List of derivations for minor (symbols have their usual meanings)

Derive the angular momentum of an RB about a moving point A w.r.t ref. frame F

where, $H_{A|F} = \int (Y_{PA} \times V_{PA|F}) dm$ and pt C is the COM of body

the RB

Q) Given
$$| \rangle H_{AII} = H_{CII} + m(r_{CA} \times Y_{CAII}),$$

 $| \Rightarrow \frac{d}{dt} \{ H_{OII} \} |_{I} = M_{o} \text{ (Euler's 2nd axiom)} \}$
derive:

where A is a moving pt w.r.t an inertia frame I and MA is the net moment due to all external forces octing on the RB about point A. O is a point fixed to I.

3) Storting from the defition of angular momentum of an RB as $H_{AIF} = \int (Y_{PA} \times Y_{PAIF}) dm$

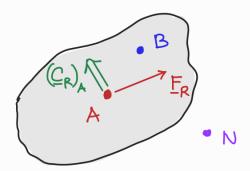
derive the relationship between the angular momentum about a point A fixed on RB (\underline{H}_{AlF}) to the angular velocity \underline{W}_{mlF}

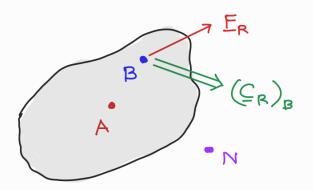
$$(\underline{H}_{A})_{i} = I_{ij}^{A} \omega_{j}$$
, where $I_{ij}^{A} = \int (\Upsilon^{2} \delta_{ij} - \varkappa_{i} \varkappa_{j}) dm$

Note: $\left| \Upsilon_{PA} \right| = \Upsilon$

and
$$\Upsilon_{PA} = \chi_1 \hat{e}_1 + \chi_2 \hat{e}_2 + \chi_3 \hat{e}_3 = \chi_p \hat{e}_p$$

4) Given two force systems (left and right)





Find the relationship between $(\subseteq_R)_A$ and $(\subseteq_R)_B$ if
the net resultant moments of the two systems about pt A
is the same. i.e. $M_A = M_A'$

Further, prove that $\underline{M}_N = \underline{M}_N'$, where N is another point in space (no restrictions)