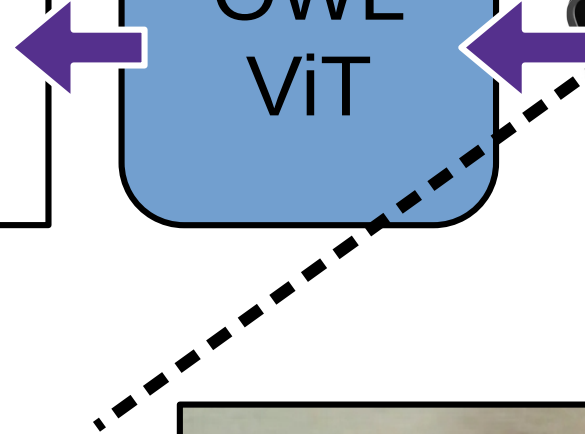


```
[ ...,  
{ Prob: {grn: 0.50, blu: 0.25, ylw: 0.25},  
  Pose: [pX, pY, pZ, rW, rX, rY, rZ],  
  Count: 4,  
  Time: 14.5 },  
... ]
```

OWL
ViT



S_{obj}

Beliefs:
Bayesian
Update

Last-Known-Good:

- Reconcile Collisions
- Filter by Score
- Update action results

S'_{obj}

Symbol Grounding:

- Reconcile Collisions
- Compute Joint P
- Filter by score
- Rank by score

PDDL
Stream

BT

