

# HyperNova: (Multi-Folding Scheme)

removing of cross-terms.

## #1: Revisit R1CS:

$$A, B, C \in \mathbb{F}^{m \times m}$$

assignment  $\vec{z} = (\vec{x}, 1, \vec{w}) \in \mathbb{F}^m$

public inputs  $\vec{x}$       witness  $\vec{w}$

$$(A \cdot \vec{z}) \circ (B \cdot \vec{z}) = C \cdot \vec{z} \Rightarrow \begin{cases} \vec{V}_A = A \cdot \vec{z}, \vec{V}_B = B \cdot \vec{z}, \vec{V}_C = C \cdot \vec{z} & (\text{Lin-check}) \\ \vec{V}_A \circ \vec{V}_B = \vec{V}_C & (\text{Row-check}) \end{cases}$$

## #2: MLE and Sumcheck.

$$\vec{a} \in \mathbb{F}^n, \quad \tilde{a}(\vec{x}) = a_i, \quad \forall \vec{x} \in \{0, 1\}^s, \quad s = \log(n)$$

$$\tilde{a}(\vec{y}) = \sum_{\vec{x} \in \{0, 1\}^s} a_i \cdot \tilde{e}_q(\vec{x}, \vec{y})$$

Lagrange Polynomial

$$\tilde{e}_q(\vec{x}, \vec{y}) = \prod_i [x_i y_i + (1 - x_i) \cdot (1 - y_i)]$$

$\tilde{a}(x)$  is the encoding of  $\vec{a}$

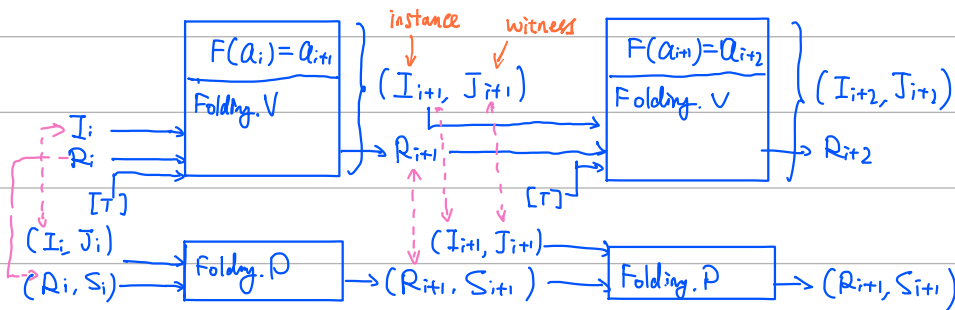
Sumcheck can reduce summation to polynomial evaluation:

$$\sum_{\vec{x} \in \{0, 1\}^s} \tilde{a}(\vec{x}) \stackrel{?}{=} h$$

$\Uparrow$

$$\tilde{a}(\vec{r}) \stackrel{?}{=} h'$$

## #3: Revisit Nova. (IVC scheme)



#### #4: Multi-Folding Scheme.

Incremental Instance-Witness:  $(\vec{x}_1, [\vec{w}_1]; \vec{w}_1)$

$$\vec{z}_1 = (\vec{x}_1, 1, \vec{w}_1)$$

Running Instance-Witness:  $(\vec{x}_2, [\vec{w}_2], u, \vec{r}, \vec{V}_A, \vec{V}_B, \vec{V}_C; \vec{w}_2)$

$$\vec{z}_2 = (\vec{x}_2, u, \vec{w}_2)$$

Folding. P

Folding. V

$$\leftarrow \alpha, \vec{\beta} \in \mathbb{F}^S$$

$$G(\vec{x}) \triangleq Q(\vec{x}) + \alpha \cdot L_A(\vec{x}) + \alpha^2 \cdot L_B(\vec{x}) + \alpha^3 \cdot L_C(\vec{x})$$

$$\begin{aligned} \vec{V}_A &\stackrel{?}{=} L_A(\vec{x}) \triangleq \tilde{eq}(\vec{r}, \vec{x}) \cdot \tilde{V}_{A,2}(\vec{x}) \\ \vec{V}_B &\stackrel{?}{=} L_B(\vec{x}) \triangleq \tilde{eq}(\vec{r}, \vec{x}) \cdot \tilde{V}_{B,2}(\vec{x}) \\ \vec{V}_C &\stackrel{?}{=} L_C(\vec{x}) \triangleq \tilde{eq}(\vec{r}, \vec{x}) \cdot \tilde{V}_{C,2}(\vec{x}) \end{aligned} \quad \left. \vphantom{\begin{aligned} \vec{V}_A \\ \vec{V}_B \\ \vec{V}_C \end{aligned}} \right\} \text{Lin-check}$$

Row-check

$$\begin{cases} \tilde{V}_{A,1}(\vec{x}) = \sum_{\vec{y}} \tilde{A}(\vec{x}, \vec{y}) \cdot \vec{z}_1(\vec{y}) & (A \cdot \vec{z}_1) \\ \tilde{V}_{B,1}(\vec{x}) = \sum_{\vec{y}} \tilde{B}(\vec{x}, \vec{y}) \cdot \vec{z}_1(\vec{y}) & (B \cdot \vec{z}_1) \\ \tilde{V}_{C,1}(\vec{x}) = \sum_{\vec{y}} \tilde{C}(\vec{x}, \vec{y}) \cdot \vec{z}_1(\vec{y}) & (C \cdot \vec{z}_1) \end{cases}$$

$$\begin{cases} \tilde{V}_{A,2}(\vec{x}) = \sum_{\vec{y}} \tilde{A}(\vec{x}, \vec{y}) \cdot \vec{z}_2 & (A \cdot \vec{z}_2) \\ \tilde{V}_{B,2}(\vec{x}) = \sum_{\vec{y}} \tilde{B}(\vec{x}, \vec{y}) \cdot \vec{z}_2 & (B \cdot \vec{z}_2) \\ \tilde{V}_{C,2}(\vec{x}) = \sum_{\vec{y}} \tilde{C}(\vec{x}, \vec{y}) \cdot \vec{z}_2 & (C \cdot \vec{z}_2) \end{cases}$$

$$0 \stackrel{?}{=} Q(\vec{x}) \triangleq \tilde{eq}(\vec{\beta}, \vec{x}) \cdot [\tilde{V}_{A,1}(\vec{x}) \cdot \tilde{V}_{B,1}(\vec{x}) - \tilde{V}_{C,1}(\vec{x})]$$

$$\begin{aligned} &\text{sumcheck:} \\ &\sum_{\vec{x}} G(\vec{x}) \stackrel{?}{=} 0 + \alpha \cdot \vec{V}_A + \alpha^2 \cdot \vec{V}_B + \alpha^3 \cdot \vec{V}_C \\ &\leftarrow G(\vec{r}') \stackrel{?}{=} h' \end{aligned}$$

$$V_{A,1} = \tilde{V}_{A,1}(\vec{r}')$$

$$V_{B,1} = \tilde{V}_{B,1}(\vec{r}')$$

$$V_{C,1} = \tilde{V}_{C,1}(\vec{r}')$$

$$V_{A,2} = \tilde{V}_{A,2}(\vec{r}')$$

$$V_{B,2} = \tilde{V}_{B,2}(\vec{r}')$$

$$V_{C,2} = \tilde{V}_{C,2}(\vec{r}')$$

$$\underline{(V_{A,1}, V_{B,1}, V_{C,1}, V_{A,2}, V_{B,2}, V_{C,2})}$$

$$e_1 = \tilde{eq}(\vec{\beta}, \vec{r}')$$

$$e_2 = \tilde{eq}(\vec{r}, \vec{r}')$$

$$\begin{cases} \alpha \cdot e_2 \cdot V_{A,2} + \alpha^2 \cdot e_2 \cdot V_{B,2} + \alpha^3 \cdot e_2 \cdot V_{C,2} \stackrel{?}{=} h \\ (V_{A,1} \cdot V_{B,1} - V_{C,1}) \cdot e_1 \stackrel{?}{=} 0 \end{cases}$$

$$\leftarrow \rho$$

$$[\vec{w}^*] = [\vec{w}_2] + \rho \cdot [\vec{w}_1]$$

$$\vec{x}^* = \vec{x}_2 + \rho \cdot \vec{x}_1$$

$$u^* = u_2 + \rho \cdot 1$$

$$\vec{w}^* = \vec{w}_2 + \rho \cdot \vec{w}_1$$

$$\vec{r}^* = \vec{r}'$$

$$\vec{V}_A^* = V_{A,2} + \rho \cdot V_{A,1}$$

$$\vec{V}_B^* = V_{B,2} + \rho \cdot V_{B,1}$$

$$\vec{V}_C^* = V_{C,2} + \rho \cdot V_{C,1}$$