## Πανελλήνιες Φυσική Γ Λυκείου 2017

## Θέμα Β

Β1. Στην ΘΙ, θα ισχύει

$$\begin{split} \Sigma F &= 0 \implies \\ F_{\varepsilon\lambda} - mg &= 0 \implies \\ k\Delta l &= mg \implies \\ \Delta l &= \frac{mg}{k} \end{split}$$

Επειδή στη ΘΦΜ ισχύει v=0, άρα  $\Delta l=A$  και χάρις ΑΔΕΤ

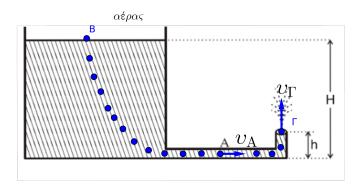
$$\begin{split} E_{\tau\alpha\lambda_{(\Gamma)}} &= E_{\tau\alpha\lambda_{(\Gamma')}} \implies K_{\Gamma} + U_{\Gamma} = K'_{\Gamma} + U'_{\Gamma} \implies \\ &\frac{1}{2}DA^2 = \frac{1}{2}kx_2^2 \implies x_2 = A \end{split}$$

έτσι

$$U_{\varepsilon \lambda_{max}} = \frac{1}{2} k \left( 2A \right)^2 = \frac{1}{2} 4A^2 = 2k \frac{m^2 g^2}{k^2} = \frac{2m^2 g^2}{k^2}$$

άρα σωστό το (ii)

B2. Από εξίσωση Bernoulli



B3. Ο παρατηρητής B πλησιάζει την πηγή A και η πηγή απομακρύνεται από τον παρατηρητή B άρα θα ισχύει

$$\stackrel{B}{\longrightarrow} \stackrel{v_2}{\longrightarrow} \qquad f_s \left( \left( \stackrel{A}{\smile} \stackrel{v_1}{\longrightarrow} \right) \right)$$

$$f_{\rm B} = \frac{v_{\eta\chi} + v_2}{v_{\eta\chi} + v_1} f_s = \frac{v_{\eta\chi} + \frac{v_{\eta\chi}}{10}}{v_{\eta\chi} + \frac{v_{\eta\chi}}{5}} f_s = \frac{\frac{11v_{\eta\chi}}{10}}{\frac{6v_{\eta\chi}}{10}} f_s = \frac{11 \cdot 5}{10 \cdot 6} f_s = \frac{11}{12} f_s$$

άρα το σωστό είναι το (ii)

## Θέμα Γ

Γ1.

$$-A \to A : \Delta t = \frac{T}{2}$$

σε  $\Delta t$  διαταραχή σε απόσταση  $\Delta x = 4cm = 0,04m$ .

$$v_{\delta} = \frac{\Delta x}{\Delta t} = \frac{0.04}{0.4} = 0.1 m/s$$

$$v_{\delta} = \frac{\lambda}{T} \implies \lambda = 0,08m$$

Το  $\Delta m$  εκτελεί α.α.τ.:

$$D = \Delta m \cdot \omega^2 = \Delta m \frac{4\pi^2}{T^2} = 10^{-6} \frac{4\pi^2}{0,64} = \frac{\pi^2}{16} 10^{-4} \frac{N}{m}$$

$$E_T = \frac{1}{2}D \cdot A^2 \implies 5\pi^2 10^{-7} = \frac{1}{2} \cdot \frac{\pi^2}{16} 10^{-4} A^2 \implies A^2 = 0, 16 \implies A = 0, 4m$$
 (πλάτος)

Γ2. Η εξίσωση του κύματος είναι:

$$y = A\eta\mu \left(\frac{2\pi t}{T} - \frac{2\pi x}{\lambda}\right) = 0, 4\eta\mu \left(\frac{5\pi t}{2} - 25\pi x\right) \text{ (SI)}$$

Στιγμιότυπο την  $t_1=1,4s$ 

$$x_1 = v_{\delta}t_1 = 0, 1 \cdot 1, 4 = 0, 14m$$

$$N_1=rac{x_1}{\lambda}=rac{0,14}{0.08}=rac{14}{8}=rac{7}{4}$$
 μήκη κύματος

ή

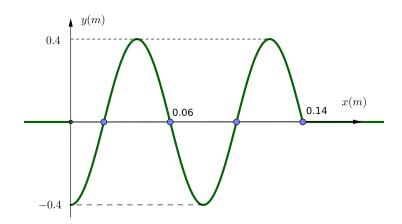
$$t_1=0 \implies \frac{5\pi\cdot 1, 4}{2} - 25\pi x_1 = 0 \implies x_1=0, 14m$$

$$y_0 = 0, 4\eta\mu(3, 5\pi) = -0, 4m$$

$$y_{t_1} = \begin{cases} 0, 4\eta\mu \left(\frac{5\pi t}{2} - 25\pi x\right), & 0 \leq x \leq 0, 14m \\ 0, & 0, 14m < x \end{cases}$$

Γ3.  $A\Delta E_{\tau\alpha\lambda}$  για  $\Delta m$ 

$$\begin{split} E_T &= K + U \implies E_T = K + \frac{1}{2} D y^2 \stackrel{y = \frac{A}{2}}{\implies} E_T = K + \frac{1}{2} D \frac{A^2}{4} \implies \\ E_T &= K + \frac{1}{4} E_T \implies K = \frac{3}{4} E_T = \frac{3}{4} 5 \pi^2 10^{-7} = \frac{3 \pi^2}{8} 10^{-6} J \end{split}$$



$$y = A\eta\mu\varphi = \frac{A}{2} \implies \eta\mu\varphi = \frac{1}{2} \implies \varphi = \begin{cases} 2k\pi + \frac{\pi}{6} & (1) \\ 2k\pi + \frac{5\pi}{6} & (2) \end{cases}$$

$$v = \omega A \sigma v \nu \varphi = \begin{cases} = \omega A \sigma v \nu \left( 2k\pi + \frac{\pi}{6} \right) = \frac{\omega A \sqrt{3}}{2} \\ \omega A \sigma v \nu \left( 2k\pi + \frac{5\pi}{6} \right) = -\frac{\omega A \sqrt{3}}{2} \end{cases}$$

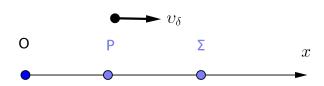
$$K = \frac{1}{2} \Delta m \cdot v^2 = \frac{1}{2} \Delta m \left( \pm \frac{\omega A \sqrt{3}}{2} \right)^2 = \frac{1}{2} \Delta m \cdot \frac{\omega^2 A^2 3}{4} = \frac{3}{4} \cdot \frac{1}{2} D \cdot A^2 = \frac{3}{4} E_T$$

Γ4.

$$\varphi_{\mathrm{P}}-\varphi_{\Sigma}=\frac{3\pi}{2}rad, (\varphi_{\mathrm{P}}>\varphi_{\Sigma})$$

$$\left. \begin{array}{l} y_{\mathrm{P}} = 0, 4m = A \\ y_{\mathrm{P}} = A \eta \mu \varphi_{\mathrm{P}} \end{array} \right\} \eta \mu \varphi_{\mathrm{P}} = 1 \implies \varphi_{\mathrm{P}} = 2k\pi + \frac{\pi}{2}, k = 0, 1, 2, \dots$$

$$2k\pi + \frac{\pi}{2} - \varphi_{\Sigma} = \frac{3\pi}{2} \implies \varphi_{\Sigma} = 2k\pi - \pi$$

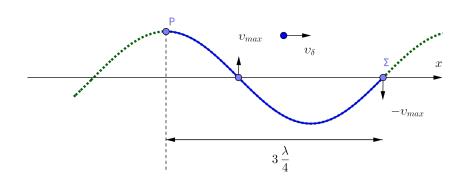


Άρα

$$v_{\Sigma} = \frac{5\pi}{2} \cdot 0, 4 \cdot \sigma v \nu \left(2k\pi - \pi\right) \implies v_{\Sigma} = -\pi \frac{m}{s}$$

ή

$$\begin{split} \varphi_{\mathrm{P}} - \Phi_{\Sigma} &= \frac{3\pi}{2} \implies \\ \frac{5\pi t}{2} - 25\pi x_{\mathrm{P}} - \left(\frac{5\pi t}{2} - 25\pi x_{\Sigma}\right) = \frac{3\pi}{2} \implies x_{\Sigma} - x_{\mathrm{P}} = \frac{3}{50} \\ \frac{2\pi t}{T} - \frac{2\pi x_{\mathrm{P}}}{\lambda} - \left(\frac{2\pi t}{T} - \frac{2\pi x_{\Sigma}}{\lambda}\right) = \frac{3\pi}{2} \implies x_{\Sigma} - x_{\mathrm{P}} = \frac{3\lambda}{4} \end{split} \right\} \implies \frac{3\lambda}{4} = \frac{3}{50} \implies \lambda = 0,08 = \frac{4}{50}m$$



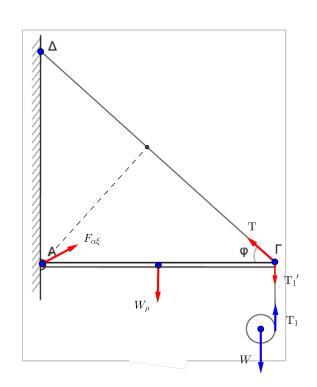
όταν  $y_{\rm P}=A$ ,

$$v_{\Sigma}=-\omega A=-\pi\frac{m}{s}$$

## Θέμα Δ

Δ1.

$$\Sigma F = m \cdot a_m \implies W - T_1 = m \cdot a_m \big\} \, T_1 = \frac{m \cdot a_{cm}}{2}, W = \frac{3m \cdot a_{cm}}{2}$$



$$0 = v_{\Gamma} = v_{Z} = v_{cm} - v_{\gamma \rho_{Z}} \implies v_{cm} = \omega R \implies a_{cm} = a_{\gamma}R \implies a_{cm} = \frac{2}{3}g = \frac{20}{3}\frac{m}{s}$$

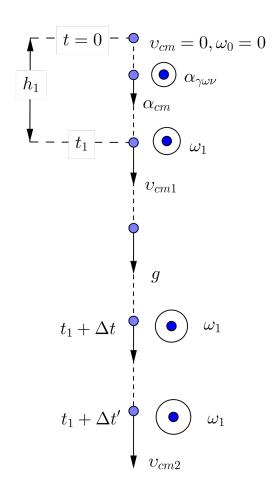
$$T_1' = T_1 = \frac{2 \cdot 20}{2 \cdot 3} = \frac{20}{3}N$$

Δ2. Για τη ράβδο που ισορροπεί:

$$\Sigma_{\tau_{(\mathrm{A})}} = 0 \implies w_{\rho} \cdot \frac{l}{2} + T_{1}^{\prime} \cdot l - T \cdot l \cdot \eta \mu \varphi = 0 \implies T = \frac{100}{3} N$$

Δ3. Την  $t_1$ ,  $h_1 = 0, 3m$ 

$$h_1 = \frac{1}{2} a_{cm} t_1^2 \implies 0, 3 = \frac{1}{2} \cdot \frac{20}{3} t_1^2 \implies t_1 = 0, 3s$$



$$a_{\gamma\omega\nu}=\frac{a_{cm}}{R}=\frac{200}{3}r/s^2$$

$$w_1 = a_{\gamma\omega\nu}t_1 = 20r/s$$

 $t \to t_1 + \Delta t$ :

$$\tau_{w_{cm}} = 0 = \frac{\Delta L}{\Delta t} \implies L_{t_1} = L_{t_1 + \Delta_t}$$

Η μόνη δύναμη που ασκείται στο δίσκο είναι το βάρος W.

Όπου

$$L_{t_1} = I \cdot W_1$$

$$I = \frac{1}{2}mp^2 = \frac{1}{2} \cdot 2 \cdot 0, 1^2 = 0,01kgm^2$$

Άρα

$$L_{t_1} = 0.2kg \frac{m^2}{s} = L_{t_1 + \Delta t}$$

ή ΘΜΚΕ $_{(0\to h_1)}:$ 

$$\left.\begin{array}{l} \text{ wet: } \frac{1}{2}mv_{cm}^2-0=W\cdot h_1-T_1\cdot h_1\\ \text{ stp: } \frac{1}{2}I\omega^2-0=+(T_1\cdot R)\cdot \theta_1\\ v_{cm}=\omega_1\cdot R\\ x_{cm}=\theta\cdot R \implies h_1=\theta_1\cdot R \end{array}\right\} \Longrightarrow\\ \frac{1}{2}mv_{cm}^2+\frac{1}{2}I\omega_1^2=mgh_1 \implies\\ \frac{1}{2}v_{cm}^2+\frac{1}{4}\cdot v_{cm}^2=gh_1 \implies v_{cm}^2=\frac{4gh_1}{3} \implies v_{cm}=2m/s \implies \omega_1=20r/s \implies\\ L_{t_1}=I\omega_1=0,2kg\frac{m^2}{s} \end{array}$$

Η δύναμη  $T_1$  δε μετατοπίζει το σημείο εφαρμογής της, αφού κάθε στιγμή ασκείται σε διαφορετικό σημείο του δίσκου, λειτουργεί δηλαδή όπως η στατική τριβή στη Κ.Χ.Ο. Επομένως η μηχανική ενέργεια του δίσκου διατηρείται.

 $A\Delta ME_{(0,h_1)}:$ 

$$\begin{split} K_{(0)} + U_{(0)} &= K_{(t_1)} + U_{(t_1)} \\ 0 + mgh_1 &= \left(\frac{1}{2}mv_{cm}^2 + \frac{1}{2}I\omega_1^2\right) + 0 \\ K_{\sigma\tau\rho} &= \frac{1}{2}I\omega_1^2 \\ L &= I\omega \end{split} \right\} K_{\sigma\tau\rho} = \frac{L^2}{2I} \end{split}$$

$$\begin{split} mgh_1 &= \frac{1}{2} m \omega^2 R^2 + \frac{1}{2} I \omega^2 \\ mgh_1 &= I \omega^2 + \frac{1}{2} I \omega^2 = 3 \cdot \frac{1}{2} I \omega^2 \\ mgh_1 &= 3K_{(\sigma\tau\rho)} = \frac{3L^2}{2I} \\ 9 \cdot 10 \cdot 0, 3 &= \frac{3L_{t_1}^2}{2 \cdot 0, 01} \implies L_{t_1} = 0, 2kg \frac{m^2}{s} \end{split}$$

 $\Delta 3. \ t_2 = t_1 + \Delta t'$ 

$$\frac{K_{\sigma\tau\rho(t_2)}}{K_{\mu\varepsilon\tau(t_2)}} = \frac{\frac{1}{2}I\omega_2^2}{\frac{1}{2}mv_{cm_2}^2}$$

 $t_1 = t_2$ :

$$\begin{split} \Sigma \tau_{cm} &= 0 \implies \omega_2 = \omega_1 = 20 r/s \\ \Sigma F &= m \cdot a_{cm} \implies W = m \cdot a_{cm} \implies a_{cm} = g = 10 m/s^2 \\ v_{cm_2} &= v_{cm_1} + g \cdot \Delta t' = 2 + 10 \cdot 0, 1 = 3 m/s \end{split}$$

$$\begin{split} \frac{K_{\pi\varepsilon\rho}}{K_{\mu\varepsilon\tau}} &= \frac{\frac{1}{2}I\omega^2}{\frac{1}{2}mv^2} = \frac{\frac{1}{2}mR^2\omega_2^2}{mv_2^2} = \frac{2}{9}\\ &\qquad \frac{K_{\pi\varepsilon\rho}}{K_{\mu\varepsilon\tau}} = \frac{2}{9} \end{split}$$