

Active Magnetic Bearing Project For a Satellite Reaction Wheel

Rafael Corsi Ferrão

José Jaime da Cruz

Escola Politécnica da Universidade de São Paulo

rafael.corsi@usp.br, jaime@lac.usp.br

Abstract.

In this paper, the development of a novel active magnetic bearing (MB) system for reaction wheels applicable in satellite attitude control. The proposed bearing has four degrees of freedom passively stable (EMB) with one pair of passive permanent magnet rings. Two degrees of freedom (AMB) are actively stabilized with eight magnetic poles. The magnetic model of both EMB and AMB are presented and the equations of force-current and force-position are analyzed by the magnetic circuit approach and by finite element method. With the force vs. current curves we present one non-linear dynamic model for the MB and a control system for it.

Keywords: Active Magnetic Bearing, Reaction Wheel, Attitude Control