3.5"MICRO FLOPPY DISK DRIVE

PRELIMINARY
OEM MANUAL

CONTENTS

1.	PURPOSE		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	2
2.	(2) DC power red(3) Permitted dri(4) Environmenta	uirements ve orientation conditions		
3.		nd maintainability ACTERISTICS AND	TIMING	***************************************
	(2) Signal level (3) Input signal (4) Output signal	description		6 7 8
4.	PART NAMES AND	OPERATION		13
	(2) Cable and co (3) Pin assignmen	nnector		14
7.	DIMENSIONAL DAT	FA	RECORD OF REVISIONS	17
ſ	REVISION	DATE	NOTES	
1-	1	Apr. 1984	Original issue	
ŀ				

1. PURPOSE

This specification provides the information necessary to interface the micro floppy disk drive to floppy disk controller, and provides the technical specifications for reference in OEM contracts.

2. SPECIFICATIONS

1) PERFORMANCE

FDA-3400

		AXJ	Ą	AXJ	В	AXK	1	AXKB	
	Type	TD-3	35JA	TD-3	351B	TD-:	B5KA	TD-3	35KB
Item		FM	MFM	FM	MFM	FM	MFM	FM	MFM
CAPACITY									
Unformatted per disk	bytes	125 K	250 K	250 K	500 K	250 K		500 K	1 M
Unformatted per track	bytes	3.125K	6.25K	3.125K	6.25K	3.125K	6.25K	3.125K	6.25K
ACCESS TIME									
Track to track	msec		6		6		3		3
Average access time *1	msec		93		93		94		94
Settling time	msec		15	1	15		15		15
Average latency	msec	1	00	1	00	1	0 0	1	00
Motor start time *2	msec	5	00	5	00	5	00	5	00
FUNCTIONAL									
Max.recording density	BPI	4063	8126	4324	8647	4094	8187	4359	8717
Data transfer rate	bits/sec	125 K	250 K	125 K	250 K	125 K	250 K	125 K	250
Track density	TPI		67.5		67.5	1	35	1	35
Cylinders	pcs		40		40		80		80
Tracks	pcs		40		80		80	1	60
R/W heads	pcs		1		2		1		2
Rotational speed	rpm					300		<u> </u>	
Dimensions	mm			101.6	6(W) ×	40.0(H)	× 150.0	(D)	
(w/o Front panel)	Inch				.0(W) ×				
Weight	g,lbs				700	g, 1.54	lbs		
DC POWER CONSUMPTION				•					
operating	W					4.5W, Ty	Р		
stand-by	W					3.0W, Ty	Р		

Note: *| Average access time = 1/3 * (Track No.) * (Track to track time) * (Settling time)

*2 The lapse of time from output of the MOTOR ON signal until output of the READY signal upon sensing that the motor has reached the specified rotational speed.

2) DC POWER REQUIREMENTS

Item	status	Standby *	Operating *	During motor start-up *
DC 12V	Tolerance		± 5%	
	Max. ripple		100mVp-p	
	Current consumption	0.13A (typ)	0.25A (typ)	0.4A (max)
DC 5V	Tolerance		± 5%	
	Max. ripple		50mVp-p	
	Current consumption	0.29A (typ)	0.30A (typ)	0.5A (max)
Nominal p	ower consumption	3.0W (typ)	4.5W (typ)	

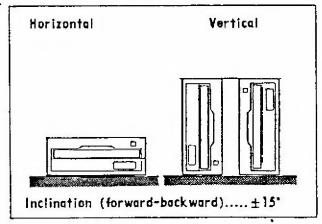
Note: * Standby, Operating, and During motor start-up resectively correspond to the following status:

	Drive motor	Recording disk	Seek operation
standby	OFF	Dismounted or mounted	OFF
Operating	٥N	Mounted	ON or OFF
During motor start-up	ОИ	Mounted	OFF

3) PERMITTED DRIVE ORIENTATION

The drive may be mounted in either a horizontal or vertical position.
In the horizontal position the drive must be positioned with the printed circuit board on top.
No other restrictions concerning

No other restrictions concerning orientation exist.



4) ENVIRONMENTAL CONDITIONS

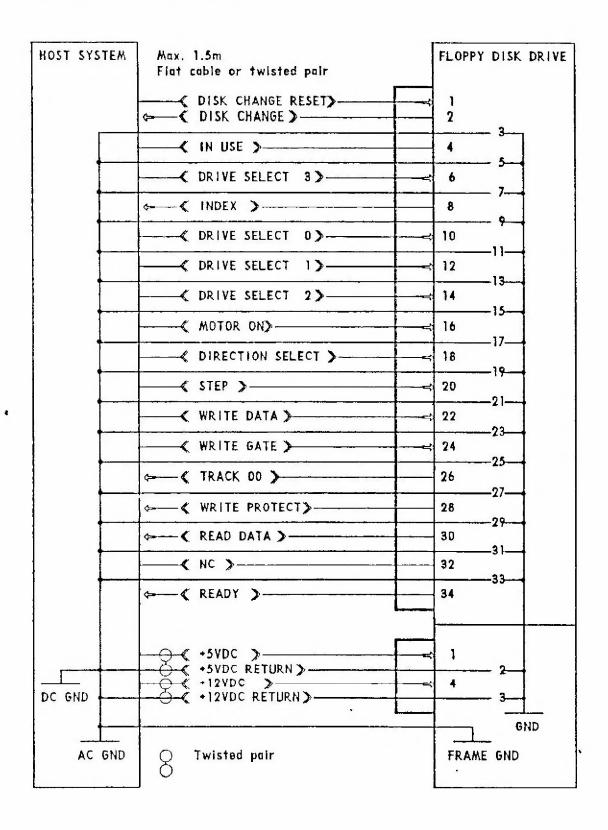
TEMPERATURE	Operating	40° F to 115° F (5°C to 45°C)
	Non-Operating (Storage)	-15" F to 140" F (-20°C to 60°C)
	Transporting	-40° F to 140° F (-40°C to 60°C)
HUMIDITY	Operating	20% to 80% relative humidity, with a wet bulb temperature of 85° F (29°C) and no condensation.
	Non-Operating (Storage)	5% to 95% relative humidity and no condensation.
	Transporting	8% to 90% relative humidity and no condensation.
VIBRATION	Operating	The unit shall perform all read/write operations (no seek) according to specifications, with continuous vibration of less than 0.56 $(\pm 10\%)$ from 5Hz to 100Hz (along the x, y, z plane).
	Non-Operating	The unit when packed for shipment shall withstand $\pm 2G$ from 5Hz to 100Hz along each of the three mutually perpendicular axes.
SHOCK	Non-Operating	The unit when unpacked shall withstand 60G.

5) RELIABILITY AND MAINTAINABILITY

Preventive Maintenance (PM)	Not required
Mean time between failures (MTBF)	8,000 POH (Power On Hour)
Mean time to repair (MTTR)	30 min
Component life	5 years or 15,000 POH
Disk life	3 0 ×10 ⁶ passes/track
Disk Interchange	20,000 times
Soft Read Error	1 per 10 ⁹ bits read
Hard Read Error	1 per 10 ¹² bits read
Seek Error	1 per 10 ⁶ seeks

3.INTERFACE CHARACTERISTICS AND TIMING

1) INTERFACE SIGNAL DIAGRAM



2) SIGNAL LEVEL

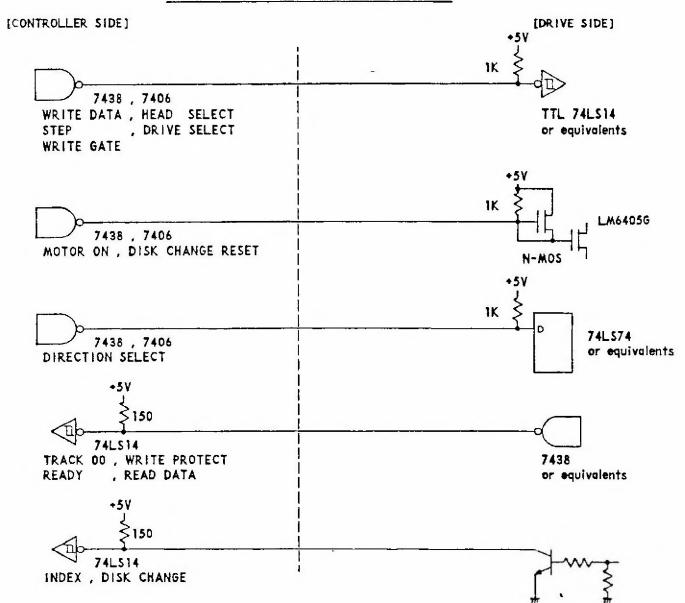
The Input signals to the drive unit have the following requirements at the FDD's input terminals:

Logical Zero	0.0 V to +0.8 V
Logical One	+2.0 V to +5.25 V

The output signals from the drive unit have the following characteristics:

True = Logical Zero	0.0 V to +0.4 V
False = Logical One	+2.4 V to +5.25 V

INTERFACE CIRCUITRY



3) INPUT SIGNAL DESCRIPTION

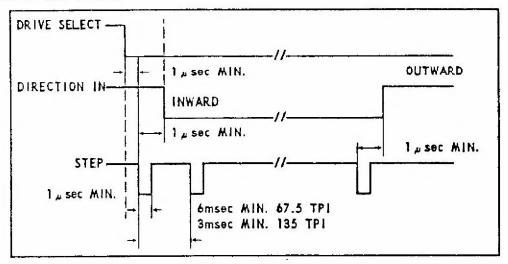
INPUT SIGNAL	DESCRIPTION			
DRIVE SELECT 0 - DRIVE SELECT 3	Logical zero on this line selects the designated drive for operation.			
MOTOR ON	Logical zero on this line causes the drive motor to rotate.			
DIRECTION SELECT	This line defines the direction of head movement when the step line is activated. Logical one on this line defines the direction as OUT, and when the line is activated the head will move to the outside of the disk. Logical zero on this line defines the direction as IN, and when the step line is activated the head will move to the center of the disk.			
STEP	This line causes the read/write head to move in the direction defined by the DIRECTION SELECT line. The transition from logical one to logical zero initiates the stepping motion.			
SIDE SELECT	Logical one on this line selects the read/write head 0 for operation; logical zero selects the read/write head 1 for operation.			
WRITE GATE	This line defines an operation as read or write. Logical zero on this line enables data to be written on the disk; logical one identifies a read operation. And this line control the tunnel erase head.			
WRITE DATA	This line is used for data that is to be written on the disk. A transition from logical one to logical zero changes the polarity of read/write head current and causes a data bit to be written on the disk. This data line is active when the WRITE GATE and READY signals are logical zero, and the WRITE PROTECT signal is logical one.			
DISK CHANGE RESET	This line is used to reset the DISK CHANGE signal. When the disk is inserted, the drive is selected and this line goes to logical zero, the DISK CHANGE goes to logical one.			

4) OUTPUT SIGNAL DESCRIPTION

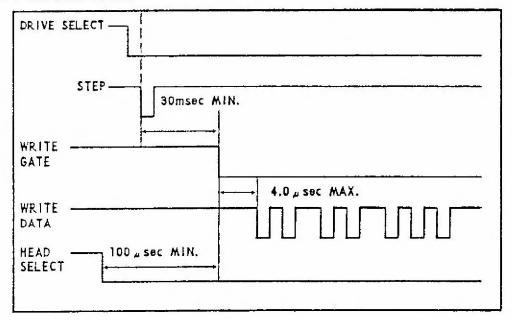
OUTPUT SIGNAL	DESCRIPTION
INDEX	This line is used to indicate a reference position on a track. The line is usually a logical one; it becomes logical zero when the drive senses the index hole. The trailing edge of the signal should be used to determine position. This line becomes logical one when the drive is not selected.
READY	This line is togical zero when a) disk is inserted and b) motor is rotating and drive unit is selected At all other times this line is logical one.
TRACK 00	This line indicates that read/write head located at track 00 (the outer most track). Logical zero on this line indicates the head is located at track 00. Logical one indicates the read/write head is not at track 00.
READ DATA	This line provides unseparated data (data and clock combined). The line is normally logical one, and becomes logical zero when data is read.
WRITE PROTECT	This line indicates that a disk is write protected. Logical zero on this line indicates a write protected disk is inserted in the drive. Logical one on this line indicates data may be written on the disk. If no disk is inserted in the drive, logical zero appears on this line. If the drive not selected, this line is logical one.
DISK CHANGE	This line is used to monitor if disk has been changed. This line goes to logical zero when the disk is ejected from the drive and stays logical zero until DISK CHANGE RESET is applied. The drive should be selected to monitor its DISK CHANGE.

5) TIMING CHART

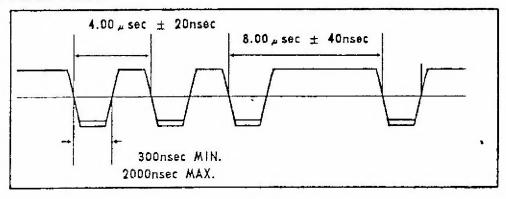
(1) TRACK ACCESS TIMING



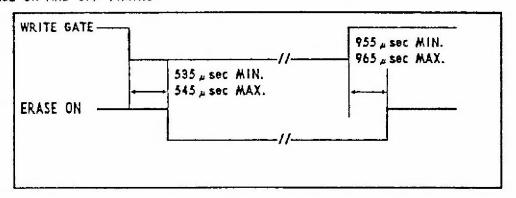
(2) WRITE INITIATE TIMING



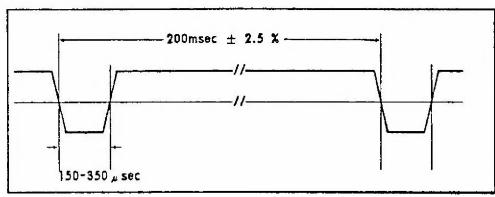
(3) WRITE DATA TIMING



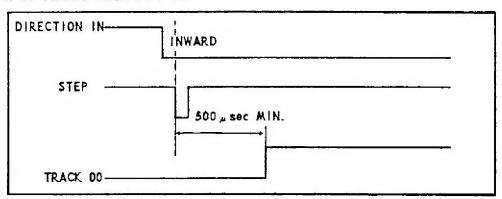
(4) ERASE ON AND OFF TIMING



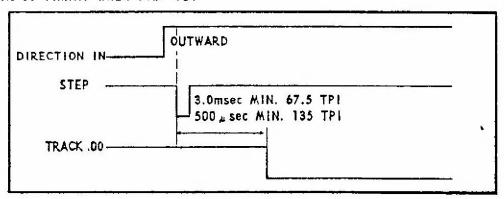
(5) INDEX MARK TIMING



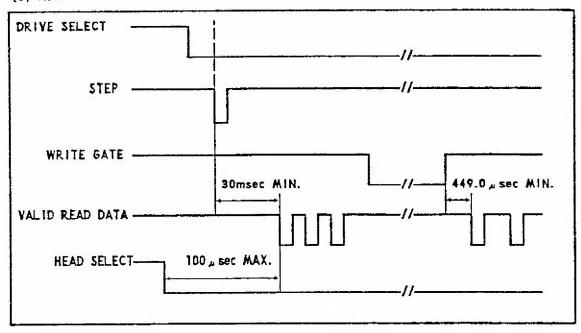
(6) TRACK OO TIMING WHEN STEP IN



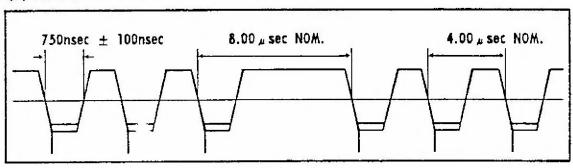
(7) TRACK DO TIMING WHEN STEP OUT



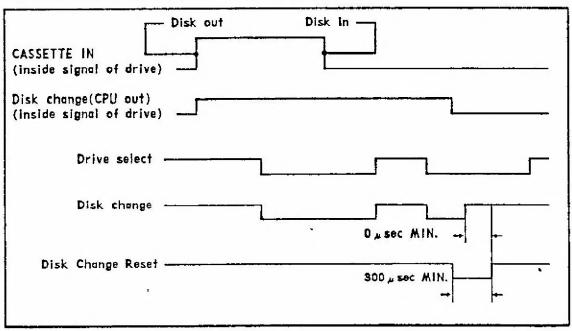
(8) READ INITIATE TIMING



(9) READ DATA TIMING

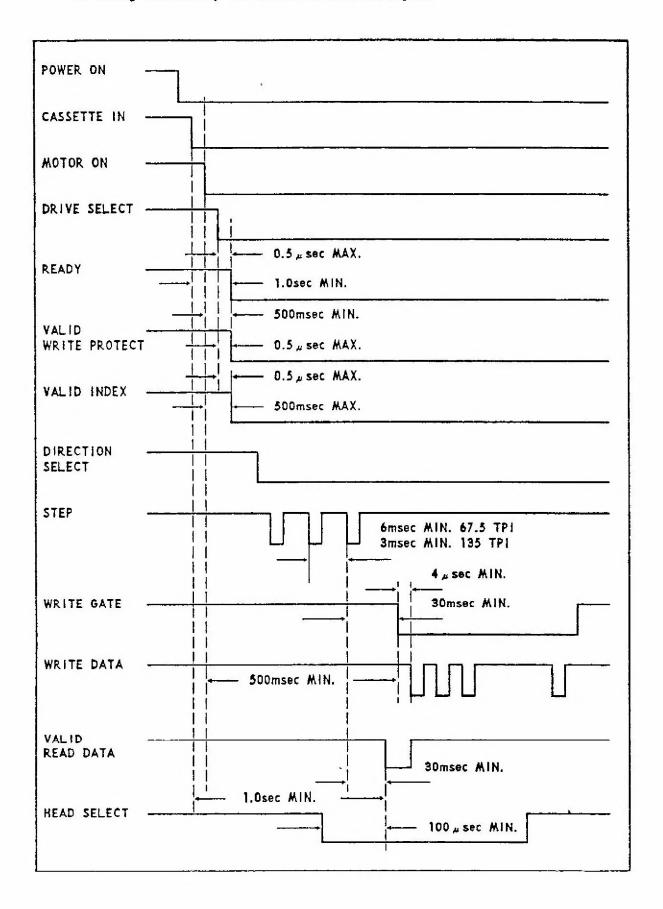


(10) DISK CHANGE AND DISK CHANGE RESET TIMING



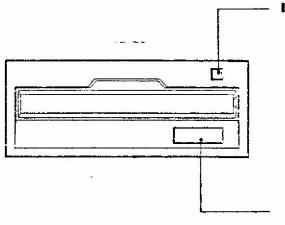
(11) INTERFACE TIMING

The timing relationship for host/drive interface signal.



4.PART NAMES AND OPERATION

1) FRONT PANEL



IN USE INDICATOR

The in use indicator indicates that a disk is in the unit and head is loaded.

EJECT BUTTON

The eject button is used to remove a disk cartridge from the unit. Depression of the eject button causes the disk cartridge in the unit to be ejected.

2) OPERATION

I.DISK CARTRIDGE EJECT MECHANISM

SANYO's fail-safe eject mechanism prevents damage to disk or drive by ejecting the Micro Floppy Disk in the event it is improperly inserted.

2.DISK CARTRIDGE INSERTION

Do not apply any force to a disk cartridge. With metal center hub downwards, insert the disk, shutter edge first, into the disk drive. When the Motor on signal is logical "0", the disk cartridge is in the drive, the motor will rotate; motor rotation stops only when disk cartridge is removed from the drive. The Micro Floppy Disk drive is now ready for operation. Operation of Micro Floppy Disk does not require any extra handling (such as removal and reinsertion).

3.DISK CARTRIDGE REMOVAL

Depress eject button to remove disk cartridge. Do not depress eject button if in use indicator is illuminated.

*** DISK PRECAUTIONS ********

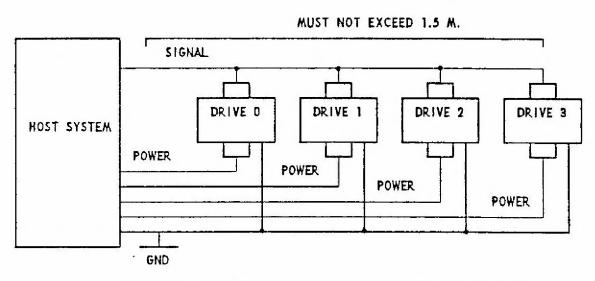
The following precautions will assure full disk life and maximum data integrity;

- 1) When handling disk, do not touch exosed disk surface itself.
- 2) Keep disks away from magnetic materials.
- 3) Do not expose disks to excessive heat or direct sunlight.
- 4) Never aftempt to clean disk surface.

 This may result in damage to disk or drive head.

5. ELECTRICAL CONNECTORS

1) CONNECTORS



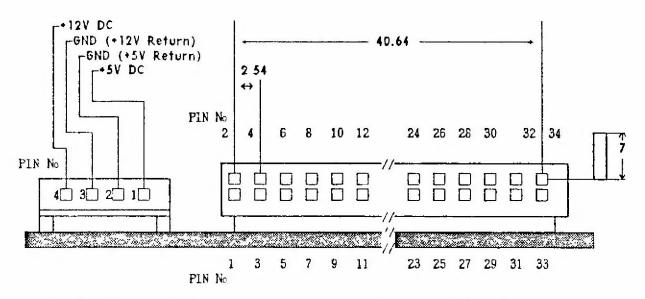
(PHYSICAL INTERCONNECTION FOR DAISY CHAIN APPLICATION)

2) CABLE AND CONNECTOR

	Cable		Cable-side connector	Drive-side connector	
cable name	type	length	Producer and part No.	Producer and part №	
signal	Flat cable AWG #28 or above			JAE PS-34PE-D4LT1-PN1	
	Twisted pair AWG #28 or above	1.5 m	JAE PS-34SEN-D4P1-1C		
DC power	AWG #20 or above	(max)	AMP Housing : 171822+4 Contact : 108-5118	AMP 171826-4	
Ground	AWG #16 or above		AMP 61697-1	AMP 170001-3	

3) PIN ASSIGNMENTS

* Reor view of drive

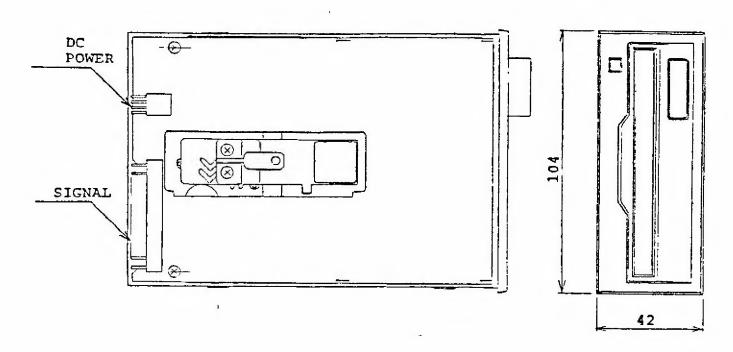


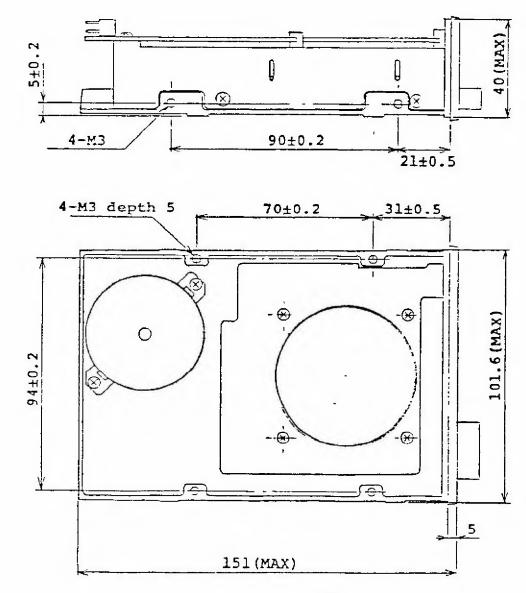
(DC POWER CONNECTOR)

(SIGNAL CONNECTOR)

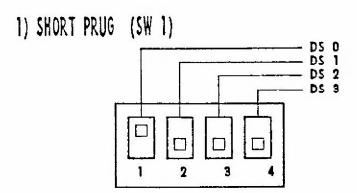
SIGNAL CONNECTOR

Pin No	Description	Pin No.	Description
1	Disk Change Reset	2	Disk Change
3	E	4	In Use
5	E	6	Drive Select 3
	E	8	Index
7 9	E	10	Drive Select O
11	E	12	Drive Select 1
13	E	14	Drive Select 2
15	E	16	Motor ON
17	E	18	Direction Select
19	E	20	Step
21	E	22	Write Data
23	E	24	Write Gate
25	E	26	Track 00
27	E	28	Write Protect
29	E .	30	Read Data
31	E	32	Side Select
33	E	34	Ready





6. SELECTION OF SHORT PLUG

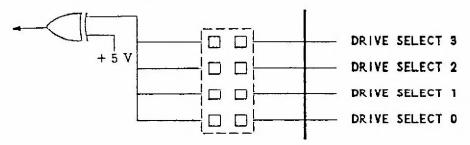


2) FUNCTION OF SHORT PRUG

SHORT PLUG		FUNCTION		
SETTING	OPEN	- FUNCTION		
DS 0	DS 1,2,3	Logical zero on DRIVE SELECT O line selects the designated drive for operation.		
D5 1	DS 0,2,3	Logical zero on DRIVE SELECT 1 line selects the designated drive for operation.		
DS 2	DS 0,1,3	Logical zero on DRIVE SELECT 2 line selects the designated drive for operation.		
DS 3	DS 0,1,2	Logical zero on DRIVE SELECT 3 line selects the designated drive for operation.		

3) SHORT PLUG CONNECTION

DRIVE ACTIVE



Note: Drive select short plug, located on the printed circuit board, is used to designated drive in a daisy chain application.

The micro floppy disk drive is shipped from the factory designated as drive "0".

RE: AX-KB

SPARE PARTS

1. L5: 470uH.... 100pcs.
2. L6: 470uH
3.R57: 1.8Kohm .. 70 "
4. L3: 100uH ... 70 "
5.C28: 820pF ... 70 " 6. PC Board ipce.

MODEL AX-KB

HOW TO CHANGE THE PARTS ON PCB:

	OLD		NEW
L5,	680 µ H	→ 4	·70μΗ
L6;	680 μН	→ 4	7 0 μ H
R57;	2. 2 K Ω	→ 1	. 8 K Q
L 3 ;	4 7 μ H	→ 1	00 μН
C 2 8 ;	330 p F	→ 8	20 p F
C ;	3 3 p F	→ D	ELETE