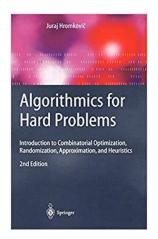
4-12 Approximation Algorithms

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Following the notion of approximability we divide the class NPO of optimization problems into the following five subclasses:

NPO(I): Contains every optimization problem from NPO for which there exists a FPTAS.

{In Section 4.3 we show that the knapsack problem belongs to this class.}

NPO(II): Contains every optimization problem from NPO that has a PTAS.

{In Section 4.3.4 we show that the makespan scheduling problem belongs to this class.}

NPO(III): Contains every optimization problem $U \in NPO$ such that

- (i) there is a polynomial-time δ-approximation algorithm for some δ > 1, and
- (ii) there is no polynomial-time d-approximation algorithm for U
 for some d < δ (possibly under some reasonable assumption
 like P ≠ NP), i.e., there is no PTAS for U.

{The minimum vertex cover problem, Max-Sat, and \triangle -TSP are examples of members of this class.}

NPO(IV): Contains every $U \in NPO$ such that

- (i) there is a polynomial-time f(n)-approximation algorithm for U for some f: N → R⁺, where f is bounded by a polylogarithmic function, and
- (ii) under some reasonable assumption like P ≠ NP, there does not exist any polynomial-time δ-approximation algorithm for U for any δ ∈ ℝ⁺.

{The set cover problem belongs to this class.}

NPO(V): Contains every $U \in \text{NPO}$ such that if there exists a polynomial-time f(n)-approximation algorithm for U, then (under some reasonable assumption like $P \neq NP$) f(n) is not bounded by any polylogarithmic function.

 $\{TSP\ and\ the\ maximum\ clique\ problem\ are\ well-known\ members\ of\ this\ class.\}$

Definition (NPO: NP Optimization)

$$\Pi = (L, sol, cost, goal)$$

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 $L: l \in L$ is an instance decidable in poly. time

 $sol: x \in sol(l)$ is a feasible solution of l verifiable in poly. time

cost: cost(x) is the cost of x computable in poly. time

 $goal: goal \in \{\min, \max\}$



$$f(n)$$
-APX: $f(n)$ -approximation

Exp-APX:
$$f(n) = O(2^{n^c})$$

Poly-APX:
$$f(n) = O(n^c)$$

Log-APX:
$$f(n) = O(\log n)$$

APX:
$$f(n) = c \ (c > 1)$$

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APX:
$$f(n) = c \ (c > 1)$$

PTAS: Poly. time approximation scheme

- $\triangleright \forall \epsilon > 0 : (1 + \epsilon)$ -approximation
- $ightharpoonup P: Poly(n) \qquad O((1/\epsilon) \cdot n^2) \quad O(n^{2/\epsilon})$

FPTAS: Fully poly. time approximation scheme

- $\blacktriangleright \forall \epsilon > 0 : (1 + \epsilon)$ -approximation
- $ightharpoonup \operatorname{FP}: \operatorname{Poly}(n, 1/\epsilon) \qquad O((1/\epsilon)^2 \cdot n^3)$



(if $P \neq NP$)

 $PO \subsetneq FPTAS \subsetneq PTAS$ $\subset APX \subset Log_APX \subset$

 $\subsetneq \mathsf{APX} \subsetneq \mathsf{Log\text{-}APX} \subsetneq \mathsf{Poly\text{-}APX} \subsetneq \mathsf{Exp\text{-}APX}$

 $\subsetneq \mathrm{NPO}$

(if $P \neq NP$)

$$\begin{split} \operatorname{PO} &\subsetneq \operatorname{FPTAS} \subsetneq \operatorname{PTAS} \\ &\subsetneq \operatorname{APX} \subsetneq \operatorname{Log-APX} \subsetneq \operatorname{Poly-APX} \subsetneq \operatorname{Exp-APX} \\ &\subsetneq \operatorname{NPO} \end{split}$$

- ▶ Knapsack \in FPTAS \ PO
- ▶ Makespan \in PTAS \ FPTAS (TODAY)
- ▶ Vertex Cover \in APX \ PTAS
- ▶ Set Cover \in Log-APX \ APX (CLRS 35.3)
- ▶ Clique \in Poly-APX \ Log-APX
- ▶ $TSP \in Exp-APX \setminus Poly-APX$

Makespan scheduling problem

Makespan scheduling problem (MS)

- ightharpoonup n jobs: J_1, \ldots, J_n
- ightharpoonup processing time: p_1, \ldots, p_n
- ▶ $m \ge 2$ machines: M_1, \ldots, M_m
- ightharpoonup goal: minimize the makespan

MS is NP-complete

Definition (Partition)

Instance:

$$\forall a \in A : s(a) \in \mathbb{Z}^+$$

Question: Is there a subset $A' \subseteq A$:

$$\sum_{a \in A'} s(a) = \sum_{a \in A \setminus A'} s(a)$$

$$A = \{5, 1, 3, 4, 8, 2, 7\} \implies A' = \{5, 3, 7\}, A \setminus A' = \{1, 2, 4, 8\}$$



MS is strongly NP-complete

Definition (3-Partition)

Instance:

$$|A| = 3m, B \in \mathbb{Z}^+$$
$$\forall a \in A : s(a) \in \mathbb{Z}^+, B/4 < s(a) < B/2$$

Question: Can A be partitioned into m disjoint sets S_1, \ldots, S_m :

$$\forall 1 \le i \le m : |S_i| = 3, \sum_{a \in S_i} s(a) = B$$

$$A = \{1, 2, 2, 3, 3, 4, 6, 7, 8\}, m = 3, B = 12 \implies \{1, 3, 8; 2, 4, 6; 2, 3, 7\}$$

List-Scheduling (LS) algorithm

List-Scheduling algorithm (JH 4.2.1.4)

- ▶ online
- ▶ assign job to the least heavily loaded

$$J = 2, 3, 4, 6, 2, 2$$
 $m = 3$

LS is 2-approx.

$$T \text{ vs. } T^* : \frac{T}{T^*}$$

$$T^* \ge \frac{1}{m} \sum_{j} t_j$$

$$T^* \ge \max_{j} t_j$$

- 1. M_i : with the maximum load
- 2. J_i : the last job on M_i

$$ms_i \le \sum_j t_j \implies s_i \le \frac{1}{m} \sum_j t_j \le T^*$$

$$T = c_i = s_i + p_i \le T^* + T^* = 2T^*$$



2-approx. is (almost) tight

$$n = \underbrace{m(m-1)}_{p_i=1} + \underbrace{1}_{p_i=m}$$

$$\frac{T}{T^*} = \frac{2m-1}{m} = 2 - \frac{1}{m}$$

LS is $(2-\frac{1}{m})$ -approx.

$$ms_i \le \sum_{j \ne i} p_j = \frac{1}{m} (\sum_j p_j - p_i)$$
$$= \frac{1}{m} \sum_j p_j - \frac{1}{m} p_i$$
$$\le T^* - \frac{1}{m} p_i$$

$$T = c_i = s_i + p_i$$

$$\leq T^* + (1 - \frac{1}{m})p_i$$

Sorting-Scheduling algorithm

Sorting-Scheduling algorithm (JH 4.2.1.5)

Longest Processing Time (LPT) rule:

- ► sorting non-increasingly
- ▶ applying LS
- 1. M_i : with the maximum load
- 2. J_i : the last job on M_i

$$|M_i| = 1 \implies T = T^*$$

$$|M_i| \ge 2 \implies p_i \le \frac{1}{2}T^*$$

$$\implies T = s_i + p_i \le (\frac{3}{2} - \frac{1}{2m})T^*$$



LPT rule is $(\frac{4}{3} - \frac{1}{2m})$ -approx.

$$p_1 \ge p_2 \ge \cdots \ge p_n$$

CASE
$$p_i \leq \frac{1}{3}T^*$$
:

$$T \le \left(\frac{4}{3} - \frac{1}{3m}\right)T^*$$

CASE
$$p_i > \frac{1}{3}T^*$$
:

$$p_i \equiv p_n(\text{w.l.o.g: } T \text{ unchanged; } T^* \text{ not smaller})$$

$$\implies p_1 \ge p_2 \ge \dots \ge p_n > \frac{1}{3} T^* \implies |M_i| \le 2$$

$$\implies n \le 2m \implies n = 2m - h \xrightarrow{\text{exchange}} T = T^*$$

$$(\frac{4}{3} - \frac{1}{3m})$$
-approx. is tight

$$n = 2m + 1$$

LPT:
$$J_1 = x$$
, $J_{2m} = y$, $J_{2m+1} = z$
OPT: $J_{2m-1} = J_{2m} = J_{2m+1} = y$
 $vs. \frac{x+2y}{3y} = \frac{4}{3} - \frac{1}{3m}$

$$J = \{2m - 1, 2m - 1, \dots, m + 1, m + 1, m, m, m\}$$

Reference

- ▶ "Bounds on Multiprocessing Timing Anomalies" by R.L.Graham, 1969
- ▶ "Approximation Algorithms for NP-Hard Problems" edited by Dorit Hochbaum, 1996 (Theorem 1.5)

PTAS for MS

- 1. M_i : with the maximum load
- 2. J_i : the last job on M_i

$$T = s_i + p_i \le T^* + p_i$$

- 1. $J = J_L \triangleq \{\text{long jobs}\} \uplus J_S \triangleq \{\text{short jobs}\}$
- 2. S_L : the optimal schedule for J_L
- 3. S: apply List-Scheduling to S_L and J_S

Reference

► "The Design of Approximation Algorithms" by David P. Williamson and David Shmoys, 2011 (Section 3.2).



PTAS for MS

1. Split J:

$$J_i \in J_S \iff p_i \le \epsilon \cdot \frac{1}{m} \sum_j p_j$$

$$\implies |J_L| < \frac{1}{\epsilon} \cdot m$$

2. Time for S_L (*m* being a constant!):

$$m^{\frac{1}{\epsilon} \cdot m} \cdot O(n)$$

3. Approx. ratio $(p_i \in J_S \text{ case})$:

$$T = s_i + p_i \le \frac{1}{m} \sum_j p_j + \epsilon \cdot \frac{1}{m} \sum_j p_j$$
$$= (1 + \epsilon) \frac{1}{m} \sum_j p_j$$
$$\le (1 + \epsilon) T^*$$

No FPTAS for MS

Theorem $(MS \in PTAS \setminus FPTAS)$

No FPTAS for MS.

MS is strongly NP-complete \implies MS with $\max_{j} p_{j} \leq q(n)$ is NP-complete

Reference

► "The Design of Approximation Algorithms" by David P. Williamson and David Shmoys, 2011 (Section 3.2).

No FPTAS for MS

Theorem

$\exists FPTAS \ for \ MS \implies MS \in P.$

$$A_{\epsilon} : \epsilon = \frac{1}{\lceil 2nq(n) \rceil}$$

$$(1+\epsilon)T^* = T^* + \epsilon \cdot T^*$$

$$\leq T^* + \frac{1}{\lceil 2nq(n) \rceil} \cdot nq(n)$$

$$\leq T^* + \frac{1}{2}$$

Time:
$$\operatorname{Poly}(\frac{1}{\epsilon}, n) = \operatorname{Poly}(\lceil 2nq(n) \rceil, n) = \operatorname{Poly}(n)$$

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