EEL 4837Programming for Electrical Engineers II

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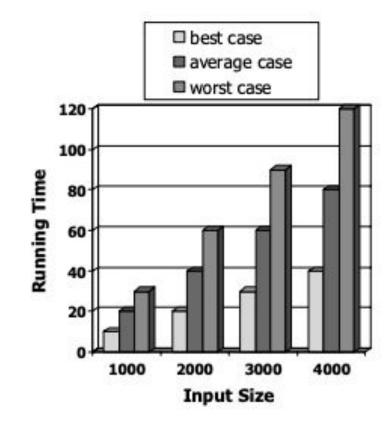
Time complexity and Big-Oh notation

Readings:

- Weiss chapter 2
- Horowitz 1.3

Program running time

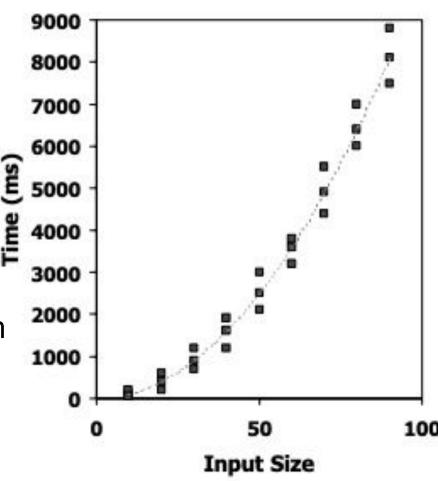
- Most algorithms transform input objects into output objects.
- The running time of an algorithm typically grows with the input size.



- Generally difficult to measure average case
- We typically focus on worst-case analysis (particularly critical for applications like automotive, hardware design, games, etc.)

Measuring program running time

- Write a program.
- Run the program with inputs of varying size.
- "Accurately" measure the running time (e.g., using Unix commands to get wall clock time, user time, system time, kernel time, etc.)
- Plot the results
- May not be indicative of the behavior of the program on other inputs
 - Relies too much on the hardware specifics
- In order to compare two algorithms we have to use same hardware/software environments



Pseudocode

- High-level description of algorithm
- More structured than English prose
- Less detailed than program code
- Preferred notation for describing algorithms
- Hides programming syntax

Example: find max element of an array

Algorithm arrayMax(A, n)
Input array A of n integers
Output maximum element of A

 $currentMax \leftarrow A[0]$ for $i \leftarrow 1$ to n-1 do if A[i] > currentMax then $currentMax \leftarrow A[i]$ return currentMax

Primitive operations

- Basic computations performed by algorithm
- Identifiable in pseudocode
- Largely independent of programming language
- Assumed to take constant time to compute

- Evaluating an expression
- Assigning a value to a variable
- Indexing into an array
- Calling a method
- Returning from a method

Primitive Operations

By inspecting the pseudocode, we determine the maximum number of primitive operations executed by an algorithm, as a function of input size

```
Algorithm arrayMax(A, n)
                                                             a = Time taken by the fastest primitive operation
                                    # operations
  currentMax \leftarrow A[0]
                                                             b = Time taken by the slowest primitive operation
  for i \leftarrow 1 to n-1 do
                                        2(n-1)
      if A[i] > currentMax then
             currentMax \leftarrow A[i]
                                       2(n-1)
                                                       Let T(n) be worst-case time of arrayMax. Then
  { increment counter i }
                                        2(n-1)
                                                                    a (8n-3) \le T(n) \le b(8n-3)
  return currentMax
                                                      "worst-case" in terms of operation counts, not time
                                 Total 8n - 3
```

Linear growth of T(n) is an intrinsic property of algorithm arrayMax. Changing hardware or software will not change this property.

Big-Oh Notation

f(n) = O(g(n)) means there are positive constants c and n_0 , such that $0 \le f(n) \le cg(n)$ for all $n \ge n_0$. The values of c and n_0 must be fixed for the function f and must not depend on n.

Example: 2n + 10 is O(n)

- $2n + 10 \le cn$
- (c-2) n ≥ 10
- $n \ge 10/(c-2)$
- Pick c = 3 and $n_0 = 10$

Example: the function n^2 is not O(n)

- $n^2 \le cn$
- $n \le c$
- The above inequality cannot be satisfied since c must be a constant

Big-Oh Examples

f(n) = O(g(n)) means there are positive constants c and n_0 , such that $0 \le f(n) \le cg(n)$ for all $n \ge n_0$. The values of c and n_0 must be fixed for the function f and must not depend on n.

```
♦ 7n-2
```

```
7n-2 is O(n) need \ c>0 \ and \ n_0\geq 1 \ such \ that \ 7n-2\leq c\bullet n \ for \ n\geq n_0 this is true for c=7 and n_0=1
```

■ $3n^3 + 20n^2 + 5$ $3n^3 + 20n^2 + 5$ is $O(n^3)$ need c > 0 and $n_0 \ge 1$ such that $3n^3 + 20n^2 + 5 \le c \cdot n^3$ for $n \ge n_0$ this is true for c = 4 and $n_0 = 21$

■ 3 log n + 5

```
3 \log n + 5 \text{ is } O(\log n)
need c > 0 and n_0 \ge 1 such that 3 \log n + 5 \le c \cdot \log n for n \ge n_0
this is true for c = 8 and n_0 = 2
```

Some Rules

- If is f(n) a polynomial of degree d, then f(n) is $O(n^d)$, i.e.,
 - 1. Drop lower-order terms
 - Drop constant factors
- Use the smallest possible class of functions
 - Say "2n is O(n)" instead of "2n is O(n²)"
- Use the simplest expression of the class
 - Say "3n + 5 is O(n)'' instead of "3n + 5 is O(3n)''

Big-Oh and Growth Rate

- Big-Oh gives an upper bound on the growth rate of a function
- The statement ``f(n) is O(g(n))'' means that the growth rate of f(n) is no more than the growth rate of g(n)
- We can use Big-Oh to rank functions according to their growth rates

Math you should review

- Seven functions that often appear in algorithm analysis:
 - Constant ≈ 1
 - Logarithmic ≈ log n
 - Linear ≈ n
 - N-Log-N ≈ n log n
 - Quadratic ≈ n²
 - Cubic ≈ n³
 - Exponential ≈ 2ⁿ

- Summations
- Logarithms and Exponents
 - properties of logarithms:

$$log_b(xy) = log_bx + log_by$$

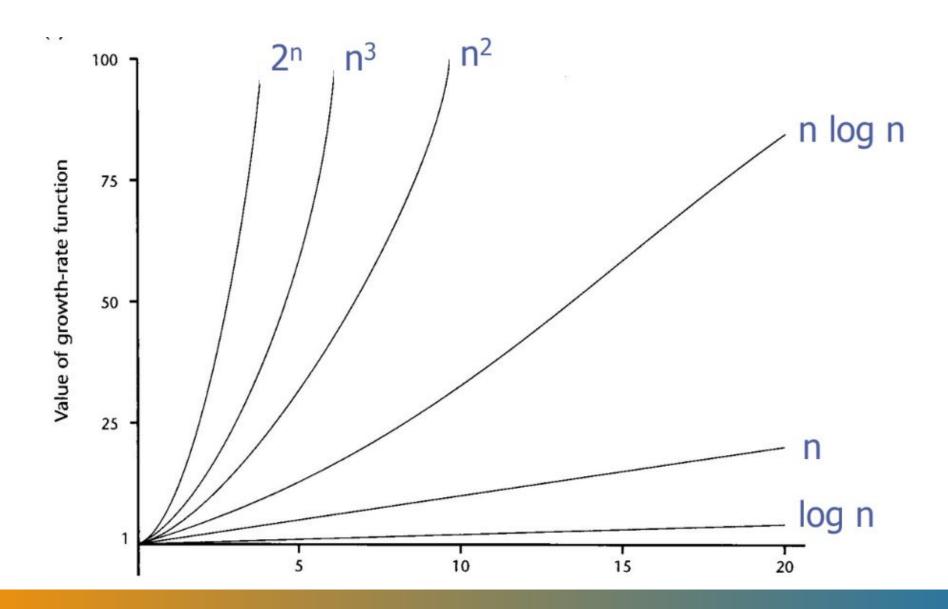
 $log_b(x/y) = log_bx - log_by$
 $log_bx^a = alog_bx$
 $log_ba = log_xa/log_xb$

properties of exponentials:

$$a^{(b+c)} = a^b a^c$$

 $a^{bc} = (a^b)^c$
 $a^b / a^c = a^{(b-c)}$
 $b = a^{\log_a b}$
 $b^c = a^{c*\log_a b}$

Growth rates



Big-Oh and Asymptotic Analysis

- The asymptotic analysis of an algorithm determines the running time in big-Oh notation
- To perform the asymptotic analysis
 - We find the worst-case number of primitive operations executed as a function of the input size
 - We express this function with big-Oh notation

Essentially, this analysis seeks the **smallest**, **most minimal** function g(n) such that the T(n) = O(g(n))

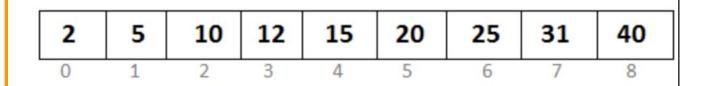
Example:

- We determine that algorithm arrayMax executes at most 8n - 2 primitive operations
- We say that algorithm arrayMax "runs in O(n) time"
- Since constant factors and lower-order terms are eventually dropped anyhow, we can disregard them when counting primitive operations

Algorithm Example: Linear Search

```
int lSearch(int arr[], int n, int x)
                                                     contiguous memory locations
   int i;
                                                   208 212 216 220 224 228 232 236 240 244
                                               204
   for (i = 0; i < n; i++)
       if (arr[i] == x)
                                                    17
                                                        89
                                                                  90
                                                                                  23
                                                                                      43
                                                                                          99
           return i;
                                                        3
                                                             4
   return -1:
                                                    Index
int main()
                                           Is the number 26 in the array?
   int arr[] = { 3, 4, 1, 7, 5 };
                                            Time complexity: O(n)
   int n = 5;
   int x = 4;
   int index = 1Search(arr, n, x);
   if (index == -1)
       cout << "Element is not present in the array" << endl;</pre>
   else
       cout << "Element found at position " << index << endl;</pre>
    return 0;
```

Searching a Sorted Array



Is the number 26 in the array?

```
int binarySearch(int arr[], int left, int right, int x) {
   while (left <= right) {
     int mid = left + (right - left) / 2;
     if (arr[mid] == x) return mid;
     else if (arr[mid] < x) left = mid + 1;
     else right = mid - 1;
   }
   return -1;
}</pre>

• Number of halved in
   o After k
   consider

Algorithm
```

- Number of array indices considered is halved in each iteration
 - After k iterations, the number of indices considered will be n/2^k
- Algorithm stops when indices run out: $n/2^k \le 1$
- So we choose the *smallest* k such that $n/2^k = 1$

$$\circ$$
 n = 2^k

$$\circ$$
 k = O(log n)

Is binary search a more efficient algorithm than linear search?

Relatives of Big-Oh

big-Omega

f(n) is Ω(g(n)) if there is a constant c > 0 and an integer constant n₀ ≥ 1 such that f(n) ≥ c•g(n) for n ≥ n₀

big-Theta

f(n) is Θ(g(n)) if there are constants c' > 0 and c"
 o and an integer constant n₀ ≥ 1 such that c'•g(n) ≤ f(n) ≤ c"•g(n) for n ≥ n₀

Example Uses of Ω and θ

■ $5n^2$ is $\Omega(n^2)$

```
f(n) is \Omega(g(n)) if there is a constant c > 0 and an integer constant n_0 \ge 1 such that f(n) \ge c \cdot g(n) for n \ge n_0
let c = 5 and n_0 = 1
```

\blacksquare 5n² is $\Omega(n)$

```
f(n) is \Omega(g(n)) if there is a constant c > 0 and an integer constant n_0 \ge 1 such that f(n) \ge c \cdot g(n) for n \ge n_0
let c = 1 and n_0 = 1
```

■ $5n^2$ is $\Theta(n^2)$

```
f(n) is \Theta(g(n)) if it is \Omega(n^2) and O(n^2). We have already seen the former, for the latter recall that f(n) is O(g(n)) if there is a constant c > 0 and an integer constant n_0 \ge 1 such that f(n) \le c \cdot g(n) for n \ge n_0. Let c = 5 and n_0 = 1
```

Space complexity

- The amount of extra space the program needs
 - Can be in abstract "memory units" or bytes
- Same ideas as with the time complexity:
 - Typically focus on the worst-case scenario
 - Count the required memory
 - Use the Big-O notation to express the complexity class
- Example:
 - Function dedup(int[] arr, int n) removes duplicates
 - It allocates another array of size n to store the results
 - Its space complexity: O(n)

Abstract data type: Stack

Readings:

- Weiss 3.6
- Horowitz 2.1

Why So Many Data Structures?

Ideal data structure:

fast, elegant, memory efficient

Generates tensions:

- time vs. space
- performance vs. elegance
- generality vs. simplicity
- one operation's performance
 vs. another's

A **dictionary** is implementable with:

- array
- list
- binary search tree
- AVL tree
- Splay tree
- Red-Black tree
- hash table

How Should We Learn Data Structures?

- Present a data structure
- Motivate with some applications
- Repeat until browned entirely through
 - o develop a way to implement the data structure
 - analyze its properties
 - efficiency
 - correctness
 - limitations
 - ease of programming
- Contrast data structure's strengths and weaknesses
 - o understand when to use each one

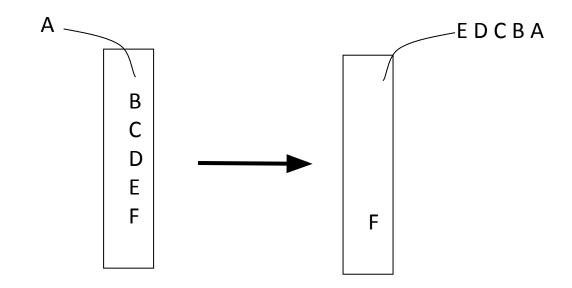
Abstract data types

- Idea: define a data structure by specifying what functions it supports
- Separates the interface from the implementation
 - Implementation details are hidden
 - The "client" code can be used with any implementation

An **abstract data type** is a mathematical representation of a data structure with a *set of values* and a *set of operations* supported by these values

Stack

- Stack operations
 - create
 - destroy
 - o push
 - o pop
 - is_empty
 - Is_full (???)



• Stack property – LIFO (Last In First Out): if x is on the stack before y is pushed, then x will be popped after y is popped

Implementing a Stack with arrays

- A simple way of implementing the Stack ADT uses an array
- We add elements from left to right
- A variable keeps track of the index of the top element



Stack Implementation

```
#define SIZE 5
using namespace std;
class STACK
    private:
        int num[SIZE];
        int top;
    public:
        STACK();
        int push(int);
        int pop();
        int isEmpty();
        int isFull();
};
```

```
int STACK::isEmpty() {
    if(top==-1)
        return 1;
    else
        return 0;
}

int STACK::isFull() {
    if(top==(SIZE-1))
        return 1;
    else
        return 0;
}
```

```
int STACK::push(int n){
    //check stack is full or not
    if(isFull()){
        return 0;
    ++top;
    num[top]=n;
    return n;
int STACK::pop(){
    //to store and print which number
    //is deleted
    int temp;
    //check for empty
    if(isEmpty())
        return 0;
    temp=num[top];
    --top;
    return temp;
```

Performance and Limitations

Performance

- Let n be the number of elements in the stack
- The space used is O(n)
- Each operation runs in time O(1)

Limitations

- The maximum size of the stack must be defined a priori and cannot be changed
- Trying to push a new element into a full stack causes an implementation-specific exception

Evaluating (infix) Expressions

```
(1+((2+3)*(4*5)))
```

Two-stack algorithm. [E. W. Dijkstra]

- Value: push onto the value stack.
- Operator: push onto the operator stack.
- Left parenthesis: ignore.
- Right parenthesis: pop operator and two values; push the result of applying that operator to those values onto the operand stack.

Exercise: Implement this algorithm in C++

```
(1+((2+3)*(4*5)))
 +((2+3)*(4*5)))
 ((2+3)*(4*5)))
+3)*(4*5)))
3)*(4*5)))
) * (4 * 5 ) ) )
* (4 * 5 ) ) )
(4*5)))
* 5 ) ) )
 5)))
)))
- ))
```

Postfix Expressions

- Postfix notation is another way of writing arithmetic expressions
- In postfix notation, the operator is written after the two operands

```
infix: 2+5 postfix: 25+
infix (3+ ((4+5)*2)) postfix: 345+2*+
```

- Expressions are evaluated from left to right
 - Pushing operands into a stack
 - Pop and execute operations
- Precedence rules and parentheses are never needed!

Exercises:

- 1. Convert a (fully parenthesized) infix expression to postfix
- 2. Evaluate a postfix expression