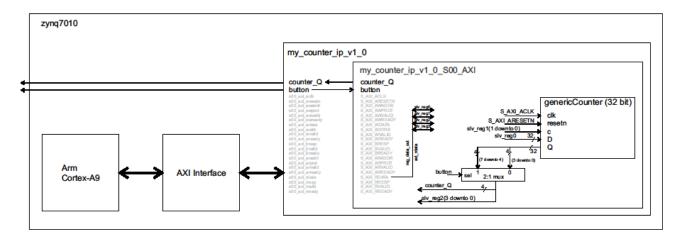
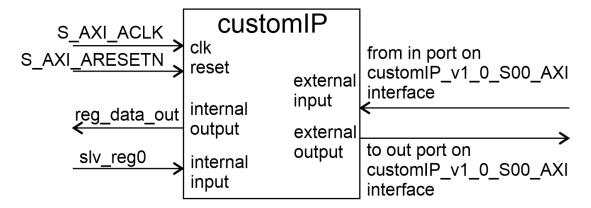
Creating an AXI peripheral.

Our goal will be to connect our custom IP to the Arm Cortex-A9 through the AXI interface. This will create the following architecture



As a first step, you will want to add your custom IP inside the my\_counter\_ip\_v1\_0\_S00\_AXI architecture. Scroll to the bottom of this architecture and find the handy "insert your code here" comments. Paste in your code.

While the genericCounter and mux look familiar, some of the signals look strange. In general terms, your custom IP will get its input from either the Arm Cortex-A9 (internal) or from outside the Zynq chip (external). The same goes for the outputs. Let's examine how to make each of these connections.



Any external inputs or outputs must be added to the my\_counter\_ip\_v1\_0\_S00\_AXI entities port. The red text shows where you should add these external signals.

```
entity my_counter_ip_v1_0_S00_AXI is
      generic (
             -- Width of S AXI data bus
             C_S_AXI_DATA_WIDTH : integer
                                              := 32;
             -- Width of S AXI address bus
             C S AXI ADDR WIDTH : integer
                                               := 4
      );
      port (
             counter Q : out std logic vector(3 downto 0);
                       in std \overline{\log}ic;
             button:
             -- Global Clock Signal
             S AXI ACLK : in std logic;
             -- Global Reset Signal. This Signal is Active LOW
```

You can provide internal inputs directly from the slv\_regx directly. For example, the control and data inputs to the counter. Internal outputs must be assigned a local signal (counter\_Q\_Internal in the counter instantiation) and then use this local signal to replace one of the slv\_reg reference in a process that sits around the middle of the architecture.

```
process (slv reg0, slv reg1, counter Q Internal, slv reg3, axi araddr, S AXI ARESETN,...
variable loc_addr :std_logic_vector(OPT_MEM_ADDR_BITS downto 0);
begin
    -- Address decoding for reading registers
    loc addr := axi araddr(ADDR LSB + OPT MEM ADDR BITS downto ADDR LSB);
    case loc addr is
      when b^{-0}00" =>
        reg_data_out <= slv_reg0;</pre>
      when b"01" =>
       reg data out <= slv reg1;
      when b"10" =>
       reg data out <= counter Q Internal;
      when b"11" =>
       reg data out <= slv reg3;
      when others =>
       reg data out <= (others => '0');
    end case;
end process;
```

Next you need to provide the component declaration for any components you added to inside the my\_counter\_ip\_v1\_0\_S00\_AXI architecture as well as any signals needed to connect the parts of your IP together.

```
architecture arch_imp of my_counter_ip_v1_0_S00_AXI is

component genericCounter is
    generic(N: integer:=4);
    port(    clk,resetn : in std_logic;
        c: in STD_LOGIC_VECTOR(1 downto 0);
        d : in STD_LOGIC_VECTOR(N-1 downto 0);
        q : out STD_LOGIC_VECTOR(N-1 downto 0));
end component;
signal counter_Q_Internal: std_logic_vector(31 downto 0);

-- AXI4LITE signals
    signal axi_awaddr : std_logic_vector(C_S_AXI_ADDR_WIDTH-1 downto 0);
```

You are done with my\_counter\_ip\_v1\_0\_S00\_AXI. Now let's look at the my\_counter\_ip\_v1\_0 component which wraps everything up and will interface with the AXI bus.

Start by adding the external inputs or outputs from the my\_counter\_ip\_v1\_0\_S00\_AXI entities to the my\_counter\_ip\_v1\_0 component entity port. The red text shows where you should add these external signals.

```
entity my counter ip v1 0 is
      generic (
             C S00 AXI DATA WIDTH
                                                 := 32;
                                     : integer
             C_S00_AXI_ADDR_WIDTH
                                      : integer
                                                   := 4
      ) ;
      port (
             -- Users to add ports here
             counter Q : out std logic vector(3 downto 0);
             button: in std logic;
             -- User ports ends
             -- Do not modify the ports beyond this line
             -- Ports of Axi Slave Bus Interface S00 AXI
```

Next you need to edit the component declaration of the my\_counter\_ip\_v1\_0\_S00\_AXI entity to include the external input and output ports that you added in the previous step. Scroll down and find the my\_counter\_ip\_v1\_0\_S00\_AXI component declaration and add the red text.

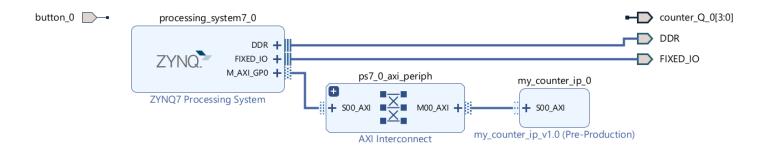
```
-- component declaration
component my_counter_ip_v1_0_S00_AXI is
    generic (
        C_S_AXI_DATA_WIDTH : integer := 32;
        C_S_AXI_ADDR_WIDTH : integer := 4
    );
    port (
        counter_Q : out std_logic_vector(3 downto 0);
        button: in std_logic;
        S_AXI_ACLK : in std_logic;
        S_AXI_ARESETN: in std_logic;
```

Finally, you need to connect the external ports on my\_counter\_ip\_v1\_0\_S00\_AXI entity to the external ports on the my\_counter\_ip\_v1\_0\_S00\_AXI entity.

If you followed all these steps correctly, your custom IP should now have a block diagram that looks like this.



You will then take your custom IP and connect it the Arm Cortex-A9 through the AXI interconnect.



You will need to specify the pin assignment for the button\_0 and counter\_Q\_0