

Lecture 1

APL104

Solid Mechanics

Instructors: Prof. Ajeet Kumar, Prof. Rajdip Nayek

TAs:

Course website:

Minor - 30%

Major - 40%

2 quizzes: 10x2

Attendance: 10% ($> 80\%$)

Reference book

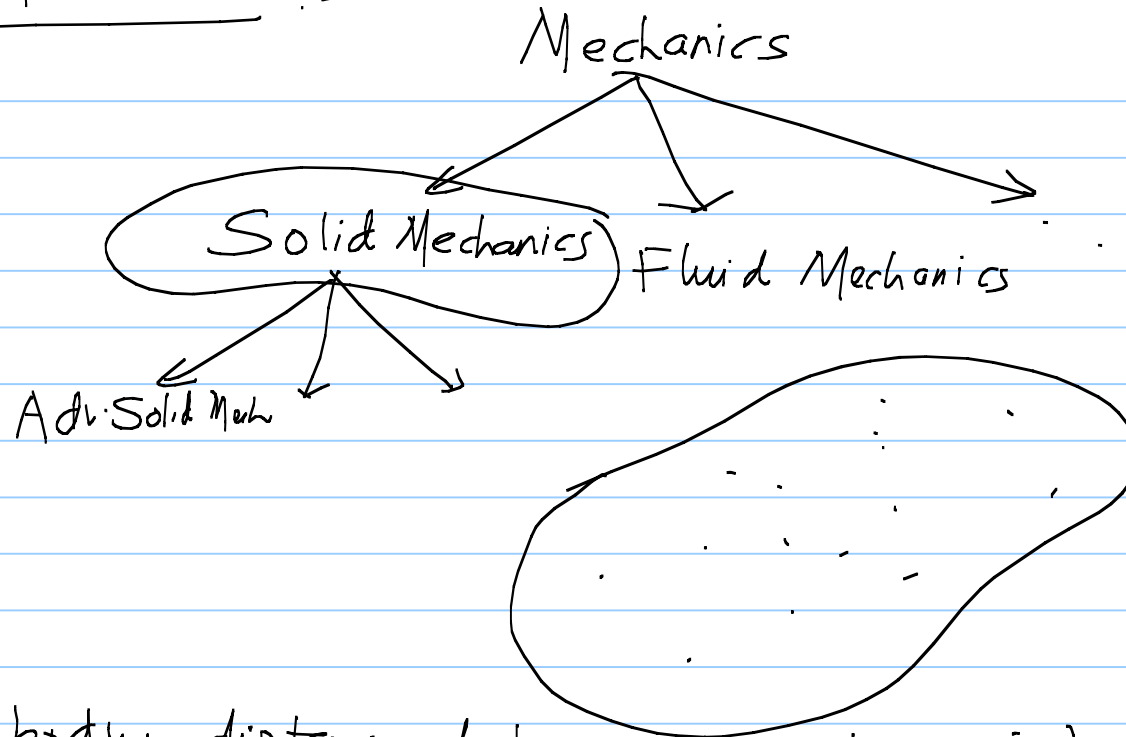
→ Advanced Mechanics of Solids
(LS Srinath)

→ Strength of Materials (Timoshenko)

↓
Father of Solid Mech.

→ If it is not more than 80%, you will fail

Solid Mechanics :-

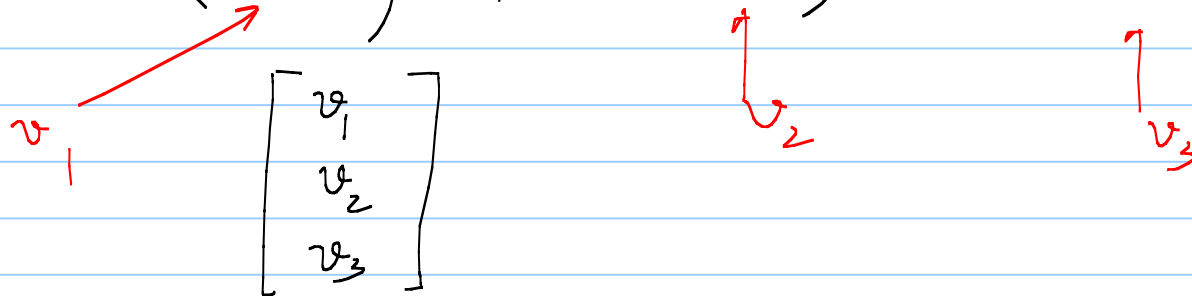


rigid body: distance between any two points remain the same!

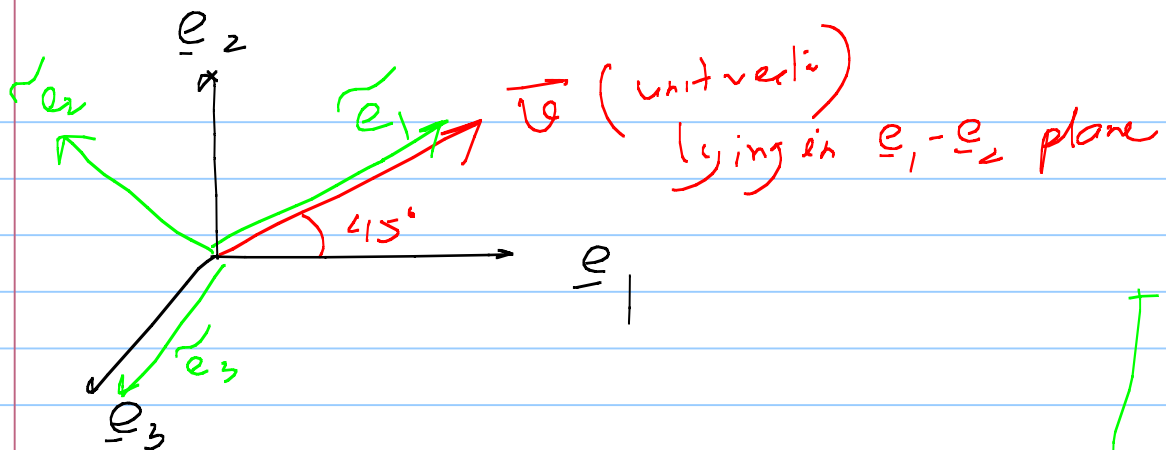
Mathematical preliminaries

Vectors: A vector has magnitude and direction

$$\vec{v} = (\vec{v} \cdot \hat{e}_1) \hat{e}_1 + (\vec{v} \cdot \hat{e}_2) \hat{e}_2 + (\vec{v} \cdot \hat{e}_3) \hat{e}_3$$


$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

→ A vector is independent of the coordinate system whereas its components (its column form) are dependent on the coordinate system.



$$\begin{bmatrix} \underline{v} \end{bmatrix}_{(\underline{e}_1, \underline{e}_2, \underline{e}_3)} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \tilde{\underline{v}} \end{bmatrix}_{(\tilde{\underline{e}}_1 - \tilde{\underline{e}}_2 - \tilde{\underline{e}}_3)} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$