

Recommender Systems: Advanced

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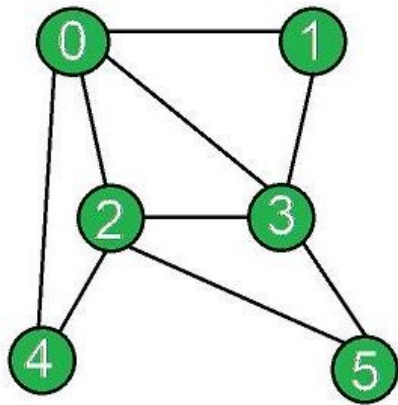


Outline

1. **Graph-based recommendation**
2. Graph neural networks
3. Neural graph collaborative filtering
4. Summary

Graphs

- Data structure that represents connections and relationships.
 - A graph consists of **nodes** (e.g., users) and **edges** (e.g., friendship).
 - A graph is represented as a **sparse adjacency matrix**.
 - $a_{ij} = 1$ if nodes i and j are connected; $a_{ij} = 0$ otherwise.



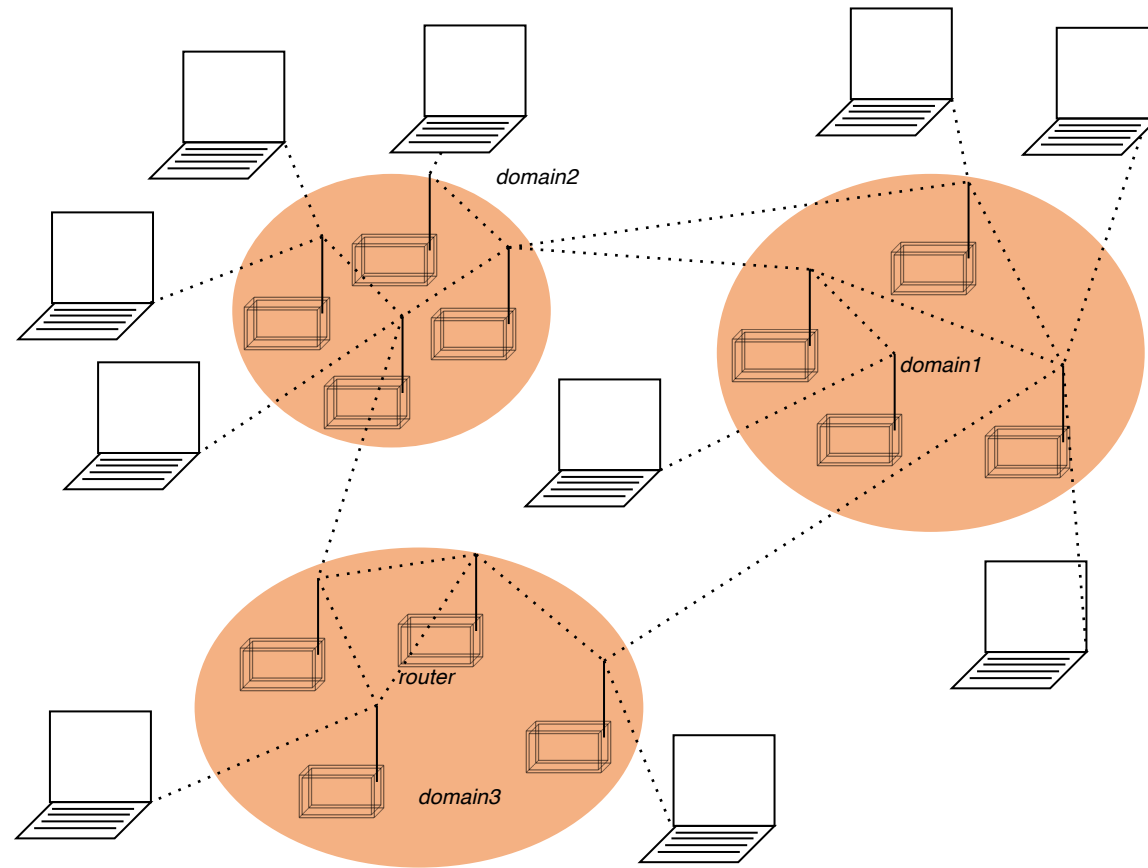
| | 0 | 1 | 2 | 3 | 4 | 5 |
|---|---|---|---|---|---|---|
| 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 1 | 1 | 0 | 0 | 1 | 0 | 0 |
| 2 | 1 | 0 | 0 | 1 | 1 | 1 |
| 3 | 1 | 1 | 1 | 0 | 0 | 1 |
| 4 | 1 | 0 | 1 | 0 | 0 | 0 |
| 5 | 0 | 0 | 1 | 1 | 0 | 0 |

Graph Data: Social Networks



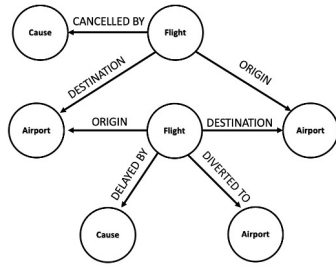
Source: [Backstrom et al., 2011]

Graph Data: Communication



Source: Stanford CS246

Various Types of Graphs

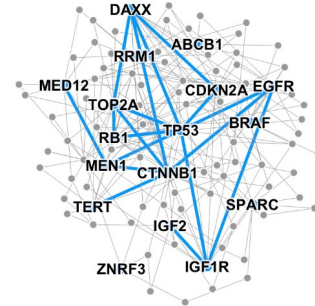


Event Graphs



Image credit: [SalientNetworks](#)

Computer Networks



Disease Pathways

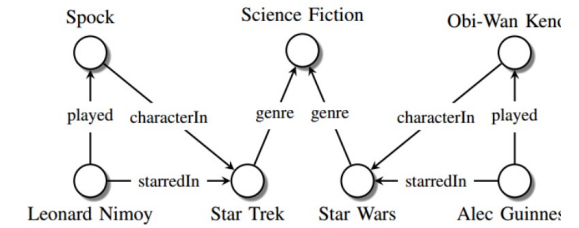


Image credit: [Maximilian Nickel et al](#)

Knowledge Graphs

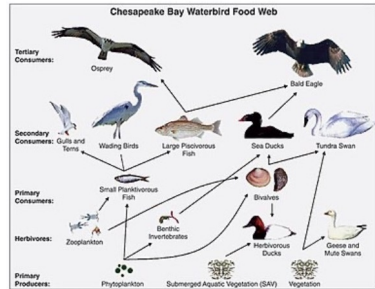


Image credit: [Wikipedia](#)

Food Webs



Image credit: [Pinterest](#)

Particle Networks



Image credit: [visitlondon.com](#)

Underground Networks

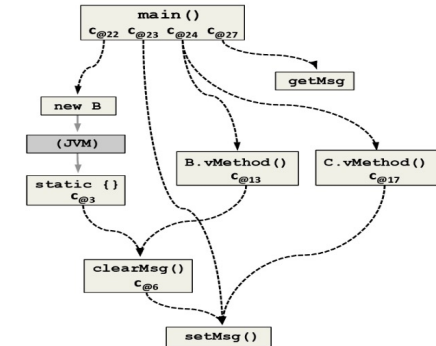


Image credit: [ResearchGate](#)

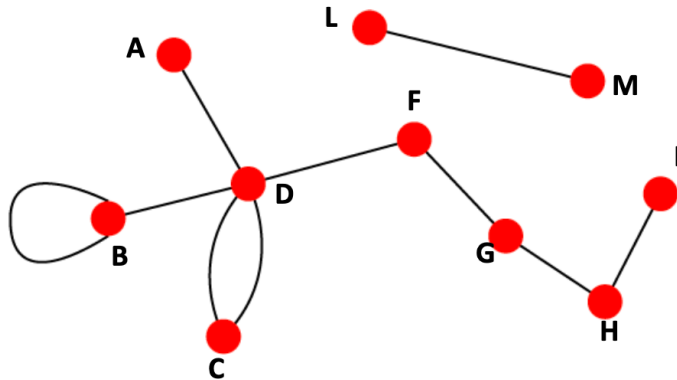
Code Graphs

Directed vs. Undirected Graphs

- We focus on **undirected graphs**, which is a simpler structure.

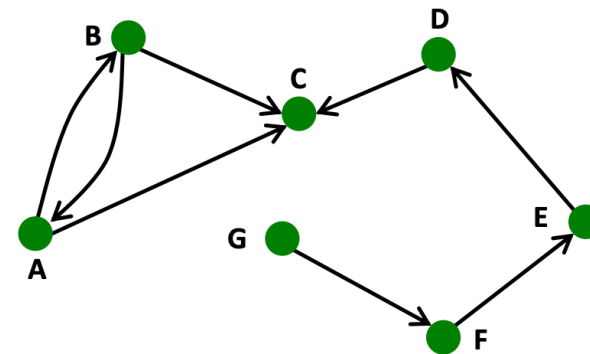
Undirected

- **Links:** undirected
(symmetrical, reciprocal)



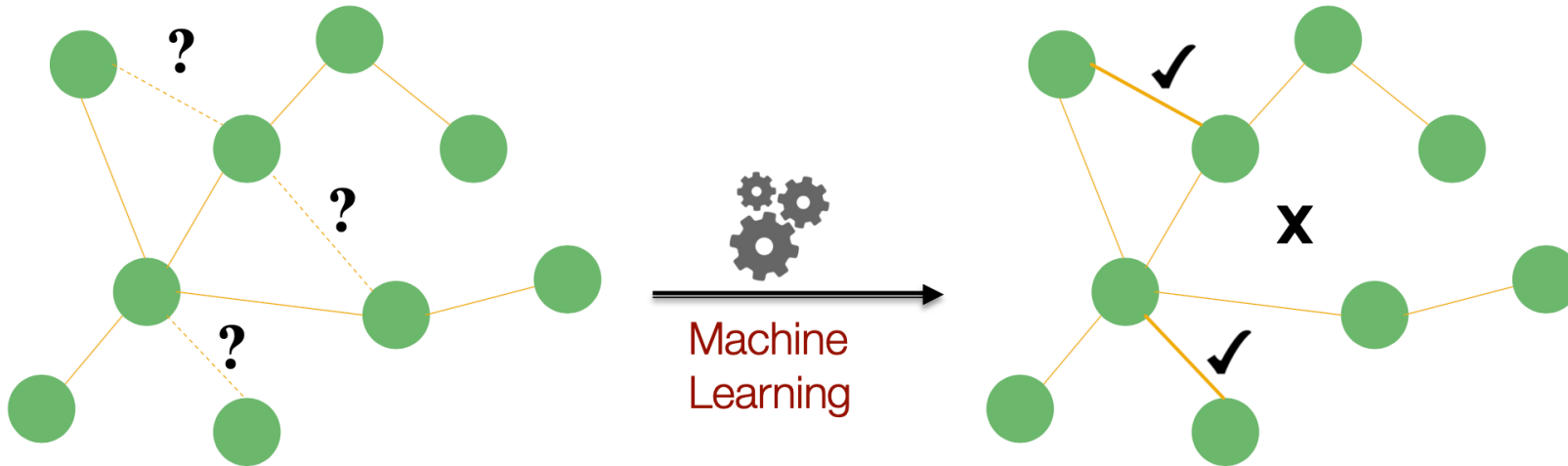
Directed

- **Links:** directed



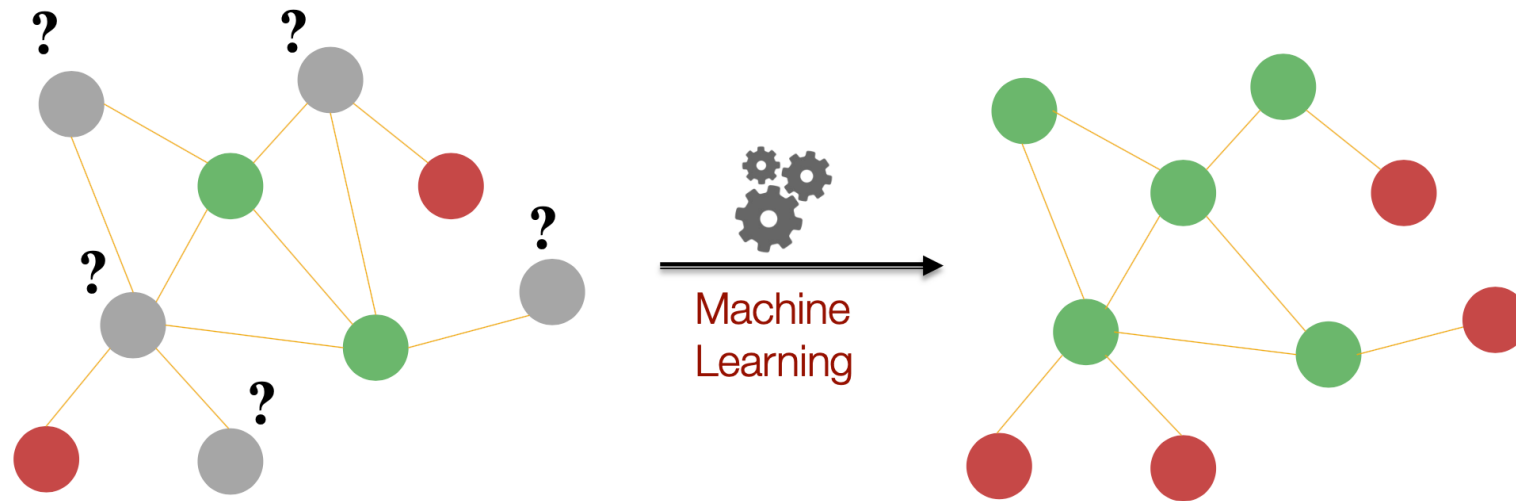
What to Do with Graphs: Link Prediction

- We can solve various tasks defined on graph datasets.
- **Link prediction** is to predict the appearance of new edges.
 - Identifying possible friends in Facebook.
 - Recommending new movies to users in Netflix.



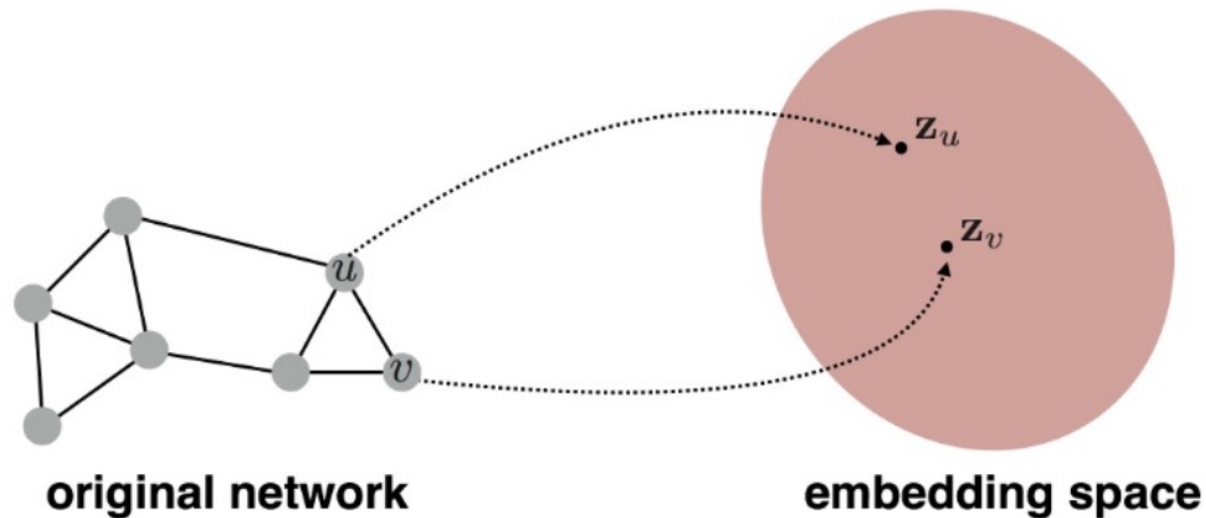
What to Do with Graphs: Node Classification

- **Node classification** is to classify each node in a graph.
 - Identifying political stance of users in Facebook.
 - Categorizing movies in Netflix, going over typical genres.



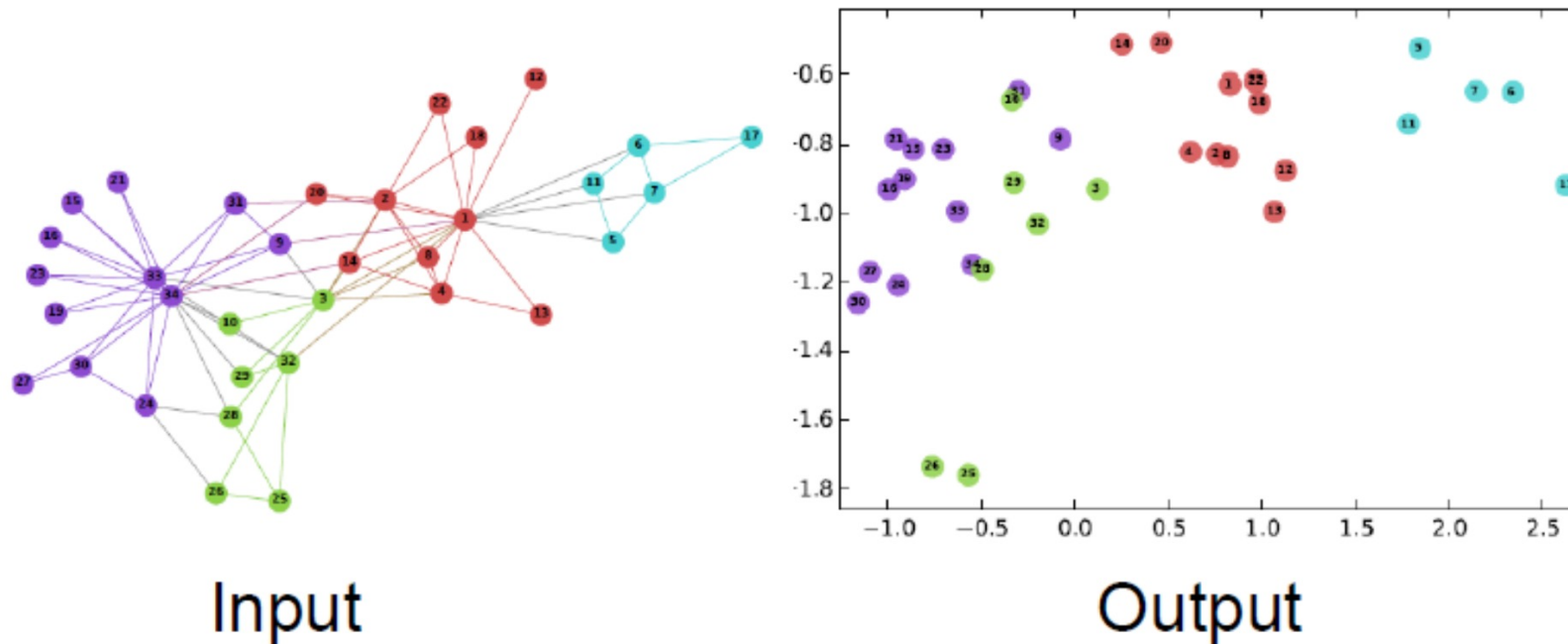
Representation Learning in Graphs

- Both tasks can be solved by **graph representation learning**.
 - **For** (i) nodes, (ii) subgraphs, or the (iii) entire graph.
 - **Learn** low-dimensional embeddings.
 - **Such that** their relationships reflect the graph structure.



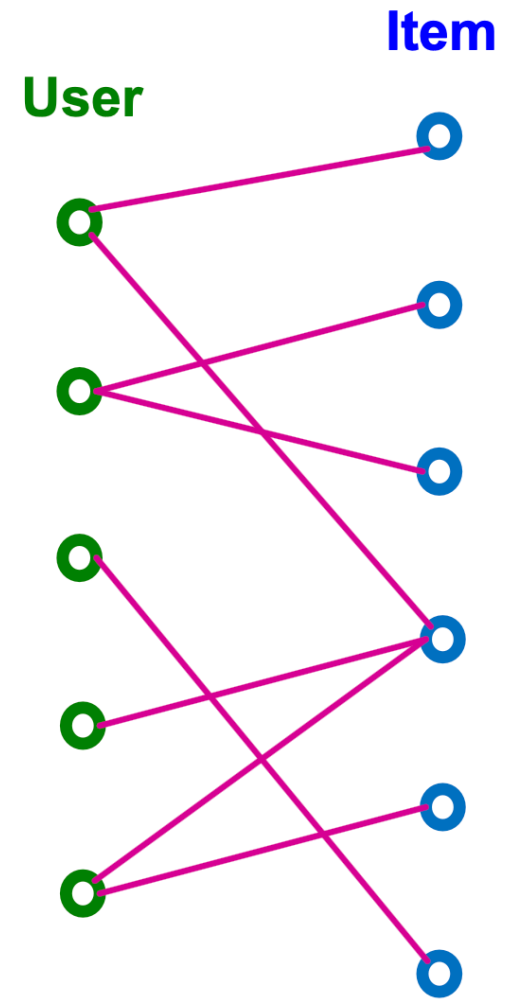
Example of Node Embeddings

- 2D embedding of nodes of the Zachary's Karate Club network
 - Each node is originally a $|V| (= 34)$ -dimensional sparse vector



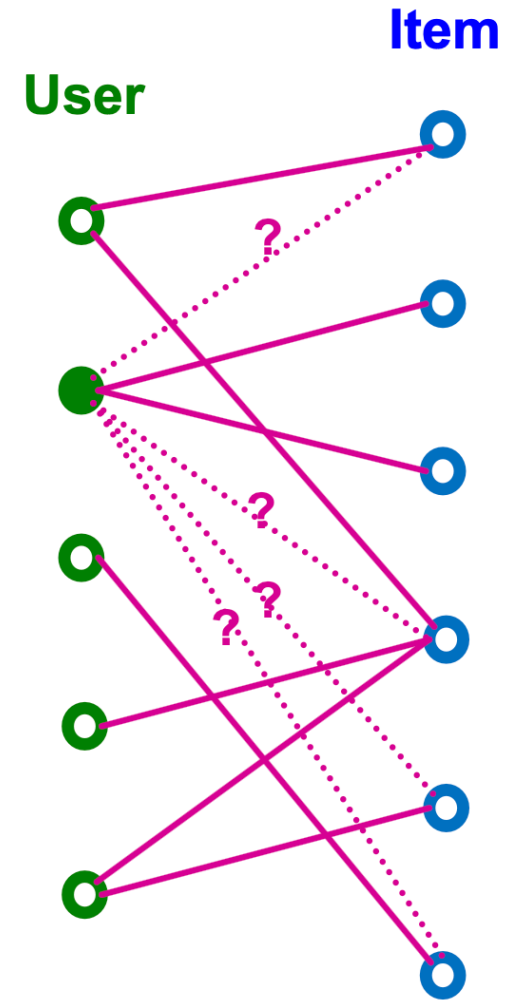
Recommender System as a Graph

- Recommender system is modeled as a **bipartite graph**.
- Edges connect **users** and **items**:
 - User-item interaction (e.g., click, purchase, review etc.).
 - Often associated with timestamp (timing of the interaction).



Recommendation Task

- **Given** past user-item interactions (as a graph).
 - Implicit feedback is assumed for simplicity.
- **Predict** items each user will interact in the future.
 - Can be cast as a **link prediction** problem.
 - Predict new user-item edges given the past edges
 - Aim to learn a real-valued score function $f(u, v)$.
 - Between a user u and an item v .
 - Recommend items with the highest $f(u, v)$.

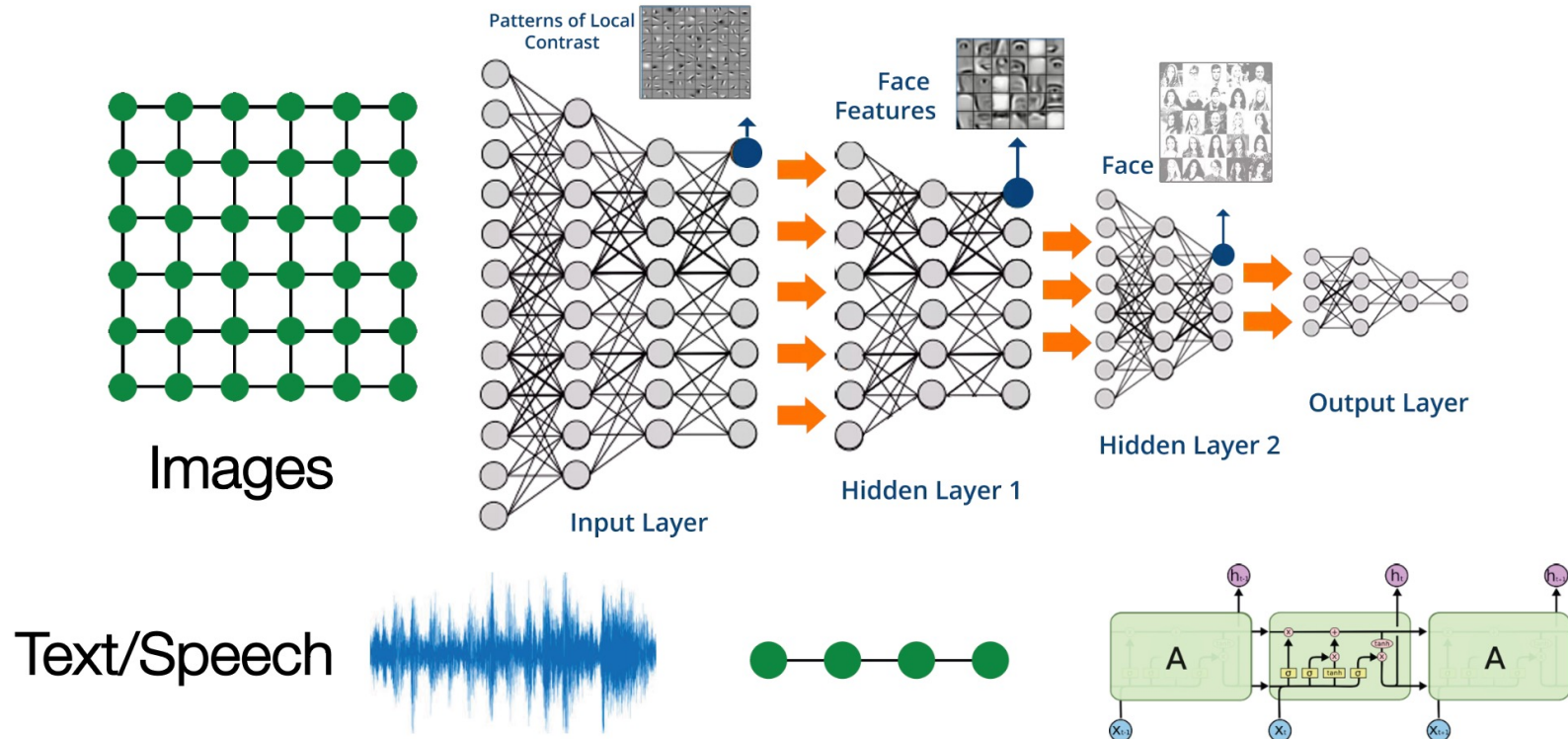


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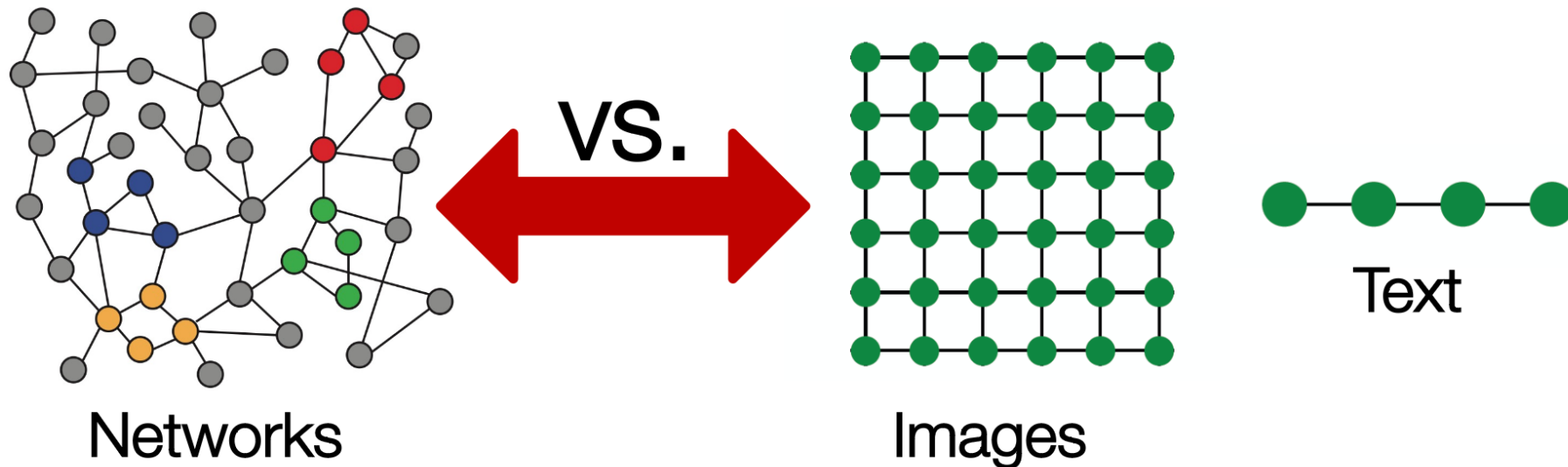
Deep Learning on Graphs

- Modern deep learning focuses on simple **sequences** and **grids**.



Deep Learning on Graphs

- Graph-structured data are far more complex.
 - Graphs have arbitrary size and complex topological structure.
 - No fixed node ordering or reference point.
 - Graph G with nodes $(1, 2, 3)$ is the same as G' with nodes $(1, 3, 2)$?

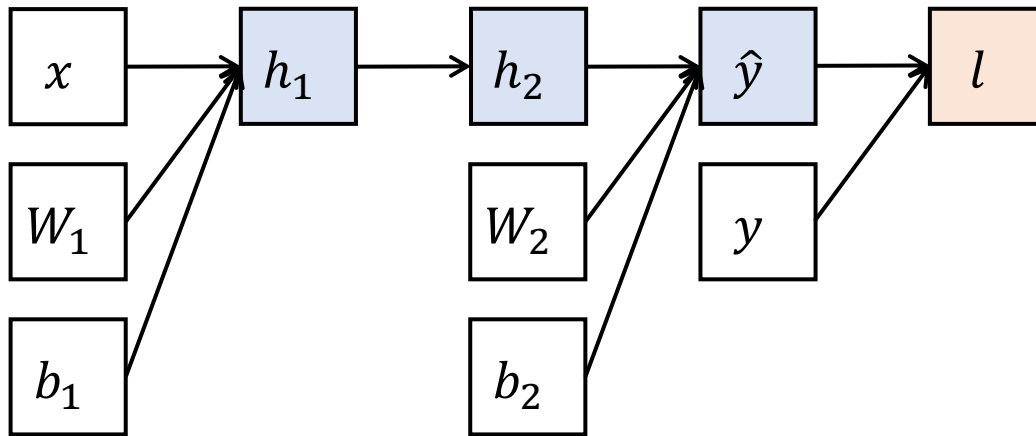


Problem Definition

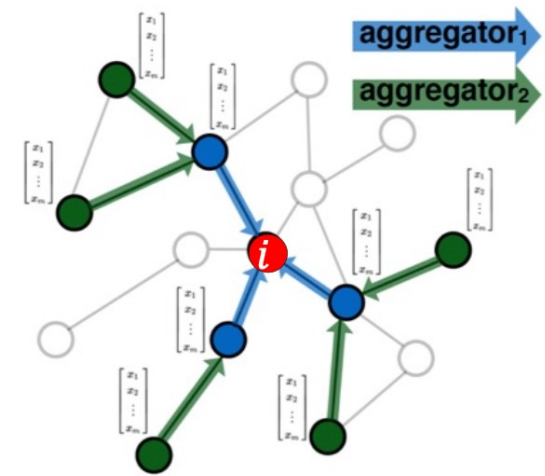
- **Given** a graph $G = (A, X)$.
 - $A \in \{0,1\}^{|V| \times |V|}$ is a (symmetric) adjacency matrix.
 - $X \in \mathbb{R}^{|V| \times d}$ is a node feature matrix.
 - It can be a learnable matrix.
- **Goal:** Train a neural network for useful graph tasks.
 - E.g., node classification or link prediction.
 - Different types of **labels** will be given based on the task.

Graph Neural Networks

- **Graph neural networks (GNNs)** are neural nets for graphs.
- **Idea:** Node's neighborhood defines a **computation graph**.
 - Generalize the chain graph of an MLP.



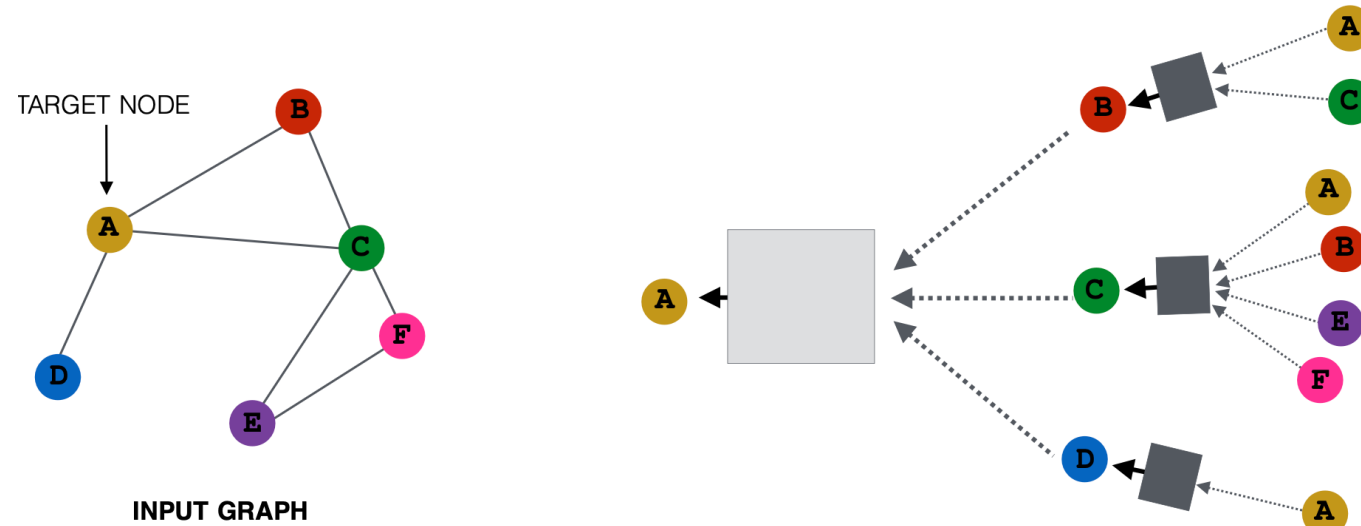
\approx



Propagate and transform information

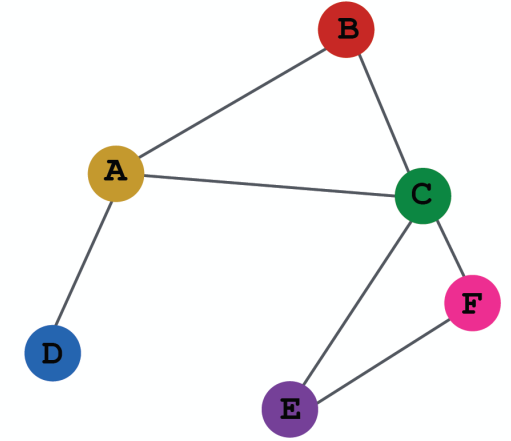
Computation Graph

- Computation graph creates a **tree structure** through layers.
 - Let $h_A^{(l)}$ be the hidden representation of node A at layer l .
 - $h_A^{(l)}$ is computed from $h_A^{(l-1)}$, $h_B^{(l-1)}$, $h_C^{(l-1)}$, and $h_D^{(l-1)}$ at layer $l - 1$.

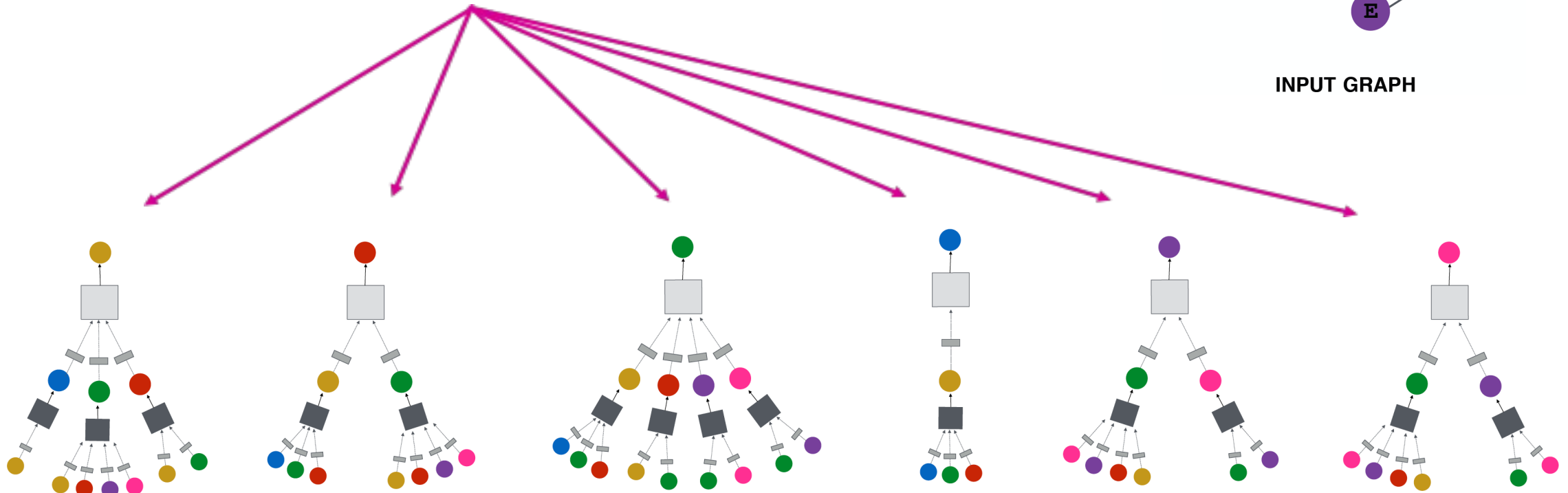


Computation Graph

- **Every node** defines a computation graph based on its neighborhood, in parallel.

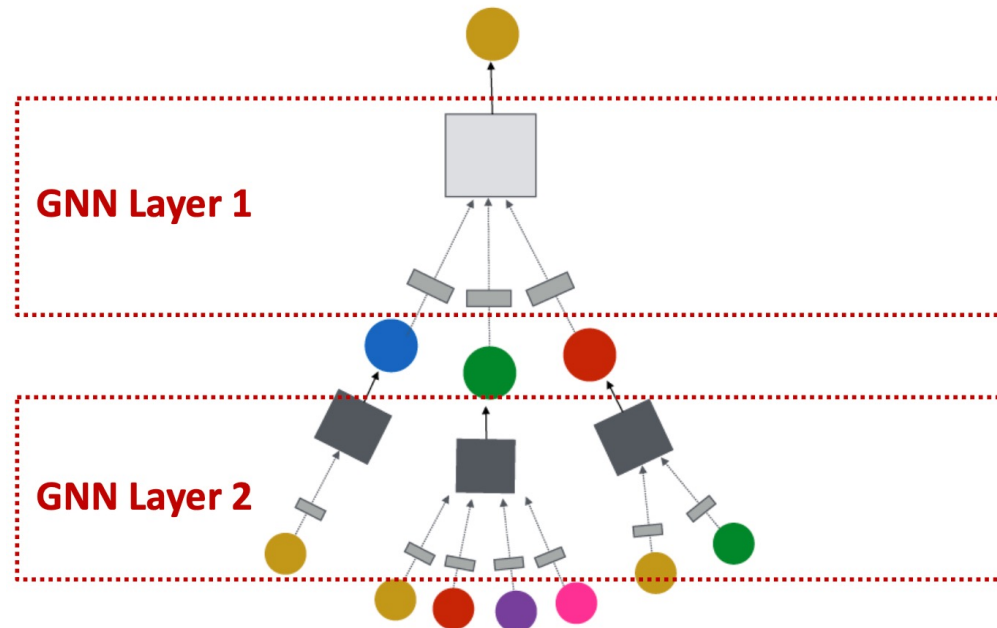


INPUT GRAPH



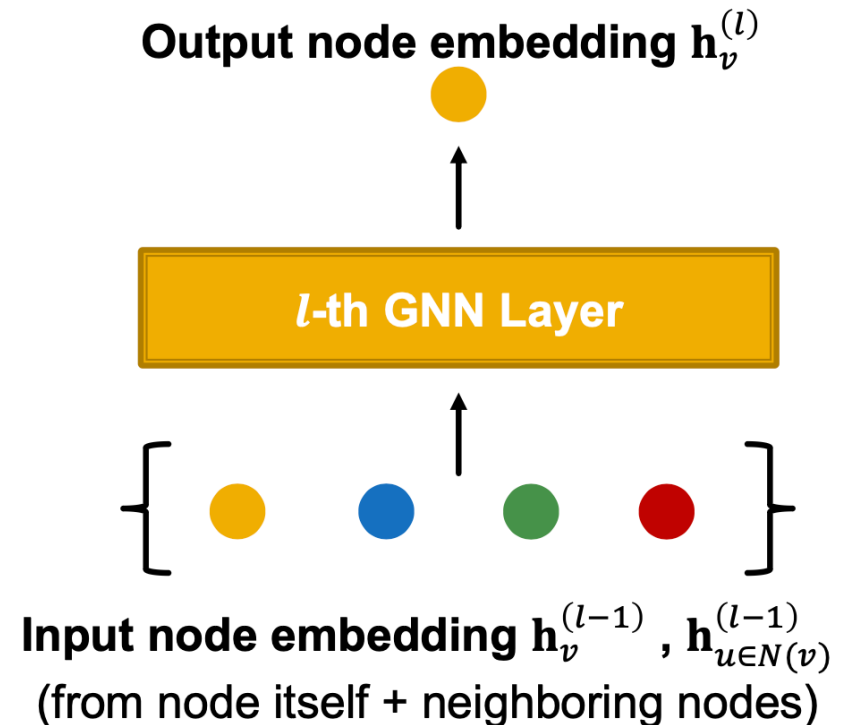
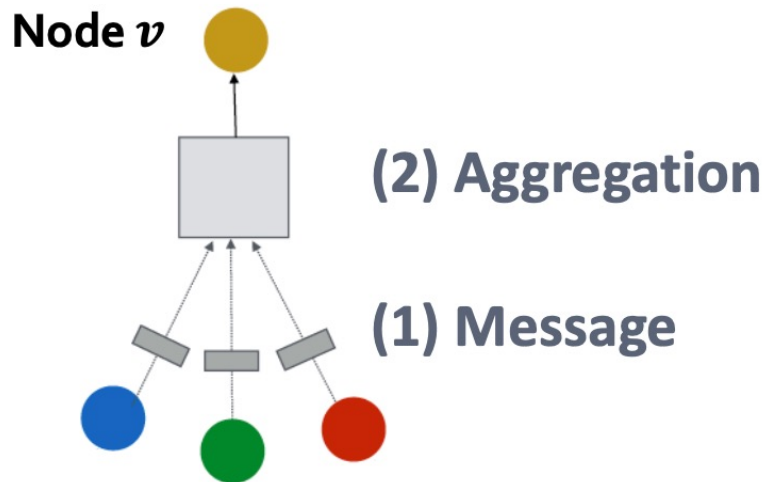
GNN Layers

- **GNN layers** are a core building block of GNNs.
 - The number of layers determines the expressiveness of GNNs.
 - L -layer GNN considers the L -hop neighborhood of each node.



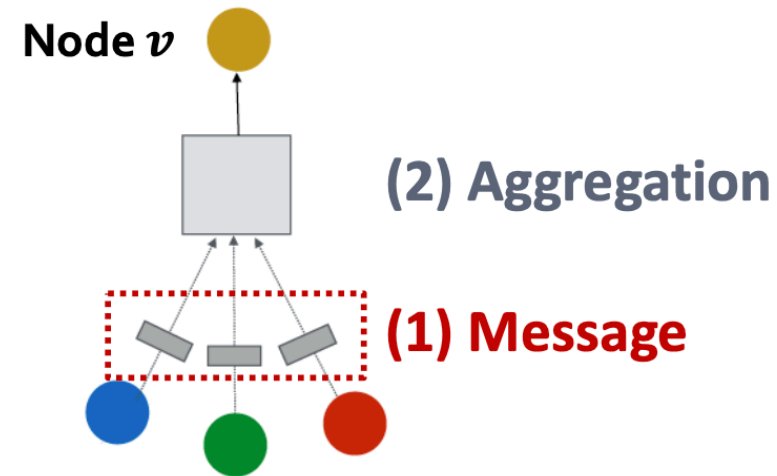
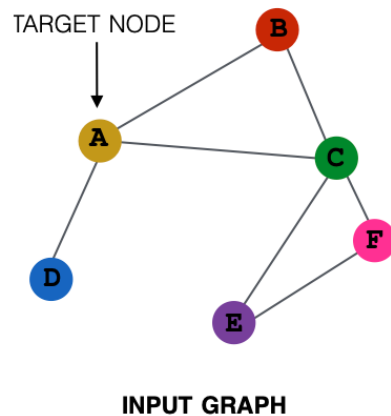
Components of Each Layer

- GNN layer is a function from a set of vectors into a single vector.
 1. **Message:** Transform each vector.
 2. **Aggregation:** Aggregate the messages.



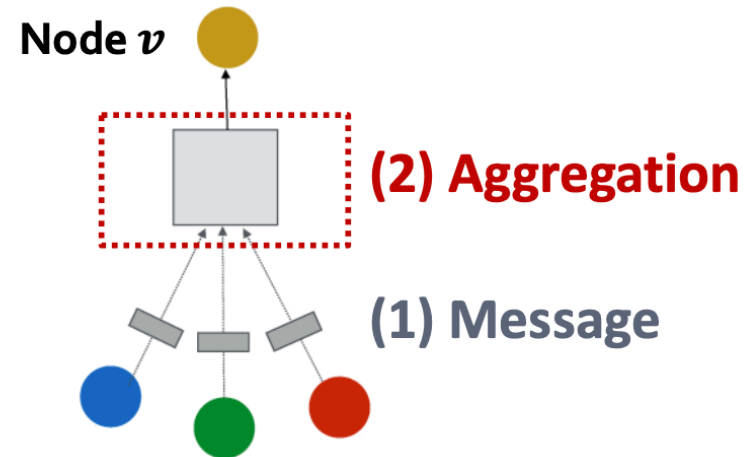
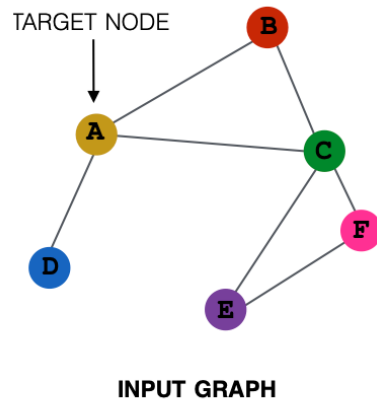
Message Computation

- **Message** is defined as $m_u^{(l)} = \text{MSG}^{(l)}(h_u^{(l-1)})$.
 - **Intuition:** Each node creates a message, which is sent to other nodes.
 - **Example:** Linear layer $m_u^{(l)} = W^{(l)} h_u^{(l-1)}$.



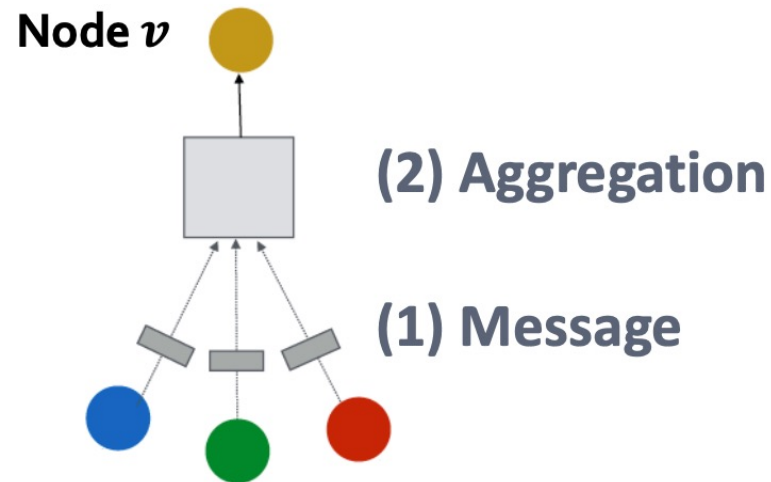
Aggregation

- **Aggregation** is defined as $h_v^{(l)} = \text{AGG}^{(l)}(\{m_u^{(l)} \mid u \in N(v)\})$.
 - **Intuition:** Aggregate the messages from node v 's neighbors.
 - **Example:** Elementwise $\text{sum}(\cdot)$, $\text{mean}(\cdot)$, or $\text{max}(\cdot)$ operator.
 - Any many-to-one function is okay.



Self-Connection

- We should also include a **self-connection** at each layer.
 - We don't want to lose information from node v .
 - Use $N(v) \cup \{v\}$ instead of $N(v)$.



General Framework

- Putting things together, we have a **GNN layer** defined as
 - **Message:** $m_u^{(l)} = \text{MSG}^{(l)}(h_u^{(l-1)})$ where $u \in \{N(v) \cup \{v\}\}$.
 - **Aggregation:** $\hat{h}_v^{(l)} = \text{AGG}^{(l)}(\{m_u^{(l)} \mid u \in N(v)\}, m_v^{(l)})$.
 - **Activation function:** $h_v^{(l)} = \sigma(\hat{h}_v^{(l)})$.
 - The function σ can be ReLU, Sigmoid, etc., and is used for nonlinearity.
- There are many GNNs with different choices of components.
 - GCN, GraphSAGE, GAT, GIN, etc.

Graph Convolutional Network

- **Graph convolutional network (GCN)** is defined as

$$\hat{h}_v^{(l)} = \sum_{u \in N(v) \cup \{v\}} \frac{W^{(l)} h_u^{(l-1)}}{\sqrt{(d_v + 1)(d_u + 1)}}$$

- where d_v is the degree of node v , i.e., $d_v = |N(v)|$.
- The actual representation is $h_v^{(l)} = \sigma(\hat{h}_v^{(l)})$ with nonlinearity.

GCN in the Matrix Form

- We implement a GNN with **matrix-vector operations**.
- For example, the following two are equivalent:

$$h_u^{(l)} = \sum_{u \in N(v) \cup \{v\}} \frac{W^{(l)} h_u^{(l-1)}}{\sqrt{(d_v+1)(d_u+1)}}, \quad H^{(l)} = \tilde{D}^{-1/2} \tilde{A} \tilde{D}^{-1/2} H^{(l-1)} W^{(l)}.$$

- $\tilde{A} = A + I$ is the adjacency matrix with self-loops.
- \tilde{D} is the degree matrix of \tilde{A} , such that $\tilde{d}_{ii} = \sum_k \tilde{a}_{ik}$.

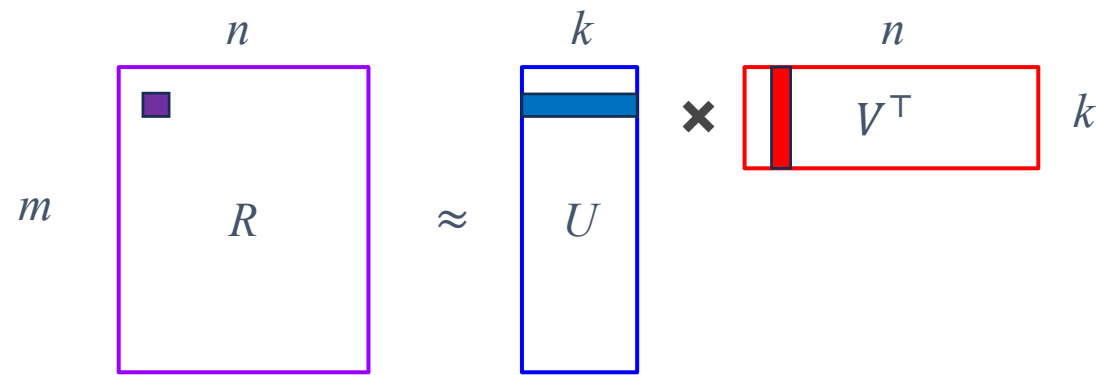
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Recap: Latent Factor Models

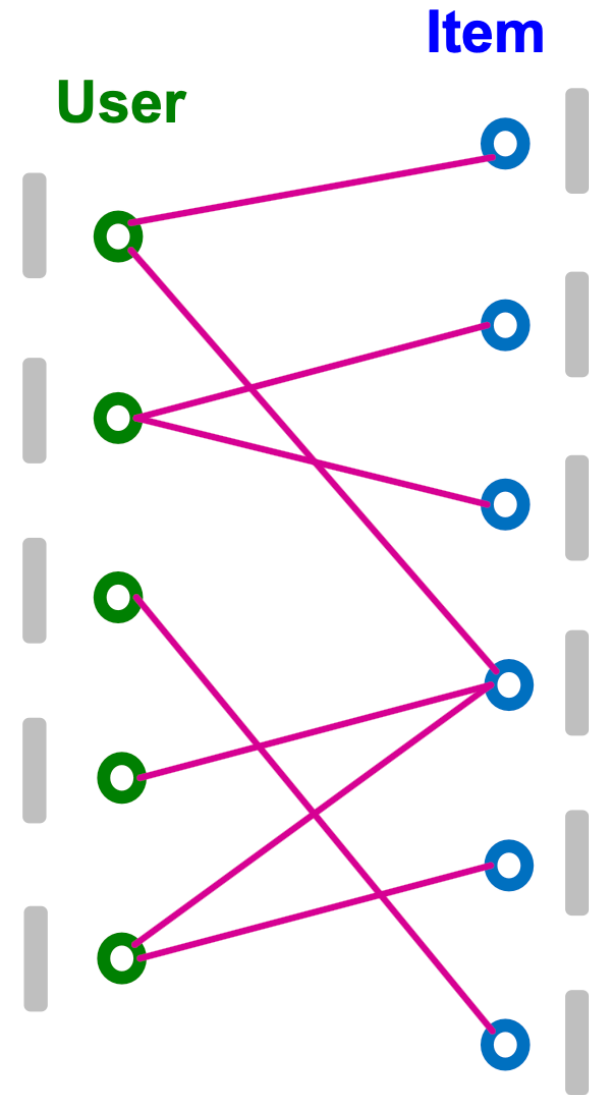
- **Latent factor models:**

- Learn an embedding \mathbf{z}_u and \mathbf{z}_v for every user u and item v , resp.
- Given a user u , find an item v with a high score $f(u, v) = \mathbf{z}_u^\top \mathbf{z}_v$.
- The score function can be modeled as a neural network.
 - Use $f_\theta(u, v)$ with learnable parameters θ as a score function.



Limitations of LFM

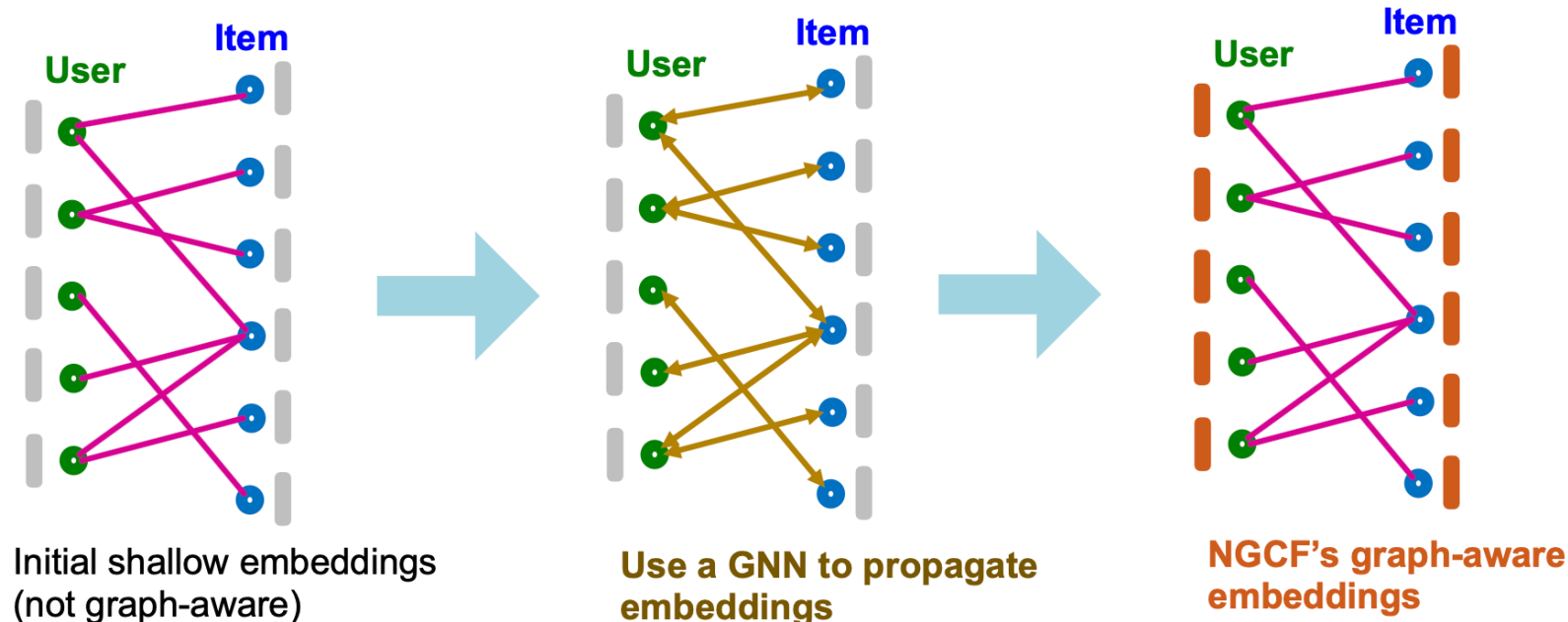
- CF captures only the **first-order** structure.
 - Only u and v participate in computing $f(u, v)$.
 - High-order graph structure (e.g. K -hop paths between u and v) is not explicitly captured.
- **Example:**
 - $K = 2$: Users u_1 and u_2 bought the same item.
 - $K = 4$: Users u_1 and u_2 bought items v_1 and v_2 that are bought by the same user u_3 .
 - Represents high-order similarity.



Neural Graph Collaborative Filtering

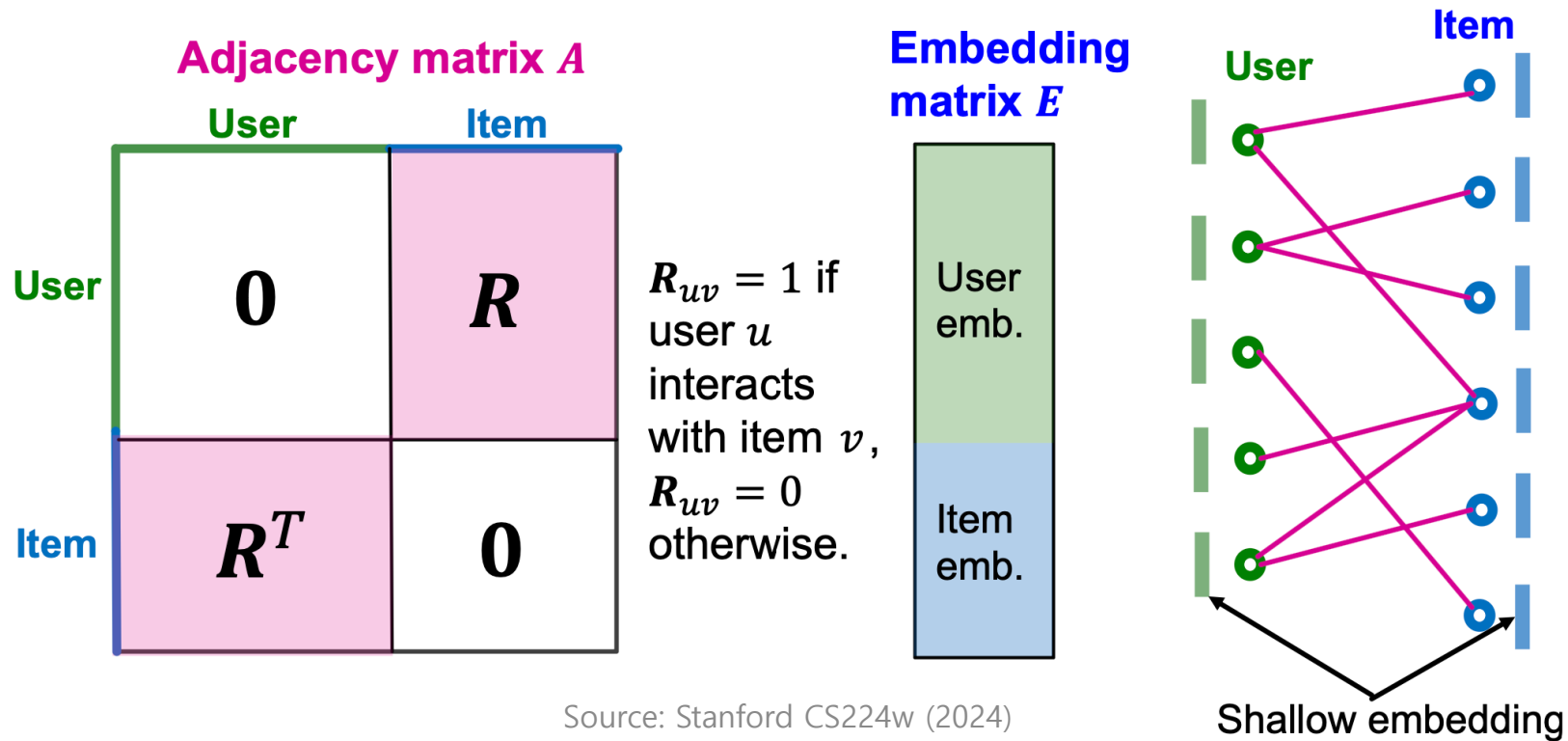
- **Neural Graph Collaborative Filtering (NGCF):**

- Explicitly incorporates the high-order graph structure for embeddings.
- **Key idea:** Use a GNN to generate graph-aware final embeddings.



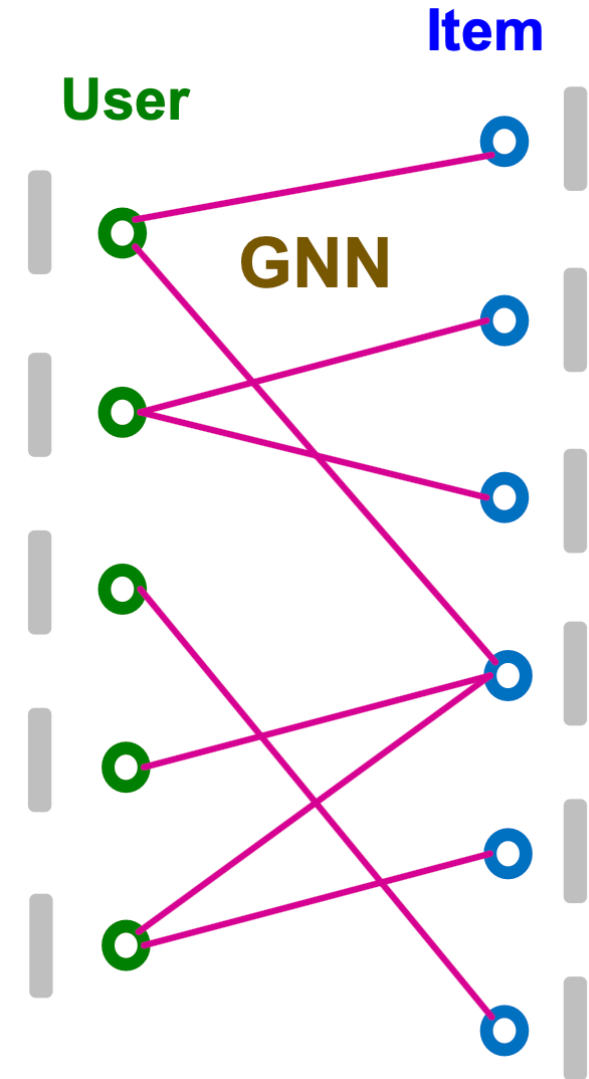
NGCF Visualization

- A graph (with the matrix A) is created from the utility matrix R .



NGCF Framework

- **Given:** User-item bipartite graph G .
- **NGCF framework:**
 - Initialize learnable node embeddings E .
 - Use a GNN to propagate E through G .
- Contains two kinds of parameters:
 - Shallow user/item embeddings: $O(D|V|)$.
 - $|V|$ is the number of nodes.
 - D is the embedding dimension.
 - GNN's parameters: $O(LD^2)$.
 - L is the number of GNN layers.

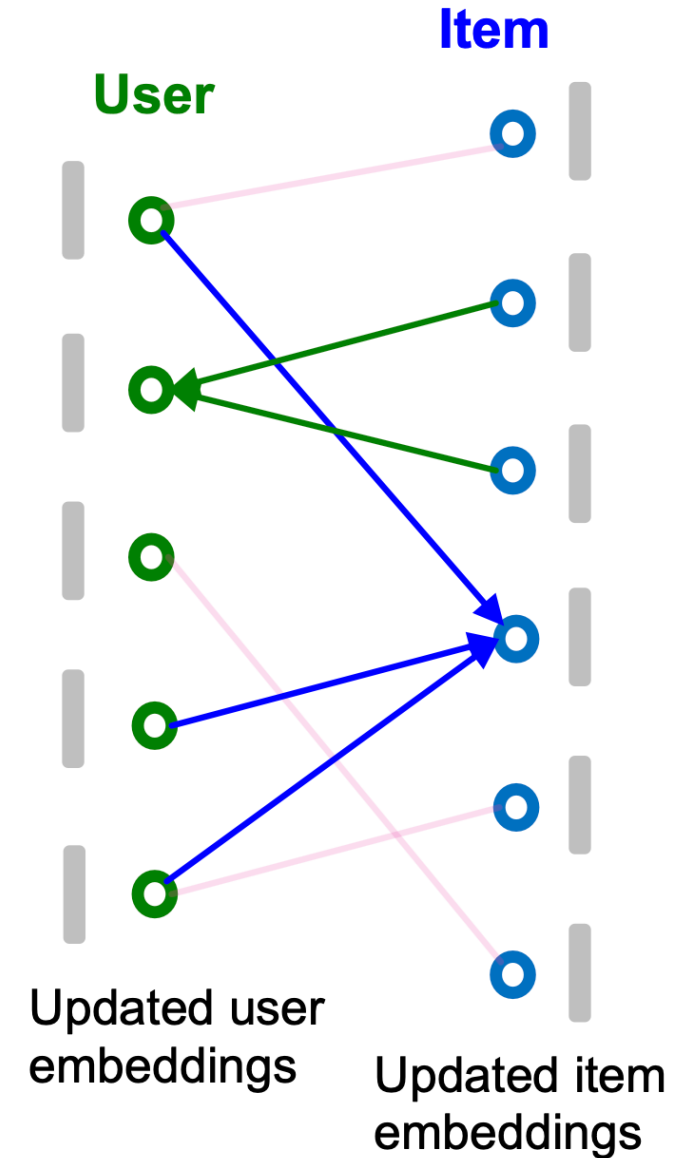


Neighborhood Aggregation

- **Step 1:** Set embeddings as initial features.
 - Each node u has a learnable embedding $\mathbf{h}_u^{(0)}$.
- **Step 2:** Update the embeddings through layers.

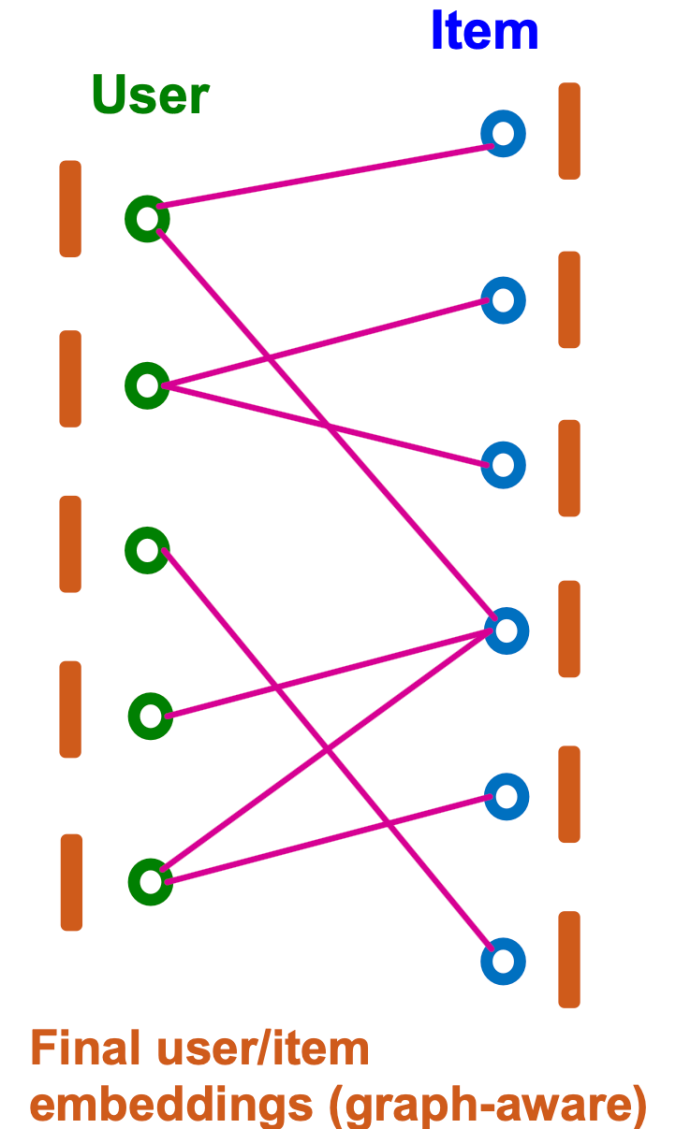
$$\mathbf{h}_u^{(l+1)} = \text{COMBINE} \left(\mathbf{h}_u^{(l)}, \text{AGG} \left(\left\{ \mathbf{h}_v^{(l)} \mid v \in N(u) \right\} \right) \right).$$

- Done for all users/items simultaneously.
- COMBINE and AGG functions can be anything.



Score Function

- Get final embeddings $\mathbf{z}_u = \mathbf{h}_u^{(L)}$ and $\mathbf{z}_v = \mathbf{h}_v^{(L)}$.
- Use the inner product $\mathbf{z}_u^\top \mathbf{z}_v$ as a score function.
- Training done by (stochastic) gradient descent.
- Any loss function for implicit feedback is used.
 - E.g., BPR loss.



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Summary

- Graphs can represent various datasets and tasks.
- GNNs are a core deep learning architecture for graphs.
 - The main idea is to apply convolution to graphs.
- Graph-based recommendation utilize graph information.
 - We can capture high-order relationships of users/items.