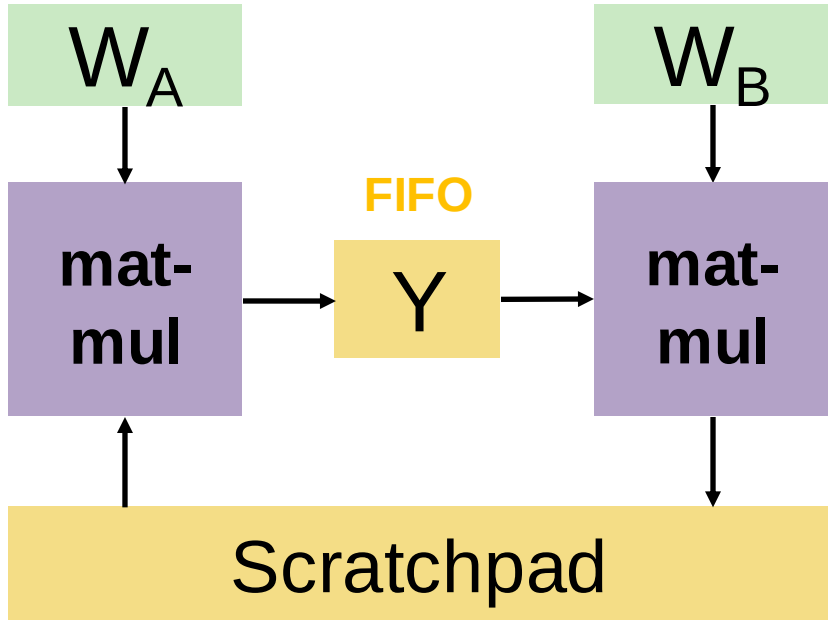


Temporal Composition

Spatial Composition



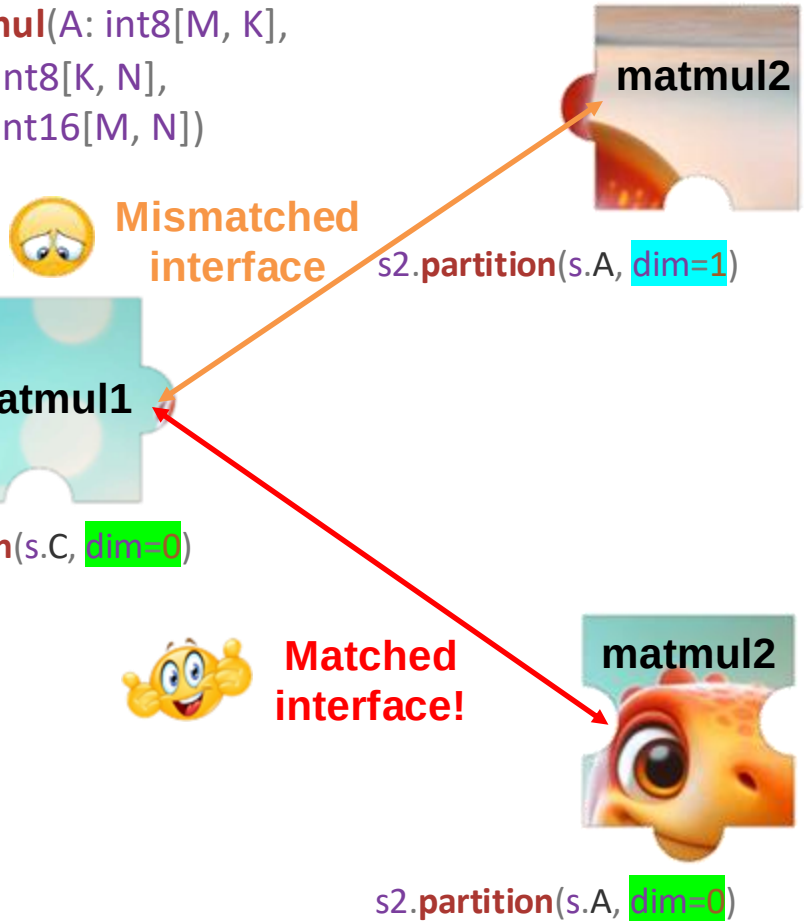

```
def top(
  X: int8[M, K],
  W_A: int8[K, N],
  W_B: int8[N, K]):
  Y: ?
  Z: int8[M, K] = 0
  matmul(X, W_A, Y)
  matmul(Y, W_B, Z)
  return Z
```



Temporal Composition

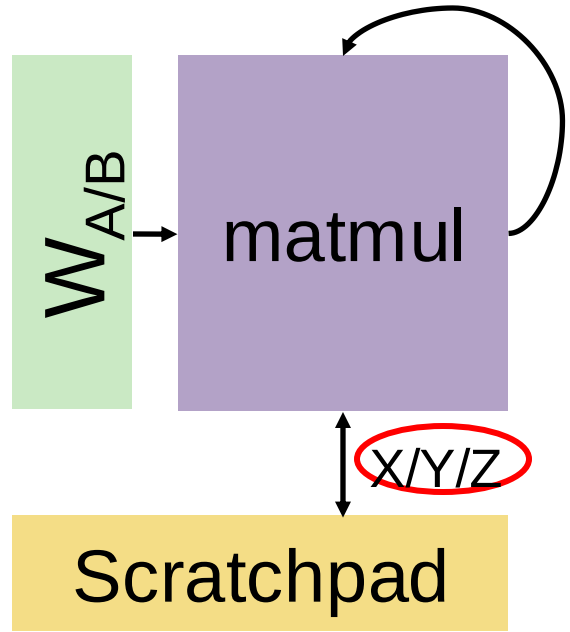
➔ **Given optimized kernel implementations**

```
def matmul(A: int8[M, K],
           B: int8[K, N],
           C: int16[M, N])
```



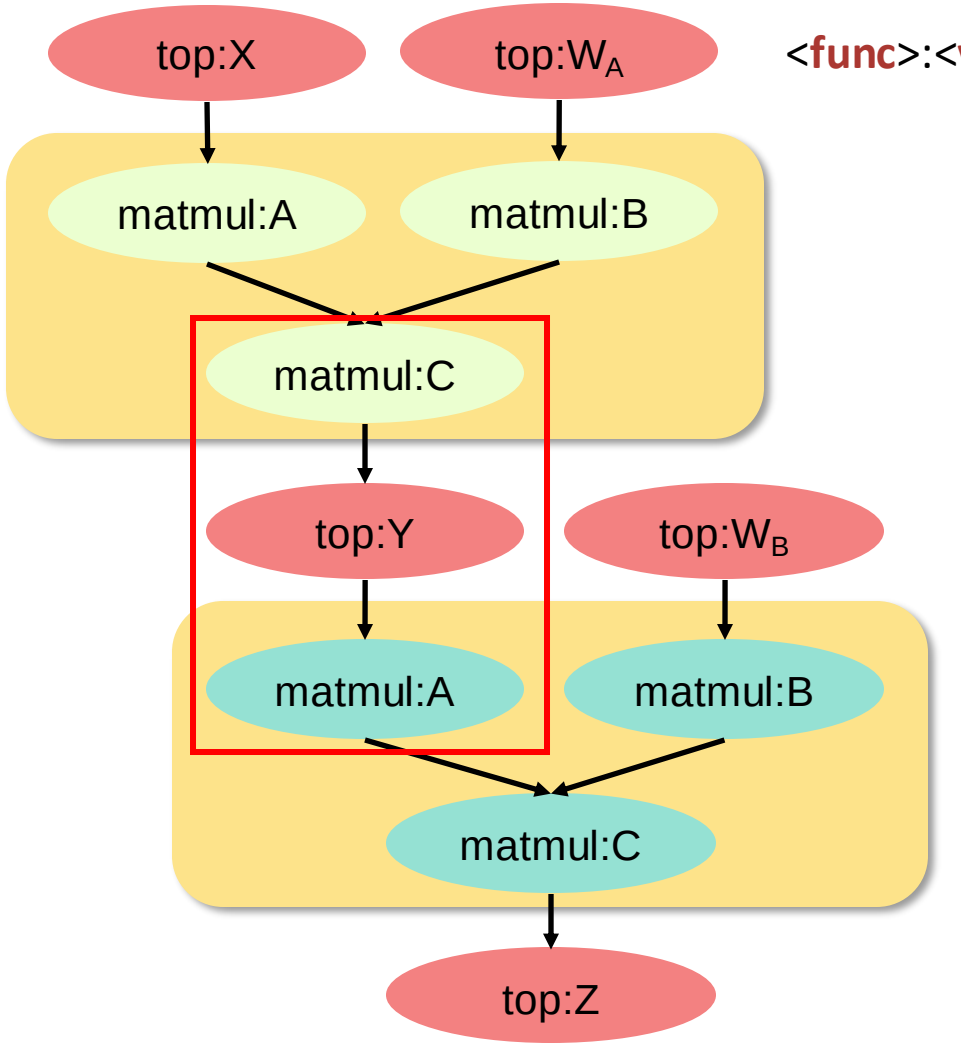
➔ **Algorithm specification (Hierarchical)**

```
def top(X: int8[M, K], W_A: int8[K, N],
        W_B: int8[N, K]):
  Y: int8[M, N] = 0
  Z: int8[M, K] = 0
  matmul(X, W_A, Y)
  matmul(Y, W_B, Z)
  return Z
```



Need to ensure interface consistency

Temporal Composition



Hierarchical use-def graph

➔ Algorithm specification (Hierarchical)

```
def top(X: int8[M, K], W_A: int8[K, N],
        W_B: int8[N, K], Y: int8[M, K]):
  Y: int8[M, N] = 0
  Z: int8[M, K] = 0
  matmul(X, W_A, Y)
  matmul(Y, W_B, Z)
  return Z
```

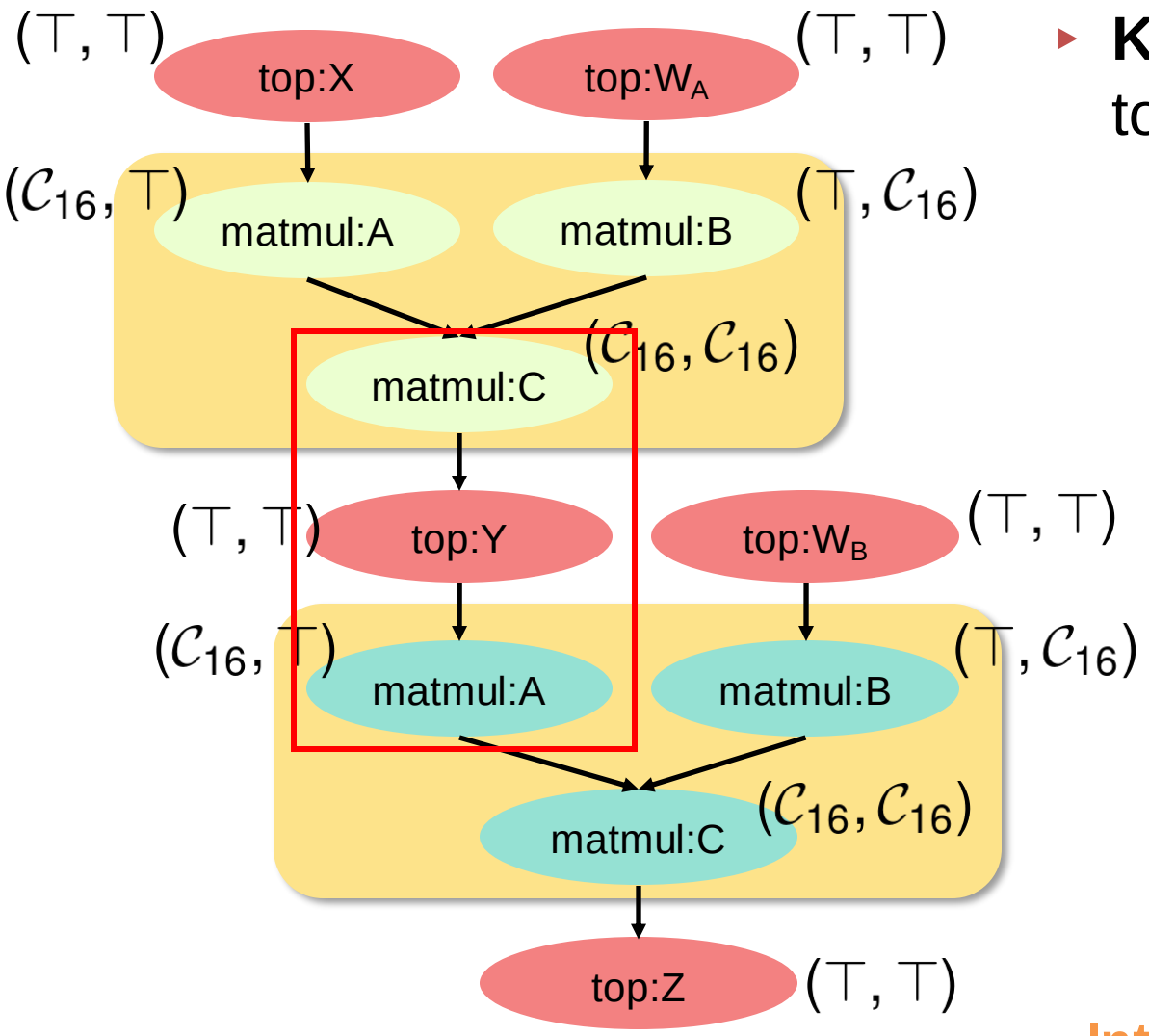
← **Caller definition**

➔ Callee definition

```
def matmul(A: int8[M, K],
           B: int8[K, N],
           C: int16[M, N])
```

Need to ensure interface consistency

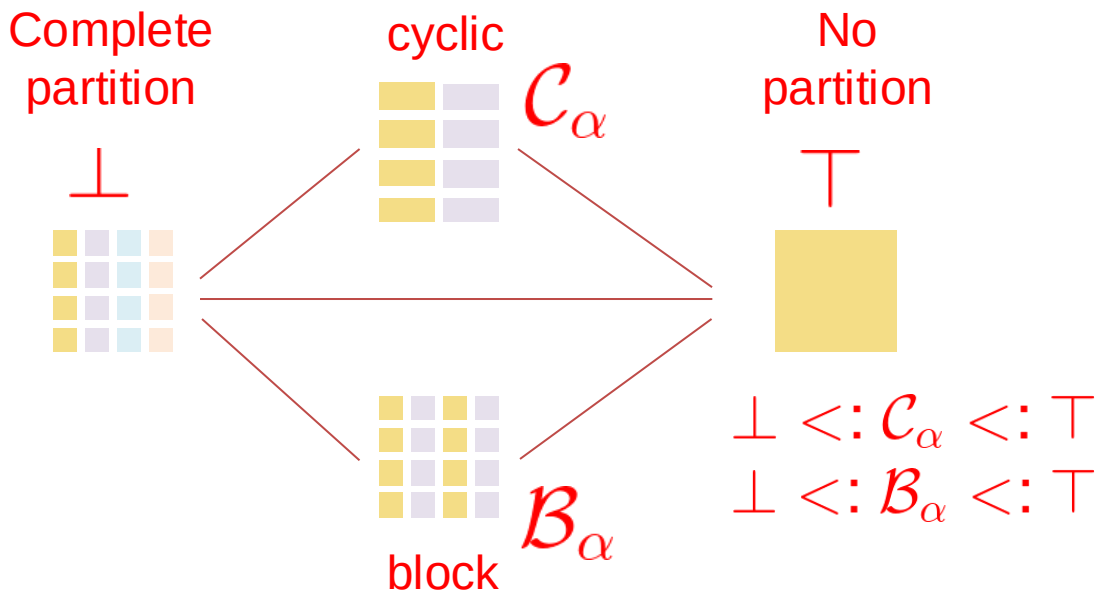
Temporal Composition



Hierarchical use-def graph

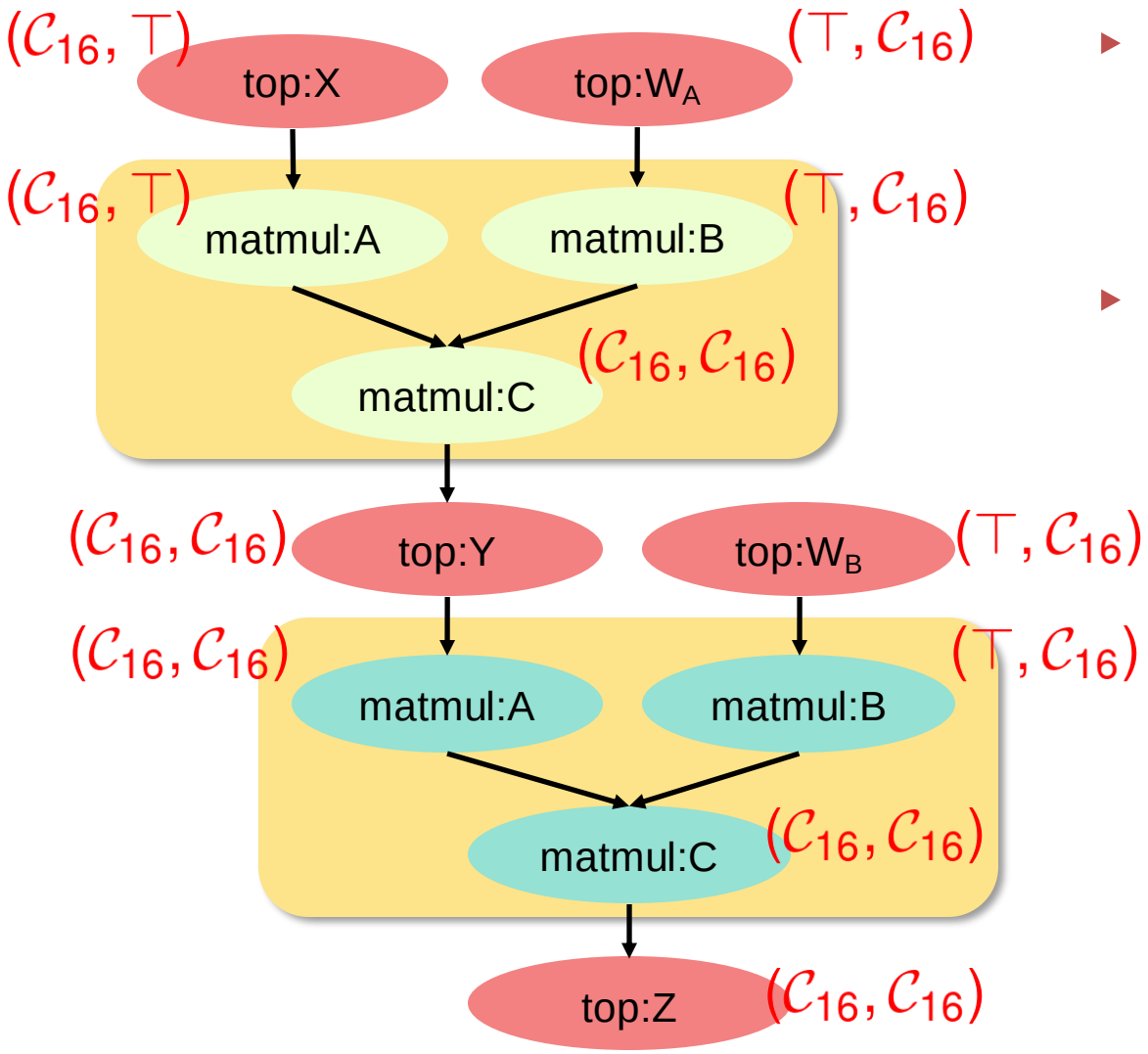
- **Key idea: Model memory banking as a type** to ensure kernel interfaces are consistent

Subtyping relation forms a **lattice**!



Intuition:
We can supply more read/write parallelism, but not less!

Temporal Composition

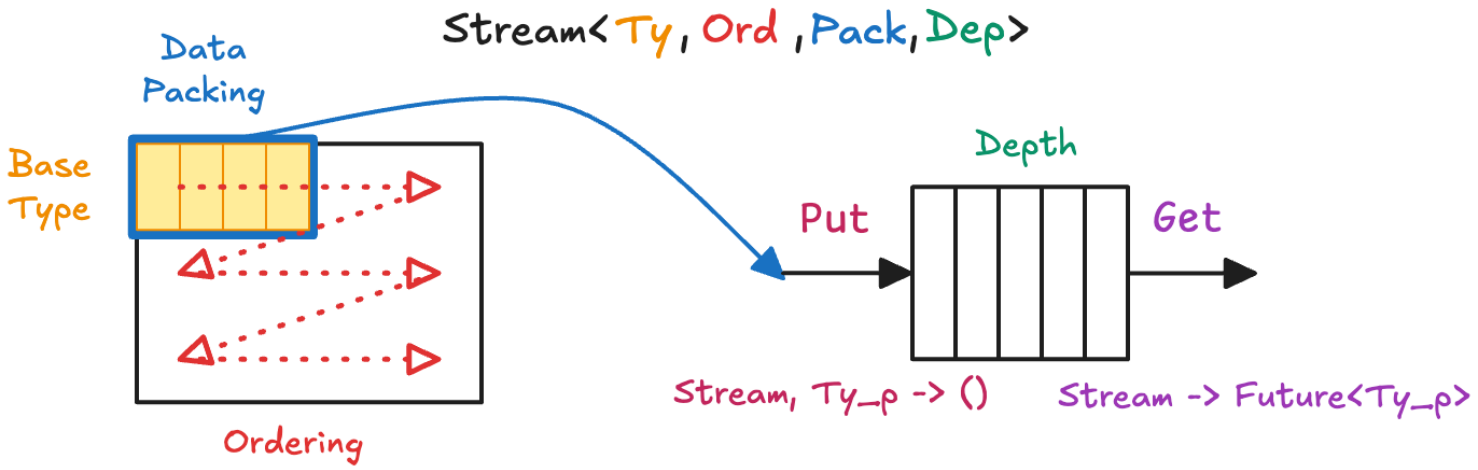


Hierarchical use-def graph

- **Key idea: Model data layout as a type** to ensure the kernel interfaces are consistent
- Lattice-based subtyping relation permits **linear-time layout inference** through Worklist algorithm

Spatial Composition

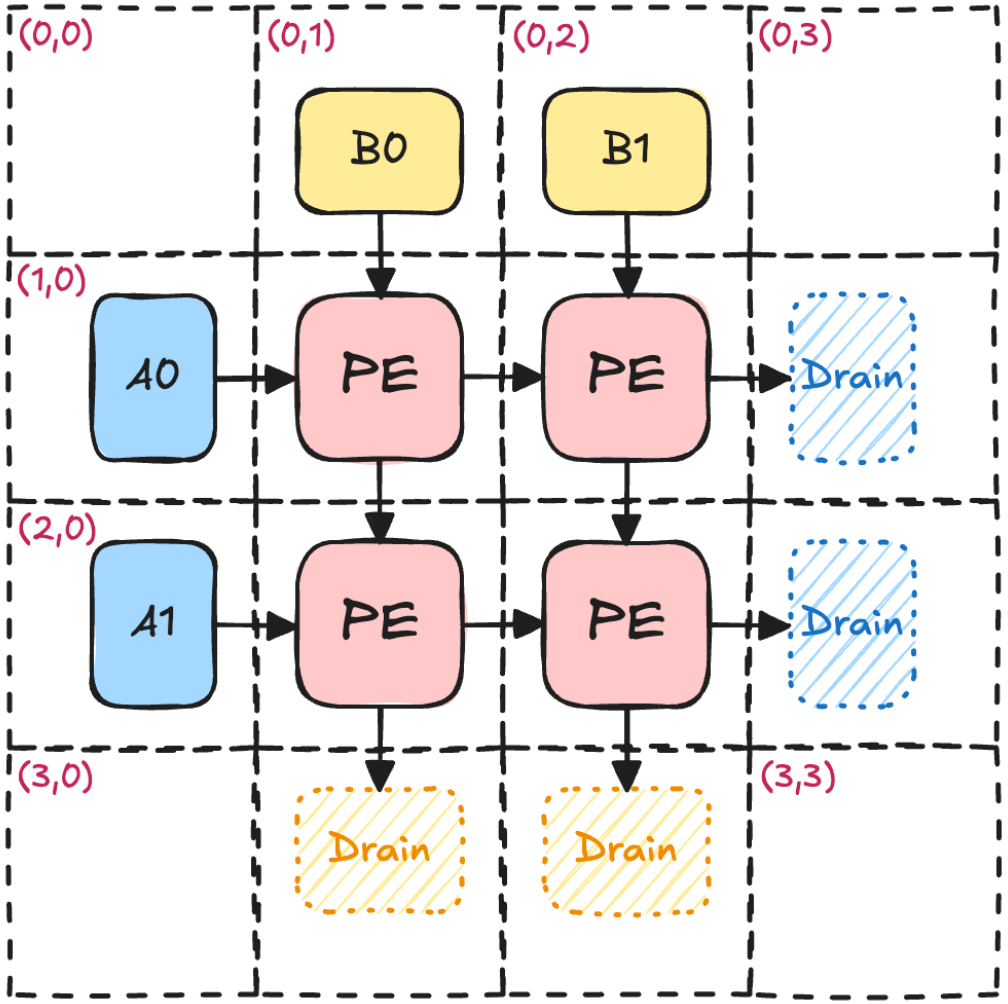
- **Model data streaming as a type**




```
@df.region
def top():
 pipe: Stream[Ty[M, N],
              "R", 1, 4]

@df.kernel(mapping=[1])
def producer(A: Ty[M, N]):
 for i, j in allo.grid(M, N):
  # send data
  pipe.put(A[i, j])

@df.kernel(mapping=[1])
def consumer(B: Ty[M, N]):
 for i, j in allo.grid(M, N):
  # receive data
  B[i, j] = pipe.get() + 1
```

Spatial Composition

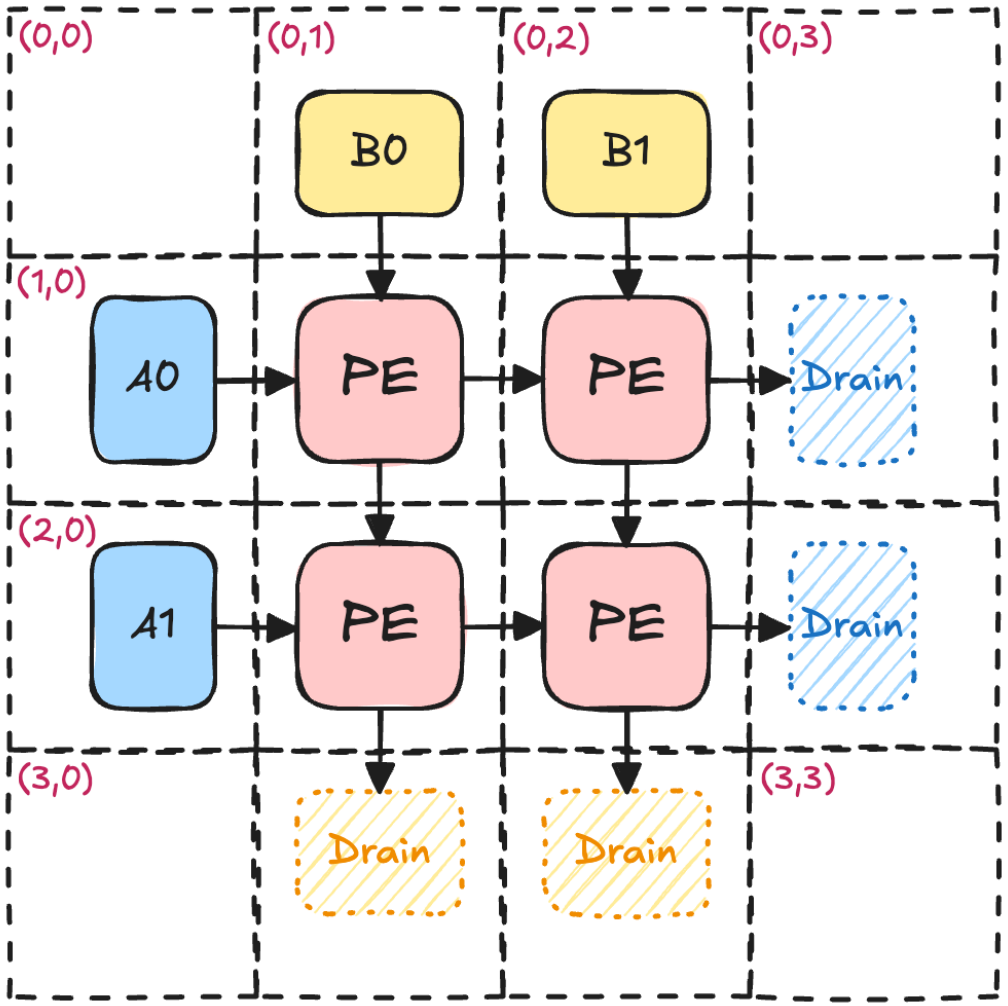
```
@df.region()
def top():
 fifo_A = df.array(df.pipe(dtype=float32, depth=4), shape=(P0, P1))
 fifo_B = df.array(df.pipe(dtype=float32, depth=4), shape=(P0, P1))

 @df.kernel(mapping=[P0, P1])
 def gemm(A: float32[M, K],
          B: float32[K, N],
          C: float32[M, N]):
  i, j = df.get_pid()
  # peripheral kernels
  with allo.meta_if(i in {0, M + 1}
              and j in {0, N + 1}):
    pass
  with allo.meta_elif(j == 0):
   # i > 0
   for k in range(K):
    fifo_A[i, j + 1].put(A[i - 1, k])
  with allo.meta_elif(i == 0):
   # j > 0
   for k in range(K):
    fifo_B[i + 1, j].put(B[k, j - 1])
```



Spatial Composition

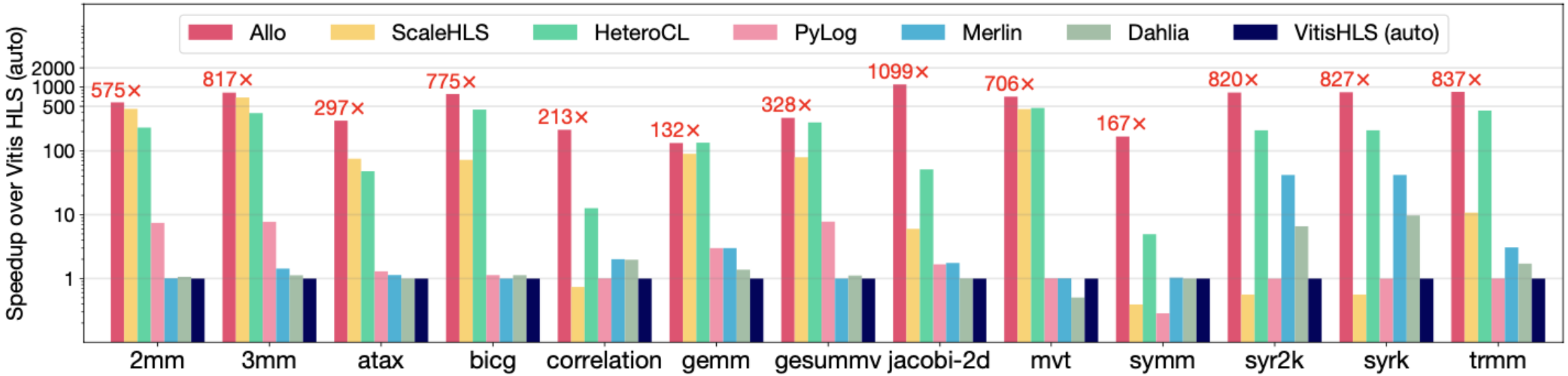
```
@df.region()
def top():
  fifo_A = df.array(df.pipe(dtype=float32, depth=4), shape=(P0, P1))
  fifo_B = df.array(df.pipe(dtype=float32, depth=4), shape=(P0, P1))
```

```
# drain
with allo.meta_elif(i == M + 1 and j > 0):
  for k in range(K):
    b: float32 = fifo_B[i, j].get()
with allo.meta_elif(j == N + 1 and i > 0):
  for k in range(K):
    a: float32 = fifo_A[i, j].get()
# main body
with allo.meta_else():
  c: float32 = 0
  for k in range(K):
    a: float32 = fifo_A[i, j].get()
    b: float32 = fifo_B[i, j].get()
    c += a * b
    fifo_A[i, j + 1].put(a)
    fifo_B[i + 1, j].put(b)
    C[i - 1, j - 1] = c
```



Single-Kernel Evaluation

- Benchmarks from PolyBench; Target hardware: AMD U280 FPGA
- Normalized against AMD VitisHLS-auto (pragmas automatically inserted)
- Other baselines
  - ADLs: HeteroCL [FPGA'19], Dahlia [PLDI'20], PyLog [TC'21]
  - Automated DSE for HLS: ScaleHLS [HPCA'22], Merlin [TRETS'22]



Allo achieves (much) higher performance by optimizing data placement with a custom memory hierarchy

Single-Kernel Evaluation

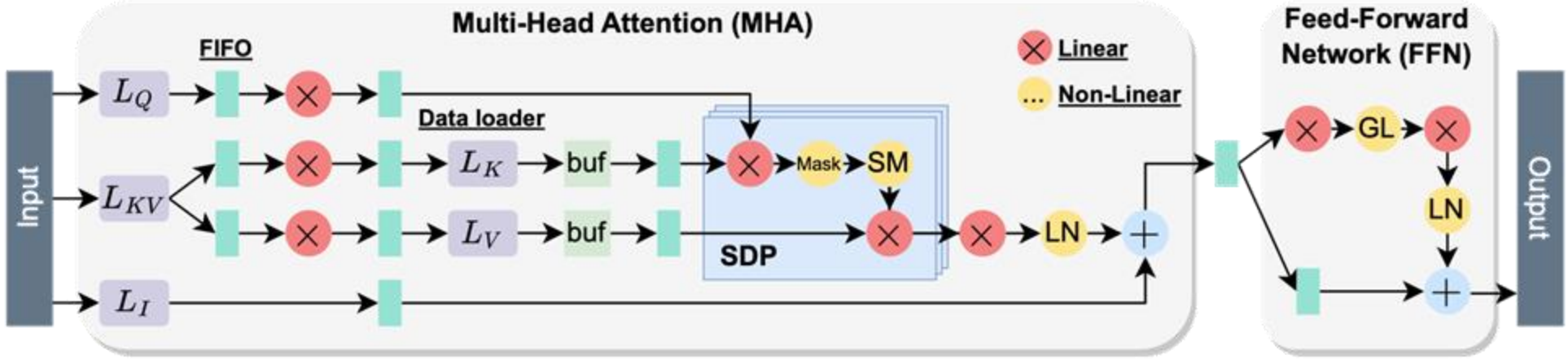
- Compared to ScaleHLS [HPCA'22], Allo achieves
  - Lower latency with much more effective use of compute resources
  - Higher post place-and-route frequency due to better pipelining

Benchmark	Allo						ScaleHLS				
	Latency (cycles)	II	DSP Usage	PnR Freq. (MHz)	Lines of Allo Custm.	Compile Time (s)	Latency (cycles)	II	DSP Usage	PnR Freq. (MHz)	Compile Time (s)
atax	4.9K (↓ 3.9×)	1	403 (↑ 2.9×)	411	9	1.0	19.4K	4	141	329	36.1
correlation	498.7K (↓ 290.5×)	1	4168 (↑ 38.2×)	362	19	0.8	144.9M	667	109	305	638.8
jacobi-2d	58.8K (↓ 183.1×)	1	3968 (↑ 72.1×)	411	17	0.9	10.8M	28	55	308	47.9
symm	405.7K (↓ 427.4×)	1	1208 (↑ 201.3×)	402	15	1.0	182.4M	13	6	397	3.5
trmm	492.6K (↓ 78.0×)	1	101 (↑ 14.4×)	414	12	0.8	38.4M	4	7	382	1.4

Allo achieves (much) higher performance by optimizing data placement with a custom memory hierarchy

Multi-Kernel Evaluation: A Complete LLM Accelerator

- GPT2 model (the only open-source LLM in the GPT family)
  - 355M parameters, 24 hidden layers, 16 heads
  - W4A8 quantization



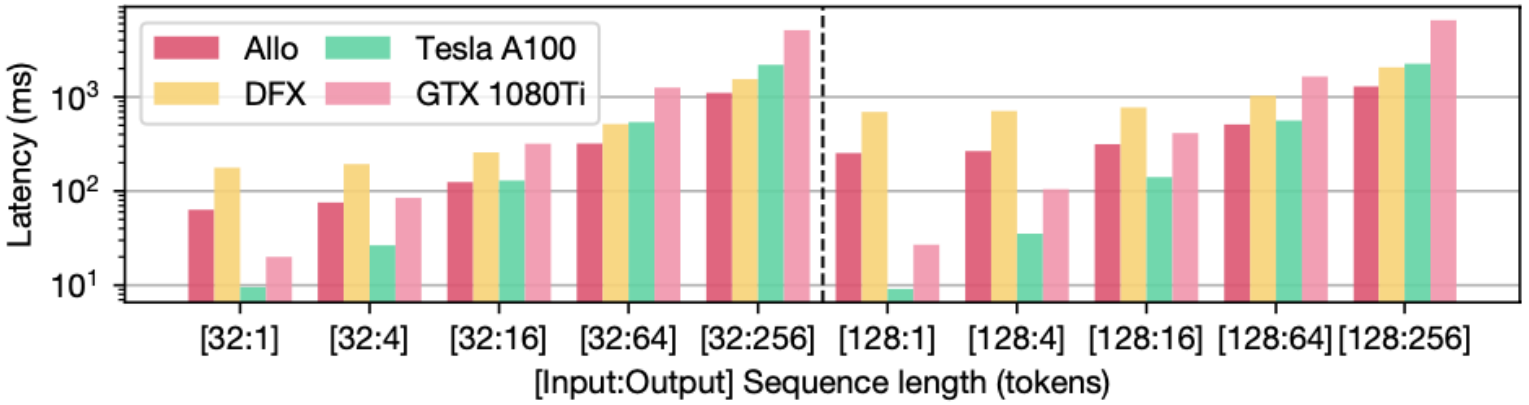

```
def GPT_layer(inp: float32[L, D], ...)
            -> float32[L, D]:
  # 1. Multi-Head Attention (MHA)
  Q = Linear_layer_qkv(inp, Wq, Bq)
  K = Linear_layer_qkv(inp, Wk, Bk)
  V = Linear_layer_qkv(inp, Wv, Bv)
  attn_sf_outp = Self_attention(Q, K, V)
  # ...
  # 2. Feed Forward Network (FFN)
  # ...
  return ffn_res_outp
```

Compose all the schedules together

```
s = allo.customize(GPT_layer)
s.compose([s_qkv, ..., s_gelu])
```

LLM Accelerator Evaluation

- GPT2: single-batch, low-latency, generative inference settings
  - AMD U280 FPGA (16nm), 250MHz
  - **2.2x speedup in prefill stage** compared to DFX [MICRO'22] (an FPGA-based overlay)
  - **1.9x speedup for long output** sequences and **5.7x more energy-efficient** vs. NVIDIA A100 GPU (7nm)
  - Fewer than 50 lines of schedule code in Allo



	Allo	DFX
Device	U280	U280
Freq.	250MHz	200MHz
Quant.	W4A8	fp16
BRAM	384 (19.0%)	1192 (59.1%)
DSP	1780 (19.73%)	3533 (39.2%)
FF	652K (25.0%)	1107K (42.5%)
LUT	508K (39.0%)	520K (39.9%)

H. Chen et al., "Understanding the Potential of FPGA-Based Spatial Acceleration for Large Language Model Inference", ACM TRETS (FCCM Journal Track), 2024.

High-Level PyTorch Frontend

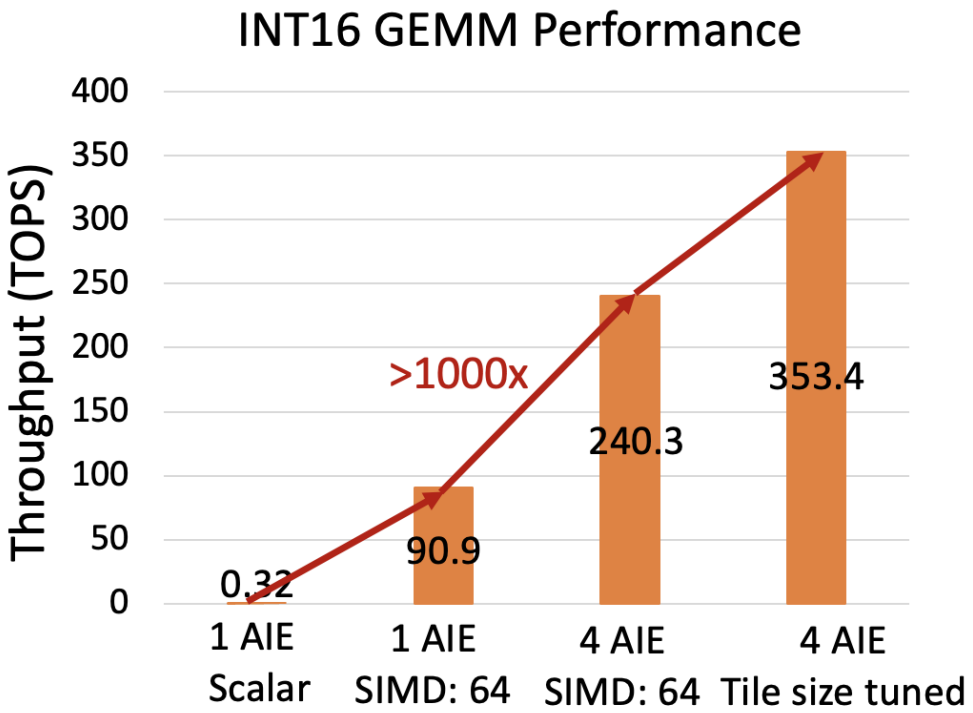
- Predefined schedules for commonly used NN operators
- Can directly import model from PyTorch and build optimized xcel design
  - Through TorchDynamo and torch.fx

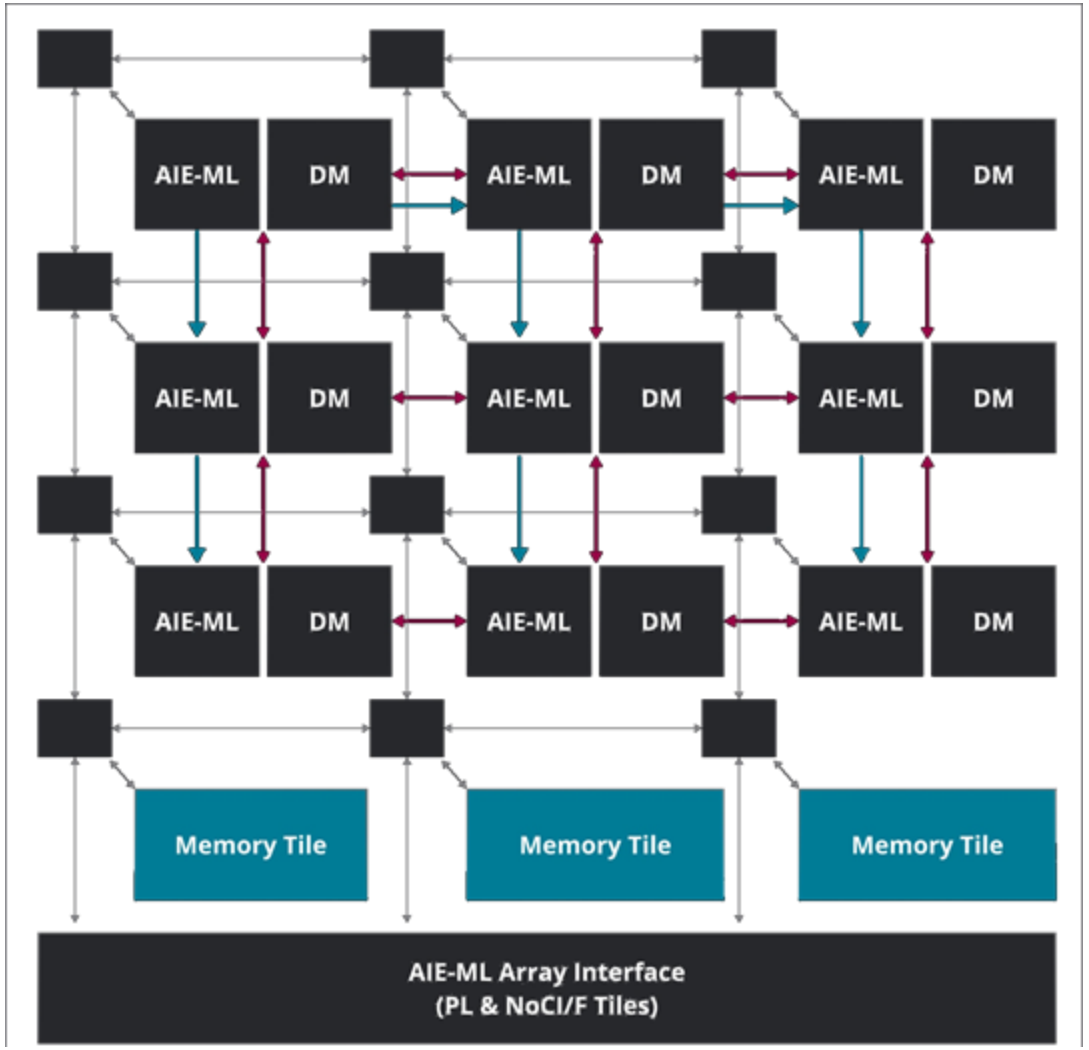
```
import torch
import allo
import numpy as np
from transformers import AutoConfig
from transformers.models.llama.modeling_llama import LlamaModel

bs, seq, hs = 1, 512, 1024

example_inputs = [torch.rand(bs, seq, hs)]
config = AutoConfig.from_pretrained("meta-llama/Meta-Llama-3-8B")
module = GPT2Model(config).eval()
mlir_mod = allo.frontend.from_pytorch(
  module,
  example_inputs=example_inputs,
)
```

Other Backends: AMD AI Engine Evaluation

- GEMM on AMD Ryzen 7940 SoC (CPU + AIE NPU)
  - Orders of magnitude improvement using the streaming interface

```
mod = df.build(target="aie")
```



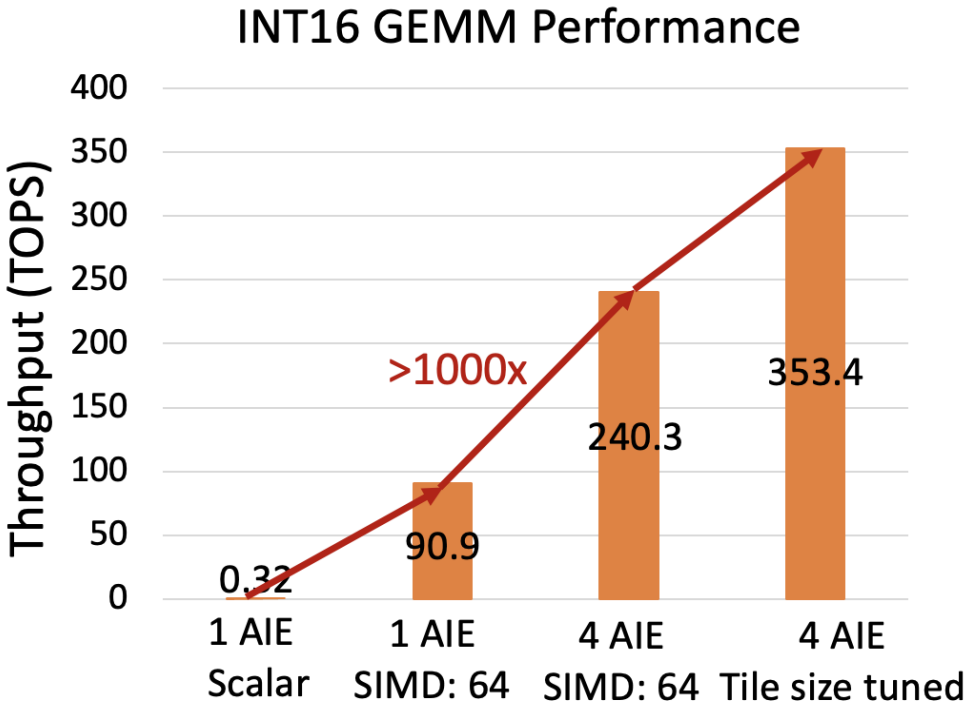


J. Zhuang et al., "An Agile MLIR-Based Compilation Flow for Reconfigurable Devices with AI Engines", FPGA, 2025.

Other Backends: AMD AI Engine Evaluation

- ResNet on on AMD Ryzen 7940 SoC (CPU + AIE NPU)
  - 23x speedup compared to AMD Riallto

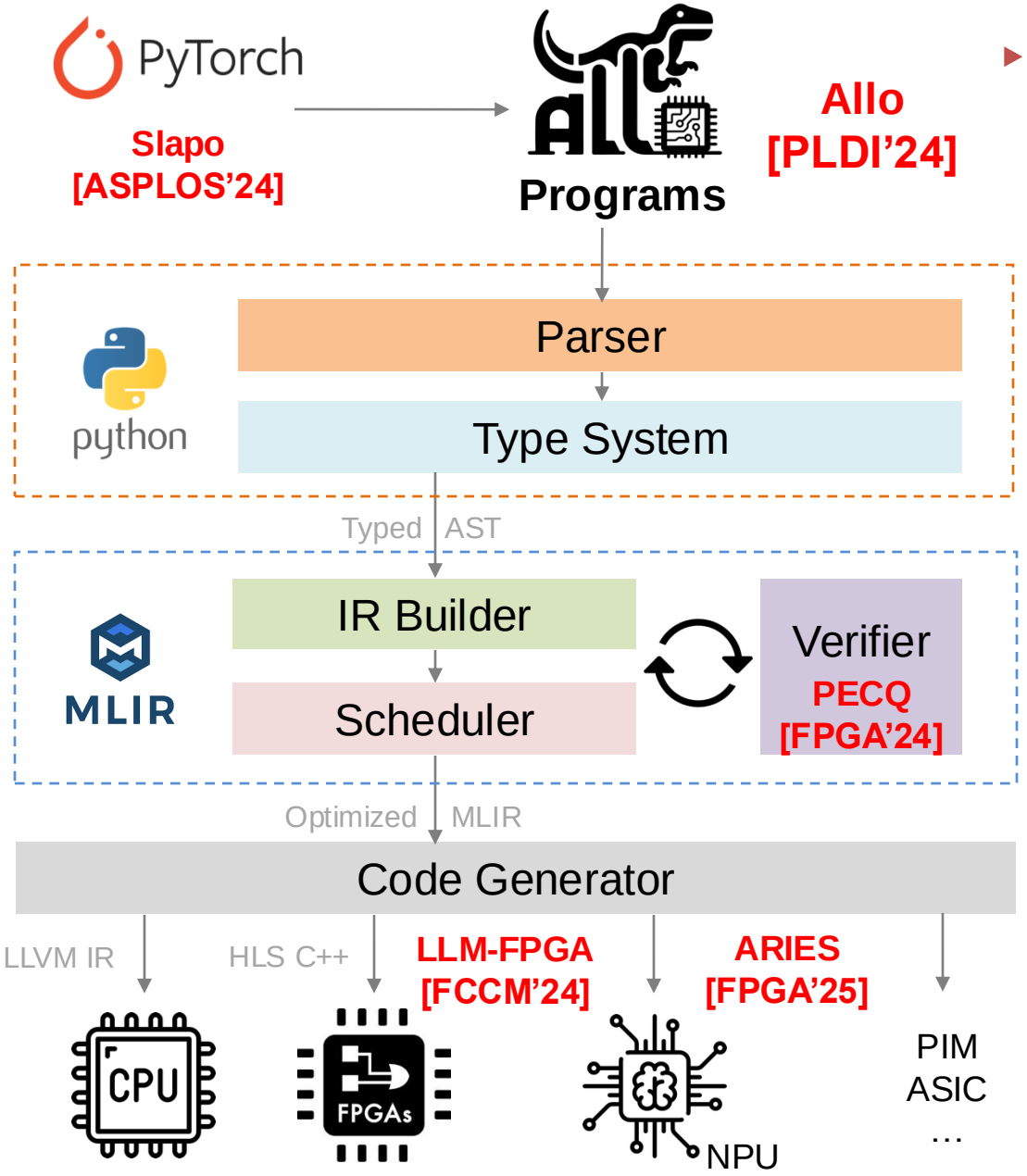
- LLaMA models being evaluated



Designs	Tile	SL	IP	Util (%)	RT (ms)	Speedup
D1 scalar	[16, 16]	1	No	15	57.40	1.24
D2 +vectorized	[16, 16]	4	No	15	16.63	4.29
D3 +vectorized	[16, 16]	8	No	15	9.82	7.27
D4 +conv3×3-2core	[16, 16]	8	No	20	9.18	7.77
D5 +inst-pipeline	[16, 16]	8	Yes	20	8.44	8.45
D6 +opt-tile-size	[32, 16]	8	Yes	20	5.72	13.70
D7 +opt-tile-size	[32, 32]	8	Yes	20	5.21	12.48
D8 +opt-tile-size	[32, 64]	8	Yes	20	4.99	14.30
D9 +more-cores	[32, 64]	8	Yes	40	3.16	22.58
Riallto / RAI-SW[20]	-	-	-	20	71.36	1x

J. Zhuang et al., “An Agile MLIR-Based Compilation Flow for Reconfigurable Devices with AI Engines”, FPGA, 2025.

Summary



- Features of Allo ADL
  - Pythonic
  - Decoupled & verifiable customizations
  - Composability

https://github.com/cornell-zhang/allo

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