

# Dynamics of infectious diseases (continuation)

S-I-R model

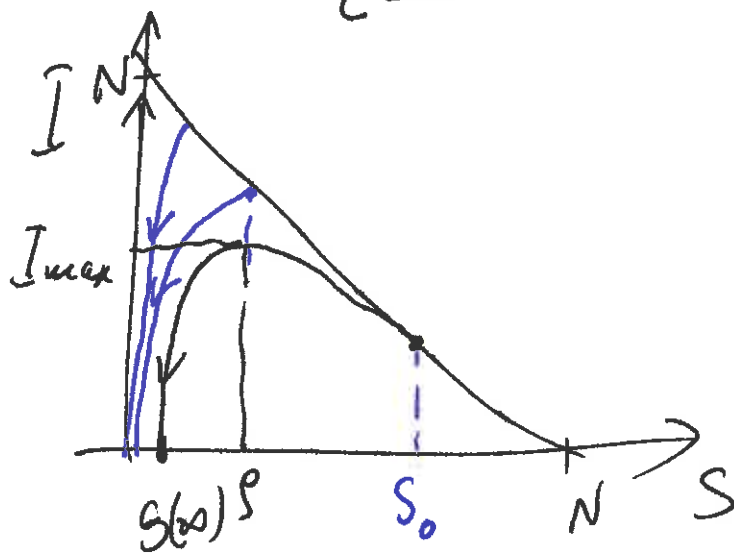
$$\frac{dS}{dt} = -rSI$$

$$\frac{dI}{dt} = rSI - aI$$

$$\frac{dR}{dt} = aI$$

$$S + I + R = N = \text{const}$$

$$t=0 \quad \underbrace{S_0 + I_0 + 0}_{t=0} = N = \underbrace{S(\infty) + 0 + R(\infty)}_{t=\infty}$$



$$S + I = N$$

$$\frac{dI}{dt} = I(rS - a) = 0$$

$$S = \frac{a}{r} \equiv \rho$$

Reproduction rate  $R_0 = \frac{rS_0}{a} = \frac{S_0}{\rho}$

If  $R_0 > 1$  then clearly an epidemic ensues.

$$\frac{dI}{dS} = \frac{rsI - aI}{-rsI} = -\frac{rs - a}{rs} = -1 + \frac{p}{S}$$

$$(p = \frac{a}{r})$$

$$dI = (-1 + \frac{p}{S})dS \Rightarrow I = -S + p \ln S + \text{const}$$

$$I + S - p \ln S = \text{const} = \underbrace{I_0 + S_0 - p \ln S_0}_N$$

$$I(S) = N - S + p \ln S - p \ln S_0$$

$$I(S) = N - S + p \ln\left(\frac{S}{S_0}\right)$$

$$I_{\max} = I(p) = N - p + p \ln \frac{p}{S_0}, \quad S_0 > p$$

$$I_{\max} = I(S_0) = N - S_0 + 0 = N - S_0, \quad S_0 < p$$

$$\frac{dS}{dR} = \frac{rsI}{aI} = -\frac{1}{p}S \Rightarrow \frac{dS}{dR} = -\frac{1}{p}S$$

$$S(t) = S_0 e^{-\frac{1}{p}R(t)}$$

$$t \rightarrow \infty \quad S(\infty) = S_0 e^{-\frac{1}{p}[N - S(\infty)]}$$

$S_\infty$  is the positive root  $0 < S(\infty) < p$

- 3 -

$$\frac{dR}{dt} = aI = a(N - S - R)$$

$$\frac{dR}{dt} = a(N - S_0 e^{-\frac{1}{\rho} R} - R) \rightarrow \text{ODE for } \underline{R}$$

$$\frac{dR}{dt} = a(N - R - S_0 e^{-\frac{R}{\rho}}) \rightarrow R = \underline{R(t)}$$

$$\begin{aligned} S(t) &= S_0 \exp\left(-\frac{R(t)}{\rho}\right) \\ I(t) &= N - S(t) + \rho \ln \frac{S(t)}{S_0} \end{aligned}$$

$$e^x = 1 + x + \frac{x^2}{2} + \frac{x^3}{3!} + \dots$$

Assumption:  $\boxed{\frac{R}{\rho} \ll 1}$

$$e^{-\frac{R}{\rho}} \approx 1 - \frac{R}{\rho} + \frac{1}{2} \frac{R^2}{\rho^2}$$

$$\frac{dR}{dt} = a \left[ N - R - S_0 \left( 1 - \frac{R}{\rho} + \frac{1}{2} \frac{R^2}{\rho^2} \right) \right]$$

$$\frac{dR}{dt} = a \left( N - R - S_0 + \frac{S_0 R}{\rho} - \frac{S_0}{2\rho^2} R^2 \right)$$

$$\frac{dR}{dt} = a \left[ N - S_0 + \left( \frac{S_0}{\rho} - 1 \right) R - \frac{S_0}{2\rho^2} R^2 \right]$$

-4-

$$\boxed{x = \frac{s_0 R}{p^2}} \quad R = \frac{p^2 x}{s_0}$$

$$\frac{p^2}{s_0} \frac{dx}{dt} = a \left[ N - s_0 + \left( \frac{s_0}{p} - 1 \right) \frac{p^2 x}{s_0} - \frac{s_0}{2p^2} \frac{p^4 x^2}{s_0^2} \right]$$

$$\frac{p^2}{s_0} \frac{dx}{dt} = a \left[ N - s_0 + \left( \frac{s_0}{p} - 1 \right) \frac{p^2}{s_0} x - \frac{p^2 x^2}{2s_0} \right]$$

$$\frac{dx}{dt} = -a \frac{x^2}{2s_0} \left[ (N - s_0) \left( -\frac{2s_0}{p^2} \right) + \frac{2s_0}{p^2} \left( \frac{s_0}{p} - 1 \right) \frac{p^2}{s_0} x + x^2 \right]$$

$$\frac{dx}{dt} = -\frac{a}{2} \left[ x^2 - 2x \left( \frac{s_0 - p}{p} \right) - \frac{2s_0}{p^2} (N - s_0) \right]$$

$$\frac{dx}{dt} = -\frac{a}{2} \left[ \left( x - \frac{s_0}{p} + 1 \right)^2 - \left( \frac{s_0}{p} - 1 \right)^2 - \frac{2s_0}{p^2} (N - s_0) \right]$$

$$\boxed{\alpha^2 = \left( \frac{s_0}{p} - 1 \right)^2 + \frac{2s_0 (N - s_0)}{p^2}} \quad (10.14)$$

Define:  $y = x - \frac{s_0}{p} + 1$        $dx = dy$

$$\frac{dy}{dt} = -\frac{a}{2} (y^2 - \alpha^2)$$

$$\int \frac{dy}{y^2 - \alpha^2} = \int -\frac{a}{2} dt$$

-5-

$$\int \frac{dy}{y^2 - \alpha^2} = -\frac{1}{\alpha} \operatorname{arctanh} \frac{y}{\alpha}$$

$$\tanh y = \frac{\sinh y}{\cosh y} = \frac{e^y - e^{-y}}{e^y + e^{-y}}$$

$$-\frac{1}{\alpha} \operatorname{arctanh} \frac{y}{\alpha} = -\frac{a}{2} t + C$$

$$\operatorname{arctanh} \frac{y}{\alpha} = \frac{\alpha a}{2} t + C_1$$

$$y = \alpha \tanh\left(\frac{\alpha a t}{2} + C_1\right)$$

$$y = x - \frac{s_0}{\rho} + 1 = \frac{s_0 R}{\rho^2} - \frac{s_0}{\rho} + 1,$$

$$\underbrace{\frac{s_0 R}{\rho^2} - \frac{s_0}{\rho} + 1}_y = \alpha \tanh\left(\frac{\alpha a t}{2} + \phi\right)$$

"const."

$t=0$  then  $R(0) = 0$

$$1 - \frac{s_0}{\rho} = \alpha \tanh(\phi)$$

$$\phi = -\tanh^{-1}\left[\frac{1}{\alpha}\left(1 - \frac{s_0}{\rho}\right)\right]$$

$$\boxed{\phi = \tanh^{-1}\left[\frac{1}{\alpha}\left(\frac{s_0}{\rho} - 1\right)\right]}$$

$$\underline{R(t)} = \frac{p^2}{S_0} \left[ \frac{S_0}{p} - 1 + \alpha \tanh\left(\frac{\alpha t}{2} - \phi\right) \right]$$

$$\phi = \tanh^{-1} \left[ \frac{1}{\alpha} \left( \frac{S_0}{p} - 1 \right) \right] = \text{const.}$$

$$\alpha = \sqrt{\left( \frac{S_0}{p} - 1 \right)^2 + \frac{2S_0}{p^2} (N - S_0)} = \text{const.}$$

'Removal rate':  $\frac{dR}{dt}$

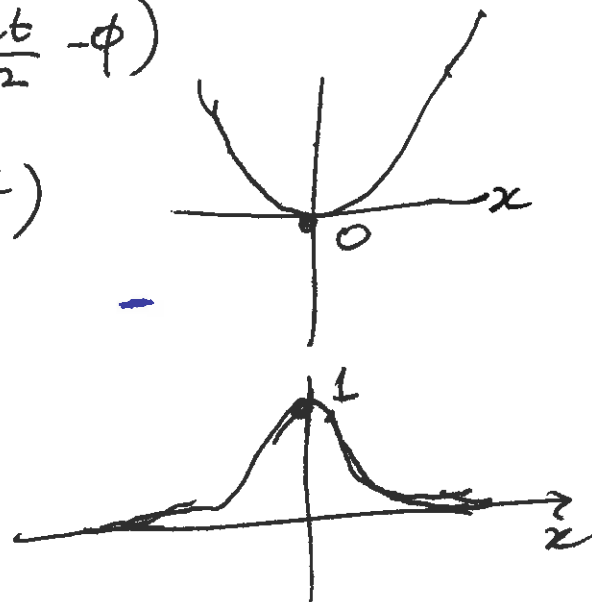
$$\frac{dR}{dt} = \frac{p^2}{S_0} \alpha \operatorname{sech}^2\left(\frac{\alpha t}{2} - \phi\right) \cdot \left(\frac{\alpha}{2}\right)$$

$$\frac{dR}{dt} = \frac{ap^2\alpha^2}{2S_0} \operatorname{sech}^2\left(\frac{\alpha t}{2} - \phi\right) \quad (10.15)$$

$$\frac{dR}{dt} = \frac{ap^2\alpha^2}{2S_0 \cosh^2\left(\frac{\alpha t}{2} - \phi\right)}$$

$$\cosh x = \frac{1}{2} (e^x + e^{-x})$$

$$\frac{1}{\cosh^2 x}$$



# Modelling Venereal Diseases

S.T.D. characteristics

1. Restricted to sexually active community.

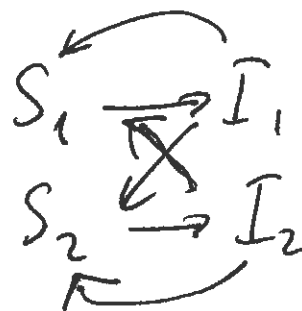
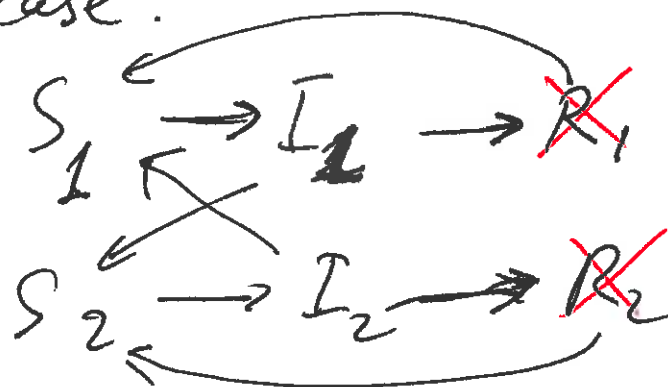
2. Carrier is asymptomatic.

3. No acquired immunity.

gonorrhea, syphilis, chlamidia

4. Two interacting classes - males & females

5. Passed from member of one class to the other (criss-cross type of disease).



$$\frac{dS_1}{dt} = -r_1 S_1 I_2 + q I_1$$

$$\frac{dI_1}{dt} = r_1 S_1 I_2 - q I_1$$

$$S_1(t) + I_1(t) = N_1 = \text{const}$$

$$1 \leftrightarrow 2$$

$$S_1(0) = S_{1,0} \quad I_1(0) = I_{1,0}$$

$$S_2(0) = S_{2,0} \quad I_2(0) = I_{2,0}$$

$$S_{1,2} = N_{1,2} - I_{1,2}$$

↑  
const.

$$\left| \begin{aligned} \frac{dI_1}{dt} &= r_1 \underbrace{(N_1 - I_1)}_{S_1} I_2 - a_1 I_1 = f_1(I_1, I_2) \\ \frac{dI_2}{dt} &= r_2 (N_2 - I_2) I_1 - a_2 I_2 = f_2(I_1, I_2) \end{aligned} \right.$$

$$(I_1, I_2) = (0, 0)$$

$$r_1 (N_1 - I_1) I_2 = a_1 I_1 \Rightarrow I_2 = \frac{a_1 I_1}{r_1 (N_1 - I_1)}$$

$$p_1 = \frac{a_1}{r_1} \quad p_2 = \frac{a_2}{r_2} \Rightarrow I_2 = \frac{p_1 I_1}{N_1 - I_1}$$

$$\left( \frac{r_2}{r_2} (N_2 - \frac{p_1 I_1}{N_1 - I_1}) \right) I_1 = \frac{p_2 I_1}{N_1 - I_1} \Leftrightarrow f_2 = 0$$

$$\frac{N_2 (N_1 - I_1) - p_1 I_1}{N_1 - I_1} = \frac{p_2 I_1}{N_1 - I_1}$$



$$N_1 N_2 - N_2 I_1 - P_1 I_1 = P_1 P_2$$

$$N_1 N_2 - P_1 P_2 = I_1 (P_1 + N_2)$$

~~$$I_1^* = \frac{N_1 N_2 - P_1 P_2}{P_1 + N_2}$$~~

$$I_1^* = \frac{N_1 N_2 - P_1 P_2}{P_1 + N_2}$$

$$I_2^* = \frac{N_1 N_2 - P_1 P_2}{P_2 + N_1}$$

$$1 \leftrightarrow 2$$

$$(0, 0) \quad \& \quad (I_1^*, I_2^*)$$

exists only if  $N_1 N_2 > P_1 P_2$

'threshold condition'

$$A = \begin{pmatrix} \frac{\partial f_1}{\partial I_1} & \frac{\partial f_1}{\partial I_2} \\ \frac{\partial f_2}{\partial I_1} & \frac{\partial f_2}{\partial I_2} \end{pmatrix} = \begin{pmatrix} -r_1 I_2 - a_1 & r_1 (N_1 - I_1) \\ r_2 (N_2 - I_2) & -r_2 I_1 - a_2 \end{pmatrix}$$

$$A(0,0) = \begin{pmatrix} -a_1 & r_1 N_1 \\ r_2 N_2 & -a_2 \end{pmatrix}$$

$$\lambda^2 - (\text{tr} A) \lambda + \det A = 0$$

$$\lambda^2 + (a_1 + a_2) \lambda + a_1 a_2 - r_1 r_2 N_1 N_2 = 0$$

$$\lambda_{1,2} = \frac{-(a_1 + a_2) \pm \sqrt{(a_1 + a_2)^2 - 4(a_1 a_2 - r_1 r_2 N_1 N_2)}}{2}$$

$$p_k = \frac{q_k}{r_k}$$

$$\lambda_{1,2} = \frac{-(a_1 + a_2) \pm \sqrt{(a_1 + a_2)^2 + 4a_1 a_2 \left(\frac{N_1 N_2}{p_1 p_2} - 1\right)}}{2}$$

I.  $N_1 N_2 > p_1 p_2$  then  $D > 0$ ,

$\lambda_1 > 0$ ,  $\lambda_2 < 0$  saddle pt.  
unstable.

II.  $N_1 N_2 < p_1 p_2$  then  $\lambda_1 < 0$ ,  $\lambda_2 < 0$

i.e.  $(0,0)$  is the only stable

Steady state,  $(I_1^*, I_2^*)$  does  
not exist.

→ Stability of  $(I_1^*, I_2^*)$  when  $N_1 N_2 > p_1 p_2$

$$A(I_1^*, I_2^*) = \begin{pmatrix} -a_1 - r_1 I_2^* & r_1 (N_1 - I_1^*) \\ r_2 (N_2 - I_2^*) & -a_2 - r_2 I_1^* \end{pmatrix}$$

-11-

$$\lambda^2 - \text{tr} A \lambda + \det A = 0$$

$$\lambda^2 + (a_1 + a_2 + r_1 \bar{I}_1^* + r_2 \bar{I}_2^*) \lambda + (a_1 + r_1 \bar{I}_2^*)(a_2 + r_2 \bar{I}_1^*) - r_1 r_2 (N_1 - \bar{I}_1^*)(N_2 - \bar{I}_2^*) = 0$$

$$\text{tr} A = -(a_1 + a_2) - r_1 \bar{I}_2^* - r_2 \bar{I}_1^* < 0$$

always.

$$\det A = a_1 a_2 + a_1 r_2 \bar{I}_1^* + r_1 a_2 \bar{I}_2^* + r_1 r_2 \bar{I}_1^* \bar{I}_2^* - r_1 r_2 (N_1 N_2 - \bar{I}_1^* N_2 - N_1 \bar{I}_2^* + \bar{I}_1^* \bar{I}_2^*)$$

$$= a_1 a_2 - r_1 r_2 N_1 N_2 + a_1 r_2 \bar{I}_1^* + r_1 a_2 \bar{I}_2^* + r_1 r_2 \bar{I}_1^* N_2 + r_1 r_2 \bar{I}_2^* N_1$$

$a_1 a_2 (1 - \frac{N_1 N_2}{\rho_1 \rho_2})$

$$\rho_k = \frac{a_k}{r_k}$$

- 12 -

$$\boxed{P_k = \frac{a_k}{r_k}}$$

$$\det A = a_1 a_2 \left( 1 - \frac{N_1 N_2}{P_1 P_2} \right) + (a_1 r_2 + r_1 r_2 N_2) I_1^* + (r_1 a_2 + r_1 r_2 N_1) I_2^*$$

$$= a_1 a_2 \left( \frac{P_1 P_2 - N_1 N_2}{P_1 P_2} \right) + r_2 a_1 \left( 1 + \frac{P_1 N_2}{P_1} \right) \frac{N_1 N_2 - P_1 P_2}{P_1 + N_2} + r_1 a_2 \left( 1 + \frac{P_2 N_1}{P_2} \right) \frac{N_1 N_2 - P_1 P_2}{P_2 + N_1}$$

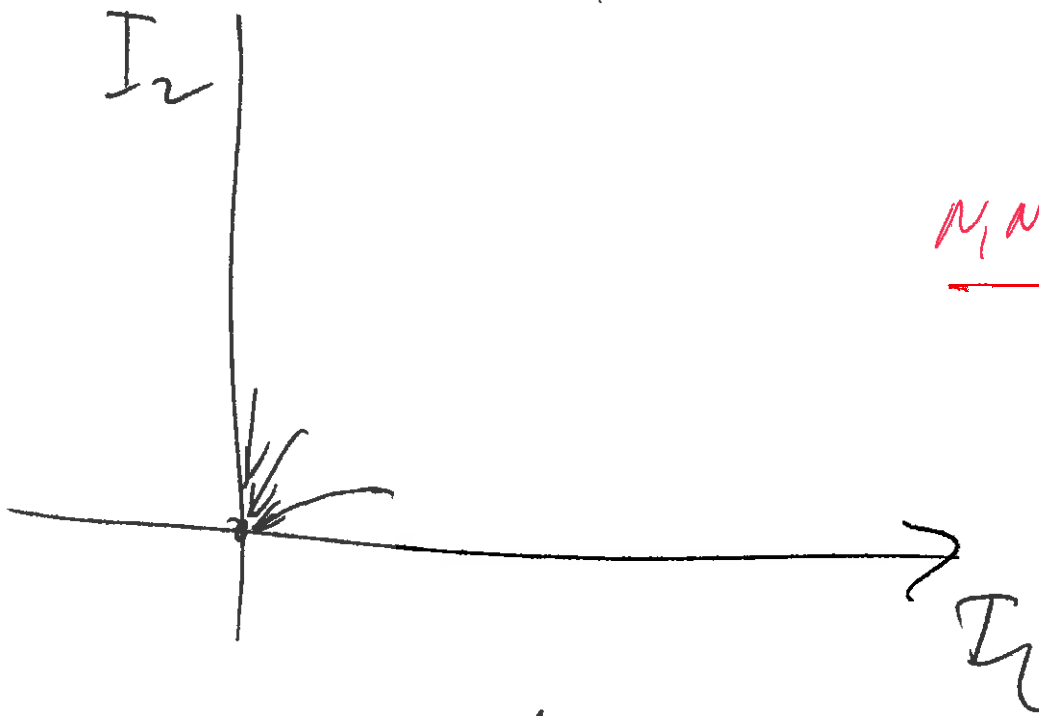
$$= (N_1 N_2 - P_1 P_2) \left[ \frac{r_2 a_1 \left( \frac{P_1 + P_1 N_2}{P_1} \right)}{P_1 (P_1 + N_2)} + \frac{r_1 a_2 \left( \frac{P_2 + P_2 N_1}{P_2} \right)}{P_2 (P_2 + N_1)} - \frac{a_1 a_2}{P_1 P_2} \right] + (?)$$

$$= (N_1 N_2 - P_1 P_2) (r_1 r_2 + r_1 r_2 - r_1 r_2) = r_1 r_2 (N_1 N_2 - P_1 P_2) > 0$$

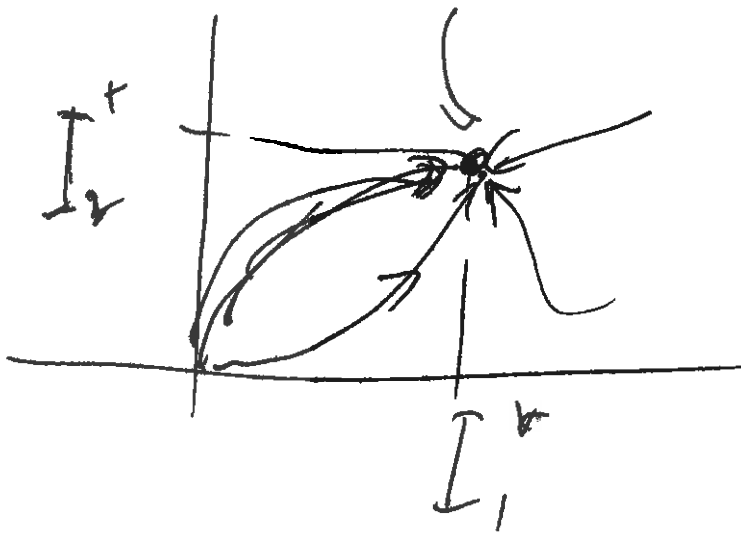
$$A = U \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} U^{-1} \quad \left( \begin{matrix} -5 \\ 3 \end{matrix} \right)$$

det A > 0 !

$\Rightarrow (I_1^*, I_2^*)$  is a stable steady state!



$N_1 N_2 < P_1 P_2$



$N_1 N_2 > P_1 P_2$