

## Chapter 7

# Integration of a function of one variable: Revision

{chap:7}

### 7.1 Indefinite Integrals: Swokowski Chapter 4

{sec:7.1}

The integral of a function  $f(x)$  is denoted by  $\int f(x)dx$ . It is called the *indefinite integral* because the limits are not specified.

What does it mean? What does it tell us?

Some people like to think of it as the area under a curve  $y = f(x)$  but this is not always helpful. For example,  $f(x)$  could be negative! We will come back to this later. An indefinite integral is itself a function of  $x$ , denoted by  $F(x)$ , where  $F$  satisfies

$$\frac{dF}{dx} = f(x).$$

So, the indefinite integral is the function  $F(x)$  whose derivative is the integrand,  $f(x)$ . This is why  $F(x)$  is sometimes called the *anti-derivative*. Note that if you can find a function  $F(x)$  satisfying  $\frac{dF}{dx} = f(x)$ , then  $F(x) + C$ , where  $C$  is any constant, *also* satisfies  $d(F + C)/dx = f(x)$  because  $dC/dx = 0$ .  $F$  is, therefore, only known to within an arbitrary constant.

Sometimes, in say some physical application, we are given additional information that allows us to choose the constant  $C$  uniquely.

Why is integration an art?  $F(x)$  is not known for every  $f(x)$  because some integrals are just too tough. Not in this course, however! On the other hand, you can take the derivative of every (reasonable) function  $F(x)$  to get  $f(x)$ . For these  $f(x)$ ,  $F(x)$  is obviously known.

There is no systematic procedure to integrate analytically (we can always do definite integrals numerically to whatever accuracy we desire), but there are a finite number of methods to try when faced with a new integral.

### 7.2 Techniques of Integration: Swokowski Chapter 7

{sec:7.2}

Here are a few standard techniques of integration that you have met either at school or in earlier modules. They are important to know and require practice to become proficient in integration.

### 7.2.1 Integration by parts

{subsec:7.2.1}

We express

$$f(x) = u(x) \frac{dv(x)}{dx},$$

and use

{7.1}

$$\int u \frac{dv}{dx} dx = uv - \int \frac{du}{dx} v dx. \quad (7.1)$$

By suitable choices of  $u$  and  $v$  (usually based on experience that comes from practice), the integral on the r.h.s. can be made into a simpler integral. This is particularly effective when  $u$  is an integer power of  $x$  and  $dv/dx$  is either a trigonometric function or an exponential (including hyperbolic) function.

### 7.2.2 Partial Fractions

.2.2}

This is useful when  $f(x)$  is the ratio of two polynomials, for example,

$$f(x) = \frac{a_1 x + a_0}{b_2 x^2 + b_1 x + b_0},$$

and when the degree of the numerator is less than the degree of the denominator, namely 1 and 2 respectively in this example. The idea is to factorise the denominator in linear factors. This can always be done *provided we allow for complex factors*. Then, we rewrite  $f(x)$  as a sum of fractions where the denominators only contain polynomials of degree 1.

Let's illustrate these ideas with a couple of examples.

#### Example 7.46

Integrate

$$f(x) = \frac{1}{(x-1)(x+1)}.$$

#### Solution 7.46

Here we split the expression into the two fractions

$$\frac{1}{(x-1)(x+1)} = \frac{A}{x-1} + \frac{B}{x+1},$$

where we need to find the values for  $A$  and  $B$ . The cover-up rule can be used but I prefer to use the fail-safe method of recombining the fractions with a common denominator (basically the product of all the linear, and possible quadratic, factors). Thus, we express

$$\frac{A}{x-1} + \frac{B}{x+1} = \frac{A(x+1) + B(x-1)}{(x-1)(x+1)}.$$

Comparing with the original function, we must have

$$A(x+1) + B(x-1) = 1, \quad \text{for all } x.$$

Since this is true for all  $x$ , it must be true for  $x = 1$  and  $x = -1$ . Choosing  $x = 1$  we have

$$2A = 1, \quad \Rightarrow \quad A = \frac{1}{2}.$$

Choosing  $x = -1$ , we have

$$-2B = 1, \quad \Rightarrow \quad B = -\frac{1}{2}.$$

Thus, we have

$$\int \frac{1}{(x-1)(x+1)} dx = \int \frac{1}{2} \frac{1}{x-1} - \frac{1}{2} \frac{1}{x+1} dx = \frac{1}{2} \int \frac{1}{x-1} dx - \frac{1}{2} \int \frac{1}{x+1} dx.$$

Finally, the integrals give logarithms and so

$$\int \frac{1}{(x-1)(x+1)} dx = \frac{1}{2} \log |x-1| - \frac{1}{2} \log |x+1| + C = \frac{1}{2} \log \frac{|x-1|}{|x+1|} + C = \log \left( \frac{|x-1|}{|x+1|} \right)^{1/2} + C$$

### Example End

### Example 7.47

Integrate

$$f(x) = \frac{1}{x^2 - 3x + 2}.$$

### Solution 7.47

First of all, we need to factorise the denominator. Thus,

$$x^2 - 3x + 2 = (x-1)(x-2).$$

If this is not obvious, then you obtain the roots of the quadratic  $x^2 - 3x + 2 = 0$ . Hence, the roots are  $(3 \pm \sqrt{9-8})/2 = 2$  or  $1$ . Now we use partial fractions

$$\frac{1}{x^2 - 3x + 2} = \frac{A}{x-1} + \frac{B}{x-2} = \frac{A(x-2) + B(x-1)}{(x-1)(x-2)} \quad \Rightarrow \quad A(x-2) + B(x-1) = 1.$$

As this must be true for all  $x$ , we set  $x = 1$  to get  $A = -1$  and  $x = 2$  to get  $B = 1$ . Thus,

$$\int \frac{1}{x^2 - 3x + 2} dx = \int -\frac{1}{x-1} + \frac{1}{x-2} dx = -\log |x-1| + \log |x-2| + C = \log \left( \frac{|x-2|}{|x-1|} \right) + C.$$

### Example End

Probably, it is worth reminding you that the integral of  $1/x$  is  $\log |x|$ . Obviously we can drop the modulus signs when  $x$  is positive.

### 7.2.3 Substitution

{subsec:7.2.3}

This is one of the most effective methods and will be used in many subsequent modules. The general idea is to make a change of variable or *substitution* of the form  $s = g(x)$  (or maybe  $x = g(s)$ ), for some cleverly chosen function  $g$ , which reduces

$$\int f(x)dx \text{ to } \int h(s)ds,$$

where  $h(s)$  is simpler to integrate. How do you know what function to choose for the substitution? Well this really comes down to knowing the standard integrals. If the integral is not a standard integral, then you need to choose a substitution to put it into a standard form. We illustrate the idea through a few examples.

#### Example 7.48

Integrate  $f(x) = x/(x^2 - 1)$  with respect to  $x$ . Note, I am going to emphasise which variable we are integrating with respect to now. This is important when using substitutions. Thus, we wish to evaluate

$$I = \int \frac{x}{x^2 - 1} dx.$$

#### Solution 7.48

We could do this by partial fractions as above but instead we try the substitution

$$s = x^2 - 1, \quad \Rightarrow \quad \frac{ds}{dx} = 2x, \quad \Rightarrow \quad ds = 2x dx.$$

Thus, we replace  $x^2 - 1$  by  $s$  and  $dx$  by  $ds/2$  to obtain

$$\int \frac{x}{x^2 - 1} dx = \int \frac{ds/2}{s} = \frac{1}{2} \int \frac{1}{s} ds = \frac{1}{2} \log |s| + C.$$

Finally, we replace  $s$  by  $x^2 - 1$  to get the answer in terms of  $x$ . Hence,

$$\int \frac{x}{x^2 - 1} dx = \frac{1}{2} \log |x^2 - 1| + C.$$

Note that when we did the substitution, *all*  $x$ 's were replaced by  $s$ 's. Thus the integration was done with respect to  $s$ . This is important. You *cannot* substitute only some of the integrand in terms of  $s$  and leave some in terms of  $x$ . That just *does not* work.

#### Example End

#### Example 7.49

Integrate

$$\int \frac{1}{x^2 + 1} dx.$$

This looks like the last example but the simple substitution  $s = x^2 + 1$  *does not* help here. Instead we need some inspiration, or better recognise that this form can always be done using a trigonometric substitution.

**Solution 7.49**

First of all, we remind you of a few trigonometric identities.

$$\begin{aligned}\sin^2 \phi + \cos^2 \phi &= 1, \\ \text{divide both sides by } \cos^2 \phi & \\ \tan^2 \phi + 1 &= \sec^2 \phi.\end{aligned}$$

Remember that

$$\frac{\sin \phi}{\cos \phi} = \tan \phi \text{ and } \sec \phi = \frac{1}{\cos \phi}.$$

Finally, the last reminder before completing this example involves the derivatives of trigonometric functions. These should be memorised!

$$\begin{aligned}\frac{d}{d\phi} \sin \phi &= \cos \phi, \\ \frac{d}{d\phi} \cos \phi &= -\sin \phi, \\ \frac{d}{d\phi} \tan \phi &= \sec^2 \phi, \\ \frac{d}{d\phi} \sec \phi &= \sec \phi \tan \phi.\end{aligned}$$

Now we are ready to progress! Set

$$x = \tan \phi, \quad \Rightarrow \quad \frac{dx}{d\phi} = \sec^2 \phi \quad \Rightarrow \quad dx = \sec^2 \phi d\phi.$$

Using  $\tan^2 \phi + 1 = \sec^2 \phi$ , we have  $x^2 + 1 = \sec^2 \phi$ . Therefore,

$$\frac{1}{x^2 + 1} = \frac{1}{\sec^2 \phi} = \cos^2 \phi.$$

Thus,

$$\int \frac{1}{x^2 + 1} dx = \int \cos^2 \phi (\sec^2 \phi d\phi) = \int d\phi = \phi + C.$$

Hence, substituting back for  $x$  (using the fact that if  $x = \tan \phi$ , then  $\phi = \tan^{-1} x$  where the power *minus one* means *INVERSE FUNCTION* and not reciprocal) we have

$$\int \frac{1}{x^2 + 1} dx = \tan^{-1} x + C.$$

The natural extension of this gives the standard integral

$$\int \frac{1}{x^2 + a^2} dx = \frac{1}{a} \tan^{-1} \left( \frac{x}{a} \right) + C.$$

**Example End**

**Example 7.50**

This example uses the same idea of trigonometric substitutions. Consider

$$\int \frac{1}{\sqrt{a^2 - x^2}} dx.$$

**Solution 7.50**

For expressions involving purely  $\sqrt{a^2 - x^2}$  (and powers of this square root) always try

$$x = a \sin \phi.$$

[As an aside, note that the integrand  $x/\sqrt{a^2 - x^2}$  could use the simpler substitution  $u = a^2 - x^2$ .]

Since,

$$\begin{aligned} \sin^2 \phi + \cos^2 \phi &= 1, \\ a^2 \sin^2 \phi + a^2 \cos^2 \phi &= a^2, \\ x^2 + a^2 \cos^2 \phi &= a^2, \\ a^2 \cos^2 \phi &= a^2 - x^2 \quad \Rightarrow \quad \sqrt{a^2 - x^2} = a \cos \phi. \end{aligned}$$

So the denominator simplifies to  $a \cos \phi$ . What about the  $dx$ ? Thus,

$$x = a \sin \phi \quad \Rightarrow \quad \frac{dx}{d\phi} = a \cos \phi \quad \Rightarrow \quad dx = a \cos \phi d\phi.$$

Substituting these into the original integral gives,

$$\int \frac{1}{\sqrt{a^2 - x^2}} dx = \int \frac{1}{a \cos \phi} a \cos \phi d\phi = \int d\phi = \phi + C.$$

Finally, substituting back in terms of  $x$  gives

$$\int \frac{1}{\sqrt{a^2 - x^2}} dx = \sin^{-1} \left( \frac{x}{a} \right) + C.$$

**Example End****Example 7.51**

One last common trigonometric substitution involves integrals of the form

$$\int \frac{1}{\sqrt{x^2 - a^2}} dx.$$

Note that we cannot use  $x = a \sin \phi$  because  $\sin \phi$  is less than or equal to one and so  $x$  is less than or equal to  $a$ . Therefore,  $x^2 - a^2$  is less than or equal to zero. Hence, we cannot take the square root. The assumption must be that  $x$  is greater or equal to  $a$ . We need another substitution.

**Solution 7.51**

Instead we make use of

$$\tan^2 \phi + 1 = \sec^2 \phi.$$

Rearranging this gives

$$\tan^2 \phi = \sec^2 \phi - 1.$$

Multiplying by  $a^2$  and comparing with the denominator suggests trying

$$x = a \sec \phi \Rightarrow x^2 - a^2 = a^2 \sec^2 \phi - a^2 = a^2 \tan^2 \phi.$$

So far so good. Now we need to replace  $dx$  by the correct expression involving only  $\phi$  and  $d\phi$ . Thus,

$$\begin{aligned} \frac{dx}{d\phi} &= a \sec \phi \tan \phi \\ dx &= a \sec \phi \tan \phi d\phi. \end{aligned}$$

Thus we have converted the original integral into

$$\int \frac{1}{\sqrt{x^2 - a^2}} dx = \int \frac{1}{a \tan \phi} a \sec \phi \tan \phi d\phi = \int \sec \phi d\phi = \int \frac{d\phi}{\cos \phi}.$$

This integral may appear simpler but still requires a bit of effort to get a final answer. This illustrates that you may need to do several substitutions to get to the actual result.

To proceed, and I suspect you would never guess this, consider the two derivatives discussed above,

$$\begin{aligned} \frac{d}{d\phi} \tan \phi &= \sec^2 \phi, \\ \frac{d}{d\phi} \sec \phi &= \sec \phi \tan \phi. \end{aligned}$$

Add these equations together to get

$$\begin{aligned} \frac{d}{d\phi} (\tan \phi + \sec \phi) &= \sec^2 \phi + \sec \phi \tan \phi, \\ &= \sec \phi (\tan \phi + \sec \phi). \end{aligned}$$

Hence, we have the result

$$\frac{1}{v} \frac{dv}{d\phi} = \sec \phi,$$

where

$$v = \tan \phi + \sec \phi.$$

Therefore,

$$\int \sec \phi d\phi = \int \frac{1}{\cos \phi} d\phi = \int \frac{1}{v} dv = \log |v| + C = \log |\tan \phi + \sec \phi| + C.$$

This is not a result I would expect you know.

**Example End**

**Example 7.52**

Consider

$$\int \frac{x}{\sqrt{x^2 - a^2}} dx.$$

**Solution 7.52**

It is the  $x dx$  that appears in the numerator that should warn you that a simple trigonometric substitution will not work. The correct substitution to use is

$$u = x^2 - a^2 \quad \Rightarrow \quad \frac{du}{dx} = 2x \quad \Rightarrow \quad \frac{1}{2} du = x dx.$$

Hence, the original integral can be re-written as

$$\int \frac{x}{\sqrt{x^2 - a^2}} dx = \frac{1}{2} \int \frac{1}{\sqrt{u}} du = \frac{1}{2} \int u^{-1/2} du.$$

Therefore,

$$\int \frac{x}{\sqrt{x^2 - a^2}} dx = u^{1/2} + C = \sqrt{x^2 - a^2} + C.$$

Note that you can always check that you have done the integration correctly by differentiating and retrieving the original integrand. Remember

$$F(x) = \int f(x) dx \quad \Longleftrightarrow \quad \frac{dF}{dx} = f(x).$$

**Example End****7.3 Definite Integrals**

These refer to integrals with *limits*, i.e.

$$\int_a^b f(x) dx. \tag{7.2}$$

Remember that the answer is a *number* if  $a$  and  $b$  are numbers. It is *NOT* a function of  $x$ . However, we can use the indefinite integral, which is a function of  $x$ , as an intermediate step. Let

$$F(x) = \int f(x) dx, \quad \text{or equivalently} \quad \frac{dF}{dx} = f(x),$$

Then

$$\int_a^b f(x) dx = [F(x)]_a^b = F(b) - F(a). \tag{7.3}$$

Note we could think of the integral as being a function of the end points. This will be useful when the integrals are double integrals and the limits in, say  $x$ , involve functions of  $y$ . More on this later.



**Example 7.53**

Consider

$$I = \int_0^{\pi/4} \tan x dx.$$

What is the value of the *number*  $I$ ?

**Solution 7.53**

First step is to find the indefinite integral.

$$F(x) = \int \tan x dx = \int \frac{\sin x}{\cos x} dx.$$

Use the substitution  $u = \cos x$ , so that

$$u = \cos x \quad \Rightarrow \quad \frac{du}{dx} = -\sin x \quad \Rightarrow \quad du = -\sin x dx.$$

Hence,

$$F = \int \frac{\sin x}{\cos x} dx = - \int \frac{1}{u} du = -\log |u| + C.$$

Finally, we can replace  $u$  by  $\cos x$  in the answer. Remember that the constant  $C$  is *NOT* important when evaluating definite integrals. Thus,

$$I = \int_0^{\pi/4} \tan x dx = [-\log |\cos x|]_0^{\pi/4} = -\log |\cos(\pi/4)| + \log |\cos(0)|.$$

Hence,

$$I = -\log \left( \frac{1}{\sqrt{2}} \right) + \log 1 = \log \left( \frac{1}{\sqrt{2}} \right)^{-1} + 0 = \log \sqrt{2}$$

There are, of course, other ways of writing this answer, such as  $I = (1/2) \log 2$ , but the final number is  $I \approx 0.346$ .

**Example End**

**7.4 Linearity**

{sec:7.4}

This section contains some obvious (and perhaps not so obvious) properties of integrals.

1.

$$\int (f(x) + g(x)) dx = \int f(x) dx + \int g(x) dx.$$

2.

$$\int cf(x) dx = c \int f(x) dx$$

where  $c$  is a constant. This means that Integration is a *vector space*.

3.

$$\int_a^b f(x)dx = \int_a^c f(x)dx + \int_c^b f(x)dx.$$

Thus, you can always split the integration range into smaller pieces and still get the same result. In a sense, this comes from the fact the *integration is the limit of a sum*. The formal definition of an integral is

$$\int f(x)dx = \lim_{\delta x \rightarrow 0} \sum_{i=1}^n f(x_i)\delta x,$$

where  $x_0 = a$  and  $x_n = b$ , which means that  $n\delta x = b - a$ . Thus, as  $\delta x \rightarrow 0$ ,  $n \rightarrow \infty$ .

4.

$$\int_a^b f(x)dx = - \int_b^a f(x)dx.$$

Hence, switching the limits switches the sign in front of the integral (but the value of  $I$  remains the same). From above with  $b = a$ , we have

$$\int_a^a f(x)dx = 0 = \int_a^c f(x)dx + \int_c^a f(x)dx, \Rightarrow \int_a^c f(x)dx = - \int_c^a f(x)dx,$$

as stated above.

Chopping the range of integration up can be very useful. One particular instance is when  $f(x) \rightarrow \infty$  at a point  $c$ , with  $a < c < b$ , but the integral still exists. It just depends on how ‘singular’  $f$  is at  $c$ . The integral exists if  $\lim_{x \rightarrow c} \{(x - c)f(x)\} = 0$ .

### Example 7.54

An example is

$$f(x) = \frac{1}{\sqrt{|x - 1|}}, \quad a = 0, b = 5.$$

Note that we are using the modulus of  $x - 1$  instead the square root so that  $|x - 1|$  is always positive and we can always take the square root. The integrand is shown in Figure 7.1.

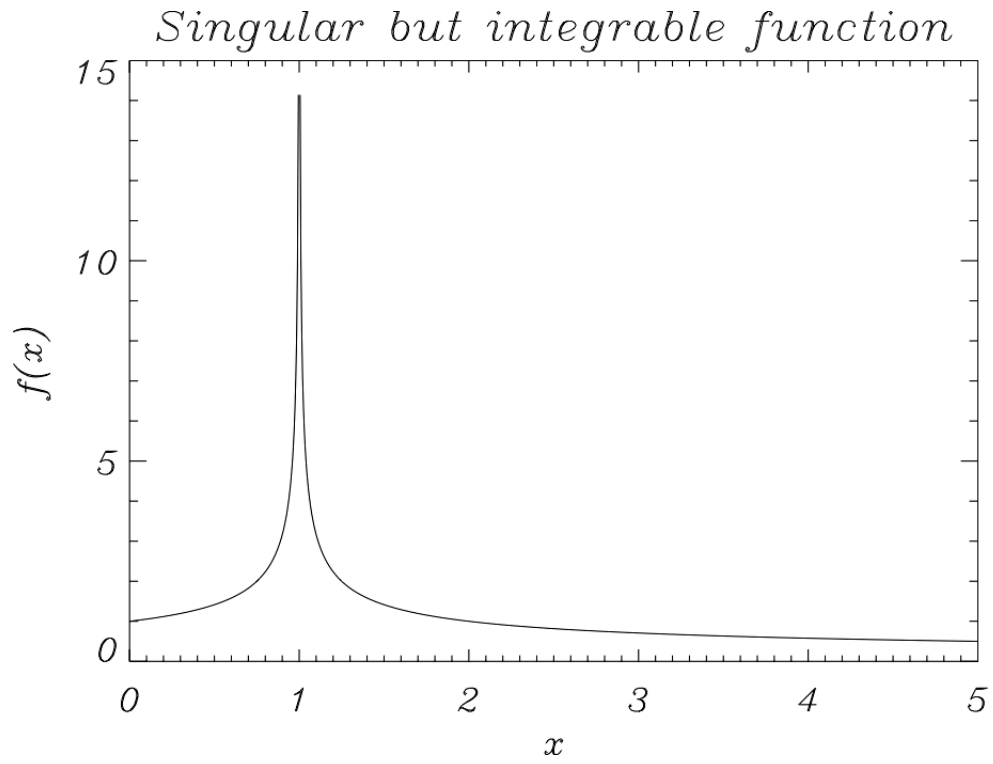
### Solution 7.54

Thus, we split the range of integration at  $x = 1$ .

$$\begin{aligned} I &= \int_0^5 \frac{1}{\sqrt{|x - 1|}} dx, \\ &= \int_0^1 \frac{1}{\sqrt{1 - x}} dx + \int_1^5 \frac{1}{\sqrt{x - 1}} dx \\ \text{since } |x - 1| &= \begin{cases} 1 - x & \text{for } x \leq 1, \\ x - 1 & \text{for } x \geq 1. \end{cases} \end{aligned}$$

The first integral has an indefinite integral,  $F(x) = -2\sqrt{1 - x}$  and so its contribution to  $I$  is  $F(1) - F(0) = 0 - (-2) = 2$ . For the second integral,  $F(x) = +2\sqrt{x - 1}$  and so its contribution to  $I$  is  $F(5) - F(1) = 2\sqrt{4} - 0 = 4$ . Hence,

$$I = 2 + 4 = 6.$$



{fig:7.1}

Figure 7.1: A singular function,  $f(x) = 1/\sqrt{|x-1|}$ , but it is integrable.

**Example End**