Legend: RoboMonkey, π_0, π_0 + Inst. Aug., π_0 + Rand. Reph., CoVer-VLA, CoVer-VLA + Inst. Aug.
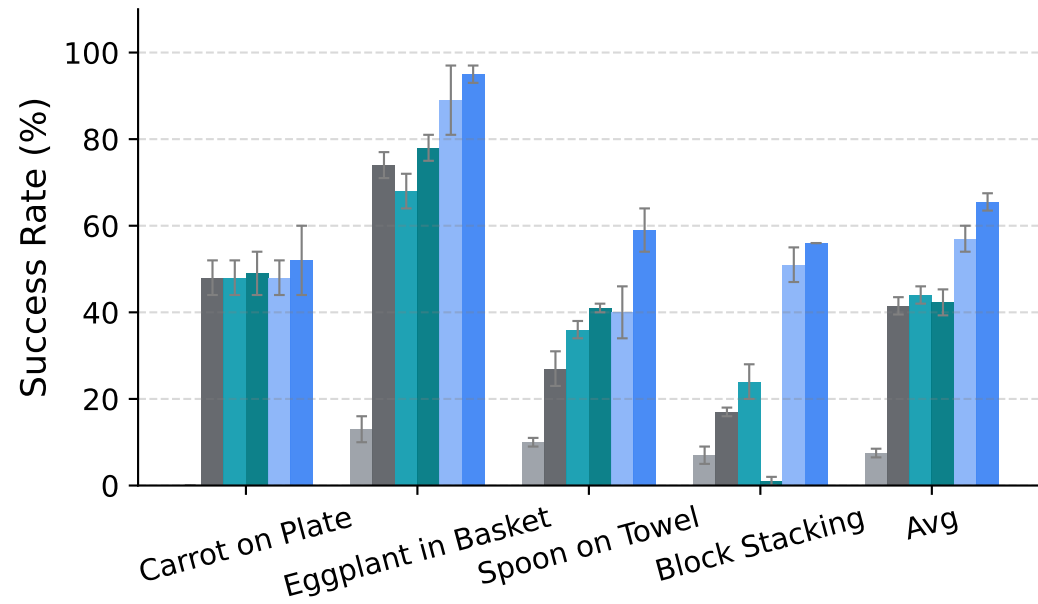
In-Distribution Environments — Success Rate (%) vs. Carrot on Plate, Eggplant in Basket, Spoon on Towel, Block Stacking, Avg

Out-of-Distribution Environments — Success Rate (%) vs. Redbull on Plate, Zucchini on Towel, Tennis in Basket, Avg