

DOOR ACCESS CONTROL SYSTEM WITH FACE RECOGNITION

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PROBLEM STATEMENT

Door access control system using face
recognition



Why we've chosen it

In today's world, home security is of utmost priority. IOT (Internet of Things) being an emerging technology can be used along with facial recognition to make our task of providing smart home security easier, simpler and foolproof.

The Face Detection System (FDRS) is a technology that recognizes body features by using mathematical factors inherent in human appearance. This technology is easy to use and secure. The Internet of Things (IoT) is a popular technology that allows you to track and control harmful devices in your house. Identifying a person to enter and exit the house is an important aspect of a home security system.

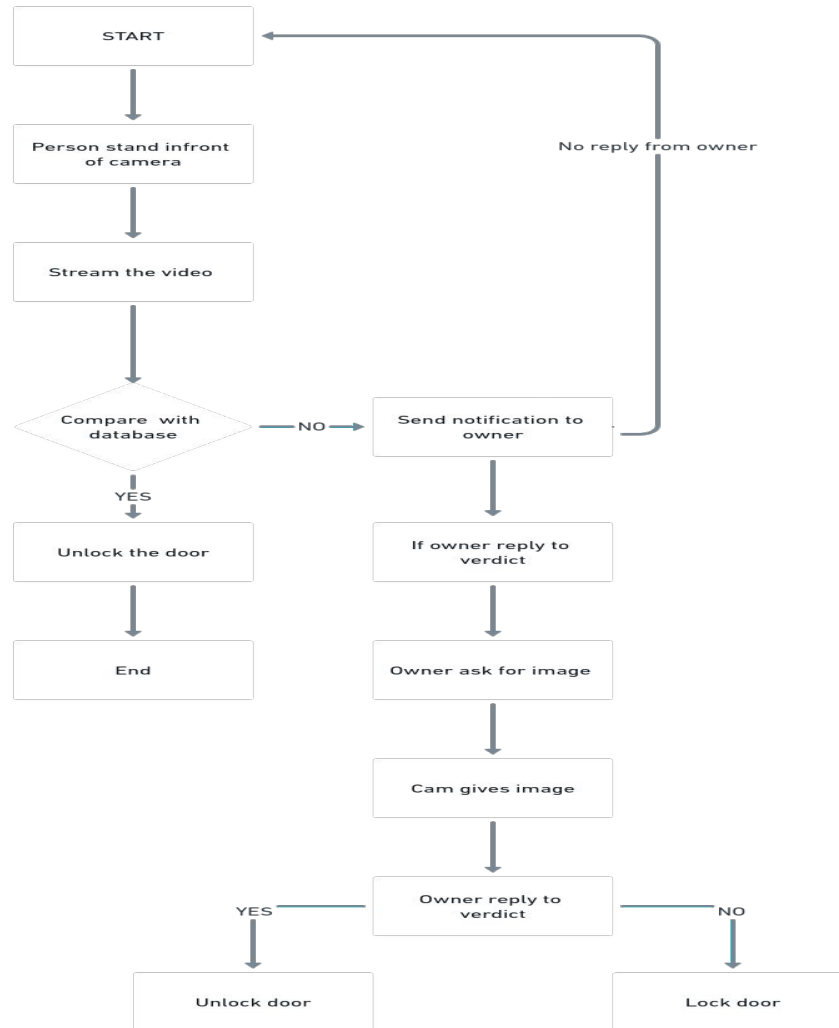


APPLICATION

The aim of this project is to assist users for improvement of the door security of sensitive locations by using face detection and recognition. The proposed system mainly consists of subsystems namely image capture, face detection and recognition, notification and automatic door access management. Face Recognition supported openCV is brought up because it uses Eigen faces(it utilizes linear algebra and Principal Component Analysis (PCA) to perform face recognition). and reduces the scale of face images without losing vital features, facial images for many persons can be stored in the database. The door lock can also be accessed remotely from any part of the room. The captured image from esp32 camera will be sent to the authorized person.



USE CASE DIAGRAM





SOLUTION

- **HARDWARE requirements**
 - ESP32 CAM WiFi Module Bluetooth with OV2640 Camera Module 2MP For Face Recognition
 - FT232RL USB to TTL 3.3V 5.5V Serial Adapter Module
 - Bread Board
 - Arduino Uno
 - Jumper wires
 - Serial port USB cable 5V mini
 - Electronic door lock 12V
 - PCB Mounted Passive Buzzer Module
 - 2 Channel 5V Relay Module with Optocoupler
 - Battery
- **Software requirements**
 - OpenCV python package
 - Arduino software
 - Web Browser
 - Raspberry Pi/ PC as server
- **Technology/language requirements**
 - C++/C
 - Python



Deliverable

User can expect:

- Fully functional Facial recognition device.
- User also get a list of people with time who are coming in front of camera.
- The device setup also consist of a strong solenoid lock.
- For security purposes, video streaming can only be seen if both the devices are on same network.



Timeline

Module 1 - Connect esp32 cam with PC and stream the data in real time from esp32 to processing unit, and for security purpose we are transferring the data directly by wifi. The only requirement is that both sender and receiver has to be connected to that same wifi service.

Module 2 - Processing unit is able to process the real time stream, applies Face Recognition model and check that person in our database. It then sends the verdict to the solenoid lock. If it is “YES”, we open the lock, else we take some photos of that person, and send them to the user. If user allows that person, lock opens and that person is registered in the database else the lock remains closed. Also if user ignores, then that is interpreted as “NO”.

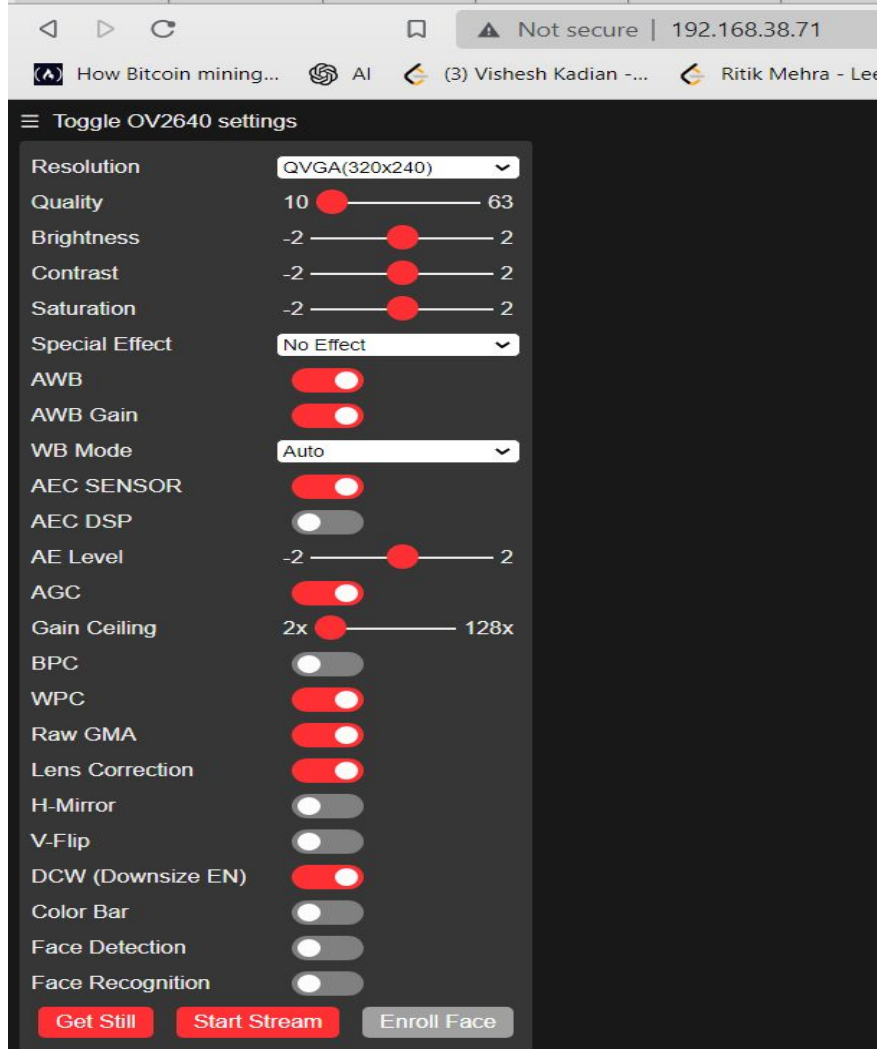
Module 3 - With the given verdict processing unit is able to open the lock and also maintaining a excel sheet by which client can get info about who is entering at what time.



Implementation of Module 1










- Screenshot
- Readme file Explaining in details how to run your code
- Code
- Sample input/output


Screenshot of ESP32 Website where video is streamed



Video streamed on site

☰ Toggle OV2640 settings

Resolution	QVGA(320x240) ▼
Quality	10  63
Brightness	-2  2
Contrast	-2  2
Saturation	-2  2
Special Effect	No Effect ▼
AWB	
AWB Gain	
WB Mode	Auto ▼
AEC SENSOR	
AEC DSP	
AE Level	-2  2



A video stream showing a person sitting at a desk with electronic equipment, including a camera and various cables. The video is displayed in a window with a red close button in the top right corner.

Continuous Image Transfer log

COM7

Send

```
02:13:17.196 -> MJPG: 3880B 39ms (25.6fps), AVG: 42ms (23.8fps), 0+0+0+0=0 0
02:13:17.242 -> MJPG: 3881B 38ms (26.3fps), AVG: 43ms (23.3fps), 0+0+0+0=0 0
02:13:17.289 -> MJPG: 3864B 39ms (25.6fps), AVG: 43ms (23.3fps), 0+0+0+0=0 0
02:13:17.334 -> MJPG: 3858B 56ms (17.9fps), AVG: 44ms (22.7fps), 0+0+0+0=0 0
02:13:17.382 -> MJPG: 3894B 31ms (32.3fps), AVG: 41ms (24.4fps), 0+0+0+0=0 0
02:13:17.382 -> MJPG: 3866B 31ms (32.3fps), AVG: 43ms (23.3fps), 0+0+0+0=0 0
02:13:17.427 -> MJPG: 3861B 40ms (25.0fps), AVG: 41ms (24.4fps), 0+0+0+0=0 0
02:13:17.518 -> MJPG: 4000B 76ms (13.2fps), AVG: 43ms (23.3fps), 0+0+0+0=0 0
02:13:17.518 -> MJPG: 3977B 14ms (71.4fps), AVG: 40ms (25.0fps), 0+0+0+0=0 0
02:13:17.560 -> MJPG: 3956B 28ms (35.7fps), AVG: 41ms (24.4fps), 0+0+0+0=0 0
02:13:17.601 -> MJPG: 3909B 47ms (21.3fps), AVG: 41ms (24.4fps), 0+0+0+0=0 0
02:13:17.638 -> MJPG: 3915B 33ms (30.3fps), AVG: 41ms (24.4fps), 0+0+0+0=0 0
02:13:17.684 -> MJPG: 3894B 59ms (16.9fps), AVG: 40ms (25.0fps), 0+0+0+0=0 0
02:13:17.730 -> MJPG: 3901B 20ms (50.0fps), AVG: 41ms (24.4fps), 0+0+0+0=0 0
02:13:17.730 -> MJPG: 3898B 39ms (25.6fps), AVG: 39ms (25.6fps), 0+0+0+0=0 0
```

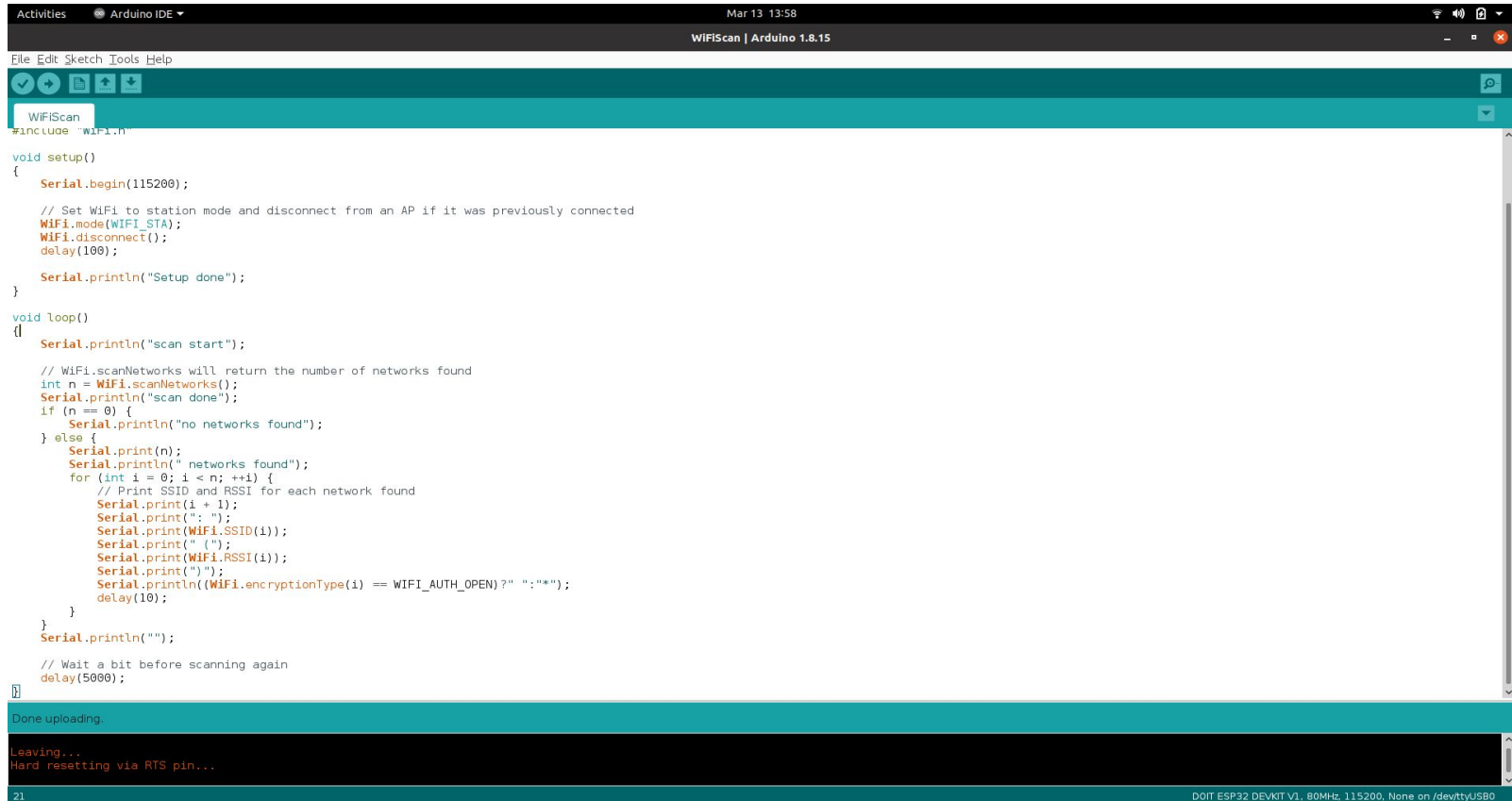
☒ Autoscroll ☒ Show timestamp

Newline

115200 baud

Clear output

Code Screenshots



The screenshot shows the Arduino IDE interface. The top bar indicates the date and time as "Mar 13 13:58" and the current sketch is "WiFiScan | Arduino 1.8.15". The menu bar includes "File", "Edit", "Sketch", "Tools", and "Help". The toolbar contains icons for opening, saving, and running the sketch. The main text area displays the following C++ code:

```
#include <WiFi.h>

void setup()
{
    Serial.begin(115200);

    // Set WiFi to station mode and disconnect from an AP if it was previously connected
    WiFi.mode(WIFI_STA);
    WiFi.disconnect();
    delay(100);

    Serial.println("Setup done");
}

void loop()
{
    Serial.println("scan start");

    // WiFi.scanNetworks will return the number of networks found
    int n = WiFi.scanNetworks();
    Serial.println("scan done");
    if (n == 0) {
        Serial.println("no networks found");
    } else {
        Serial.print(n);
        Serial.println(" networks found");
        for (int i = 0; i < n; ++i) {
            // Print SSID and RSSI for each network found
            Serial.print(i + 1);
            Serial.print(": ");
            Serial.print(WiFi.SSID(i));
            Serial.print(" (");
            Serial.print(WiFi.RSSI(i));
            Serial.print(")");
            Serial.println((WiFi.encryptionType(i) == WIFI_AUTH_OPEN) ? " : *" : "");
            delay(10);
        }
    }
    Serial.println("");

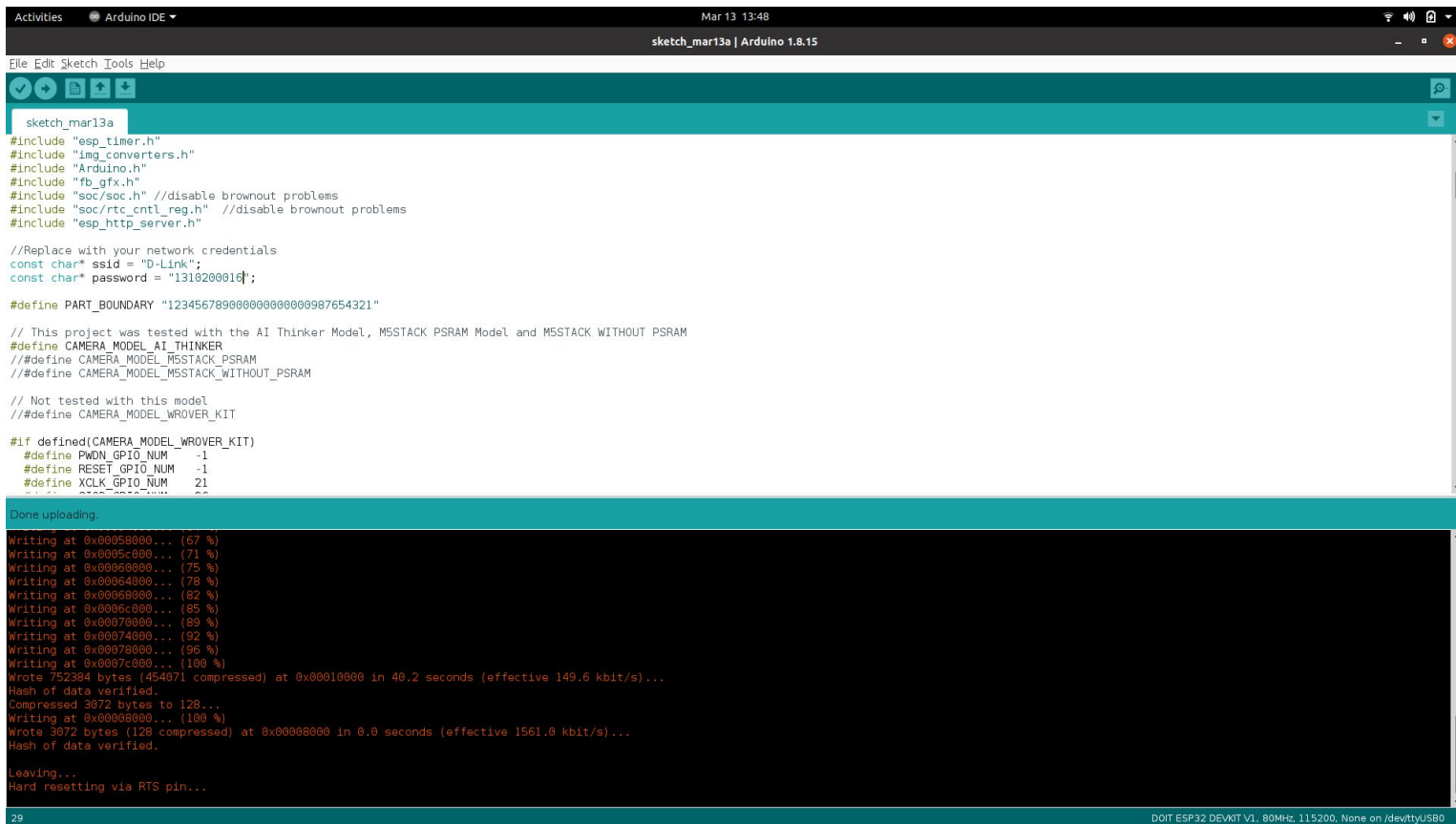
    // Wait a bit before scanning again
    delay(5000);
}
```

At the bottom of the IDE, a teal progress bar shows "Done uploading." Below this, a black status bar displays the following messages:

```
Leaving...
Hard resetting via RTS pin...
```

The bottom status bar of the IDE shows the board and port information: "21 DOIT ESP32 DEVKIT V1, 80MHz, 115200, None on /dev/ttyUSB0".

Code Screenshots



```
Activities Arduino IDE Mar 13 13:48
sketch_mar13a | Arduino 1.8.15

File Edit Sketch Tools Help

sketch_mar13a

#include "esp_timer.h"
#include "img_converters.h"
#include "Arduino.h"
#include "fb_gfx.h"
#include "soc/soc.h" //disable brownout problems
#include "soc/rtc_cntl_reg.h" //disable brownout problems
#include "esp_http_server.h"

//Replace with your network credentials
const char* ssid = "D-Link";
const char* password = "1310200016";

#define PART_BOUNDARY "12345678900000000000000987654321"

// This project was tested with the AI Thinker Model, MSSTACK PSRAM Model and MSSTACK WITHOUT PSRAM
#define CAMERA_MODEL_AI_THINKER
// #define CAMERA_MODEL_MSSTACK_PSRAM
// #define CAMERA_MODEL_MSSTACK_WITHOUT_PSRAM

// Not tested with this model
// #define CAMERA_MODEL_WROVER_KIT

#if defined(CAMERA_MODEL_WROVER_KIT)
  #define PWDN_GPIO_NUM    -1
  #define RESET_GPIO_NUM  -1
  #define XCLK_GPIO_NUM    21
  #define YP_GPIO_NUM      32
  #define YN_GPIO_NUM      33
  #define YB_GPIO_NUM      34
  #define VBUS_GPIO_NUM    35
  #define PWDN_GPIO_NUM    38
  #define RESET_GPIO_NUM  39
  #define XCLK_GPIO_NUM    40
  #define YP_GPIO_NUM      41
  #define YN_GPIO_NUM      42
  #define YB_GPIO_NUM      43
  #define VBUS_GPIO_NUM    44
  #define PWDN_GPIO_NUM    45
  #define RESET_GPIO_NUM  46
  #define XCLK_GPIO_NUM    47
  #define YP_GPIO_NUM      48
  #define YN_GPIO_NUM      49
  #define YB_GPIO_NUM      50
  #define VBUS_GPIO_NUM    51
  #define PWDN_GPIO_NUM    52
  #define RESET_GPIO_NUM  53
  #define XCLK_GPIO_NUM    54
  #define YP_GPIO_NUM      55
  #define YN_GPIO_NUM      56
  #define YB_GPIO_NUM      57
  #define VBUS_GPIO_NUM    58
  #define PWDN_GPIO_NUM    59
  #define RESET_GPIO_NUM  60
  #define XCLK_GPIO_NUM    61
  #define YP_GPIO_NUM      62
  #define YN_GPIO_NUM      63
  #define YB_GPIO_NUM      64
  #define VBUS_GPIO_NUM    65
  #define PWDN_GPIO_NUM    66
  #define RESET_GPIO_NUM  67
  #define XCLK_GPIO_NUM    68
  #define YP_GPIO_NUM      69
  #define YN_GPIO_NUM      70
  #define YB_GPIO_NUM      71
  #define VBUS_GPIO_NUM    72
  #define PWDN_GPIO_NUM    73
  #define RESET_GPIO_NUM  74
  #define XCLK_GPIO_NUM    75
  #define YP_GPIO_NUM      76
  #define YN_GPIO_NUM      77
  #define YB_GPIO_NUM      78
  #define VBUS_GPIO_NUM    79
  #define PWDN_GPIO_NUM    80
  #define RESET_GPIO_NUM  81
  #define XCLK_GPIO_NUM    82
  #define YP_GPIO_NUM      83
  #define YN_GPIO_NUM      84
  #define YB_GPIO_NUM      85
  #define VBUS_GPIO_NUM    86
  #define PWDN_GPIO_NUM    87
  #define RESET_GPIO_NUM  88
  #define XCLK_GPIO_NUM    89
  #define YP_GPIO_NUM      90
  #define YN_GPIO_NUM      91
  #define YB_GPIO_NUM      92
  #define VBUS_GPIO_NUM    93
  #define PWDN_GPIO_NUM    94
  #define RESET_GPIO_NUM  95
  #define XCLK_GPIO_NUM    96
  #define YP_GPIO_NUM      97
  #define YN_GPIO_NUM      98
  #define YB_GPIO_NUM      99
  #define VBUS_GPIO_NUM   100

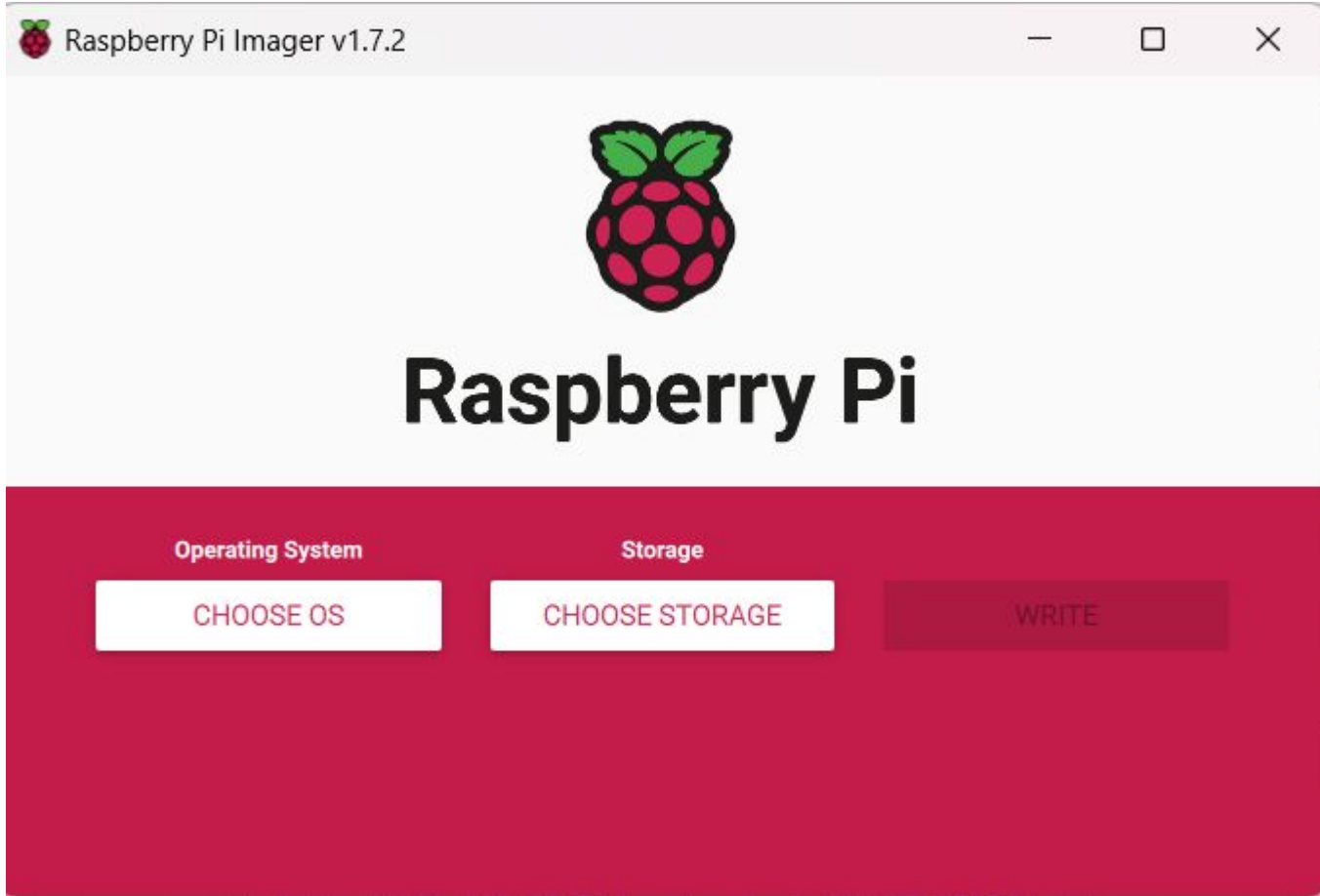
Done uploading.

Writing at 0x00050000... (67 %)
Writing at 0x0005c000... (71 %)
Writing at 0x00060000... (75 %)
Writing at 0x00064000... (78 %)
Writing at 0x00068000... (82 %)
Writing at 0x0006c000... (85 %)
Writing at 0x00070000... (89 %)
Writing at 0x00074000... (92 %)
Writing at 0x00078000... (96 %)
Writing at 0x0007c000... (100 %)
Wrote 752384 bytes (454071 compressed) at 0x00010000 in 40.2 seconds (effective 149.6 kbit/s)...
Hash of data verified.
Compressed 3072 bytes to 128...
Writing at 0x00000000... (100 %)
Wrote 3072 bytes (128 compressed) at 0x00000000 in 0.0 seconds (effective 1561.0 kbit/s)...
Hash of data verified.

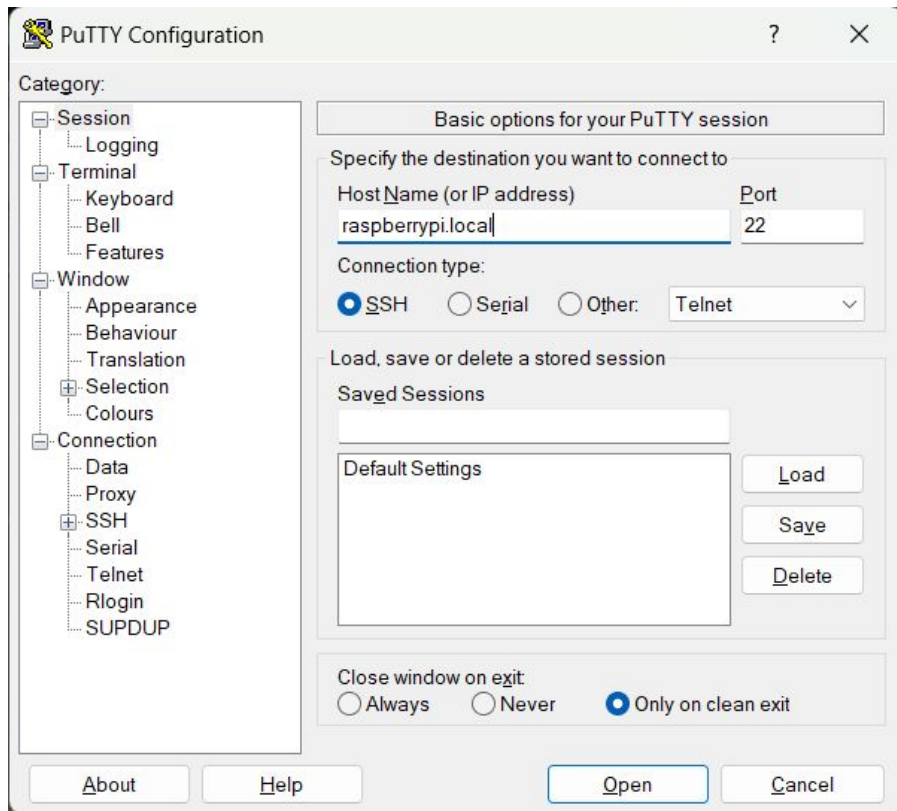
Leaving...
Hard resetting via RTS pin...

29 DOIT ESP32 DEVKIT V1, 80MHz, 115200, None on /dev/ttyUSB0
```

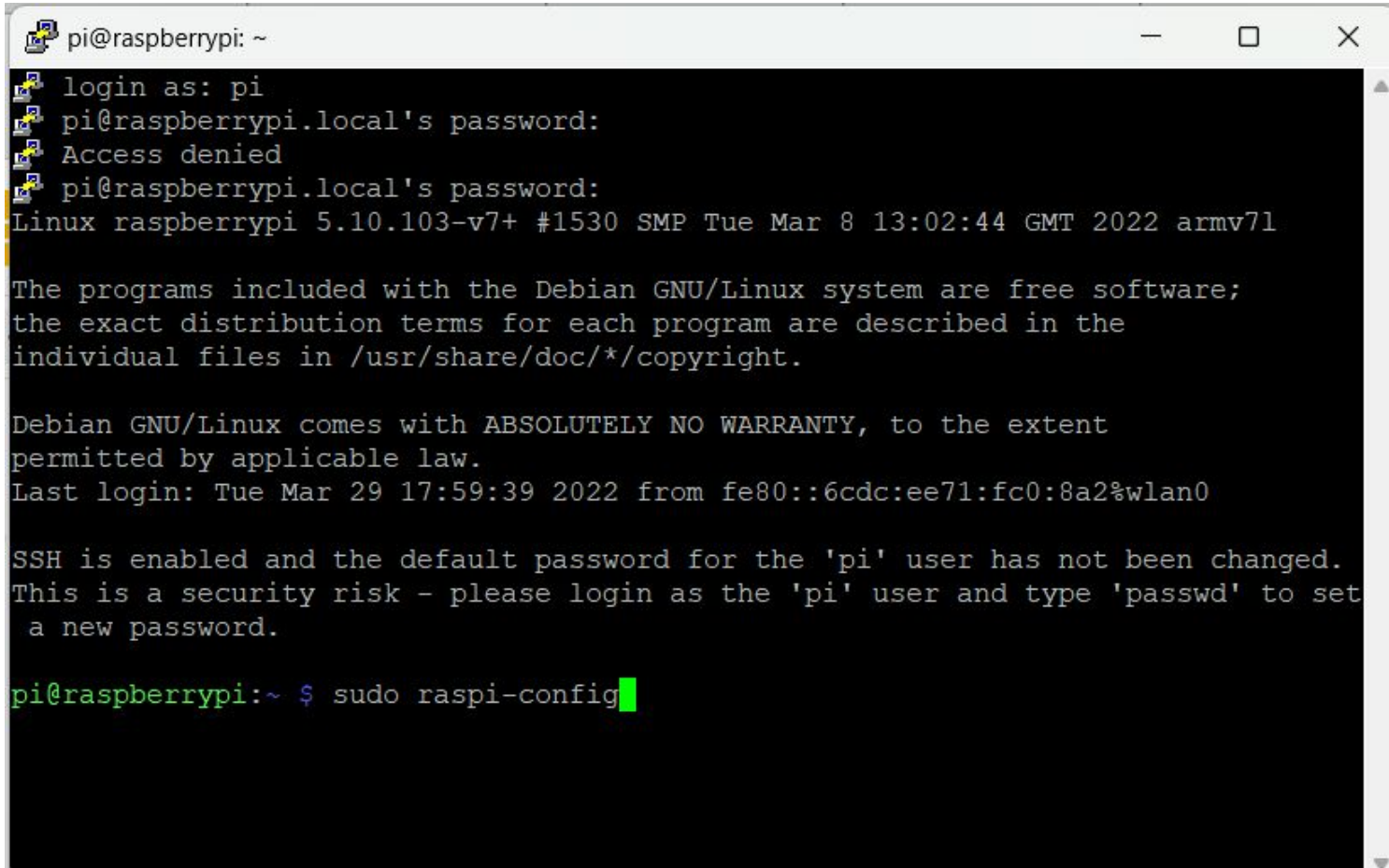
Using Raspberry Pi imager to write on disk



Setting PuTTY for configuration



Configuring raspberry pi



```
pi@raspberrypi: ~  
login as: pi  
pi@raspberrypi.local's password:  
Access denied  
pi@raspberrypi.local's password:  
Linux raspberrypi 5.10.103-v7+ #1530 SMP Tue Mar 8 13:02:44 GMT 2022 armv7l  
  
The programs included with the Debian GNU/Linux system are free software;  
the exact distribution terms for each program are described in the  
individual files in /usr/share/doc/*/copyright.  
  
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent  
permitted by applicable law.  
Last login: Tue Mar 29 17:59:39 2022 from fe80::6cdc:ee71:fc0:8a2%wlan0  
  
SSH is enabled and the default password for the 'pi' user has not been changed.  
This is a security risk - please login as the 'pi' user and type 'passwd' to set  
a new password.  
  
pi@raspberrypi:~ $ sudo raspi-config
```

Raspberry Pi 3 Model B Plus Rev 1.3

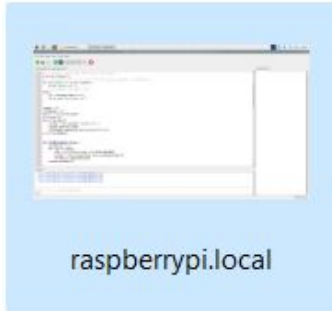
Raspberry Pi Software Configuration Tool (raspi-config)

- | | | |
|---|----------------------|---|
| 1 | System Options | Configure system settings |
| 2 | Display Options | Configure display settings |
| 3 | Interface Options | Configure connections to peripherals |
| 4 | Performance Options | Configure performance settings |
| 5 | Localisation Options | Configure language and regional settings |
| 6 | Advanced Options | Configure advanced settings |
| 8 | Update | Update this tool to the latest version |
| 9 | About raspi-config | Information about this configuration tool |

<Select>

<Finish>

Using VNC viewer to display Raspi's screen





Thonny - <untitled> @ 1:4

New Load Save Run Debug Over Into Out Stop Zoom Quit [Switch to regular mode](#)

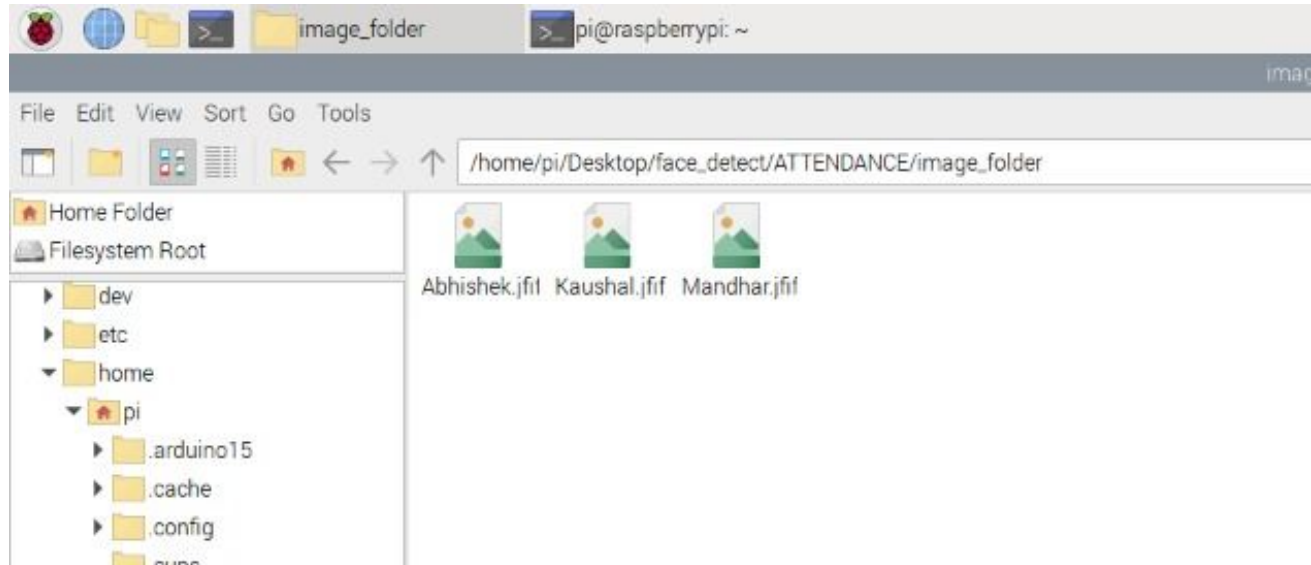
<untitled> *
1 SSS

Shell
Python 3.9.2 (/usr/bin/python3)
>>>


Python 3.9.2

Implementation of Module 2

In this module, we implemented the machine learning part in Raspi and ran a successful facial recognition. We have a folder named `image_folder` that contains images of all the person allowed to enter. We feed those images to our machine learning algorithm to train it so that it can recognize them whenever they come in front of camera. The screenshots of the same are attached here.



Implementation of Module 2



All the important packages are imported including matplotlib.image which is used to handle images and datetime, face_recognition to recognize faces

```
> IoT Face Recognition > face-detect > home > pi > Desktop > face_de
1  import matplotlib.image as mpimg
2  import matplotlib.pyplot as plt
3  import pandas as pd
4  import cv2
5  import urllib.request
6  import numpy as np
7  import os
8  from datetime import datetime
9  import face_recognition
10 #####
11 # For buzzer -----
12 import RPi.GPIO as GPIO
13 from time import sleep
14 #Disable warnings (optional)
15 GPIO.setwarnings(False)
16 #Select GPIO mode
17 GPIO.setmode(GPIO.BCM)
18 #Set buzzer - pin 23 as output
19 buzzer=23
20 GPIO.setup(buzzer,GPIO.OUT)
21 redlight = 22
22 greenlight = 27
23 #####
```


Implementation of Module 2



This is where we set the path of the training data set containing images of all the authorized people and the url to the live streaming of esp32 cam. Both are stored in their respective variables.

```
#
path = "/home/pi/Desktop/face_detect/DoorLockUnlock/image_folder"
# url = 'http://192.168.135.71' #/cam-hi.jpg'
url = r"http://192.168.214.71/capture?_cb=1649673650721.jpg"
##'''cam.bmp / cam-lo.jpg /cam-hi.jpg / cam.mjpeg '''
print(os.listdir())
# if 'Attendance.csv' in os.listdir(os.path.join(os.getcwd(), 'attendace')):
```


Implementation of Module 2



This section right here shows two functions, findEncodings which is used to find encodings in a n image and another is markAttendance, which is used to mark the entry time of any person who enters through the door.

```
def findEncodings(images):
    encodeList = []
    for img in images:
        img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
        encode = face_recognition.face_encodings(img)[0]
        encodeList.append(encode)
    return encodeList

def markAttendance(name):
    with open("EntryTime.csv", 'r+') as f:
        myDataList = f.readlines()
        nameList = []
        for line in myDataList:
            entry = line.split(',')
            nameList.append(entry[0])
            if name not in nameList:
                now = datetime.now()
                dtString = now.strftime('%H:%M:%S')
                f.writelines(f'\n{name},{dtString}')

encodeListKnown = findEncodings(images)
print('Encoding Complete')
```



Implementation of Module 2

Now from this while loop, our main logic starts. This while loop make sure that the esp32 cam runs constantly and in each run, we capture the livestream, check if there is someone in front of the camera, and if there is a person, there are two scenarios created:

1. **Person is known** : In this case, the door simply unlocks and allows the person to enter
2. **Person is Unknown** : In this scenario, a photo is take of the intruder, and sent to the owner. Now the owner has to allow or disallow the intruder.

```
7  while True:
8
9      #success, img = cap.read()
10     print(url)
11     img_resp = urllib.request.urlopen(url)
12     imgnp = np.array(bytearray(img_resp.read()), dtype=np.uint8)
13     img = cv2.imdecode(imgnp, -1)
14     # print(img)
15     # im = cv.LoadImage(url)
16     # a = np.asarray(img)
17     # cv2.imshow(a)
18     # img = captureScreen()
19     imgS = cv2.resize(img, (0, 0), None, 0.25, 0.25)
20     imgS = cv2.cvtColor(imgS, cv2.COLOR_BGR2RGB)
21     imgS = img
22     # cv2.imshow(imgS)
23
24     facesCurFrame = face_recognition.face_locations(imgS)
25     encodesCurFrame = face_recognition.face_encodings(imgS, facesCurFrame)
26
27     for encodeFace, faceLoc in zip(encodesCurFrame, facesCurFrame):
28         matches = face_recognition.compare_faces(encodeListKnown, encodeFace)
29         faceDis = face_recognition.face_distance(encodeListKnown, encodeFace)
30     # print(faceDis)
31     matchIndex = np.argmin(faceDis)
32     if matches[matchIndex]:
33         #print(matchIndex)
34         name = classNames[matchIndex].upper()
35
36         print(name)
37
38         y1, x2, y2, x1 = faceLoc
39         y1, x2, y2, x1 = y1 * 4, x2 * 4, y2 * 4, x1 * 4
40         cv2.rectangle(img, (x1, y1), (x2, y2), (0, 255, 0), 2)
```

Implementation of Module 3



This part is handled here. When the person is not recognized, we take a snap from the livestream, save it as *test.jpg*, and send it our app which is hosted at herokuapp. Our app has a basic functionality. The image of the intruder is shown and there are two options, YES, or NO. If the owner hits YES, the intruder is given the permission to enter, or else the intruder is disallowed. If the owner does not respond, the intruder is disallowed automatically after 20 seconds.

```
print("Not Match\n")

#save image
urllib.request.urlretrieve(url, "test.jpg")

##sending image part
with open("test.jpg", "rb") as img_file:
    my_string = base64.b64encode(img_file.read())

url1 = 'https://iot-door-lock-system.herokuapp.com/send'

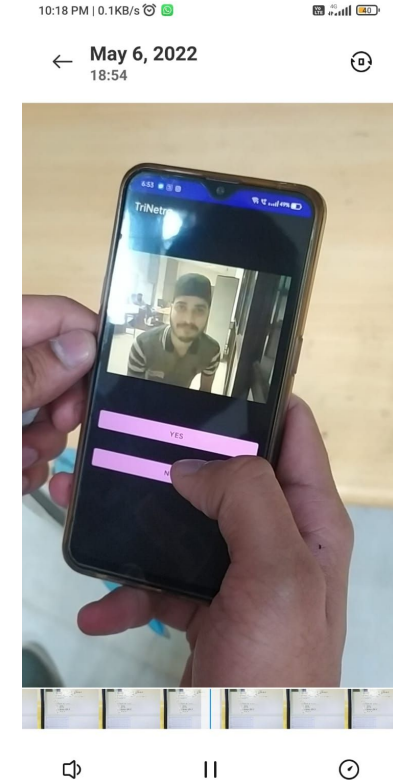
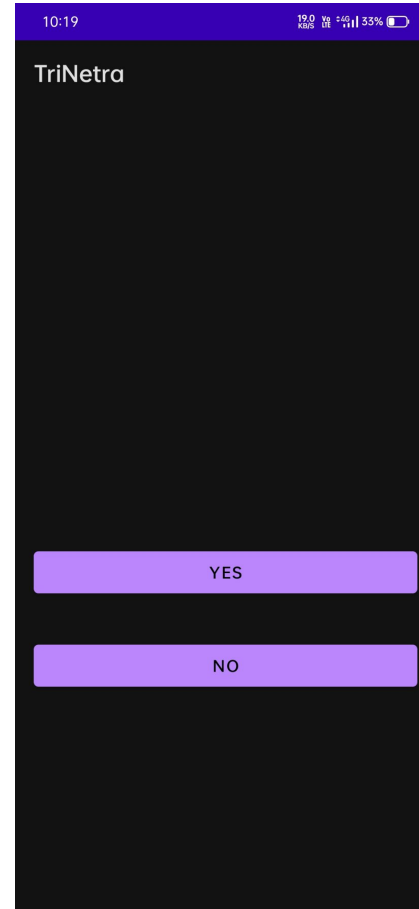
r = requests.post('https://iot-door-lock-system.herokuapp.com/send', json={
    "Id": 78912,
    "Customer": "Unknown",
    "Quantity": 1,
    "Price": 18.00,
    "file": my_string.decode("utf-8")
})
print(r.text)

time.sleep(20)
##

##check
url1 = 'https://iot-door-lock-system.herokuapp.com/doorstate'
response = requests.get(url1)
data = response.json()
print(data['msg'])
if(data['msg']=="NO"):
    #don't open raspberry pi
    i = 0
    GPIO.output(buzzer,GPIO.HIGH)
```

Implementation of Module 3

This is the UI of our app. It displays a photo of the intruder and gives two options to the user, Yes(to allow) and No(to disallow).





Final Results

Below attached are the screenshots of verdict given by our Machine Learning Model.

<http://192.168.38.71/capture?cb=1649673650721.jpg>

MANDHAR

When an unknown person comes in front of camera

```
81 encodesCurFrame = face_recognition.face_encodings(imgs, facesC
82
83 for encodeFace, faceLoc in zip(encodesCurFrame, facesCurFrame)
84     compare_faces(encodeListKnown,
85     face_distance(encodeListKnown,
86 # F
87     Dis)
88
89
90     Index].upper()
91
92
93
94 c
95 , x2 * 4, y2 * 4, x1 * 4
```



Shell x

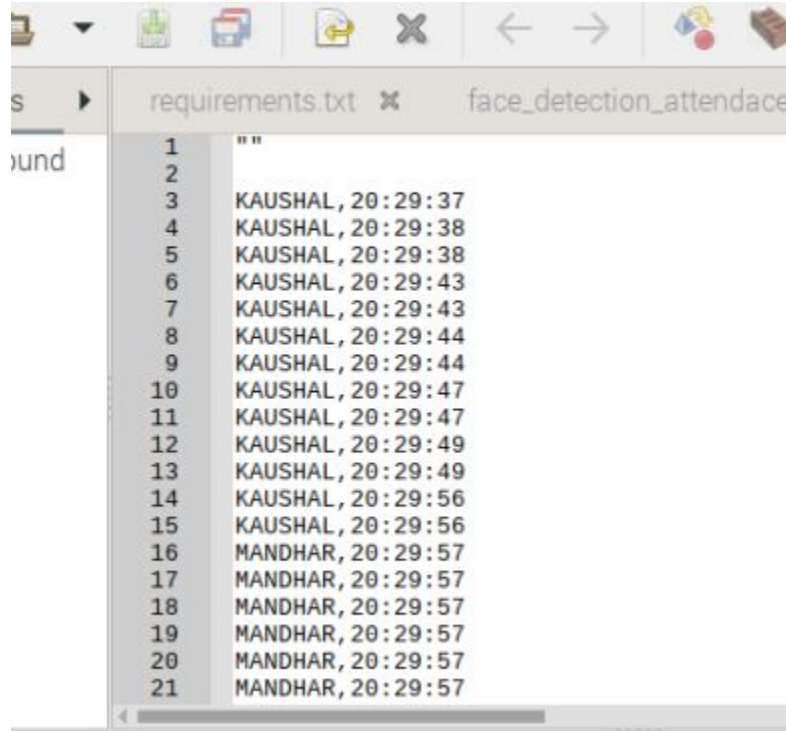
http://192.168.38.71/capture?_cb=1649673650721.jpg

Not Match

http://192.168.38.71/capture?_cb=1649673650721.jpg

Not Match

EntryTime.csv maintaining all records



1	""
2	
3	KAUSHAL, 20:29:37
4	KAUSHAL, 20:29:38
5	KAUSHAL, 20:29:38
6	KAUSHAL, 20:29:43
7	KAUSHAL, 20:29:43
8	KAUSHAL, 20:29:44
9	KAUSHAL, 20:29:44
10	KAUSHAL, 20:29:47
11	KAUSHAL, 20:29:47
12	KAUSHAL, 20:29:49
13	KAUSHAL, 20:29:49
14	KAUSHAL, 20:29:56
15	KAUSHAL, 20:29:56
16	MANDHAR, 20:29:57
17	MANDHAR, 20:29:57
18	MANDHAR, 20:29:57
19	MANDHAR, 20:29:57
20	MANDHAR, 20:29:57
21	MANDHAR, 20:29:57



Challenges Faced

Since it was an IoT project involving lots of hardware and software components, collaborating the hardware with the required software was a major challenge we faced.

The computation power of Raspi 3b+ was not enough to handle big machine learning models like face recognition. Also the modules required for the program took hours for installation in Raspi.

The connection of esp32 with wired was on breadboard and thus was not tight. So it would disassemble any time. Each time it did, we have to reset the whole ESP32 cam module and start again.

Each time the ESP32 was disconnected from internet, the IP address gets changed and therefore we have to reset it in the code.



Future Scope

This project is in ready-to-use state. We can just put the system on any door and it will work just fine.

In future, there is a huge scope in it,

1. We can always make the app better, giving more functionalities like blocking a particular intruder, emergency calling(in case of breach), sending the notification to multiple users.
2. We can improve the computational efficiency of raspberry which therefore improves the speed and we can also improve the face recognition algorithm for better accuracy.



README.MD

ESP32 Arduino code