

### Q1

- a. Not valid. arr\_1 is a const address of the first element of the array, so it should not be changed.
- b. Valid. arr\_2 is a pointer that can be moved by arithmetic operators.
- c. Not valid. &arr\_1 is the pointer to the whole array, i.e., the data type of the value is an array, while arr\_2 is a pointer to an int value. (In other words, &arr\_1 is a pointer to a pointer to an int, while arr\_2 is a pointer to an int – type mismatch.)  
<https://stackoverflow.com/questions/8412694/address-of-an-array>
- d. Not valid. Even though both arr\_1 and arr\_2 are address and the difference between them can be calculated, the result of arr\_2 - arr\_1 is an integer and it cannot be directly assigned to a pointer.
- e. Valid. Same as part d, the result of subtraction is an integer and can be stored as an element in the array.

### Q2

```
class Node {
public:
    int val;
    Node *next;
    Node() : val(0), next(nullptr) {}
    Node(int x) : val(x), next(nullptr) {}
    Node(int x, Node *next) : val(x), next(next) {}
};

int getLength(Node* head) //this function give out the length of the linked list
{
    int length = 0;
    Node* current = head;
    while (current != nullptr) //if the pointer is not null
    {
        length++; //count it
        current = current->next; //go to the next node
    }
    return length;
}

void shuffle(Node* head)
{
    int length = getLength(head);
    if (length <= 2) //if it is less than length of 2, return
    {
        return;
    }
}
```

```

Node* nd = head;//split the array in half
Node* prev1 = nullptr;
for(int i = 0; i < (length+1)/2; i++)//go to the middle of the linked list
{
    prev1 = nd;
    nd = nd->next;
}
prev1->next = nullptr;//split the array in half


//reverse part
Node* current = nd;
Node* next = nullptr;
Node* prev = nullptr;

while (current != nullptr)//reverse the second half of the linked list
{
    next = current->next;
    current->next = prev;
    prev = current;
    current = next;
}


Node* temp = head;
Node* head1 = head->next;
Node* tail = prev;
while (head1 != nullptr && tail != nullptr)//combine two linked list together
{
    temp->next = tail;
    tail = tail->next;
    temp = temp->next;
    temp->next = head1;
    head1 = head1->next;
    temp = temp->next;
}

if (tail != nullptr)//if there is still remain of the second linked list
{
    temp->next = tail;
}

}

```

Q3

```
class CircularQueue
{
public:
    CircularQueue(int n);
    CircularQueue(const CircularQueue& c);
    ~CircularQueue();
    void enqueue(float value);
    float dequeue();
    bool isFull();
    bool isEmpty();
    float getLast();
    float getFront();
private:
    float* arr;
    int size;
    int head_ind;
    int tail_ind;
    int count;
};
```

```
bool CircularQueue::isFull()
{
    return (count == size);
}
```

```
bool CircularQueue::isEmpty()
{
    return (count == 0);
}
```

```
float CircularQueue::getFront()
{
    return arr[head_ind];
}
```

```
float CircularQueue::getLast()
{
    return arr[tail_ind];
}
```

// Constructor

```
CircularQueue::CircularQueue(int n)
```

```
{  
    arr = new float[n];  
    size = n;  
    tail_ind = -1;  
    head_ind = 0;  
    count = 0;  
}
```

```
// Copy constructor
```

```
CircularQueue::CircularQueue(const CircularQueue& c)
```

```
{  
    arr = new float[c.size]; // Allocate new array  
    size = c.size;  
    tail_ind = c.tail_ind;  
    head_ind = c.head_ind;  
    count = c.count;  
  
    // Copy all array element values  
    for (int i = 0; i < c.size; i++)  
    {  
        arr[i] = c.arr[i];  
    }  
}
```

```
// Destructor
```

```
CircularQueue::~CircularQueue()
```

```
{  
    delete[] arr;  
}
```

```
void CircularQueue::enqueue(float value)
```

```
{  
    if (isFull())  
    {  
        throw logic_error("Cannot add to full queue");  
    }  
    else  
    {  
        ++tail_ind;  
        tail_ind = tail_ind % size;  
        arr[tail_ind] = value;  
        count++;  
    }  
}
```

```

}

float CircularQueue::deQueue()
{
    if (isEmpty()) // Prevent reading from empty queue
    {
        throw logic_error("Cannot read from empty queue");
        return 0;
    }
    else // Return the first element added
    {
        float result = arr[head_ind];
        head_ind = (head_ind + 1) % size;
        count--;
        return result;
    }
}

```

#### Q4

```

//finds factor to zero out vector element
double findFactor(double pivot_row, double under_row) {
    return (-1.0 * (under_row)) / pivot_row;
}

//multiplies a scalar with a vector
vector<double> scalarMultiply(double factor, vector<double> vec){
    for (int i = 0; i < vec.size(); i++) { // loops through vecotr changing each element
        vec[i] *= factor;
    }
    return vec;
}

//swaps two vectors in memory
void swap(vector<double>& actual_pivot_row, vector<double>& row_with_pivot) {
    vector<double> temp = actual_pivot_row; //take the original pivot row and store it
    actual_pivot_row = row_with_pivot; //swap it with the row that actually can be pivot row
    row_with_pivot = temp;
}

//adds 2 vectors
vector<double> add(vector<double> actual_pivot_row, vector<double> under_rows) {
    for (int i = 0; i < actual_pivot_row.size(); i++) { // loops through vector adding each
        element to eachother
        under_rows[i] += actual_pivot_row[i];
    }
}

```

```

    }
    return under_rows;
}

```

```

bool isInvertible(vector< vector<double> >& mat) {

    int columns = mat.size();

    if (columns == 0) { return false; } //checking the 0 case

    //checking to make sure its a square matrix
    for (int i = 0; i < columns; i++) {
        if (mat[i].size() != columns) {
            return false;
        }
    }
    int rows = mat.size();
    //Pseudo Gaussian elimination function
    for (int pivot = 0; pivot < columns; pivot++) {

        for (int under_row = pivot; under_row < columns; under_row++) {
            if (mat[under_row][pivot] != 0) { //if we found we with a nonzero pivot, we
swap it to the beginning
                swap(mat[pivot], mat[under_row]);

                for (int k = pivot+1; k < rows; k++) { //go through each row and
make it 0]
                    if (mat[k][pivot] == 0) { continue; } //if row already has a
zero, nothing to do
                        mat[pivot] = scalarMultiply(findFactor(mat[pivot][pivot],
mat[k][pivot]), mat[pivot]); //reference function descriptions
                            mat[k] = add(mat[pivot], mat[k]); //If row did not have a
zero, we follow through the gaussian algorithm 4and make a zero
                                }
                                    break;
                                        }
                                            else if (under_row == rows - 1) { //means its gone through every row and
couldning find a nonzero one to switch
                                                return false;
                                                    }
                                                        }
                                                            }
                                                                }
                                                                    return true; //finally returns true after the elimination and the diagonal numbers are all
nonzero

```

}