

NRC7292 Evaluation Kit

User Guide

(SDK API Manual)

Ultra-low power & Long-range Wi-Fi

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NEWRACOM, Inc.

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Ultra-low power & Long-range Wi-Fi

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1 API Reference

1.1 Wi-Fi

1.1.1 void nrc_wifi_register_event_handler (event_callback_fn fn)

Register a Wi-Fi event handler callback function pointer. The callback function will be called each time a Wi-Fi event happens and should not be time-consuming.

Parameters:

<i>fn</i>	Callback function pointer
-----------	---------------------------

Returns:

N/A

1.1.2 bool nrc_wifi_set_dhcp (bool dhcp, char *ip_addr)

Set the DHCP option and manually configure the static IP if DHCP mode is disabled.

Parameters:

<i>dhcp</i>	true: Enable DHCP, false: Disable DHCP and use a static IP.
<i>ip_addr</i>	Static IP address (must be provided if DHCP is set to false)

Returns:

true: success

false: fail

1.1.3 bool nrc_wifi_get_dhcp (void)

Set the DHCP mode.

Parameters:

N/A

Returns:

true: enabled

false: disabled

1.1.4 **int nrc_wifi_get_nd (void)**

Request a network index associated with the Wi-Fi connection.

Parameters:

N/A

Returns:

On success, a nonnegative network index is returned. Otherwise, one of the negative-valued error codes (WIFI_GET_ND or WIFI_SET_FAIL) is returned.

1.1.5 **int nrc_wifi_get_network_index (void)**

Get the current network index.

Parameters:

N/A

Returns:

The current network index.

1.1.6 **int nrc_wifi_set_security (int index, int mode, char *password)**

Set the security parameters for Wi-Fi connection.

Parameters:

<i>index</i>	Network index
<i>mode</i>	Security mode: OPEN, WPA, WPA2 (recommended)
<i>password</i>	Password

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.7 **int nrc_wifi_set_ssid (int index, char * ssid)**

(For STA only) Set the SSID of the AP to establish connection with.

Parameters:

<i>index</i>	Network index
<i>ssid</i>	SSID (max 20 bytes)

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.8 **int nrc_wifi_scan (void)**

Start scanning and block until the scanning procedure is complete.

Parameters:

N/A

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.9 **int nrc_wifi_scan_results (SCAN_RESULTS *results)**

Get scan results. (should be called after calling nrc_wifi_scan())

Parameters:

<i>Results</i>	scan list (refer to SCAN_RESULTS structure)
----------------	---

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.10 int nrc_wifi_connect (int index)

Attempt a new connection with the AP and block until the procedure is complete.

Parameters:

<i>index</i>	network index
--------------	---------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.11 int nrc_wifi_connect_async (int index)

Asynchronously attempt a new connection with the AP without blocking.

Parameters:

<i>index</i>	network index
--------------	---------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.12 int nrc_wifi_disconnect (int index)

Asynchronously disconnect from the AP without blocking.

Parameters:

<i>index</i>	network index
--------------	---------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.13 int nrc_wifi_disconnect_sync (int index)

Disconnect from the AP and block until the disconnect procedure is complete.

Parameters:

<i>index</i>	network index
--------------	---------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.14 int nrc_wifi_set_country (char *country_code)

Set the country code.

Parameters:

<i>country_code</i>	Country code ("US", "KR", "JP", "CN", "EU", "TW") Default: "KR" (refer to Appendix)
---------------------	--

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.15 int nrc_wifi_get_ip (void)

Request a dynamic IP via DHCP or set a static IP. For DHCP, the function blocks until the allocation procedure is complete.

Parameters:

N/A

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.16 char* nrc_wifi_get_ip_address (void)

Get the current IP address.

Parameters:

N/A

Returns:

On success, the IP address is returned. On error, NULL is returned.

1.1.17 int nrc_wifi_softap_set_ip (char* ip_addr)

Set the Soft AP IP address.

Parameters:

<i>ip_addr</i>	IP address
----------------	------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SOFTAP_FAIL is returned.

1.1.18 int nrc_wifi_softap_set_conf (int index, char *ssid, int channel, int sec_mode, char *password)

Set the Soft AP configuration parameters.

Parameters:

<i>index</i>	Network index
<i>ssid</i>	SSID
<i>channel</i>	S1G(Sub 1G) channel index (refer to Appendix)
<i>sec_mode</i>	Security mode
<i>password</i>	Password (only valid if <i>sec_mode</i> is not open)

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.19 int nrc_wifi_softap_start (int index)

Start the Soft AP operation and block until the start procedure is complete.

Parameters:

<i>index</i>	Network index
--------------	---------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.20 int nrc_wifi_softap_start_dhcp_server (void)

Start a DHCP server and block until the start procedure is complete. (Only valid while operating as a Soft AP)

Parameters:

N/A

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.21 WLAN_STATE_ID nrc_wifi_get_state (void)

Get the current Wi-Fi connection state.

Parameters:

N/A

Returns:

WLAN_STATE_INIT
WLAN_STATE_READY
WLAN_STATE_TRY_CONNECT
WLAN_STATE_CONNECTED
WLAN_STATE_TRY_GET_IP
WLAN_STATE_GET_IP
WLAN_STATE_TRY_DISCONNECT
WLAN_STATE_DISCONNECTED
WLAN_STATE_SOFTAP_CONF
WLAN_STATE_SOFTAP_START
WLAN_STATE_DHCP_START

1.1.22 void nrc_wifi_set_state (WLAN_STATE_ID state)

Configure the Wi-Fi connection state.

Parameters:

<i>state</i>	Wi-Fi connection state
--------------	------------------------

Returns:

N/A

1.1.23 int nrc_wifi_set_tx_power (int tx_power)

Configure the TX power level.

Parameters:

<i>tx_power</i>	TX power level (1 ~ 30) in dBm
-----------------	--------------------------------

Returns:

On success, the status code WIFI_SUCCESS is returned. On error, the status code WIFI_SET_FAIL is returned.

1.1.24 int nrc_wifi_get_tx_power (void)

Get the current TX power level.

Parameters:

N/A

Returns:

TX power level (1 ~ 30) in dBm

1.1.25 int8_t nrc_wifi_get_rssi (void)

Get the current RSSI level.

Parameters:

N/A

Returns:

RSSI in dBm

1.1.26 int nrc_wifi_get_snr (void)

Get the current SNR level.

Parameters:

N/A

Returns:

SNR in dB

1.1.27 char* nrc_wifi_get_mac_address (void)

Get the MAC address.

Parameters:

N/A

Returns:

The stored MAC Address.

1.1.28 void nrc_wifi_set_rate_control (bool enable)

Set the MCS rate control option.

Parameters:

<i>enable</i>	true: enable, false: disable
---------------	------------------------------

Returns:

N/A

1.1.29 bool nrc_wifi_get_rate_control (void)

Get the MCS rate control option.

Parameters:

N/A

Returns:

true: enabled, false: disabled

1.1.30 void nrc_wifi_set_mcs (uint8_t mcs)

Set the MCS index.

Parameters:

<i>mcs</i>	MCS index (0~7 or 10)
------------	-----------------------

Returns:

N/A

1.1.31 **bool nrc_wifi_get_mcs (void)**

Get the current MCS index

Parameters:

N/A

Returns:

The current MCS index (0~7 or 10).

1.2 Timer

1.2.1 void nrc_timers_init (void)

Initialize timers

Parameters:

N/A

Returns:

N/A

1.2.2 timer_id nrc_timer_create (uint64_t time, bool repeat, timer_callback handler)

Create and start a timer.

Parameters:

<i>time</i>	Time duration value in microsecond
<i>repeat</i>	true (repeat) or false (single)
<i>handler</i>	Callback handler function when the timer expired

Returns:

The timer ID. (Can be used to stop the timer using nrc_timer_stop())

1.2.3 void nrc_timer_stop (timer_id id)

Stop the timer associated with the timer ID.

Parameters:

<i>id</i>	Timer ID
-----------	----------

Returns:

N/A

1.3 UART

1.3.1 **bool nrc_uart_set_channel (int ch)**

Set the UART channel index.

Parameters:

<i>ch</i>	UART channel index (0~3)
-----------	--------------------------

Returns:

On success, true is returned. Otherwise, false is returned.

1.3.2 **void nrc_uart_register_intr_handler (int ch, intr_handler_fn cb)**

Register an interrupt handler for the specified UART channel. The callback function should not be time-consuming.

Parameters:

<i>ch</i>	UART channel index (0~3)
<i>cb</i>	Callback function of interrupt handler

Returns:

N/A

1.3.3 **void nrc_uart_set_config (NRC_UART_CONFIG * conf)**

Set the configuration for the current UART channel.

Parameters:

<i>conf</i>	UART configuration structure (included in api_uart.h)
-------------	---

Returns:

N/A

1.3.4 void nrc_uart_set_interrupt (int ch, bool tx_en, bool rx_en)

Enable or disable interrupt for the specified UART channel.

Parameters:

<i>ch</i>	UART channel index (0~3)
<i>tx_en</i>	true: enable TX interrupt, false: disable TX interrupt
<i>rx_en</i>	true: enable RX interrupt, false: disable RX interrupt

Returns:

N/A

1.3.5 void nrc_uart_intr_clr (int ch, bool tx_int, bool rx_int, bool to_int)

Clear interrupt with a specific channel.

Parameters:

<i>ch</i>	UART channel index (0~3)
<i>tx_en</i>	true: clear TX interrupt, false: do nothing
<i>rx_en</i>	true: clear RX interrupt, false: do nothing
<i>to_int</i>	true: clear RX timeout interrupt, false: do nothing

Returns:

N/A

1.3.6 bool nrc_uart_get (int ch, char * c)

Get a byte from the specified UART channel.

Parameters:

<i>ch</i>	UART channel index (0~3)
<i>c</i>	Pointer to which the received byte will be written

Returns:

true(1) or false(0)

1.3.7 int nrc_uart_get_intr_type (int ch)

Get the interrupt type for the specified UART channel.

Parameters:

<i>ch</i>	UART channel index (0~3)
-----------	--------------------------

Returns:

Interrupt type

UART_INT_NONE

UART_INT_ERROR

UART_INT_TIMEOUT

UART_INT_RX_DONE

UART_INT_TX_EMPTY

1.3.8 bool nrc_uart_put (int ch, char c)

Send a byte through the specified UART channel.

Parameters:

<i>ch</i>	UART channel index (0~3)
<i>c</i>	Byte to send.

Returns:

true(1) or false(0)

1.3.9 void nrc_uart_console_enable(void)

Enable the UART debug console on UART channel 3.

Parameters:

N/A

Returns:

N/A

1.3.10 void nrc_uart_printf(const char *f, ...)

Print on the debug console.

Parameters:

<i>f</i>	Format
...	Optional arguments

Returns:

N/A

1.3.11 void nrc_uart_vprintf(const char *f, va_list ap)

Print on the debug console.

Parameters:

<i>f</i>	Format
<i>ap</i>	Arguments

Returns:

N/A

※ Defined structure

```
typedef struct {
    int ch;                                /* UART Channel Index */
    NRC_UART_DATA_BIT db;                  /* Data bit */
    int br;                                /* Baud rate */
    NRC_UART_STOP_BIT stop_bit;            /* Stop bit */
    NRC_UART_PARITY_BIT parity_bit;        /* Parity bit */
    NRC_UART_HW_FLOW_CTRL hw_flow_ctrl;    /* HW flow control */
    NRC_UART_FIFO fifo;                    /* FIFO */
} NRC_UART_CONFIG;
```

1.4 GPIO

1.4.1 void nrc_gpio_config (NRC_GPIO_CONFIG * conf)

Set the GPIO configuration (direction, alternative function, mode).

Parameters:

<i>conf</i>	GPIO configuration (refer to api_gpio.h for more information)
-------------	---

Returns:

N/A

1.4.2 void nrc_gpio_register_intr_handler (NRC_GPIO_PIN pin, intr_handler_fn cb)

Register an interrupt handler callback function with the specified GPIO pin.

Parameters:

<i>pin</i>	GPIO pin index (refer to the datasheet for more information)
<i>cb</i>	Interrupt handler callback function

Returns:

N/A

1.4.3 int nrc_gpio_inputb (int pin)

Read from the specified GPIO pin.

Parameters:

<i>pin</i>	GPIO pin index (refer to the datasheet for more information)
------------	--

Returns:

0(LOW) or 1(HIGH)

1.4.4 void nrc_gpio_outputb (int pin, int level)

Write to the specified GPIO pin.

Parameters:

<i>pin</i>	GPIO pin index (refer to the datasheet for more information)
<i>level</i>	GPIO level (0: LOW or 1: HIGH)

Returns:

N/A

※ Defined structure

```
typedef struct {  
    NRC_GPIO_PIN gpio_pin;      /* Pin number */  
    NRC_GPIO_DIR gpio_dir;      /* Direction */  
    NRC_GPIO_ALT gpio_alt;      /* Alternative function */  
    NRC_GPIO_MODE gpio_mode;    /* Mode */  
} NRC_GPIO_CONFIG;
```

1.5 I2C

1.5.1 void nrc_i2c_init (uint32_t clk)

Initialize the I2C controller.

Parameters:

<i>clk</i>	I2C controller clock speed in Hz. (Max: 400,000)
------------	--

Returns:

N/A

1.5.2 void nrc_i2c_enable (bool enable)

Enable or disable the I2C controller.

Parameters:

<i>enable</i>	true(enable) or false(disable)
---------------	--------------------------------

Returns:

N/A

1.5.3 void nrc_i2c_ch_reset (void)

Reset the I2C controller.

Parameters:

N/A

Returns:

N/A

1.5.4 void nrc_i2c_start (void)

Start the I2C operation.

Parameters:

N/A

Returns:

N/A

1.5.5 **bool nrc_i2c_writebyte (uint8_t data)**

Write data to the I2C controller.

Parameters:

<i>data</i>	Data to write
-------------	---------------

Returns:

true or false

1.5.6 **bool nrc_i2c_readbyte (uint8_t * data, bool ack)**

Read data from the I2C controller.

Parameters:

<i>data</i>	Pointer to store the read byte.
<i>ack</i>	true(ACK) or false(NACK)

Returns:

true

1.5.7 **bool nrc_i2c_waitack (void)**

Block until receiving ACK or NACK from the I2C controller.

Parameters:

N/A

Returns:

true(ACK) or false(NACK)

1.5.8 **void nrc_i2c_stop (void)**

Stop the I2C operation.

Parameters:

N/A

Returns:

N/A

1.6 ADC

1.6.1 void nrc_nadc_init (void)

Initialize the ADC controller.

Parameters:

N/A

Returns:

N/A

1.6.2 void nrc_nadc_fini (void)

Finalize the ADC controller.

Parameters:

N/A

Returns:

N/A

1.6.3 uint16_t nrc_nadc_get_data (uint32_t id)

Read data from the specified channel

Parameters:

<i>id</i>	Channel ID (1~3)
-----------	------------------

Returns:

Data value (0x000 ~ 0x1FF)

1.7 PWM

1.7.1 void nrc_pwm_init (uint8_t ch, uint8_t gpio_num, uint8_t use_high_clk)

Initialize a PWM controller and assign it to the specified GPIO pin.

Parameters:

<i>ch</i>	PWM channel index (0~3)
<i>gpio_num</i>	GPIO pin allocation index (8~11)
<i>use_high_clk</i>	If 0, then a 1-bit pulse duration is about 20.8us. Otherwise, the duration is about 10.4us

Returns:

N/A

1.7.2 void nrc_pwm_config (uint8_t ch, uint32_t pattern1, uint32_t pattern2, uint32_t pattern3, uint32_t pattern4)

Configure the duty cycle for the specified PWM channel. One duty cycle consists of 128-bit pulse patterns. The pattern begins at the MSB of pattern1 and ends at the LSB of pattern4.

Parameters:

<i>Ch</i>	PWM channel index (0~3)
<i>pattern1</i>	Pattern bits 0~31
<i>pattern2</i>	Pattern bits 32~63
<i>pattern3</i>	Pattern bits 64~95
<i>pattern4</i>	Pattern bits 96~127

Returns:

N/A

1.7.3 void nrc_pwm_enable (uint32_t ch, bool enable)

Enable the specified PWM channel.

Parameters:

<i>ch</i>	PWM channel index (0~3)
<i>enable</i>	true(enable) or false(disable)

Returns:

N/A

1.8 SPI

1.8.1 void nrc_spi_init (enum spi_mode mode, enum spi_frame_bits bits, uint32_t clock)

Initialize the SPI controller.

Parameters:

<i>mode</i>	SPI mode ([CPOL, CPHA] = 0: [L, L], 1: [L, H], 2: [H, L], 3: [H, H])
<i>bits</i>	SPI frame bits
<i>clock</i>	SPI clock frequency

Returns:

N/A

1.8.2 void nrc_spi_enable (bool enable)

Enable or disable SPI.

Parameters:

<i>enable</i>	true(enable) or false(disable)
---------------	--------------------------------

Returns:

N/A

1.8.3 void nrc_spi_writebyte (uint8_t reg, uint8_t data)

Write a byte value to the specified register address.

Parameters:

<i>Reg</i>	Register address
<i>Data</i>	Byte value

Returns:

N/A

1.8.4 `uint8_t nrc_spi_readbyte (uint8_t reg)`

Read from the specified register address.

Parameters:

<i>reg</i>	Register address
------------	------------------

Returns:

The byte value read from the specified register address.

1.8.5 `uint32_t nrc_spi_xfer (uint8_t *wbuffer, uint8_t *rbuffer, uint32_t size)`

Transfer data between the master and the slave.

Parameters:

<i>wbuffer</i>	Write buffer pointer
<i>rbuffer</i>	Read buffer pointer
<i>size</i>	Number of bytes to transfer

Returns:

The actual number of transferred bytes.

1.9 HTTP Client

1.9.1 `httpc_ret_e nrc_httpc_get(con_handle_t *handle, const char *url, const char *custom_header, httpc_data_t *data, ssl_certs_t *certs)`

Send a GET request to the specified URL.

Parameters:

<i>handle</i>	Connection handle
<i>url</i>	Destination URL
<i>custom_header</i>	Custom HTTP request header. The headers (" <code><method></code> <code><uri></code> HTTP/1.1") and "Host: <code><host-name></code> " will be always sent by default. The string <code>custom_header</code> will be appended to the default header.
<i>data</i>	Pointer to the 'httpc_data_t' data handling structure.
<i>certs</i>	Pointer to the 'ssl_certs_t' for certificates structure.

Returns:

Error code (`httpc_ret_e`). See `api_httpc.h` for more information.

1.9.2 `httpc_ret_e nrc_httpc_post(con_handle_t *handle, const char *url, const char *custom_header, httpc_data_t *data, ssl_certs_t *certs)`

Send a POST request to the specified URL.

Parameters:

<i>handle</i>	Connection handle
<i>url</i>	Destination URL
<i>custom_header</i>	Custom HTTP request header. The headers (" <code><method></code> <code><uri></code> HTTP/1.1") and "Host: <code><host-name></code> " will be always sent by default. The string <code>custom_header</code> will be appended to the default header.
<i>data</i>	Pointer to the 'httpc_data_t' data handling structure.
<i>certs</i>	Pointer to the 'ssl_certs_t' for certificates structure.

Returns:

Error code (`httpc_ret_e`). See `api_httpc.h` for more information.

1.9.3 `httpc_ret_e nrc_httpc_put(con_handle_t *handle, const char *url, const char *custom_header, httpc_data_t *data, ssl_certs_t *certs)`

Send a PUT request to the specified URL.

Parameters:

<i>handle</i>	Connection handle
<i>url</i>	Destination URL
<i>custom_header</i>	Custom HTTP request header. The headers (" <code><method><uri> HTTP/1.1</code> ") and " <code>Host: <host-name></code> " will be always sent by default. The string <code>custom_header</code> will be appended to the default header.
<i>data</i>	Pointer to the ' <code>httpc_data_t</code> ' data handling structure.
<i>certs</i>	Pointer to the ' <code>ssl_certs_t</code> ' for certificates structure.

Returns:

Error code (`httpc_ret_e`). See `api_httpc.h` for more information.

1.9.4 `httpc_ret_e nrc_httpc_delete(con_handle_t *handle, const char *url, const char *custom_header, httpc_data_t *data, ssl_certs_t *certs)`

Send a DELETE request to the specified URL.

Parameters:

<i>handle</i>	Connection handle
<i>url</i>	Destination URL
<i>custom_header</i>	Custom HTTP request header. The headers (" <code><method><uri> HTTP/1.1</code> ") and " <code>Host: <host-name></code> " will be always sent by default. The string <code>custom_header</code> will be appended to the default header.
<i>data</i>	Pointer to the ' <code>httpc_data_t</code> ' data handling structure.
<i>certs</i>	Pointer to the ' <code>ssl_certs_t</code> ' for certificates structure.

Returns:

Error code (`httpc_ret_e`). See `api_httpc.h` for more information.

1.9.5 `httpc_ret_e nrc_httpc_rcv_response(con_handle_t *handle, httpc_data_t *data)`

Retrieves the response data when there're remains after executing the request functions

Parameters:

<i>handle</i>	Connection handle
<i>data</i>	Pointer to the 'httpc_data_t' data handling structure.

Returns:

Error code (`httpc_ret_e`). See `api_httpc.h` for more information.

1.9.6 `void nrc_httpc_close(con_handle_t *handle)`

Close a HTTP connection.

Parameters:

<i>handle</i>	Connection handle
---------------	-------------------

Returns:

N/A

※ Defined structure

```
typedef struct {
    const char *server_cert;    /* Server certification. */
    const char *client_cert;    /* Client certification. */
    const char *client_pk;      /* Client private key. */
    int server_cert_length;     /* Server certification length, server_cert buffer size. */
    int client_cert_length;     /* Client certification length, client_cert buffer size. */
    int client_pk_length;       /* Client private key length, client_pk buffer size. */
} ssl_certs_t;
```

```
typedef struct {
    char *data_out;             /* Pointer of the output buffer for data sending. */
    uint32_t data_out_length;   /* Output buffer length. */
    char *data_in;              /* Pointer of the input buffer for data receiving. */
    uint32_t data_in_length;    /* Input buffer length. */
    int rcvd_size;              /* Actual received data size. */
} httpc_data_t;
```

1.10FOTA

1.10.1 void nrc_fota_write (uint32_t dst, uint8_t *src, uint32_t len)

Write data to the serial flash.

Parameters:

<i>Dst</i>	Destination address in the serial flash
<i>Src</i>	Pointer to the start of the data
<i>Len</i>	Length of the data

Returns:

N/A

1.10.2 void nrc_fota_erase (uint32_t dst, uint32_t len)

Erase the serial flash memory block at the specified address.

Parameters:

<i>dst</i>	Destination address
<i>len</i>	Length of bytes to erase

Returns:

N/A

1.10.3 void nrc_fota_set_info (uint32_t len, uint32_t crc)

Set the firmware metainformation (length and CRC value).

Parameters:

<i>len</i>	Length of the firmware
<i>crc</i>	CRC value of the firmware binary

Returns:

N/A

1.10.4 void nrc_fota_update_done (fota_info_t* fw_info)

Requests the system to update the newly downloaded firmware and reset. The function must be called after the new firmware has been successfully downloaded and stored on the system.

Parameters:

<i>fw_info</i>	Firmware metainformation (length and CRC value)
----------------	---

Returns:

N/A

1.10.5 uint32_t nrc_fota_cal_crc (uint8_t* data, uint32_t len)

Compute and retrieve the CRC value of the data

Parameters:

<i>data</i>	Data
<i>len</i>	Length of the data

Returns:

The CRC value of the data.

※ Defined structure

```
typedef struct {  
    uint32_t fw_length;    /* Length of a firmware binary file */  
    uint32_t crc;          /* CRC of a firmware binary file */  
} fota_info_t;
```


1.11 SerialFlash

1.11.1 `bool nrc_sf_erase_user_config(uint8_t user_area)`

Erase 4KB user config area

Parameters:

<code>user_area</code>	User config area
------------------------	------------------

Returns:

true: success

false: fail

1.11.2 `bool nrc_sf_read_user_config(uint8_t user_area, uint8_t *data, size_t size)`

Read user config data from the `user_config` address of the serial flash

Parameters:

<code>user_area</code>	User config area
<code>data</code>	User config data
<code>size</code>	Length of the data

Returns:

true: success

false: fail

1.11.3 `bool nrc_sf_write_user_config(uint8_t user_area, uint8_t *data, size_t size)`

Write user config data to the `user_config` address of the serial flash

Parameters:

<code>user_area</code>	User config area
<code>data</code>	User config data
<code>size</code>	Length of the data

Returns:

true: success

false: fail

2 Middleware API Reference

2.1 FreeRTOS

FreeRTOS is a market-leading real-time operating system (RTOS) for microcontrollers and small microprocessors.

- Official Website:
 - <https://www.freertos.org/RTOS.html>
- Online Documentation:
 - <https://www.freertos.org/features.html>
- Git Repository:
 - <https://github.com/FreeRTOS/FreeRTOS>

2.2 lwIP

lwIP (lightweight IP) is a widely used open source TCP/IP stack designed for embedded systems.

- Official Website:
 - <http://savannah.nongnu.org/projects/lwip>
- Online Documentation:
 - <http://www.nongnu.org/lwip>
- Git Repository:
 - <https://git.savannah.nongnu.org/git/lwip.git>

2.3 MbedTLS

MbedTLS is an implementation of the TLS and SSL protocols and the respective cryptographic algorithms and support code required.

- Official Website:
 - <https://tls.mbed.org>
- Online API Reference:
 - <https://tls.mbed.org/api>
- GitHub Page:
 - <https://github.com/ARMmbed/mbedtls>

2.4 cJSON

cJSON is an ultralightweight JSON parser in ANSI C.

- GitHub Page:
 - <https://github.com/DaveGamble/cJSON>

2.5 MQTT

MQTT (MQ Telemetry Transport) is an open OASIS and ISO standard (ISO/IEC PRF 20922) lightweight, publish-subscribe network protocol that transports messages between devices. Any network protocol that provides ordered, lossless, bi-directional connections can support MQTT.

- Official Website:
 - <https://mqtt.org/>
- Online Documentation:
 - <http://mqtt.org/documentation>
- GitHub Page:
 - <https://github.com/eclipse/paho.mqtt.embedded-c>

2.6 CoAP

The Constrained Application Protocol (CoAP) is a specialized web transfer protocol (RFC 7252) for use with constrained nodes and constrained networks in the Internet of Things. The protocol is designed for machine-to-machine (M2M) applications such as smart energy and building automation.

- Official website:
 - <https://coap.technology/>
- Specification (RFC 7252):
 - <https://tools.ietf.org/html/rfc7252>
- C-Implementation of CoAP:
 - <https://libcoap.net/>

2.7 Mini-XML

Mini-XML is a tiny XML library that can be used to read and write XML and XML-like data files without requiring large non-standard libraries.

- Official website:
 - <https://www.msweet.org/mxml/>
- Online Documentation:
 - <https://www.msweet.org/mxml/mxml.html>
- GitHub Page:
 - <https://github.com/michaelsweet/mxml>

3 Revision history

Revision No	Date	Comments
Ver 1.0	11/01/2018	Initial version for customer release created
Ver 1.1	03/25/2019	APIs for Wi-Fi, Timer, ADC, and SPI updated
Ver 1.2	04/05/2019	APIs for Wi-Fi, Connection, Timer, I2C, ADC, SPI, PWM updated
Ver 1.3	07/02/2019	APIs for Wi-Fi, Connection updated
Ver 1.4	11/07/2019	Add HTTP Client API and FOTA API
Ver 1.5	07/05/2020	Add Serial Flash API