```
clc
close all
velocity smoothing
% elimate a bunch of zero entries from SMA's
sma v1 = sma v1(200:length(sma v1));
sma_v2 = sma_v2(200:length(sma_v2));
sma v3 = sma v3(200:length(sma v3));
sma_v4 = sma_v4(200:length(sma_v4));
% eliminate a bunch of entries from adjusted SMA's
sma v1 adj = sma v1 adj(199:length(sma v1 adj));
sma v2 adj = sma v2 adj(199:length(sma v2 adj));
sma_v3_adj = sma_v3_adj(199:length(sma_v3_adj));
sma v4 adj = sma v4 adj(199:length(sma v4 adj));
% elimate points prior to 10 seconds for flights
noisy flight1 = noisy flight1(200:length(noisy flight1));
noisy flight2 = noisy flight2(200:length(noisy flight2));
noisy_flight3 = noisy_flight3(200:length(noisy_flight3));
noisy flight4 = noisy flight4(200:length(noisy flight4));
R = 287; % ideal gas constant of air
g0 = 9.8; % gravitational constant
a = -0.0065;
rho ref = 1.225;
T ref = 288.15;
% TIME FOR SOME DYNAMICS
t = linspace(10, 28, 1800);
%t = linspace(18.2,28,2000);
URRG = 728; % URRG start in ft
spaceport = 4595; % spaceport start in ft
starting data point = 1;
% dry masses from launches
mt122 = 91.3;
mc122 = 98.7;
mt123 = 127.5;
mc123 = 134.5;
% temperatures from launches
    % TEMP TL 22 = 292.55 K
    % TEMP CL 22 = 304.85 K
    % TEMP TL 23 = 301.25 K
    % TEMP CL 23 = 313.35 K
% adjusted Reference temperatures
T_TL22 = 300 + (292.55-295)*4;
```

```
T CL22 = 300 + (304.85-295)*4;
T TL23 = 300 + (301.25-295)*4;
T CL23 = 300 + (313.35-295)*4;
[t,x1] = ode45(@(t,X) pic(t,X,URRG,mt122,T TL22),t,
[noisy flight1(starting data point+1); sma v1 adj(starting data point)]);
[t2,x2] = ode45(@(t,X) pic(t,X,spaceport,mcl22,T CL22),t,
[noisy flight2(starting data point+1); sma v2 adj(starting data point)]);
[t3,x3] = ode45(@(t,X) pic(t,X,URRG,mtl23,T TL23),t,
[noisy flight3(starting data point+1);sma v3 adj(starting data point)]);
[t4,x4] = ode45(@(t,X) pic(t,X,spaceport,mcl23,T_CL23),t,
[noisy flight4(starting data point+1); sma v4 adj(starting data point)]);
% REPETITIVE APOGEE PREDICTION
predictions = [];
predictions2 = [];
for i = 3:length(noisy flight1)-1
    starting data point = i;
    [t,x] = ode45(@(t,X) pic(t,X,URRG,mt122,T_TL22),t,
[noisy flight1(starting data point+1); sma v1 adj(starting data point)]);
    predictions(i) = max(x(:,1));
end
for i = 3:length(noisy flight2)-1
    starting data point = i;
    [t2,x2] = ode45(@(t,X) pic(t,X,spaceport,mcl22,T CL22),t,
[noisy_flight2(starting_data_point+1);sma_v2_adj(starting_data_point)]);
    predictions2(i) = max(x2(:,1));
end
for i = 3:length(noisy flight3)-1
    starting data point = i;
    [t3,x3] = ode45(@(t,X) pic(t,X,URRG,mtl23,T TL23),t,
[noisy flight3(starting data point+1);sma v3 adj(starting data point)]);
    predictions3(i) = max(x3(:,1));
end
for i = 3:length(noisy flight4)-1
    starting data point = i;
    [t4,x4] = ode45(@(t,X) pic(t,X,spaceport,mcl23,T CL23),t,
[noisy flight4(starting data point+1);sma v4 adj(starting data point)]);
    predictions4(i) = max(x4(:,1));
end
predictions = predictions';
predictions2 = predictions2';
predictions3 = predictions3';
predictions4 = predictions4';
```

```
predictions_residuals = predictions - 10707;
predictions2 residuals = predictions2 - 10350;
predictions3 residuals = predictions3 - 12315;
predictions4 residuals = predictions4 - 10067;
count = length([predictions;predictions2;predictions3;predictions4]);
good count = 0;
for i = 1:length(predictions)
    if predictions residuals(i) < 300</pre>
        good count = good count + 1;
    end
end
for i = 1:length(predictions2)
    if predictions2 residuals(i) < 300</pre>
        good count = good count + 1;
    end
end
for i = 1:length(predictions3)
    if predictions3 residuals(i) < 300</pre>
        good count = good count + 1;
    end
end
for i = 1:length(predictions4)
    if predictions4 residuals(i) < 300</pre>
        good count = good count + 1;
    end
end
good percent = good count / count;
disp(good_percent)
figure
scatter(t(3:1799), predictions residuals(3:1799), 'b');
hold on
scatter(t2(3:1799),predictions2 residuals(3:1799),'r');
scatter(t3(3:1799),predictions3 residuals(3:1799),'g');
scatter(t4(3:1799), predictions4 residuals(3:1799), 'c');
xlabel('Time into Flight (s)', 'FontSize', 14)
ylabel('Predicted Apogee - Actual Apogee (ft)', 'FontSize',14)
title('Residuals of Predictions', 'FontSize', 20)
legend('TL 22 Residuals','CL 22 Residuals','TL 23 Residuals','CL 23
 Residuals', 'FontSize', 14)
hold off
function Xdot = pic(t, X, xstart, m, T ref)
    x = X(1);
    xdot = X(2);
    R = 287;
    %R = 85;
    g0 = 9.81;
```

```
g = 32.17; % ft/s
    a = -0.0065;
    rho ref = 1.225;
    rho ref = 1.6;
    T ref = 288.15;
    T ref = 400;
    Cd = 0.536; % coefficient of drag as predicted on open rocket
    %Cd = 0.77;
    S = pi*0.25^2; % cross sectional area of rocket in ft^2
    %S = pi*0.25^2 + (0.05*S); % cross sectional area of rocket in ft^2
    % MASSES
    % DRY MASS TL 22 = 91.3 lbm
    % DRY MASS CL 22 = 98.7 lbm
    % DRY MASS TL 23 = 127.5 1bm
    % DRY MASS CL 23 = 134.5 lbm
    % TEMPERATURES
    % TEMP TL 22 = 292.55 K
    % TEMP CL 22 = 304.85 K
    % TEMP TL 23 = 301.25 K
    % TEMP CL 23 = 313.35 K
    beta = 0.5*Cd*S;
    rho = (1/16.0185)*(\text{rho ref}*(1+(a*((x+xstart)*0.3048)/T ref)).^((-g0/
(a*R))-1)); % ft/lb^3
    altitude = x + xstart;
    %if xstart < 2000
        rho = (x+xstart)*(1.1350e-5) - 0.0274;
    %else
        rho = 0.033;
    %end
    T = 80 - 0.00649*(x+xstart);
    p = 101.29*((T+273.1)/288.08)^5.256;
    % \text{rho} = p / (0.2869*(T+273.1));
    rho = rho*(1/16.0185);
    xdoubledot = -g - beta/m*rho*xdot^2;
    Xdot = [xdot; xdoubledot];
end
```

Warning: Column headers from the file were modified to make them valid MATLAB identifiers