Using Numpy, Linear algebra functionality

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Chris Cornwell

Intro to NumPy

NumPy arrays

Linear algebra

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Getting started with NumPy

- One of the main packages for scientific computing, a must for machine learning and data science.
- ▶ Not built-in must import NumPy into Python session.

We will also want to track runtime, so we import the package time.

```
import numpy as np import time
```

Create a shortcut, ${\tt np}$, for NumPy. This is a common convention.

▶ Depending on how you are interacting with Python, may have to install the numpy package before the first use. Open a command terminal (Ctrl+`, in VSCode on Windows) and type the appropriate command below.

```
py -m pip install numpy (Windows)
python3 -m pip install numpy (macOS)
sudo pip install numpy (Linux based)
```

When installing other packages, replace numpy with the package name. After install, the import commands above should run without error.

Intro to NumPy

NumPy arrays

Linear algebra

Basic NumPy arrays

The main type of object in NumPy is the ndarray (n-dimensional array), which is constructed from a list using the command

```
np.array(the_list).
```

If items in the_list are of numeric type, then think of the resulting ndarray as like a vector. Operations on NumPy arrays work like vectors in linear algebra.

Example:

```
v = np.array([-1, 1, 1])
w = np.array([0.5, 0, 1.1])

# print the (vector) sum: [-0.5 1. 2.1]
print(v + w)
# prints [1.0, 0.0, 2.2]
print(2*w)
```

More than 1d

A NumPy array from a list containing numeric types makes a vector – also known as a 1-dimensional array (Python language), or a tensor of order 1 (mathematics).

A 2-dimensional array, or tensor of order 2, is like a matrix. You construct it with np.array() from a list of lists – each of the same length.

```
A = np.array([[1, 2, 3], [4, 5, 6]])
```

Each "inside list" is a row. The array A is a 2×3 matrix.

Every array in NumPy has an attribute shape.

- ▶ Previous slide: v = np.array([-1,1,1]) has v.shape = (3,).
- ► The matrix A: A. shape is equal to (2, 3).

Operations on arrays

Multiplying two arrays: most recent version of Python uses the @ symbol.¹ When the arrays are both matrices, it computes their matrix product; when one is a vector, it computes the matrix-vector product; when both are vectors, it computes the dot product.

For example, say that A is the matrix $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ from before, v is the vector (-1,1,1), and let B and u be the matrix and vector defined in the code below.

```
1 | B = np.array([[1, 0], [1, -1], [1, 1]])

2 | u = np.array([1, 1, 0])

3 |

4 | (A @ B, A @ v, v @ u)
```

Output is the ordered triple

```
( array([[6, 1], [15, 1]]), array([4, 7]), 0).
```

 $^{^{1}}$ In older versions, matrix multiplication is np.matmul() and dot product is np.dot().

Indexing and slicing arrays

Items in 1d array are accessed the same way as in a list

e.g., v[o] is the first item, at index o.

For a 2d array, say the matrix A, we can access the item in the row i and column j by A[i, j].

Like lists, can also use slicing with arrays. Examples:

- 1. To get first column of the matrix A, write A[: , o].2
- 2. To get top-right 2×2 submatrix of a matrix M, then use M[:2, -2:].

With arrays, can even get non-consecutive indices. For example,

A[: ,[0,2]] gives two columns that are not adjacent.

If A is a 2d array, its transpose is A.T (providing yet another alternative for accessing a column).

²Recall the use of the colon from before. It functions the same way here.

Intro to NumPy

NumPy arrays

Linear algebra

Constructing special matrices

Some types of matrices are used a lot; would be cumbersome to always write the row lists ourselves (e.g., in a 100×100 matrix).

Zero matrix: The command np.zeros((m, n)) constructs an $m \times n$ matrix with all entries equal to zero.

Diagonal matrix: If d is a 1d array of length n, the command np.diag(d) constructs an $n \times n$ diagonal matrix which has d as its diagonal entries.

Identity matrix: The command np.identity(n) (also, np.eye(n)) constructs the $n \times n$ identity matrix.

Extracting part of matrix: May want to get part of a matrix. To get a submatrix from consecutive rows and columns, use slicing. Also, here are functions that return part of the matrix (other entries being set to 0).

```
1  # return lower triangular part (at or below the diagonal)
2  np.tril(A)
3  # return upper triangular part (at or above the diagonal)
4  np.triu(A)
5  # return the diagonal of A
6  np.diag(A)
```

Using NumPy for linear algebra

In addition to the product operations on arrays, NumPy has a library (linalg) with many functions for linear algebra.

Examples:

- If M is a square matrix, can compute det(M) with the command np.linalg.det(M).
- When M is invertible, can compute M⁻¹ with the command np.linalg.inv(M).
- 3. If M is a square matrix, can compute eigenvalues and eigenvectors with np.linalg.eig(M).

There are many other linear algebra functions (see the docs here). Some are only implemented for square matrices (and perhaps only invertible ones), even though it would make sense to have them work more generally – for example, $\operatorname{np.solve}(A, b)$ only solves the system Ax = b if A is a square invertible matrix.

Solving a linear system & Errors

To solve Ax = b, with a square invertible matrix A and vector b of the right size, you can use np.linalg.solve(A, b).

What happens when ${\tt A}$ is not square? Execute the following code in Python.

```
A = np.array([[1, 2, 3], [1, 4, -1]])
b = np.array([1, -5])

# system has solution x = [0, -1, 1]
but next line raises an error

x = np.linalg.solve(A, b)
```

A message is generated about the error. It gives you helpful information, if it can. In this case, it is a LinAlgError with the message Last 2 dimensions of the array must be square.

Spend time trying to use error messages to understand issues in your code. Also, have healthy skepticism about AI assistants. They hallucinate; error messages don't.³

³While writing this slide, Github Copilot suggested I write that it would be a ValueError from *mismatched dimensions*: rows of A being size (3,) and the vector b being size (2,).

Intro to NumPy

NumPy arrays

Linear algebra

Broadcasting, universal functions

Say that you have a 1d array and you want to make array with square root the entries.

First thought: use a loop, taking square root (and assigning) as you go through items in the array.

NumPy has an efficient way to handle it, called *broadcasting*. If ν is your array, then you can simply type

```
| sqrt_v = np.sqrt(v)
```

The function np.sqrt() takes the square root of each entry in v; you don't need to write the for loop.⁴

Functions that work on arrays this way are quite common in NumPy. They are called **ufuncs** (universal functions).

Other examples of ufuncs in NumPy:

```
np.abs(), np.sum(), np.maximum(), np.minimum(), np.exp(),
np.log().
```

⁴Technically, there's a for loop in the background, but it happens in C and works much faster.

More on broadcasting

Many basic operations with NumPy arrays use broadcasting. Here are a few examples with an array \mathbf{v} .

- 1. To add the same scalar, say 3, to every array entry: type v+3.
- 2. To multiply every entry by 3: type 3*v.
- 3. To square every entry of an array: type v**2.
- 4. To multiply v by another array w, entry-wise⁵: type v*w.

Everything mentioned here works just as well on matrices (2d arrays), and generally on any nd array (higher order tensors).

Exercise.

Write out code that uses broadcasting to create a 100×100 matrix where all non-diagonal entries are -1 and all diagonal entries are 2.

⁵In mathematics, this product on vectors is called the Hadamard product.

Experiment with runtime for universal function

To check the efficiency of broadcasting, use the time package. Beforehand, make sure that you imported both numpy and time (see slide in first section).

Something simple: from a large identity matrix, we will get the exponential of the matrix (apply the function e^x to every entry). First, we use a for loop. Run the code below in your Jupyter notebook.

```
id_matrix = np.eye(1000)
exp_matrix = np.eyes(1000, 1000))
start = time.time()
for i in range(1000):
    for j in range(1000):
        exp_matrix[i,j] = np.exp(id_matrix[i,j])
end = time.time()
print(f"Seconds taken: {end-start}.")
```

The output gives the number of seconds to run the computation. The exact time will vary based on your computer. Mine took around 0.55 seconds.

Experiment with runtime for universal function

Now, we will use broadcasting to compute the exponential of the identity matrix.

Run the following code in your Jupyter notebook.

```
id_matrix = np.eye(1000)
exp_matrix = np.zeros((1000, 1000))
start = time.time()
exp_matrix = np.exp(id_matrix)
end = time.time()
print(f"Seconds taken: {end-start}.")
```

Again, the output is the number of seconds of runtime. For this approach with np.exp(), my computer took around 0.0045 seconds. That is over 100 times faster than writing the loop!