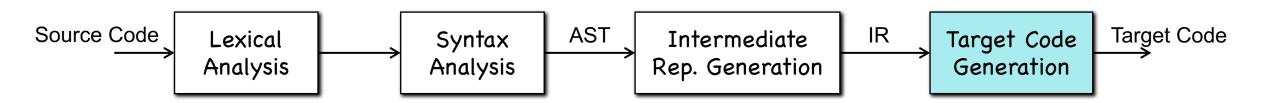


# Chapter 10 Instruction Scheduling

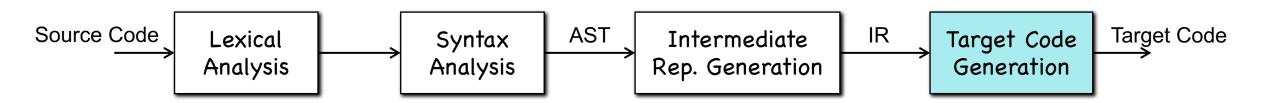
Qingkai Shi qingkaishi@nju.edu.cn





Can we generate code to leverage modern CPUs for better instruction-level parallelization?





- Every modern high-performance processor can execute several operations in a single clock cycle.
- Billion-Dollar Question: how fast can a program be run on a processor with instruction-level parallelism?

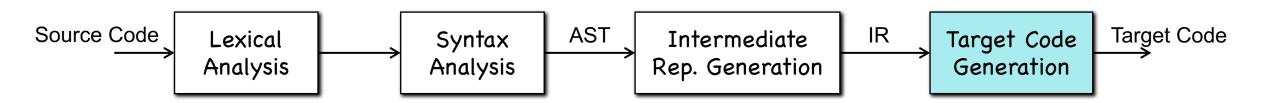
The potential parallelism in the program

The available parallelism on the processor

Our ability to extract parallelism from the code

Our ability to find the best scheduling





- Every modern high-performance processor can execute several operations in a single clock cycle.
- Billion-Dollar Question: how fast can a program be run on a processor with instruction-level parallelism?

The potential parallelism in the program

The available parallelism on the processor

Our ability to extract parallelism from the code

Our ability to find the best scheduling



Instruction pipelines

```
\mathbf{IF}
         ID
                          \operatorname{IF}
         EX
                          ID
                                           \operatorname{IF}
         MEM
                          \mathbf{E}\mathbf{X}
                                           ID
                                                            \operatorname{IF}
                          MEM
                                           \mathbf{E}\mathbf{X}
                                                             ID
         WB
                                                                              \operatorname{IF}
6.
                                           MEM
                          WB
                                                             \mathbf{E}\mathbf{X}
                                                                              ID
                                            WB
                                                             MEM
                                                                              \mathbf{E}\mathbf{X}
8.
                                                                              MEM
                                                             WB
                                                                              WB
9.
```



Instruction pipelines

```
IF
       ID
                       \operatorname{IF}
       EX
                       ID
                                      \operatorname{IF}
        MEM
                       EX
                                      ID
                                                     \operatorname{IF}
5.
                       MEM
                                      \mathbf{E}\mathbf{X}
                                                     ID
        WB
                                                                    \operatorname{IF}
6.
                       WB
                                      MEM
                                                     \mathbf{E}\mathbf{X}
                                                                    ID
                                      WB
                                                     MEM
                                                                     \mathbf{E}\mathbf{X}
8.
                                                                     MEM
                                                     WB
                                                                     WB
9.
```



Instruction pipelines

1.	$\operatorname{IF}$				
2.	ID	$\mathbf{IF}$			
3.	$\mathbf{E}\mathbf{X}$	ID	$\operatorname{IF}$		
4.	MEM	$\mathbf{E}\mathbf{X}$	$\operatorname{ID}$	$\operatorname{IF}$	
5.	WB	MEM	$\mathbf{E}\mathbf{X}$	ID	IF
6.		WB	MEM	$\mathbf{E}\mathbf{X}$	ID
7.			WB	MEM	$\mathbf{E}\mathbf{X}$
8.				WB	MEM
9.					WB



• Instruction pipelines Note: an instruction may not contain all five phases

1.	IF				
2.	ID	$\operatorname{IF}$			
3.	$\mathbf{E}\mathbf{X}$	ID	$\operatorname{IF}$		
4.	MEM	$\mathbf{E}\mathbf{X}$	$\operatorname{ID}$	$\operatorname{IF}$	
5.	WB	MEM	EX	ID	IF
6.		WB	MEM	$\mathbf{E}\mathbf{X}$	ID
7.			WB	MEM	$\mathbf{E}\mathbf{X}$
8.				WB	MEM
9.					WB



- Machine types
  - VLIW (Very long instruction machine) machine
    - Instruction words are longer, encode the operations to be issued in a single clock
    - Compilers decide which operations are scheduled in parallel by encoding such info into the instructions



- Machine types
  - VLIW (Very long instruction machine) machine
  - Superscalar machine
    - Regular instruction set with an ordinary sequential-execution semantics
    - Automatically detect dependencies and issue them in parallel

```
1. IF
2. ID IF
3. EX ID IF
4. MEM EX ID IF
5. WB MEM EX ID IF
6. WB MEM EX ID
7. WB MEM EX
8. WB MEM
9. WB WB
```



- Machine types
  - VLIW (Very long instruction machine) machine
  - Superscalar machine
  - "Out-of-order" machine
    - Automatically issue as many instructions as possible
    - Stop them until all operands are ready



- Machine types
  - VLIW (Very long instruction machine) machine
  - Superscalar machine
  - "Out-of-order" machine
- Why compilers matter?



- Machine types
  - VLIW (Very long instruction machine) machine
  - Superscalar machine
  - "Out-of-order" machine
- Why compilers matter?
  - Hardware only can execute instructions that have been fetched



- Machine types
  - VLIW (Very long instruction machine) machine
  - Superscalar machine
  - "Out-of-order" machine

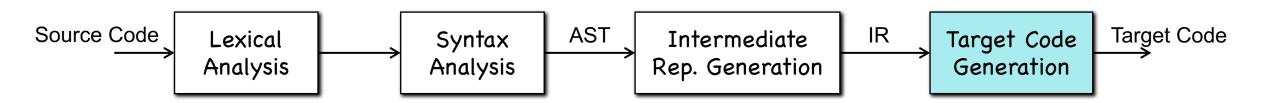
- Why compilers matter?
  - Hardware only can execute instructions that have been fetched
  - Hardware has limited space to buffer operations that must be stalled



- Machine types
  - VLIW (Very long instruction machine) machine
  - Superscalar machine
  - "Out-of-order" machine

- Why compilers matter?
  - Hardware only can execute instructions that have been fetched
  - Hardware has limited space to buffer operations that must be stalled
  - Compilers can place independent operations close together to allow better hardware utilization





- Every modern high-performance processor can execute several operations in a single clock cycle.
- Billion-Dollar Question: how fast can a program be run on a processor with instruction-level parallelism?

The potential parallelism in the program

The available parallelism on the processor

Our ability to extract parallelism from the code

Our ability to find the best scheduling



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

$$a = 2 * a * b * c$$



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	

$$a = 2 * a * b * c$$



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

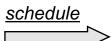


#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

a = 2 \* a \* b \* c



1	LD	R1,	a	•••••
2				
3				R1 ready
4				
- 5				
6				
7				
8				
9				
10				
11				
12				
13				
14				
15				
16				



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; Al

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

schedule

a =	2	*	а	*	b	*	C
-----	---	---	---	---	---	---	---

1	LD	R1,	а		
2					
3					R1 ready
4	ADD	R1,	R1,	R1	R1 ready
5					
6					
7					
8					
9					
10					
11					
12					
13					
14					
15					
16					

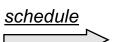


#### Example: Superscalar maching

LD/ST 3 cycles; MUL 2 cycles; Al

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

a = 2 \* a \* b \* c



1	LD	R1,	а		
2					
3					R1 ready
4	ADD	R1,	R1,	R1	R1 ready
5	LD	R2,	b		R1 ready
6					R1 ready
7					R1/R2 ready
8					
9					
10					
11					
12					
13					
14					
15					
16					



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; Al

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

a = 2 \* a \* b \* c

schedule

2		
3		R1 ready
4	ADD R1, R1, R1	R1 ready
- 5	LD R2, b	R1 ready
6		R1 ready
7		R1/R2 ready
8	MUL R1, R1, R2	R2 ready
9	Next op does not use	R1!
10		
11		
12		
13		
14		
15		
16		

R1, a



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	

<u>schedule</u>

1	LD	R1,	a		•••••
2					
3					R1 ready
4	ADD	R1,	R1,	R1	R1 ready
5	LD	R2,	b		R1 ready
6					R1 ready
7					R1/R2 ready
8	MUL	R1,	R1,	R2	R2 ready
9	LD	R2,	С		R1 ready
10					R1 ready
11					R1/R2 ready
12					
13					
14					
15					
16					



R1 ready

R1 ready

R1 ready

## Instruction Sche

#### • Example: Superscalar machi 4

• LD/ST 3 cycles: MUL 2 cycles: Al

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	

a

ED/OT 5 Cycles, MOL	2 0y0100, 7 ti	6					R1 ready
	1	7					R1/R2 ready
LD R1, a	schedule	8	MUL	R1,	R1,	R2	R2 ready
ADD R1, R1, R1		9	LD	R2,	С		R1 ready
LD R2, b	<u>schedule</u>	10					R1 ready
MUL R1, R1, R2		11					R1/R2 ready
LD R2, c		12	MUL	R1,	R1,	R2	R2 ready
MUL R1, R1, R2		13					R1/R2 ready
ST a, R1		14					_
a = 2 * a * b * c		15					
		16					
		<u> </u>					

LD

ADD

LD

R1, a

R2, b

R1, R1, R1



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

<u>schedule</u>

1	LD	R1,	a		•••••
2					
3					R1 ready
4	ADD	R1,	R1,	R1	R1 ready
5	LD	R2,	b		R1 ready
6					R1 ready
7					R1/R2 ready
8	MUL	R1,	R1,	R2	R2 ready
9	LD	R2,	С		R1 ready
10					R1 ready
11					R1/R2 ready
12	MUL	R1,	R1,	R2	R2 ready
13					R1/R2 ready
14	ST	а,	R1		
15					
16					Done!

a = 2 \* a \* b \* c



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; Al

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

<u>schedule</u>

2					•••••
3					R1 ready
4	ADD	R1,	R1,	R1	R1 ready
5	LD	R2,	b		R1 ready
6					R1 ready
7					R1/R2 ready
8	MUL	R1,	R1,	R2	R2 ready
9	LD	R2,	С		R1 ready
10					R1 ready
11					R1/R2 ready
12	MUL	R1,	R1,	R2	R2 ready
13					R1/R2 ready
14	ST	а,	R1		
15					
16					Done!

LD

R1, a

a = 2 \* a \* b \* c



Can a compiler generate better code?



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	



- Example: Superscalar machine (1 functional unit)
  - LD/ST 3 cycles; MUL 2 cycles; ADD 1 cycle

LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	

LD	R1,	a		
LD	R2,	b		
LD	<u>R3</u> ,	С		
ADD	R1,	R1,	R1	
MUL	R1,	R1,	R2	
MUL	R1,	R1,	R3	
ST	a,	R1		-

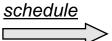
$$a = 2 * a * b * c$$



- Example: Superscalar machin
  - LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

a = 2 \* a \* b \* c



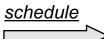
1	LD	R1,	а	•••••
2				
3				R1 ready
4				
5				
6				
7				
8				
9				
10				
11				
12				
13				
14				
<b>1</b> 5				
16				



- Example: Superscalar machin
  - LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	a	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

a = 2 \* a \* b \* c



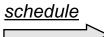
1	LD	R1,	а	•••••
2				
3				R1 ready
4				
5				
6				
7				
8				
9				
10				
11				
12				
13				
14				
15				
16				



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а		
LD	R2,	b		
LD	R3,	С		
ADD	R1,	R1,	R1	
MUL	R1,	R1,	R2	
MUL	R1,	R1,	R3	
ST	a,	R1		



1	LD	R1,	a	
2	LD	R2,	b	
3				R1 ready
4				R1/R2 ready
5				
6				
7				
8				
9				
10				
11				
12				
13				
14				
15				
16				

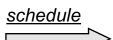


#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

a = 2 \* a \* b \* c



1	LD	R1,	a	
2	LD	R2,	b	
3	LD	R3,	С	R1 ready
4				R1/R2 ready
5				R1/R2/R3 ready
6				
7				
8				
9				
10				
11				
12				
13				
14				
15				
16				

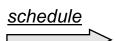


#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

a = 2 \* a \* b \* c



1	LD	R1,	a		
2	LD	R2,	b		
3	LD	R3,	С		R1 ready
4	ADD	R1,	R1,	R1	R1/R2 ready
5					R1/R2/R3 ready
6					
7					
8					
9					
10					
11					
12					
13					
14					
15					
16					

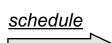


#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

a = 2 \* a \* b \* c



LD	R1,	a		•••••
LD	R2,	b		
LD	R3,	С		R1 ready
ADD	R1,	R1,	R1	R1/R2 ready
MUL	R1,	R1,	R2	R2/R3 ready
				R1/R2/R3 ready
	LD LD ADD	LD R2, LD R3, ADD R1,	LD R2, b  LD R3, c  ADD R1, R1,	LD R2, b  LD R3, c  ADD R1, R1, R1



#### Example: Superscalar machi

LD/ST 3 cycles; MUL 2 cycles; Al

LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

a = 2 \* a \* b \* c

	3	LD	R3,	С		R1 ready
ar machii	4	ADD	R1,	R1,	R1	R1/R2 ready
2 cycles; Al	5	MUL	R1,	R1,	R2	R2/R3 ready
2 Oy 0100, 7 (1	6					R1/R2/R3 ready
	7	MUL	R1,	R1,	R3	R2/R3 ready
	8					R1/R2/R3 ready
	9					
<u>schedule</u>	10					
	11					
	12					
	13					
	14					
	15					
	16					

R1,

R2,



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

schedule \_\_\_\_\_

2	LD	R2,	b		
3	LD	R3,	С		R1 ready
4	ADD	R1,	R1,	R1	R1/R2 ready
5	MUL	R1,	R1,	R2	R2/R3 ready
6					R1/R2/R3 ready
7	MUL	R1,	R1,	R3	R2/R3 ready
8					R1/R2/R3 ready
9	ST	a,	R1		
10					
11					Done!
12					
13					
14					
15					
16					

R1,



#### Example: Superscalar machin

LD/ST 3 cycles; MUL 2 cycles; AL

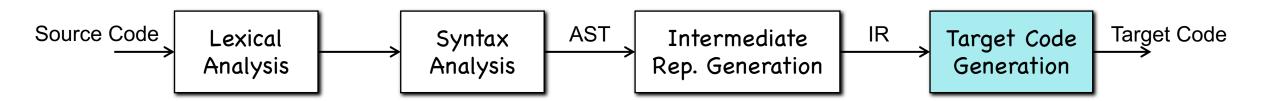
LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
MUL	R1,	R1,	R3
ST	a,	R1	

schedule

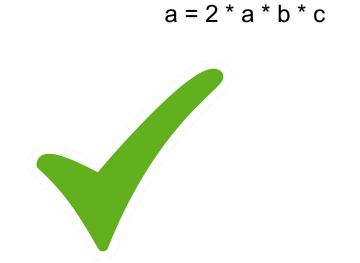
а	=	2	*	а	*	b	*	(

1	LD	R1,	a		
2	LD	R2,	b		•••••
3	LD	R3,	С		R1 ready
4	ADD	R1,	R1,	R1	R1/R2 ready
- 5	MUL	R1,	R1,	R2	R2/R3 ready
6					R1/R2/R3 ready
7	MUL	R1,	R1,	R3	R2/R3 ready
8					R1/R2/R3 ready
9	ST	а,	R1		
10					•••••
11					Done!
12					
13					
14				>><	
15			/		
16					

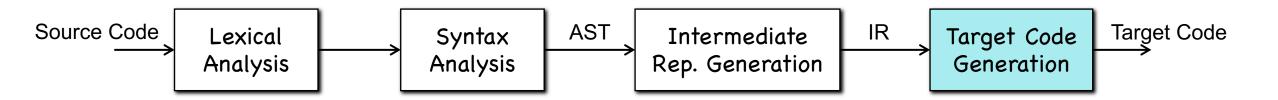




LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	



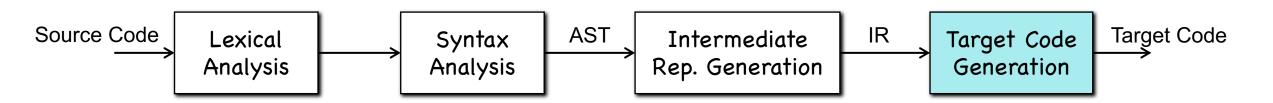




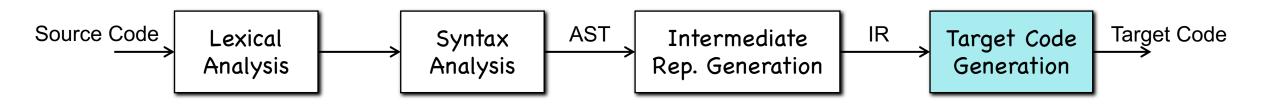
LD	R1,	а		
ADD	R1,	R1,	R1	
LD	R2,	b		
MUL	R1,	R1,	R2	
LD	R2,	С		
MUL	R1,	R1,	R2	
ST	a,	R1		











- 1. Scheduling constraints
- 2. Basic block scheduling → 3. Global scheduling
- 4. Software pipelining (optional)



### **PART I: Scheduling Constraints**



# Performance is Order Dependent

LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	



# Performance is Order Dependent

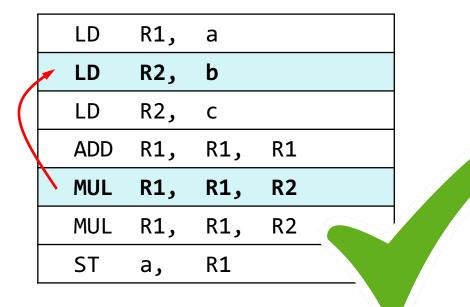
LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	

LD	R1,	a		
LD	R2,	b		
LD	R3,	С		
ADD	R1,	R1,	R1	
MUL	R1,	R1,	R2	
MUL	R1,	R1,	R3	
ST	а,	R1		



True Dependence (Read-After-Write Dependence)

	LD	R1,	a	
	ADD	R1,	R1,	R1
	LD	R2,	b	
1	MUL	R1,	R1,	R2
	LD	R2,	С	
	MUL	R1,	R1,	R2
	ST	a,	R1	





- Storage (Not True) Dependence --- Rename to Remove
  - Antidependence & Output dependence



- Storage (Not True) Dependence --- Rename to Remove
  - Antidependence (Write-After-Read) & Output dependence

	LD	R1,	a	
	ADD	R1,	R1,	R1
	LD	R2,	b	
	MUL	R1,	R1,	<u>R2</u>
1	LD	<u>R2</u> ,	С	
	MUL	R1,	R1,	R2
	ST	a,	R1	

	LD	R1,	а		
	LD	R2,	b		
	LD	<u>R3</u> ,	С		
	ADD	R1,	R1,	R1	
	MUL	R1,	R1,	<u>R2</u>	
	MUL	R1,	R1,	R3	
	ST	а,	R1		
					7/



- Storage (Not True) Dependence --- Rename to Remove
  - Antidependence & Output dependence (Write-After-Write)

LD	R1,	a	
ADD	R1,	R1,	R1
LD	<u>R2</u> ,	b	
MUL	R1,	R1,	R2
LD	<u>R2</u> ,	С	
MUL	R1,	R1,	R2
ST	a,	R1	
	ADD LD MUL LD MUL	ADD R1,  LD R2,  MUL R1,  LD R2,  MUL R1,	ADD R1, R1,  LD R2, b  MUL R1, R1,  LD R2, c  MUL R1, R1,

					_
	LD	R1,	a		
_	LD	<u>R2</u> ,	b		
	LD	<u>R3</u> ,	С		
	ADD	R1,	R1,	R1	
	MUL	R1,	R1,	R2	
	MUL	R1,	R1,	R3	
	ST	a,	R1		



Independent instructions can be scheduled in parallel



Independent instructions can be scheduled in parallel

We can remove not-true-dependence by renaming registers



Independent instructions can be scheduled in parallel

We can remove not-true-dependence by renaming registers

• However, ...



Independent instructions can be scheduled in parallel

We can remove not-true-dependence by renaming registers

However, # registers is limited! (Recall register allocation)



- Which should we do first?
- Register Allocation: Designed to use fewer registers
- Instruction Scheduling: Designed to use more registers





- Which should we do first?
- Register Allocation: Designed to use fewer registers
- Instruction Scheduling: Designed to use more registers



- It's a tough question! It depends on applications.
- Multi-objective optimization <a href="https://en.wikipedia.org/wiki/Multi-objective\_optimization">https://en.wikipedia.org/wiki/Multi-objective\_optimization</a>



# PART II: Basic Block Scheduling



Node: Instructions

Edge: True Dependence (What is a true dependence?)

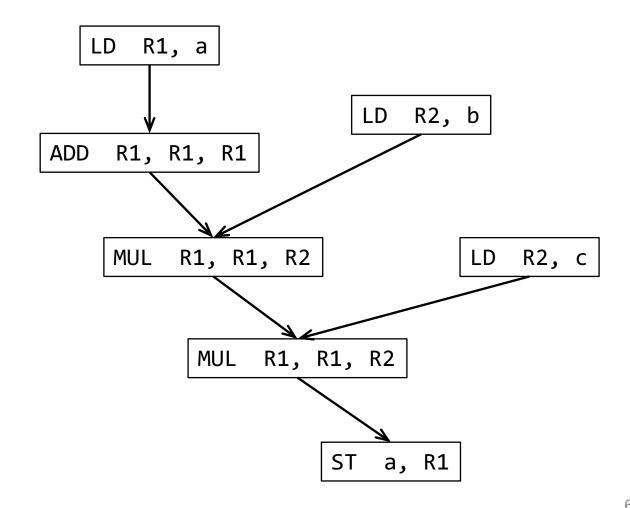


Node: Instructions

• Edge: True Dependence (Read-After-Write Dependence)

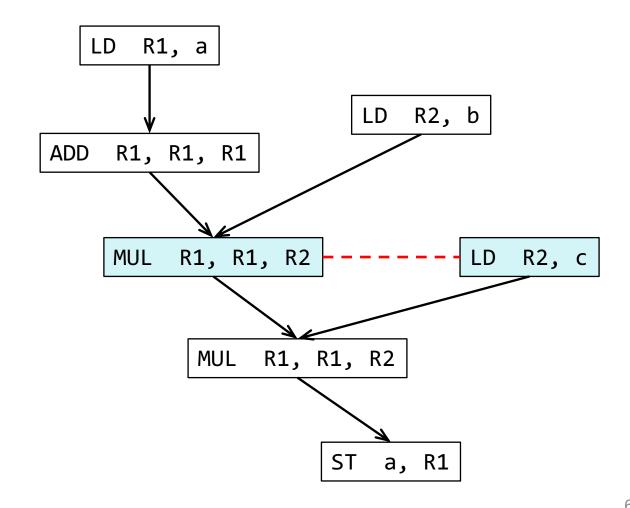


LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	a,	R1	



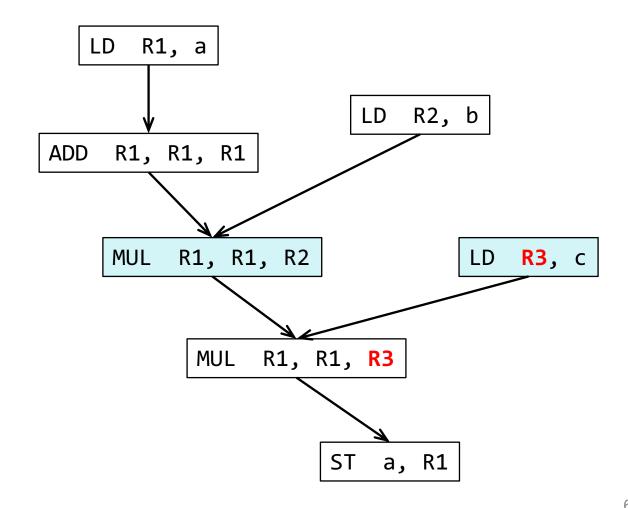


LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R2,	С	
MUL	R1,	R1,	R2
ST	а,	R1	



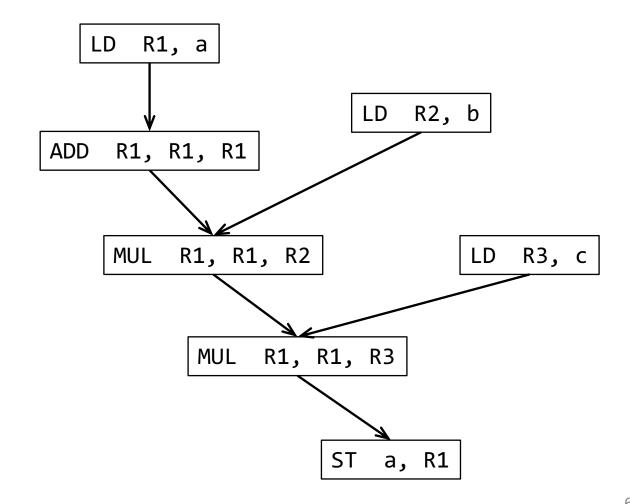


LD	D1		
LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	



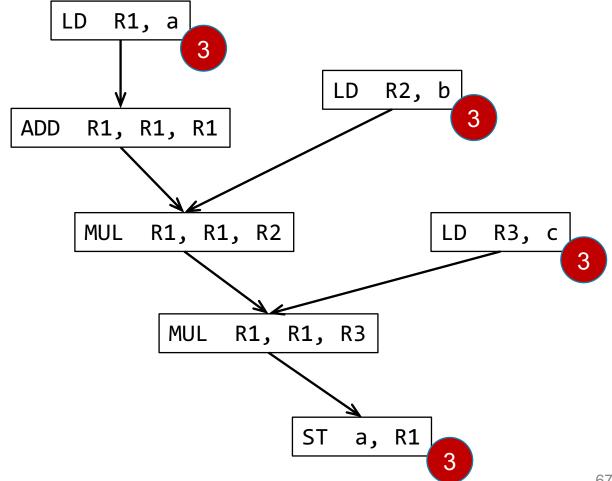


LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	



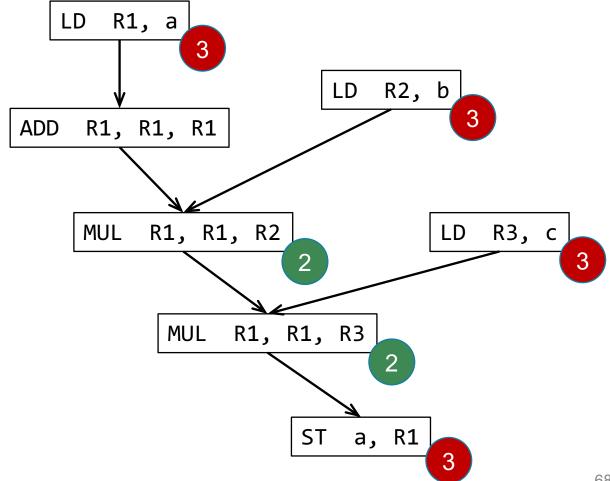


LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	



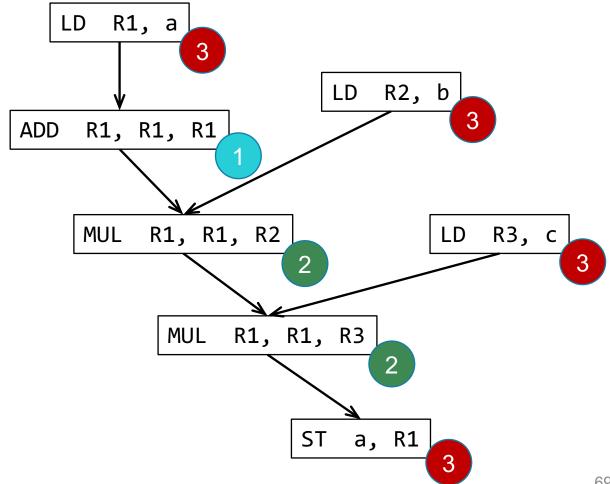


LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	



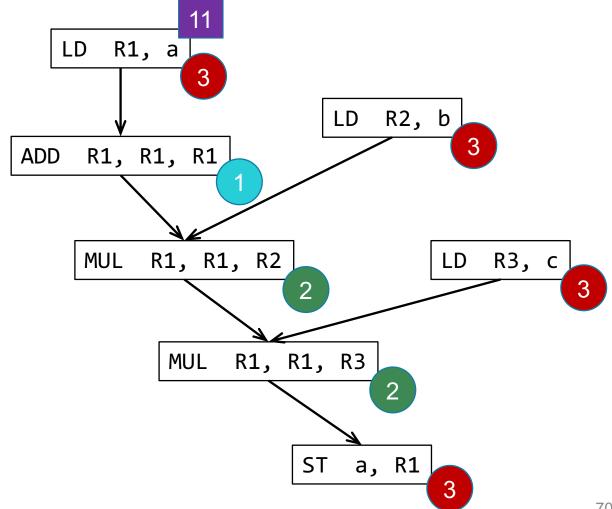


LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	



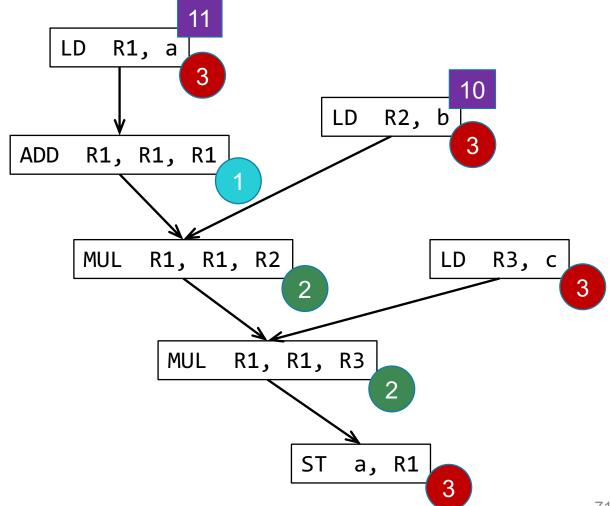


LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	



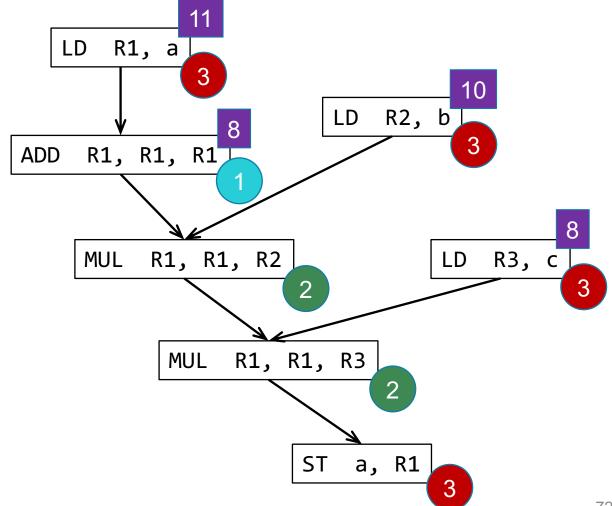


LD	R1,	а	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	





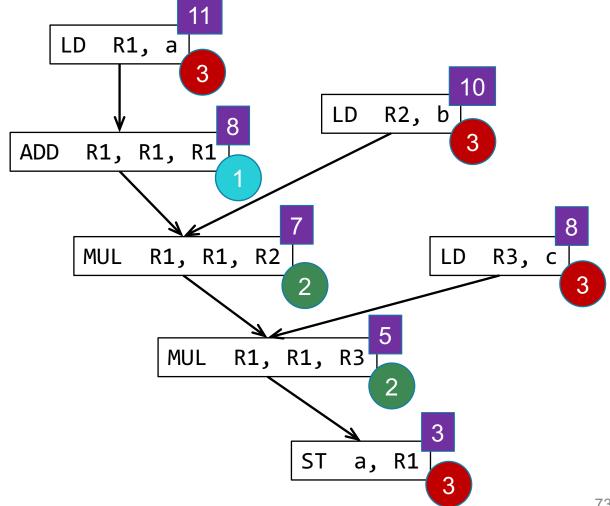
LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	а,	R1	





#### Dependence Graph

LD	R1,	a	
ADD	R1,	R1,	R1
LD	R2,	b	
MUL	R1,	R1,	R2
LD	R3,	С	
MUL	R1,	R1,	R3
ST	a,	R1	





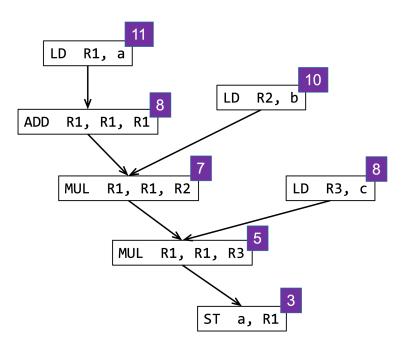
- Check each clock cycle
- Schedule instructions when they are ready



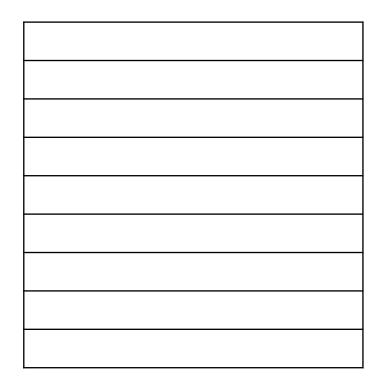
- Check each clock cycle
- Schedule instructions when they are ready
- When multi instructions can be scheduled, check their priority

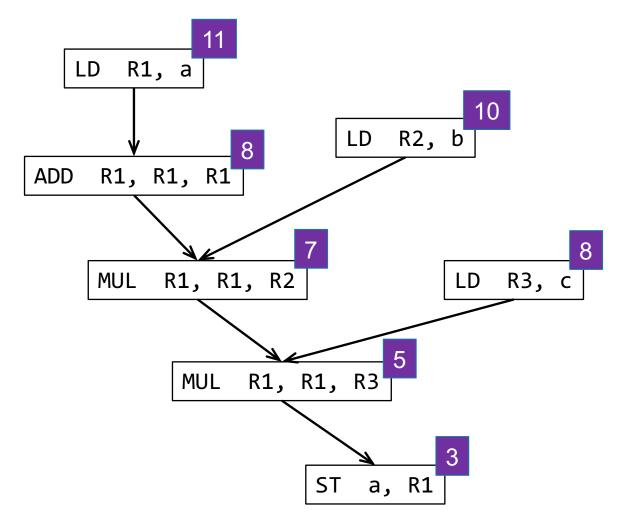


- Check each clock cycle
- Schedule instructions when they are ready
- When multi instructions can be scheduled, check their priority
  - The longest latency path
  - Using the most resources
  - . . .

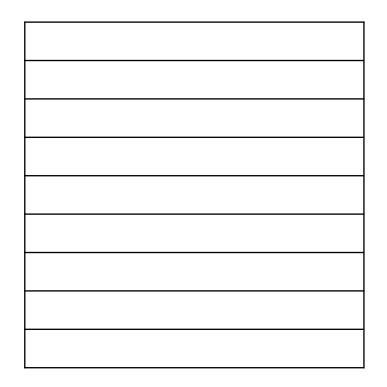


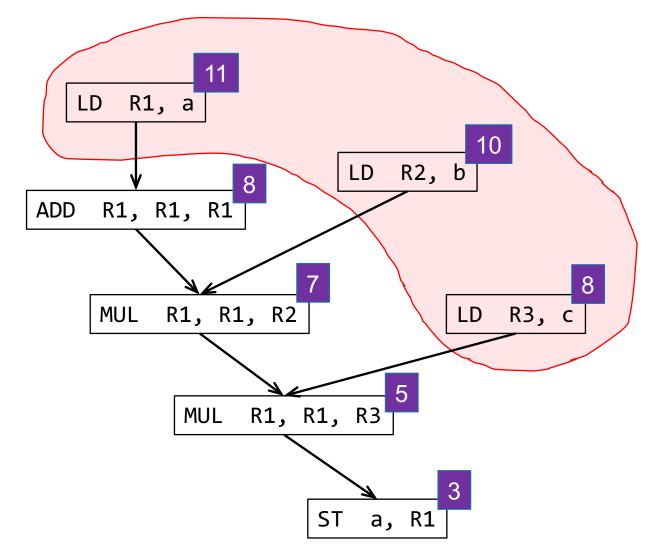




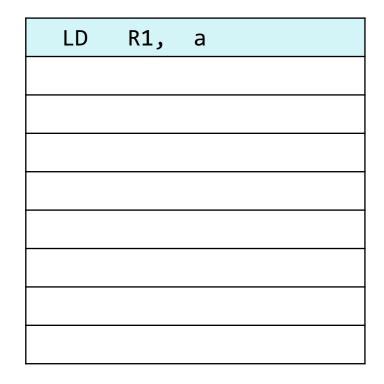


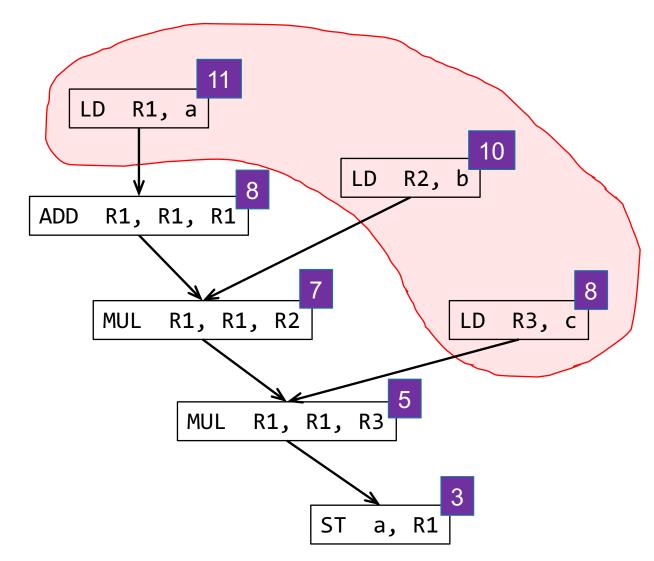




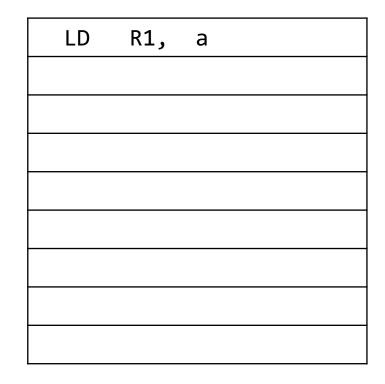


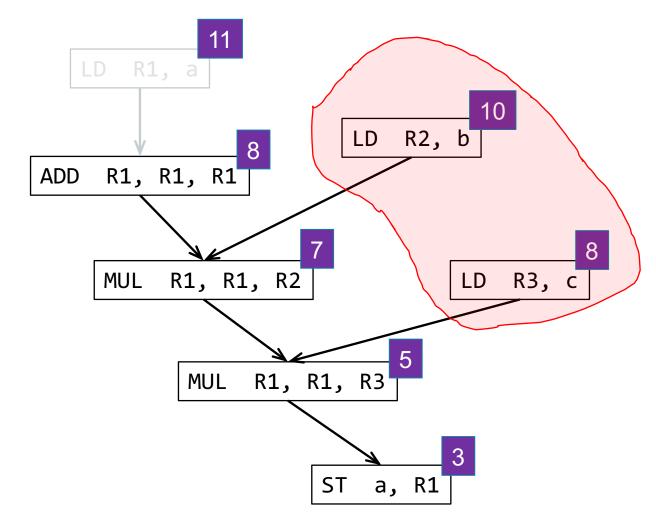






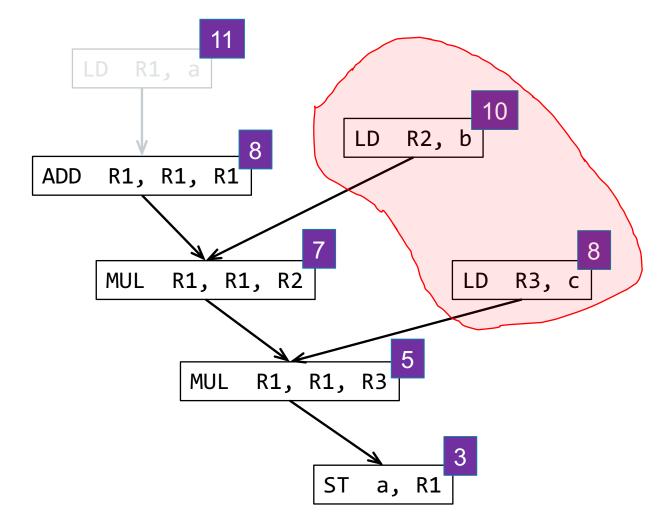






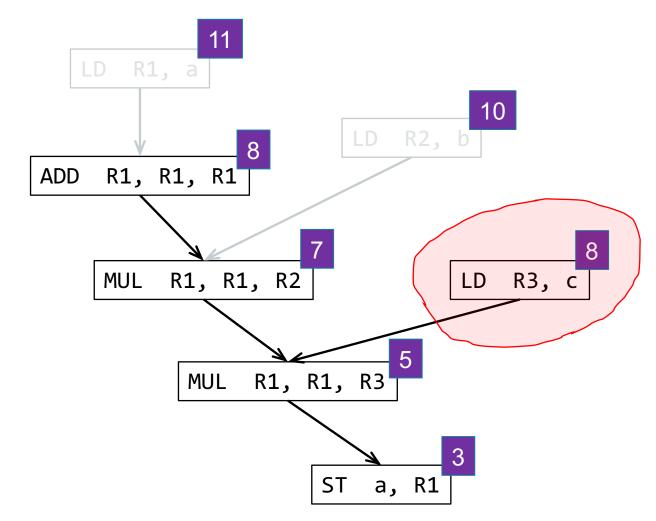


LD	R1,	а	
LD	R2,	b	



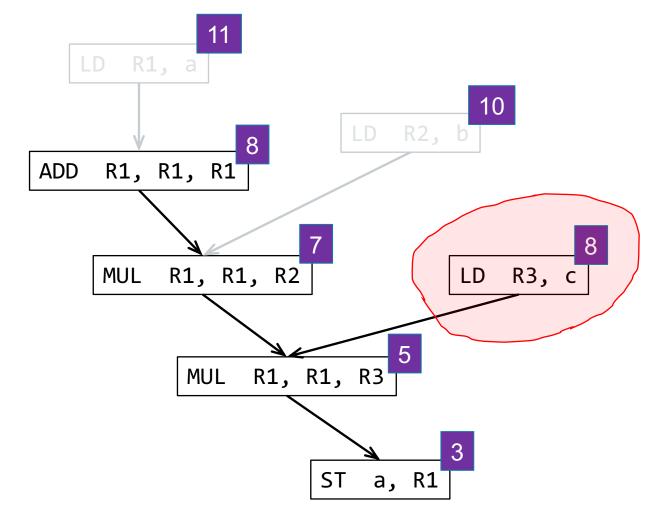


R1,	a	
R2,	b	



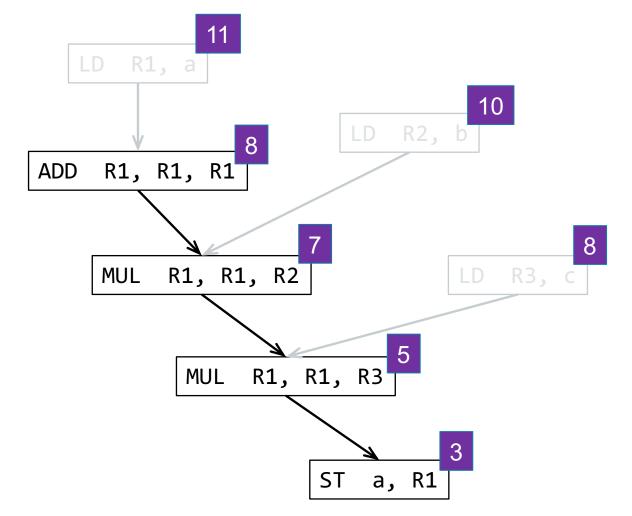


LD	R1,	a	
LD	R2,	b	
LD	R3,	С	



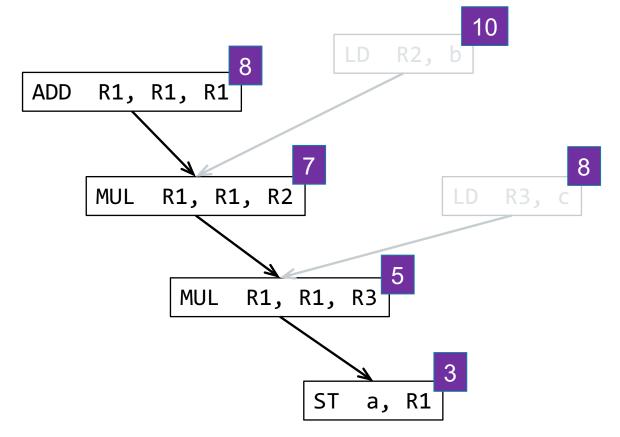


LD	R1,	a	
LD	R2,	b	
LD	R3,	С	



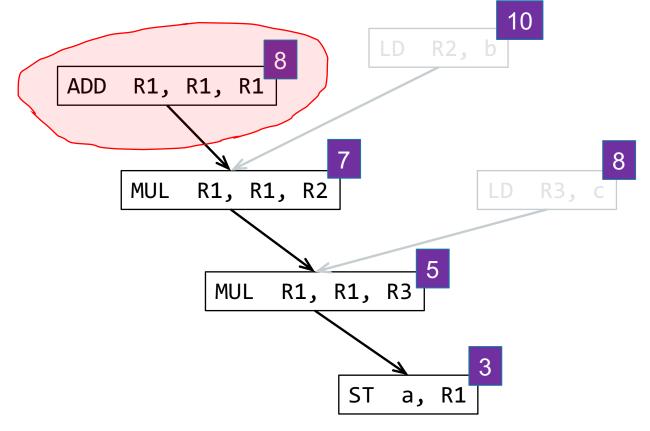


LD	R1,	a	
LD	R2,	b	
LD	R3,	С	



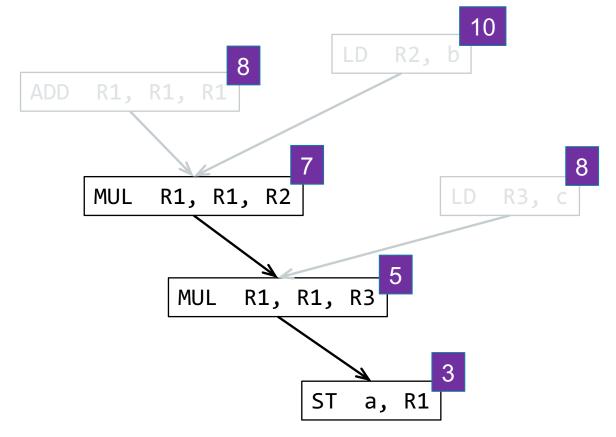


LD	R1,	a	
LD	R2,	b	
LD	R3,	С	



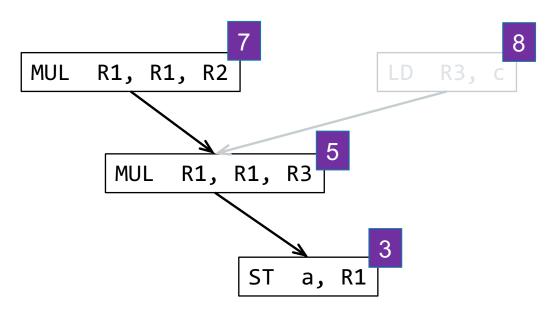


LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1



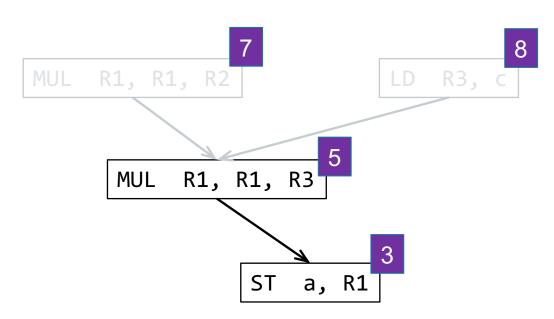


LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1



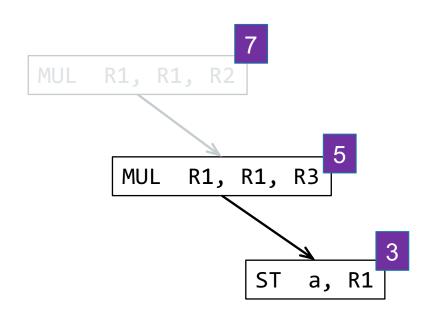


LD	R1,	а		
LD	R2,	b		
LD	R3,	С		
ADD	R1,	R1,	R1	
MUL	R1,	R1,	R2	



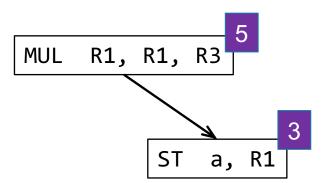


LD	R1,	а		
LD	R2,	b		
LD	R3,	С		
ADD	R1,	R1,	R1	
MUL	R1,	R1,	R2	
NOP				



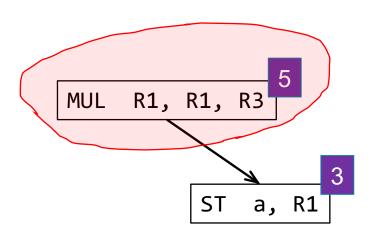


LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
NOP			





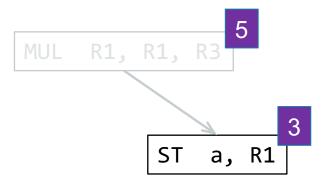
LD	R1,	а	
LD	R2,	b	
LD	R3,	С	
ADD	R1,	R1,	R1
MUL	R1,	R1,	R2
NOP			





• Cycle = 7, 8

LD	R1,	a		
LD	R2,	b		
LD	R3,	С		
ADD	R1,	R1,	R1	
MUL	R1,	R1,	R2	
NOP				
MUL	R1,	R1,	R3	
NOP				





• Cycle = 9, 10, 11

R1,	a	
R2,	b	
R3,	С	
R1,	R1,	R1
R1,	R1,	R2
R1,	R1,	R3
а,	R1	
	R2, R3, R1, R1,	R2, b R3, c R1, R1, R1, R1,

ST a, R1



#### **Summary of List Scheduling**

- Check each clock cycle
- Schedule instructions when they are ready
- When multi instructions can be scheduled, check their priority
  - The longest latency path
  - Using the most resources

• ...



#### PART III: Global Code Scheduling



#### **Recap: Dominance**

- A dominates B if and only if ...?
- A strictly dominates B if and only if ...?



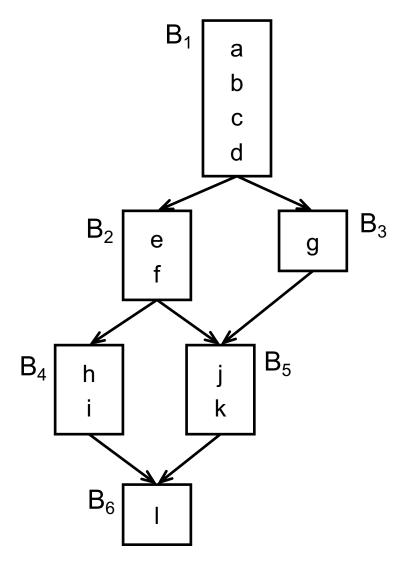
#### **Recap: Dominance**

- A dominates B if and only if ...?
- A strictly dominates B if and only if ...?

- A post-dominates B if and only if ...?
- A strictly post-dominates B if and only if ...?



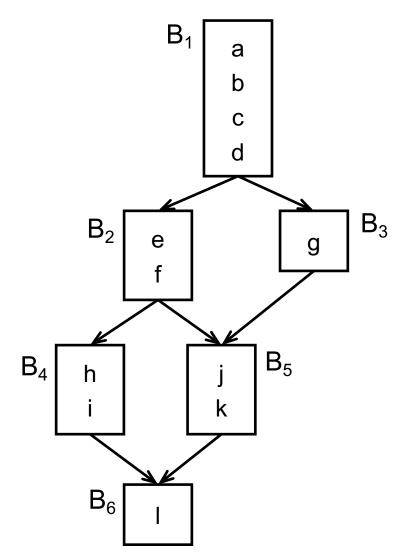
- EBB is a maximal set of blocks such that
- (1) It has a single entry, B;
- (2) All blocks except for B has only one predecessor.





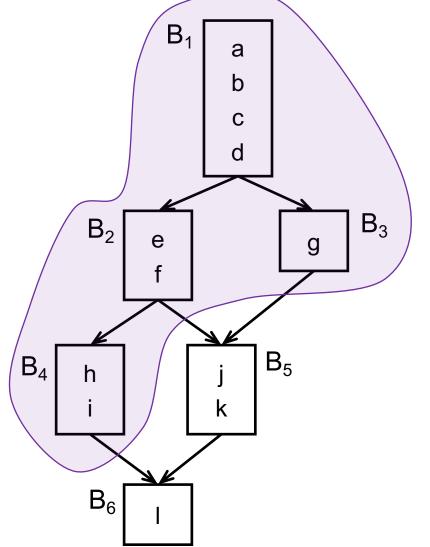
- EBB is a maximal set of blocks such that
- (1) It has a single entry, B;
- (2) All blocks except for B has only one predecessor.

Try!



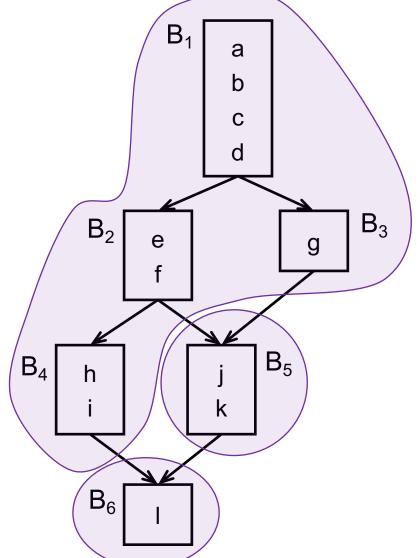


- EBB is a maximal set of blocks such that
- (1) It has a single entry, B;
- (2) All blocks except for B has only one predecessor.





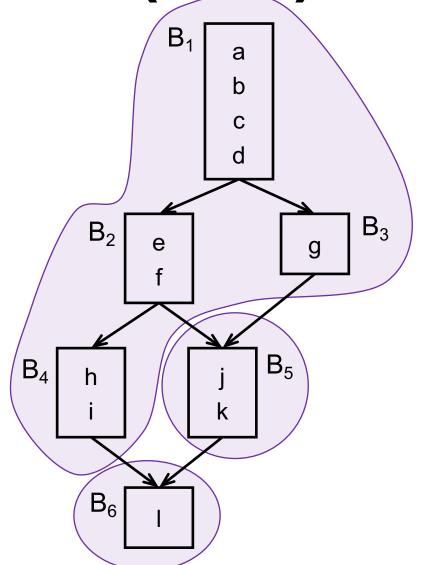
- EBB is a maximal set of blocks such that
- (1) It has a single entry, B;
- (2) All blocks except for B has only one predecessor.





- EBB is a maximal set of blocks such that
- (1) It has a single entry, B<sub>0</sub>;
- (2) All blocks except for B<sub>0</sub> has only one predecessor.

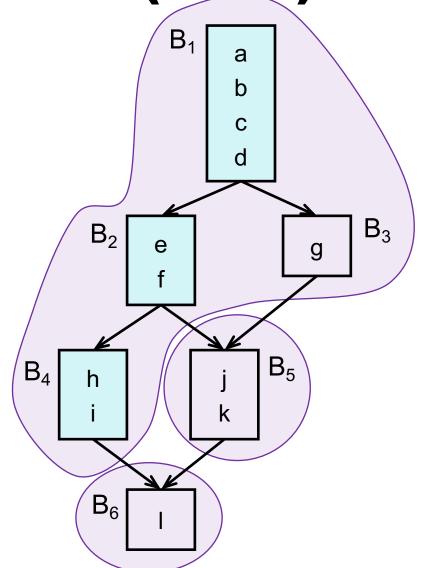
- Three EBBs in the example
- Four EBB paths





- EBB is a maximal set of blocks such that
- (1) It has a single entry, B<sub>0</sub>;
- (2) All blocks except for B<sub>0</sub> has only one predecessor.

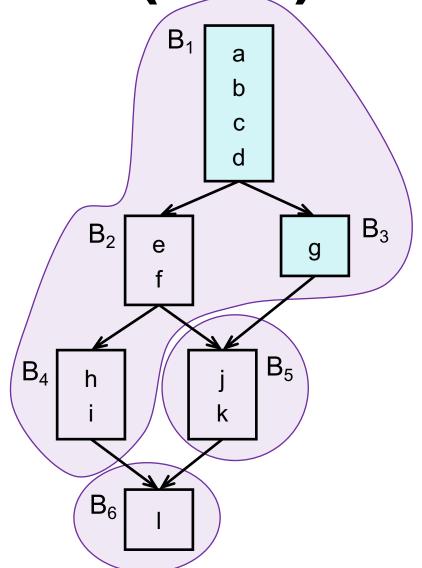
- Three EBBs in the example
- Four EBB paths





- EBB is a maximal set of blocks such that
- (1) It has a single entry, B<sub>0</sub>;
- (2) All blocks except for B<sub>0</sub> has only one predecessor.

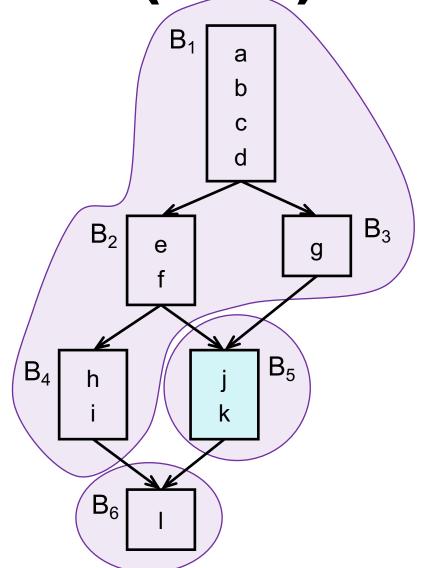
- Three EBBs in the example
- Four EBB paths





- EBB is a maximal set of blocks such that
- (1) It has a single entry, B<sub>0</sub>;
- (2) All blocks except for B<sub>0</sub> has only one predecessor.

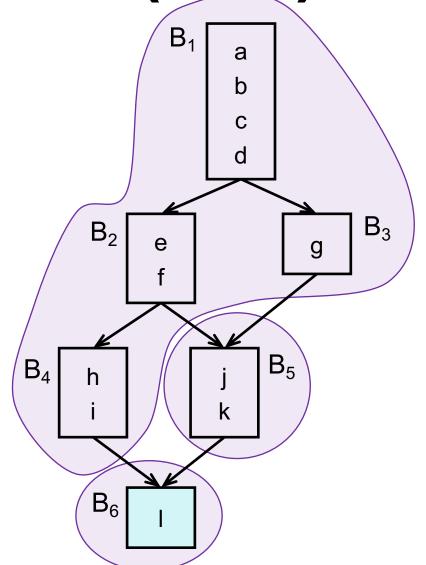
- Three EBBs in the example
- Four EBB paths





- EBB is a maximal set of blocks such that
- (1) It has a single entry, B<sub>0</sub>;
- (2) All blocks except for B<sub>0</sub> has only one predecessor.

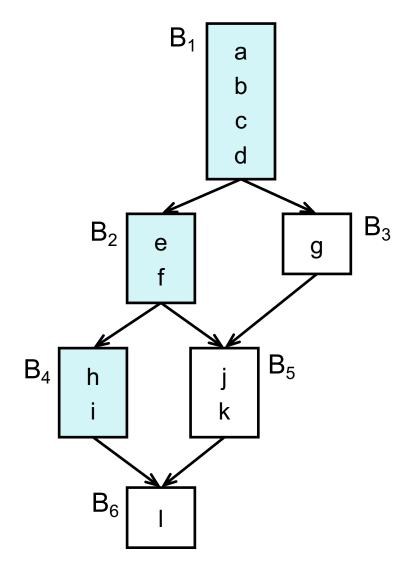
- Three EBBs in the example
- Four EBB paths





#### Global Scheduling

 Schedule each EBB path like a basic block, e.g., via list scheduling

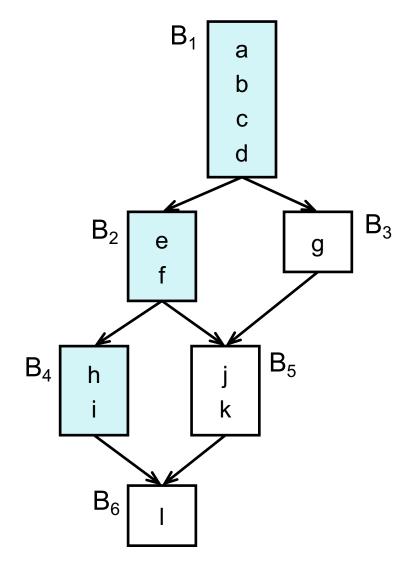




# **Global Scheduling**

 Schedule each EBB path like a basic block, e.g., via list scheduling

 Scheduling may change the order of instructions

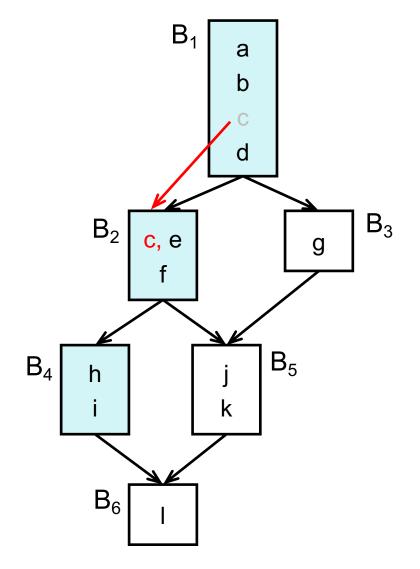




# **Global Scheduling**

 Schedule each EBB path like a basic block, e.g., via list scheduling

 Scheduling may change the order of instructions

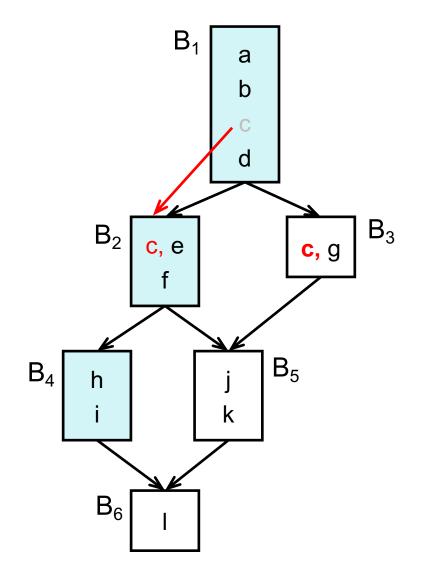




 Schedule each EBB path like a basic block, e.g., via list scheduling

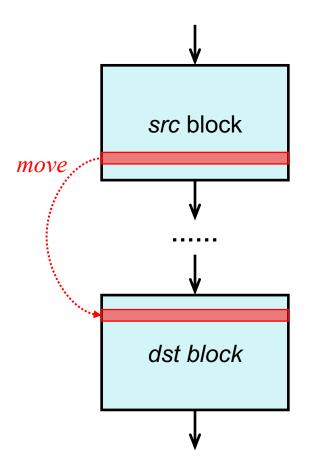
 Scheduling may change the order of instructions

 Compensation code may be necessary



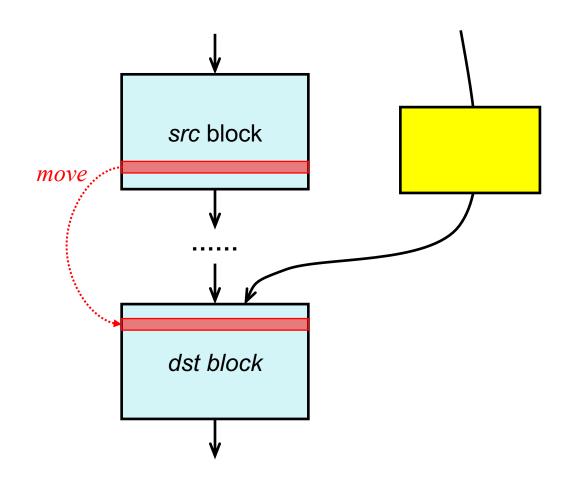


• I. src does not dominate dst



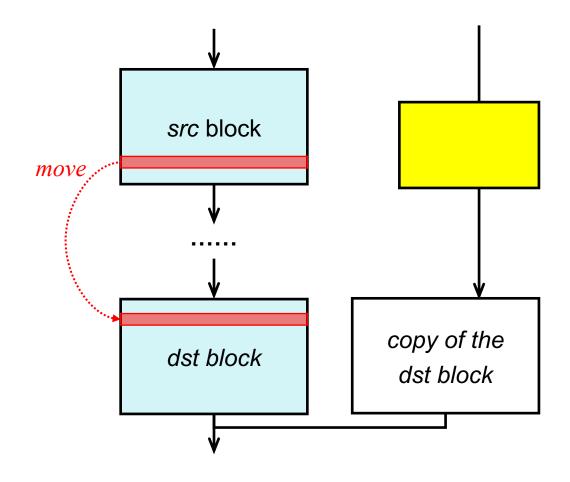


• I. src does not dominate dst



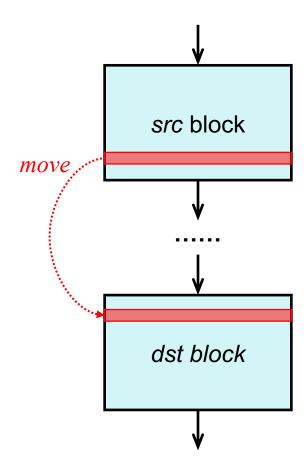


• I. src does not dominate dst



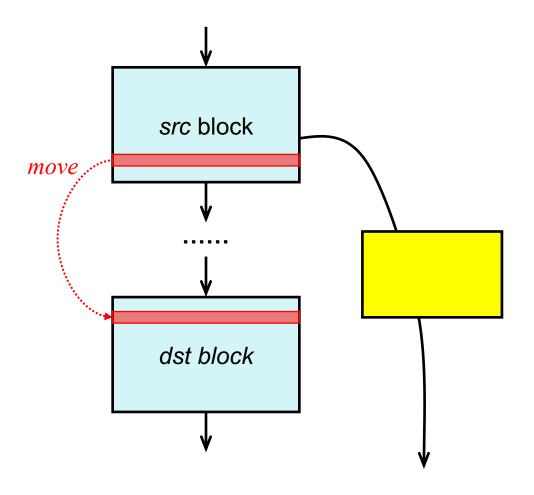


• II. *dst* does not post-dominate *src* 



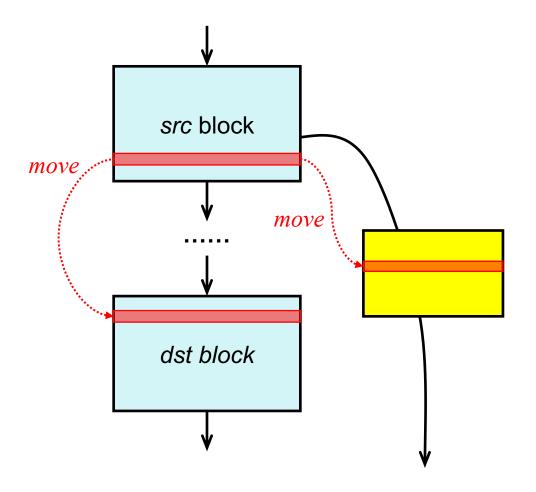


• II. *dst* does not post-dominate *src* 



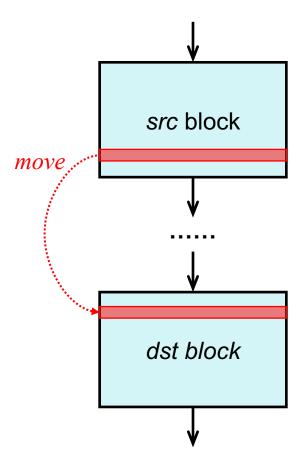


• II. *dst* does not post-dominate *src* 





• III. src dom dst & dst post-dom src

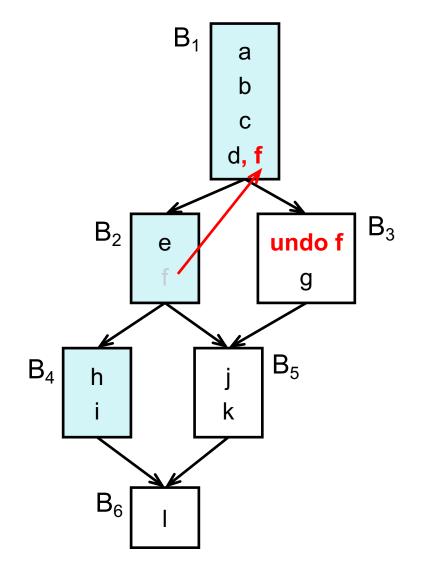




 Schedule an EBB path like a basic block, e.g., via list scheduling.

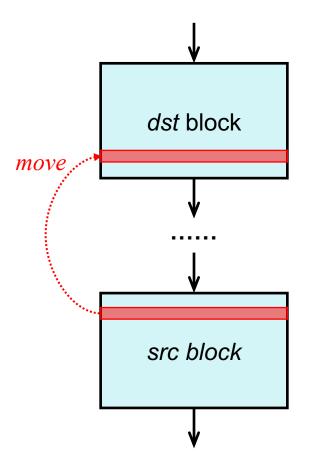
 Scheduling may change the order of instructions

 Compensation code may be necessary



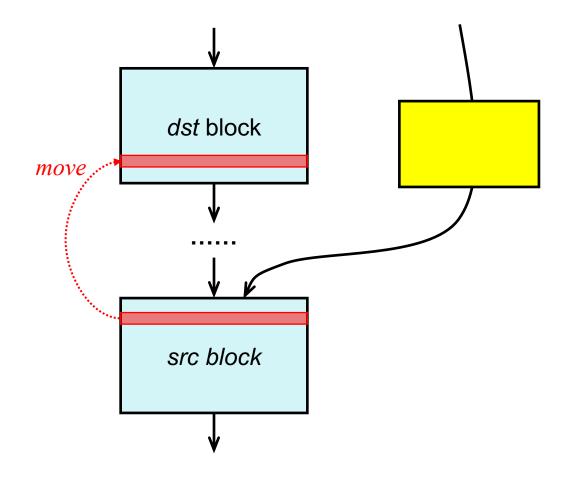


• I. dst does not dominate src



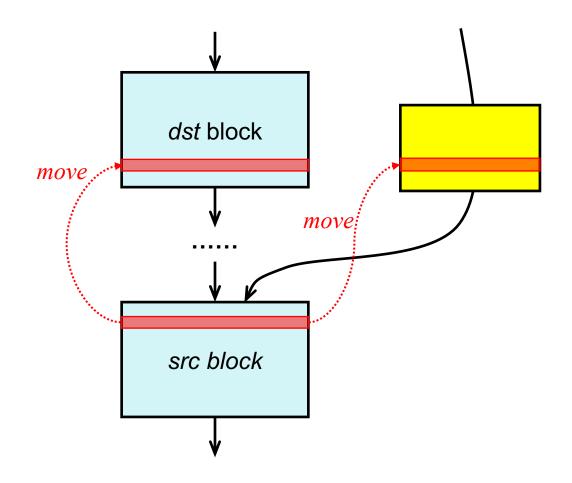


• I. dst does not dominate src



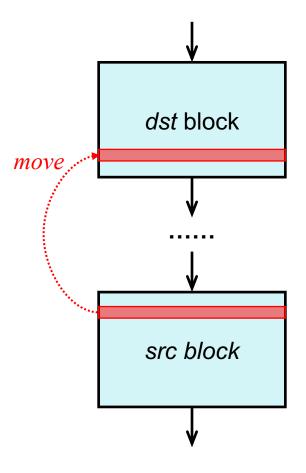


• I. dst does not dominate src



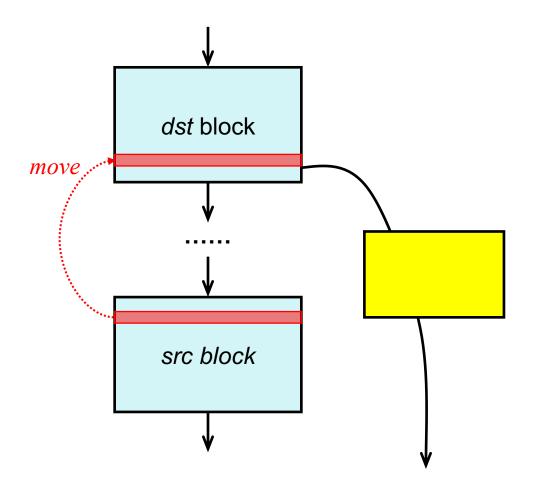


• II. src does not post-dominate dst



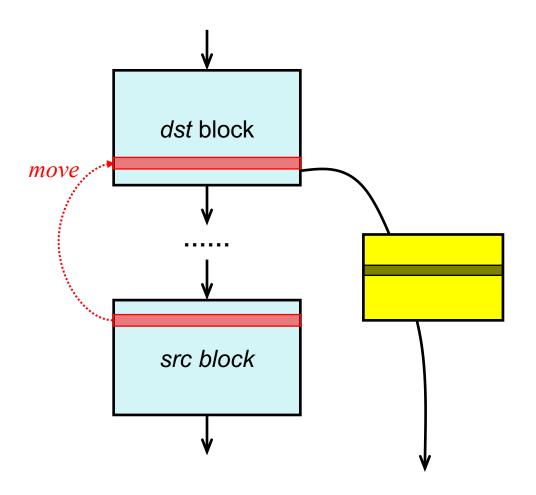


• II. src does not post-dominate dst



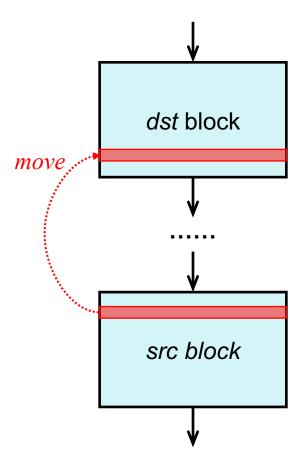


• II. src does not post-dominate dst





• III. dst dom src & src post-dom dst

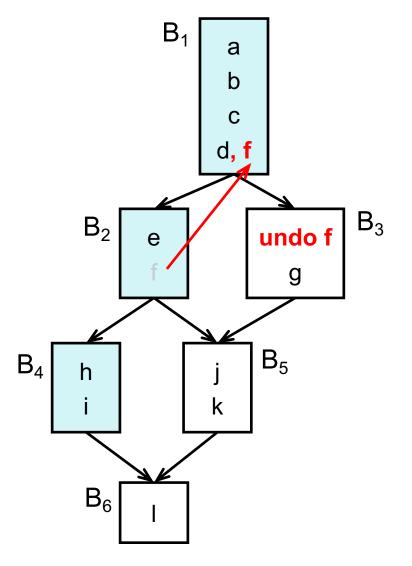




# Global Scheduling

 After scheduling an EBB path, remove it from the graph

Then schedule the next

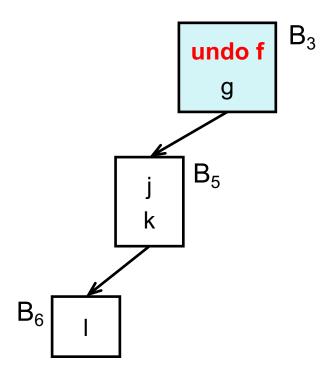




## Global Scheduling

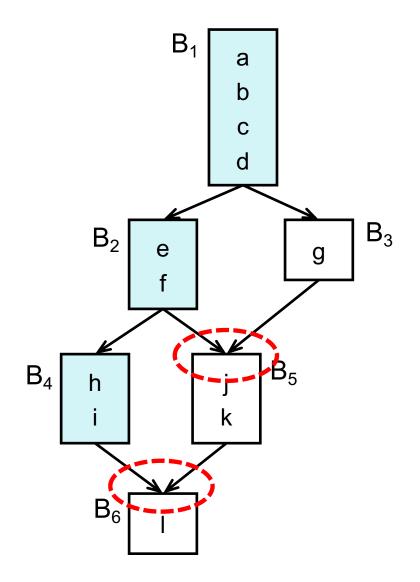
 After scheduling an EBB path, remove it from the graph

 Then schedule the next, until all EBB paths are scheduled



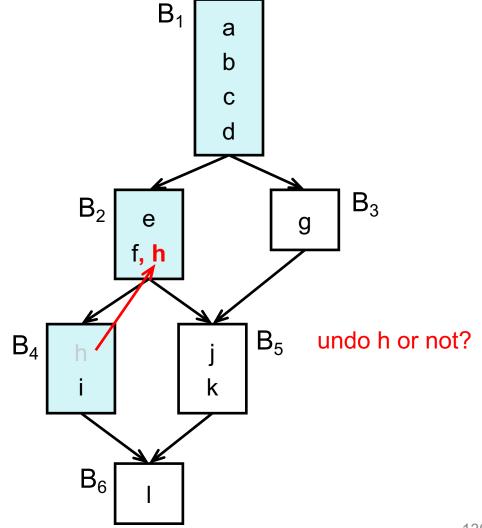


Join points



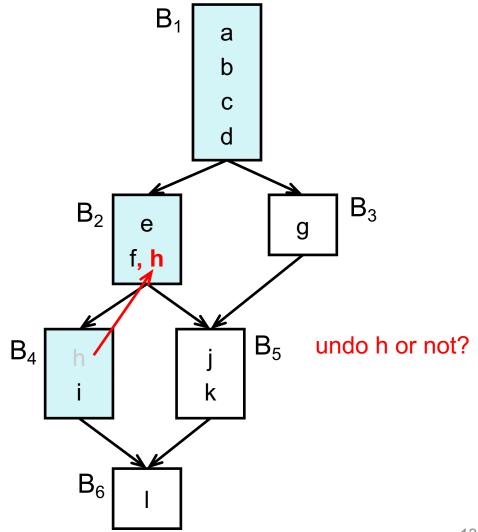


- Join points
- Context Problem:
  - From B2 to B5, Undo h
  - From B3 to B5, Undo h changes the code semantics



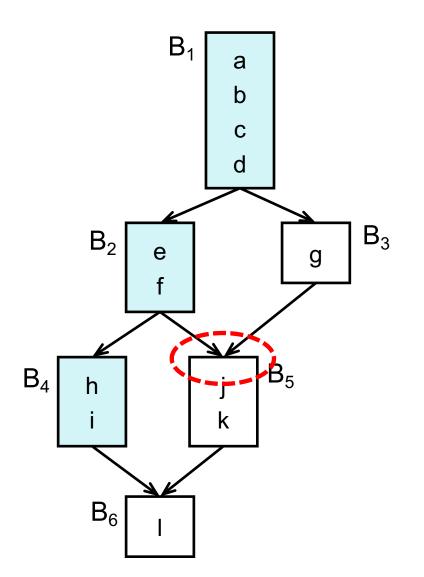


- Join points
- Context Problem:
  - From B2 to B5, Undo h
  - From B3 to B5, Undo h
     changes the code semantics
- Clone blocks to address the context problem



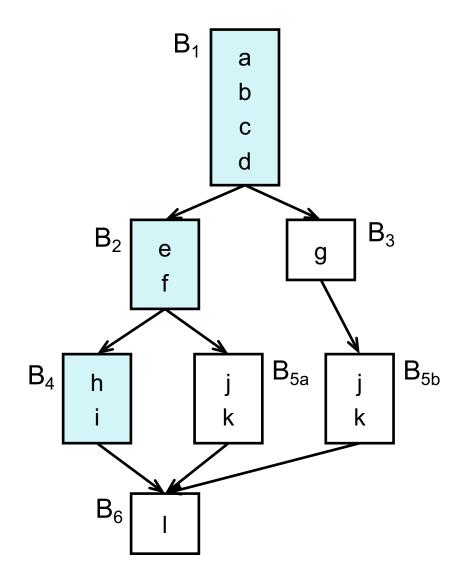


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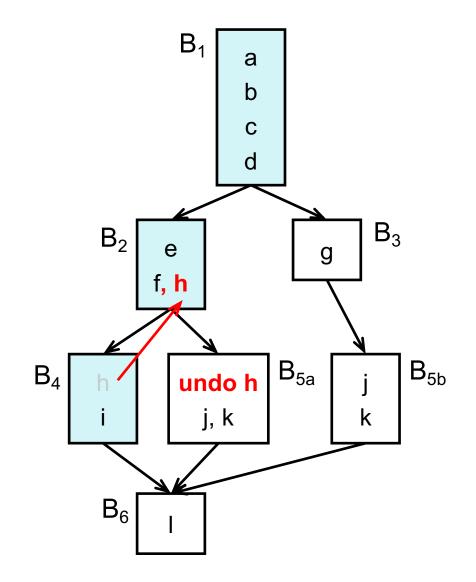


- Join points
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- Join points
- Context Problem:
  - From B2 to B5, Undo h
  - From B3 to B5, Undo h changes the code semantics
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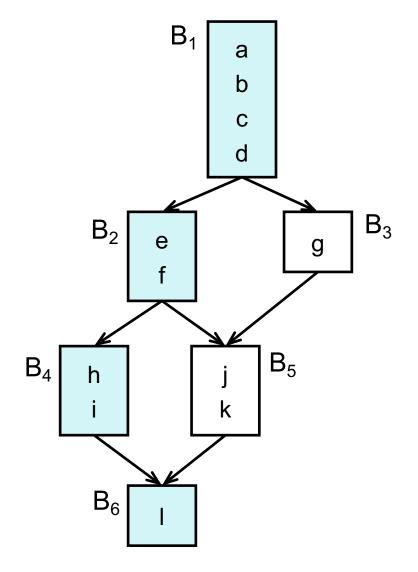


# **Trace Scheduling**



## **Trace Scheduling**

Profile and schedule the hot path

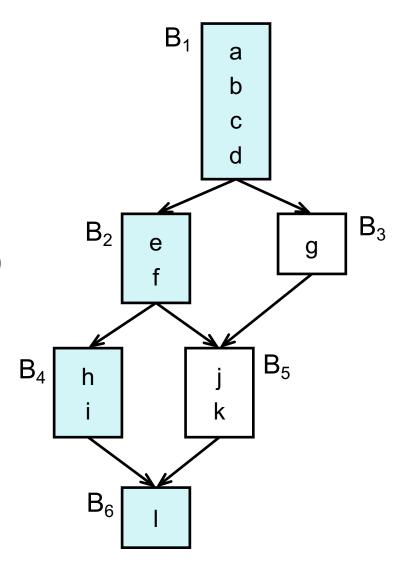




## **Trace Scheduling**

Profile and schedule the hot path

- Profiling-guided optimization
- Just-in-time compiler (that in JVM)





# **PART IV: Software Pipelining**



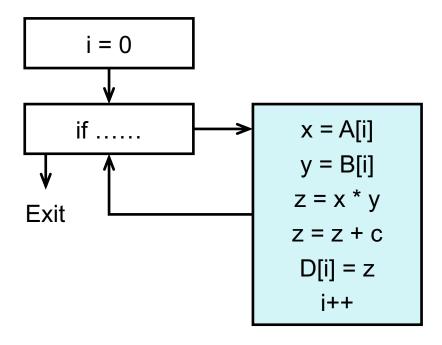
### **How about Loops?**

 We can schedule the loop body as a single block



## **How about Loops?**

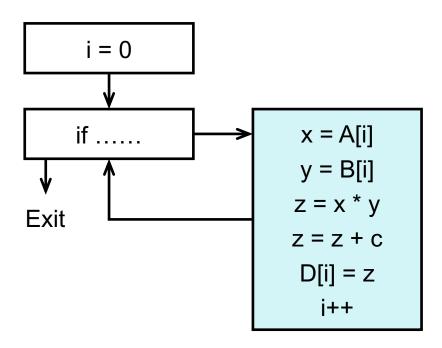
 We can schedule the loop body as a single block





## **How about Loops?**

- We can schedule the loop body as a single block
- Miss cross-iteration parallelism





```
for (i = 0; .....; i += 4)

D[i] = A[i] * B[i] + C

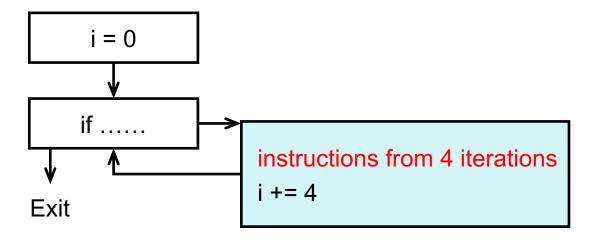
D[i+1] = A[i+1] * B[i+1] + C

D[i+2] = A[i+2] * B[i+2] + C

D[i+3] = A[i+3] * B[i+3] + C
```



```
for (i = 0; .....; i += 4)
D[i] = A[i] * B[i] + c
D[i+1] = A[i+1] * B[i+1] + c
D[i+2] = A[i+2] * B[i+2] + c
D[i+3] = A[i+3] * B[i+3] + c
```





 We still schedule the loop body as a single block

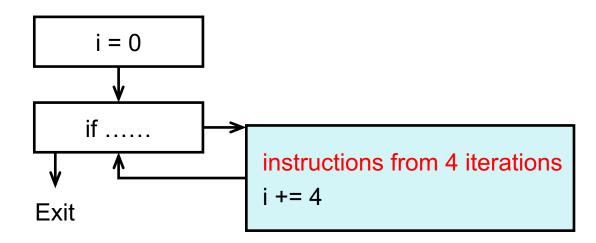
```
for (i = 0; .....; i += 4)

D[i] = A[i] * B[i] + c

D[i+1] = A[i+1] * B[i+1] + c

D[i+2] = A[i+2] * B[i+2] + c

D[i+3] = A[i+3] * B[i+3] + c
```





- We still schedule the loop body as a single block
- Let us schedule instructions across multiple loop iterations

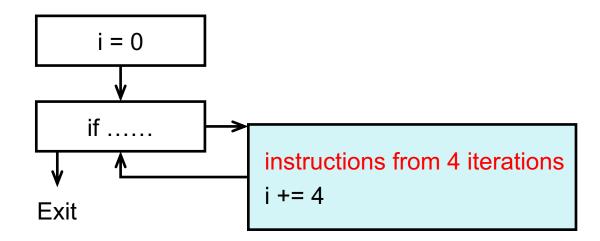
```
for (i = 0; .....; i += 4)

D[i] = A[i] * B[i] + c

D[i+1] = A[i+1] * B[i+1] + c

D[i+2] = A[i+2] * B[i+2] + c

D[i+3] = A[i+3] * B[i+3] + c
```

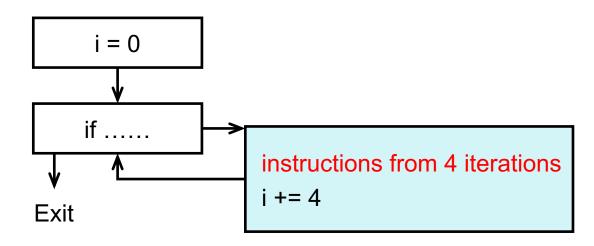




## **Problems of Loop Unrolling**

- We cannot unroll too many times, which
- I. makes code size larger
  - cache pressure
  - register pressure
  - (slows down the code)
- II. and does not break the boundary of loop iteration

```
for (i = 0; .....; i += 4)
D[i] = A[i] * B[i] + c
D[i+1] = A[i+1] * B[i+1] + c
D[i+2] = A[i+2] * B[i+2] + c
D[i+3] = A[i+3] * B[i+3] + c
```





# **Software Pipelining**

- Break the boundary of loop iterations
- Regard a loop as a whole, not separate blocks
- More chances of parallelism without bloating the code



# **Software Pipelining**

- Break the boundary of loop iterations
- Regard a loop as a whole, not separate blocks
- More chances of parallelism without bloating the code

• Refer to Chapter 10, the Dragon book



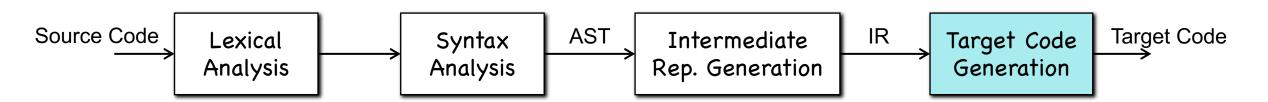
# **Software Pipelining**

- Break the boundary of loop iterations
- Regard a loop as a whole, not separate blocks
- More chances of parallelism without bloating the code

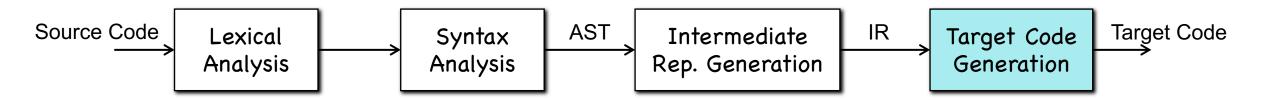
- Refer to Chapter 10, the Dragon book
- No Silver Bullet!





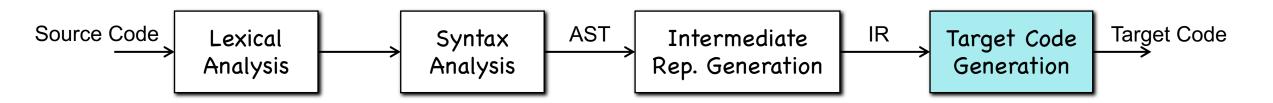






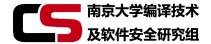
Can we generate code to leverage modern CPUs for better instruction-level parallelization? Yes! Possible!





Can we generate code to leverage modern CPUs for better instruction-level parallelization? Yes! Possible!

- Scheduling a basic block
- Scheduling extended basic blocks
- Scheduling loops (optional)



#### **THANKS!**