

<https://github.com/cowboy35927/ESL/tree/main/Hw3>

1. Base Implementation

這裡是定義通道的 header，如果沒有定義就自動定義 p2p，反之 fifo。

```
class SobelFilter: public sc_module
{
public:
    sc_in_clk i_clk;
    sc_in < bool > i_rst;
#ifdef NATIVE_SYSTEMC
    cynw_p2p< sc_dt::sc_uint<24> >::in i_rgb;
    cynw_p2p< sc_dt::sc_uint<32> >::out o_result;
#else
    sc_fifo_in< sc_dt::sc_uint<24> > i_rgb;
    sc_fifo_out< sc_dt::sc_uint<32> > o_result;
#endif

    SC_HAS_PROCESS( SobelFilter );
    SobelFilter( sc_module_name n );
    ~SobelFilter();

private:
    //void do_filter();
    //int val[MASK_N];
    //void mergeSort(unsigned char *arr, unsigned char *temp, int start, int end);
    //void merge(unsigned char *arr, unsigned char *temp, int start, int mid, int end);
    unsigned char MeanFilter(unsigned char *arr);
    void do_filter();
};
```

這裡是 filter.cpp，下圖是進行初始化，設定 rst 和 clk。

```
SobelFilter::SobelFilter(sc_module_name n) : sc_module(n)
{
    /*
#ifdef NATIVE_SYSTEMC
    HLS_FLATTEN_ARRAY(val);
#endif
    */
    SC_THREAD(do_filter);
    sensitive << i_clk.pos();
    dont_initialize();
    reset_signal_is(i_rst, false);

#ifdef NATIVE_SYSTEMC
    i_rgb.clk_rst(i_clk, i_rst);
    o_result.clk_rst(i_clk, i_rst);
#endif
}

SobelFilter::~SobelFilter() {}
```

下圖是 do_filter 進行 reset。

```
// do SobelFilter
void SobelFilter::do_filter()
{
    unsigned char buffer [3][15];
    //vector<vector<unsigned char>> buffer(3, vector<unsigned char>(15, 0));
    // int x=0;
    int i = 0;
    long long int a = 0;
    sc_time start_time;
    sc_time end_time;
    {
#ifdef NATIVE_SYSTEMC
        HLS_DEFINE_PROTOCOL("main_reset");
        i_rgb.reset();
        o_result.reset();
#endif
        wait();
    }
}
```

下圖是從 testbench 去讀取 pixel，pixel 會經過 p2p 的 channel(i_rgb)來得到，然後將 pixel 拆成 r、g、b 三個部分，分別寫入 val[0]、val[1]、val[2]。

```
while (true)
{
    unsigned char mid_r = 0, mid_g = 0, mid_b = 0;
    unsigned char val[3][9];
    //vector<vector<unsigned char>> val(3, vector<unsigned char>(9, 0));
    /*
    for (unsigned int i = 0; i < MASK_N; ++i) {
        HLS_CONSTRAIN_LATENCY(0, 1, "lat00");
        val[i] = 0;
    }*/
    for (unsigned int v = 0; v < MASK_Y; ++v)
    {
        for (unsigned int u = 0; u < MASK_X; ++u)
        {
            sc_dt::sc_uint<24> rgb;
#ifdef NATIVE_SYSTEMC
            {
                HLS_DEFINE_PROTOCOL("input");
                rgb = i_rgb.get();
                wait();
            }
        }
    }
    else
    {
        rgb = i_rgb.read();
    }
#endif
    if (v==0 && u == 0){
        start_time=sc_time_stamp();
    }
    val[0][v * 3 + u] = rgb.range(7, 0);
    val[1][v * 3 + u] = rgb.range(15, 8);
    val[2][v * 3 + u] = rgb.range(23, 16);
    /*unsigned char grey = (rgb.range(7,0) + rgb.range(15,8) + rgb.range(23, 16))/3;
    for (unsigned int i = 0; i < MASK_N; ++i) {
        HLS_CONSTRAIN_LATENCY(0, 1, "lat01");
        val[i] += grey * mask[i][u][v];
    }*/
    //cout << "Now at " << sc_time_stamp() << " read rgb,i= " << v*3+u<< endl; //print current sc_time
}
}
```

然後進行 Median Filter，取出 Median pixel。

```
for(int id=0;id<3;id++)
{
    for(int i = 8; i > 0; i--)
    {
        for(int j = 0; j ≤ i-1; j++)
        {
            if( val[id][j] > val[id][j+1])
            {
                swap(val[id][j], val[id][j+1]);
                //temp = val[id][j];
                //val[id][j] = val[id][j+1];
                //val[id][j+1] = temp;
            }
        }
    }
}
//mergeSort(val[0],r_temp, 0, 8);
//mergeSort(val[1],g_temp, 0, 8);
//mergeSort(val[2],b_temp, 0, 8);
if (i < 5)
{
    buffer[0][i * 3] = val[0][4];
    buffer[1][i * 3] = val[1][4];
    buffer[2][i * 3] = val[2][4];
}
else if (i ≥ 5 && i < 10)
{
    buffer[0][(i - 5) * 3 + 1] = val[0][4];
    buffer[1][(i - 5) * 3 + 1] = val[1][4];
    buffer[2][(i - 5) * 3 + 1] = val[2][4];
}
else
{
    buffer[0][(i - 10) * 3 + 2] = val[0][4];
    buffer[1][(i - 10) * 3 + 2] = val[1][4];
    buffer[2][(i - 10) * 3 + 2] = val[2][4];
}
}
```

下圖是 Mean filter，將得到的 median pixel 放入 buffer 後經過 Mean filter，得到 mean pixel，然後再分別乘 2^{16} 、 2^8 、1，放入 total，最後經過 p2p channel(o_result)到 testbench。

```
// cout << "Now at " << sc_time_stamp() << " 5164165165,i= " << i << endl; //print current sc_time
//vector<unsigned char> arr_r1(buffer[0].begin(), buffer[0].begin() + 9);
//vector<unsigned char> arr_g1(buffer[1].begin(), buffer[1].begin() + 9);
//vector<unsigned char> arr_b1(buffer[2].begin(), buffer[2].begin() + 9);
unsigned char arr_r1 [9];
unsigned char arr_g1 [9];
unsigned char arr_b1 [9];
for(int i=0;i<3;i++){
    for(int j=0;j<9;j++){
        if(i==0){
            arr_r1[j]=buffer[i][j];
        }else if(i==1){
            arr_g1[j]=buffer[i][j];
        }else{
            arr_b1[j]=buffer[i][j];
        }
    }
}
mid_r = MeanFilter(arr_r1);
mid_g = MeanFilter(arr_g1);
mid_b = MeanFilter(arr_b1);

int total = 0;
total = mid_r* 65536 + mid_g * 256 + mid_b ;
/*o_result_r.write(mid_r);
o_result_g.write(mid_g);
o_result_b.write(mid_b);
wait(1);*/
#ifdef NATIVE_SYSTEMC
{
    HLS_DEFINE_PROTOCOL("output");
    o_result.put(total);
    wait();
}
#else
o_result.write(total);
#endif
//cout << "Now at CPP85454123132 " << sc_time_stamp() << " i " << i << endl;
// vector<vector<unsigned char>> mean(3, vector<unsigned char>(9, 0));
```

下圖是 testbench，定義通道的 header，如果沒有定義就自動定義 p2p，反之 fifo。

```
19
20 class Testbench : public sc_module {
21 public:
22     sc_in_clk i_clk;
23     sc_out < bool > o_rst;
24 #ifndef NATIVE_SYSTEMC
25     cynw_p2p< sc_dt::sc_uint<24> >::base_out o_rgb;
26     cynw_p2p< sc_dt::sc_uint<32> >::base_in i_result;
27 #else
28     sc_fifo_out< sc_dt::sc_uint<24> > o_rgb;
29     sc_fifo_in< sc_dt::sc_uint<32> > i_result;
30 #endif
31
32     SC_HAS_PROCESS(Testbench);
33
34     Testbench(sc_module_name n);
35     ~Testbench();
36
```

下圖是 testbench 進行初始化，設定 clk。

```

Testbench::Testbench(sc_module_name n) : sc_module(n), output_rgb_raw_data_offset(54) {
    SC_THREAD(feed_rgb);
    sensitive << i_clk.pos();
    dont_initialize();
    SC_THREAD(fetch_result);
    sensitive << i_clk.pos();
    dont_initialize();
}

Testbench::~~Testbench() {
    //cout<< "Max txn time = " << max_txn_time << endl;
    //cout<< "Min txn time = " << min_txn_time << endl;
    //cout<< "Avg txn time = " << total_txn_time/n_txn << endl;
    cout << "Total run time = " << total_run_time << endl;
}

```

下圖是 testbench 的 feed_rgb，是將讀進來的圖片去解析出每個 pixel 的 rgb，將解析出來的 rgb 經過 p2p channel(o_rgb)輸出到 filter，latency 在讀第一個 pixel 後寫入當時時間 start_time，為了算 latency。

```

total_start_time = sc_time_stamp();
for (y = 0; y < height; ++y)
{
    int count = 0;
    for (x = 2; x < width; x = x + 3)
    {
        adjustX = (MASK_X % 2) ? 1 : 0; // 1
        adjustY = (MASK_Y % 2) ? 1 : 0; // 1
        xBound = MASK_X / 2; // 1
        yBound = MASK_Y / 2; // 1
        for (int count_y = 0; count_y < 3; count_y++)
        {
            int counting=0;
            for (int count_x = -2; count_x < 3; count_x++)
            {
                for (v = -yBound; v < yBound + adjustY; ++v)
                {
                    // -1, 0, 1
                    for (u = -xBound; u < xBound + adjustX; ++u)
                    {
                        // -1, 0, 1
                        if (x + count_x + u >= 0 && x + count_x + u < width && y + count_y + v >= 0 && y + count_y + v < height)
                        {
                            R = *(source_bitmap +
                                bytes_per_pixel * (width * (y + count_y + v) + (x + count_x + u)) + 2);
                            G = *(source_bitmap +
                                bytes_per_pixel * (width * (y + count_y + v) + (x + count_x + u)) + 1);
                            B = *(source_bitmap +
                                bytes_per_pixel * (width * (y + count_y + v) + (x + count_x + u)) + 0);
                        }
                        else
                        {
                            R = 0;
                            G = 0;
                            B = 0;
                        }
                    }
                    sc_dt::sc_uint<24> rgb;
                    rgb.range(7, 0) = R;
                    rgb.range(15, 8) = G;
                    rgb.range(23, 16) = B;
                }
                #ifndef NATIVE_SYSTEMC
                o_rgb.put(rgb);
                #else
                o_rgb.write(rgb);
                #endif
                if (v == -1 && u == -1) {
                    start_time = sc_time_stamp();
                }
                /*o_r.write(R);
                o_g.write(G);
                o_b.write(B);
            }
        }
    }
}

```

下圖是 fetch_result，將得到的 pixel 寫成 bmp 的圖片，會從 p2p channel(i_result)得到 pixel，再去解析 rgb 後分別寫入。

```

void Testbench::fetch_result()
{
    unsigned int x, y; // for loop counter
    int adjustX, adjustY, xBound, yBound;
    int pixel_num=0;
#ifdef NATIVE_SYSTEMC
    i_result.reset();
#endif
    wait(5);
    wait(1);
    for (y = 0; y < height; ++y)
    {
        int count = 0;
        for (x = 2; x < width; x = x + 3)
        {
            adjustX = 1; // 1
            adjustY = 1; // 1
            xBound = 1; // 1
            yBound = 1; // 1
            //cout<<"height:"<<y<<"width"<<x<<endl;
            for (int count_y = 0; count_y < 3; count_y++)
            {
                for (int count_x = -2; count_x < 3; count_x++)
                {
                    int total = 0;
                    if (count_y == 2 && count_x == 0)
                    {
#ifdef NATIVE_SYSTEMC
                        total = i_result.get();
#else
                        total = i_result.read();
#endif
                    }
                    *(target_bitmap + bytes_per_pixel * (width * y + x - 2) + 2) = total/(256*256);
                    *(target_bitmap + bytes_per_pixel * (width * y + x - 2) + 1) = (total/256)*256;
                    *(target_bitmap + bytes_per_pixel * (width * y + x - 2) + 0) = (total)*256;

                    count += 1;
                    pixel_num++;
                    //cout << "Now at " << sc_time_stamp() << " output result: " << 13 << endl; // print current sc_time
                }
            }
        }
    }
}

```

下圖是 system.h，用來定義通道的位數和合成模塊。

```

#ifdef SYSTEM_H_
#define SYSTEM_H_
#include <systemc>
using namespace sc_core;

#include "Testbench.h"
#ifdef NATIVE_SYSTEMC
#include "SobelFilter_wrap.h"
#else
#include "SobelFilter.h"
#endif

class System: public sc_module
{
public:
    SC_HAS_PROCESS( System );
    System( sc_module_name n, std::string input_bmp, std::string output_bmp );
    ~System();
private:
    Testbench tb;
#ifdef NATIVE_SYSTEMC
    SobelFilter_wrapper sobel_filter;
#else
    SobelFilter sobel_filter;
#endif
    sc_clock clk;
    sc_signal<bool> rst;
#ifdef NATIVE_SYSTEMC
    cynw_p2p< sc_dt::sc_uint<24> > rgb;
    cynw_p2p< sc_dt::sc_uint<32> > result;
#else
    sc_fifo< sc_dt::sc_uint<24> > rgb;
    sc_fifo< sc_dt::sc_uint<32> > result;
#endif
    std::string _output_bmp;
};
#endif

```

這裡是 systempipeline.cpp，類似於 verilog 的 top 模塊，用於連接所有模塊，從 testbench 通過 rgb 通道進行 filter，再通過 result 通道返回 testbench，最後輸出

bmp。

```
#include "System.h"
System::System( sc_module_name n, string input_bmp, string output_bmp ): sc_module( n ),
tb("tb"), sobel_filter("sobel_filter", clk("clk", CLOCK_PERIOD, SC_NS), rst("rst"), _output_bmp(output_bmp))
{
    tb.i_clk(clk);
    tb.o_rst(rst);
    sobel_filter.i_clk(clk);
    sobel_filter.i_rst(rst);
    tb.o_rgb(rgb);
    tb.i_result(result);
    sobel_filter.i_rgb(rgb);
    sobel_filter.o_result(result);

    tb.read_bmp(input_bmp);
}

System::~System() {
    tb.write_bmp(_output_bmp);
}
}
```

2. Improve coding styles

使用位寬來約束運算符。

```
#ifndef FILTER_DEF_H_
#define FILTER_DEF_H_

#define MASK_N 2
#define MASK_X 3
#define MASK_Y 3
typedef sc_dt::sc_uint<24> input_t;
typedef sc_dt::sc_uint<32> output_t;
#endif
```

在 filter.cpp 裡將 rgb 轉換和 mean filter 的乘法改成 shift。

```
// mid_r = 0, mid_g = 0, mid_b = 0;
for (int i = 0; i < MASK_Y * MASK_X; i++)
{
    if (i == 4)
    {
        mean_r = mean_r + (arr_r1[i] << 1) / 10;
        mean_g = mean_g + (arr_g1[i] << 1) / 10;
        mean_b = mean_b + (arr_b1[i] << 1) / 10;
    }
    else
    {
        mean_r = mean_r + arr_r1[i] / 10;
        mean_g = mean_g + arr_g1[i] / 10;
        mean_b = mean_b + arr_b1[i] / 10;
    }
}
mid_r = mean_r;
mid_g = mean_g;
mid_b = mean_b;
// mid_r = MeanFiter(arr_r1);
// mid_g = MeanFiter(arr_g1);
// mid_b = MeanFiter(arr_b1);

int total = 0;
total = (mid_r << 16) + (mid_g << 8) + mid_b ;
```

將 testbench 的除法改成 shift。


```

*(target_bitmap + bytes_per_pixel * (width * y + x) + 2) = (total>>16);
*(target_bitmap + bytes_per_pixel * (width * y + x) + 1) = (total>>8)%256;
*(target_bitmap + bytes_per_pixel * (width * y + x) + 0) = (total)%(256);

```

3. Optimized Implementation

在 do_filter 裡的 while 前加上 while_1。

```

void SobelFilter::do_filter()
{
    unsigned char buffer [3][15];
    //vector<vector<unsigned char>> buffer(3, vector<unsigned char>(15, 0));
    // int x=0;
    int i = 0;
    //long long int a = 0;
    sc_time start_time;
    sc_time end_time;
    {
#ifdef NATIVE_SYSTEMC
        HLS_DEFINE_PROTOCOL("main_reset");
        i_rgb.reset();
        o_result.reset();
#endif
        wait();
    }
    while_1:
    while (true)
    {
        unsigned char val [3][9];
        unsigned char mean_r = 0, mean_g = 0, mean_b = 0;
        int mid_r = 0, mid_g = 0, mid_b = 0;
        //vector<vector<unsigned char>> val(3, vector<unsigned char>(9, 0));
        /*
        for (unsigned int i = 0; i<MASK_N; ++i) {
            HLS_CONSTRAIN_LATENCY(0, 1, "lat00");
            val[i] = 0;
        }*/
        for (unsigned int v = 0; v < MASK_Y; ++v)
        {
            for (unsigned int u = 0; u < MASK_X; ++u)
            {
                sc_dt::sc_uint<24> rgb;
#ifdef NATIVE_SYSTEMC
                {
                    HLS_DEFINE_PROTOCOL("input");
                    rgb = i_rgb.get();
                    wait();
                }
            }
        }
    }
}

```

下圖是 HLS configuration，多加了 unroll_loops 和 constrain_latency 的指令

```

### 4. Define your HLS configuration (arbitrary names, BASIC and DPA in this example).
define_hls_config SobelFilter BASIC
define_hls_config SobelFilter DPA --dpopt_auto=op,expr
define_hls_config SobelFilter UNROLL_ALL --flatten_arrays=all -post_elab_tcl {
    unroll_loops [find -loop "*_loop" ]
    constrain_latency -max_lat $HLS::ACHIEVABLE [find -loop "while_1"]
}

```

下圖是 simulation 對 V_UNROLL_ALL。

```

### 5. Define simulation configuration for each HLS configuration
### 5.1 The behavioral simulation (C++ only).
define_sim_config B -argv "$IN_FILE_NAME $OUT_FILE_NAME"
### 5.2 The Verilog simulation for HLS config "BASIC".
define_sim_config V_BASIC "SobelFilter RTL_V BASIC" -argv "$IN_FILE_NAME $OUT_FILE_NAME"
### 5.3 The Verilog simulation for HLS config "DPA".
define_sim_config V_DPA "SobelFilter RTL_V DPA" -argv "$IN_FILE_NAME $OUT_FILE_NAME"
###
define_sim_config V_UNROLL_ALL "SobelFilter RTL_V UNROLL_ALL" -argv "$IN_FILE_NAME $OUT_FILE_NAME"

```

比較(BASIC):

1. 256*256 大小的圖片:

(1) Base Implementation:

Area:

00807:	mux_1bx31c	1	3.8	3.8
00807:	SobelFilter_Or_1Ux1U_1U_4	2	1.4	2.7
00807:	SobelFilter_N_Muxb_1_2_3_4	1	2.4	2.4
00807:	SobelFilter_Abs_9U_9U_4	1	0.0	0.0
00807:	SobelFilter_N_Mux_1_3_0_4	3	0.0	0.0
00807:	SobelFilter_RAM_27X8_1	10	?	?
00807:	SobelFilter_RAM_45X8_2	1	?	?
00808:	registers	98		
01442:	Reg bits by type:			
01442:	EN SS SC AS AC			
00809:	0 0 1 0 0	2	5.5(1)	1.4
00809:	0 1 0 0 0	1	5.5(1)	1.4
00809:	1 0 0 0 0	155	7.5(1)	0.0
00809:	1 0 1 0 0	126	7.5(1)	1.4
00809:	1 1 0 0 0	1	7.5(1)	1.4
00809:	all register bits	285	7.5(1)	0.6
02604:	estimated cntrl	1	643.2	643.2
00811:				
00812:	Total Area	2138.2(285)	4876.3	0.0
				7014.5

Run time:

```
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
Info: /OSCI/SystemC: Simulation stopped by user.
Simulation stopped via $stop(1) at time 3110592055100 PS + 0
./bdw_work/sims/top_V_BASIC.v:67 #100 $stop;
xcelium> quit
Total run time = 3110591990 ns
```

Latency:

```
SystemC 2.3.3-Accellera --- Jun 11 2021 12:51:14
Copyright (c) 1996-2018 by all Contributors,|
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
start time:132330 ns,end time:143 us,Latency:10670 ns
start time:275280 ns,end time:285950 ns,Latency:10670 ns
start time:418230 ns,end time:428900 ns,Latency:10670 ns
start time:561180 ns,end time:571850 ns,Latency:10670 ns
start time:704130 ns,end time:714800 ns,Latency:10670 ns
start time:847080 ns,end time:857750 ns,Latency:10670 ns
start time:990030 ns,end time:1000700 ns,Latency:10670 ns
```

Throughput=281,162 pxiei/s。

(2) Improve coding styles

Area:

00807:	mux_1bx31c	1		3.8	3.8
00807:	SobelFilter_Or_1Ux1U_1U_4	2		1.4	2.7
00807:	SobelFilter_N_Muxb_1_2_3_4	1		2.4	2.4
00807:	SobelFilter_Abs_9U_9U_4	1		0.0	0.0
00807:	SobelFilter_N_Mux_1_3_0_4	3		0.0	0.0
00807:	SobelFilter_RAM_27X8_1	10		?	?
00807:	SobelFilter_RAM_45X8_2	1		?	?
00808:	registers	98			
01442:	Reg bits by type:				
01442:	EN SS SC AS AC				
00809:	0 0 1 0 0	2	5.5(1)	1.4	
00809:	0 1 0 0 0	1	5.5(1)	1.4	
00809:	1 0 0 0 0	155	7.5(1)	0.0	
00809:	1 0 1 0 0	126	7.5(1)	1.4	
00809:	1 1 0 0 0	1	7.5(1)	1.4	
00809:	all register bits	285	7.5(1)	0.6	2316.0
02604:	estimated cntnl	1		643.2	643.2
00811:	-----				
00812:	Total Area		2138.2(285)	4876.3	0.0 7014.5

Run time:

```
Info: /OSCI/SystemC: Simulation stopped by user.
Simulation stopped via $stop(1) at time 3110592055100 PS + 0
/home/m111/m111064503/EE6470/Hw3/sobel_stratus_improve/stratus/bdw_work/sims/top_V_BASIC.v:67
xcelium> quit
Total run time = 3110591990 ns
```

Latency:

```
SystemC 2.3.3-Accellera --- Jun 11 2021 12:51:14
Copyright (c) 1996-2018 by all Contributors,|
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
start time:132330 ns,end time:143 us,Latency:10670 ns
start time:275280 ns,end time:285950 ns,Latency:10670 ns
start time:418230 ns,end time:428900 ns,Latency:10670 ns
start time:561180 ns,end time:571850 ns,Latency:10670 ns
start time:704130 ns,end time:714800 ns,Latency:10670 ns
start time:847080 ns,end time:857750 ns,Latency:10670 ns
start time:990030 ns,end time:1000700 ns,Latency:10670 ns
start time:1132000 ns,end time:1142650 ns,Latency:10670 ns
```

Throughput=281,162 pxiei/s。

將乘法改成 shift 後，優化過的 code 合出來的 area、latency、run time、throughput 都一樣，我認為應該是 tool 已經能自己優化乘除法器了，所以原本是用*/的部分和 shift 合出來的結果會一樣。

(3) Optimized Implementation

Area:

01442:	Reg bits by type:				
01442:	EN SS SC AS AC				
00809:	0 0 1 0 0	2	5.5(1)	1.4	
00809:	0 1 0 0 0	1	5.5(1)	1.4	
00809:	1 0 0 0 0	128	7.5(1)	0.0	
00809:	1 0 1 0 0	1315	7.5(1)	1.4	
00809:	1 1 0 0 0	1	7.5(1)	1.4	
00809:	all register bits	1447	7.5(1)	1.2	12685.5
02604:	estimated cntnl	1		319.6	319.6
00811:	-----				
00812:	Total Area		10881.1(1447)	29176.9	0.0 40058.0

Run time:

```
Info: /OSCI/SystemC: Simulation stopped by user.
Simulation stopped via $stop(1) at time 434112055100 PS + 0
/home/m111/m111064503/EE6470/Hw3/sobel_stratus_optimal/stratus/bdw_work/sims/top_V_UNROLL_ALL.v:67
xcelium> quit
Total run time = 434111990 ns
```

Latency:

```
SystemC 2.3.3-Accellera --- Jun 11 2021 12:51:14
Copyright (c) 1996-2018 by all Contributors,
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
start time:18410 ns,end time:20 us,Latency:1590 ns
start time:38360 ns,end time:39950 ns,Latency:1590 ns
start time:58310 ns,end time:59900 ns,Latency:1590 ns
start time:78260 ns,end time:79850 ns,Latency:1590 ns
start time:98210 ns,end time:99800 ns,Latency:1590 ns
start time:118160 ns,end time:119750 ns,Latency:1590 ns
start time:138110 ns,end time:139700 ns,Latency:1590 ns
start time:158060 ns,end time:159650 ns,Latency:1590 ns
start time:178010 ns,end time:179600 ns,Latency:1590 ns
start time:197960 ns,end time:199550 ns,Latency:1590 ns
```

Throughput=1,886,792 pxiei/s。

使用 unroll 後，面積暴增到了 4 萬，因為將 loop 迴圈展開，所以面積會比原本多了 6 倍多，但 latency 也少了 6 倍多，run time 則是快了 7 倍多，throughput 則多了 6 倍多，所以這邊是以面積換取速度。

2. 512*512 大小的圖片：

(2) Base Implementation:

Area:

```
00807: |          mux_1bx31c          | 1          | 3.8          | 3.8          |
00807: | SobelFilter_Or_1Ux1U_1U_4    | 2          | 1.4          | 2.7          |
00807: | SobelFilter_N_Muxb_1_2_3_4    | 1          | 2.4          | 2.4          |
00807: | SobelFilter_Abs_9U_9U_4       | 1          | 0.0          | 0.0          |
00807: | SobelFilter_N_Mux_1_3_0_4     | 3          | 0.0          | 0.0          |
00807: | SobelFilter_RAM_27X8_1        | 10         | ?           | ?           |
00807: | SobelFilter_RAM_45X8_2        | 1          | ?           | ?           |
00808: |          registers           | 98         |              |              |
01442: | Reg bits by type:            |            |              |              |
01442: |   EN SS SC AS AC            |            |              |              |
00809: |   0 0 1 0 0                | 2          | 5.5(1)       | 1.4          |
00809: |   0 1 0 0 0                | 1          | 5.5(1)       | 1.4          |
00809: |   1 0 0 0 0                | 155        | 7.5(1)       | 0.0          |
00809: |   1 0 1 0 0                | 126        | 7.5(1)       | 1.4          |
00809: |   1 1 0 0 0                | 1          | 7.5(1)       | 1.4          |
00809: | all register bits            | 285        | 7.5(1)       | 0.6          |
02604: | estimated cntl               | 1          | 643.2        | 643.2        |
00811: |-----|
00812: | Total Area                   | 2138.2(285) | 4876.3       | 0.0          | 7014.5
```

Run time:

```
Info: /OSCI/SystemC: Simulation stopped by user.
Simulation stopped via $stop(1) at time 12442368055100 PS + 0
./bdw_work/sims/top_V_BASIC.v:67 #100 $stop;
xcelium> quit
Total run time = 12442367990 ns
```

Latency:

```

SystemC 2.3.3-Accellera --- Jun 11 2021 12:51:14
Copyright (c) 1996-2018 by all Contributors,|
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
start time:132330 ns,end time:143 us,Latency:10670 ns
start time:275280 ns,end time:285950 ns,Latency:10670 ns
start time:418230 ns,end time:428900 ns,Latency:10670 ns
start time:561180 ns,end time:571850 ns,Latency:10670 ns
start time:704130 ns,end time:714800 ns,Latency:10670 ns
start time:847080 ns,end time:857750 ns,Latency:10670 ns
start time:990030 ns,end time:1000700 ns,Latency:10670 ns

```

Throughput=281,162 pxiei/s。

(2) Improve coding styles

Area:

```

00807: |-----mux_1bx311c-----| 1 | 3.8 | 3.8 |
00807: | SobelFilter_Or_1Ux1U_1U_4 | 2 | 1.4 | 2.7 |
00807: | SobelFilter_N_Muxb_1_2_3_4 | 1 | 2.4 | 2.4 |
00807: | SobelFilter_Abs_9U_9U_4 | 1 | 0.0 | 0.0 |
00807: | SobelFilter_N_Mux_1_3_0_4 | 3 | 0.0 | 0.0 |
00807: | SobelFilter_RAM_27X8_1 | 10 | ? | ? |
00807: | SobelFilter_RAM_45X8_2 | 1 | ? | ? |
00808: | registers | 98 |
01442: | Reg bits by type: |
01442: | EN SS SC AS AC |
00809: | 0 0 1 0 0 | 2 | 5.5(1) | 1.4 |
00809: | 0 1 0 0 0 | 1 | 5.5(1) | 1.4 |
00809: | 1 0 0 0 0 | 155 | 7.5(1) | 0.0 |
00809: | 1 0 1 0 0 | 126 | 7.5(1) | 1.4 |
00809: | 1 1 0 0 0 | 1 | 7.5(1) | 1.4 |
00809: | all register bits | 285 | 7.5(1) | 0.6 |
02604: | estimated cntl | 1 | 643.2 | 2316.0 |
00811: |-----Total Area-----| 2138.2(285) | 4876.3 | 0.0 | 7014.5 |
00812: |-----|-----|-----|-----|

```

Run time:

```

Info: /OSCI/SystemC: Simulation stopped by user.
Simulation stopped via $stop(1) at time 12442368055100 PS + 0
./bdw_work/sims/top_V_BASIC.v:67 #100 $stop;
xcelium> quit
Total run time = 12442367990 ns

```

Latency:

```

SystemC 2.3.3-Accellera --- Jun 11 2021 12:51:14
Copyright (c) 1996-2018 by all Contributors,|
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
start time:132330 ns,end time:143 us,Latency:10670 ns
start time:275280 ns,end time:285950 ns,Latency:10670 ns
start time:418230 ns,end time:428900 ns,Latency:10670 ns
start time:561180 ns,end time:571850 ns,Latency:10670 ns
start time:704130 ns,end time:714800 ns,Latency:10670 ns
start time:847080 ns,end time:857750 ns,Latency:10670 ns
start time:990030 ns,end time:1000700 ns,Latency:10670 ns

```

Throughput=281,162 pxiei/s。

將乘法改成 shift 後，優化過的 code 合出來的 area、latency、run time、throughput 都一樣，我認為應該是 tool 已經能自己優化乘除法器了，所以原本是用*/的部分和 shift 合出來的結果會一樣。

(3) Optimized Implementation

Area:

01442:	Reg bits by type:									
01442:	EN	SS	SC	AS	AC					
00809:	0	0	1	0	0	2	5.5(1)	1.4		
00809:	0	1	0	0	0	1	5.5(1)	1.4		
00809:	1	0	0	0	0	128	7.5(1)	0.0		
00809:	1	0	1	0	0	1315	7.5(1)	1.4		
00809:	1	1	0	0	0	1	7.5(1)	1.4		
00809:	all register bits					1447	7.5(1)	1.2	12685.5	
02604:	estimated cntrl					1		319.6	319.6	
00811:										
00812:	Total Area					10881.1(1447)	29176.9	0.0	40058.0	

Run time:

```
Info: /OSCI/SystemC: Simulation stopped by user.
Simulation stopped via $stop(1) at time 1736448055100 PS + 0
./bdw_work/sims/top_V_UNROLL_ALL.v:67      #100 $stop;
xcelium> quit
Total run time = 1736447990 ns
```

Latency:

```
SystemC 2.3.3-Accellera --- Jun 11 2021 12:51:14
Copyright (c) 1996-2018 by all Contributors,
ALL RIGHTS RESERVED
NOTE: Cadence Design Systems Hub Simulation Platform : version 21.20-p100
start time:18410 ns,end time:20 us,Latency:1590 ns
start time:38360 ns,end time:39950 ns,Latency:1590 ns
start time:58310 ns,end time:59900 ns,Latency:1590 ns
start time:78260 ns,end time:79850 ns,Latency:1590 ns
start time:98210 ns,end time:99800 ns,Latency:1590 ns
start time:118160 ns,end time:119750 ns,Latency:1590 ns
start time:138110 ns,end time:139700 ns,Latency:1590 ns
start time:158060 ns,end time:159650 ns,Latency:1590 ns
start time:178010 ns,end time:179600 ns,Latency:1590 ns
start time:197960 ns,end time:199550 ns,Latency:1590 ns
```

Throughput=1,886,792 pxel/s。

使用 unroll 後，面積暴增到了 4 萬，因為將 loop 迴圈展開，所以面積會比原本多了 6 倍多，但 latency 也少了 6 倍多，run time 則是快了 7 倍多，throughput 則多了 6 倍多，所以這邊是以面積換取速度。



