Syntax
SYNTAX #Id ::= object null SYNTAX Variable ::= #Int SYNTAX VariableName ::= v #Int
SYNTAX MethodName ::= <init></init>
SYNTAX TypeName ::= #Id #Id / TypeName SYNTAX TypeReference ::= < #Id , TypeName > SYNTAX FieldReference ::= < #Id , TypeName , #Id , TypeReference > SYNTAX MethodReference ::= < #Id , TypeName , Selector > none
SYNTAX NewInstructionBase ::= Variable =new TypeReference @ #Int SYNTAX NewInstruction ::= NewInstructionBase NewInstructionBase (Params) SYNTAX GetInstruction ::= Variable =getfield FieldReference Variable Variable =getstatic FieldReference
SYNTAX PutInstruction ::= putfield Variable = Variable FieldReference putstatic Variable FieldReference SYNTAX PhiInstruction ::= Variable = phi (Params) SYNTAX PhiPhiInstruction ::= Variable = phiphi (Params) SYNTAX InvokeSpecialInstruction ::= invokespecial MethodReference Params @ #Int exception: Variable SYNTAX Instruction ::= NewInstruction GetInstruction PutInstruction PhiInstruction PhiInstruction
PhiPhiInstruction return InvokeSpecialInstruction noinstruction SYNTAX BBEdge ::= #Id -> #Id ; SYNTAX BlockBody ::= List{Instruction, ";" }
SYNTAX Block ::= #Id : { BlockBody } SYNTAX TaskUnit ::= BBEdge Block SYNTAX Task ::= TaskUnit Task Task SYNTAX Program ::= MethodDefinition
start analysis done Program +++ Program SYNTAX MethodDefinition ::= MethodReference { Task } END MODULE
MODULE KWALA IMPORTS KWALA-SYNTAX Semantics
Configuration
CONFIGURATION:
method * basicBlocks basicBlock * methodName edges blockName k
methodName edges blockName null noinstruction invocations
cenvs *
null noinstruction 0 0
constraints pointsTo r fieldRead r name fields none"
Processing Basic Blocks
RULE I_1 ; $BBl_2 \Rightarrow I_1 \curvearrowright BBl_2$ RULE Pg_1 +++ $Pg_2 \Rightarrow Pg_1 \curvearrowright Pg_2$ SYNTAX $\textit{ListItem} ::= [\#ld , \#ld]$
RULE $BB_1 \rightarrow BB_2$; MR_1 MR_1 BB_2]
ik mname method
RULE $\left\{\begin{array}{c}BB:\{Bl\}\\ \bullet\end{array}\right\}$ $\left\{\begin{array}{c}MR_1\\ \bullet\\ BB\end{array}\right\}$ $\left\{\begin{array}{c}BB:\{Bl\}\\ \bullet\\ BB\end{array}\right\}$
RULE $BB:\{\}$ MR_1 MR_1 MR_2 MR_3 MR_4 M
RULE $MR_1 \{ T_2 \}$ MR_1 MR_1 MR_1 MR_1 MR_1 MR_1 MR_1 MR_1 MR_1
RULE start
RULE $\frac{\cdot}{\text{analysis}}$ $\frac{-}{\text{none}}$ $\frac{-}{\text{none}}$ $\frac{\cdot}{\text{substitute}}$ $\frac{\cdot}{$
Gathering Constraints
SYNTAX K ::= wrappedList(Bag) Phi functions
RULE $V_t = \text{phi}(P)$ NP
V_{i} = phi phi (P_{i}) V_{i}
$V_I = \text{phiphi}(P)$ $V_I \mapsto NP$ $NP + I_{Int} 1$ invocation k variables cenvs
$\begin{array}{c} \text{ invocation} \\ \\ \text{ V_1 = phiphi(V_2, P)} \end{array} \begin{array}{c} \text{ V_2 in $RestSet$} \\ \text{ V_1 = phiphi(V_2, P)} \end{array} \begin{array}{c} \text{ V_1 in $RestSet$} \\ \text{ V_2 in $RestSet$} \end{array}$
RULE
$ \begin{array}{c} \text{RULE} & \begin{array}{c} \text{Invocation} \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phiphi} \left(V_{S} \ , \ P \right) \\ \hline \\ V_{t} = \text{phi} \left(V_{S} $
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$SULL = \begin{bmatrix} P_{p} & P_{$
$ \begin{array}{c} \text{Total Distributions} \\ \text{Trial Particle } V_{1} = \text{Particle } V_{2} \cdot V_{2} + V_{2} + V_{3} \\ \text{Total Distributions} \\ \text{Trial Distributions} \\ Trial Distribu$
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