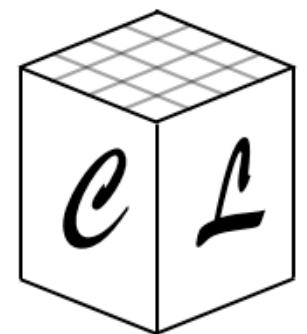


# *CosmoLattice*

School 2022 - Valencia

Non-linear dynamics of  
Axion-inflation

Joanes Lizarraga & Ander Uriol



# Basics of the model

[K. Freese, J. A. Frieman, A. V. Olinto (PRL 65,3233 1990)]

...

**Axion-inflation** +  $\frac{\phi}{\Lambda} F \tilde{F}$

Shift symmetry  $\phi \rightarrow \phi + c$

Action:

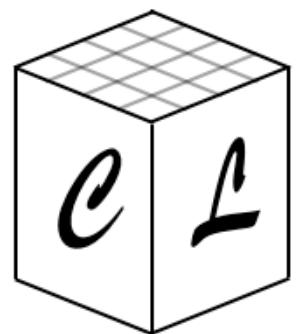
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$\phi \rightarrow$  Pseudo-scalar axion field

[M. M. Anber, L. Sorbo (0908.4089)]

[J. Cook, L. Sorbo (1109.0022)]

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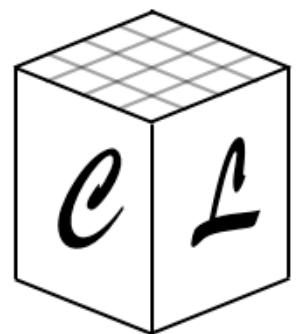
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$$A_\mu \rightarrow A_\mu + \partial_\mu \alpha(x)$$

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Non covariant

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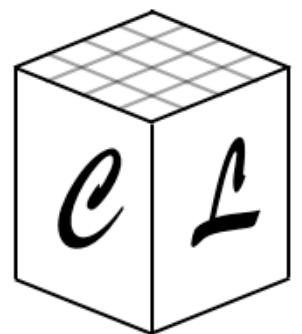
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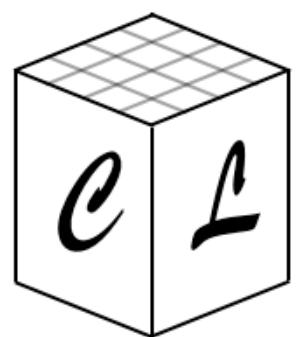
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Generated from  
external mechanism  
breaks the shift  
symmetry explicitly

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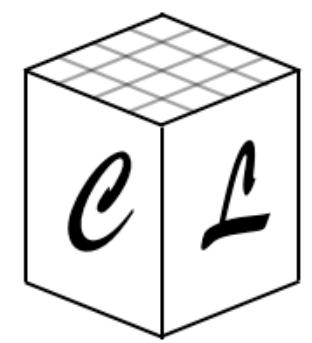
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Interaction only through this vertex  
Axion coupling!

$1/\Lambda$  Coupling constant  $[m_{\text{pl}}^{-1}]$

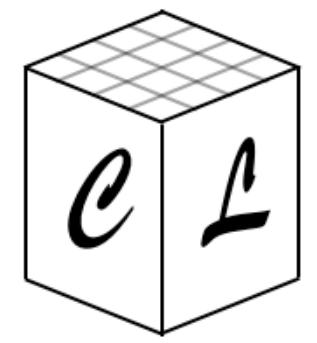
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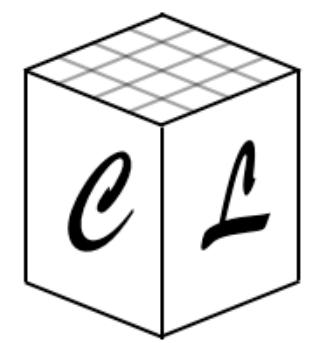
Vectorial form

$$S = \int d^4x \left[ \frac{1}{2} a^3 \pi_\phi^2 - \frac{1}{2} a \left( \vec{\nabla} \phi \right)^2 - \frac{1}{2} a^3 m^2 \phi^2 + \frac{1}{2} a \left( \vec{E}^2 - \frac{\vec{B}^2}{a^2} \right) + \frac{\phi}{\Lambda} \vec{E} \cdot \vec{B} \right]$$

@ FLRW:

$$ds^2 = -dt^2 + a^2 d\vec{x}^2$$

In cosmic time



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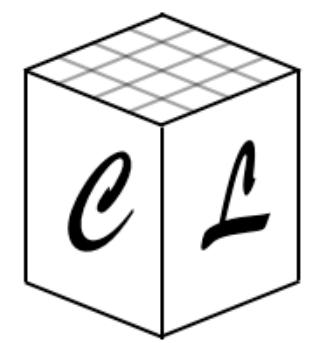
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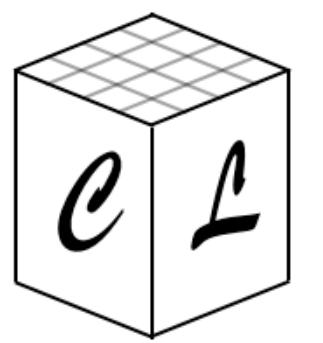
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Our choice of  
the potential,  
also:

$$V(\phi) = V_0 \left( 1 - e^{-\sqrt{\frac{2}{3}}\phi} \right)^2$$

$$V(\phi) = V_0 \left( 1 - \left( \frac{\phi}{\eta} \right)^4 \right)^2$$

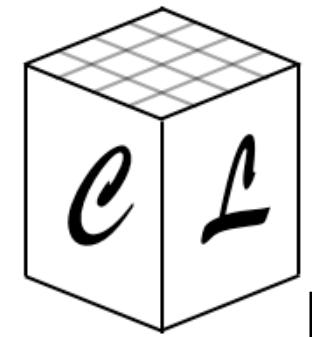
$$V(\phi) = \dots$$

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# Basics of the model

Continuum equations of motion:

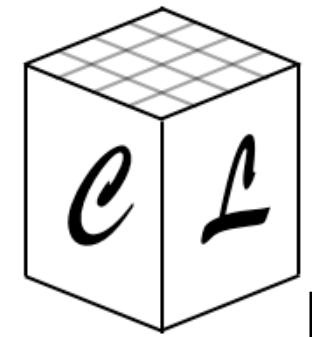
Temporal gauge

$$A_0 = 0$$

CL momentum variables

$$\tilde{\pi}_\phi = a^3 \pi_\phi, \quad \tilde{\vec{E}} = a \vec{E}$$

No Hubble friction  
term in the EoMs



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Dynamical equations:

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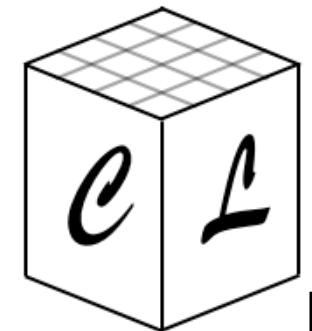
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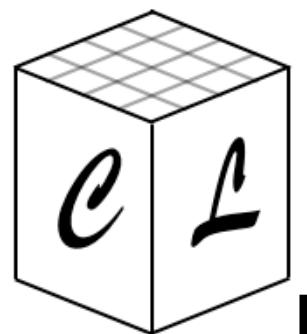
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Constraint equation:  
Gauss's law

$$\vec{\nabla} \cdot \tilde{\vec{E}} + \frac{1}{\Lambda} \vec{\nabla} \phi \cdot \vec{B} = 0$$



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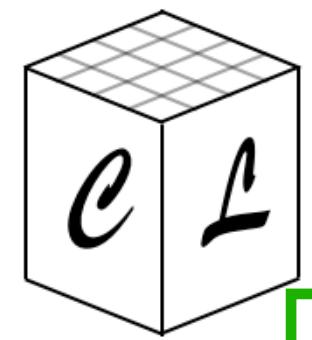
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Non-linear terms



# Basics of the model: linear regime

Let's go now deep inside inflation

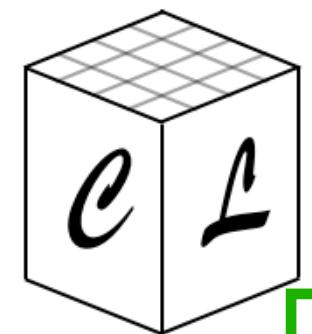
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Dynamical equations:

Inflaton in slow-roll,  
Homogeneous

+

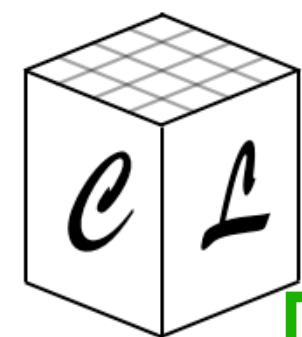
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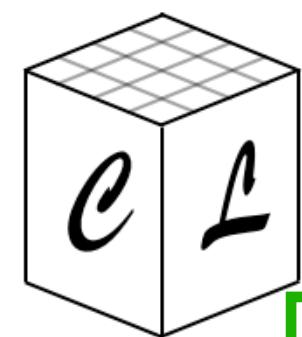
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- No backreaction in inflation's dynamics
- No generation of inhomogeneities

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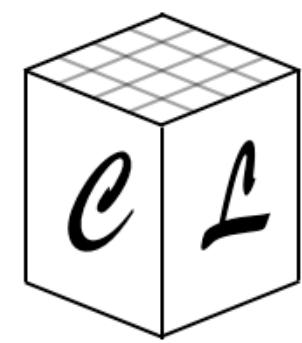
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Gauge fields get excited by this term



# Basics of the model: linear regime

EoMs

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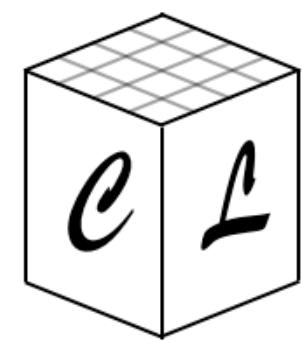
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Expansion equation:

$$\dot{\pi}_a = \frac{-a}{6m_{\text{pl}}^2}(3p + \rho) =$$

$$\frac{a}{3m_{\text{pl}}^2}\langle -2K_\phi + V - K_A - G_A \rangle$$

$$\left( \begin{array}{l} K_\phi \equiv \frac{1}{2}\pi_\phi^2 = \frac{1}{2a^6}\tilde{\pi}_\phi^2, \quad G_\phi \equiv \frac{1}{2a^2} \sum (\partial_i \phi)^2, \quad V \equiv \frac{1}{2}m^2\phi^2, \\ K_A \equiv \frac{1}{2} \sum_i \frac{E_i^2}{a^2} = \frac{1}{2} \sum_i \frac{\tilde{E}_i^2}{a^4}, \quad G_A \equiv \frac{1}{2} \sum_i \frac{B_i^2}{a^4} \end{array} \right)$$



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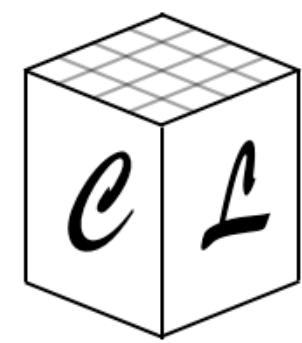
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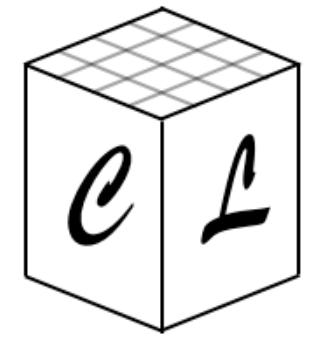
Gauge fields evolve in  
the background set by  
the axion field

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$$\begin{pmatrix} K_\phi \equiv \frac{1}{2}\pi_\phi^2 = \frac{1}{2a^6}\tilde{\pi}_\phi^2, & G_\phi \equiv \frac{1}{2a^2} \sum (\partial_i\phi)^2, & V \equiv \frac{1}{2}m^2\phi^2, \\ K_A \equiv \frac{1}{2} \sum_i \frac{E_i^2}{a^2} = \frac{1}{2} \sum_i \frac{\tilde{E}_i^2}{a^4}, & G_A \equiv \frac{1}{2} \sum_i \frac{B_i^2}{a^4} \end{pmatrix}$$



# Basics of the model: linear regime

An analytical solution can be found

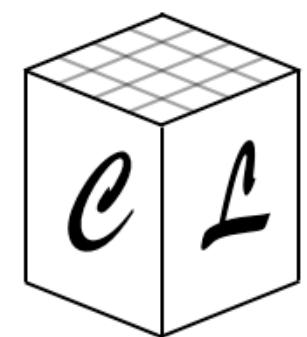
Changing to the helicity basis: + Conformal time

$$\vec{A}(\vec{x}, \tau) = \sum_{\lambda=\pm} \int \frac{d^3 k}{(2\pi)^3} A^\lambda(k, \tau) \vec{\varepsilon}^\lambda(\hat{k}) e^{i \vec{k} \cdot \vec{x}}$$

Photon with 2 helicity states

$$k_i \varepsilon_i^\pm(\hat{k}) = 0, \quad \epsilon_{ijk} k_j \varepsilon_k^\pm(\hat{k}) = \mp i k \varepsilon_i^\pm(\hat{k})$$

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An analytical solution can be found

$$\dot{\vec{E}} = -\frac{1}{a}\vec{\nabla} \times \vec{B} - \frac{1}{a^3\Lambda}\tilde{\pi}_\phi \vec{B}$$

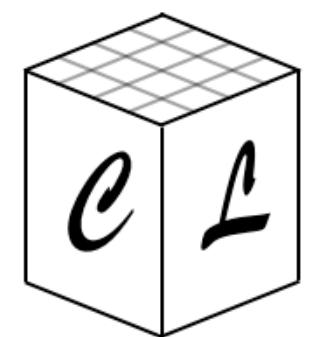
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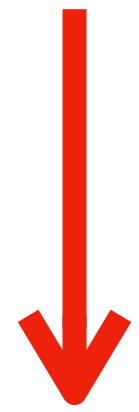
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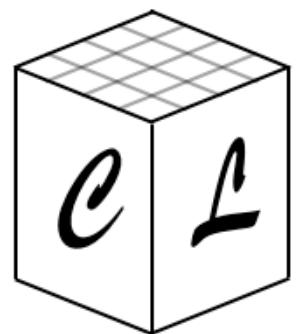
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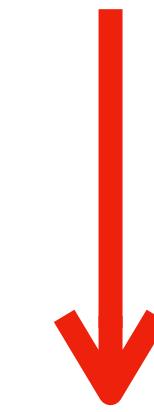
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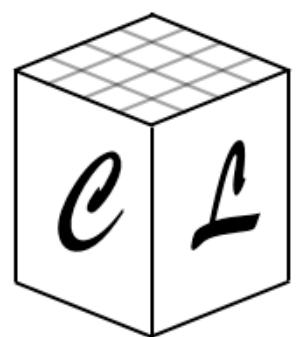
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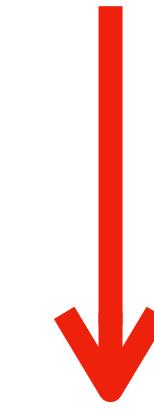
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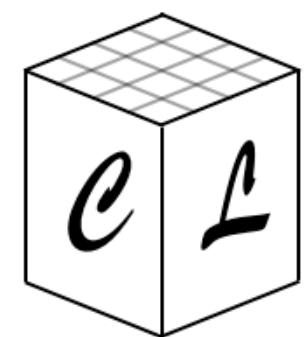
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Two polarisations:

- One exponentially amplified
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Chiral instability



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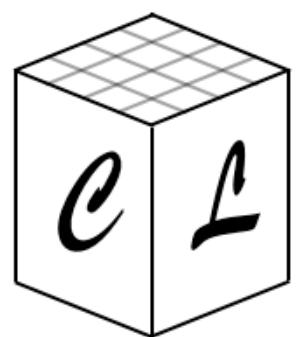
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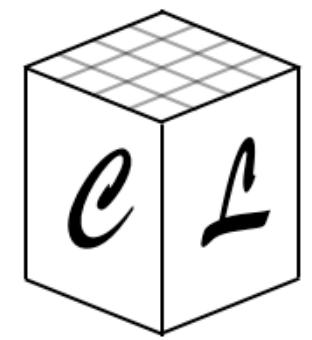
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$$|A^+| \gg |A^-|$$



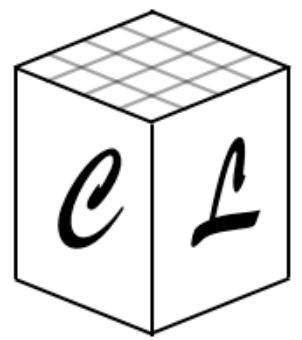
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[M. M. Anber, L. Sorbo (0908.4089)]

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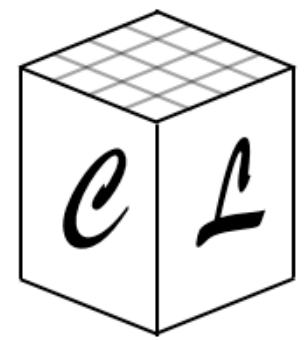
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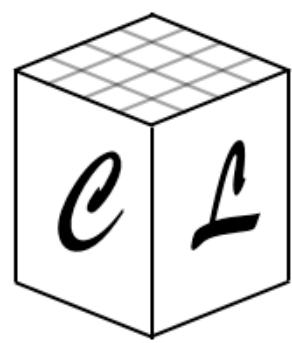
Topological term:

Appears in EoMs

$$\frac{1}{a^3} \langle \vec{E} \cdot \vec{B} \rangle \simeq 2.4 \cdot 10^{-4} \frac{H^4}{|\xi|^4} e^{2\pi|\xi|}$$

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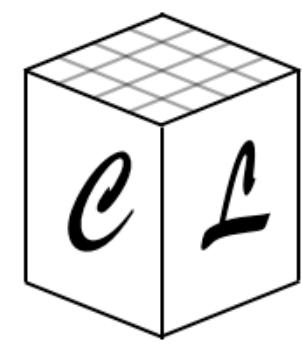
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Amplified around  
the Hubble scale  
at each time



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$\xi$

Not accurate towards the end of inflation

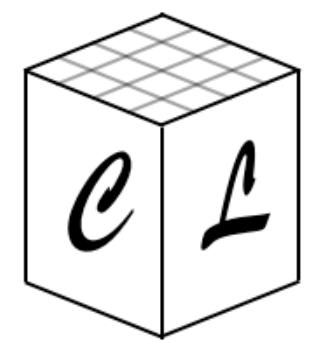
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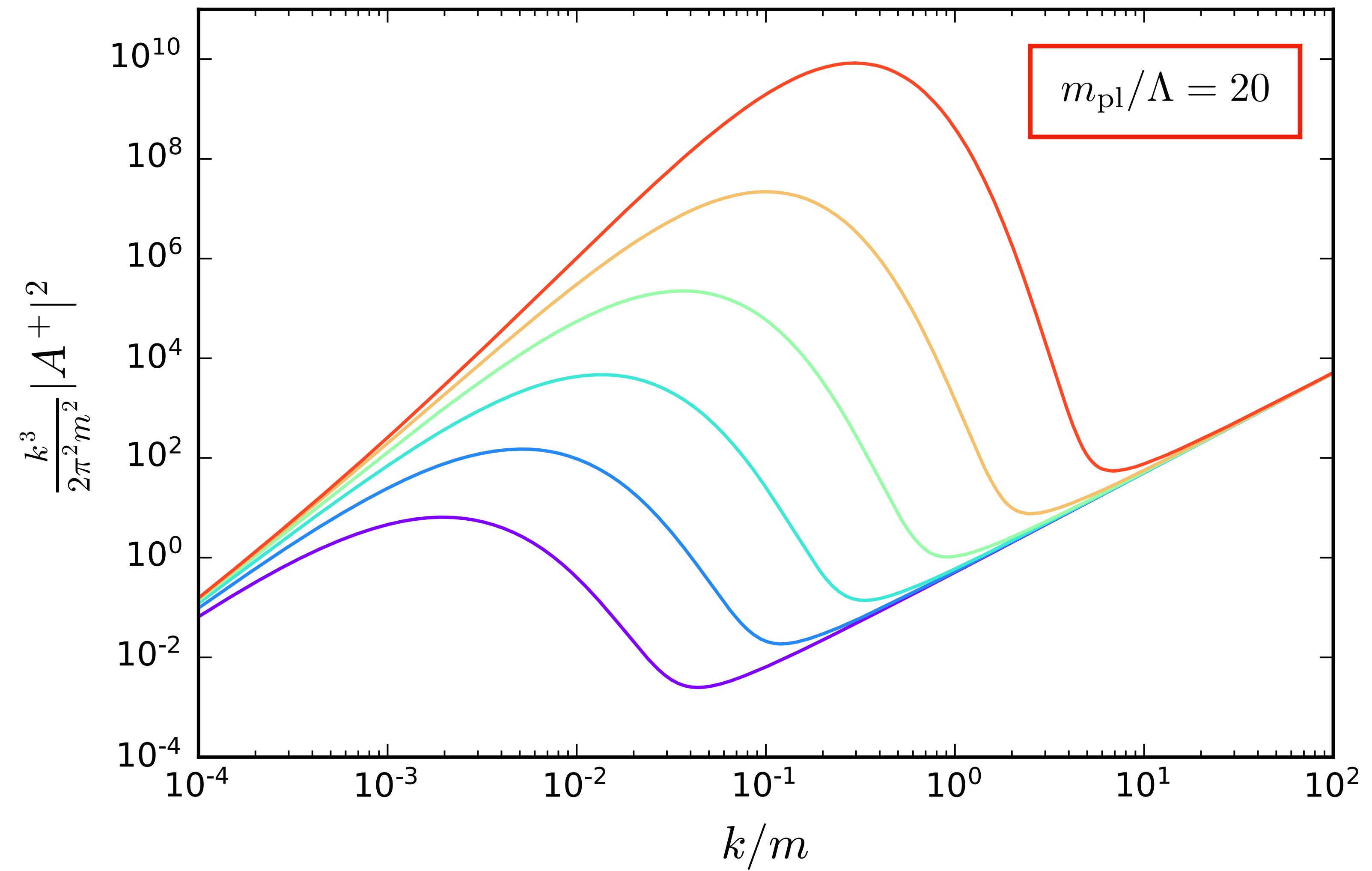
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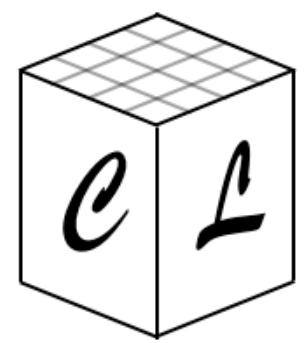


# Basics of the model: linear regime

$$\left( \frac{\partial^2}{\partial \tau^2} + k^2 \pm \frac{2k\xi}{\tau} \right) A_{\pm}(k, \tau) = 0$$

-6 eFolds  
↓  
0 eFolds

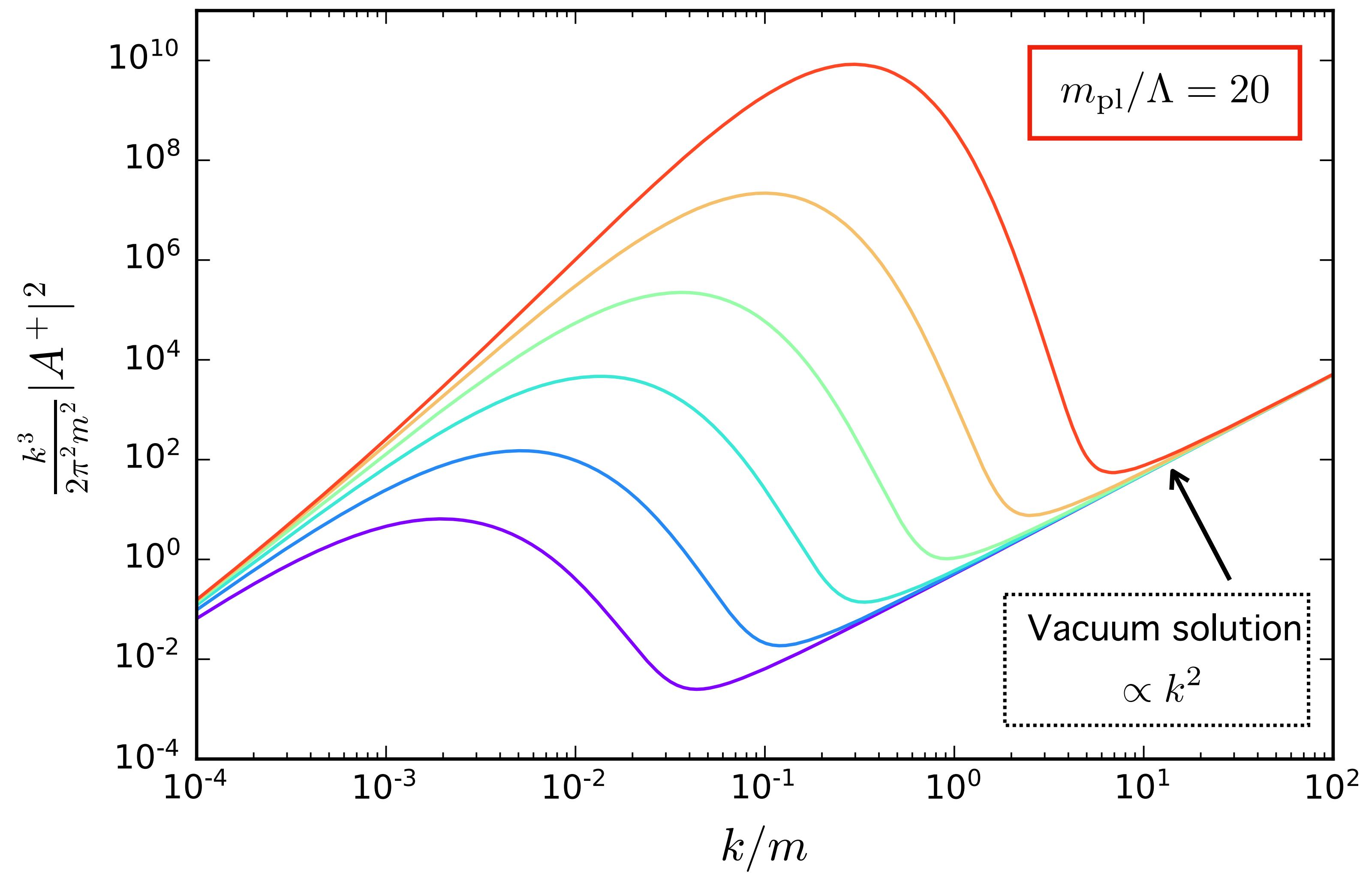


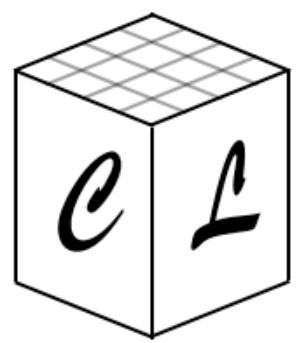


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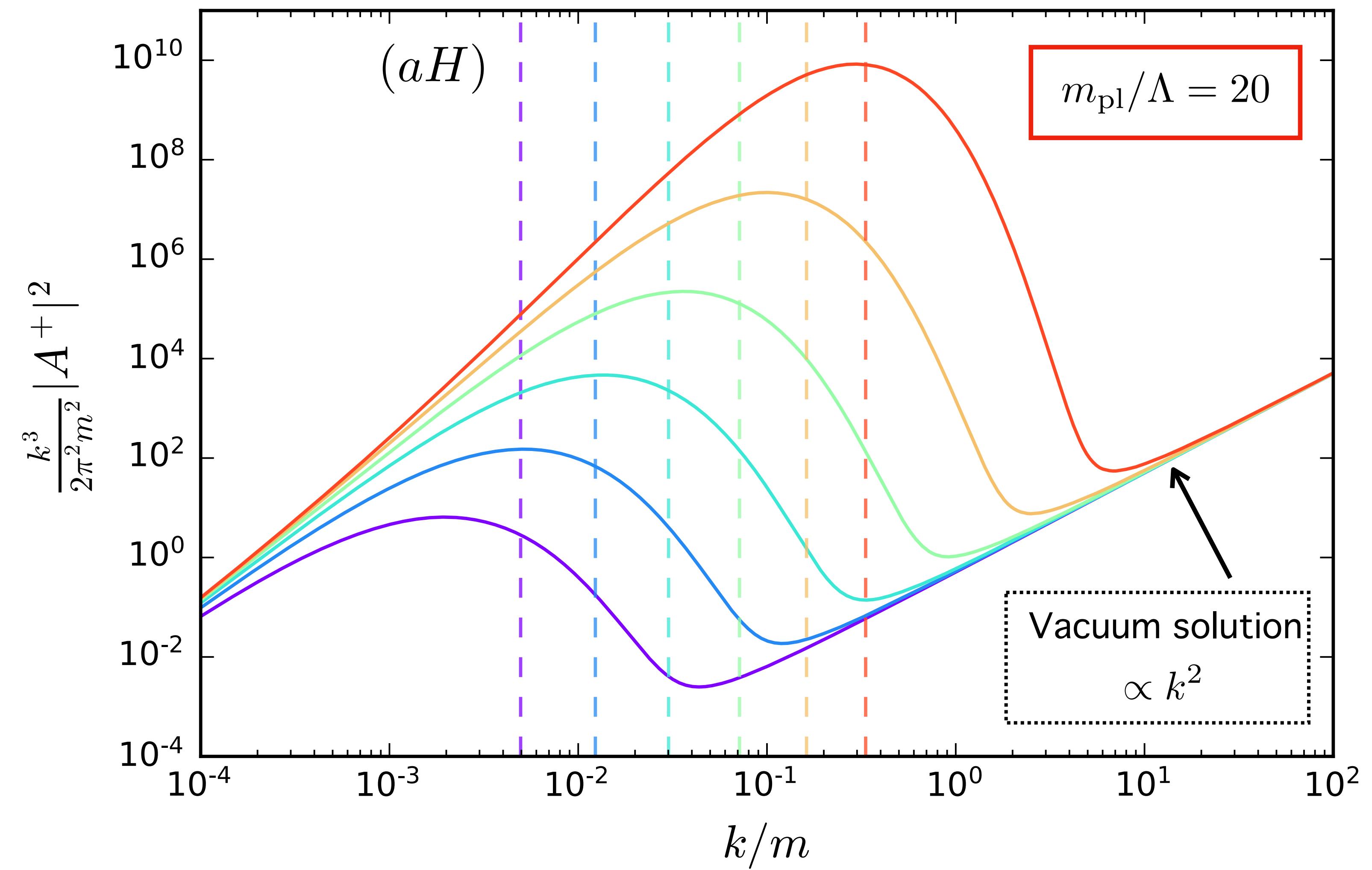


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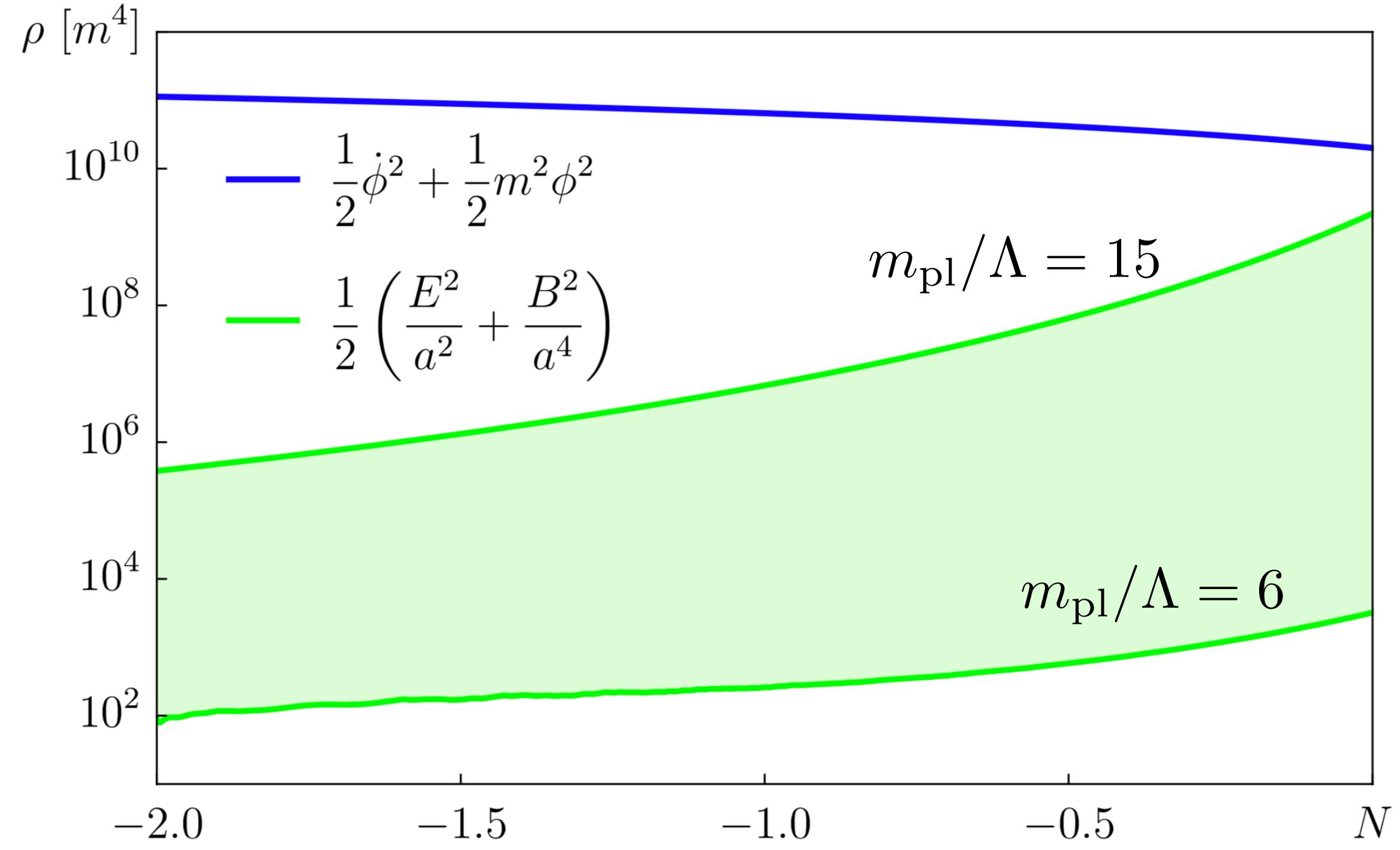
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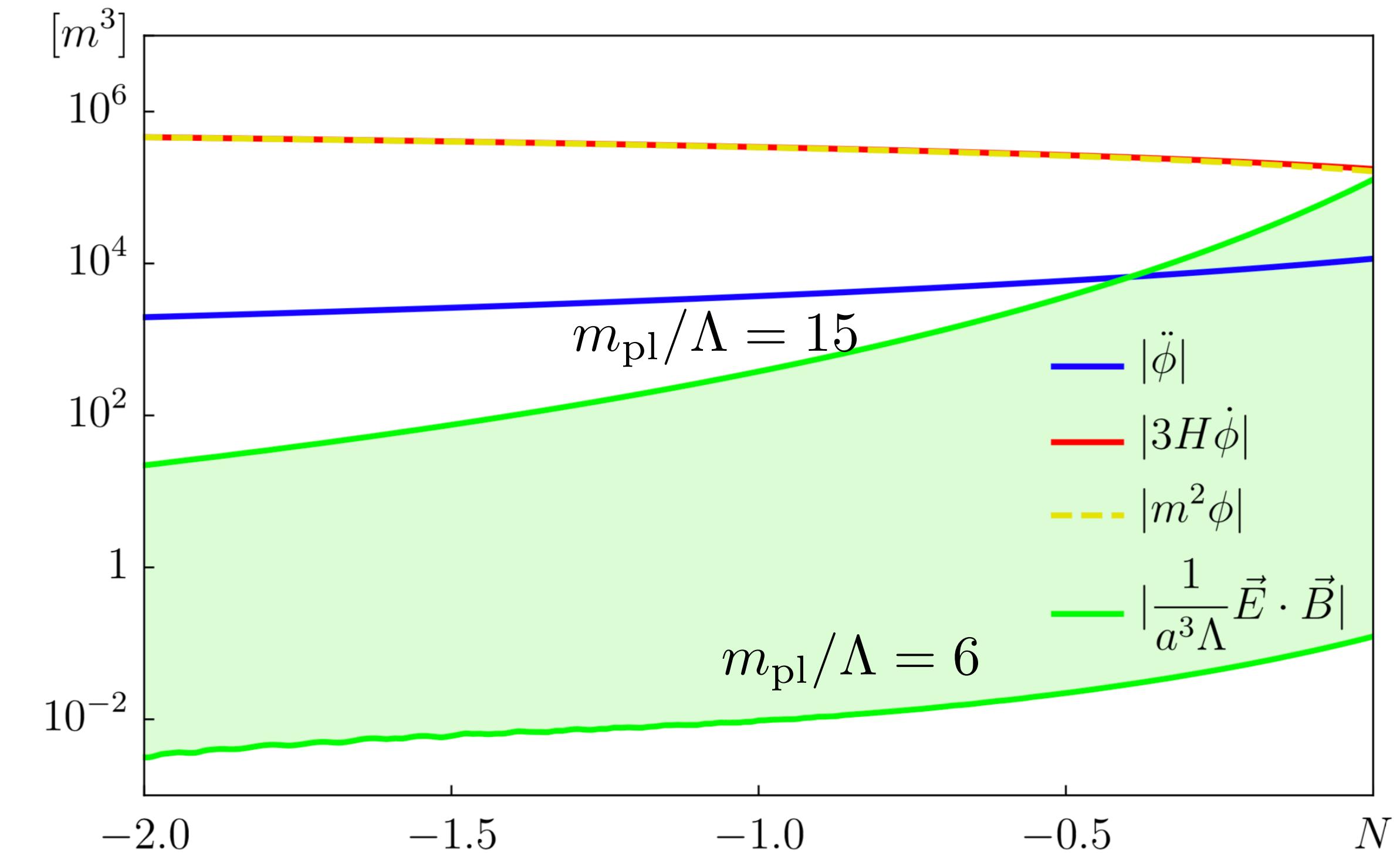
# Basics of the model: linear regime

[J. R. C. Cuissa, D. G. Figueroa (1812.03132)]

## Energy components



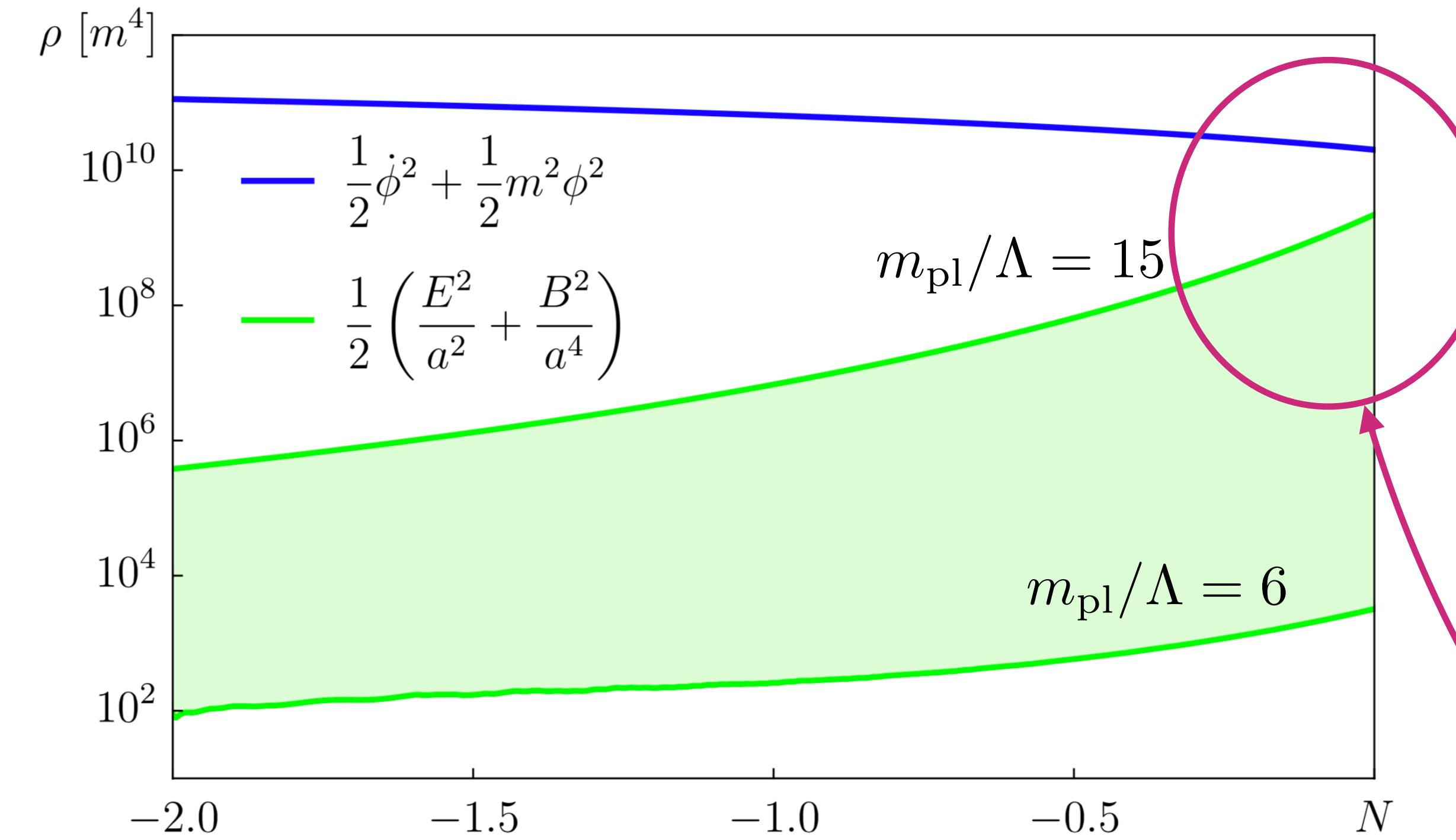
## Topological term vs slow-roll



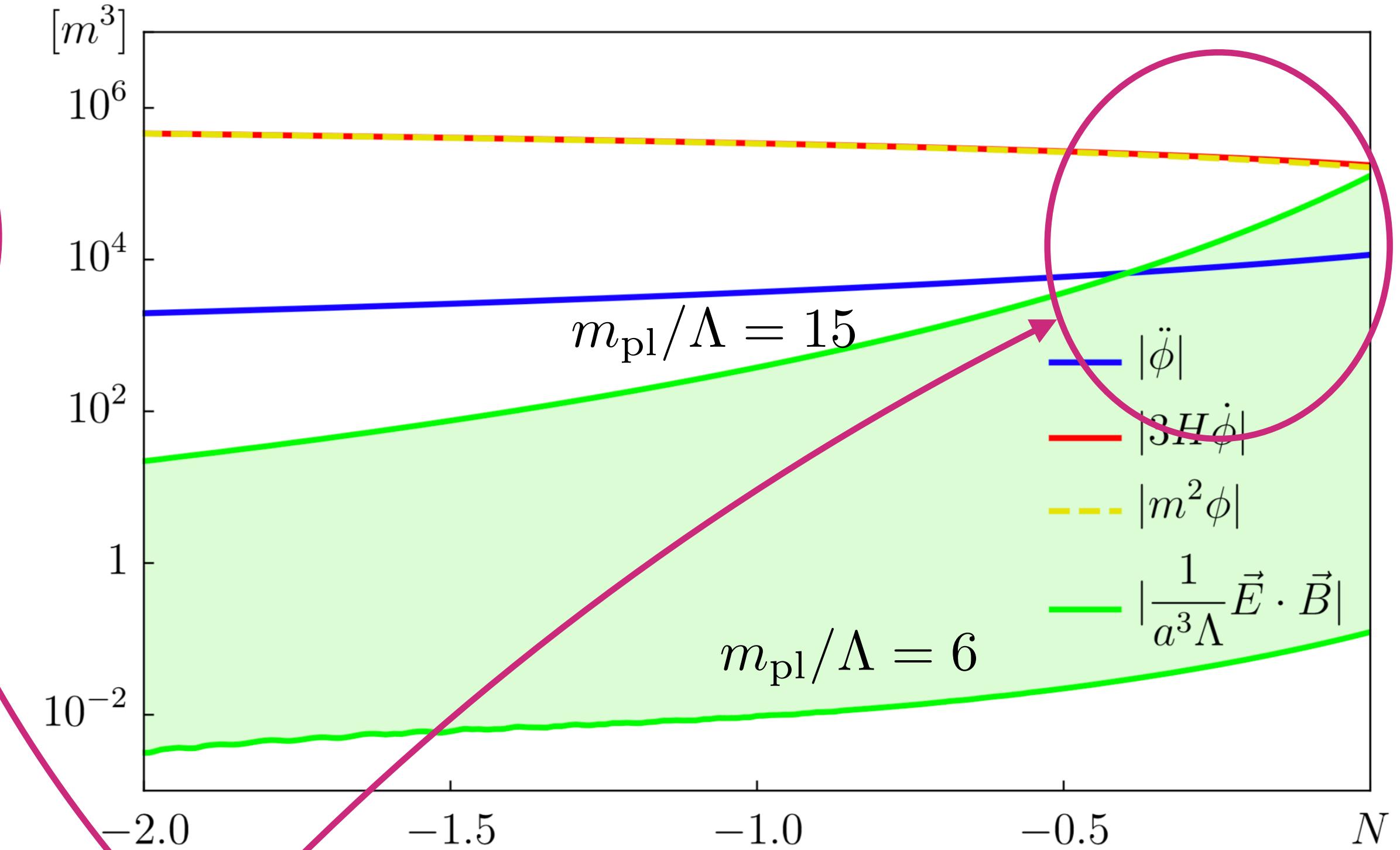
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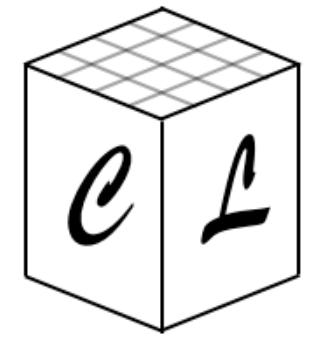
Energy components



Topological term vs slow-roll



Backreaction effect cannot be neglected



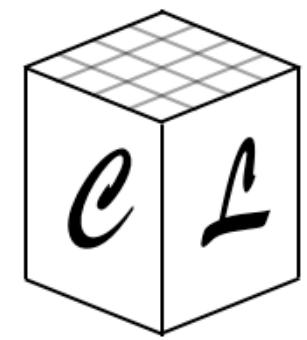
# Basics of the model: linear regime

## Linear regime

Dynamical equations:

$$\dot{\tilde{\pi}}_\phi = a \vec{\nabla}^2 \phi - a^3 m^2 \phi + \frac{1}{a\Lambda} \tilde{\vec{E}} \cdot \vec{B},$$

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# Basics of the model: linear regime

## Linear regime

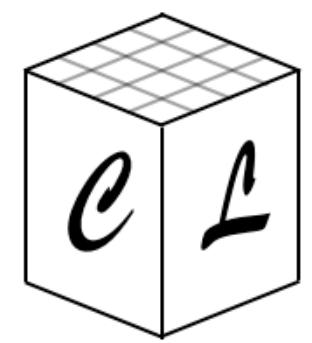
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$$\dot{\pi}_a = \frac{-a}{6m_{\text{pl}}^2}(3p + \rho) =$$

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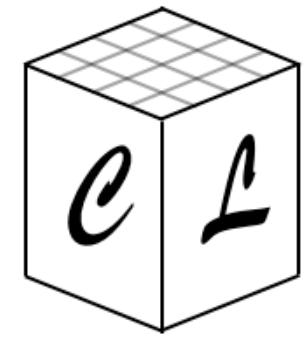
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Neglected

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# Basics of the model

Beyond the linear regime: backreaction

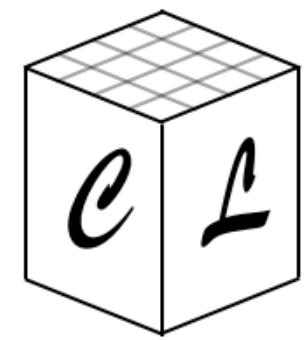
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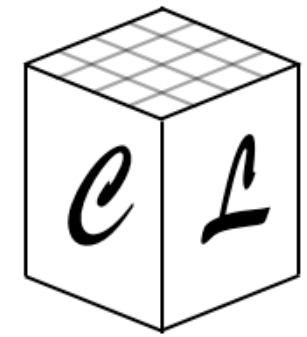
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Backreaction terms



# Basics of the model

## Beyond the linear regime: backreaction

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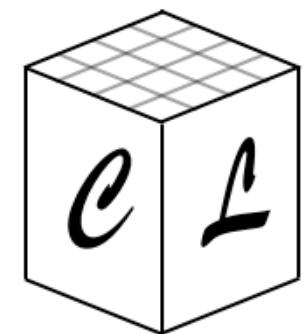
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[G. Dall'Agata, S. González-Martín, A. Papageorgiou, M. Peloso (1912.09950)]

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# Basics of the model

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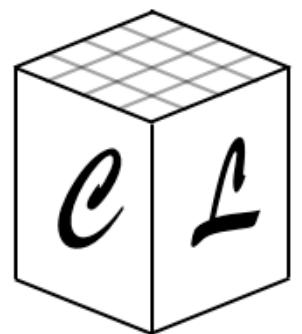
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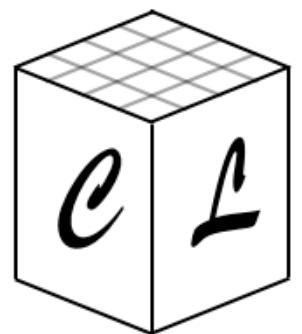
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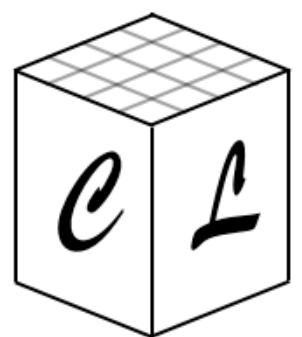
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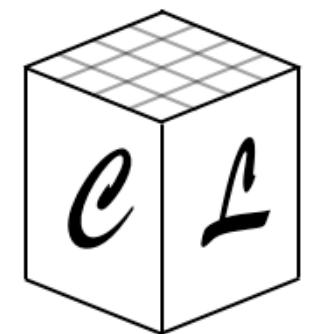
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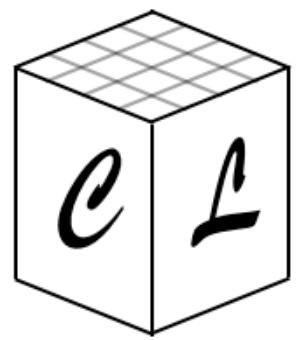
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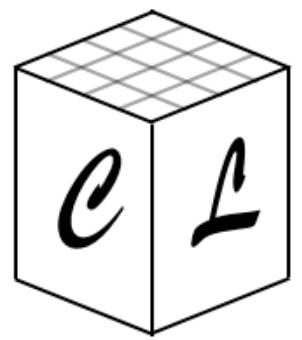
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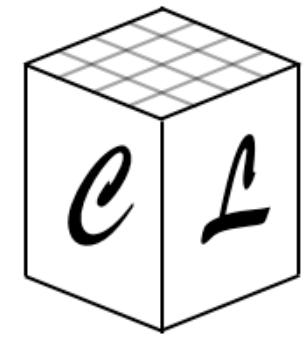
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No gradient terms induced  
(yet)

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Real time evolution of fields

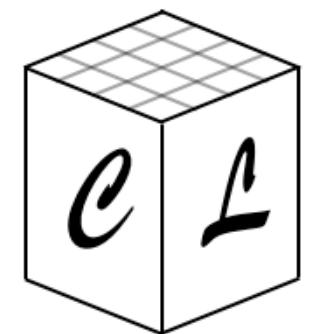
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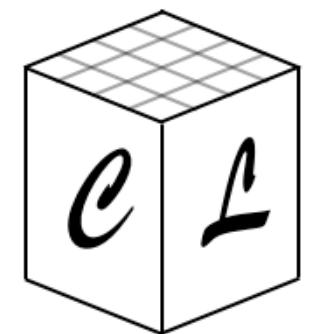
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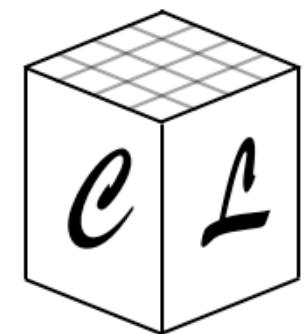
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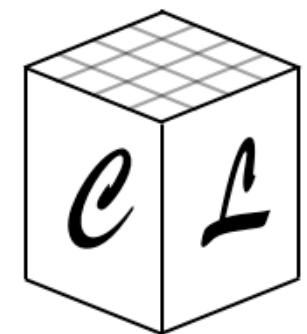
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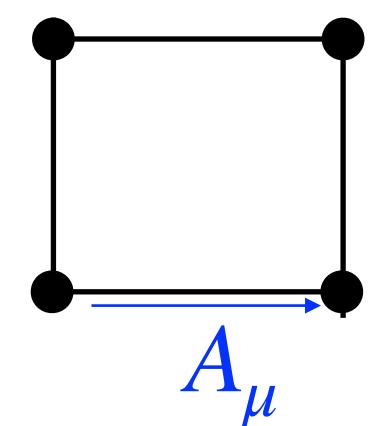
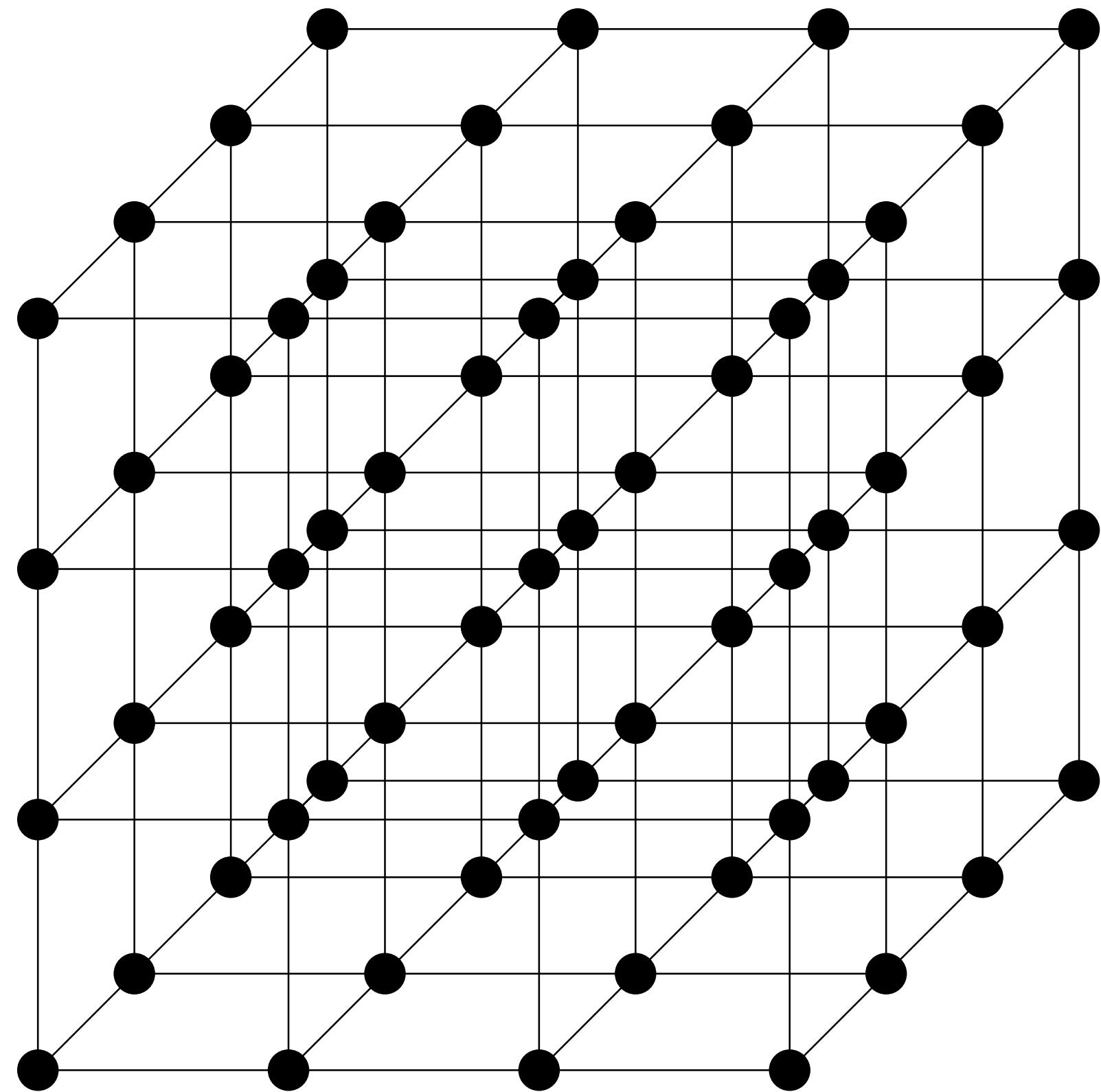
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$\forall$  D.o.F will be simultaneously  
evolved

- Track of all inhomogeneities
- Full backreaction effects included

# Discretisation procedure

[D. G. Figueroa & M. Shaposhnikov (1705.09629)]



$\phi$  @ sites  
 $A_\mu$  @ links

Want to preserve:

1- Gauge transformations

$$A_\mu \rightarrow A_\mu + \partial_\mu \alpha(x)$$

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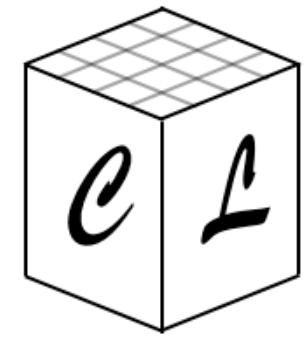
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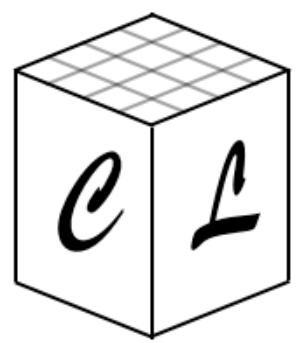
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$$\frac{\phi}{\Lambda} \vec{E} \cdot \vec{B}$$

Lattice

$$\sum_i \frac{\phi}{\Lambda} E_i^{(2)} B_i^{(4)}$$

The only one  
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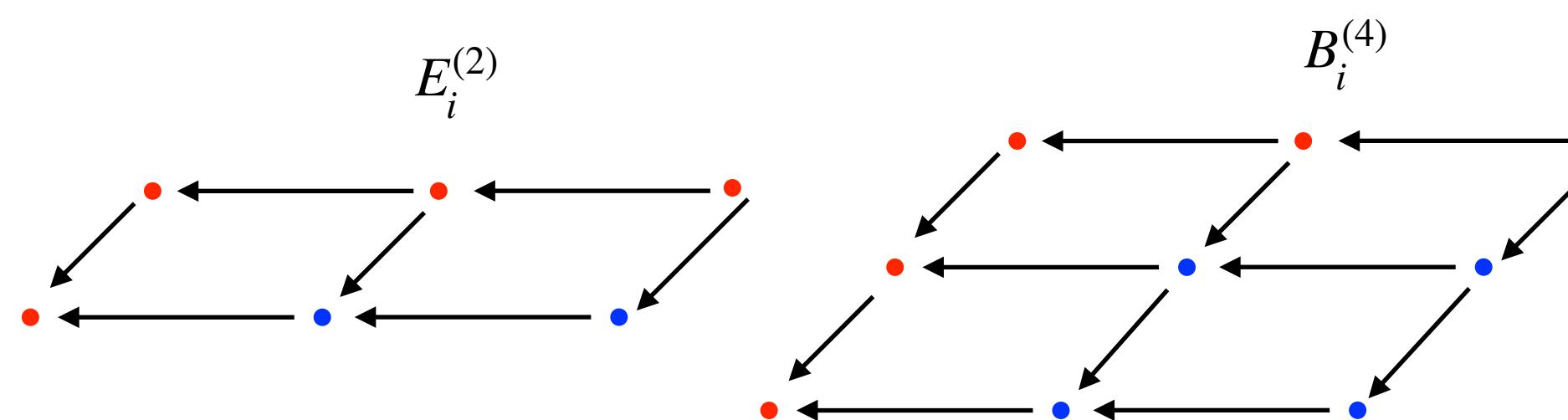
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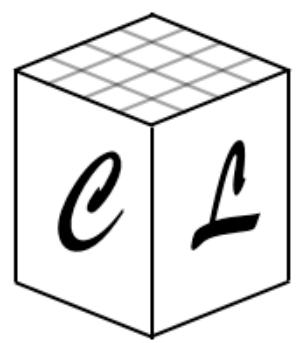
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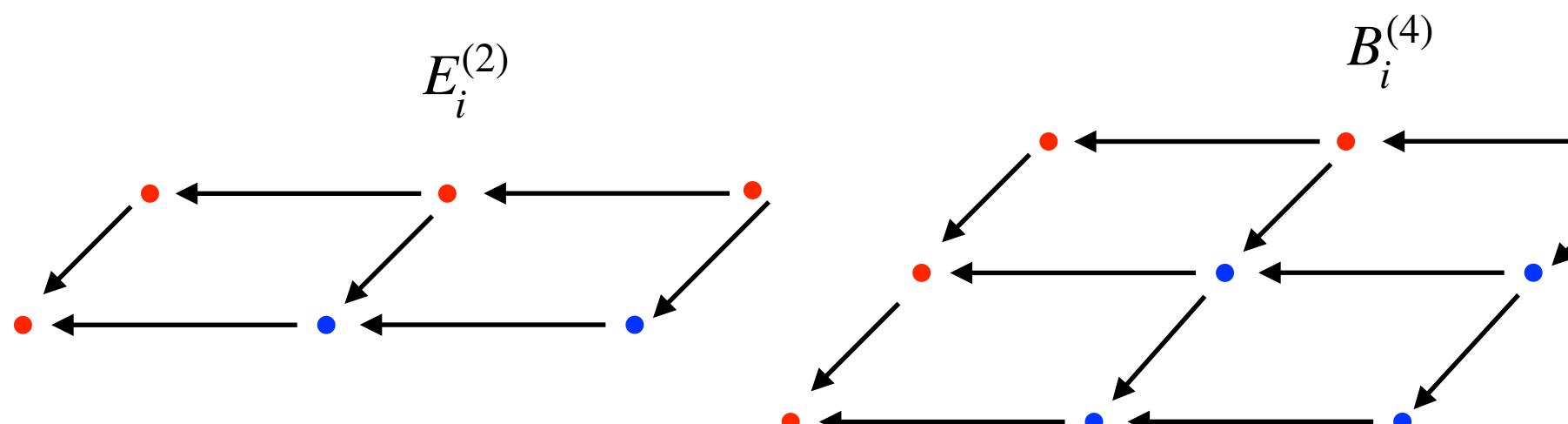
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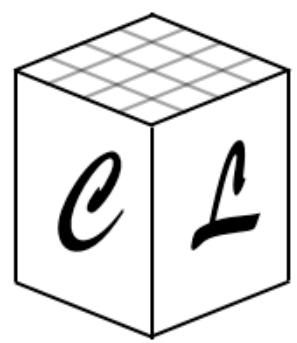
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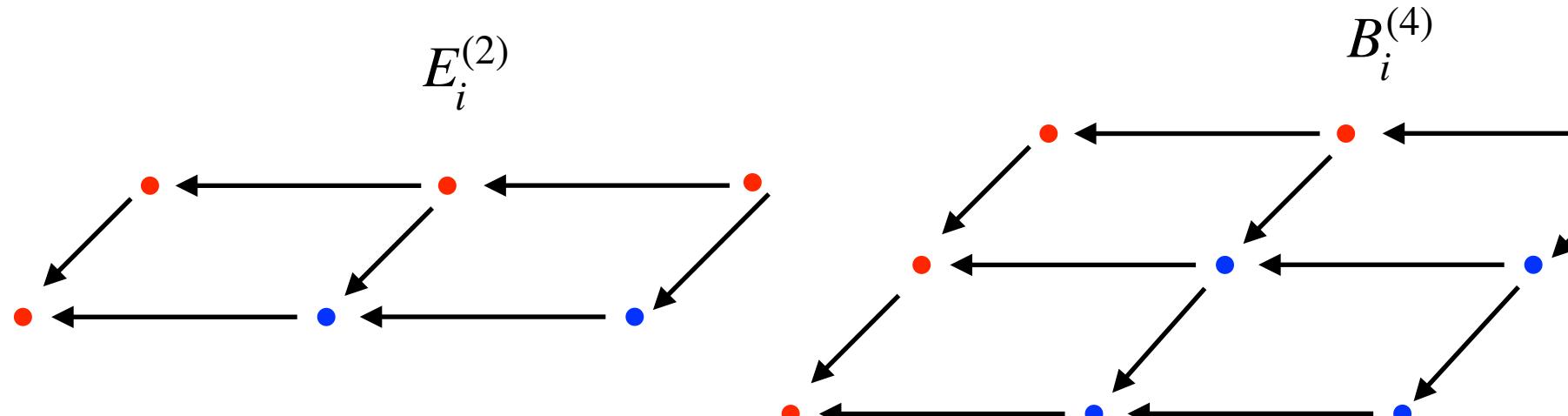
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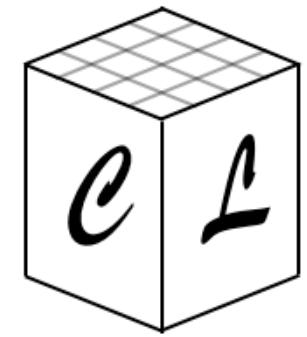
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$$F_{\mu\nu} \tilde{F}^{\mu\nu} = \text{Exact lattice shift symmetry}$$

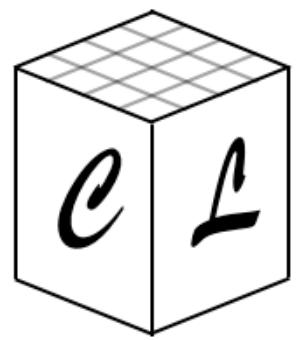
4- Continuum limit to  $\mathcal{O}(dx^2)$



# Discretisation procedure

[D. G. Figueroa, M. Shaposhnikov (1705.09629)]  
[J. R. C. Cuissa , D. G. Figueroa (1812.03132)]

$$S = \int d^4x \left[ \frac{1}{2}a^3\pi_\phi^2 - \frac{1}{2}a \left( \vec{\nabla}\phi \right)^2 - \frac{1}{2}a^3m^2\phi^2 + \frac{1}{2}a \left( \vec{E}^2 - \frac{\vec{B}^2}{a^2} \right) + \frac{\phi}{\Lambda} \vec{E} \cdot \vec{B} \right]$$



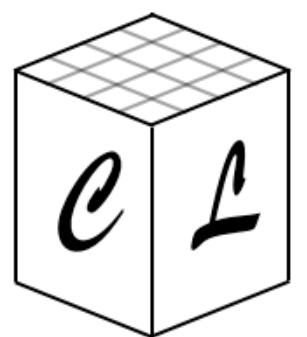
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Full discretised action:

$$\begin{aligned} S = & \Delta t \Delta x^3 \sum_{t, \vec{n}} \left[ \frac{1}{2a^3} (\tilde{\pi}_\phi)^2 - \frac{1}{2}a_{+\hat{\frac{0}{2}}} \left( \Delta_i^+ \phi_{+\hat{\frac{0}{2}}} \right)^2 - \frac{1}{2}a_{+\hat{\frac{0}{2}}}^3 m^2 \phi_{+\hat{\frac{0}{2}}} \right. \\ & + \frac{1}{2}a_{+\hat{\frac{0}{2}}} \sum_i \left( \Delta_0^+ A_i - \Delta_i^+ A_0 \right)^2 - \frac{1}{4a} \sum_{i,j} \left( \Delta_i^+ A_j - \Delta_j^+ A_i \right)^2 \\ & \left. + \frac{\phi}{a\Lambda} \sum_i \frac{1}{2} \tilde{E}_i^{(2)} \left( B_i^{(4)} + B_{i,+\hat{0}}^{(4)} \right) \right] \end{aligned}$$



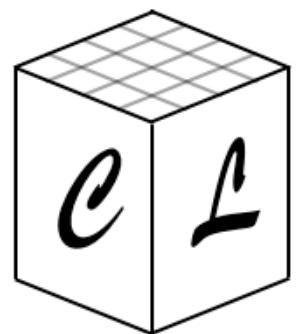
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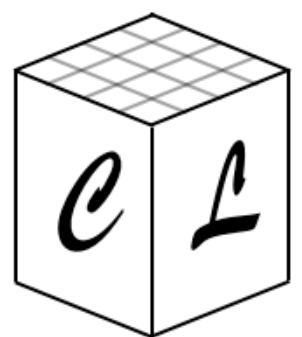
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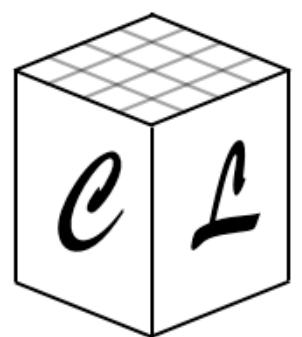
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# Discretisation procedure

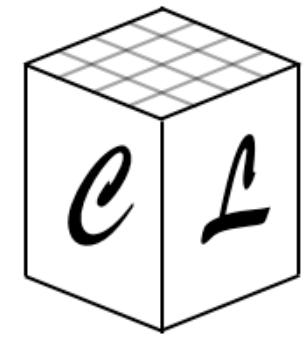
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Ready for variational principle



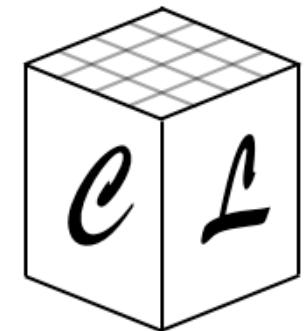
# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

$$\tilde{\pi}_{\phi,+\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L , \quad \tilde{E}_{i,+\frac{\hat{0}}{2}} = \tilde{E}_{i,-\frac{\hat{0}}{2}} + dt \mathcal{K}_{i,A}^L$$

$$\phi_{+\frac{\hat{0}}{2}} = \phi_{-\frac{\hat{0}}{2}} + \frac{dt}{a^3} \tilde{\pi}_\phi , \quad A_{i,+\hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+\frac{\hat{0}}{2}}$$



# Discretisation procedure

Common kick-drift scheme

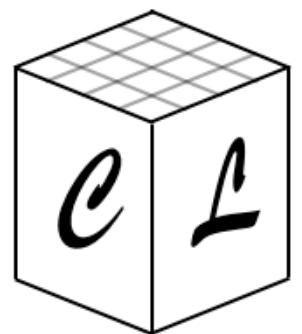
## Evolution Kernels

Dynamical equations:

$$\tilde{\pi}_{\phi,+}{}^{\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L , \quad \tilde{E}_{i,+}{}^{\hat{0}} = \tilde{E}_{i,-}{}^{\hat{0}} + dt \mathcal{K}_{i,A}^L$$

$$\phi_{+}{}^{\frac{\hat{0}}{2}} = \phi_{-}{}^{\frac{\hat{0}}{2}} + \frac{dt}{a^3} \tilde{\pi}_\phi , \quad A_{i,+}{}^{\hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+}{}^{\frac{\hat{0}}{2}}$$

$$\begin{aligned} \mathcal{K}_\phi^L &= a_{+}{}^{\frac{\hat{0}}{2}} \sum_i \Delta_i^- \Delta_i^+ \phi_{+}{}^{\frac{\hat{0}}{2}} - a_{+}^3 m^2 \phi_{+}{}^{\frac{\hat{0}}{2}} + \frac{1}{2a\Lambda} \sum_i \tilde{E}_{i,+}^{(2)} \left( B_i^{(4)} + B_{i,+}^{(4)} \right) \\ \mathcal{K}_{i,A}^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+}{}^i B_{i,+}^{(4)} \right) \\ &\quad + \frac{1}{8a\Lambda} (2 + dx \Delta_i^+) \sum_{\pm} \sum_{j,k} \left\{ \epsilon_{ijk} [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{+}{}^{\frac{\hat{0}}{2}} + [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{-}{}^{\frac{\hat{0}}{2}} \right\} \end{aligned}$$



# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

Dynamical equations:

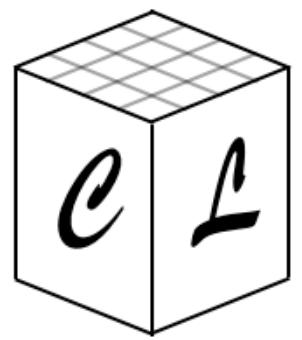
$$\tilde{\pi}_{\phi,+}{}^{\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L, \quad \tilde{E}_{i,+}{}^{\hat{0}} = \tilde{E}_{i,-}{}^{\hat{0}} + dt \mathcal{K}_{i,A}^L$$

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Gauss's constraint:

$$\sum_i \Delta_i^- \tilde{E}_{i,+}{}^{\frac{\hat{0}}{2}} = -\frac{1}{4\Lambda} \sum_{\pm} \sum_i \left( \Delta_i^\pm \phi_{+}{}^{\frac{\hat{0}}{2}} \right) \left( B_i^{(4)} + B_{i,+}^{(4)} \right)_{\pm i}$$



# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

Dynamical equations:

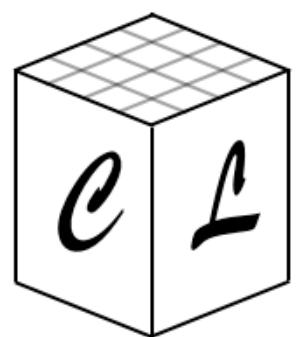
$$\tilde{\pi}_{\phi,+\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L, \quad \tilde{E}_{i,+ \frac{\hat{0}}{2}} = \tilde{E}_{i,- \frac{\hat{0}}{2}} + dt \mathcal{K}_{i,A}^L$$

$$\phi_{+ \frac{\hat{0}}{2}} = \phi_{- \frac{\hat{0}}{2}} + \frac{dt}{a^3} \tilde{\pi}_\phi, \quad A_{i,+ \hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+ \frac{\hat{0}}{2}}$$

$$\begin{aligned} \mathcal{K}_\phi^L &= a_{+ \frac{\hat{0}}{2}} \sum_i \Delta_i^- \Delta_i^+ \phi_{+ \frac{\hat{0}}{2}} - a_{+ \frac{\hat{0}}{2}}^3 m^2 \phi_{+ \frac{\hat{0}}{2}} + \frac{1}{2a\Lambda} \sum_i \tilde{E}_{i,+ \frac{\hat{0}}{2}}^{(2)} \left( B_i^{(4)} + B_{i,+ \hat{0}}^{(4)} \right) \\ \mathcal{K}_{i,A}^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right) \\ &\quad + \frac{1}{8a\Lambda} (2 + dx \Delta_i^+) \sum_{\pm} \sum_{j,k} \left\{ \epsilon_{ijk} [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{+ \frac{\hat{0}}{2}} + [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{- \frac{\hat{0}}{2}} \right\} \end{aligned}$$

Gauss's constraint:

$$\sum_i \Delta_i^- \tilde{E}_{i,+ \frac{\hat{0}}{2}} = -\frac{1}{4\Lambda} \sum_{\pm} \sum_i \left( \Delta_i^\pm \phi_{+ \frac{\hat{0}}{2}} \right) \left( B_i^{(4)} + B_{i,+ \hat{0}}^{(4)} \right)_{\pm i}$$



# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

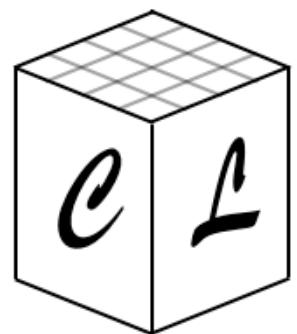
Dynamical equations:

$$\tilde{\pi}_{\phi,+\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L, \quad \tilde{E}_{i,+\frac{\hat{0}}{2}} = \tilde{E}_{i,-\frac{\hat{0}}{2}} + dt \mathcal{K}_{i,A}^L$$
$$\phi_{+\frac{\hat{0}}{2}} = \phi_{-\frac{\hat{0}}{2}} + \frac{dt}{a^3} \tilde{\pi}_\phi, \quad A_{i,+\hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+\frac{\hat{0}}{2}}$$

$$\begin{aligned} \mathcal{K}_\phi^L &= a_{+\frac{\hat{0}}{2}} \sum_i \Delta_i^- \Delta_i^+ \phi_{+\frac{\hat{0}}{2}} - a_{+\frac{\hat{0}}{2}}^3 m^2 \phi_{+\frac{\hat{0}}{2}} + \frac{1}{2a\Lambda} \sum_i \tilde{E}_{i,+\frac{\hat{0}}{2}}^{(2)} \left( B_i^{(4)} + B_{i,+\hat{0}}^{(4)} \right) \\ \mathcal{K}_{i,A}^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right) \\ &\quad + \frac{1}{8a\Lambda} (2 + dx \Delta_i^+) \sum_{\pm} \sum_{j,k} \left\{ \epsilon_{ijk} [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{+\frac{\hat{0}}{2}} + [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{-\frac{\hat{0}}{2}} \right\} \end{aligned}$$

Gauss's constraint:

$$\sum_i \Delta_i^- \tilde{E}_{i,+\frac{\hat{0}}{2}} = -\frac{1}{4\Lambda} \sum_{\pm} \sum_i \left( \Delta_i^\pm \phi_{+\frac{\hat{0}}{2}} \right) \left( B_i^{(4)} + B_{i,+\hat{0}}^{(4)} \right)_{\pm i}$$



# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

Dynamical equations:

$$\tilde{\pi}_{\phi,+\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L, \quad \tilde{E}_{i,+\frac{\hat{0}}{2}} = \tilde{E}_{i,-\frac{\hat{0}}{2}} + dt \mathcal{K}_{i,A}^L$$

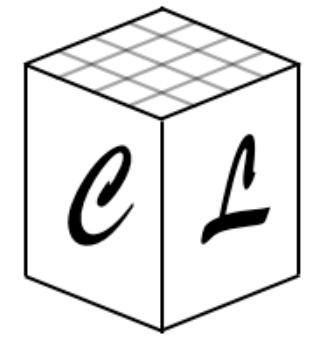
$$\phi_{+\frac{\hat{0}}{2}} = \phi_{-\frac{\hat{0}}{2}} + \frac{dt}{a^3} \tilde{\pi}_\phi, \quad A_{i,+\hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+\frac{\hat{0}}{2}}$$

$$\begin{aligned} \mathcal{K}_\phi^L &= a_{+\frac{\hat{0}}{2}} \sum_i \Delta_i^- \Delta_i^+ \phi_{+\frac{\hat{0}}{2}} - a_{+\frac{\hat{0}}{2}}^3 m^2 \phi_{+\frac{\hat{0}}{2}} + \frac{1}{2a\Lambda} \sum_i \tilde{E}_{i,+\frac{\hat{0}}{2}}^{(2)} \left( B_i^{(4)} + B_{i,+\hat{0}}^{(4)} \right) \\ \mathcal{K}_{i,A}^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right) \\ &\quad + \frac{1}{8a\Lambda} (2 + dx \Delta_i^+) \sum_{\pm} \sum_{j,k} \left\{ \epsilon_{ijk} [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{+\frac{\hat{0}}{2}} + [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{-\frac{\hat{0}}{2}} \right\} \end{aligned}$$

Gauss's constraint:

Alternative approach in:  
[A. Caravano, E. Komatsu, K. D. Lozanov, J. Weller (2204.12874)]

$$\sum_i \Delta_i^- \tilde{E}_{i,+\frac{\hat{0}}{2}} = -\frac{1}{4\Lambda} \sum_{\pm} \sum_i \left( \Delta_i^\pm \phi_{+\frac{\hat{0}}{2}} \right) \left( B_i^{(4)} + B_{i,+\hat{0}}^{(4)} \right)_{\pm i}$$



# Discretisation procedure

Common kick-drift scheme

Evolution Kernels

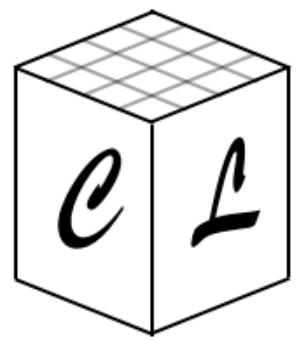
$$b_{+\hat{0}} = b + dt\mathcal{K}_a^L$$

Expansion equations:

$$\mathcal{K}_a^L = -\frac{a_{+\hat{0}/2}}{6m_{pl}^2}(\rho_L + 3p_L)_{+\hat{0}/2}$$

Hubble's constraint:

$$\pi_a^2 = \frac{a^2}{3m_{pl}^2}\rho_L$$



# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

$$b_{+\hat{0}} = b + dt \mathcal{K}_a^L$$

Expansion equations:

$$\mathcal{K}_a^L = -\frac{a_{+\hat{0}/2}}{6m_{pl}^2} (\rho_L + 3p_L)_{+\hat{0}/2}$$

$$(\rho_L + 3p_L)_{+\hat{0}/2} = 2(\bar{K}_\phi^L + \bar{K}_{\phi,+\hat{0}}^L) - 2\bar{V}_{\phi,+\hat{0}/2}^L + 2K_A^L + (G_A^L + G_{A,+\hat{0}}^L)$$

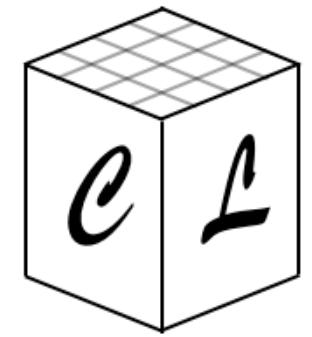
$$\rho_L = \bar{K}_\phi^L + \frac{1}{2}(\bar{G}_{\phi,-\hat{0}/2}^L + \bar{G}_{\phi,+\hat{0}/2}^L) + \frac{1}{2}(\bar{V}_{\phi,-\hat{0}/2}^L + \bar{V}_{\phi,+\hat{0}/2}^L) + \frac{1}{2}(\bar{K}_{A,-\hat{0}/2}^L + \bar{K}_{A,+\hat{0}/2}^L) + \bar{G}_A^L$$

Hubble's constraint:

$$\pi_a^2 = \frac{a^2}{3m_{pl}^2} \rho_L$$

$$\bar{K}_\phi^L = \frac{1}{N^3} \sum_{\vec{n}} \frac{1}{2a^6} \tilde{\pi}_\phi^2, \quad \bar{G}_\phi^L = \frac{1}{N^3} \sum_{\vec{n}} \frac{1}{2} \sum_i (\Delta_i^+ \phi_{+\hat{0}/2})^2, \quad \bar{V}_\phi^L = \frac{1}{N^3} \sum_{\vec{n}} \frac{1}{2} m^2 \phi_{+\hat{0}/2}^2$$

$$\bar{K}_A^L = \frac{1}{N^3} \sum_{\vec{n}} \sum_i \frac{1}{2a_{+\hat{0}/2}^4} \tilde{E}_{i,+\hat{0}/2}^2, \quad \bar{G}_A^L = \frac{1}{N^3} \sum_{\vec{n}} \sum_i \frac{1}{4a^4} (\Delta_i^+ A_j - \Delta_j^+ A_i)^2$$

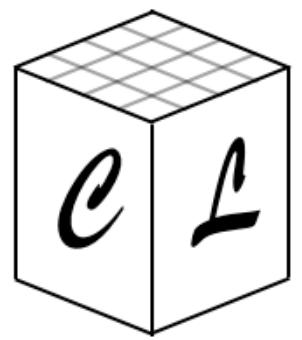


# Discretisation procedure

## Evolution Kernels

Dynamical equations:

$$\begin{aligned}\mathcal{K}_\phi^L &= a_{+\frac{\hat{0}}{2}} \sum_i \Delta_i^- \Delta_i^+ \phi_{+\frac{\hat{0}}{2}} - a_{+\frac{\hat{0}}{2}}^3 m^2 \phi_{+\frac{\hat{0}}{2}} + \frac{1}{2a\Lambda} \sum_i \tilde{E}_{i,+ \frac{\hat{0}}{2}}^{(2)} \left( B_i^{(4)} + B_{i,+ \frac{\hat{0}}{2}}^{(4)} \right) \\ \mathcal{K}_{i,A}^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right) \\ &\quad + \frac{1}{8a\Lambda} (2 + dx \Delta_i^+) \sum_{\pm} \sum_{j,k} \left\{ \epsilon_{ijk} [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{+\frac{\hat{0}}{2}} + [(\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}]_{-\frac{\hat{0}}{2}} \right\}\end{aligned}$$



# Discretisation procedure

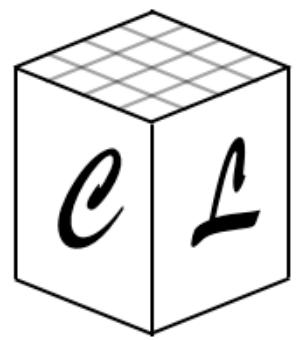
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Non-symplectic,  
Conjugate momenta in kernels!  
[Remember 4th lecture & 1st Topical]

$$\dot{\tilde{E}}_i = \mathcal{K}_{i,A}^L \left[ a, b, \phi, A_i, \tilde{E}_i \right]$$



# Discretisation procedure

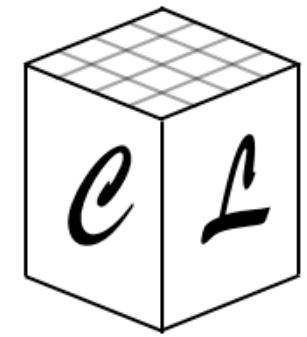
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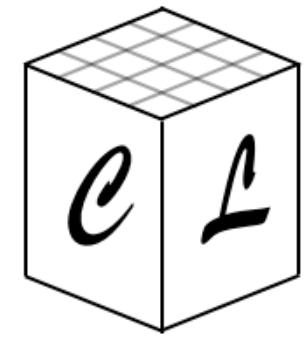
# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

$$\tilde{\pi}_{\phi,+\hat{0}} = \tilde{\pi}_\phi + dt \mathcal{K}_\phi^L , \quad \tilde{E}_{i,+\frac{\hat{0}}{2}} = \tilde{E}_{i,-\frac{\hat{0}}{2}} + dt \mathcal{K}_{i,A}^L$$

$$\phi_{+\frac{\hat{0}}{2}} = \phi_{-\frac{\hat{0}}{2}} + \frac{dt}{a^3} \tilde{\pi}_\phi , \quad A_{i,+\hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+\frac{\hat{0}}{2}}$$



# Discretisation procedure

Common kick-drift scheme

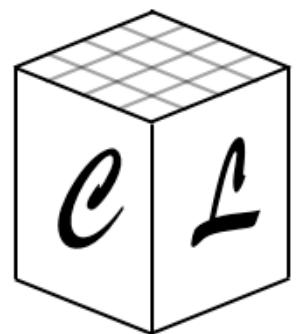
## Evolution Kernels

Dynamical equations:

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# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

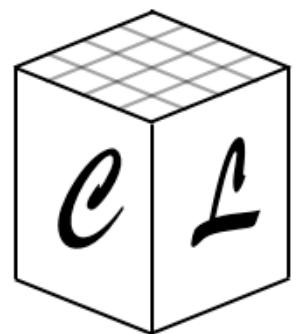
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Implicit scheme required

We need the value of the gauge's canonical momentum @ 0/2 for obtaining its value @ 0/2!



# Discretisation procedure

Common kick-drift scheme

## Evolution Kernels

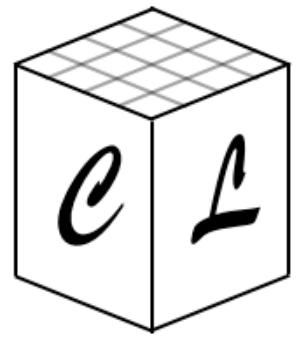
Dynamical equations:

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$$A_{i,+\hat{0}} = A_i + \frac{dt}{a} \tilde{E}_{i,+\frac{\hat{0}}{2}}$$

$$\mathcal{K}_\phi^L = a_{+\frac{\hat{0}}{2}} \sum_i \Delta_i^- \Delta_i^+ \phi_{+\frac{\hat{0}}{2}} - a_{+\frac{\hat{0}}{2}}^3 m^2 \phi$$
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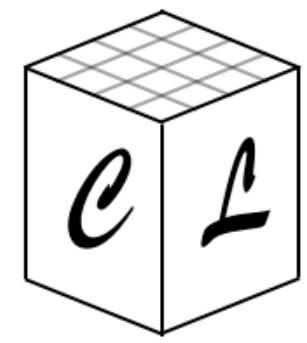
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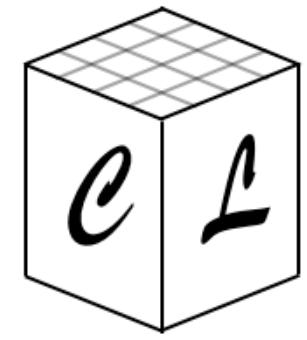
# Our Current Work



# Explicit-in-time integrator

Joanes

Ander

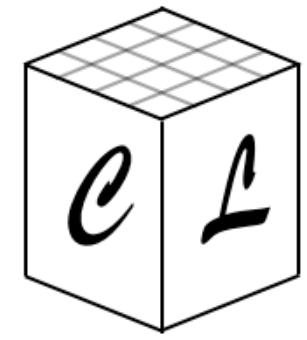


# Explicit-in-time integrator

Joanes

Ander

If momenta appear in kernels



# Explicit-in-time integrator

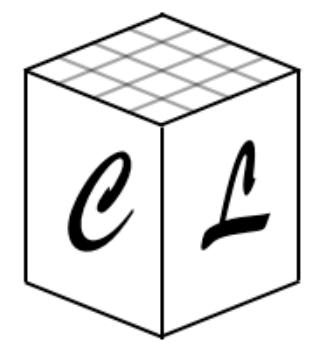
Joanes

If momenta appear in kernels



Ander

Not solvable by explicit  
symplectic integrators

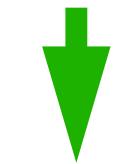


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Joanes

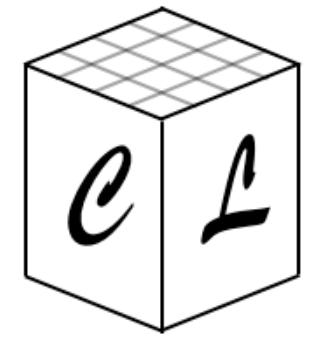
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If momenta appear in kernels



Not solvable by explicit  
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i.e. LF or VV



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Ander

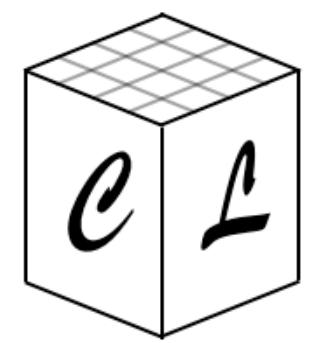
If momenta appear in kernels



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Why?



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Joanes

If momenta appear in kernels



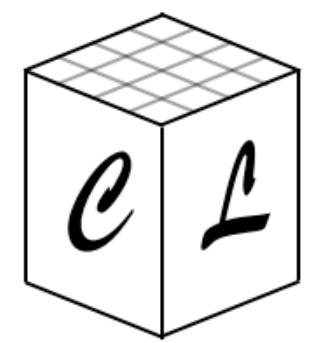
Ander

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$$\pi_{+\frac{\hat{0}}{2}} = \pi_{-\frac{\hat{0}}{2}} + \mathcal{K}[\pi_{+\frac{\hat{0}}{2}}]dt$$



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Joanes

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Ander

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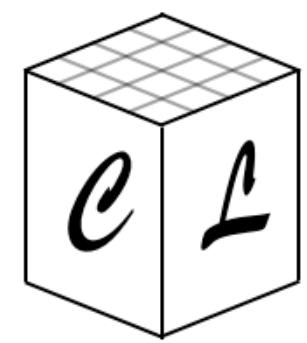
i.e. LF or VV

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Solution



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Ander

Non-symplectic integrators

Not solvable by explicit  
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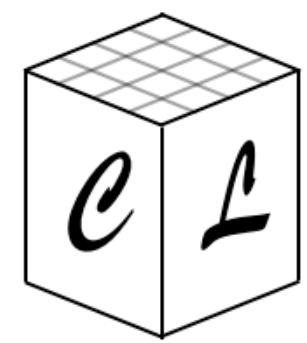
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Joanes

If momenta appear in kernels



Not solvable by explicit  
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i.e. LF or VV

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Ander

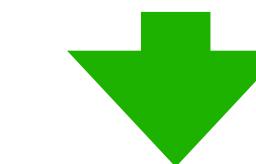
Non-symplectic integrators



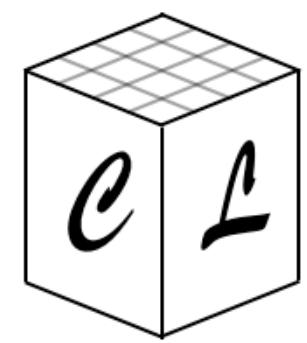
Solution



Runge-Kutta



$$\pi_{+\frac{\hat{0}}{2}} = \pi_{-\frac{\hat{0}}{2}} + \mathcal{K}[\pi_{+\frac{\hat{0}}{2}}]dt$$



# Explicit-in-time integrator

Joanes

If momenta appear in kernels



Not solvable by explicit  
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i.e. LF or VV

Why?

Ander

Non-symplectic integrators



Solution

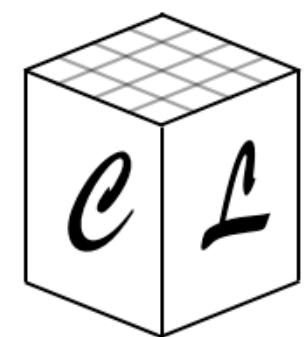


Runge-Kutta



(explicit version)

$$\pi_{+\frac{\hat{0}}{2}} = \pi_{-\frac{\hat{0}}{2}} + \mathcal{K}[\pi_{+\frac{\hat{0}}{2}}]dt$$



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If momenta appear in kernels



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Solution



Ander

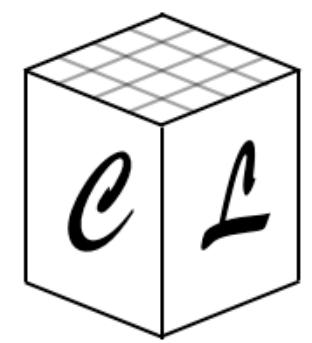
Non-symplectic integrators



(explicit version)

Runge-Kutta

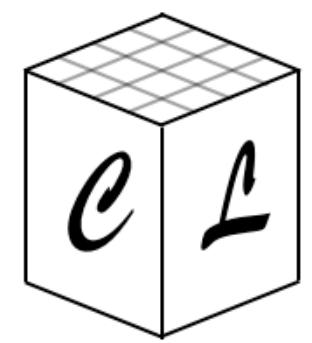
No longer!



# Explicit-in-time integrator

1<sup>st</sup> order ODE

$$\frac{dx}{dt} = v(t, x)$$



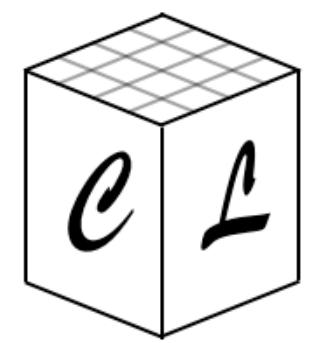
# Explicit-in-time integrator

RK2 & 2 stages

1<sup>st</sup> order ODE

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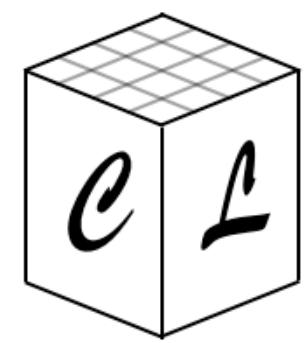
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RK2 & 2 stages

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$$\frac{dx}{dt} = v(t, x)$$

$$\left. \begin{aligned} x(t_{n+1}) &= x(t_n) + dt (b_1 G_1 + b_2 G_2) \end{aligned} \right\}$$



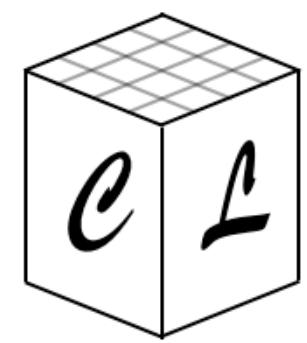
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# Explicit-in-time integrator

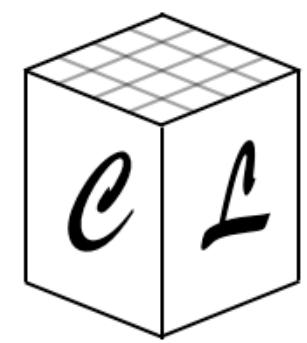
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$$x^{\text{Cont}}(t_{n+1}) - x^{\text{RK2}}(t_{n+1}) = \mathcal{O}(dt^3)$$



# Explicit-in-time integrator

RK2 & 2 stages

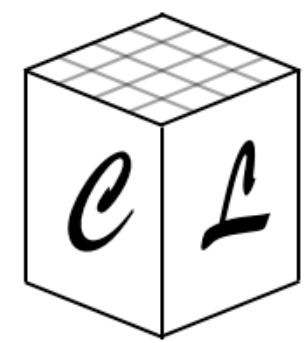
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$$\text{Constraints} \rightarrow b_1 + b_2 = 1 , \ b_2 c_2 = 1/2 , \ b_2 a_{21} = 1/2$$



# Explicit-in-time integrator

RK2 & 2 stages

1<sup>st</sup> order ODE

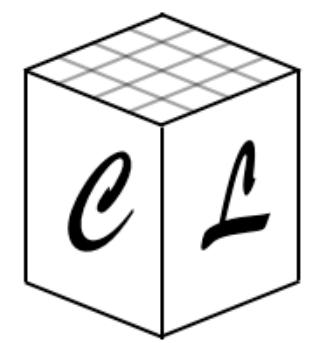
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Modified Euler



# Explicit-in-time integrator

RK2 & 2 stages

1<sup>st</sup> order ODE

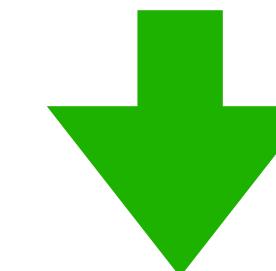
$$\frac{dx}{dt} = v(t, x)$$

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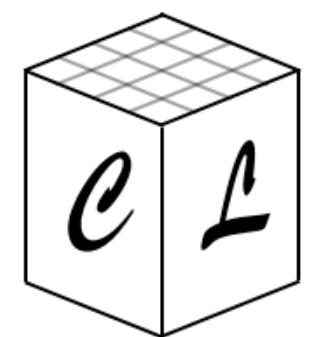
$$x^{\text{Cont}}(t_{n+1}) - x^{\text{RK2}}(t_{n+1}) = \mathcal{O}(dt^3)$$

$$\text{Constraints} \rightarrow b_1 + b_2 = 1 , \ b_2 c_2 = 1/2 , \ b_2 a_{21} = 1/2$$

Modified Euler



$$b_1 = 1/2 , \ b_2 = 1/2 , \ c_2 = 1 , \ a_{21} = 1$$



# Explicit-in-time integrator

RK2 & 2 stages

1<sup>st</sup> order ODE

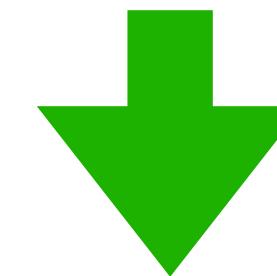
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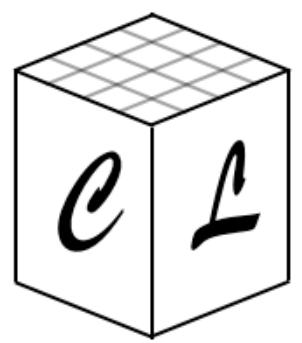
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Modified Euler

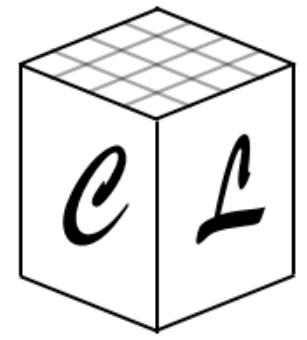


$$b_1 = 1/2 , \ b_2 = 1/2 , \ c_2 = 1 , \ a_{21} = 1$$

$$\boxed{\begin{array}{l} x(t_{n+1}) = x(t_n) + \frac{dt}{2} (G_1 + G_2) \\ G_1 = v(t_n, x(t_n)) \\ G_2 = v(t_n + dt, x(t_n) + G_1 dt) \end{array}}$$



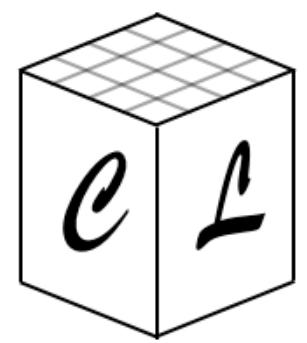
# Explicit-in-time integrator



# Explicit-in-time integrator

2<sup>nd</sup> order ODE

$$\frac{d^2x}{dt^2} = \mathcal{K}\left(t, x, \frac{dx}{dt}\right)$$

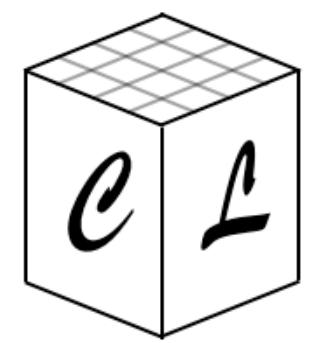


# Explicit-in-time integrator

2<sup>nd</sup> order ODE

$$\frac{d^2x}{dt^2} = \mathcal{K}\left(t, x, \frac{dx}{dt}\right)$$

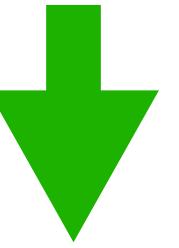
1st order ODE RK2 ?



# Explicit-in-time integrator

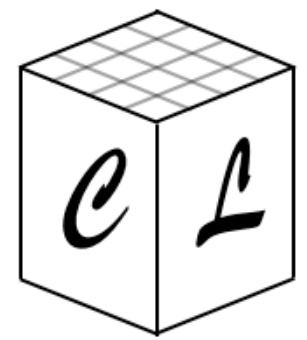
2<sup>nd</sup> order ODE

$$\frac{d^2x}{dt^2} = \mathcal{K}\left(t, x, \frac{dx}{dt}\right)$$

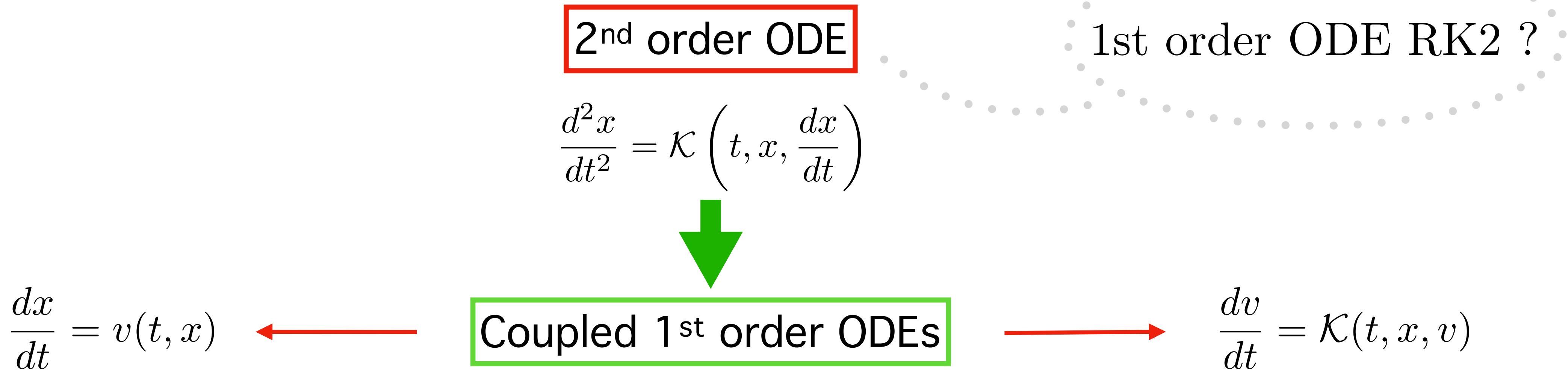


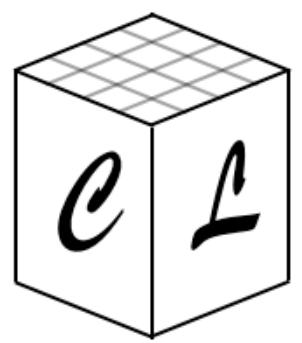
Coupled 1<sup>st</sup> order ODEs

1st order ODE RK2 ?

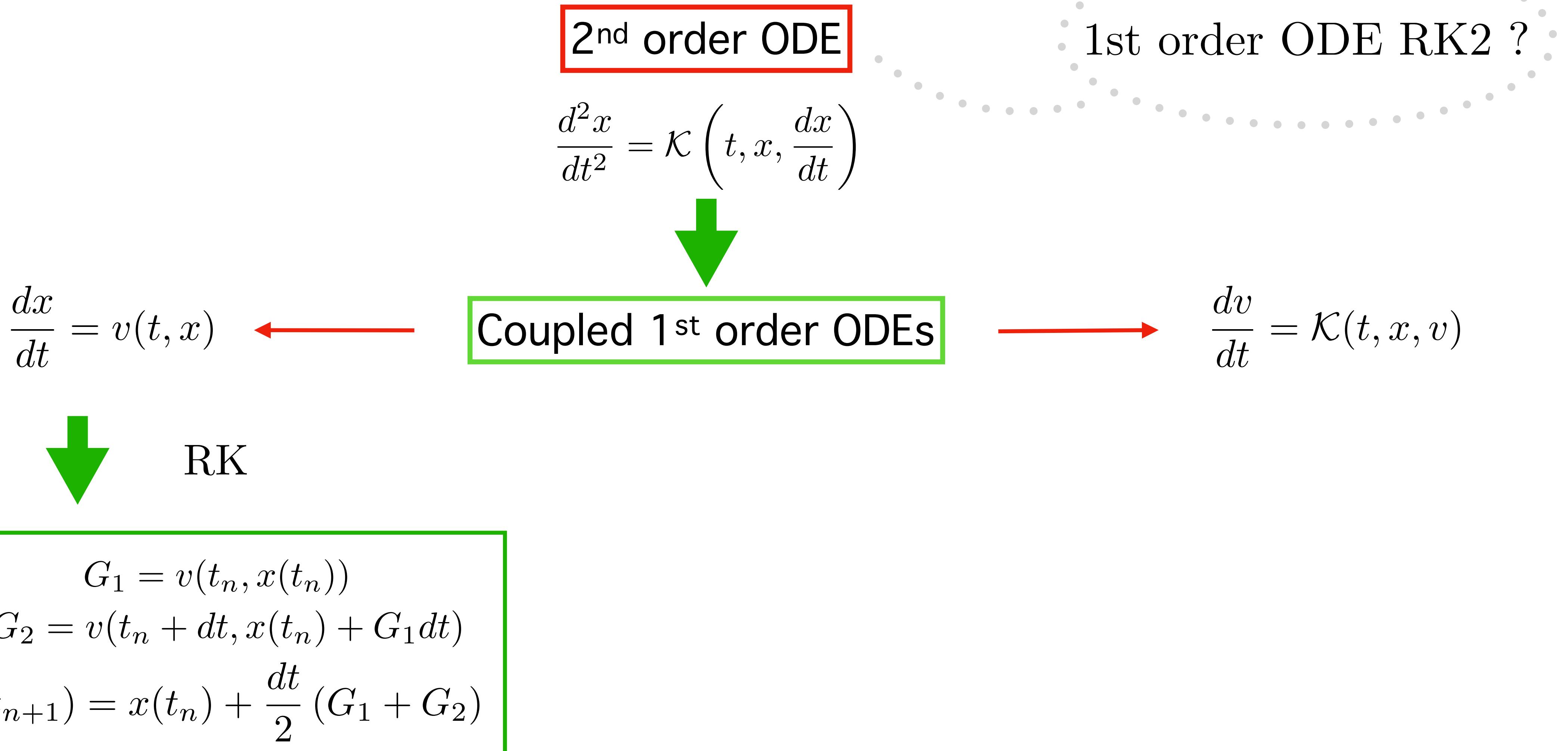


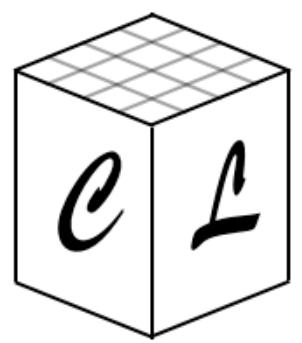
# Explicit-in-time integrator



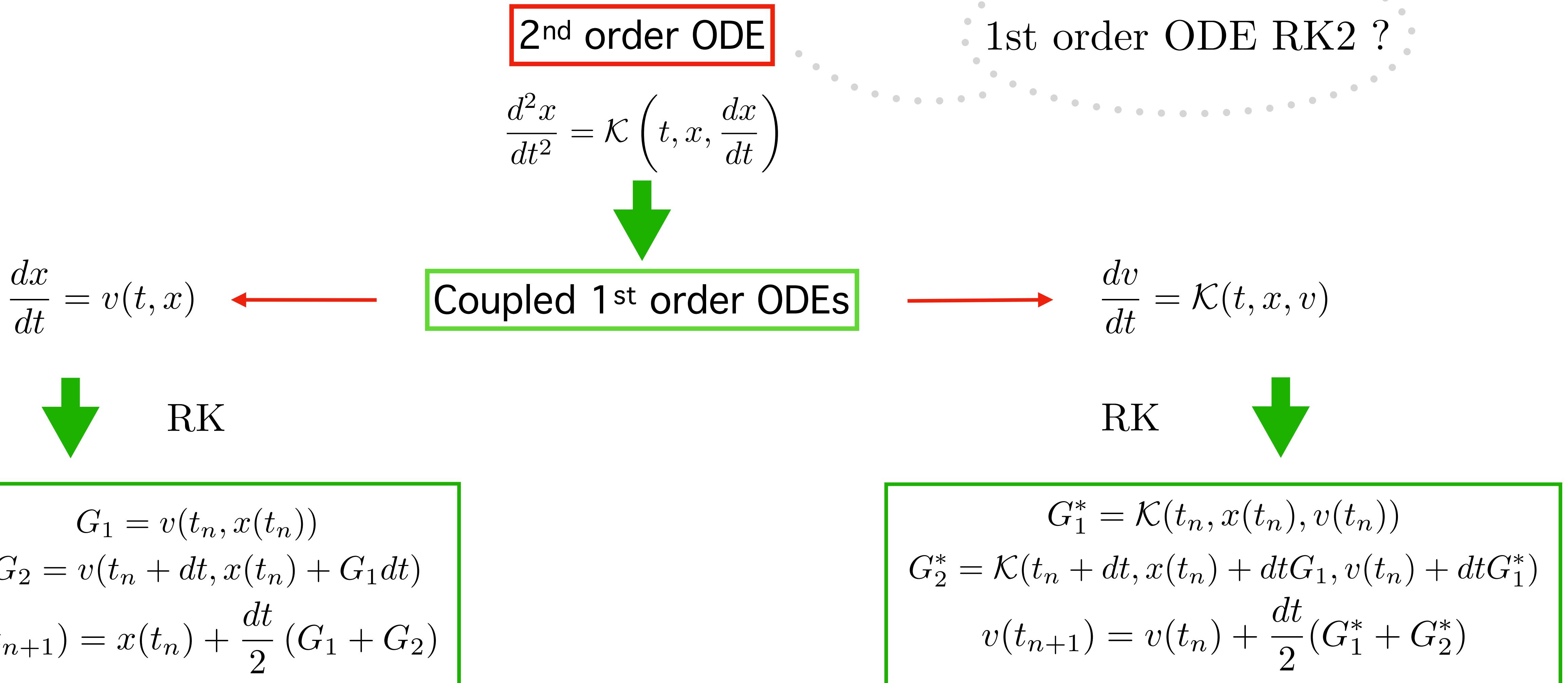


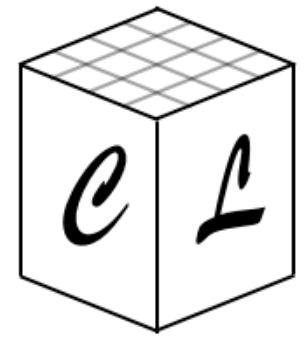
# Explicit-in-time integrator





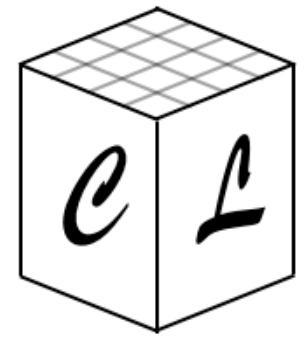
# Explicit-in-time integrator





# Explicit-in-time integrator

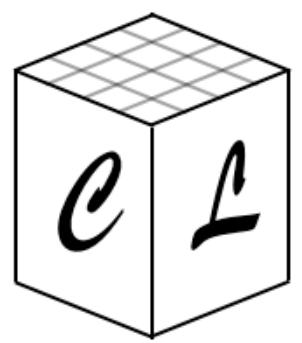
Axion-Inflation using RK2



# Explicit-in-time integrator

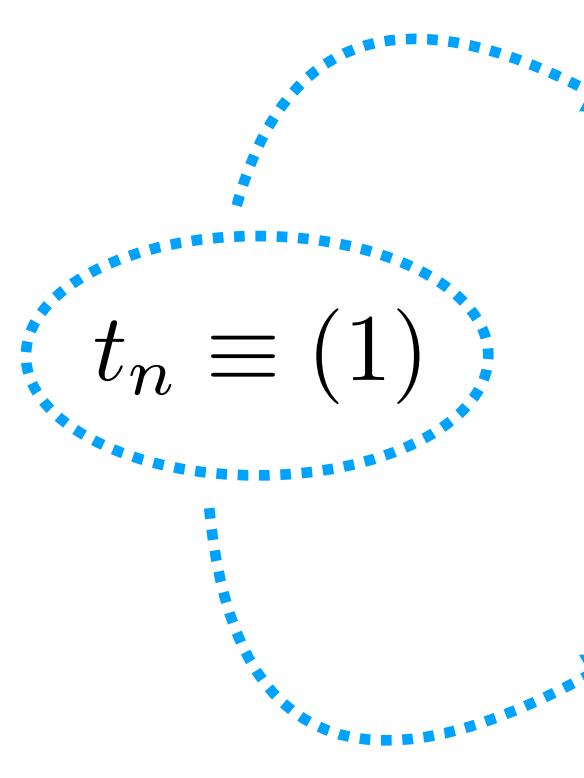
Axion-Inflation using RK2

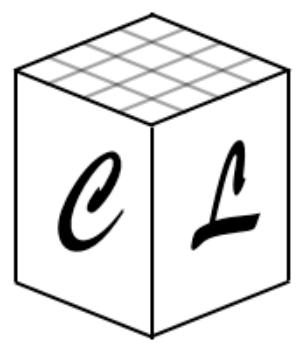
$$t_n \equiv (1)$$



# Explicit-in-time integrator

Axion-Inflation using RK2

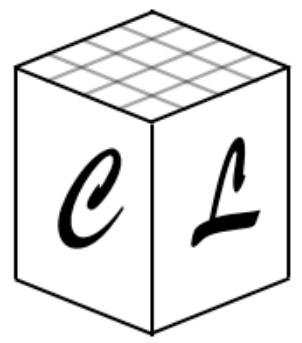
$$t_n \equiv (1) \left\{ \begin{array}{l} \phi^{(1)} = \phi(t_n) , \\ A_i^{(1)} = A_i(t_n) , \\ a^{(1)} = a(t_n) , \\ \tilde{\pi}_\phi^{(1)} = \tilde{\pi}_\phi(t_n) , \\ \tilde{E}_i^{(1)} = \tilde{E}_i(t_n) , \\ \pi_a^{(1)} = \pi_a(t_n) , \end{array} \right.$$




# Explicit-in-time integrator

Axion-Inflation using RK2

$$t_n \equiv (1) \quad \left\{ \begin{array}{l} \phi^{(1)} = \phi(t_n) , \\ A_i^{(1)} = A_i(t_n) , \\ a^{(1)} = a(t_n) , \\ \tilde{\pi}_\phi^{(1)} = \tilde{\pi}_\phi(t_n) , \\ \tilde{E}_i^{(1)} = \tilde{E}_i(t_n) , \\ \pi_a^{(1)} = \pi_a(t_n) , \end{array} \right. \quad \xrightarrow{\text{dotted arrow}} \quad \left\{ \begin{array}{l} K_\phi^{(1)} = K_\phi(a^{(1)}, \tilde{\pi}_\phi^{(1)}) \\ V^{(1)} = V(\phi^{(1)}) \\ K_A^{(1)} = K_A(a^{(1)}, \tilde{E}_i^{(1)}) \\ G_A^{(1)} = G_A(a^{(1)}, A_i^{(1)}) \end{array} \right.$$

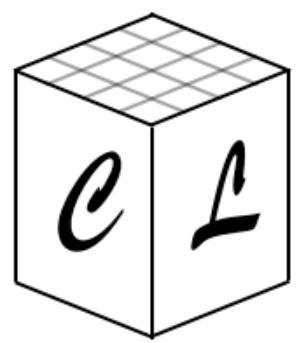


# Explicit-in-time integrator

Axion-Inflation using RK2

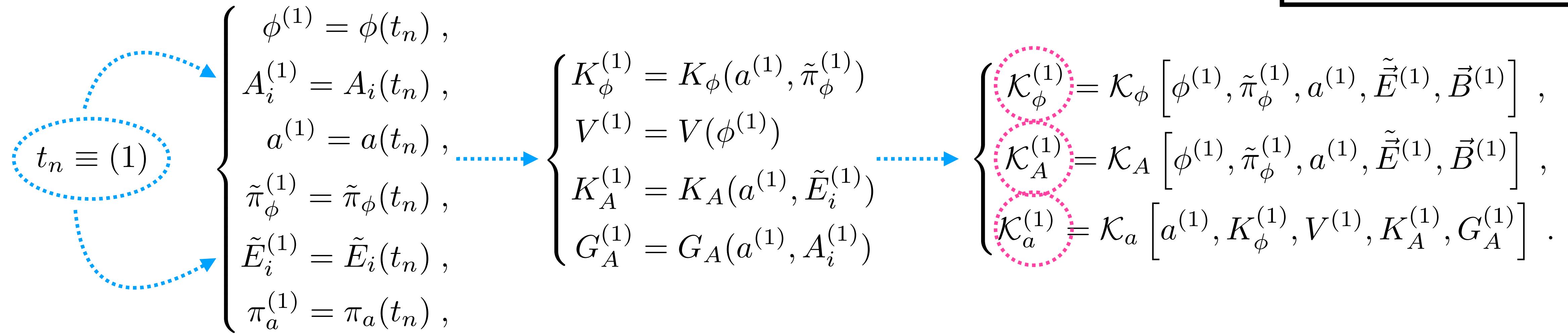
The diagram illustrates the flow of variables in an explicit-in-time integrator for Axion-Inflation using RK2. It consists of three main stages connected by dotted arrows:

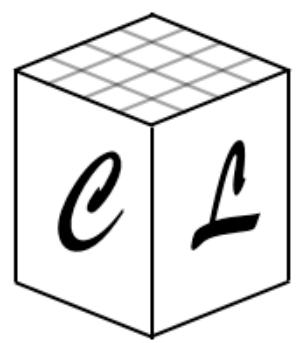
- Initial State:**  $t_n \equiv (1)$  (enclosed in a dashed circle) feeds into the first stage.
- Intermediate Stage:** This stage contains two sets of equations:
  - Left set:  $\phi^{(1)} = \phi(t_n), A_i^{(1)} = A_i(t_n), a^{(1)} = a(t_n), \tilde{\pi}_\phi^{(1)} = \tilde{\pi}_\phi(t_n), \tilde{E}_i^{(1)} = \tilde{E}_i(t_n), \pi_a^{(1)} = \pi_a(t_n)$ .
  - Right set:  $K_\phi^{(1)} = K_\phi(a^{(1)}, \tilde{\pi}_\phi^{(1)}), V^{(1)} = V(\phi^{(1)}), K_A^{(1)} = K_A(a^{(1)}, \tilde{E}_i^{(1)}), G_A^{(1)} = G_A(a^{(1)}, A_i^{(1)})$ .Dotted arrows indicate dependencies between the left and right sets.
- Final Stage:** This stage contains three equations:
$$\begin{cases} \mathcal{K}_\phi^{(1)} = \mathcal{K}_\phi \left[ \phi^{(1)}, \tilde{\pi}_\phi^{(1)}, a^{(1)}, \tilde{E}^{(1)}, \vec{B}^{(1)} \right], \\ \mathcal{K}_A^{(1)} = \mathcal{K}_A \left[ \phi^{(1)}, \tilde{\pi}_\phi^{(1)}, a^{(1)}, \tilde{E}^{(1)}, \vec{B}^{(1)} \right], \\ \mathcal{K}_a^{(1)} = \mathcal{K}_a \left[ a^{(1)}, K_\phi^{(1)}, V^{(1)}, K_A^{(1)}, G_A^{(1)} \right]. \end{cases}$$



# Explicit-in-time integrator

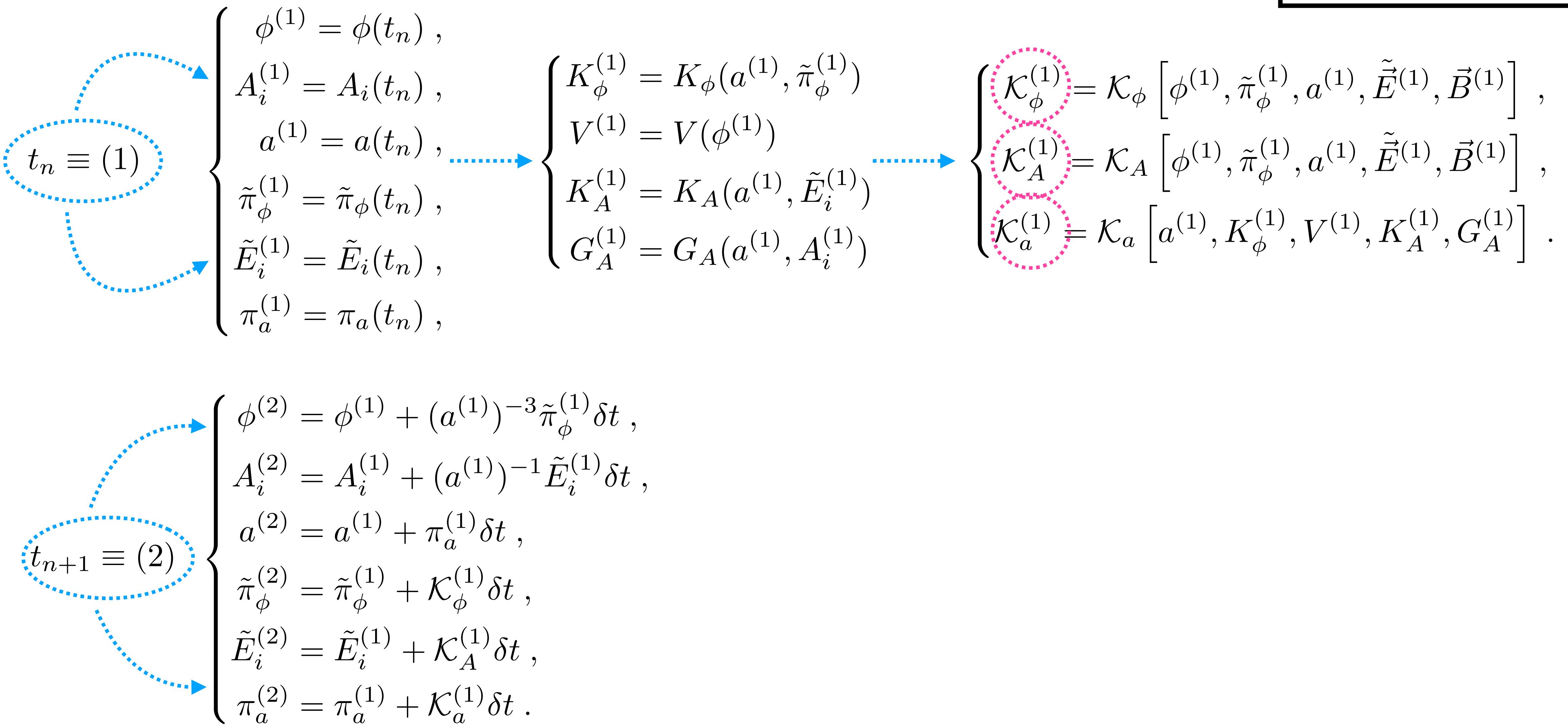
Axion-Inflation using RK2

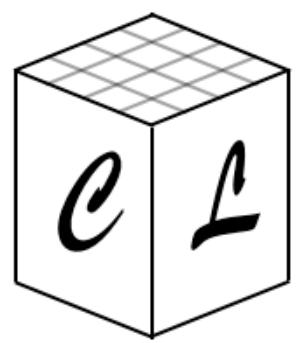




# Explicit-in-time integrator

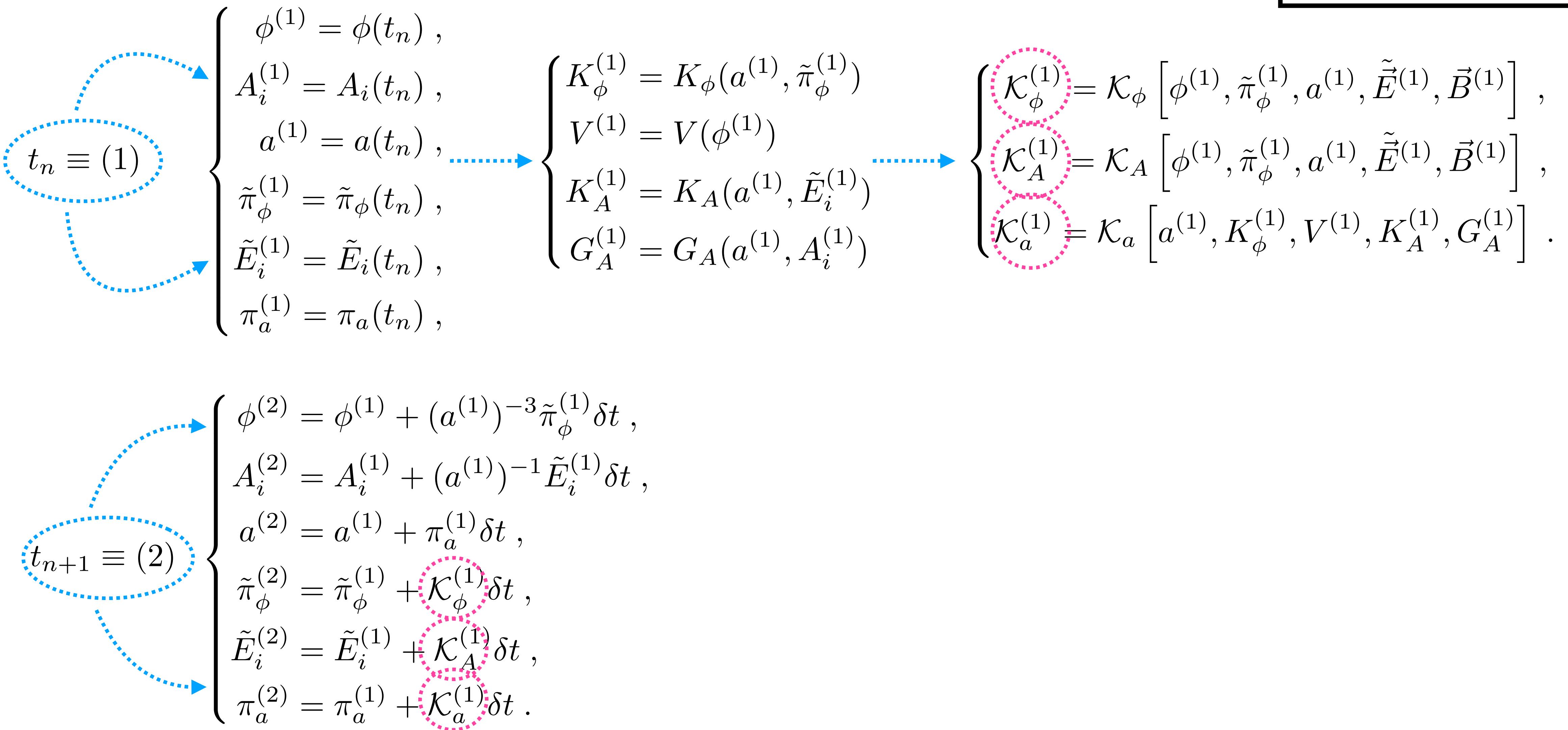
Axion-Inflation using RK2

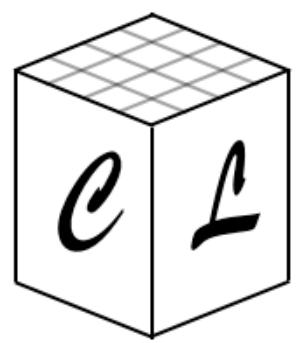




# Explicit-in-time integrator

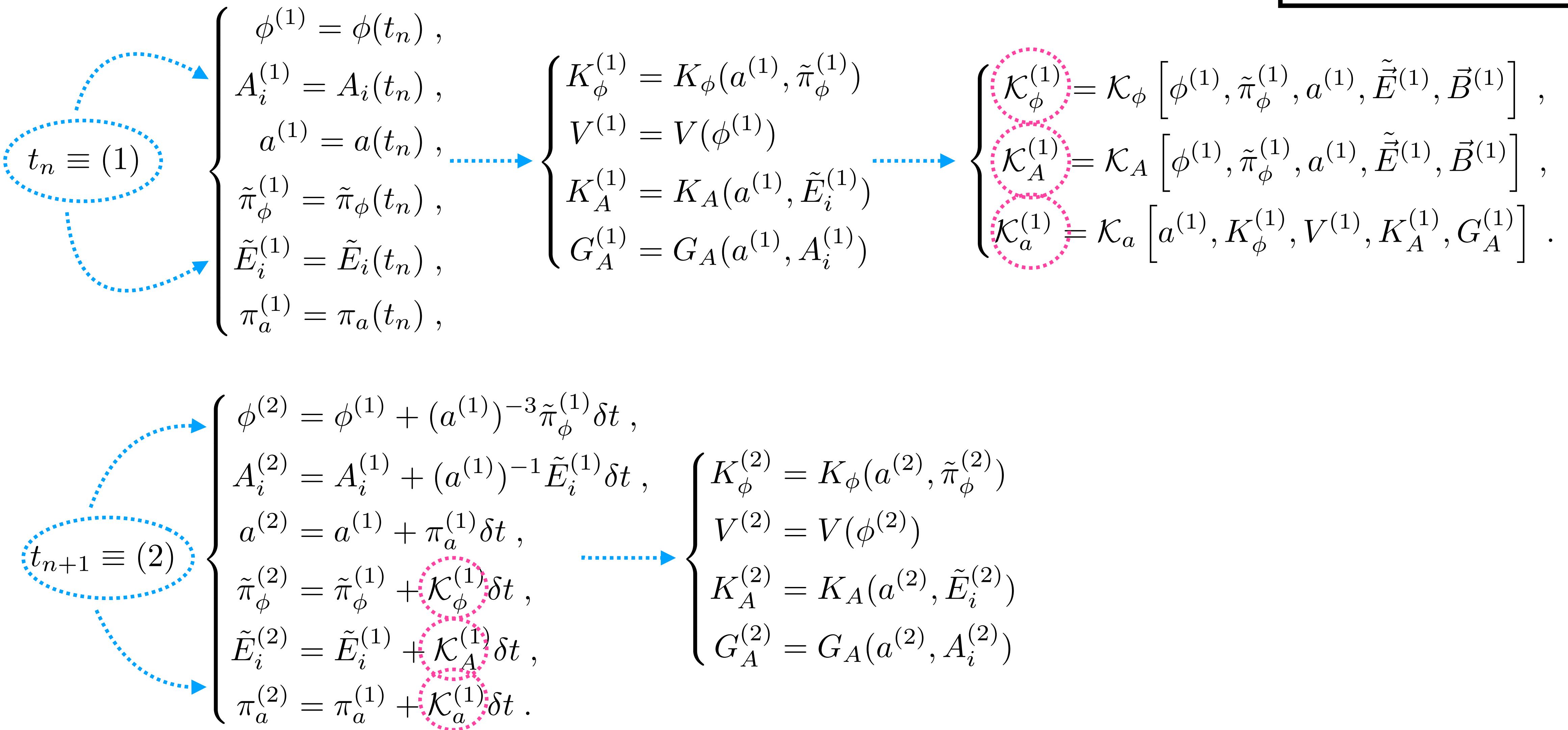
Axion-Inflation using RK2

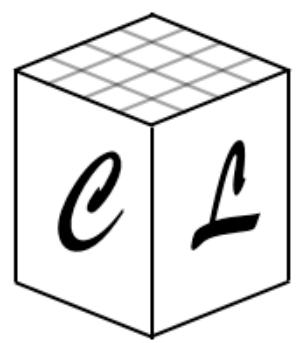




# Explicit-in-time integrator

Axion-Inflation using RK2



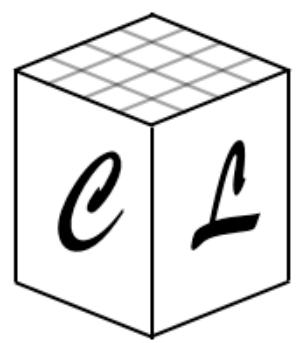


# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}
 t_n \equiv (1) & \quad \left\{ \begin{array}{l} \phi^{(1)} = \phi(t_n), \\ A_i^{(1)} = A_i(t_n), \\ a^{(1)} = a(t_n), \\ \tilde{\pi}_\phi^{(1)} = \tilde{\pi}_\phi(t_n), \\ \tilde{E}_i^{(1)} = \tilde{E}_i(t_n), \\ \pi_a^{(1)} = \pi_a(t_n), \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} K_\phi^{(1)} = K_\phi(a^{(1)}, \tilde{\pi}_\phi^{(1)}) \\ V^{(1)} = V(\phi^{(1)}) \\ K_A^{(1)} = K_A(a^{(1)}, \tilde{E}_i^{(1)}) \\ G_A^{(1)} = G_A(a^{(1)}, A_i^{(1)}) \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} \mathcal{K}_\phi^{(1)} = \mathcal{K}_\phi \left[ \phi^{(1)}, \tilde{\pi}_\phi^{(1)}, a^{(1)}, \tilde{E}^{(1)}, \vec{B}^{(1)} \right], \\ \mathcal{K}_A^{(1)} = \mathcal{K}_A \left[ \phi^{(1)}, \tilde{\pi}_\phi^{(1)}, a^{(1)}, \tilde{E}^{(1)}, \vec{B}^{(1)} \right], \\ \mathcal{K}_a^{(1)} = \mathcal{K}_a \left[ a^{(1)}, K_\phi^{(1)}, V^{(1)}, K_A^{(1)}, G_A^{(1)} \right]. \end{array} \right.
 \end{aligned}$$

$$\begin{aligned}
 t_{n+1} \equiv (2) & \quad \left\{ \begin{array}{l} \phi^{(2)} = \phi^{(1)} + (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} \delta t, \\ A_i^{(2)} = A_i^{(1)} + (a^{(1)})^{-1} \tilde{E}_i^{(1)} \delta t, \\ a^{(2)} = a^{(1)} + \pi_a^{(1)} \delta t, \\ \tilde{\pi}_\phi^{(2)} = \tilde{\pi}_\phi^{(1)} + \mathcal{K}_\phi^{(1)} \delta t, \\ \tilde{E}_i^{(2)} = \tilde{E}_i^{(1)} + \mathcal{K}_A^{(1)} \delta t, \\ \pi_a^{(2)} = \pi_a^{(1)} + \mathcal{K}_a^{(1)} \delta t. \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} K_\phi^{(2)} = K_\phi(a^{(2)}, \tilde{\pi}_\phi^{(2)}) \\ V^{(2)} = V(\phi^{(2)}) \\ K_A^{(2)} = K_A(a^{(2)}, \tilde{E}_i^{(2)}) \\ G_A^{(2)} = G_A(a^{(2)}, A_i^{(2)}) \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} \mathcal{K}_\phi^{(2)} = \mathcal{K}_\phi \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_A^{(2)} = \mathcal{K}_A \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_a^{(2)} = \mathcal{K}_a \left[ a^{(2)}, K_\phi^{(2)}, V^{(2)}, K_A^{(2)}, G_A^{(2)} \right]. \end{array} \right.
 \end{aligned}$$

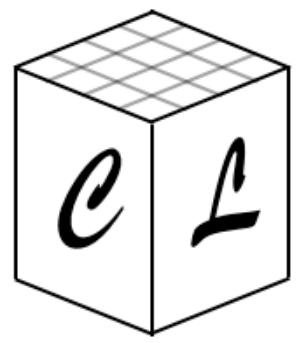


# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}
 t_n \equiv (1) & \quad \left\{ \begin{array}{l} \phi^{(1)} = \phi(t_n), \\ A_i^{(1)} = A_i(t_n), \\ a^{(1)} = a(t_n), \\ \tilde{\pi}_\phi^{(1)} = \tilde{\pi}_\phi(t_n), \\ \tilde{E}_i^{(1)} = \tilde{E}_i(t_n), \\ \pi_a^{(1)} = \pi_a(t_n), \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} K_\phi^{(1)} = K_\phi(a^{(1)}, \tilde{\pi}_\phi^{(1)}) \\ V^{(1)} = V(\phi^{(1)}) \\ K_A^{(1)} = K_A(a^{(1)}, \tilde{E}_i^{(1)}) \\ G_A^{(1)} = G_A(a^{(1)}, A_i^{(1)}) \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} \mathcal{K}_\phi^{(1)} = \mathcal{K}_\phi \left[ \phi^{(1)}, \tilde{\pi}_\phi^{(1)}, a^{(1)}, \tilde{E}^{(1)}, \vec{B}^{(1)} \right], \\ \mathcal{K}_A^{(1)} = \mathcal{K}_A \left[ \phi^{(1)}, \tilde{\pi}_\phi^{(1)}, a^{(1)}, \tilde{E}^{(1)}, \vec{B}^{(1)} \right], \\ \mathcal{K}_a^{(1)} = \mathcal{K}_a \left[ a^{(1)}, K_\phi^{(1)}, V^{(1)}, K_A^{(1)}, G_A^{(1)} \right]. \end{array} \right.
 \end{aligned}$$

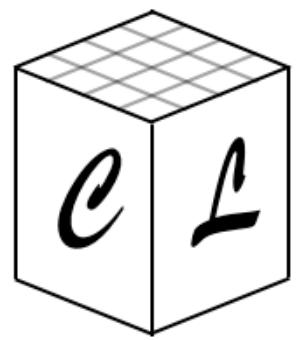
$$\begin{aligned}
 t_{n+1} \equiv (2) & \quad \left\{ \begin{array}{l} \phi^{(2)} = \phi^{(1)} + (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} \delta t, \\ A_i^{(2)} = A_i^{(1)} + (a^{(1)})^{-1} \tilde{E}_i^{(1)} \delta t, \\ a^{(2)} = a^{(1)} + \pi_a^{(1)} \delta t, \\ \tilde{\pi}_\phi^{(2)} = \tilde{\pi}_\phi^{(1)} + \mathcal{K}_\phi^{(1)} \delta t, \\ \tilde{E}_i^{(2)} = \tilde{E}_i^{(1)} + \mathcal{K}_A^{(1)} \delta t, \\ \pi_a^{(2)} = \pi_a^{(1)} + \mathcal{K}_a^{(1)} \delta t. \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} K_\phi^{(2)} = K_\phi(a^{(2)}, \tilde{\pi}_\phi^{(2)}) \\ V^{(2)} = V(\phi^{(2)}) \\ K_A^{(2)} = K_A(a^{(2)}, \tilde{E}_i^{(2)}) \\ G_A^{(2)} = G_A(a^{(2)}, A_i^{(2)}) \end{array} \right. \\
 & \xrightarrow{\text{dotted arrow}} \left\{ \begin{array}{l} \mathcal{K}_\phi^{(2)} = \mathcal{K}_\phi \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_A^{(2)} = \mathcal{K}_A \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_a^{(2)} = \mathcal{K}_a \left[ a^{(2)}, K_\phi^{(2)}, V^{(2)}, K_A^{(2)}, G_A^{(2)} \right]. \end{array} \right.
 \end{aligned}$$



# Explicit-in-time integrator

Axion-Inflation using RK2

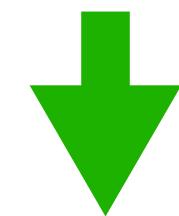
$$\begin{aligned} t_{n+1} \equiv (2) & \quad \left\{ \begin{array}{l} \phi^{(2)} = \phi^{(1)} + (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} \delta t , \\ A_i^{(2)} = A_i^{(1)} + (a^{(1)})^{-1} \tilde{E}_i^{(1)} \delta t , \\ a^{(2)} = a^{(1)} + \pi_a^{(1)} \delta t , \\ \tilde{\pi}_\phi^{(2)} = \tilde{\pi}_\phi^{(1)} + \mathcal{K}_\phi^{(1)} \delta t , \\ \tilde{E}_i^{(2)} = \tilde{E}_i^{(1)} + \mathcal{K}_A^{(1)} \delta t , \\ \pi_a^{(2)} = \pi_a^{(1)} + \mathcal{K}_a^{(1)} \delta t . \end{array} \right. \\ & \quad \xrightarrow{\text{dotted blue arrow}} \left\{ \begin{array}{l} K_\phi^{(2)} = K_\phi(a^{(2)}, \tilde{\pi}_\phi^{(2)}) \\ V^{(2)} = V(\phi^{(2)}) \\ K_A^{(2)} = K_A(a^{(2)}, \tilde{E}_i^{(2)}) \\ G_A^{(2)} = G_A(a^{(2)}, A_i^{(2)}) \end{array} \right. \\ & \quad \xrightarrow{\text{dotted blue arrow}} \left\{ \begin{array}{l} \mathcal{K}_\phi^{(2)} = \mathcal{K}_\phi \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right] , \\ \mathcal{K}_A^{(2)} = \mathcal{K}_A \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right] , \\ \mathcal{K}_a^{(2)} = \mathcal{K}_a \left[ a^{(2)}, K_\phi^{(2)}, V^{(2)}, K_A^{(2)}, G_A^{(2)} \right] . \end{array} \right. \end{aligned}$$



# Explicit-in-time integrator

Axion-Inflation using RK2

$$t_{n+1} \equiv (2) \quad \left\{ \begin{array}{l} \phi^{(2)} = \phi^{(1)} + (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} \delta t, \\ A_i^{(2)} = A_i^{(1)} + (a^{(1)})^{-1} \tilde{E}_i^{(1)} \delta t, \\ a^{(2)} = a^{(1)} + \pi_a^{(1)} \delta t, \\ \tilde{\pi}_\phi^{(2)} = \tilde{\pi}_\phi^{(1)} + \mathcal{K}_\phi^{(1)} \delta t, \\ \tilde{E}_i^{(2)} = \tilde{E}_i^{(1)} + \mathcal{K}_A^{(1)} \delta t, \\ \pi_a^{(2)} = \pi_a^{(1)} + \mathcal{K}_a^{(1)} \delta t. \end{array} \right. \quad \xrightarrow{\text{dotted blue arrows}} \quad \left\{ \begin{array}{l} K_\phi^{(2)} = K_\phi(a^{(2)}, \tilde{\pi}_\phi^{(2)}) \\ V^{(2)} = V(\phi^{(2)}) \\ K_A^{(2)} = K_A(a^{(2)}, \tilde{E}_i^{(2)}) \\ G_A^{(2)} = G_A(a^{(2)}, A_i^{(2)}) \end{array} \right. \quad \xrightarrow{\text{dotted blue arrow}} \quad \left\{ \begin{array}{l} \mathcal{K}_\phi^{(2)} = \mathcal{K}_\phi \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_A^{(2)} = \mathcal{K}_A \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_a^{(2)} = \mathcal{K}_a \left[ a^{(2)}, K_\phi^{(2)}, V^{(2)}, K_A^{(2)}, G_A^{(2)} \right]. \end{array} \right.$$



$$\phi(t_{n+1}) = \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2$$

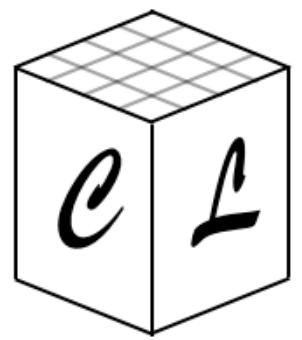
$$A_i(t_{n+1}) = A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2$$

$$a(t_{n+1}) = a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2$$

$$\tilde{\pi}_\phi(t_{n+1}) = \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t$$

$$\tilde{E}_i(t_{n+1}) = \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t$$

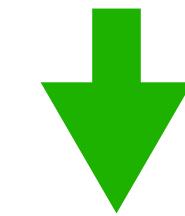
$$\pi_a(t_{n+1}) = \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t$$



# Explicit-in-time integrator

Axion-Inflation using RK2

$$t_{n+1} \equiv (2) \quad \left\{ \begin{array}{l} \phi^{(2)} = \phi^{(1)} + (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} \delta t, \\ A_i^{(2)} = A_i^{(1)} + (a^{(1)})^{-1} \tilde{E}_i^{(1)} \delta t, \\ a^{(2)} = a^{(1)} + \pi_a^{(1)} \delta t, \\ \tilde{\pi}_\phi^{(2)} = \tilde{\pi}_\phi^{(1)} + \mathcal{K}_\phi^{(1)} \delta t, \\ \tilde{E}_i^{(2)} = \tilde{E}_i^{(1)} + \mathcal{K}_A^{(1)} \delta t, \\ \pi_a^{(2)} = \pi_a^{(1)} + \mathcal{K}_a^{(1)} \delta t. \end{array} \right. \quad \xrightarrow{\text{dotted blue arrows}} \quad \left\{ \begin{array}{l} K_\phi^{(2)} = K_\phi(a^{(2)}, \tilde{\pi}_\phi^{(2)}) \\ V^{(2)} = V(\phi^{(2)}) \\ K_A^{(2)} = K_A(a^{(2)}, \tilde{E}_i^{(2)}) \\ G_A^{(2)} = G_A(a^{(2)}, A_i^{(2)}) \end{array} \right. \quad \xrightarrow{\text{dotted blue arrow}} \quad \left\{ \begin{array}{l} \mathcal{K}_\phi^{(2)} = \mathcal{K}_\phi \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_A^{(2)} = \mathcal{K}_A \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_a^{(2)} = \mathcal{K}_a \left[ a^{(2)}, K_\phi^{(2)}, V^{(2)}, K_A^{(2)}, G_A^{(2)} \right]. \end{array} \right.$$



$$\phi(t_{n+1}) = \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2$$

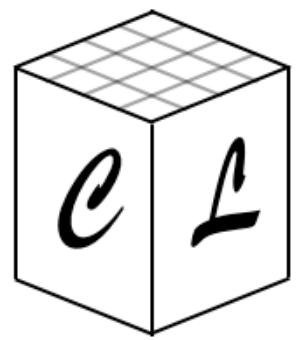
$$A_i(t_{n+1}) = A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2$$

$$a(t_{n+1}) = a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2$$

$$\tilde{\pi}_\phi(t_{n+1}) = \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t$$

$$\tilde{E}_i(t_{n+1}) = \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t$$

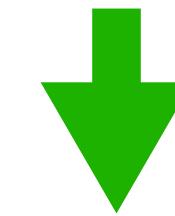
$$\pi_a(t_{n+1}) = \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t$$



# Explicit-in-time integrator

Axion-Inflation using RK2

$$t_{n+1} \equiv (2) \quad \left\{ \begin{array}{l} \phi^{(2)} = \phi^{(1)} + (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} \delta t, \\ A_i^{(2)} = A_i^{(1)} + (a^{(1)})^{-1} \tilde{E}_i^{(1)} \delta t, \\ a^{(2)} = a^{(1)} + \pi_a^{(1)} \delta t, \\ \tilde{\pi}_\phi^{(2)} = \tilde{\pi}_\phi^{(1)} + \mathcal{K}_\phi^{(1)} \delta t, \\ \tilde{E}_i^{(2)} = \tilde{E}_i^{(1)} + \mathcal{K}_A^{(1)} \delta t, \\ \pi_a^{(2)} = \pi_a^{(1)} + \mathcal{K}_a^{(1)} \delta t. \end{array} \right. \quad \xrightarrow{\text{dotted blue arrows}} \quad \left\{ \begin{array}{l} K_\phi^{(2)} = K_\phi(a^{(2)}, \tilde{\pi}_\phi^{(2)}) \\ V^{(2)} = V(\phi^{(2)}) \\ K_A^{(2)} = K_A(a^{(2)}, \tilde{E}_i^{(2)}) \\ G_A^{(2)} = G_A(a^{(2)}, A_i^{(2)}) \end{array} \right. \quad \xrightarrow{\text{dotted blue arrow}} \quad \left\{ \begin{array}{l} \mathcal{K}_\phi^{(2)} = \mathcal{K}_\phi \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_A^{(2)} = \mathcal{K}_A \left[ \phi^{(2)}, \tilde{\pi}_\phi^{(2)}, a^{(2)}, \tilde{E}_i^{(2)}, \vec{B}^{(2)} \right], \\ \mathcal{K}_a^{(2)} = \mathcal{K}_a \left[ a^{(2)}, K_\phi^{(2)}, V^{(2)}, K_A^{(2)}, G_A^{(2)} \right]. \end{array} \right.$$



$$\phi(t_{n+1}) = \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2$$

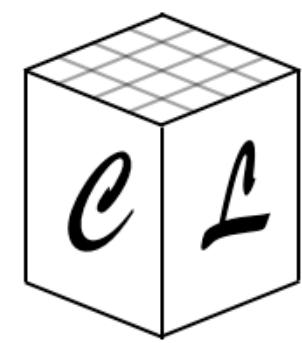
$$A_i(t_{n+1}) = A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2$$

$$a(t_{n+1}) = a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2$$

$$\tilde{\pi}_\phi(t_{n+1}) = \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t$$

$$\tilde{E}_i(t_{n+1}) = \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t$$

$$\pi_a(t_{n+1}) = \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t$$

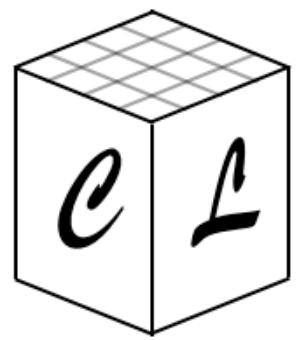


# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$



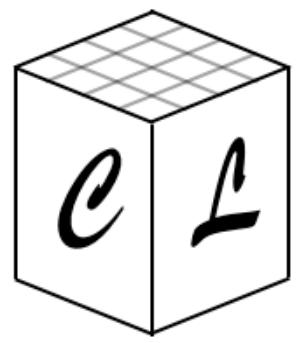
# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$

More intermediate  
kernels

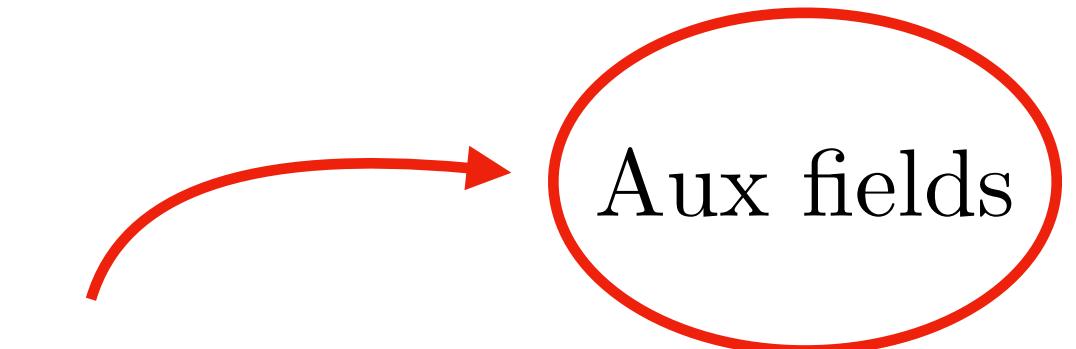


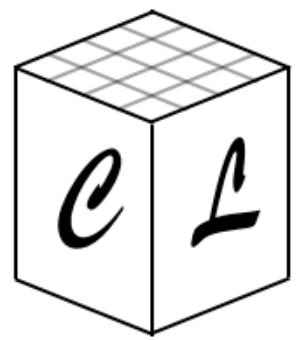
# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$



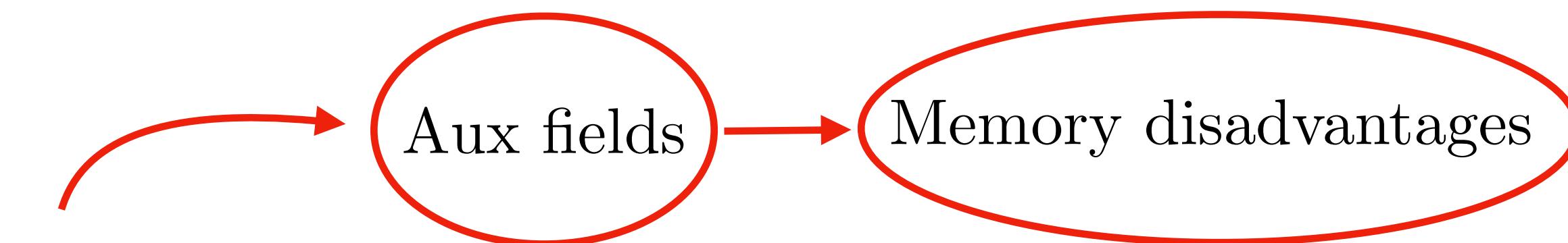


# Explicit-in-time integrator

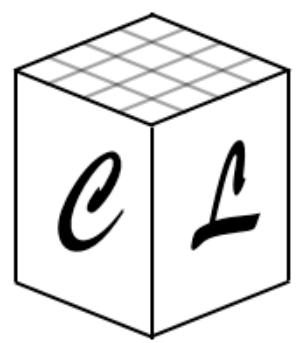
Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$



More intermediate  
kernels

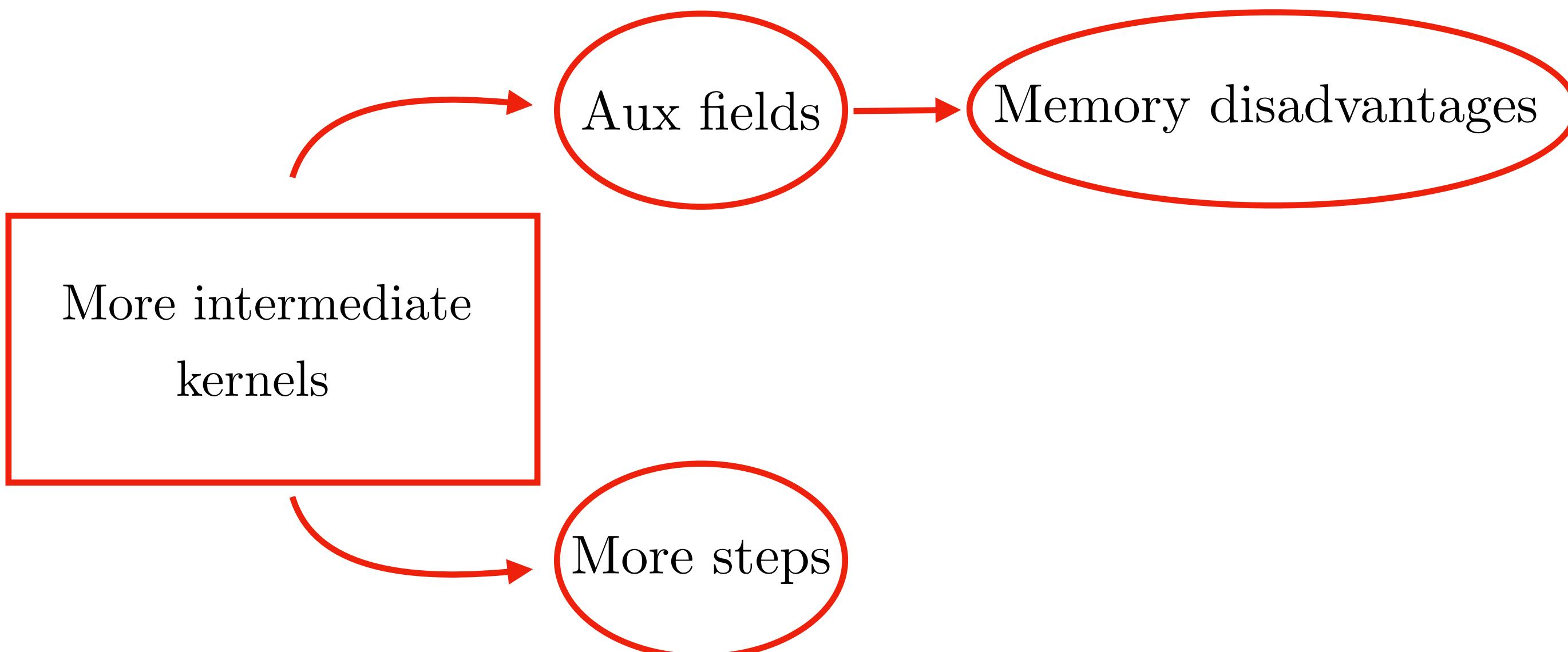


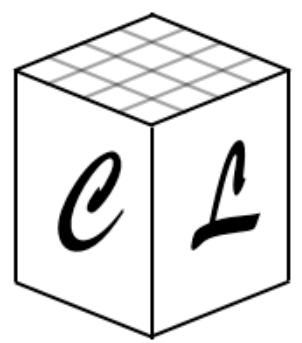
# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$



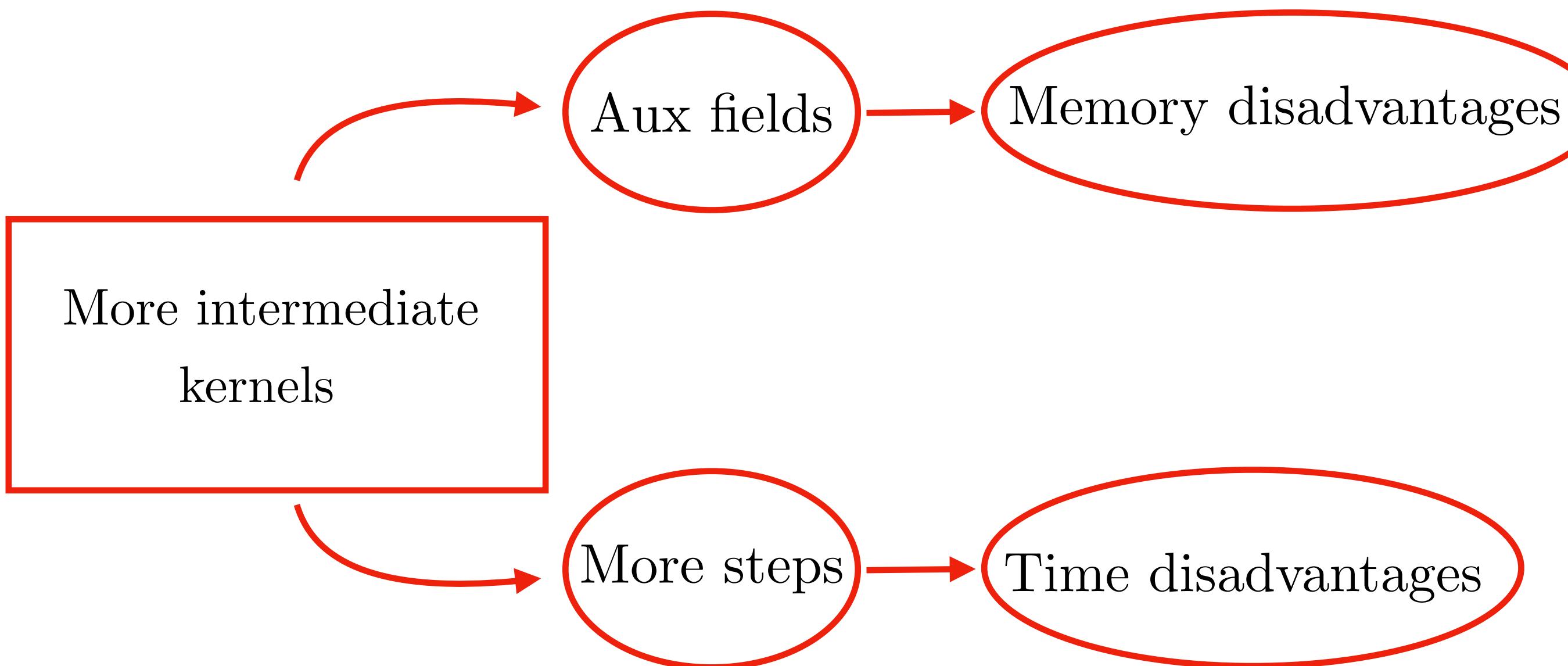


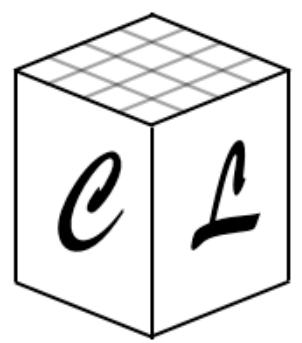
# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$



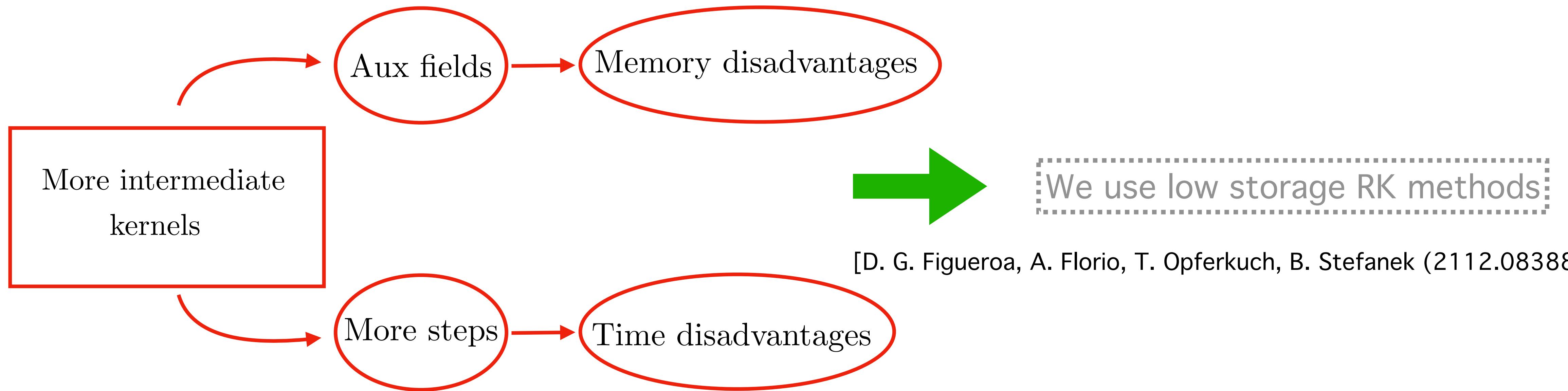


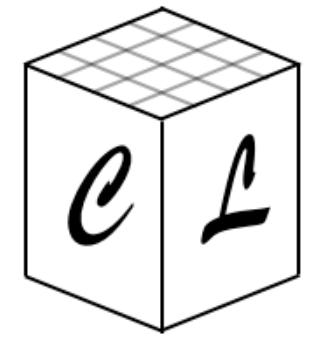
# Explicit-in-time integrator

Axion-Inflation using RK2

$$\begin{aligned}\phi(t_{n+1}) &= \phi(t_n) + \left[ (a^{(1)})^{-3} \tilde{\pi}_\phi^{(1)} + (a^{(2)})^{-3} \tilde{\pi}_\phi^{(2)} \right] \delta t / 2 \\ A_i(t_{n+1}) &= A_i(t_n) + \left[ (a^{(1)})^{-1} \tilde{E}_i^{(1)} + (a^{(2)})^{-1} \tilde{E}_i^{(2)} \right] \delta t / 2 \\ a(t_{n+1}) &= a(t_n) + (\pi_a^{(1)} + \pi_a^{(2)}) \delta t / 2\end{aligned}$$

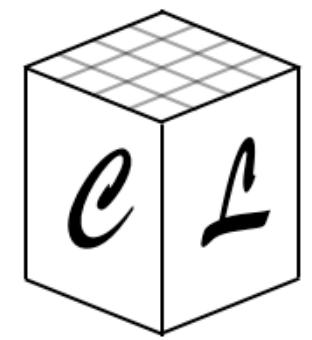
$$\begin{aligned}\tilde{\pi}_\phi(t_{n+1}) &= \tilde{\pi}_\phi(t_n) + \frac{1}{2} (\mathcal{K}_\phi^{(1)} + \mathcal{K}_\phi^{(2)}) \delta t \\ \tilde{E}_i(t_{n+1}) &= \tilde{E}_i(t_n) + \frac{1}{2} (\mathcal{K}_A^{(1)} + \mathcal{K}_A^{(2)}) \delta t \\ \pi_a(t_{n+1}) &= \pi_a(t_n) + \frac{1}{2} (\mathcal{K}_a^{(1)} + \mathcal{K}_a^{(2)}) \delta t\end{aligned}$$





# Explicit-in-time integrator

## Axion-Inflation using RK2



# Explicit-in-time integrator

## Axion-Inflation using RK2

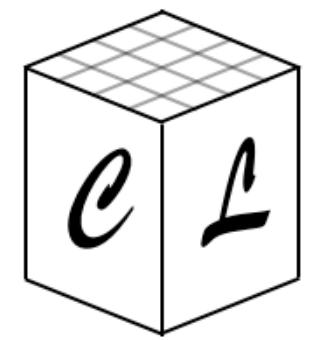
### Dynamical equations

$$\mathcal{K}_\phi^L = a \sum_i \Delta_i^- \Delta_i^+ \phi - a^3 m^2 \phi + \frac{1}{2a\Lambda} \sum_i \tilde{E}_i^{(2)} B_i^{(4)}$$

$$\mathcal{K}_A^L = -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right)$$

$$+ \frac{1}{4a\Lambda} \sum_{\pm} \sum_{j,k} \epsilon_{ijk} \left\{ \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_{+i} + \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right] \right\}$$

$$\mathcal{K}_a^L = -\frac{a}{6m_{pl}^2} (\rho_L + 3p_L)$$



# Explicit-in-time integrator

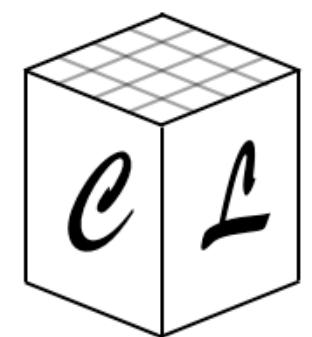
## Axion-Inflation using RK2

### Dynamical equations

$$\begin{aligned}\mathcal{K}_\phi^L &= a \sum_i \Delta_i^- \Delta_i^+ \phi - a^3 m^2 \phi + \frac{1}{2a\Lambda} \sum_i \tilde{E}_i^{(2)} B_i^{(4)} \\ \mathcal{K}_A^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right) \\ &\quad + \frac{1}{4a\Lambda} \sum_{\pm} \sum_{j,k} \epsilon_{ijk} \left\{ \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_{+i} + \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_i \right\} \\ \mathcal{K}_a^L &= -\frac{a}{6m_{pl}^2} (\rho_L + 3p_L)\end{aligned}$$

### Constraints

$$\begin{aligned}\sum_i \Delta_i^- \tilde{E}_i &= -\frac{1}{2\Lambda} \sum_{\pm} \sum_i (\Delta_i^\pm \phi) B_{i,\pm i}^{(4)} \\ \pi_a^2 &= \frac{a^2}{3m_{pl}^2} \rho_L\end{aligned}$$



# Explicit-in-time integrator

## Axion-Inflation using RK2

No temporal semi-sums

Dynamical equations

$$\mathcal{K}_\phi^L = a \sum_i \Delta_i^- \Delta_i^+ \phi - a^3 m^2 \phi + \frac{1}{2a\Lambda} \sum_i \tilde{E}_i^{(2)} B_i^{(4)}$$

$$\mathcal{K}_A^L = -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right)$$

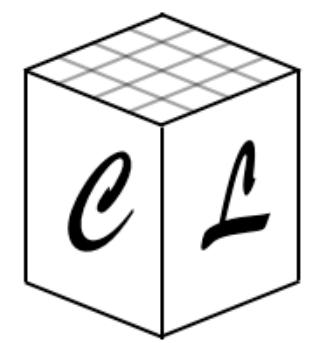
$$+ \frac{1}{4a\Lambda} \sum_{\pm} \sum_{j,k} \epsilon_{ijk} \left\{ \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_{+i} + \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_i \right\}$$

$$\mathcal{K}_a^L = -\frac{a}{6m_{pl}^2} (\rho_L + 3p_L)$$

Constraints

$$\sum_i \Delta_i^- \tilde{E}_i = -\frac{1}{2\Lambda} \sum_{\pm} \sum_i (\Delta_i^\pm \phi) B_{i,\pm i}^{(4)}$$

$$\pi_a^2 = \frac{a^2}{3m_{pl}^2} \rho_L$$



# Explicit-in-time integrator

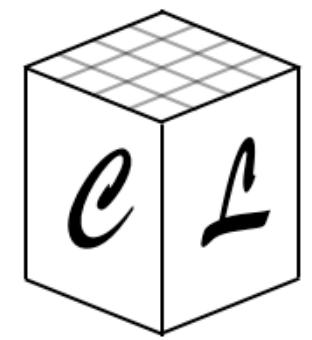
## Axion-Inflation using RK2

### Dynamical equations

$$\begin{aligned}\mathcal{K}_\phi^L &= a \sum_i \Delta_i^- \Delta_i^+ \phi - a^3 m^2 \phi + \frac{1}{2a\Lambda} \sum_i \tilde{E}_i^{(2)} B_i^{(4)} \\ \mathcal{K}_A^L &= -\frac{1}{a} \sum_{j,k} \epsilon_{ijk} \Delta_j^- B_k - \frac{1}{2a^3 \Lambda} \left( \tilde{\pi}_\phi B_i^{(4)} + \tilde{\pi}_{\phi,+i} B_{i,+i}^{(4)} \right) \\ &\quad + \frac{1}{4a\Lambda} \sum_{\pm} \sum_{j,k} \epsilon_{ijk} \left\{ \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_{+i} + \left[ (\Delta_j^\pm \phi) \tilde{E}_{k,\pm j}^{(2)} \right]_i \right\} \\ \mathcal{K}_a^L &= -\frac{a}{6m_{pl}^2} (\rho_L + 3p_L)\end{aligned}$$

### Constraints

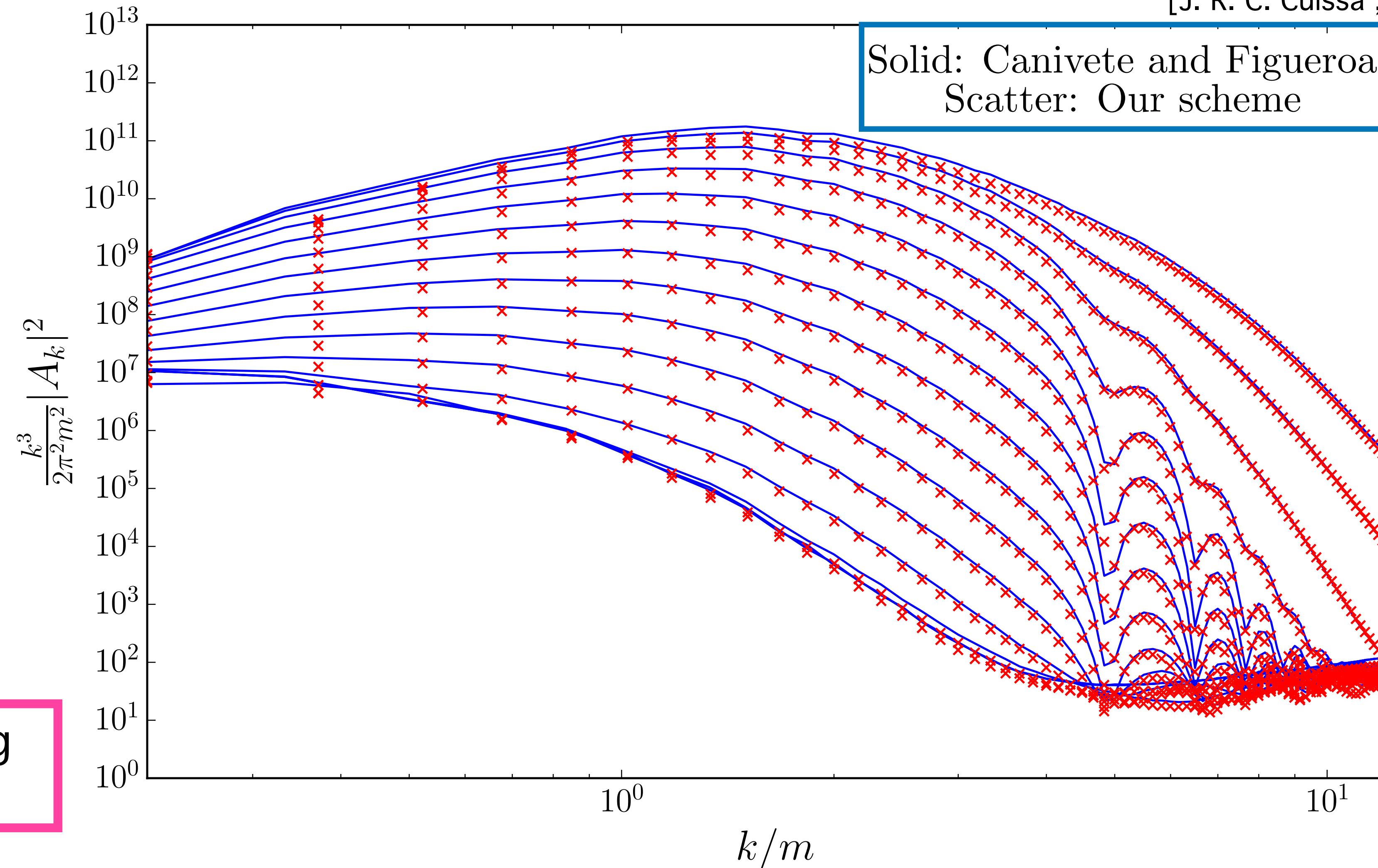
$$\begin{aligned}\sum_i \Delta_i^- \tilde{E}_i &= -\frac{1}{2\Lambda} \sum_{\pm} \sum_i (\Delta_i^\pm \phi) B_{i,\pm i}^{(4)} \\ \pi_a^2 &= \frac{a^2}{3m_{pl}^2} \rho_L\end{aligned}$$



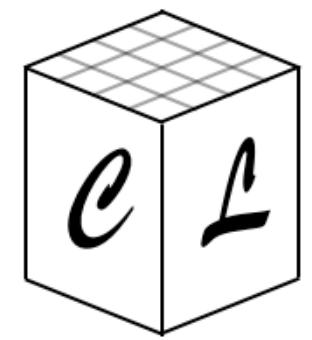
# Explicit-in-time integrator

## Axion-Inflation using RK2: validation of the scheme

[J. R. C. Cuissa , D. G. Figueroa (1812.03132)]



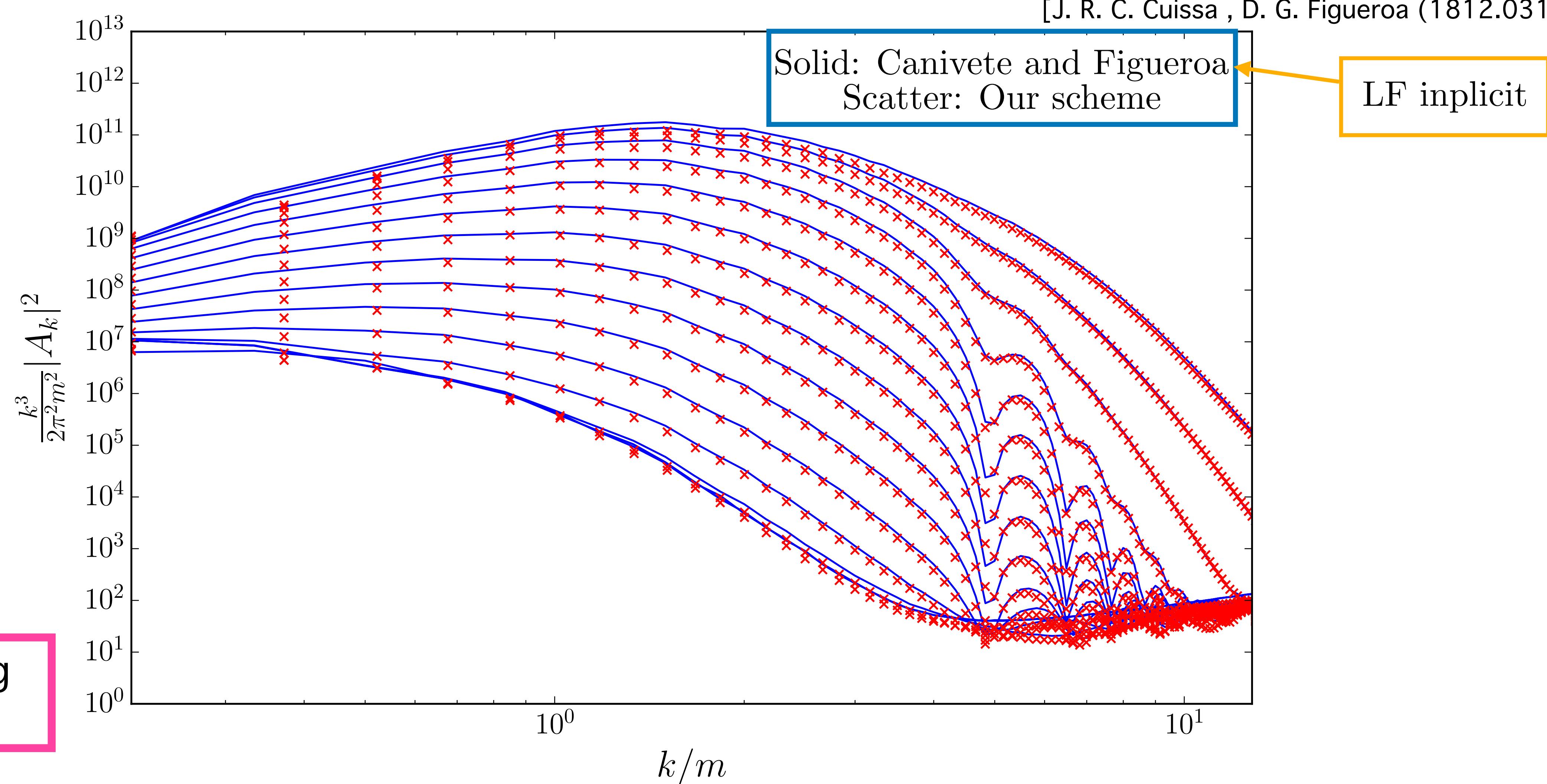
Preheating  
example

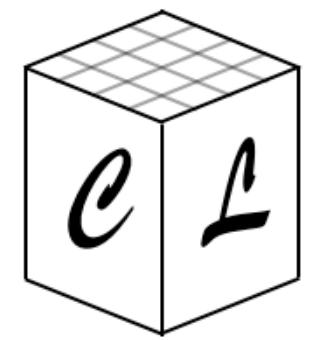


# Explicit-in-time integrator

## Axion-Inflation using RK2: validation of the scheme

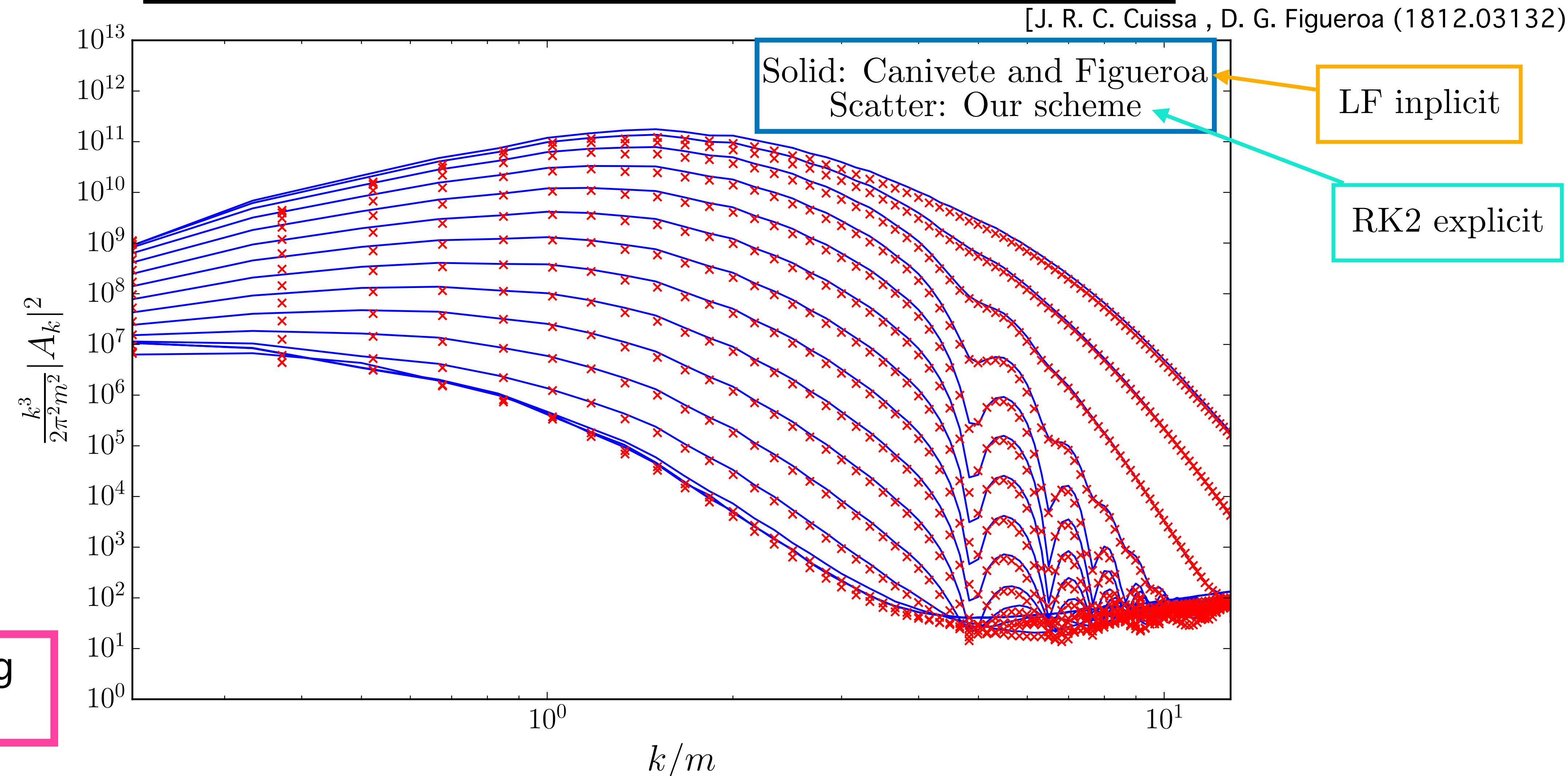
[J. R. C. Cuissa , D. G. Figueroa (1812.03132)]

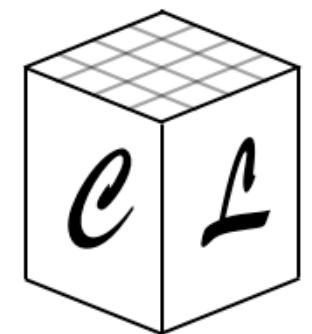




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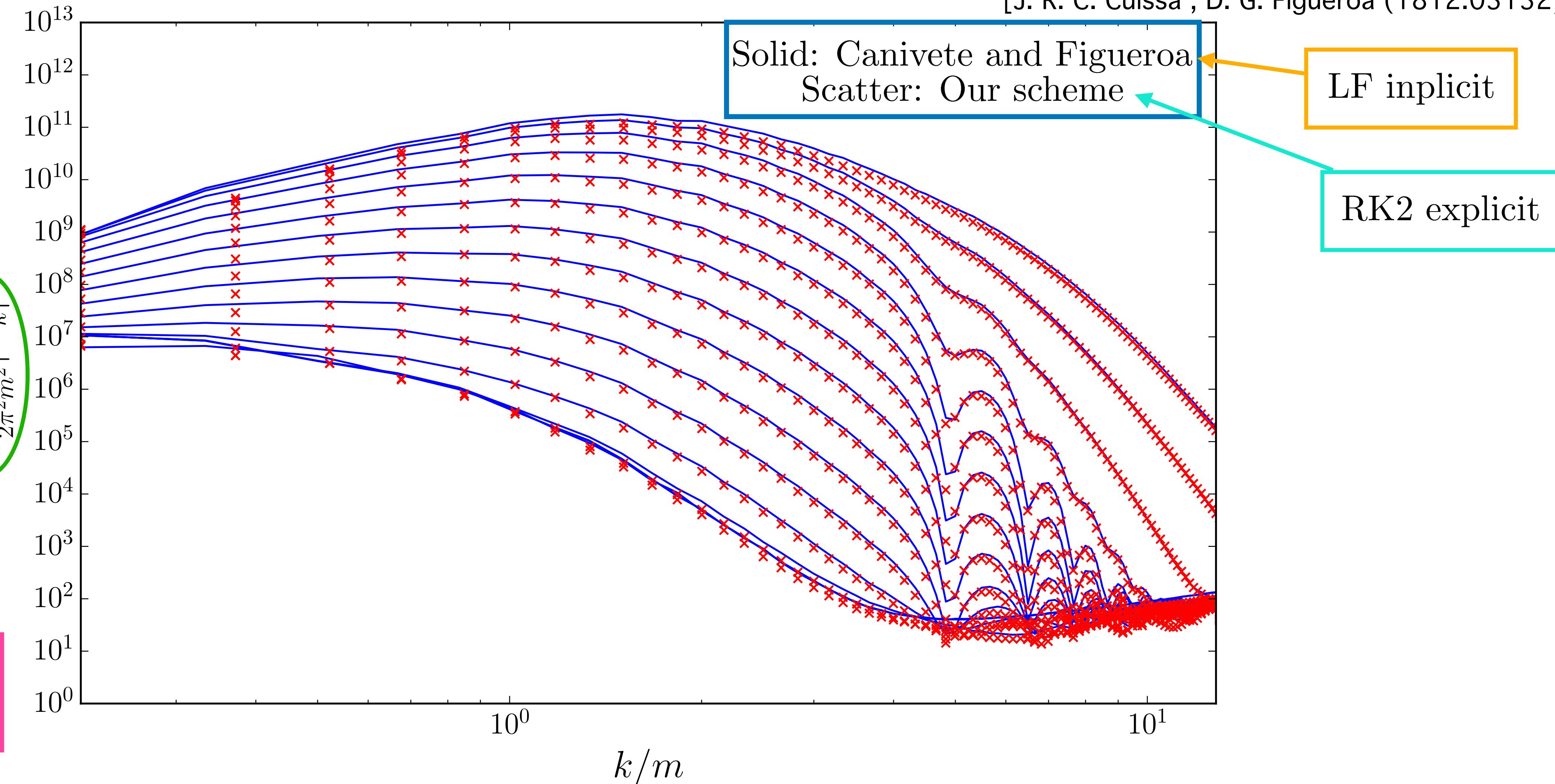
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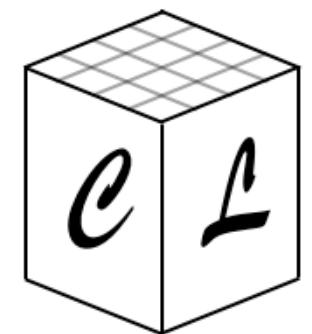
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Spectrum of  $A$

$$\frac{k^3}{2\pi^2 m^2} |A_k|^2$$

Preheating example





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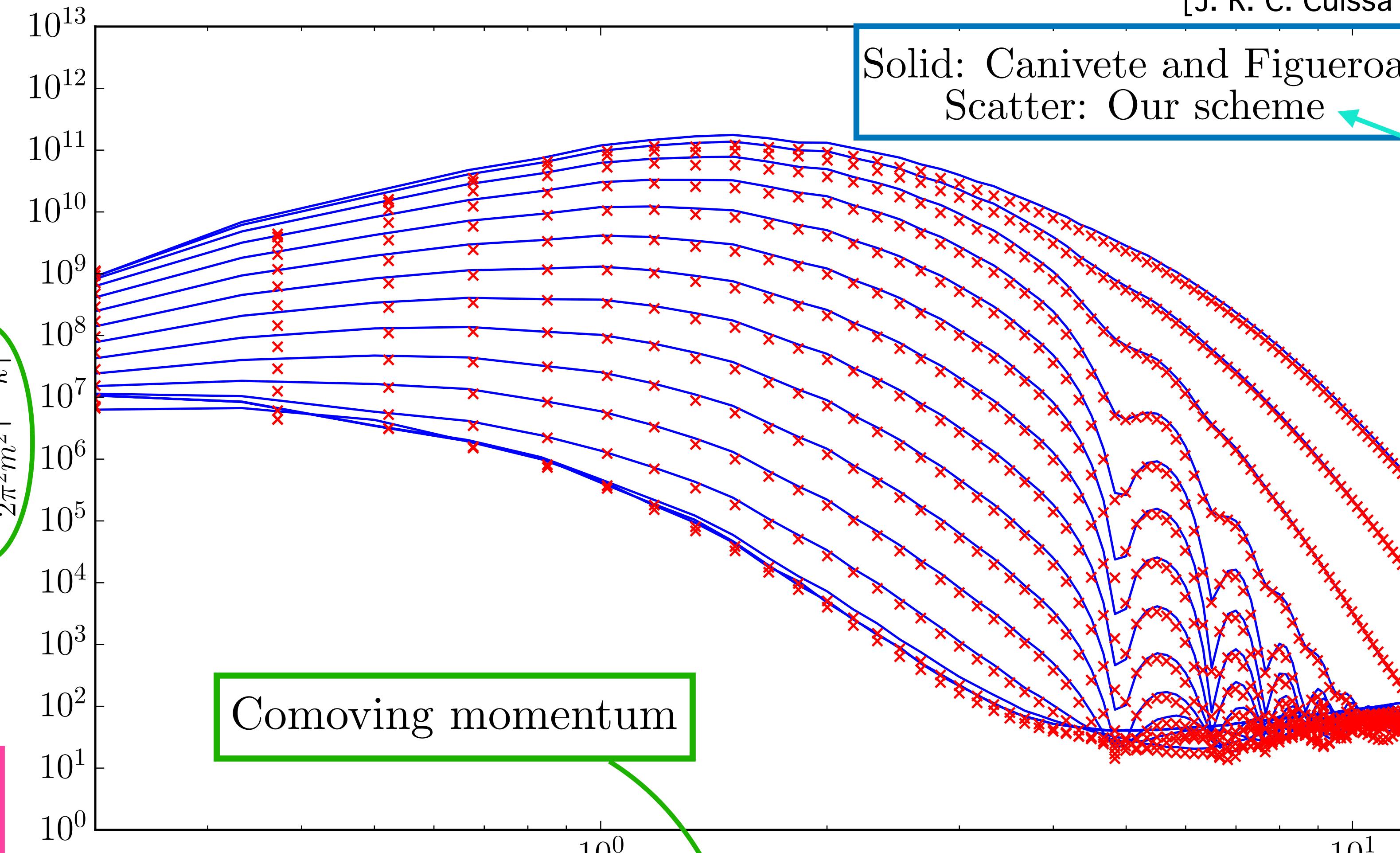
Comoving momentum

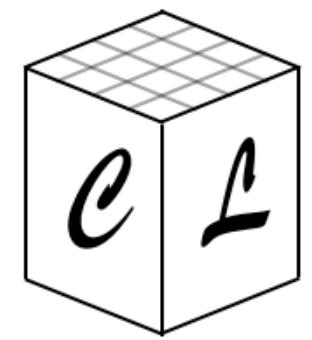
$$k/m$$

Solid: Canivete and Figueroa  
Scatter: Our scheme

LF implicit

RK2 explicit

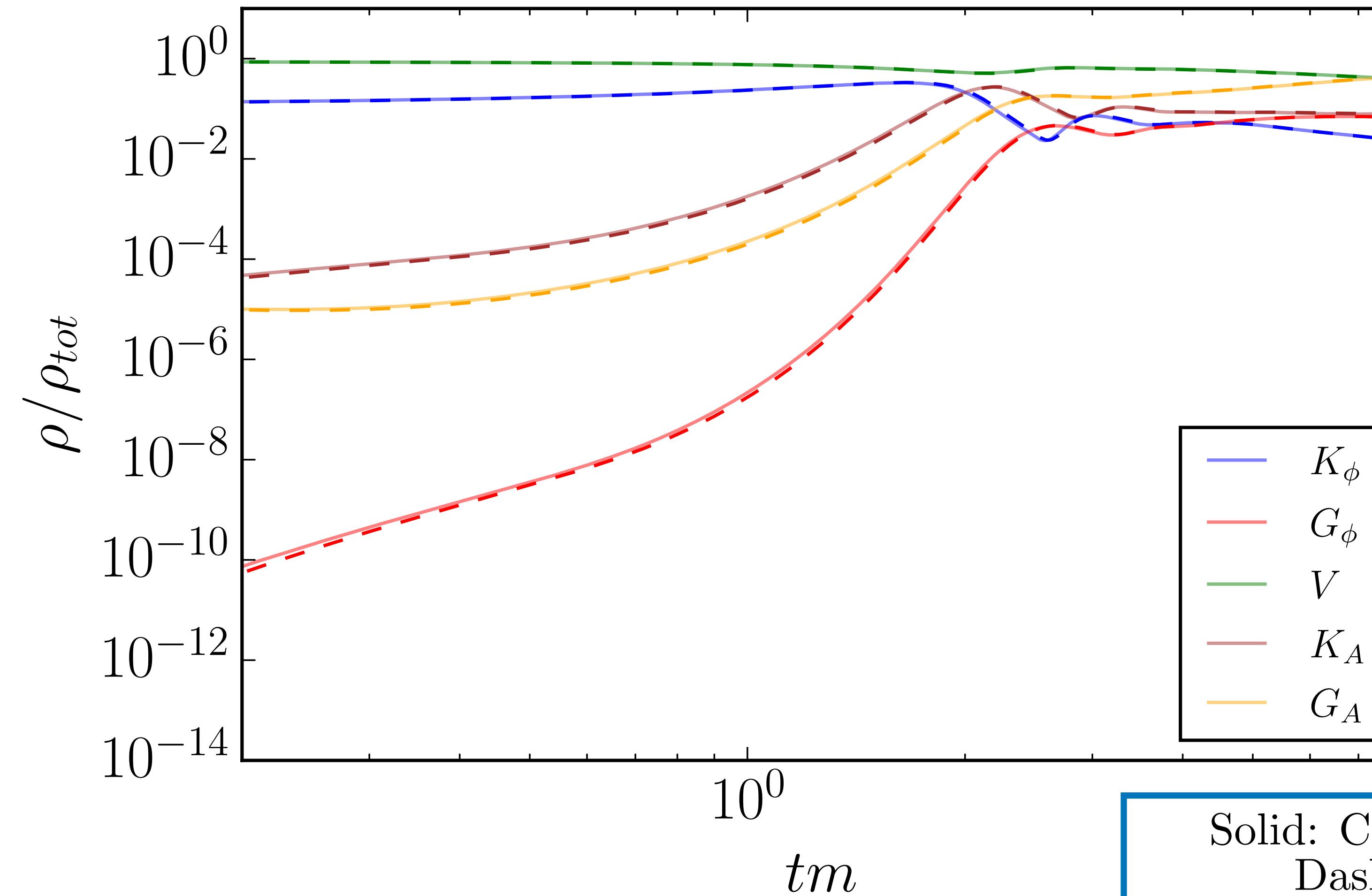




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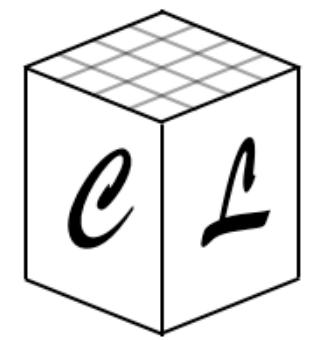
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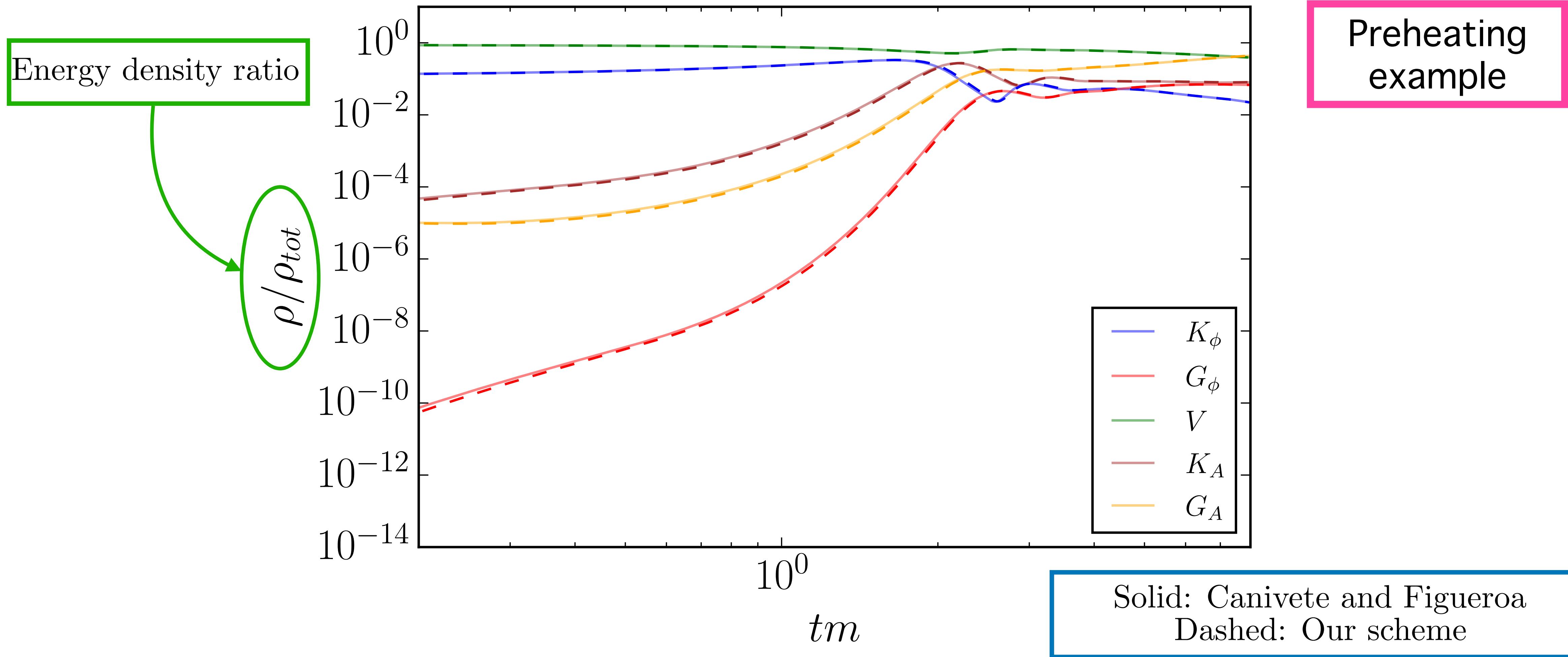
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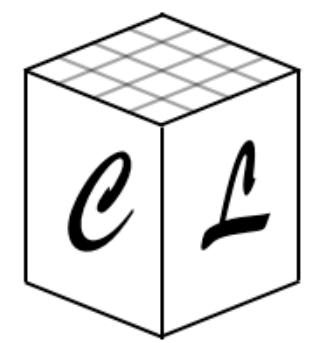


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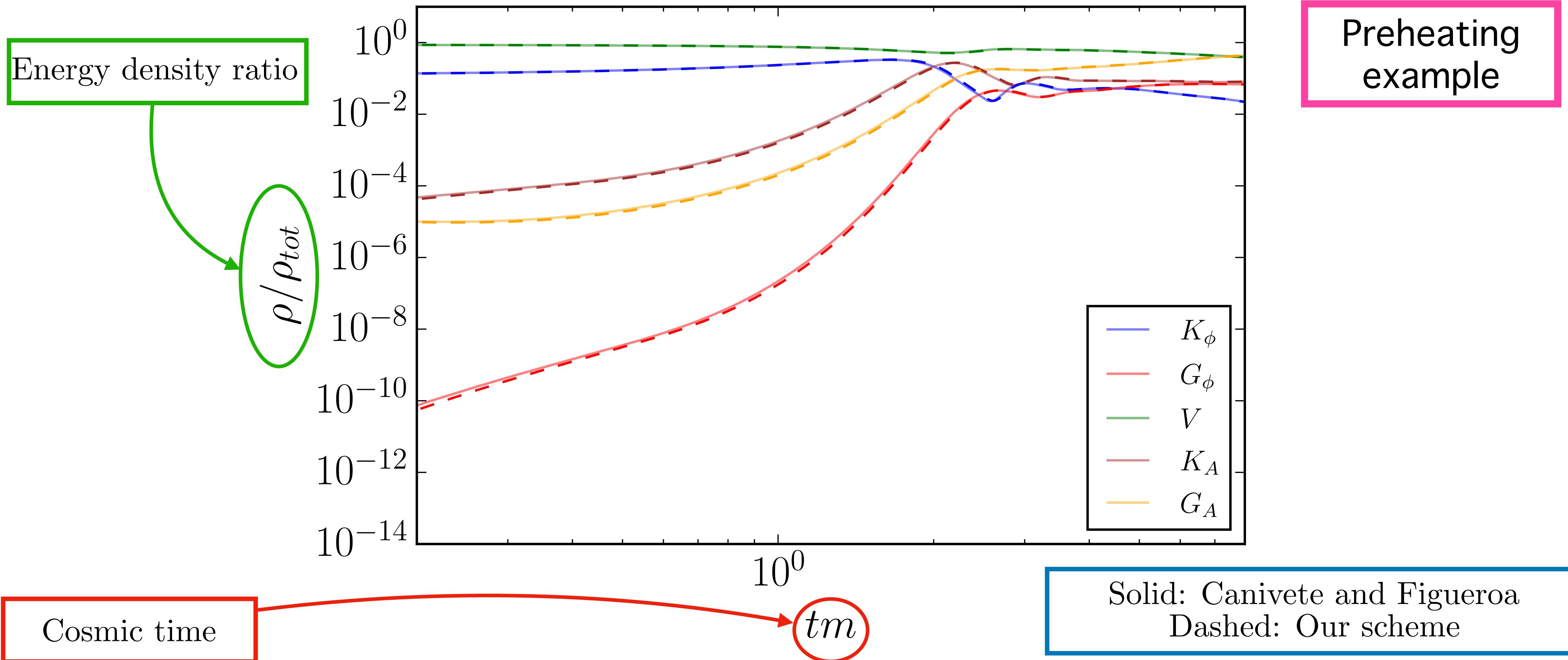


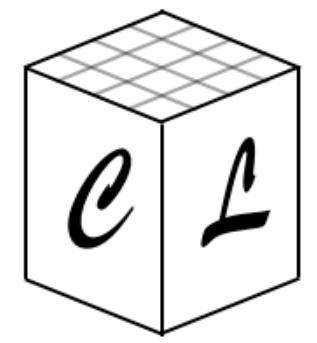


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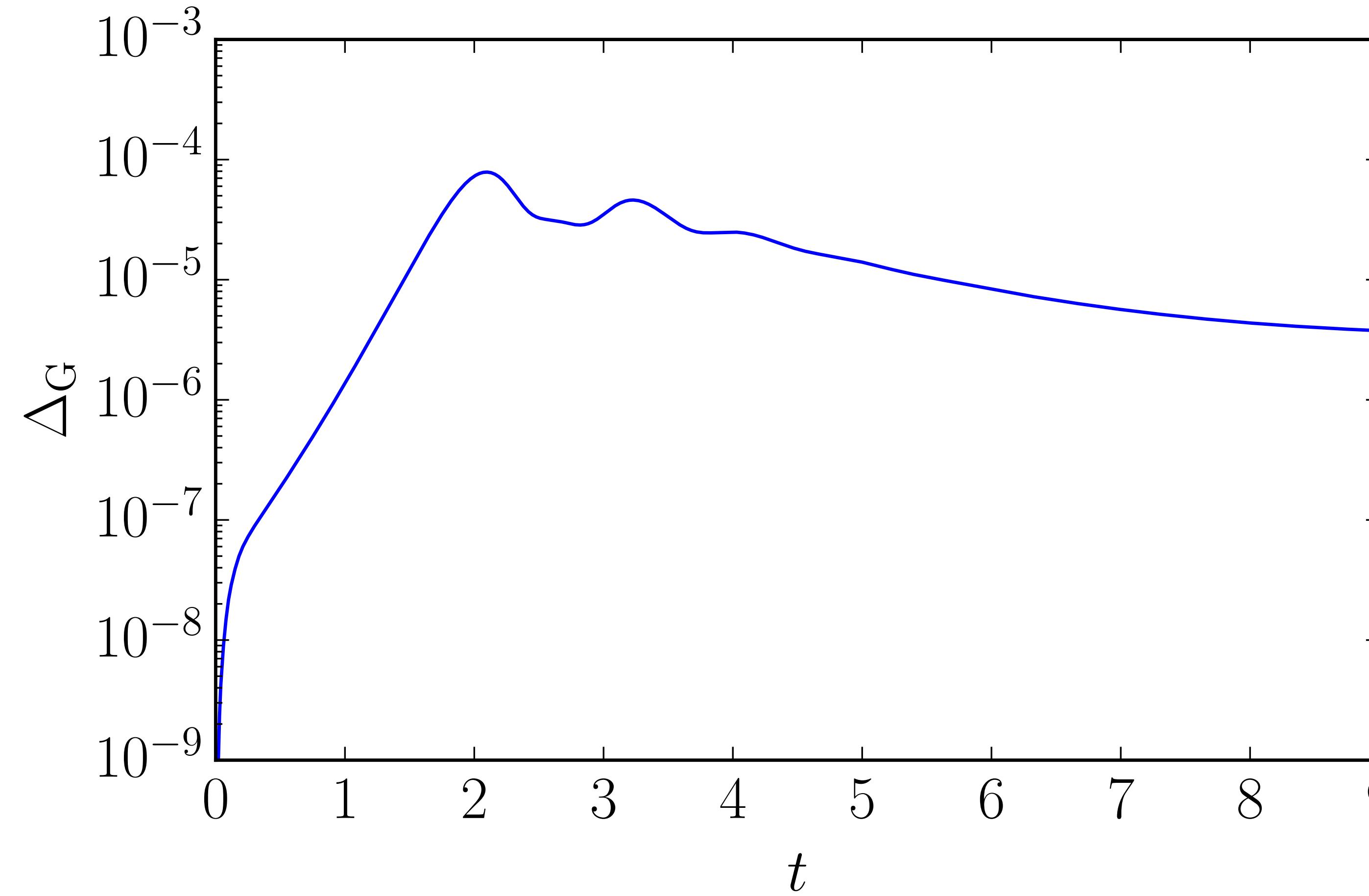
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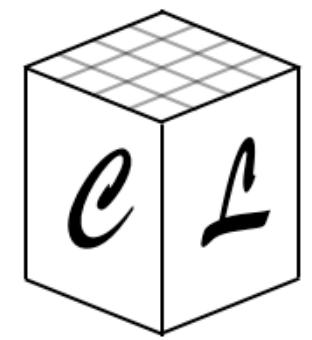




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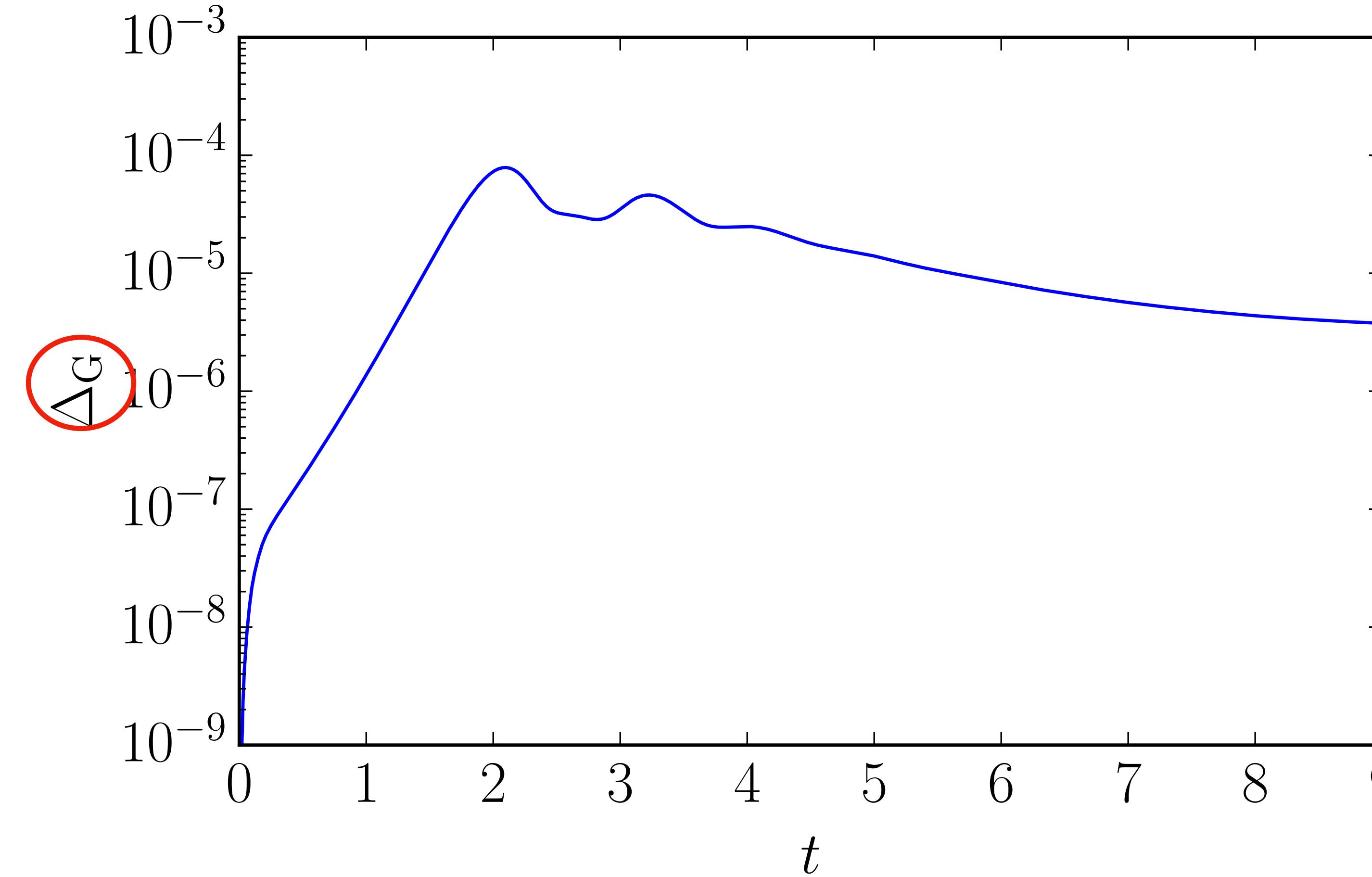


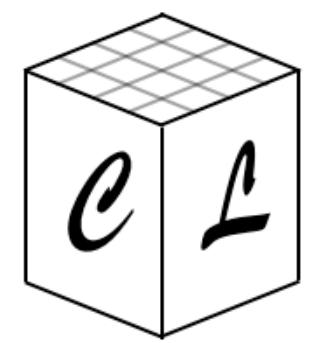


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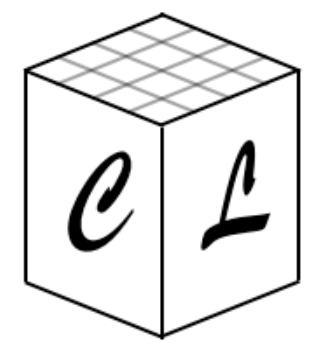
Gauss constraint  
observable





# Initial Conditions in the Linear Regime

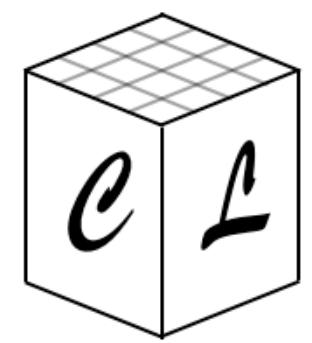
$$\dot{\vec{E}} = -\frac{1}{a}\vec{\nabla} \times \vec{B} - \frac{1}{a^3\Lambda}\tilde{\pi}_\phi \vec{B}$$



# Initial Conditions in the Linear Regime

$$\dot{\tilde{\vec{E}}} = -\frac{1}{a}\vec{\nabla} \times \vec{B} - \frac{1}{a^3\Lambda}\tilde{\pi}_\phi \vec{B}$$

Helicity basis → Conformal time

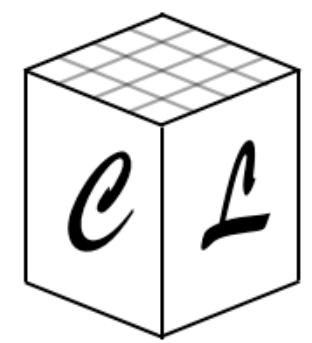


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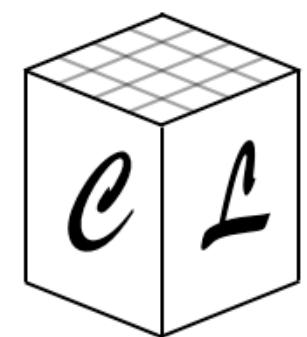
Helicity basis



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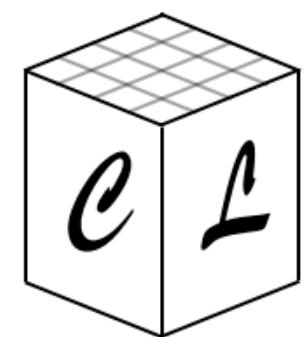
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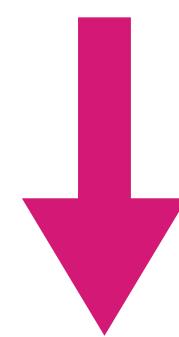
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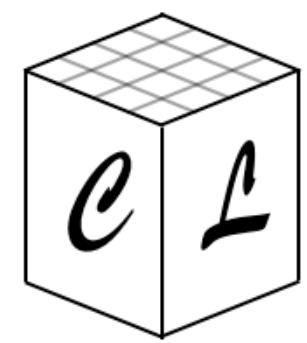
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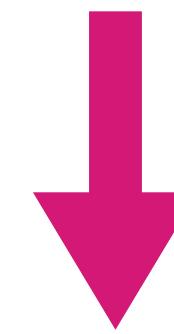
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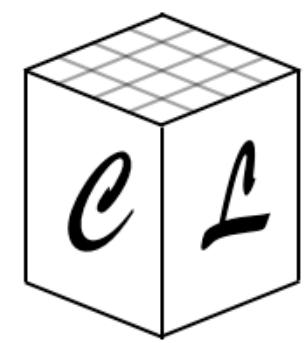
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Deep inside Hubble  $k \gg aH$



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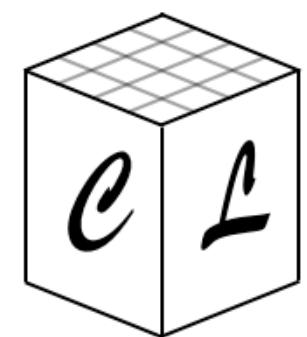
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Deep inside Hubble  $k \gg aH$

$$\left( \frac{\partial^2}{\partial\tau^2} + k^2 \right) A_+(k, \tau) \simeq 0 \quad \left( \frac{\partial^2}{\partial\tau^2} + k^2 + \frac{2k\xi}{\tau} \right) A_+(k, \tau) = 0$$

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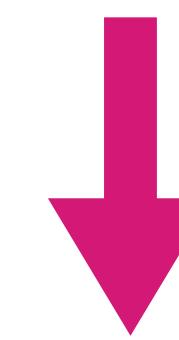
Bunch-Davies solution

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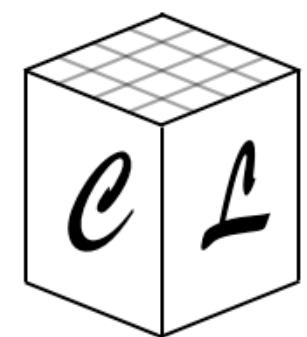
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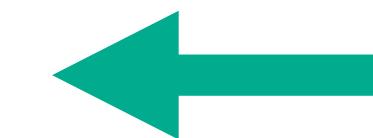
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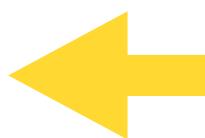
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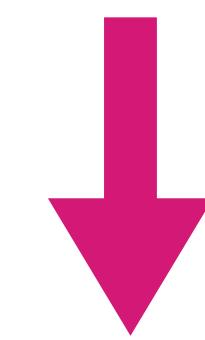
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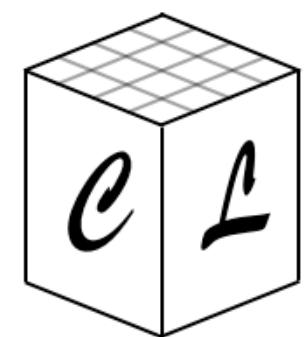
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$$\dot{\vec{E}} = -\frac{1}{a}\vec{\nabla} \times \vec{B} - \frac{1}{a^3\Lambda}\tilde{\pi}_\phi \vec{B}$$

Helicity basis



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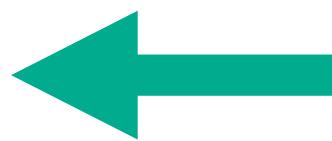
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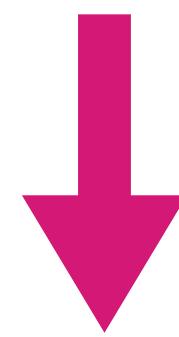
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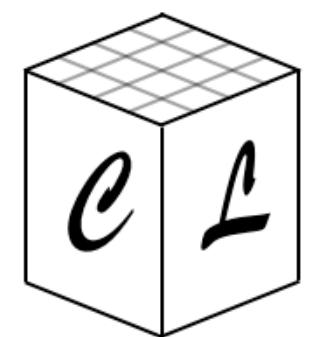
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Cosmic time

$\tau \simeq -1/aH$



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Helicity basis

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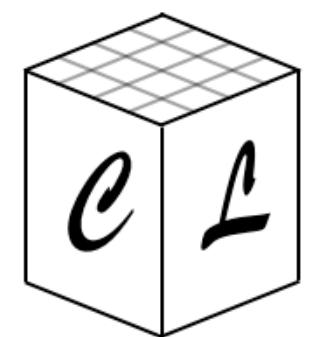
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$$A_+(k, t) \simeq \frac{1}{\sqrt{2k}} e^{ik/a(t)H(t)}$$



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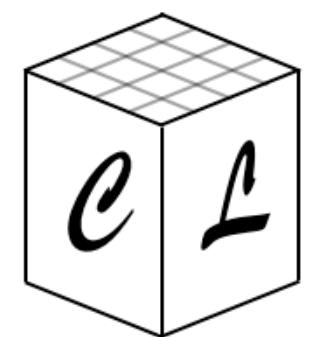
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Time derivative





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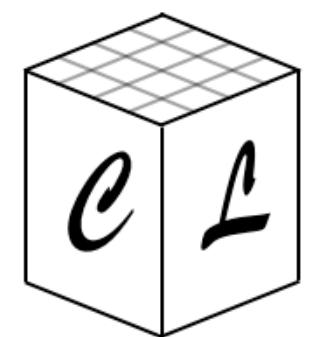
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$$E_+(k, t) \simeq \frac{i}{a} \sqrt{\frac{k}{2}} e^{ik/a(t)H(t)}$$



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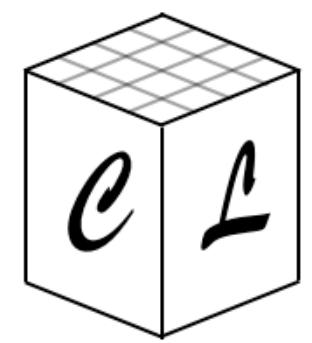
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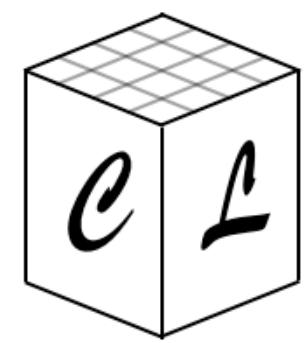
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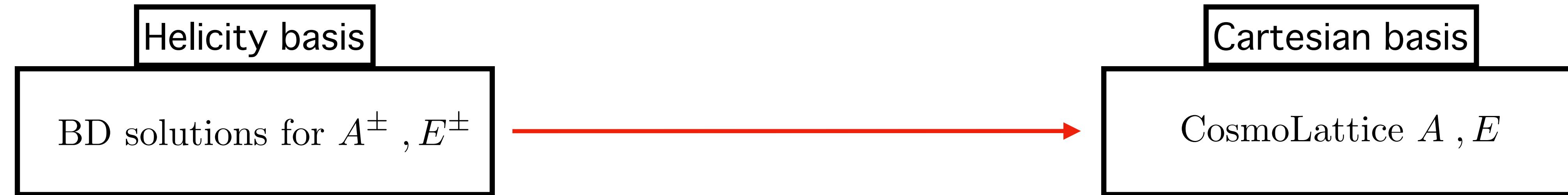
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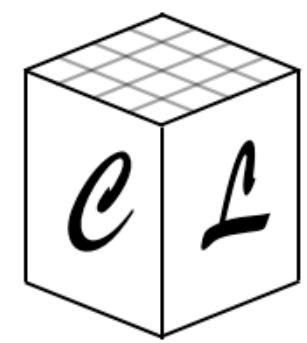
Helicity basis

BD solutions for  $A^\pm, E^\pm$

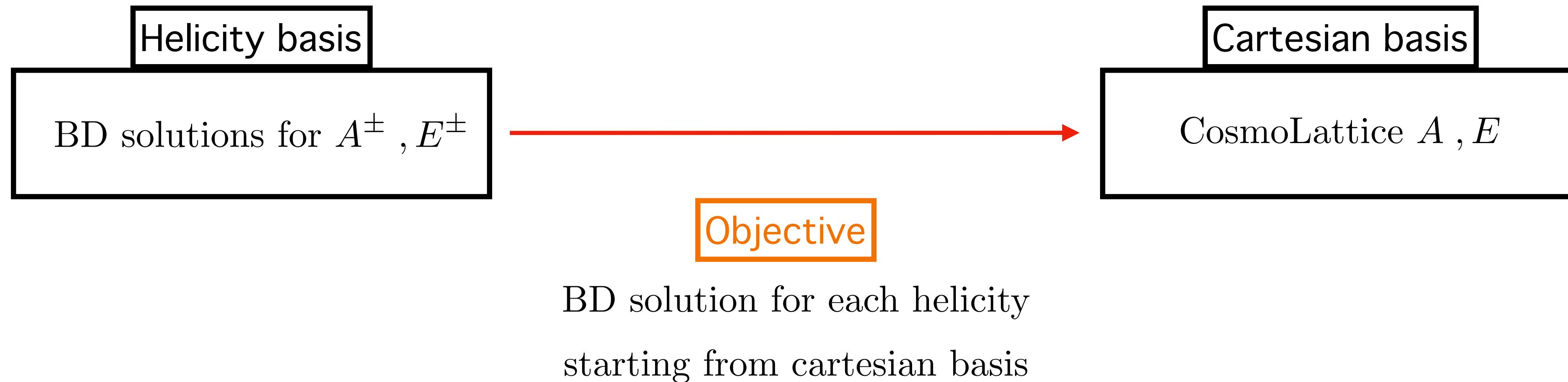


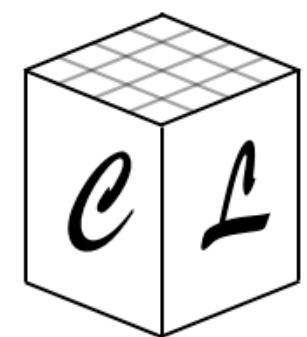
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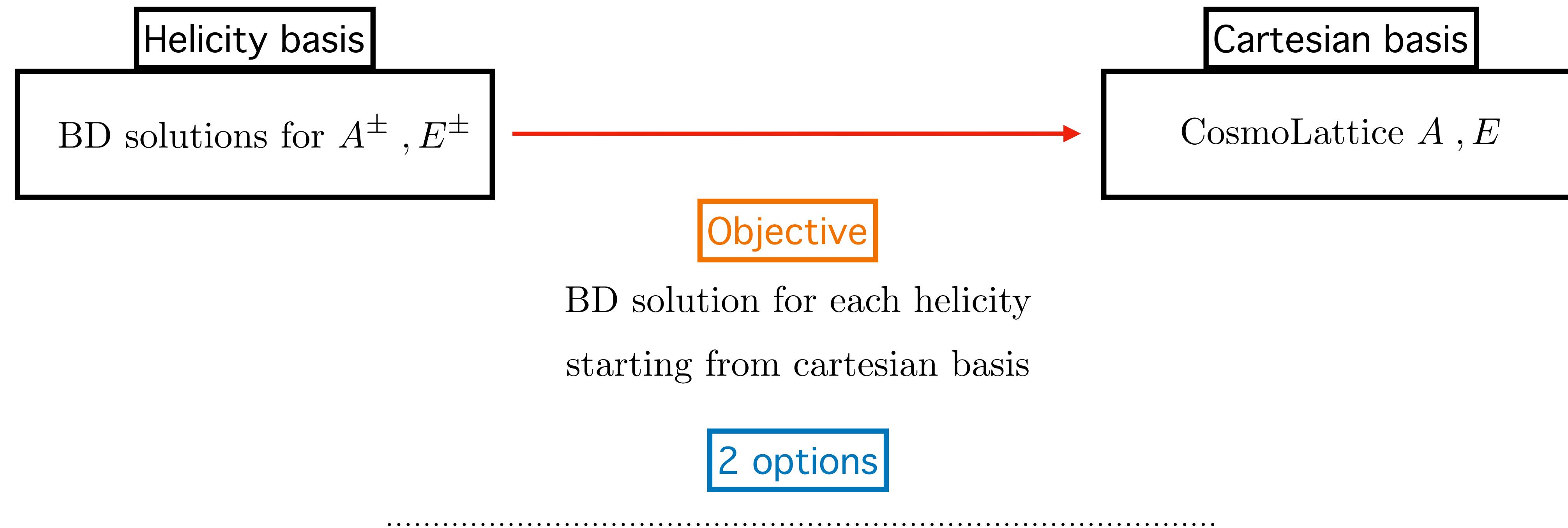


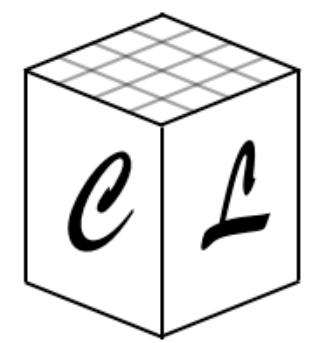
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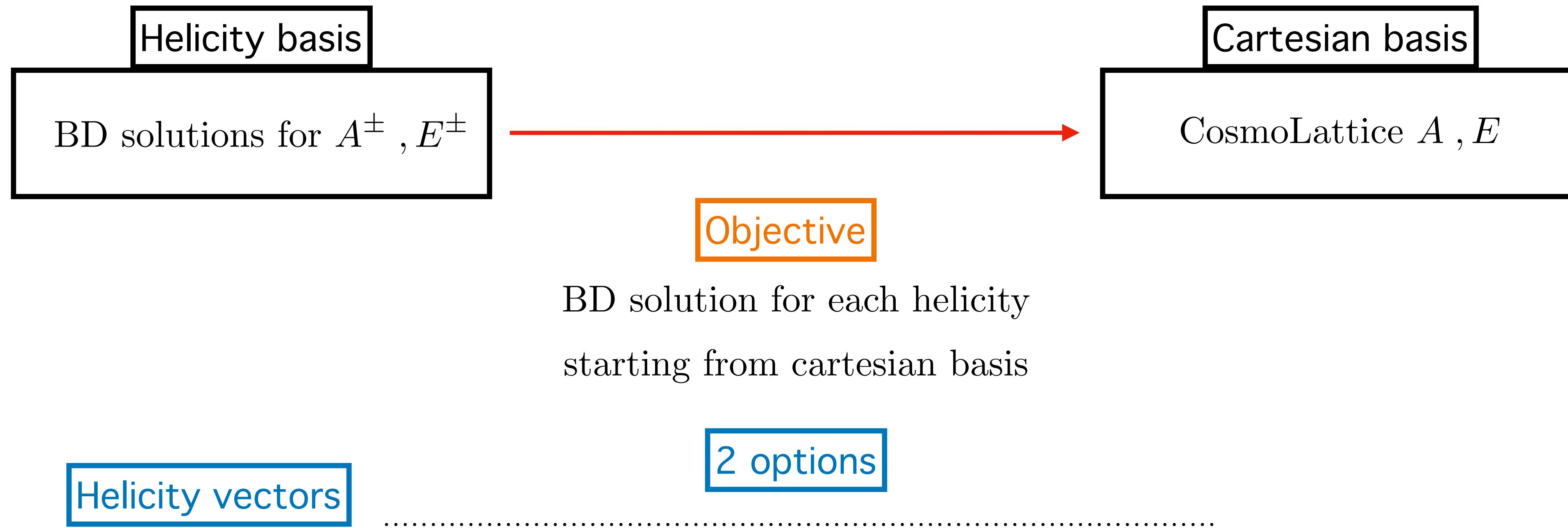


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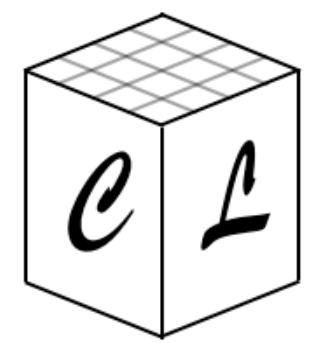


# Initial Conditions in the Linear Regime

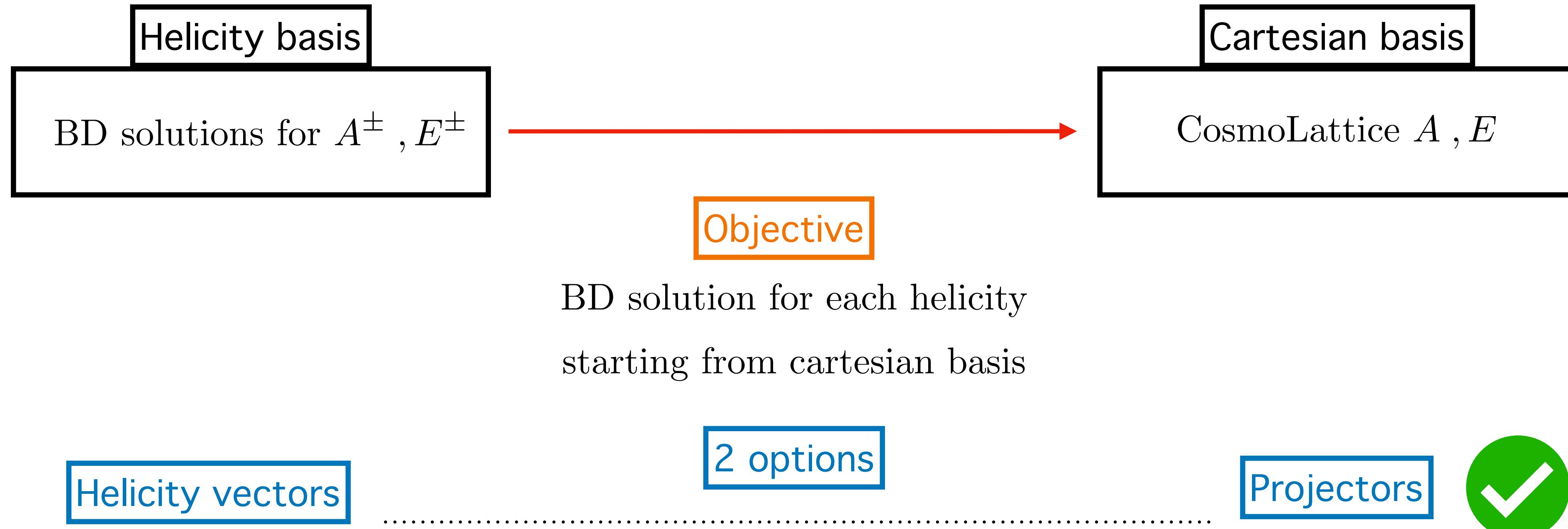


$$k_i \varepsilon_i^\pm(\hat{k}) = 0 , \quad \epsilon_{ijk} k_j \varepsilon_i^\pm(\hat{k}) = \mp i k \varepsilon_i^\pm(\hat{k}) ,$$

$$\varepsilon_i^\pm(\hat{k})^* = \varepsilon_i^\pm(-\hat{k}) , \quad \varepsilon_i^\lambda(\hat{k}) \varepsilon_i^{\lambda'}(-\hat{k}) = \delta_{\lambda\lambda'}$$



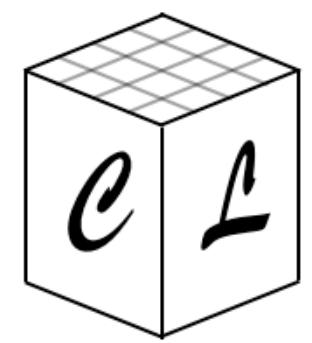
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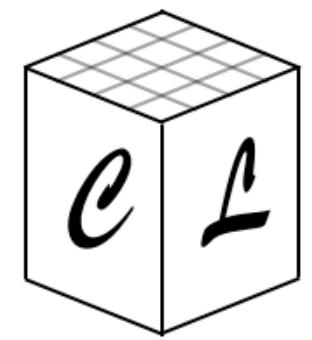
$$\varepsilon_i^\pm(\hat{k})^* = \varepsilon_i^\pm(-\hat{k}) , \quad \varepsilon_i^\lambda(\hat{k}) \varepsilon_i^{\lambda'}(-\hat{k}) = \delta_{\lambda\lambda'}$$

$$A_i^\pm = P_{ij}^\pm A_j$$



# Initial Conditions in the Linear Regime

How to build the  
Helicity Projector?

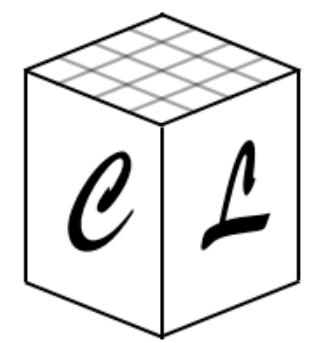


# Initial Conditions in the Linear Regime

Helicity operator

$$\Sigma_{ij}^{\pm}(k) = \pm \frac{i}{k} \epsilon_{ijk} k_k$$

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# Initial Conditions in the Linear Regime

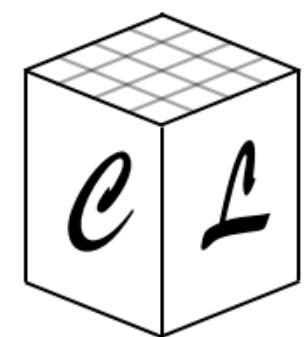
Helicity operator

$$\Sigma_{ij}^{\pm}(k) = \pm \frac{i}{k} \epsilon_{ijk} k_k$$

How to build the  
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Transverse projector

$$(\Sigma^{\pm})_{ij}^2(k) = \delta_{ij} - \frac{k_i k_j}{k^2}$$



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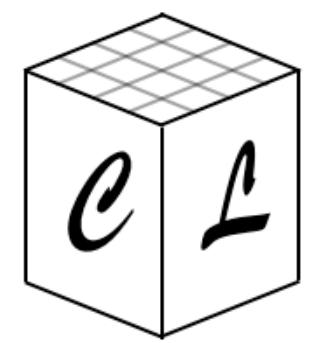
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2 eigenvalues: 1 and -1

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# Initial Conditions in the Linear Regime

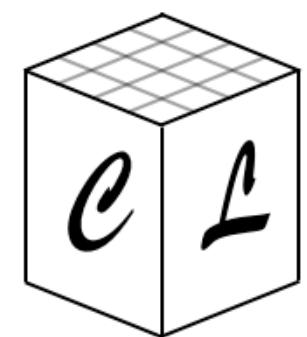
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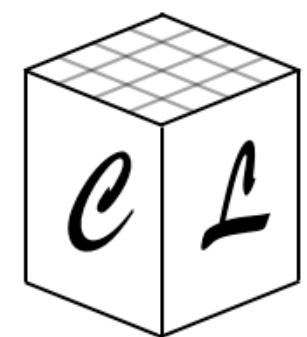


Helicity projector

$$P_{ij}^{\pm} = \frac{1}{2} (\Sigma_{ij}^{\pm} + (\Sigma^{\pm})_{ij}^2)$$

Transverse projector

$$(\Sigma^{\pm})_{ij}^2(k) = \delta_{ij} - \frac{k_i k_j}{k^2}$$



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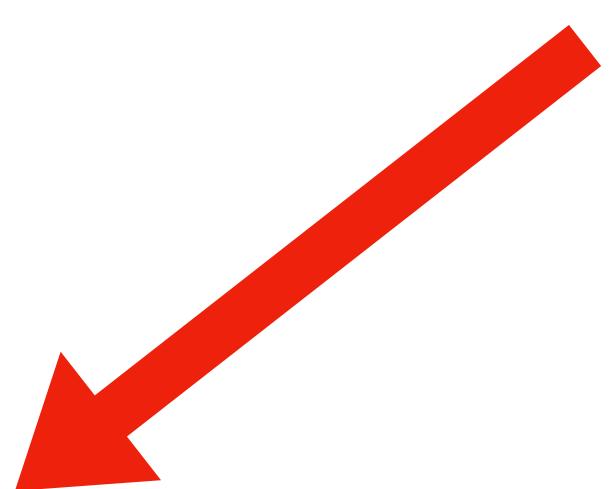


Helicity projector

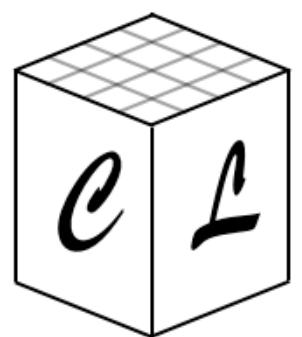
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Transverse projector

$$(\Sigma^{\pm})_{ij}^2(k) = \delta_{ij} - \frac{k_i k_j}{k^2}$$



$$P_{ij}^{\pm} = \frac{1}{2} \left( \delta_{ij} - \frac{k_i k_j}{k^2} \pm \frac{i}{k} \epsilon_{ijk} k_k \right)$$



# Initial Conditions in the Linear Regime

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How to build the  
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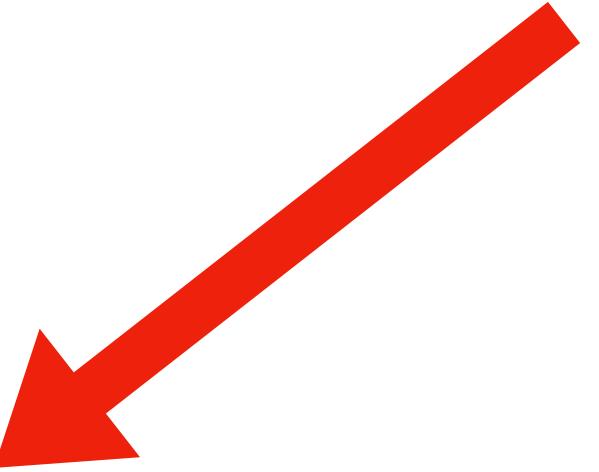


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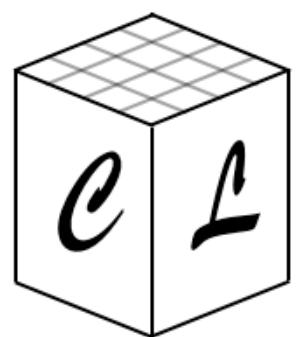
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$$A_i^{\pm} = P_{ij}^{\pm} A_j$$
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# Initial Conditions in the Linear Regime

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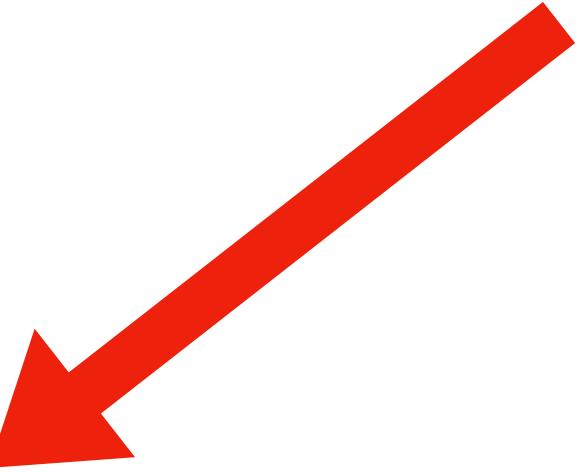


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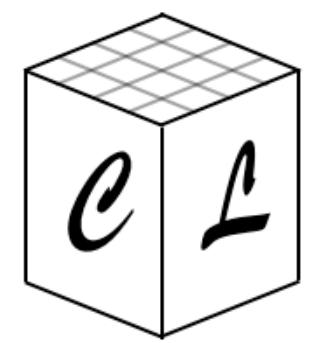
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Gauss

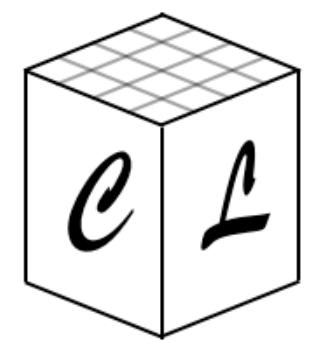
$$\vec{\nabla} \cdot \vec{E} = 0$$



# Initial Conditions in the Linear Regime

Two IC options





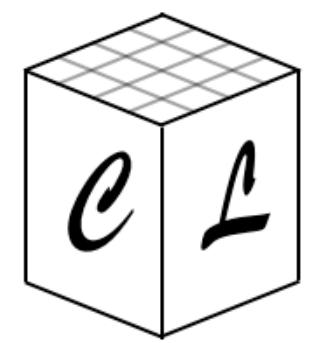
# Initial Conditions in the Linear Regime

Two IC options

One option

Only project the + helicity states





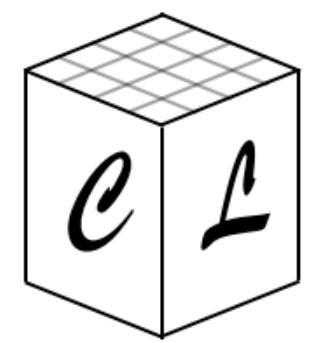
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Why?



# Initial Conditions in the Linear Regime

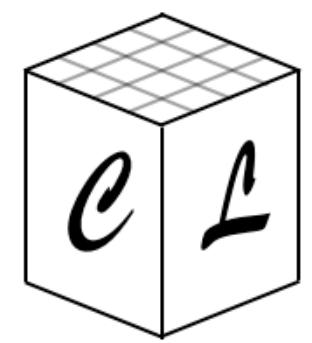
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Why?

$A^+$  is exponentially enhanced



# Initial Conditions in the Linear Regime

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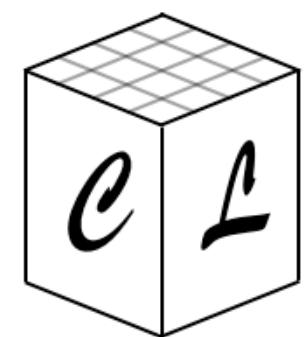
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Loss of information!



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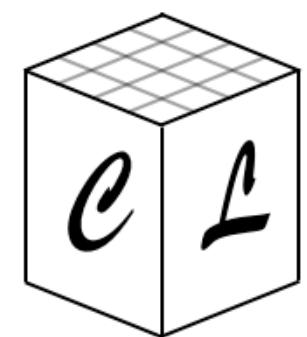


Two IC options

Our option

Project both states + and -





# Initial Conditions in the Linear Regime

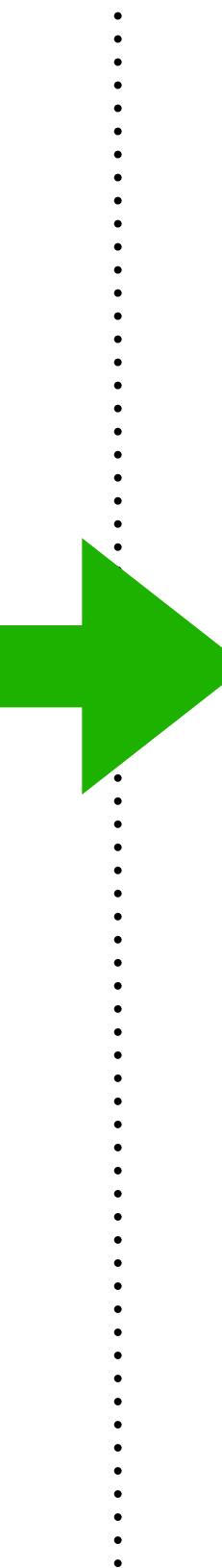
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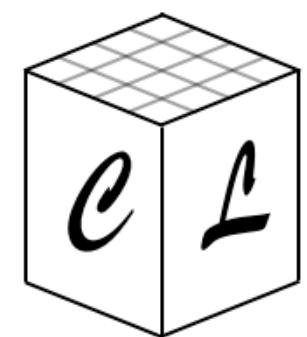
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# Initial Conditions in the Linear Regime

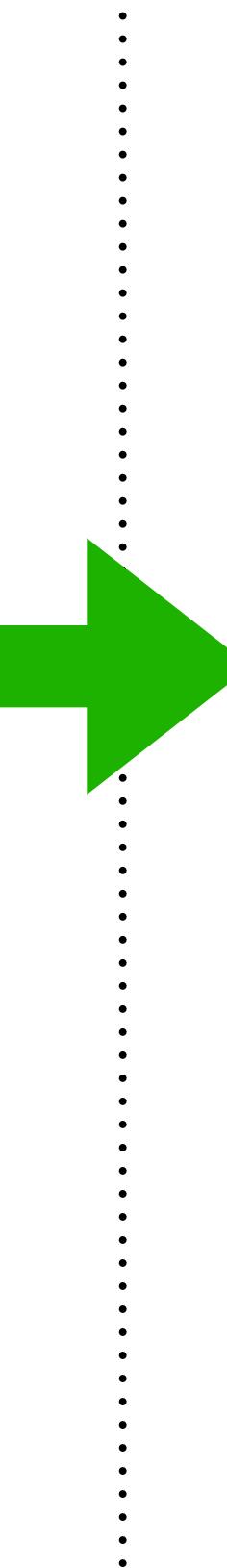
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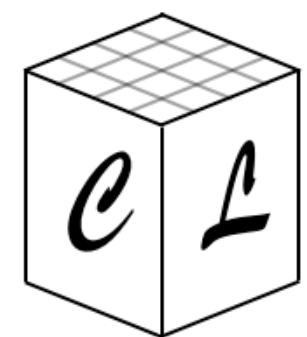
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Why?

Main objective: non-linear regime





# Initial Conditions in the Linear Regime

One option

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Loss of information!

Two IC options

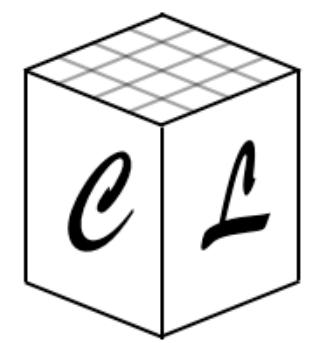
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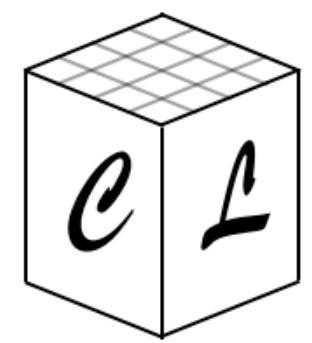
Main objective: non-linear regime

Can  $A^-$  become relevant?



# Initial Conditions in the Linear Regime

Gauge initialization process



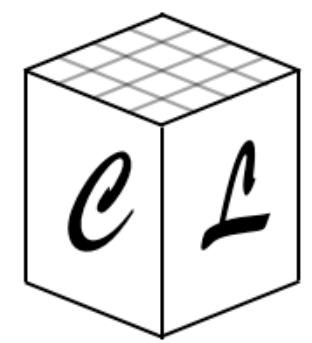
# Initial Conditions in the Linear Regime

## Gauge initialization process

1

Assign BD + solution to  $A_i$  CL variables

$$A_i \rightarrow \frac{1}{\sqrt{2k}} e^{ik/aH}$$



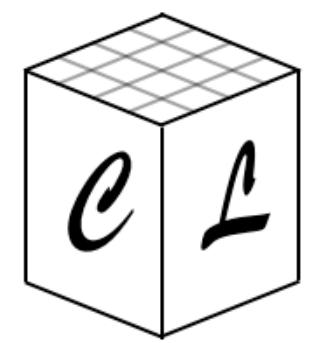
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# Initial Conditions in the Linear Regime

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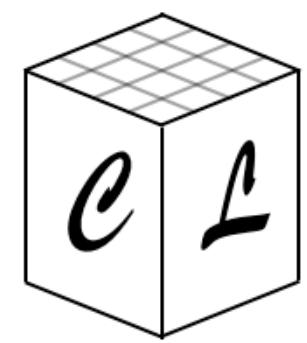
1 Assign BD + solution to  $A_i$  CL variables

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3 Use the helicity projector

$$A_i \rightarrow A^+ = P_{ij}^+ A_j$$

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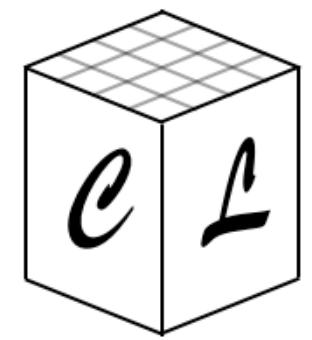
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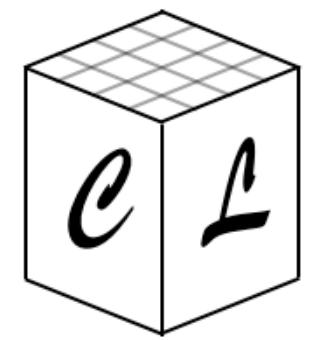
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Fourier



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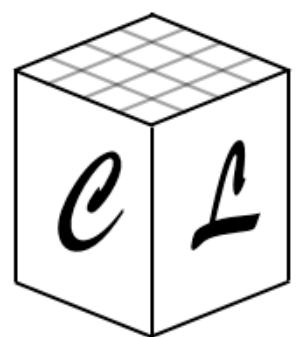
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- 5 Go back to real space via FFT



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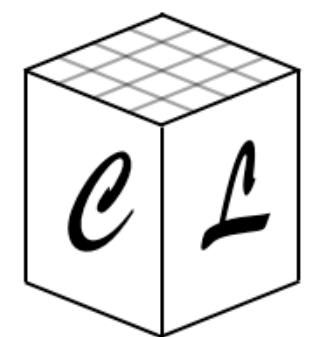
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EOMs evolved in real space!



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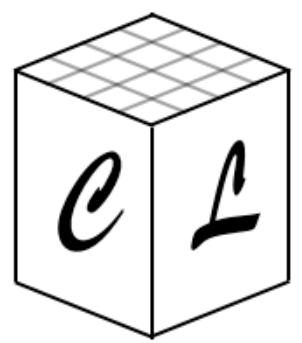
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- 6 Repeat initialization with  $E^\pm$  BD solutions

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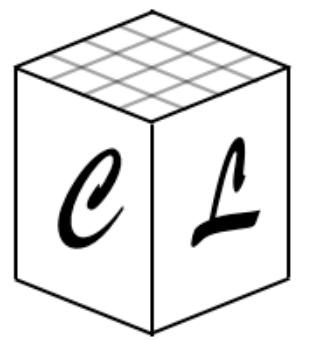
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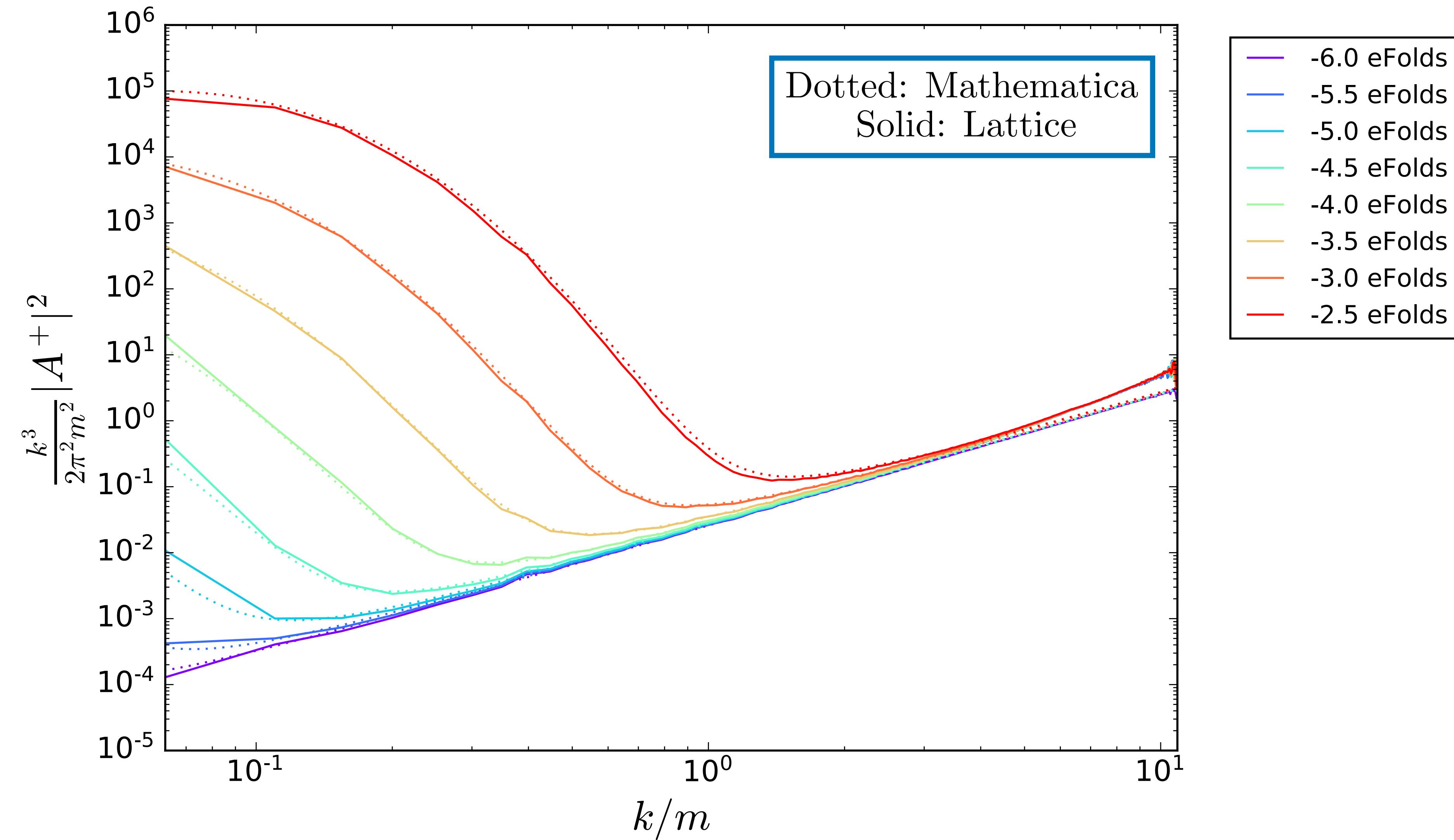
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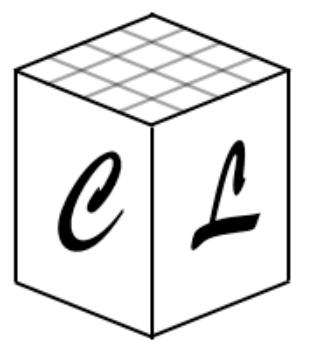
EOMs evolved in real space!

⋮ We will have an amplitude of 2 BD in  $A_i$   
$$\sum_i |A_i|^2 = |A_+|^2 + |A_-|^2$$

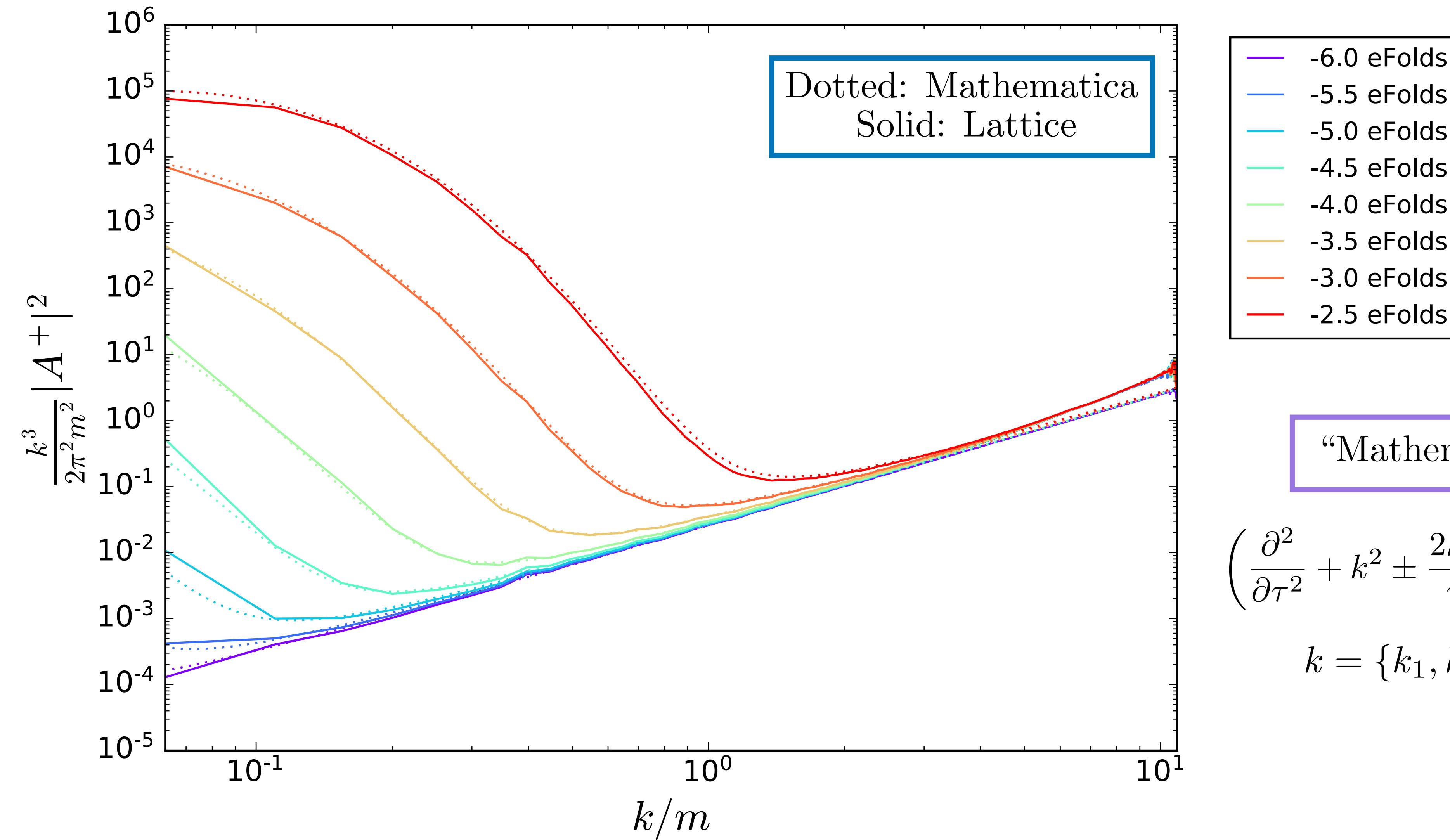


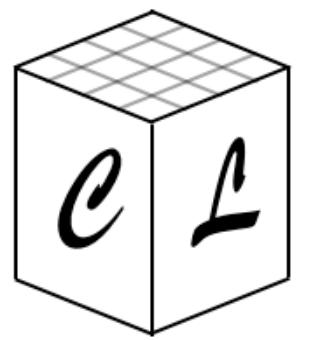
# Simulations in the Linear Regime



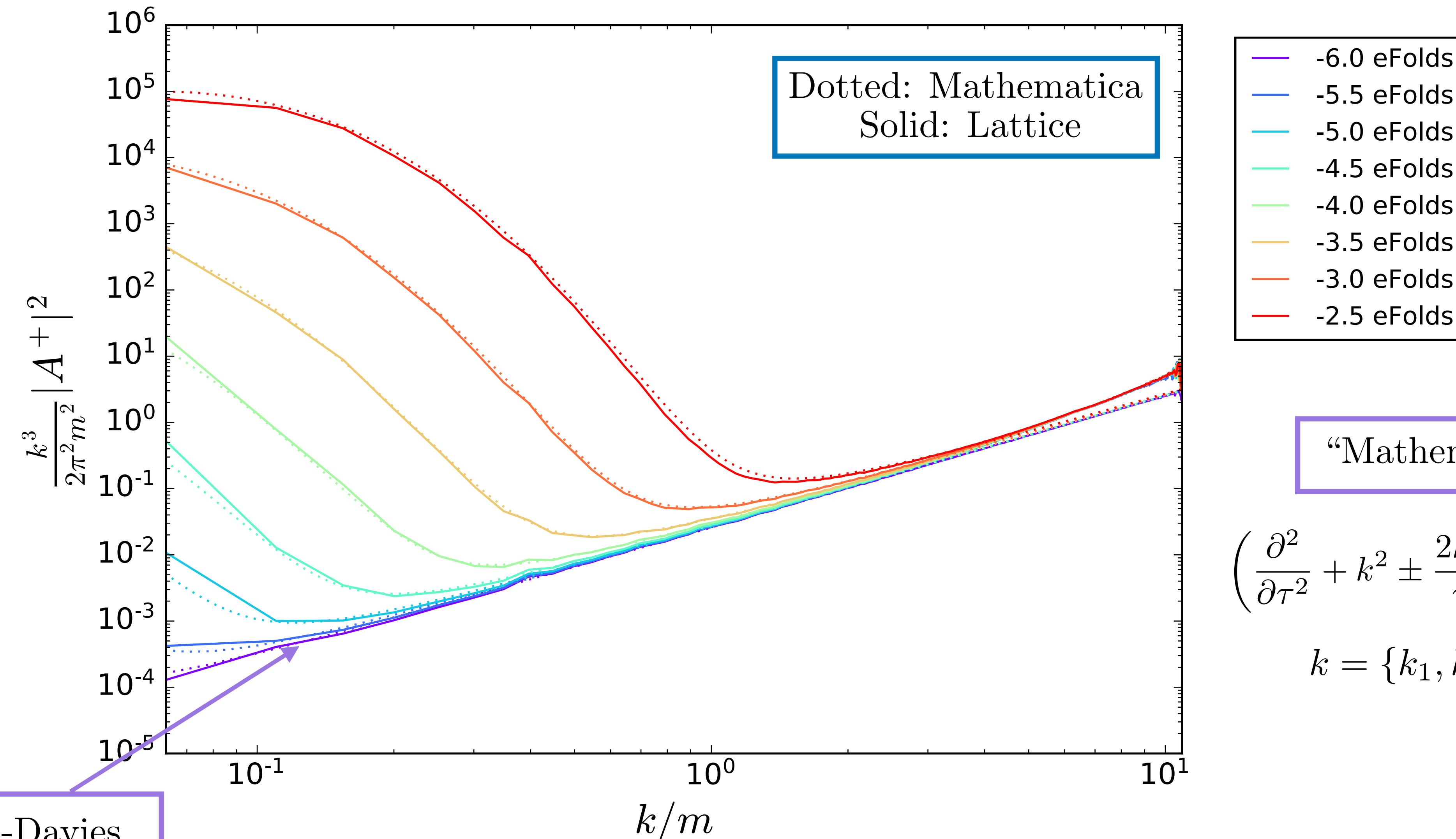


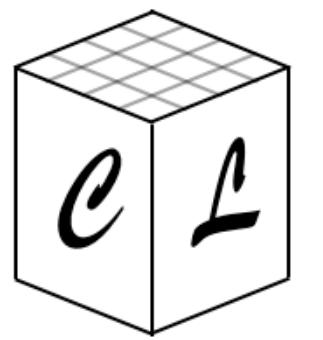
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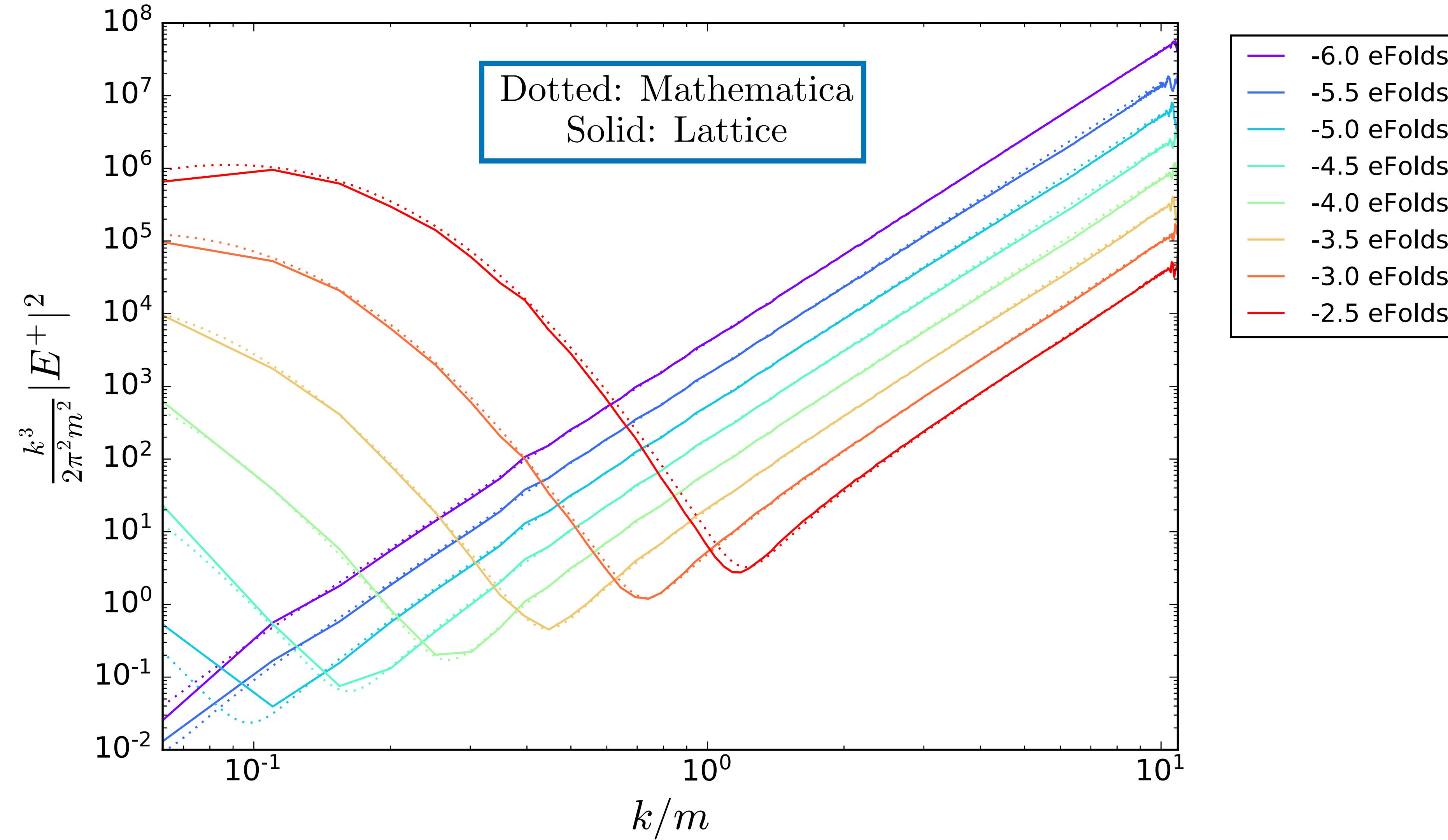


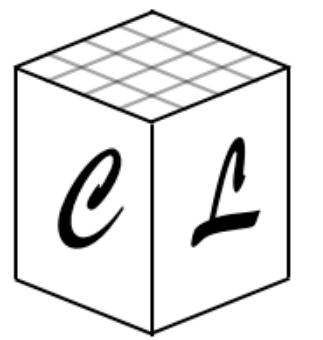
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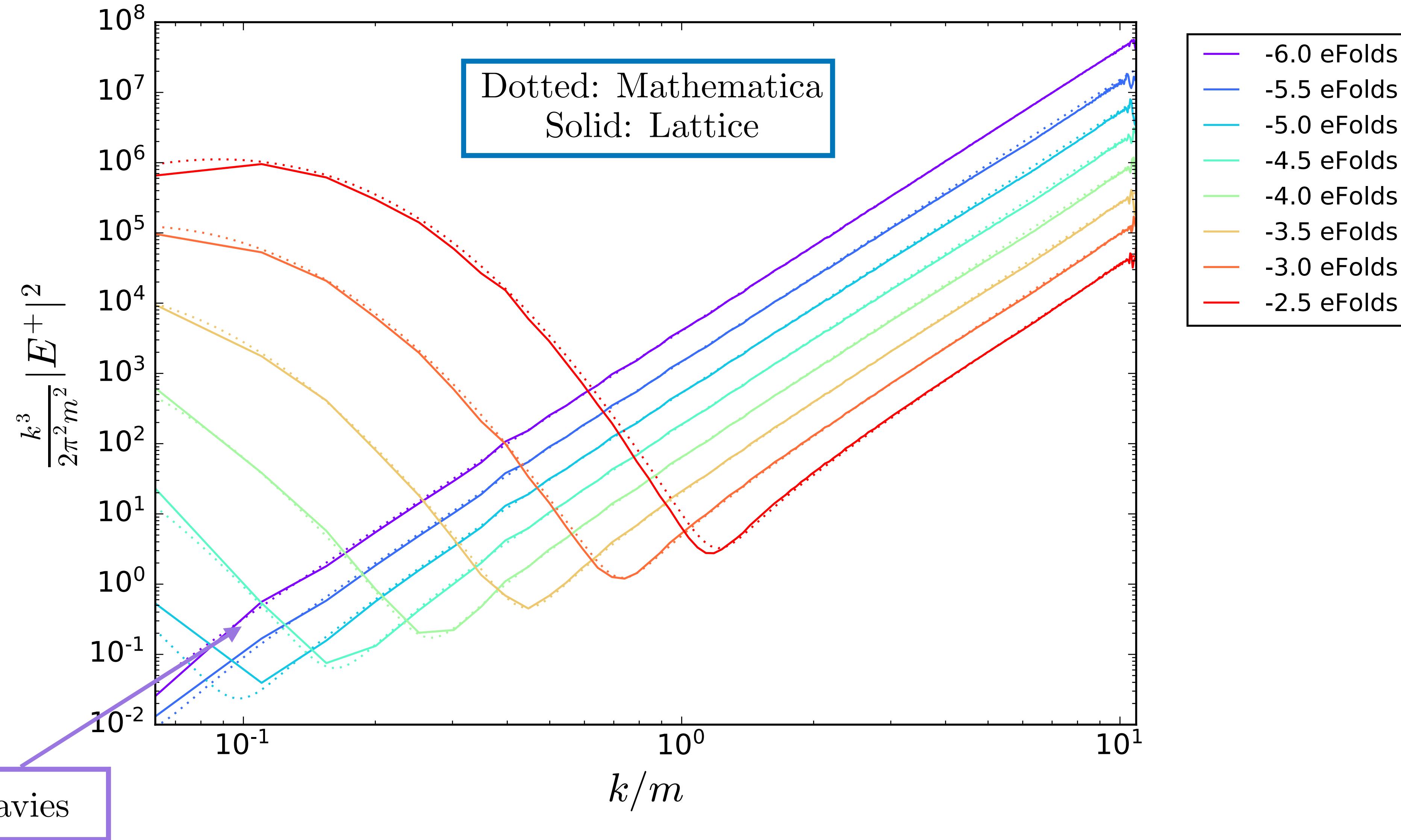


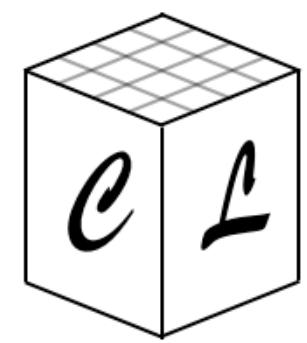
# Simulations in the Linear Regime





# Simulations in the Linear Regime





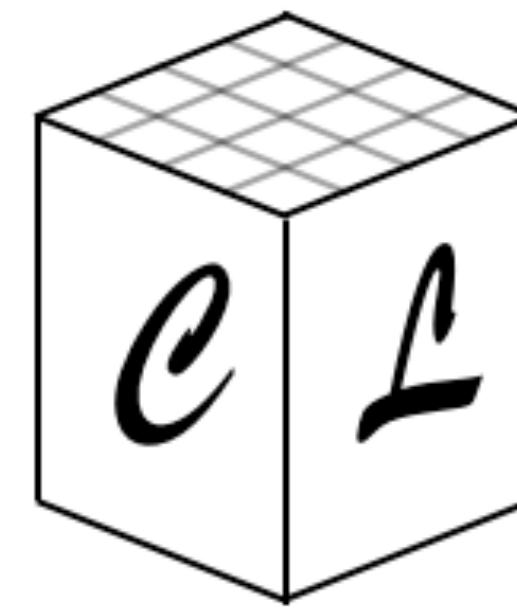
# Non-linear evolution: example

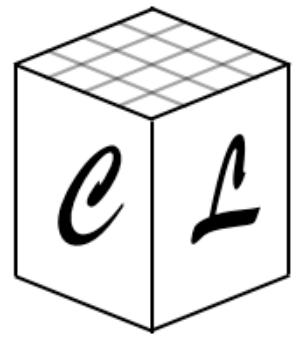
Dynamical equations:

$$\dot{\tilde{\pi}}_\phi = a \vec{\nabla}^2 \phi - a^3 m^2 \phi + \frac{1}{a\Lambda} \tilde{\vec{E}} \cdot \vec{B},$$

$$\dot{\tilde{\vec{E}}} = -\frac{1}{a} \vec{\nabla} \times \vec{B} - \frac{1}{a^3 \Lambda} \tilde{\pi}_\phi \vec{B} + \frac{1}{a\Lambda} \vec{\nabla} \phi \times \tilde{\vec{E}}$$

@





# Non-linear evolution: example

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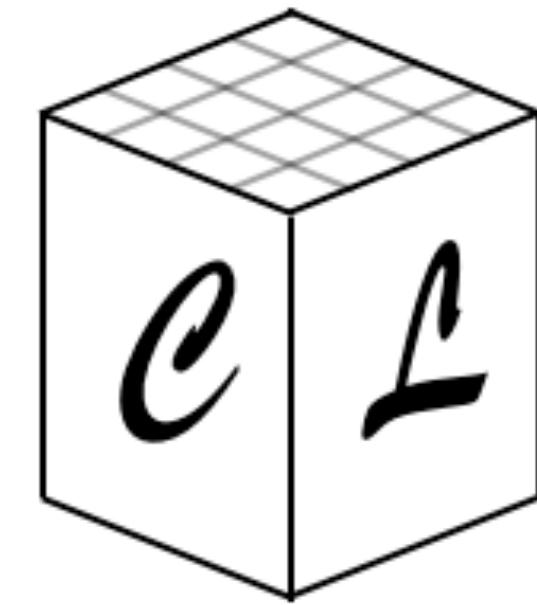
$$\dot{\tilde{\vec{E}}} = -\frac{1}{a} \vec{\nabla} \times \vec{B} - \frac{1}{a^3 \Lambda} \tilde{\pi}_\phi \vec{B} + \frac{1}{a\Lambda} \vec{\nabla} \phi \times \tilde{\vec{E}}$$

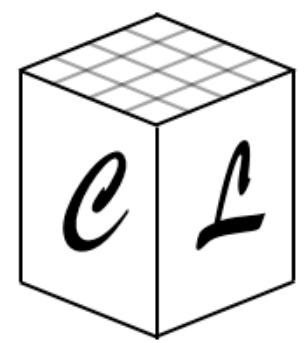
Expansion equation:

$$\dot{\pi}_a = \frac{-a}{6m_{\text{pl}}^2} (3p + \rho) =$$

$$\frac{a}{3m_{\text{pl}}^2} \langle -2K_\phi + V - K_A - G_A \rangle$$

@



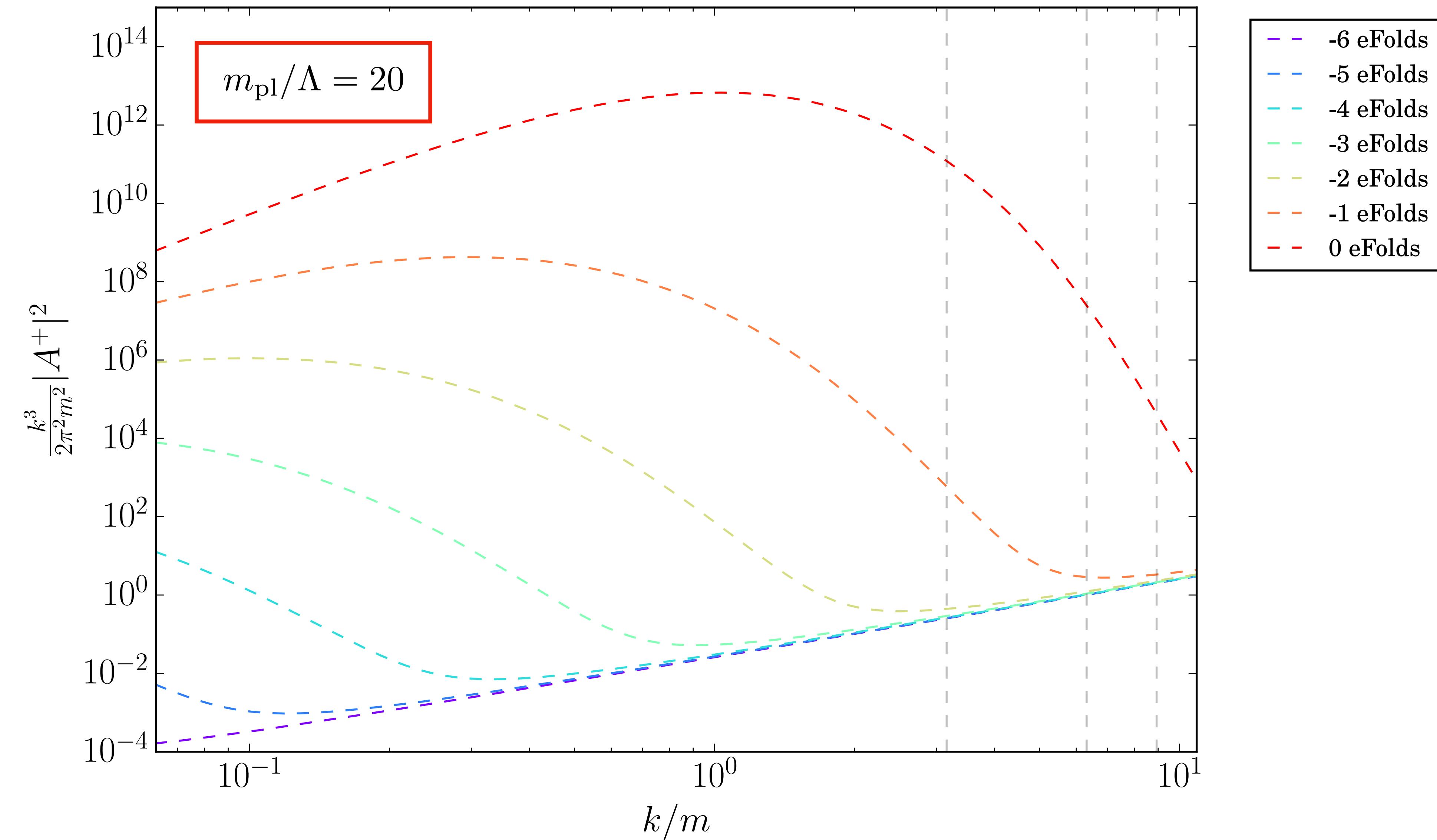


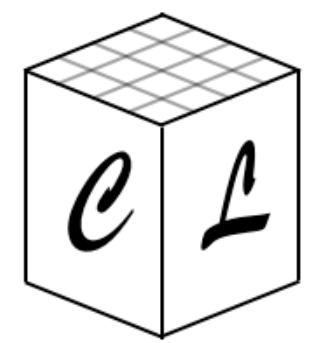
# Non-linear evolution: example

Gauge PS

$A^+$

Linear



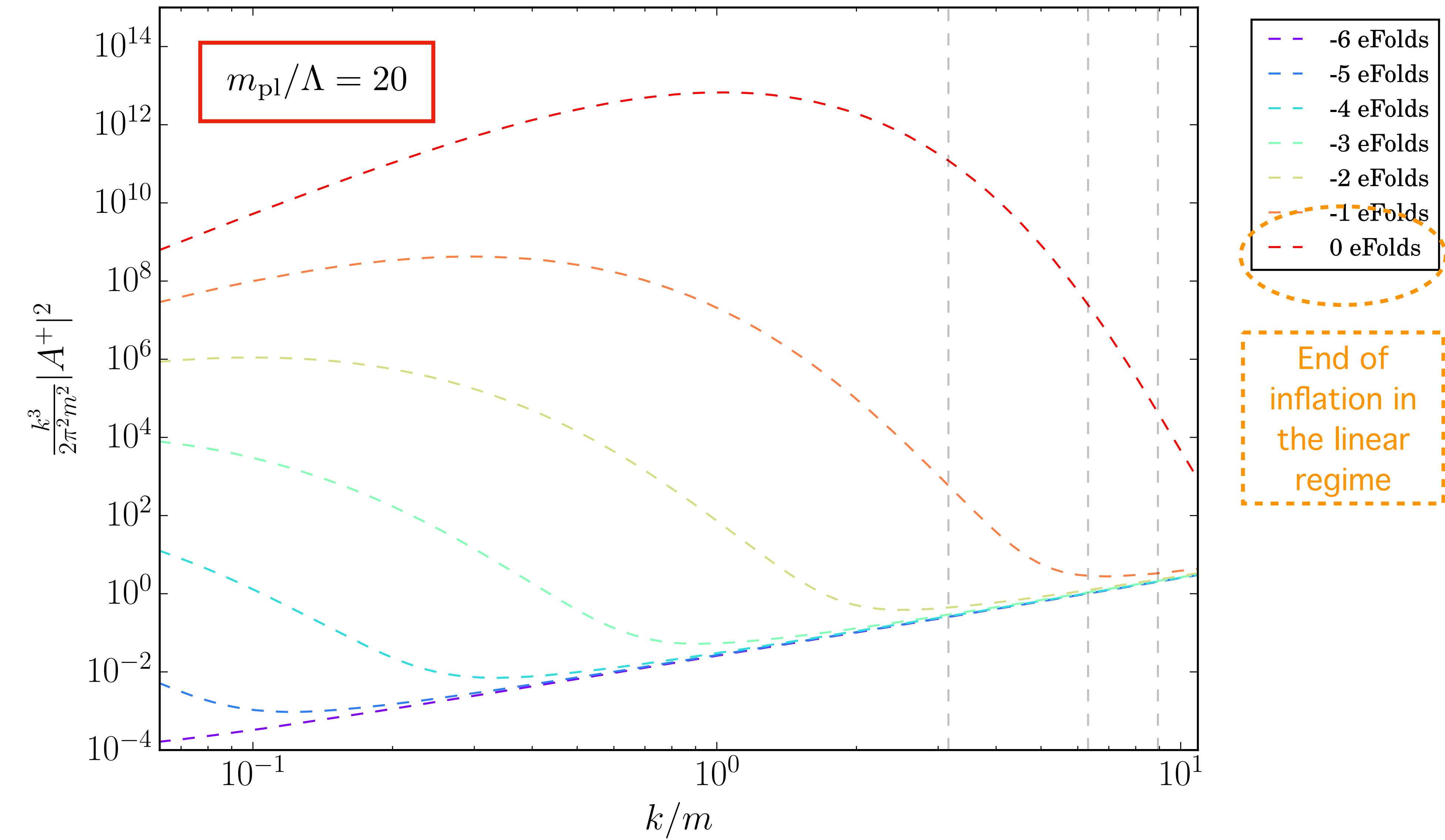


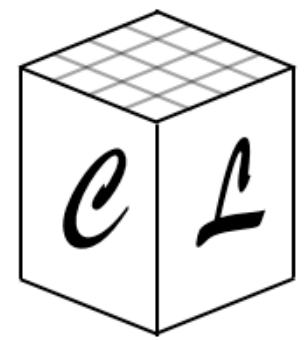
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$A^+$

Linear



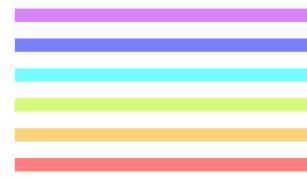


# Non-linear evolution: example

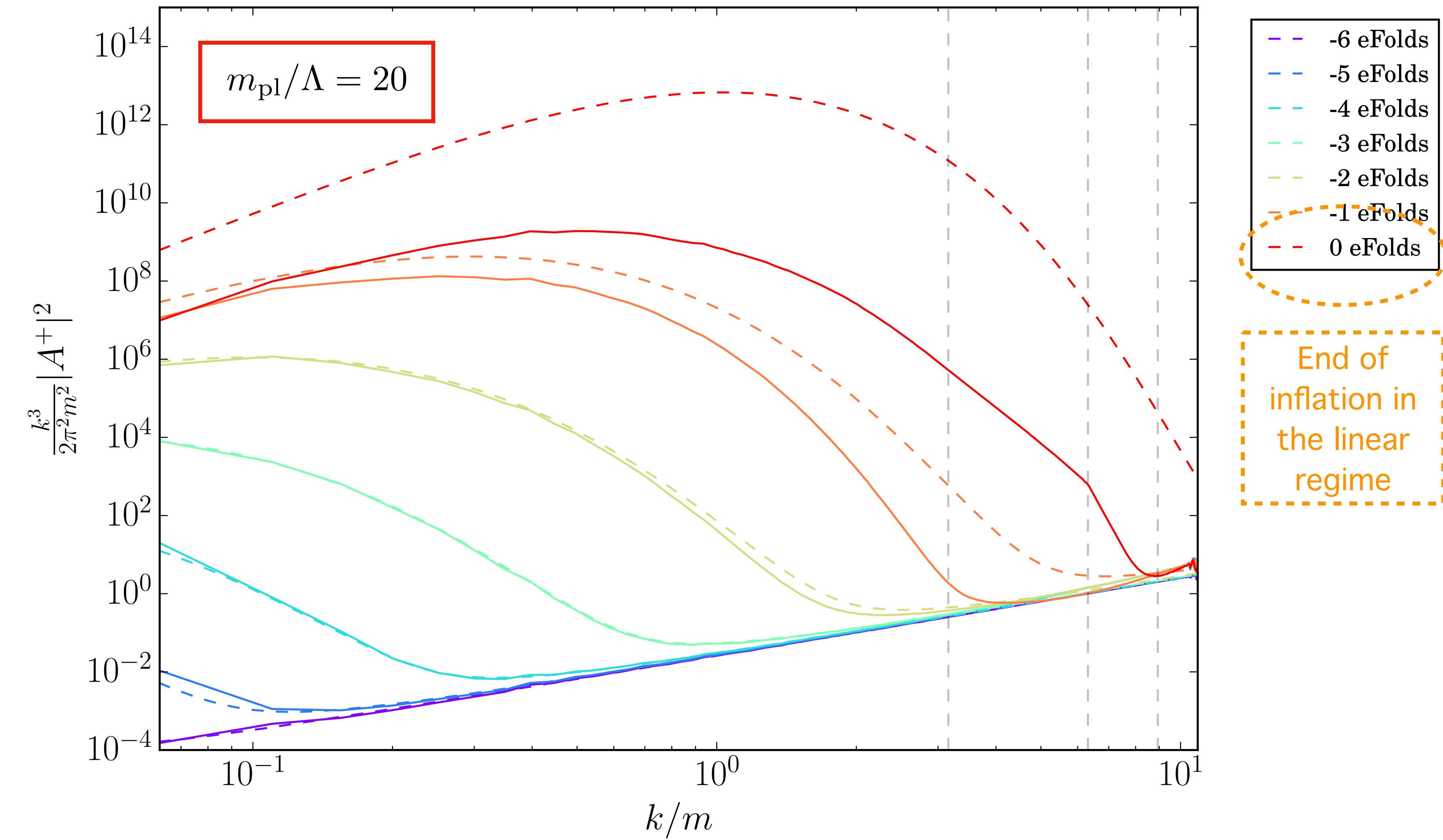
Gauge PS

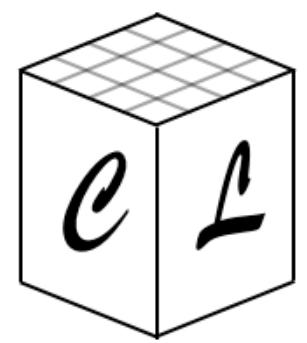
$A^+$

Linear



Non-linear



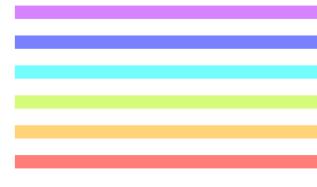


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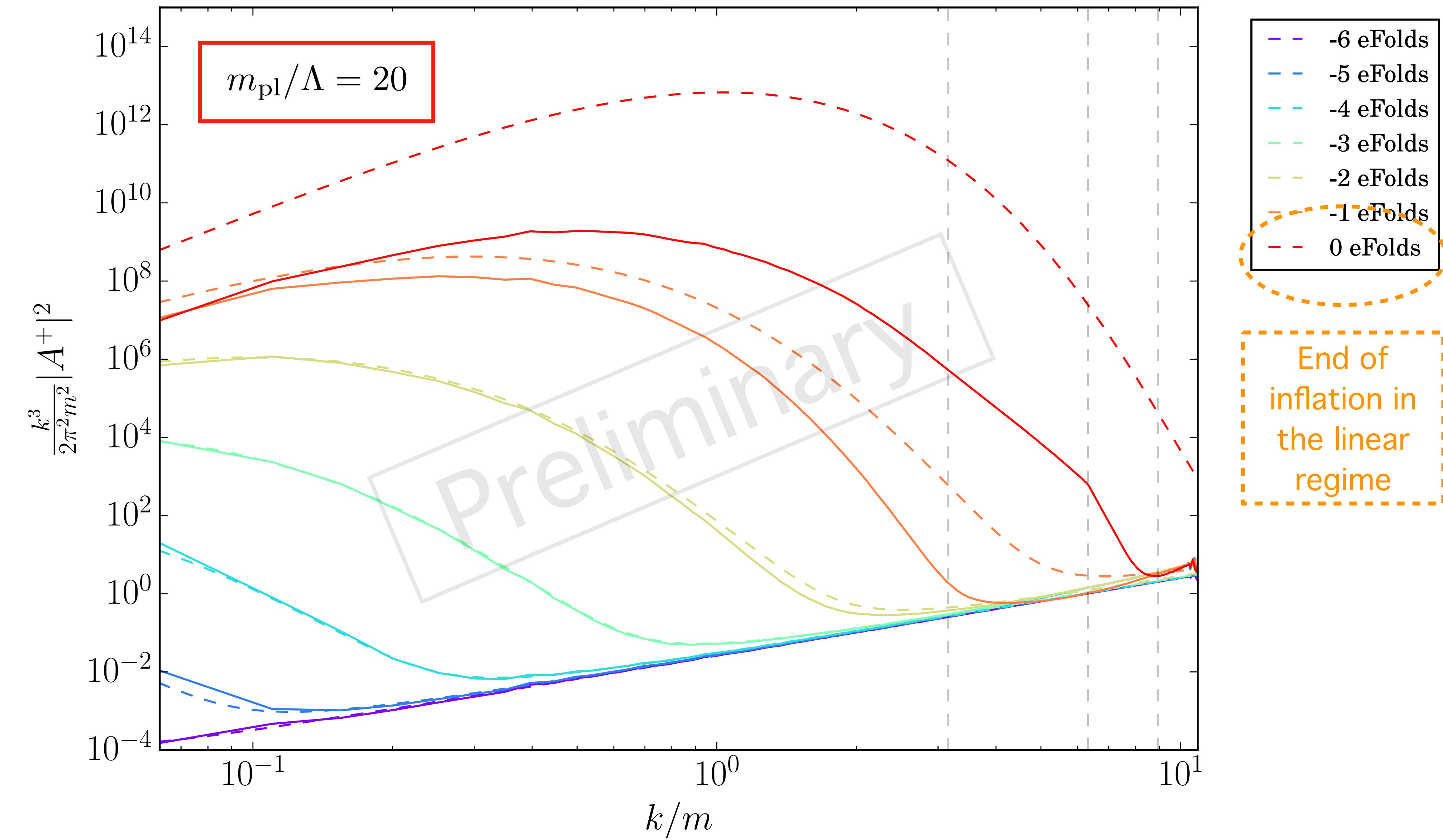
Gauge PS

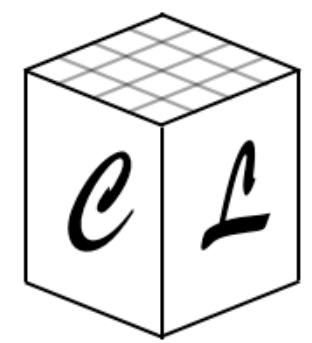
$A^+$

Linear



Non-linear

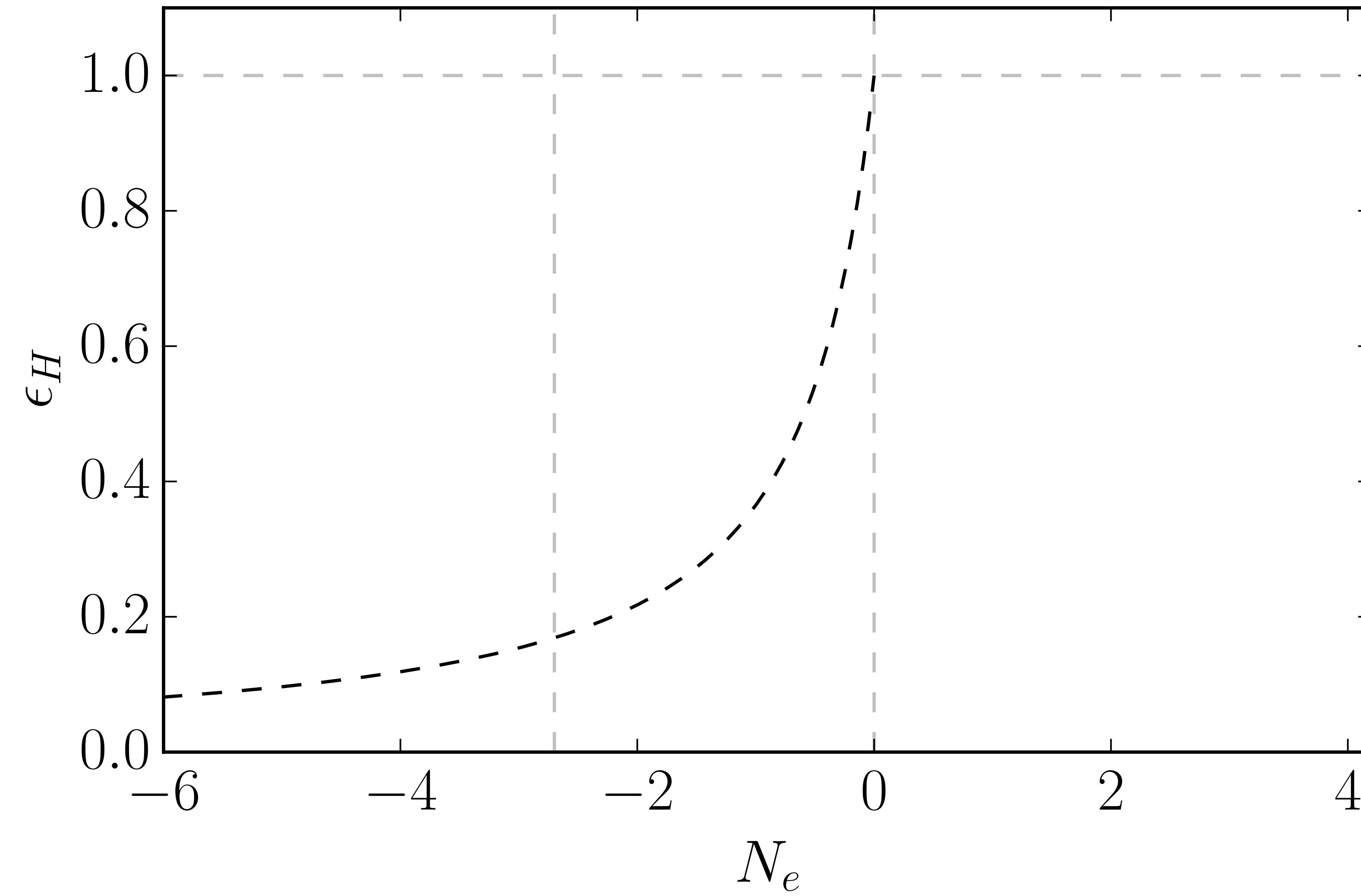


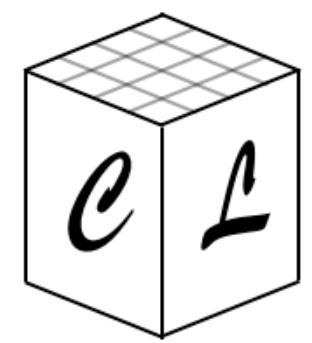


# Non-linear evolution: example

$$\epsilon_H \equiv -\frac{\dot{H}}{H^2}$$

-----  
Linear

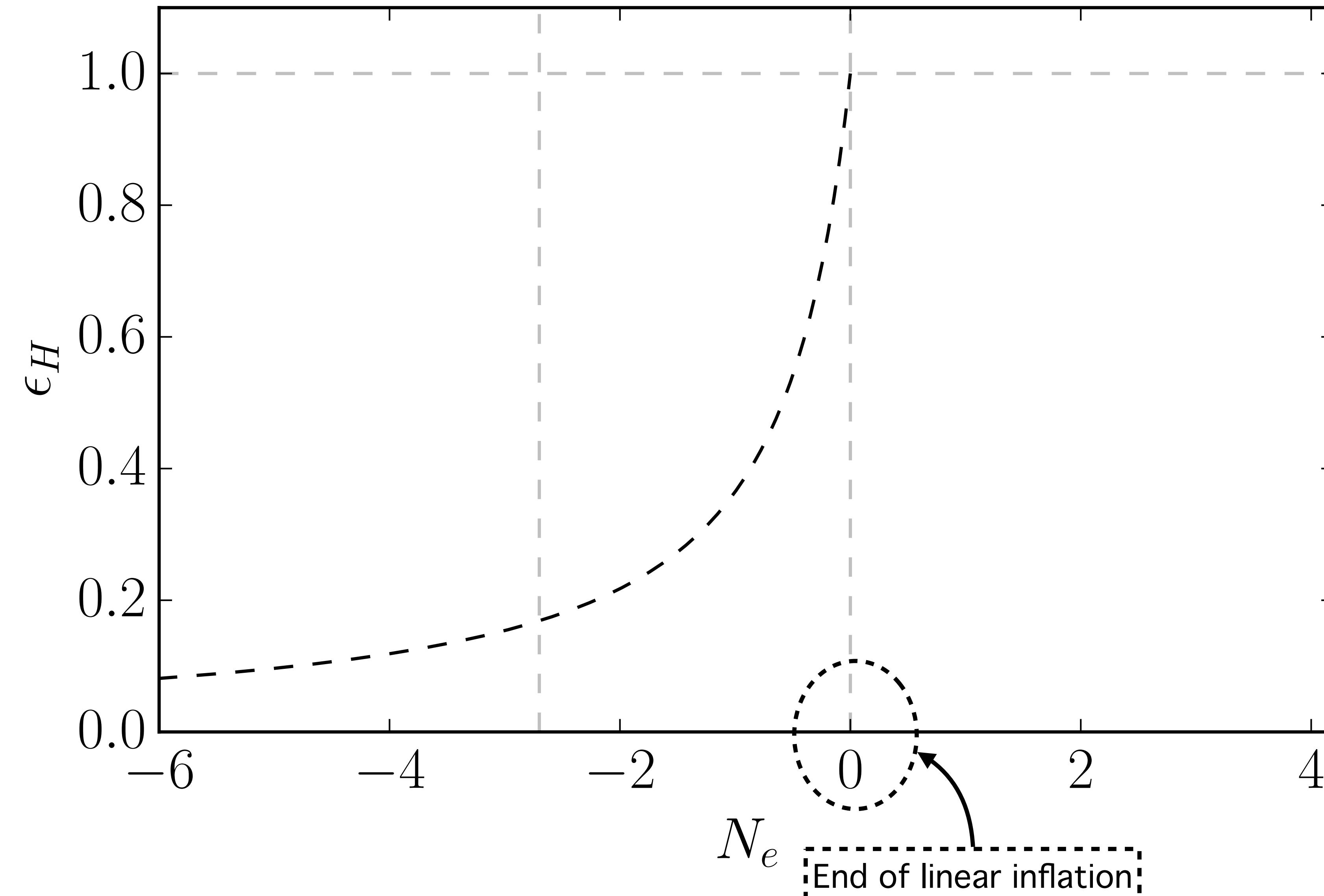


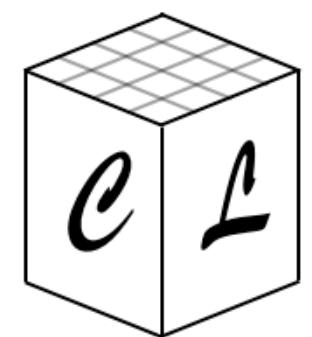


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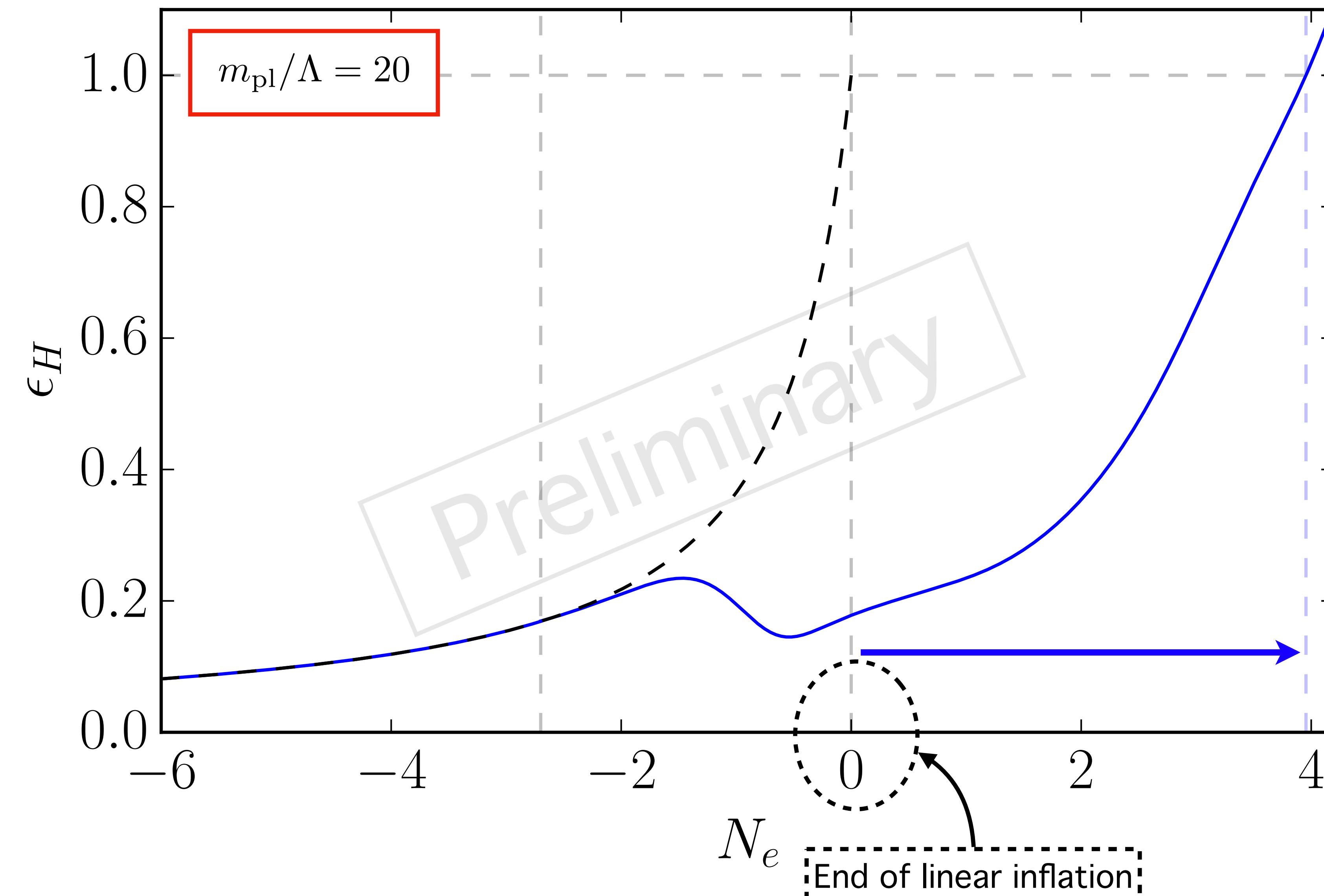


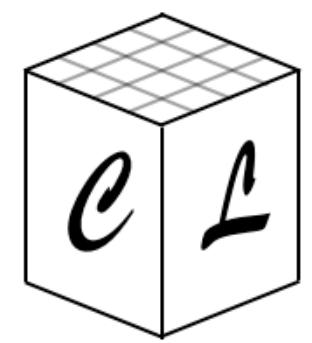
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Linear

Non-linear



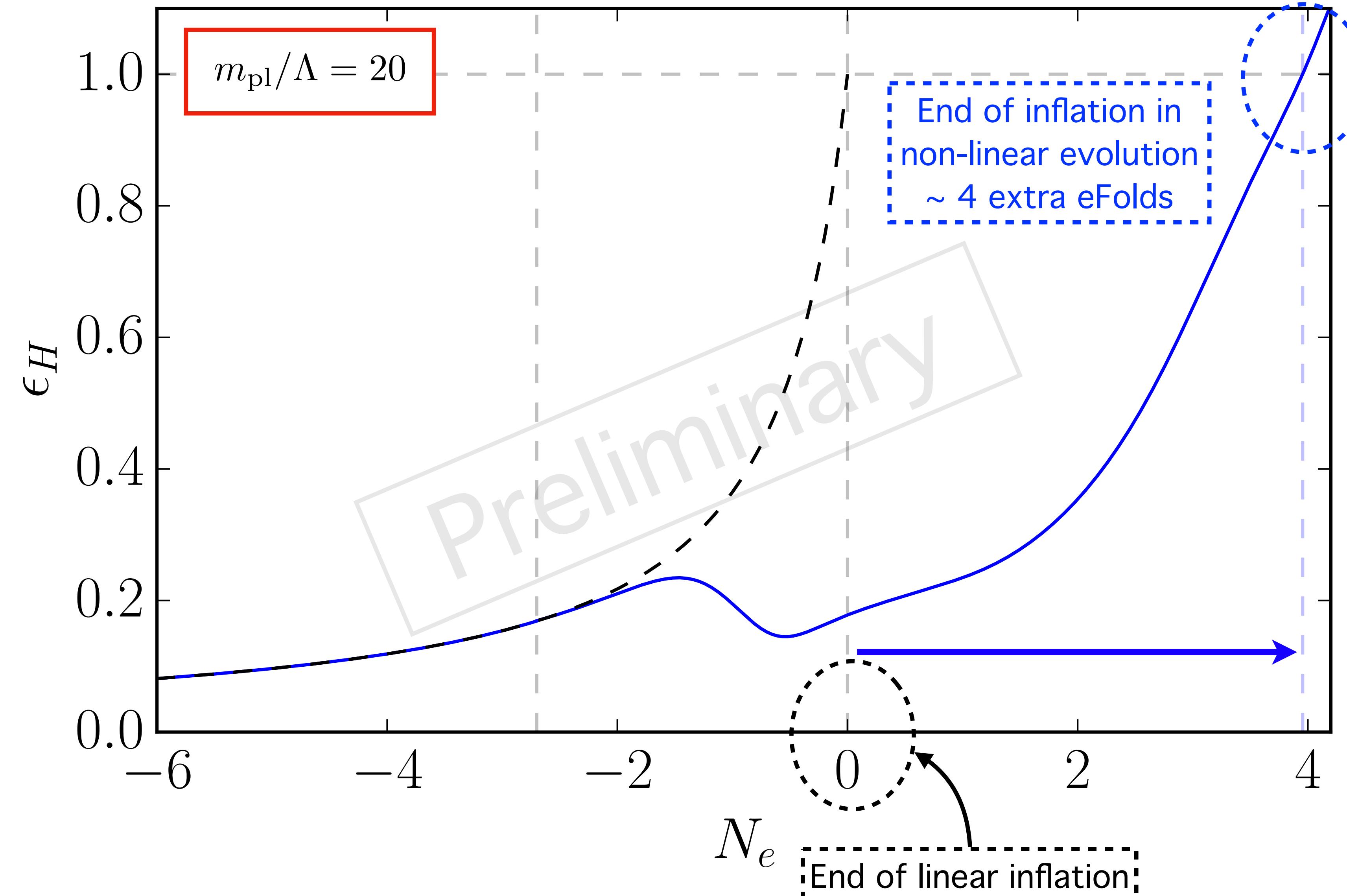


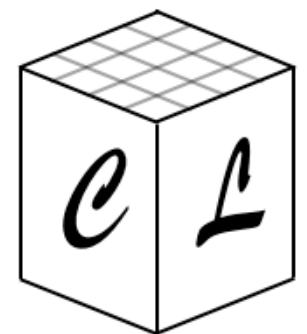
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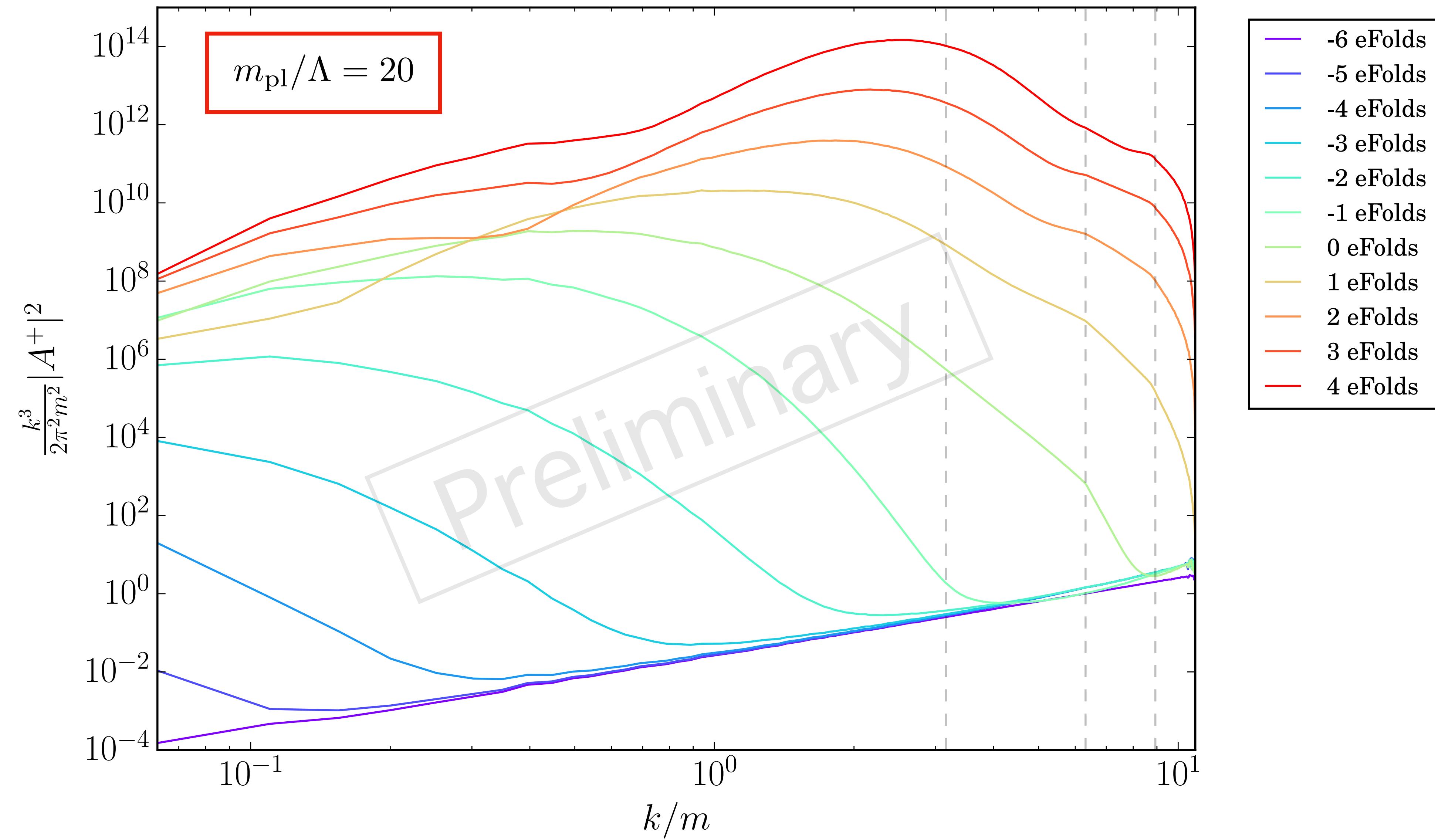
Non-linear

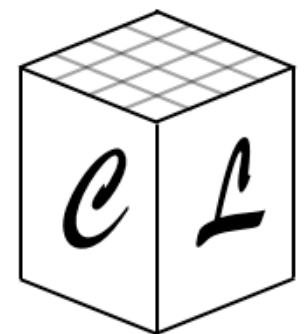




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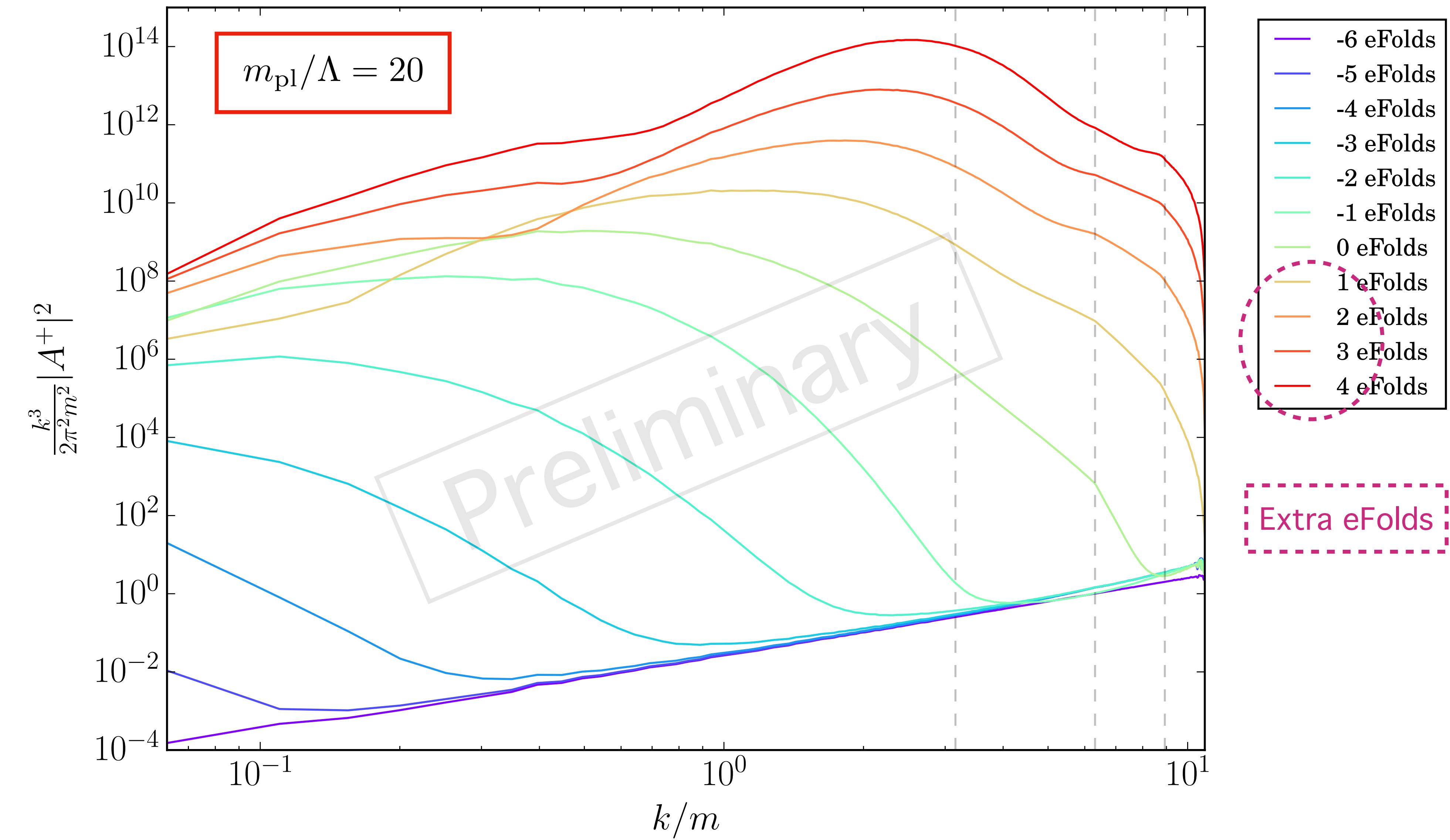
What's  
happening in  
those extra  
folds?

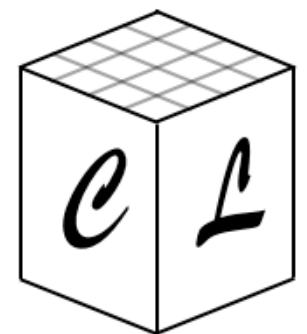




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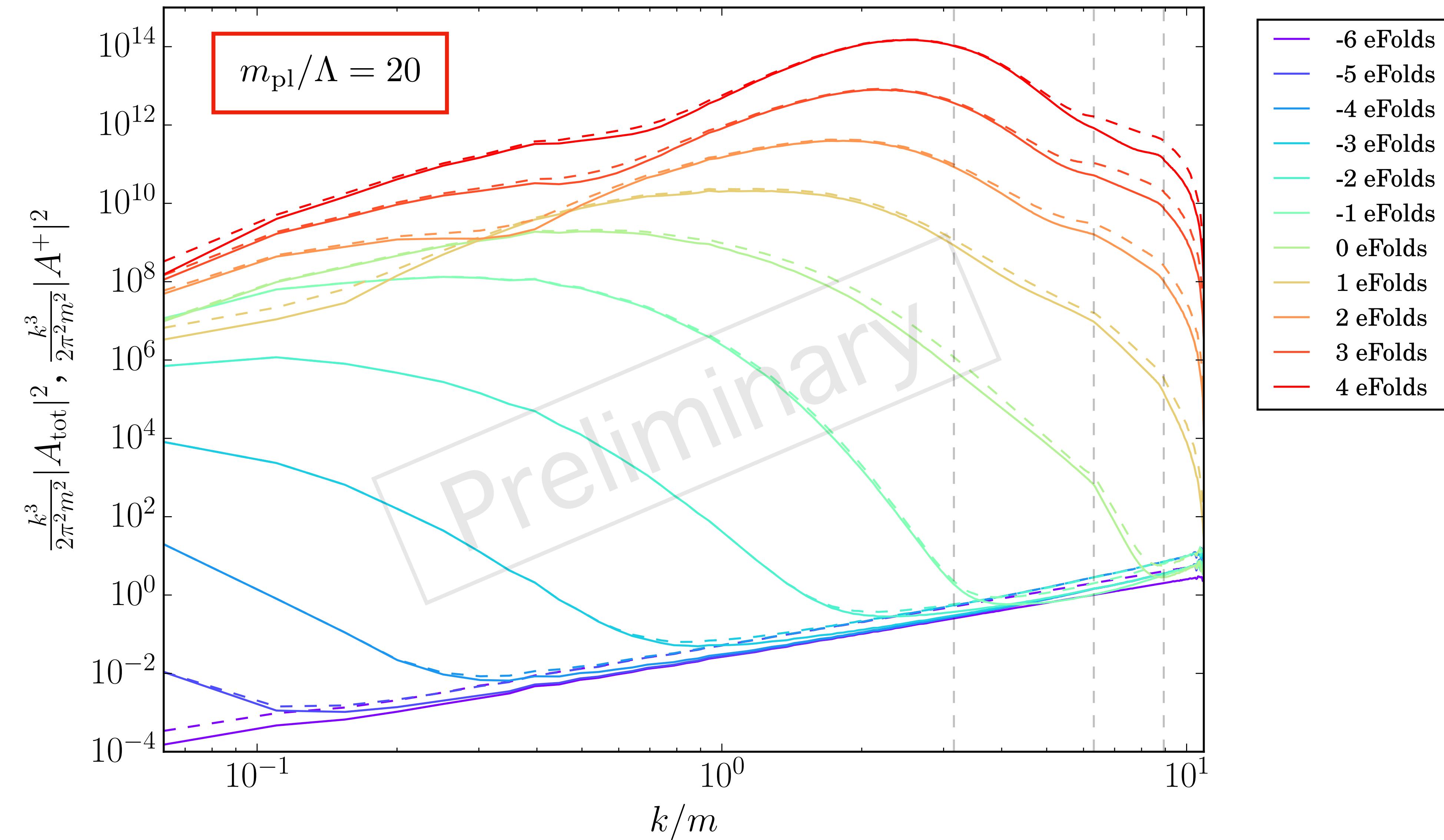


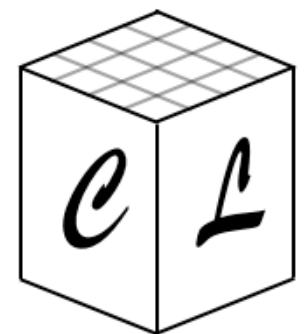


# Non-linear evolution: example

What's  
happening in  
those extra  
folds?

$A^+$   
 $A_{\text{tot}}$





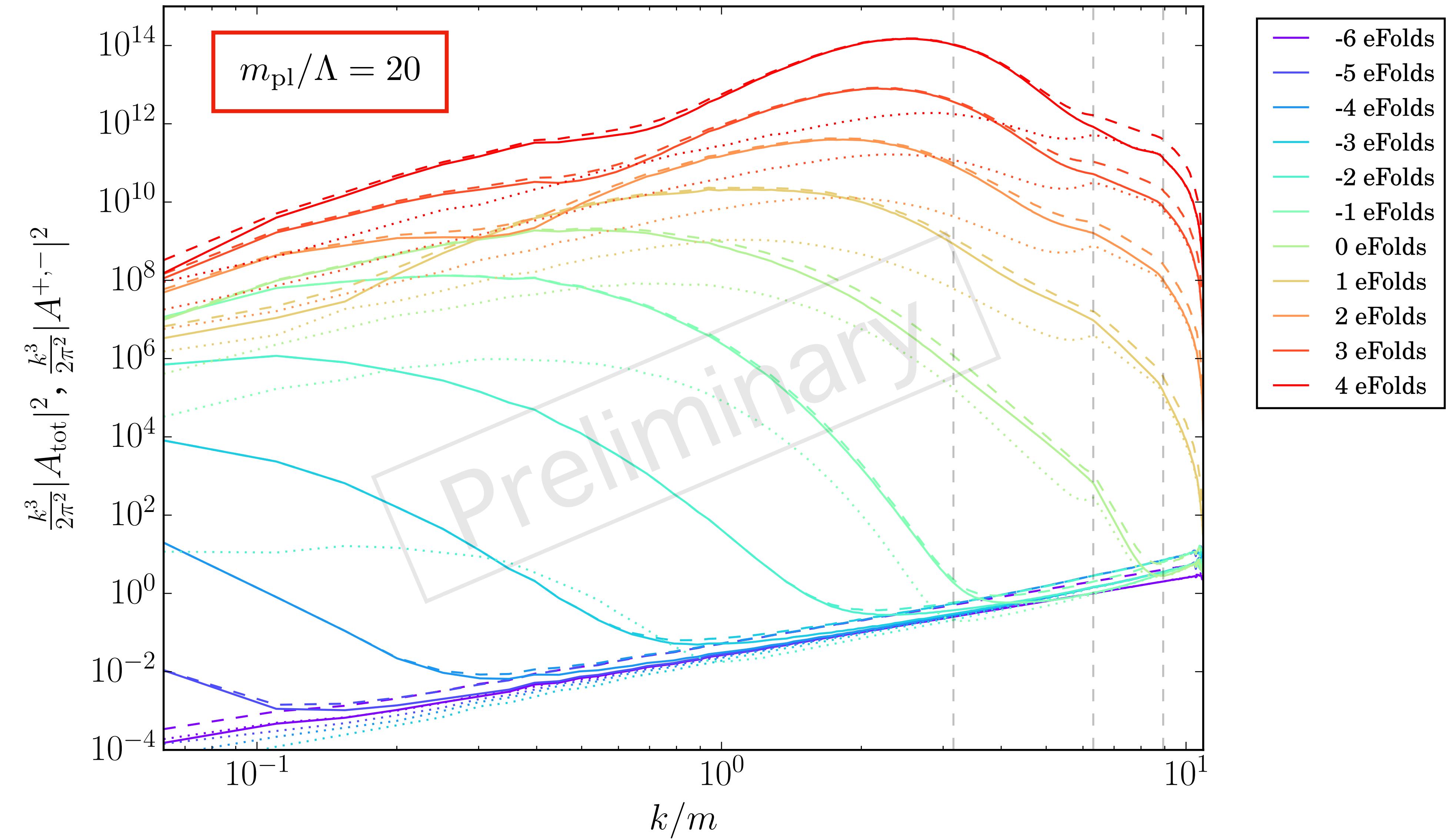
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$A^-$

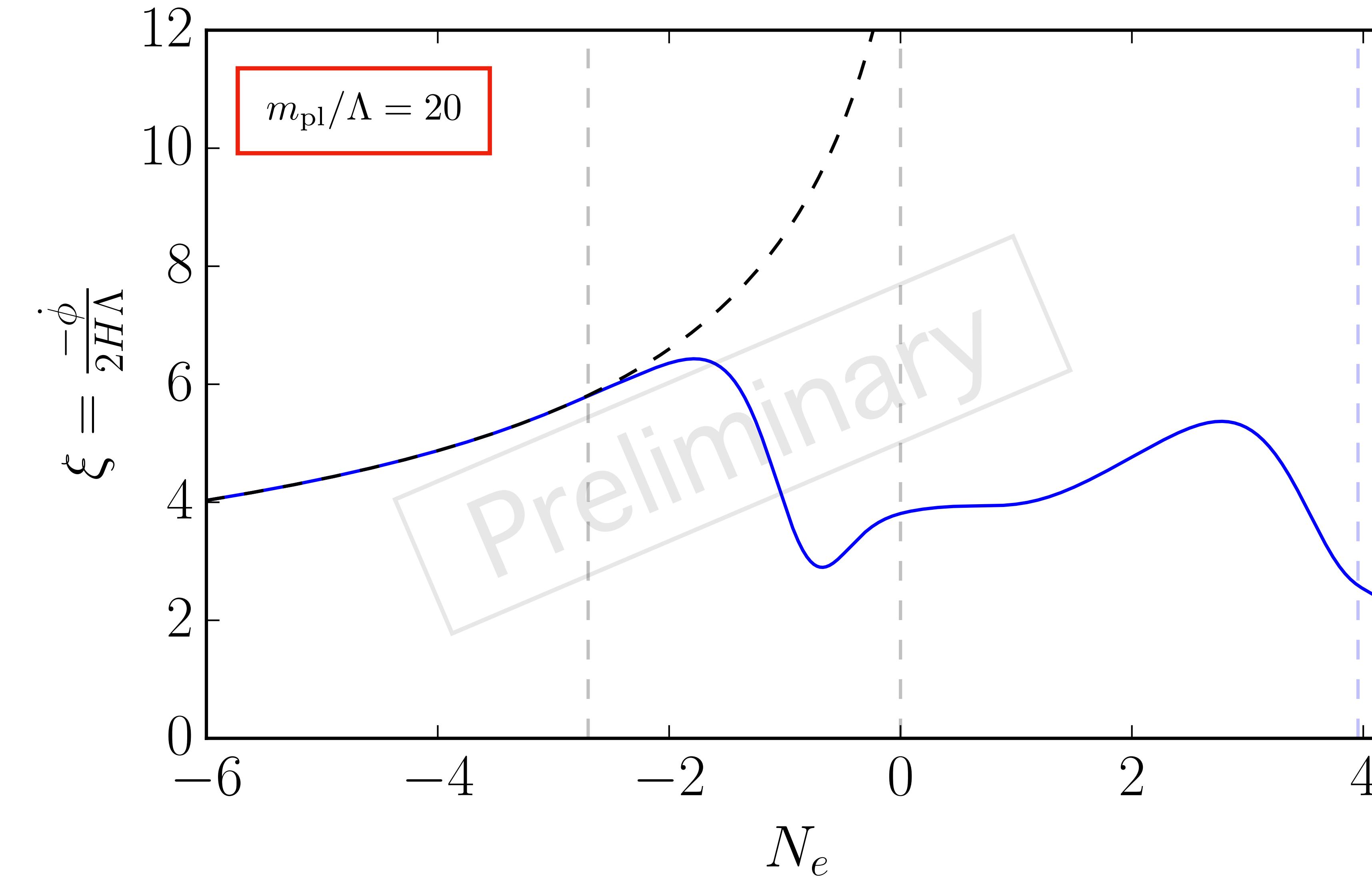


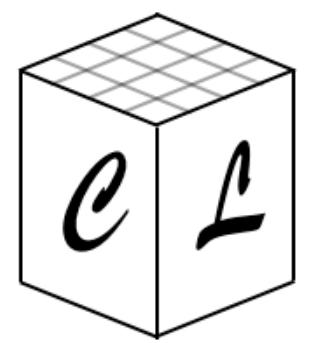
## Non-linear evolution: example

Inflation observables

Linear

Non-linear



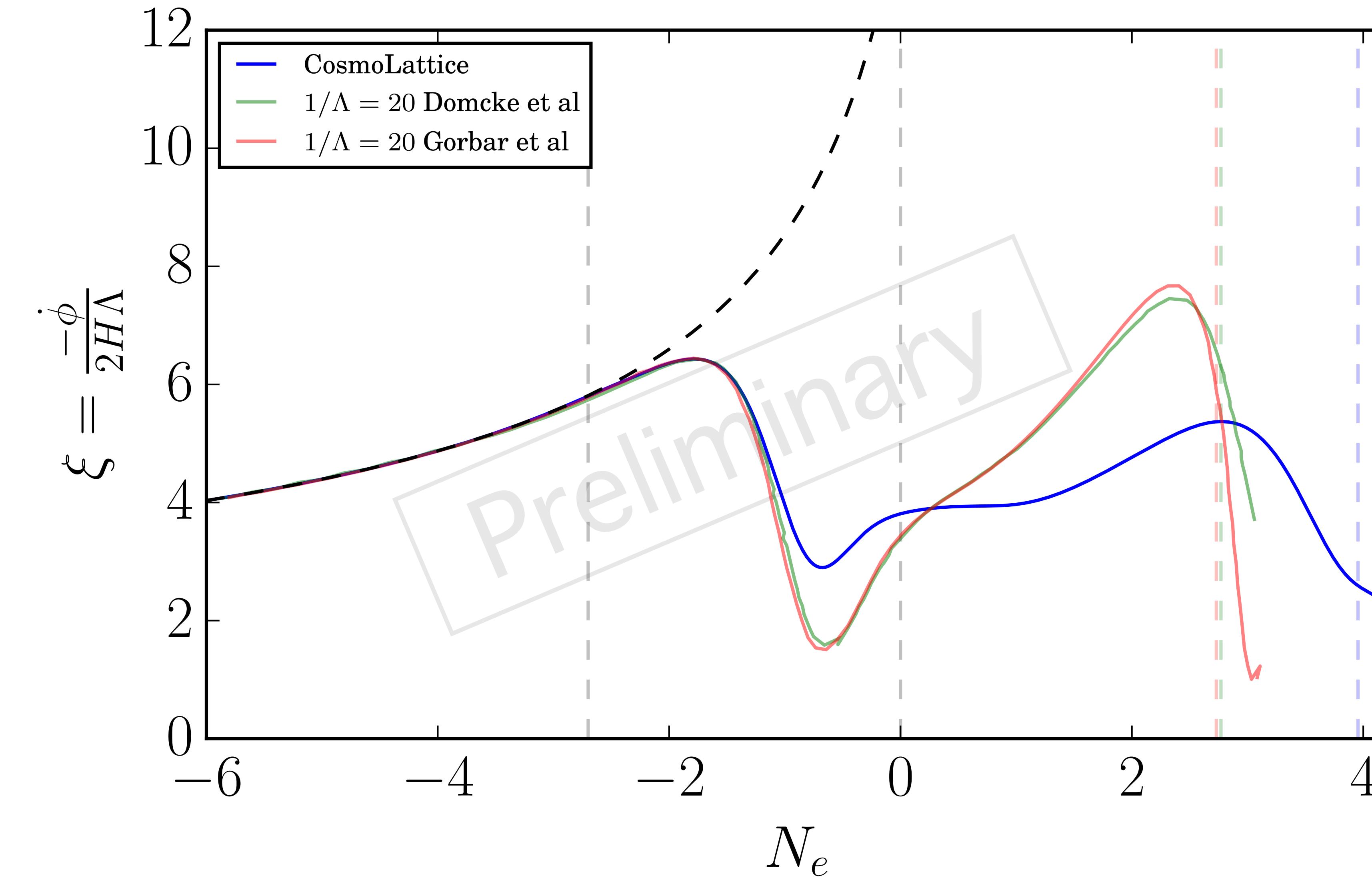


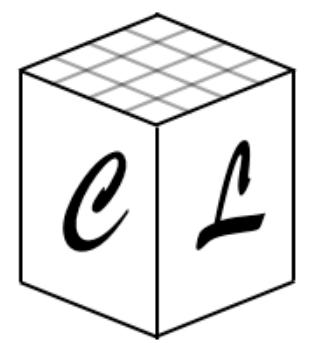
## 7- Non-linear evolution: example

Inflation observables

Linear

Non-linear



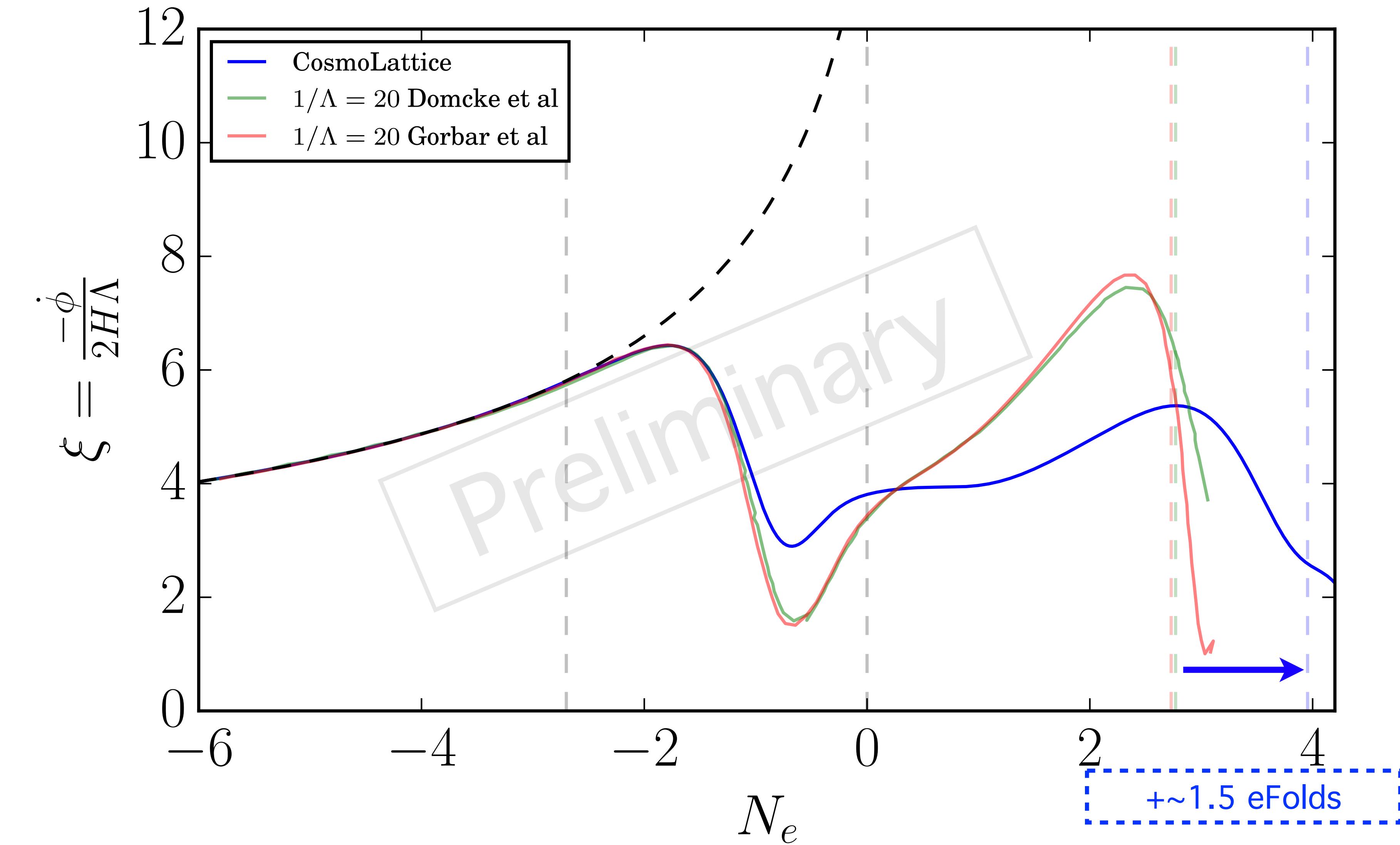


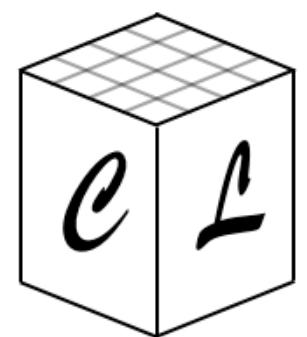
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Inflation observables

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Non-linear



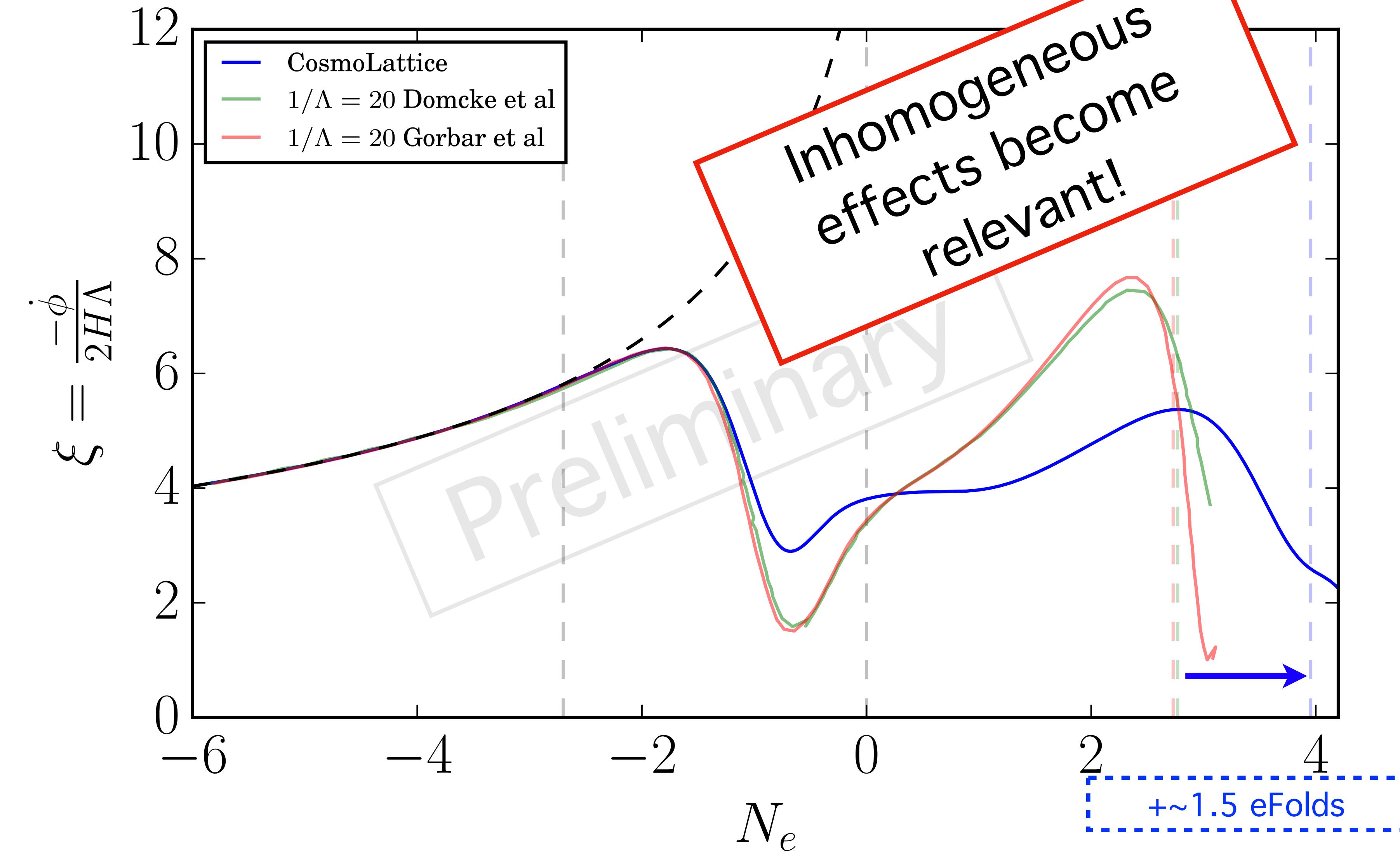


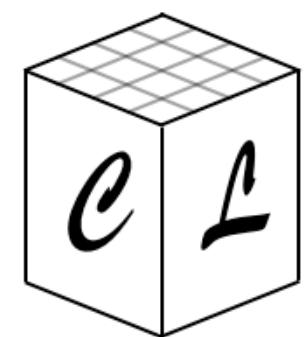
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Non-linear

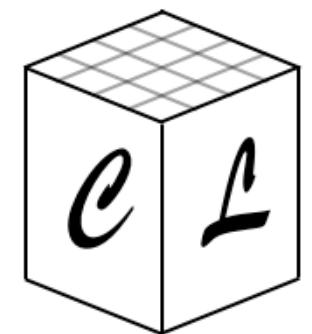




# Summary & Conclusions

- Successful implementation of axion-inflation in CL

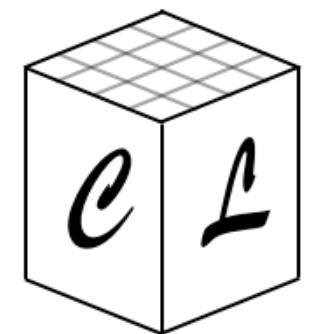
$$\frac{\phi}{\Lambda} F \tilde{F}$$



# Summary & Conclusions

- Successful implementation of axion-inflation in CL
- Non-simpletic integrators needed: RK
  - Validation: preheating

$$\boxed{\frac{\phi}{\Lambda} F \tilde{F}}$$

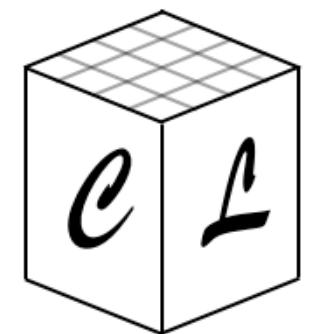


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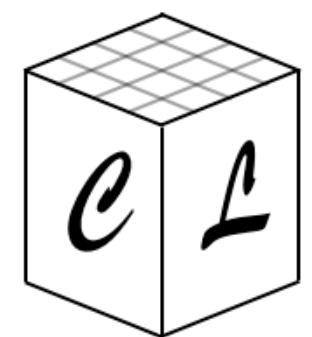
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  - Helicity basis
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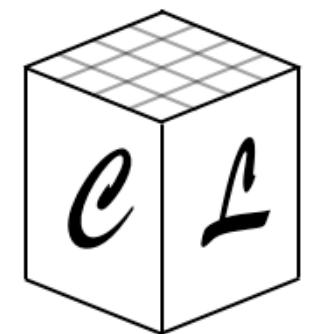
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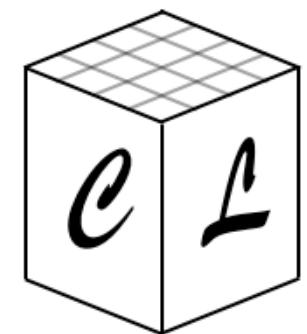
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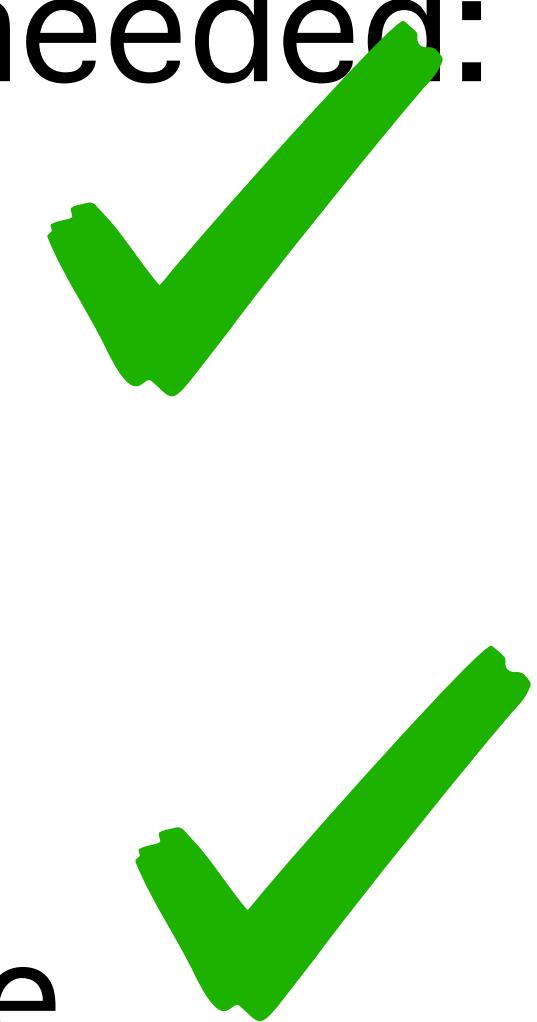
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# Summary & Conclusions

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Ready to study non-linear phenomenology!

$$\frac{\phi}{\Lambda} F \tilde{F}$$

Thank you!