# Overview of Machine Learning

in particular, Supervised Learning

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Mar 13, 2025

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## What is Machine Learning?

#### Definition by Tom Mitchell:

A "computer program" is said to **learn** from experience E, with respect to some task T and performance measure P if: its performance on T, as measured by P, improves with experience E.

- ► The definition is intentionally general. Often, could think of *E* as "training" (updates to how program runs), based on observed data.
- "computer program," for us, means a function implemented on a computer that produces output from given input. The output is how the program achieves the task T.
- The procedures discussed in class linear regression and the Perceptron algorithm for half-space model – fit into this paradigm...kind of.

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#### Examples:

- 1. Linear regression.
  - Output of  $\hat{y}$  on input x (potentially multiple variables).
  - T: fit observed points  $\{(x_i, y_i)\}_{i=1}^n$  well with predictions  $\{(x_i, \hat{y}_i)\}_{i=1}^n$  where  $\hat{y}_i = mx_i + b$  for some m, b (an expectation of  $(x, \hat{y})$  being good fit on *unobserved* data.
  - ► F: ??
    - The data are used to get *m* and *b*, but you don't really "improve" with repeated use of data.
    - <u>Closed form</u> for best choice of m, b, computing  $(A^TA)^{-1}A^Ty$ .
  - P: Mean squared error.

Having closed form, result of simplicity of the form of  $\hat{y}_i$ .

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#### Examples:

- 2. The Perceptron algorithm.
  - ▶ Output of label  $\pm 1$  on input  $\mathbf{x} \in \mathbb{R}^d$  (or something turned into  $\mathbf{x} \in \mathbb{R}^d$ ).
  - ▶ 7: predict labels correctly, using  $W = (\mathbf{w}, b) \in \mathbb{R}^{d+1}$  to decide label,  $y = \text{sign}(\mathbf{w} \cdot \mathbf{x} + b)$  ...hopefull works on *unobserved* data.
  - E: looking through observed data  $X_i = (\mathbf{x}_i, 1)$ , label  $y_i$ , and updating  $W^{(t+1)} = W^{(t)} + v_i X_i$  when i found with  $W^{(t)} \cdot (v_i X_i) < 0$ .
  - ► P: ??

Whether its labels on all observed data are correct. But, only two results: *True* or *False*.

If data is linearly separable, enough of experience *E* improves this measure (changing to *True*). Only happens if linearly separable.

## What are the general types of tasks in machine learning?

Supervised learning: the program learns from sample data that has labels. Goal: determine underlying function from sample data.

- Housing price prediction
- Whether emails are phishing or not phishing.
- Determine if a satellite image of ocean has floating trash.
- Try to auto-complete a sentence being typed.

Unsupervised learning: there is sample data, but the data does not have any labels. Goal: discover something (a pattern, grouping, or some insight) about the data.

- Business application: Market segmentation.
- News feed (grouping similar news articles).
- Separate audio sources in a mixed signal.
- Organize computing clusters.

Reinforcement learning.

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## The goal of supervised learning

Have an "input space"  $\mathbb{R}^d$  (could be more general space) and output space, or label space, Y.

From a sample  $S = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ , with  $\mathbf{x}_i \in \mathbb{R}^d$  and  $y_i \in Y$ , drawn from an (unknown) probability distribution  $P_{X,Y} : \mathbb{R}^d \times Y \to [0, \infty)$ .

Goal is to learn, from S, a function  $f: \mathbb{R}^d \to Y$  that "fits" (approximates) well the distribution  $P_{X,Y}$ . You might not be able to have the graph of f be such that it is typically very "close" to samples from  $P_{X,Y}$ . However, ideally, for an  $\mathbf{x} \in \mathbb{R}^d$  the point on the graph is approximately the expected value, given  $\mathbf{x}$ .

## How to achieve the goal

Most often, you choose a parameterized class of functions; i.e., there is a parameter space  $\Omega$ , and an  $\omega \in \Omega$  determines a function  $f_\omega : \mathbb{R}^d \to Y$ . To learn a function that fits well, you find a set of parameters. The performance measure: **(empirical) loss function**  $\mathcal{L}_{\mathcal{S}} : \Omega \to \mathbb{R}$ . (The definition of the empirical loss function uses  $\mathcal{S}$  in its definition.)

## For linear regression

Have sample data S, with data points  $x_i$  in  $\mathbb{R}$  (so, d=1). The parameter space  $\Omega=\mathbb{R}^2=\{(\textit{m},\textit{b})\mid \textit{m}\in\mathbb{R},\textit{b}\in\mathbb{R}\}$ , and if  $\omega_0=(\textit{m}_0,\textit{b}_0)$  then

$$f_{\omega_0}(x)=m_0x+b_0.$$

Loss function, use the MSE. That is, set

$$\mathcal{L}_{\mathcal{S}}(m,b) = \frac{1}{n} \sum_{i=1}^{n} (mx_i + b - y_i)^2.$$

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## Perceptron algorithm

Suppose the data is linearly separable. Also, x is an  $n \times d$  array of points, with  $i^{th}$  row equal to  $x_i$ , and y is array of the labels. The Perceptron algorithm finds W iteratively as follows.<sup>1</sup>

<sup>&</sup>lt;sup>1</sup>Recall, in pseudo-code block, left-facing arrow means assign to variable on left.

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```
\begin{array}{l} \textbf{input:} \ x, \ y \ \#\# \ x \ is \ n \ by \ d, \ y \ is \ 1d \ array \\ X \leftarrow append \ 1 \ to \ each \ row \ of \ x \\ W \leftarrow (0,0,\ldots,0) \ \#\# \ Initial \ W \\ \textbf{while} \ (exists \ i \ with \ y[\ i\ ]*dot(W, \ X[\ i\ ]) \ \leq \ 0) \{ \\ W \leftarrow W + y[\ i\ ]*X[\ i\ ] \\ \} \\ \textbf{return} \ W \end{array}
```

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