

# 3-8 Cool? We are APSP Algorithms.

Hengfeng Wei

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Please Help Me Out Here.

## Definition (Shortest Path)

$G = (V, E, w) : \text{weighted digraph}$

$$\delta(u, v) = \begin{cases} \min \{w(p) : u \rightsquigarrow^p v\} & \text{if } u \rightsquigarrow v \\ \infty & \text{o.w.} \end{cases}$$

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Shortest-path Problem *vs.* Longest-path Problem

Digraph *vs.* Undirected Graph

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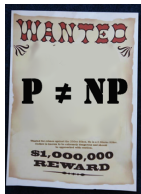
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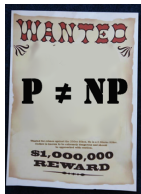
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NP-hard

# Shortest Path Problem

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Shortest Path Problem

Longest Path Problem

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Longest Path Problem

Shortest Simple Path Problem



Longest Simple Path Problem

Single Source

Undirected Graph

Single Source      Undirected Graph

Negative-weight edges allowed      (Why?)

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Simple path      (Why?)

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Single-source  $s \rightsquigarrow$  Single-target  $t$

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Luis Goddyn, Math 408

Given an edge weighted graph  $(G, d)$ ,  $d : E(G) \rightarrow \mathbb{Q}$  and two vertices  $s, t \in V(G)$ , the *Shortest Path Problem* is to find an  $s, t$ -path  $P$  whose total weight is as small as possible. Here,  $G$  may be either directed or undirected. A path in a graph is a sequence  $v_0 e_1 v_1, \dots, v_k$  of vertices and edges such that no vertex or edge appears twice, and  $e_i$  joins  $v_{i-1}$  to  $v_i$ . If  $G$  is directed, then  $e_i$  should be oriented from  $v_{i-1}$  to  $v_i$ .

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And Errors.

INTERESTED?  
*let's talk.*



## Robert W. Floyd (1936–2001)

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*the theory of parsing, the semantics of programming languages, automatic program verification, automatic program synthesis, and analysis of algorithms*

— *Turing Award*, 1978

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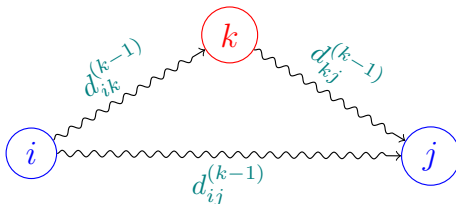
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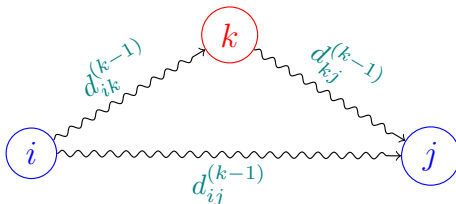
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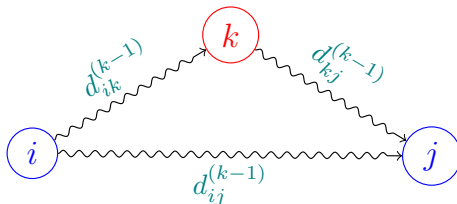
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$\dots$ , but we assume that there are **no** negative-weight cycles.

— Section 25.2 of CLRS

---

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1: procedure FLOYD-WARSHALL( $W$ )
2:    $D^{(0)} = W$ 
3:   for  $k \leftarrow 1$  to  $n$  do
4:      $D^{(k)} \triangleq \left( d_{ij}^{(k)} \right) \leftarrow$  a new  $n \times n$  matrix
5:     for  $i \leftarrow 1$  to  $n$  do
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$$\text{Space} : \Theta(n^3) \implies \Theta(n^2)$$

## FLOYD-WARSHALL Made Simple (Problem 25.2-4)

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$d_{ij}^{(k-1)}, d_{ik}^{(k-1)}, d_{kj}^{(k-1)}$  does not change.

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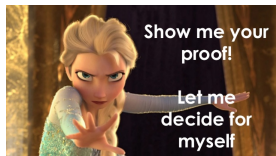
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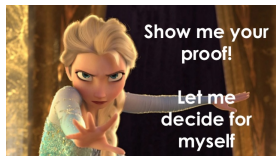
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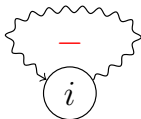
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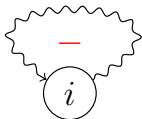
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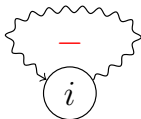


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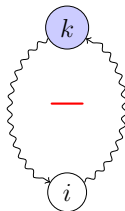
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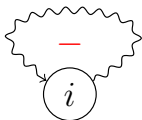
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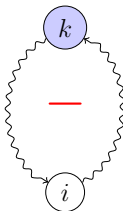
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$$L^{(n-1)} \triangleq \left( l_v^{(n-1)} \right)$$

## SSSP as a Product of Matrices and a Vector (Problem 25.1-5)

To express SSSP as a **product** of matrices and a vector.



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$$L^{(1)} = \langle w_{sv} \rangle_{v \in V}$$

$$L^{(2)} = L^{(1)} \cdot W$$

$$\dots = \dots$$

$$L^{(n-1)} = \left( \left( \left( L^{(1)} \cdot W \right) \cdot W \right) \cdot \dots \cdot W \right)$$

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$$d_v^{(0)} = \begin{cases} 0 & v = s \\ \infty & v \neq s \end{cases}$$

---

```
1: procedure BELLMAN-FORD-DP( $G, w, s$ )
2:    $d[0, s] \leftarrow 0$ 
3:   for  $(v \neq s) \in V$  do
4:      $d[0, v] \leftarrow \infty$ 
5:   for  $i \leftarrow 1$  to  $|V| - 1$  do
6:     for  $v \in V$  do
7:        $d[i, v] = \infty$ 
8:       for  $(u, v) \in E$  do
9:         if  $d[i, v] > d[i - 1, u] + w(u, v)$  then ▷
10:           $d[i, v] = d[i - 1, u] + w(u, v)$ 
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8:       for  $(u, v) \in E$  do
9:         if  $d[i, v] > d[i - 1, u] + w(u, v)$  then           ▷ Simplify?
10:           $d[i, v] = d[i - 1, u] + w(u, v)$ 
```

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---

```
1: procedure BELLMAN-FORD-DP-SIMPLIFIED( $G, w, s$ )
2:    $d[s] \leftarrow 0$ 
3:   for  $(v \neq s) \in V$  do
4:      $d[v] \leftarrow \infty$ 
5:   for  $i \leftarrow 1$  to  $|V| - 1$  do
6:     for  $v \in V$  do
7:       for  $(u, v) \in E$  do
8:         if  $d[v] > d[u] + w(u, v)$  then ▷
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▷ Relax!

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8:         if  $d[v] > d[u] + w(u, v)$  then                                 $\triangleright$  Relax!
9:            $d[v] = d[u] + w(u, v)$ 
```

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```
1: procedure BELLMAN-FORD-WITHOUT-NE( $G, w, s$ )
2:   INIT-SINGLE-SOURCE( $G, s$ )

3:   for  $i \leftarrow 1$  to  $|V| - 1$  do
4:     for  $(u, v) \in E$  do
5:       RELAX( $u, v, w$ )
```

---

Bellman-Ford:  $L \cdot W$

SLOW-ALL-PAIRS-SHORTEST-PATHS:  $W \cdot W$

Bellman-Ford:  $L \cdot W$

SLOW-ALL-PAIRS-SHORTEST-PATHS:  $W \cdot W$

SLOW-ALL-PAIRS-SHORTEST-PATHS is  $n$  instances of Bellman-Ford,  
one for each source.





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