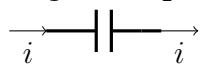
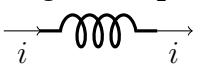
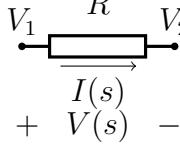
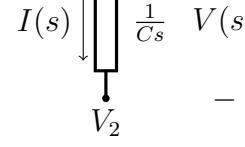
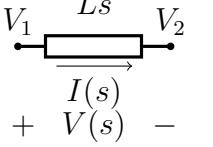
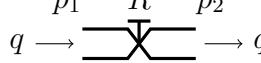
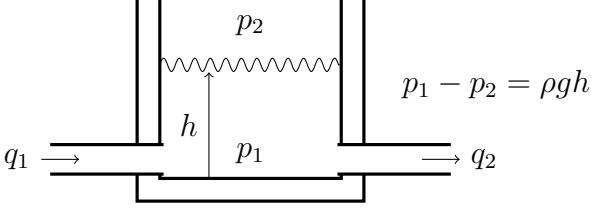
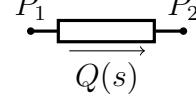
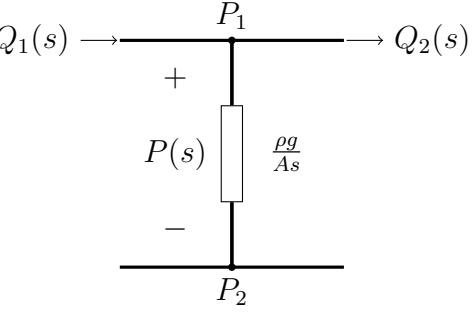


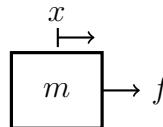
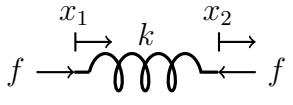
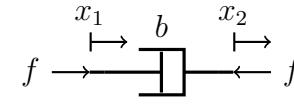
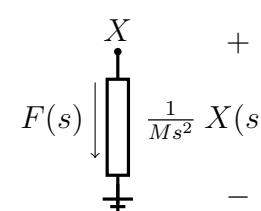
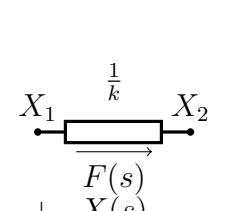
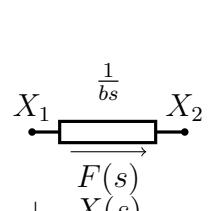
Electrical Impedance

	resistor	capacitor	inductor
Component			
Component law	$v_1 - v_2 = iR$	$i = C \frac{d(v_1 - v_2)}{dt}$	$v_1 - v_2 = L \frac{di}{dt}$
Laplace Transform	$V(s) = I(s)R$	$V(s) = \frac{1}{Cs}I(s)$	$V(s) = LsI(s)$
Impedance Component			

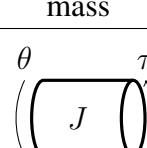
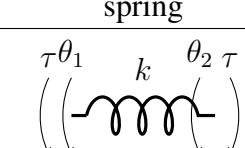
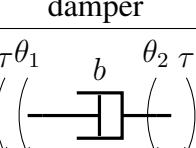
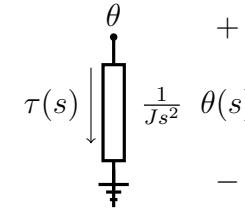
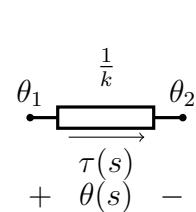
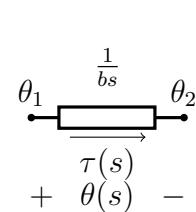
Fluid Impedance

	valve	tank
Component		 Tank Area: A
Component law	$p = p_1 - p_2$	$\frac{A}{\rho g} \frac{dp}{dt} = q_1 - q_2$
Laplace Transform	$P(s) = RQ(s)$	$\frac{A}{\rho g} sP(s) = Q_1(s) - Q_2(s)$
Impedance Component		

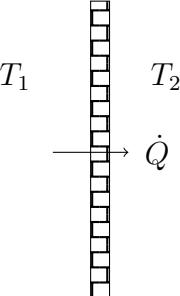
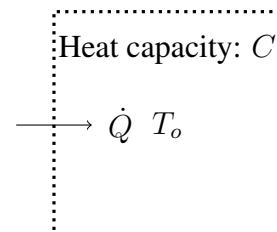
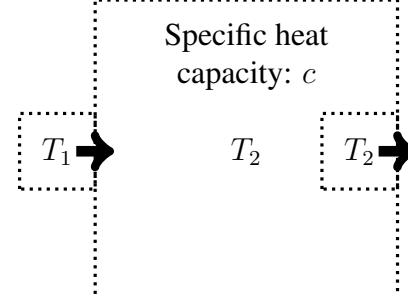
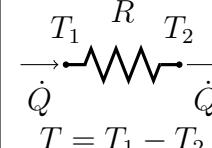
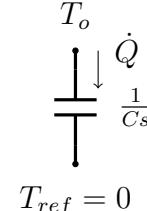
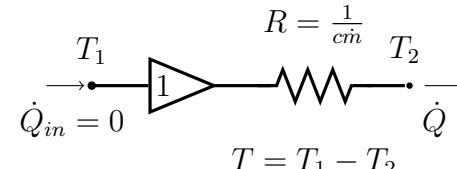
Mechanical Impedance

	mass	spring	damper
Component	 x m f	 x_1 x_2 k f $x = x_1 - x_2$	 x_1 x_2 b f $x = x_1 - x_2$
Component law	$f = m\ddot{x}$	$f = kx$	$f = b\dot{x}$
Laplace Transform	$X(s) = \frac{1}{ms^2}F(s)$	$X(s) = \frac{1}{k}F(s)$	$X(s) = \frac{1}{bs}F(s)$
Impedance Component (positive f direction agrees with positive x direction)	 $F(s)$ X $\frac{1}{Ms^2}$ $X(s)$	 X_1 X_2 $\frac{1}{k}$ $\frac{F(s)}{X(s)}$	 X_1 X_2 $\frac{1}{bs}$ $\frac{F(s)}{X(s)}$

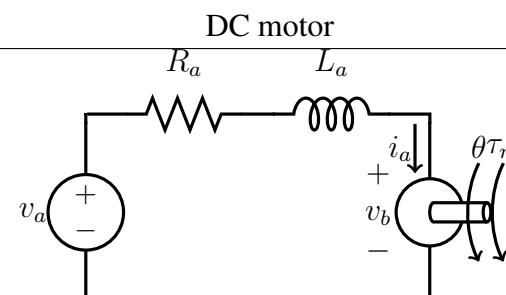
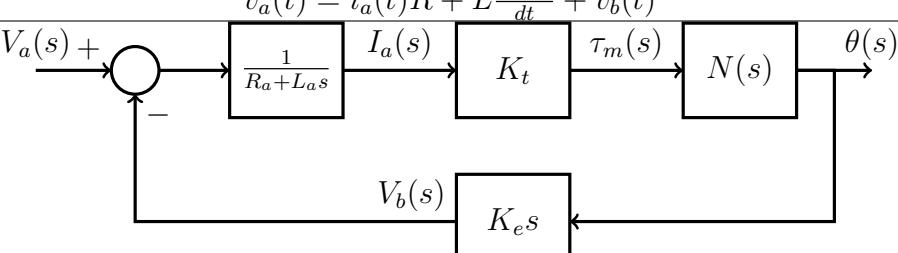
Rotational Impedance

	mass	spring	damper
Component	 θ J τ	 $\tau\theta_1$ k $\theta_2 \tau$	 $\tau\theta_1$ b $\theta_2 \tau$
Component Law	$\tau = J\ddot{\theta}$	$\tau = k\theta$	$\tau = b\dot{\theta}$
Laplace Transform	$\theta(s) = \frac{1}{Js^2}\tau(s)$	$\theta(s) = \frac{1}{k}\tau(s)$	$\theta(s) = \frac{1}{bs}\tau(s)$
Impedance Component	 $\tau(s)$ $\theta(s)$ $\frac{1}{Js^2}$	 θ_1 θ_2 $\frac{1}{k}$ $\frac{\tau(s)}{\theta(s)}$	 θ_1 θ_2 $\frac{1}{bs}$ $\frac{\tau(s)}{\theta(s)}$

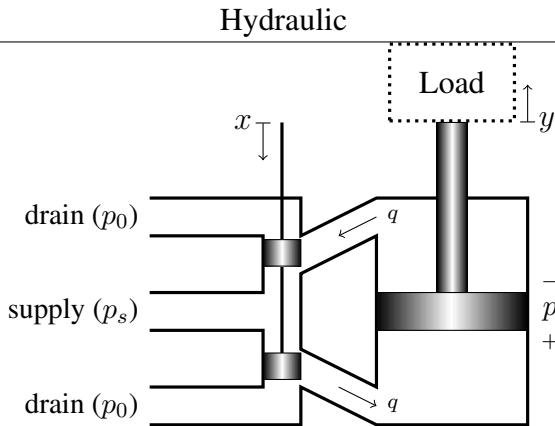
Thermal Impedance

	Resistance	Capacitance	Convection
Component			
Component law	$T = \dot{Q}R$	$\dot{Q} = C \frac{dT_o}{dt}$	$\dot{Q} = \dot{m}cT$
Laplace Transform	$T(s) = \dot{Q}(s)R$	$\dot{Q}(s) = CsT_o(s)$	$\dot{Q}(s) = \dot{m}cT(s)$
Impedance Component	 $T = T_1 - T_2$	 $T_{ref} = 0$	 $R = \frac{1}{\dot{m}c}$ $T = T_1 - T_2$

DC Motor

Component	
Component Law	$v_b = K_e \dot{\theta}$ $\tau_m = K_t i_a$ $v_a(t) = i_a(t)R + L \frac{di_a(t)}{dt} + v_b(t)$
Block Diagram	

Hydraulic



Component	Piston area: A
Component Law	$\delta q = k_x \delta x - k_p \delta p$ $f = pA$ $y = \frac{1}{A} \int q dt$
Block Diagram	