2-2 The Efficiency of Algorithms

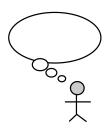
魏恒峰

hfwei@nju.edu.cn

2018年04月02日

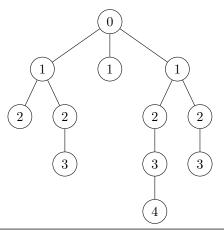
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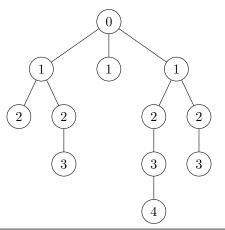
- (1) Diameter of Convex Polygon: $\Theta(n)$
- (2) Lower Bound for Sorting: $\Omega(n \lg n)$
- (3) Traversal over Trees: DFS/BFS $(\Theta(n))$



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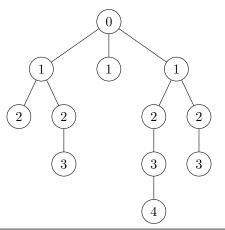
I have thought that · · ·



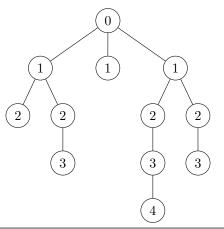


$$\mathsf{sum-of-depths}(r) = \left\{ \begin{array}{l} \sum\limits_{v: \mathsf{child of}\ r} \mathsf{sum-of-depths}(v) + \mathsf{depth of}\ r, \end{array} \right.$$

4 D > 4 B > 4 E > 4 E > E 990



$$\mathsf{sum\text{-}of\text{-}depths}(r) = \left\{ \begin{array}{ll} \mathsf{depth} \ \mathsf{of} \ r, & r \ \mathsf{is} \ \mathsf{a} \ \mathsf{leaf} \\ \sum\limits_{v: \mathsf{child} \ \mathsf{of} \ r} \mathsf{sum\text{-}of\text{-}depths}(v) + \mathsf{depth} \ \mathsf{of} \ r, & \mathsf{o.w.} \end{array} \right.$$



$$\mathsf{sum-of-depths}(r, \textcolor{red}{d}) = \left\{ \begin{array}{l} d, & r \text{ is a leaf} \\ \sum\limits_{v: \mathsf{child of } r} \mathsf{sum-of-depths}(v, \textcolor{red}{d} + 1) + d, & \mathsf{o.w.} \end{array} \right.$$

Algorithm 1 Calculate the sum of depths of all nodes of a tree T.

- 1: procedure Sum-of-Depths()
- 2: **return** SUM-OF-DEPTHS(T, 0)
- 3: **procedure** SUM-OF-DEPTHS(r, depth) $\triangleright r$: root of a tree
- 4: **if** T is a leaf **then**
- 5: **return** depth
- 6: **for all** child vertex v of r **do**
- 7: $depth \leftarrow depth + \text{Sum-of-Depths}(v, depth + 1)$
- 8: **return** depth

$$\mathsf{sum\text{-}of\text{-}depths}(r, \textcolor{red}{d}) = \left\{ \begin{array}{ll} d, & r \text{ is a leaf} \\ \sum\limits_{v: \mathsf{child} \text{ of } r} \mathsf{sum\text{-}of\text{-}depths}(v, \textcolor{red}{d} + 1) + d, & \mathsf{o.w.} \end{array} \right.$$

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Master Theorem?

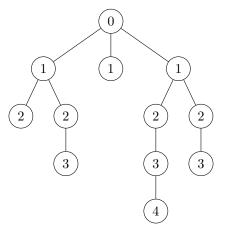
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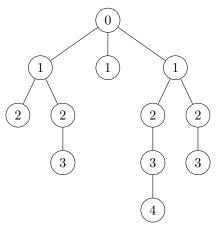
$$\Theta(m+n) = \Theta(n)$$

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DH 4.2 (b): Number of Nodes at Depth K



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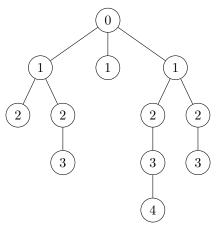


$$\mathsf{nodes}\text{-}\mathsf{at}\text{-}\mathsf{depth}(r, \pmb{k}) =$$

 $\mathsf{nodes}\text{-}\mathsf{at}\text{-}\mathsf{depth}(v, \frac{k}{k} - 1),$

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DH 4.2 (b): Number of Nodes at Depth K



$$\mathsf{nodes-at-depth}(r, \pmb{k}) = \left\{ \begin{array}{l} 1, & k = 0 \\ 0, & k > 0 \land r \text{ is a leaf} \\ \sum & \mathsf{nodes-at-depth}(v, \pmb{k-1}), & \mathsf{o.w.} \end{array} \right.$$

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Algorithm 2 Count the number of nodes in T at depth K.

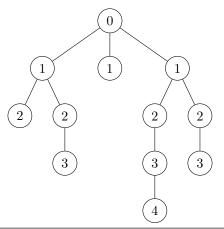
- 1: procedure Nodes-At-Depth()
- 2: **return** Nodes-At-Depth(T, K)

```
3: procedure Nodes-At-Depth(r, k)
```

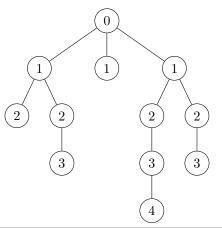
- 4: **if** k = 0 **then**
- 5: return 1
- 6: **if** r is a leaf **then**
- 7: **return** 0
- 8: $num \leftarrow 0$
- 9: **for all** child vertex v of r **do**
- 10: $num \leftarrow num + \text{Nodes-at-Depth}(v, k 1)$
- 11: return num

 $\triangleright r$: root of a tree

DH 4.2 (c): Any Leaf at an Even Depth?

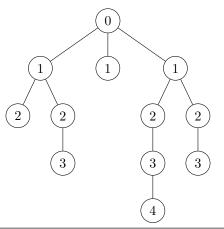


DH 4.2 (c): Any Leaf at an Even Depth?



$$\mathsf{leaf-at-depth}(r, \underbrace{parity}) = \left\{ \begin{array}{l} \sum\limits_{v: \mathsf{child of } r} (v, \mathbf{1} - parity), \end{array} \right.$$

DH 4.2 (c): Any Leaf at an Even Depth?



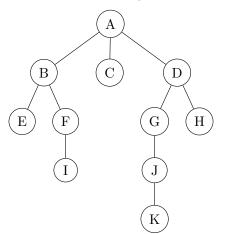
$$\mathsf{leaf-at-depth}(r, \underbrace{parity}) = \left\{ \begin{array}{ll} 1 - parity, & r \text{ is a leaf} \\ \sum\limits_{v: \mathsf{child of } r} (v, 1 - parity), & \mathsf{o.w.} \end{array} \right.$$

Algorithm 3 Check whether a tree T has any leaf at an even depth.

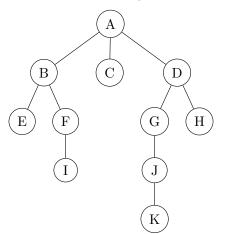
- 1: **procedure** Leaf-at-Even-Depth()
- 2: **return** Leaf-at-Depth(T, even = 0)
- 3: **procedure** Leaf-at-Depth(r, parity)
 - parity) ightharpoonup r: root of a tree

- 4: **if** r is a leaf **then**
- 5: **return** 1 parity
- 6: $result \leftarrow 0$
- 7: **for all** child vertex v of r **do**
- 8: $result \leftarrow result \lor \text{Leaf-at-Depth}(v, 1 parity)$
- 9: **return** result

DH 4.3 (a): Sum of Contents at Each Depth



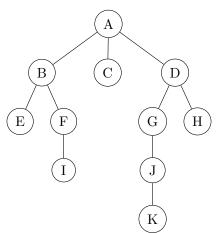
DH 4.3 (a): Sum of Contents at Each Depth



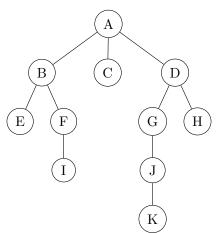
Algorithm 4 Calculate the sum of contents of nodes of a tree T at each depth.

```
1: procedure SUM-AT-DEPTH(r)
                                                               \triangleright r: root of the tree T
        r.depth \leftarrow 0
 2:
        Q \leftarrow \emptyset
 3:
         ENQUEUE(Q, r)
 4:
        while Q \neq \emptyset do
 5:
             u \leftarrow \text{DEQUEUE}(Q)
 6:
             sumAtDepth[u.depth] += u.content
 7:
             for all child vertex v of u do
 8.
                 v.depth \leftarrow u.depth + 1
 g.
                 ENQUEUE(Q, v)
10:
```

DH 4.3 (b): Depth K with the Maximum Number of Nodes



DH 4.3 (b): Depth K with the Maximum Number of Nodes



Algorithm 5 Count the number of nodes of a tree T at each depth.

```
1: procedure Nodes-At-Depth(r)
                                                               \triangleright r: root of the tree T
        r.depth \leftarrow 0
 2:
        Q \leftarrow \emptyset
 3:
        ENQUEUE(Q, r)
 4:
        while Q \neq \emptyset do
 5:
             u \leftarrow \text{DEQUEUE}(Q)
 6:
             nodesAtDepth[u.depth] += 1
 7:
             for all child vertex v of u do
 8:
                 v.depth \leftarrow u.depth + 1
 9:
                  Enqueue(Q, v)
10:
```

Lower Bound for Comparion-based Sorting

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Prove a lower bound of $O(n \lg n)$ on the time complexity of any comparison-based sorting algorithm.

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Lower Bound for Comparison-based Sorting (DH 6.13)

Prove a lower bound of $\Omega(n \lg n)$ on the time complexity of any comparison-based sorting algorithm.

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the only way to gain order info.

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$$x \in [1 \cdots 99]$$
$$x/10$$

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Cost Model:

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the critical operations to count

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$$x \in [1 \cdots 99]$$
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Lower Bound for Comparison-based Sorting (DH 6.13)

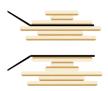
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Cost Model:

Computational Model: the critical operations to count

the only way to gain order info.

$$x \in [1 \cdots 99]$$
$$x/10$$



"Bounds For Sorting By Prefix Reversal", 1979

An argument from a student:

▶ Any comparison-based sorting algorithm can be considered to work by *putting elements into their final positions one by one*. (Take the last time one element is put into its final position.)

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- ▶ To put the element e which is the i-th one being put into its final position, the algorithms should know the relative ordering between e and the first n-1 elements that are already put into their final positions. This costs at least $\Omega(\lg i)$ comparisons.

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- ▶ Any comparison-based sorting algorithm can be considered to work by putting elements into their final positions one by one. (Take the last time one element is put into its final position.)
- ▶ To put the element e which is the i-th one being put into its final position, the algorithms should know the relative ordering between e and the first n-1 elements that are already put into their final positions. This costs at least $\Omega(\lg i)$ comparisons.
- ► Therefore, the total number of comparisons is at least

$$\sum_{i=1}^{n-1} \lg i = \Omega(n \lg n).$$



Is this lower bound proof for the comparison-based sorting problem correct?



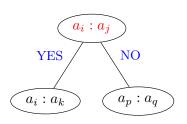


Is this lower bound proof for the comparison-based sorting problem correct?



"This makes claims without justification."

-D.W.

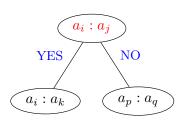


Nodes: comparisions $a_i : a_j$

$$<, \ \leq, \ =, \ \geq, \ >$$

Edges: two-way decisions (Y/N)

Leaves: possible permutations



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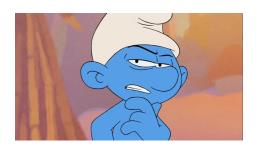
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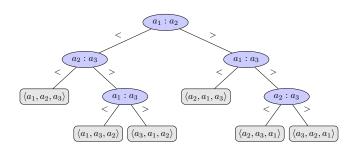
Assumption (By aware of any assumptions !!!):

All the input elements are **distinct**.

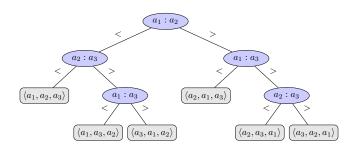
$$a_i < a_j$$







Any Comparison-based Sorting Algorithm $\xrightarrow{\text{modeled by}}$ A Decision Tree



The decision tree for insertion sort on three elements.

Any Comparison-based Sorting Algorithm $\stackrel{\text{modeled by}}{\longrightarrow}$ A Decision Tree

```
1: procedure -\operatorname{SORT}(A,n)

2: for i \leftarrow 1 to n-1 do

3: for j \leftarrow i+1 to n do

4: if A[j] < A[i] then

5: \operatorname{SWAP}(A[j], A[i])
```

Any Comparison-based Sorting Algorithm $\stackrel{\text{modeled by}}{\longrightarrow}$ A Decision Tree

```
1: procedure SELECTION-SORT(A, n)

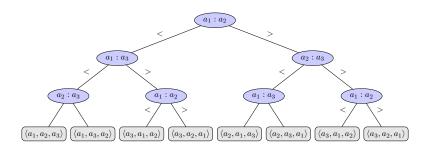
2: for i \leftarrow 1 to n-1 do

3: for j \leftarrow i+1 to n do

4: if A[j] < A[i] then

5: SWAP(A[j], A[i])
```

Any Comparison-based Sorting Algorithm $\stackrel{\text{modeled by}}{\longrightarrow}$ A Decision Tree



The decision tree for selection sort on three elements.

Any Comparison-based Sorting Algorithm $\mathcal{A} \xrightarrow{\mathsf{modeled}\ \mathsf{by}} \mathsf{A}$ Decision Tree \mathcal{T}

Any Comparison-based Sorting Algorithm $\mathcal{A} \xrightarrow{\mathsf{modeled}\ \mathsf{by}} \mathsf{A}$ Decision Tree \mathcal{T}

Algorithm $\mathcal A$ on a specific input of size $n \xrightarrow{\mathsf{modeled}\ \mathsf{by}} \mathsf A$ path through $\mathcal T$

Any Comparison-based Sorting Algorithm $\mathcal{A} \xrightarrow{\mathsf{modeled}\ \mathsf{by}} \mathsf{A}$ Decision Tree \mathcal{T}

Algorithm ${\mathcal A}$ on a specific input of size $n \xrightarrow{\operatorname{modeled}} {\mathsf A}$ path through ${\mathcal T}$

Worst-case time complexity of $\mathcal{A} \xrightarrow{\mathsf{modeled}\ \mathsf{by}}$ The height of \mathcal{T}

Any Comparison-based Sorting Algorithm $\mathcal{A} \xrightarrow{\mathsf{modeled}\ \mathsf{by}} \mathsf{A}$ Decision Tree \mathcal{T}

Algorithm $\mathcal A$ on a specific input of size $n \xrightarrow{\mathsf{modeled}\ \mathsf{by}} \mathsf A$ path through $\mathcal T$

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Worst-case Lower Bound of Comparison-based Sorting on inputs of size n $\underline{ \text{modeled by} }$

The Minimum Height of All \mathcal{T} s

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To be a full binary tree:

$$\#$$
 of leaves $\leq 2^h$

Worst-case Lower Bound of Comparison-based Sorting on inputs of size n $\underline{\underline{\mathsf{modeled by}}}$

The Minimum Height of All \mathcal{T} s

To be a full binary tree:

$$\#$$
 of leaves $\leq 2^h$

To be a correct sorting algorithm:

$$\#$$
 of leaves $> n!$



Lower Bound for Comparison-based Sorting

 $n! \le \#$ of leaves $\le 2^h$

Lower Bound for Comparison-based Sorting

$$n! \leq \#$$
 of leaves $\leq 2^h$

$$h \ge \lg n! = \Omega(n \lg n)$$

Lower Bound for Comparison-based Sorting

$$n! \le \#$$
 of leaves $\le 2^h$

$$h \ge \lg n! = \Omega(n \lg n)$$

Stirling Formula (by James Stirling):

$$n! = \Theta\Big(\sqrt{2\pi n} \Big(\frac{n}{e}\Big)^n\Big)$$



Looking Back

Looking Back



Looking Back



Assumptions (By aware of any assumptions !!!):

- (a) Comparison-based sorting algorithms.
- (b) All the input elements are distinct.

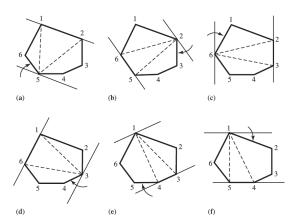
The k-sorted Problem

An array $A[1\cdots n]$ is k-sorted if it can be divided into k blocks, each of size n/k (we assume that $n/k\in\mathbb{N}$), such that the elements in each block are larger than the elements in earlier blocks and smaller than elements in later blocks. The elements within each block need not be sorted.

- (a) Describe an algorithm that k-sorts an arbitrary array in $O(n \log k)$ time.
- (b) Prove that any comparison-based k-sorting algorithm requires $\Omega(n\log k)$ comparisons in the worst case.
- (c) Describe an algorithm that completely sorts an already k-sorted array in $O(n\log(n/k))$ time.
- (d) Prove that any comparison-based algorithm to completely sort a k-sorted array requires $\Omega(n\log(n/k))$ comparisons in the worst case.

Show that the "Convex Polygon Diameter" algorithm is of linear-time complexity.

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Show that the "Convex Polygon Diameter" algorithm is of **linear-time** complexity.

Q: Linear-time of WHAT?

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Q: Linear-time of WHAT?

A: Linear-time of the size of input

Show that the "Convex Polygon Diameter" algorithm is of **linear-time** complexity.

Q: Linear-time of WHAT?

A: Linear-time of the size of input

Q: What is the input?

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Q: Linear-time of WHAT?

A: Linear-time of the size of input

Q: What is the input?

A : A convex polygon

Show that the "Convex Polygon Diameter" algorithm is of **linear-time** complexity.

Q: Linear-time of WHAT?

A: Linear-time of the size of input

Q: What is the input?

A: A convex polygon represented by n vertices

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Q: What are the critical operations?

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$$A: d(p_1, p_2) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

Show that the "Convex Polygon Diameter" algorithm is of **linear-time** complexity.

Q: Linear-time of WHAT?

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$$A: d(p_1, p_2) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

$$\Theta(c \cdot n) = \Theta(n)$$



Correctness



For a convex polygon, a pair of vertices determine the diameter.

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Proof.



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BUT, we have *not* enumerated *all* pairs of vertices.

For a convex polygon, a pair of vertices determine the diameter.

Proof.

BUT, we have *not* enumerated *all* pairs of vertices.

We have enumerated all pairs of vertices

For a convex polygon, a pair of vertices determine the diameter.

Proof.

BUT, we have *not* enumerated *all* pairs of vertices.

We have enumerated *all* pairs of vertices which *admits parallel supporting lines*.

A line L is a ${\it line \ of \ support}$ of a convex polygon P if

 $L \cap P = \text{ a vertex/an edge of } P.$

A line L is a *line of support* of a convex polygon P if

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 $L \cap P \neq \emptyset$ and P lies entirely on one side of L.

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Definition (Antipodal)

An antipodal is a pair of points that admits parallel supporting lines.

A line L is a *line of support* of a convex polygon P if

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 $L \cap P \neq \emptyset$ and P lies entirely on one side of L.

Definition (Antipodal)

An antipodal is a pair of points that admits parallel supporting lines.

We have enumerated all antipodals.

Theorem

If AB is a diameter of a convex polygon P, then AB is an antipodal.

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Proof.

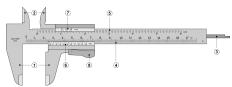
Theorem

If AB is a diameter of a convex polygon P, then AB is an antipodal.

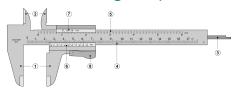
Proof.



Rotating Caliper



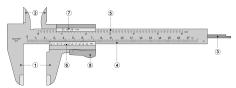
Rotating Caliper





"Computational Geometry" Ph.D Thesis, Michael Shamos, 1978

Rotating Caliper

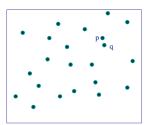


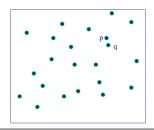


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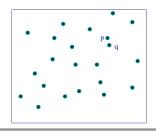


"Solving Geometric Problems with the Rotating Calipers", 1983



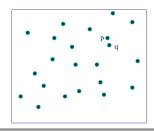


 $\label{lem:approx} A\ Classic\ and\ Beautiful\ Divide-Conquer\ Algorithm:$



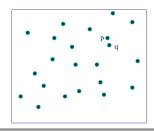
A Classic and Beautiful Divide-Conquer Algorithm:





A Classic and Beautiful Divide-Conquer-Combine Algorithm:





A Classic and Beautiful Divide-Conquer-Combine Algorithm:



Section 33.4, CLRS









Repeated Elements Problem

Thank You!