Solved Exercises of chapter 5 from D'Inverno MSc. Fernando Claudio Guesser March 2, 2011

1. In Euclidean 3-space \mathbb{R}^3 :

(i) Write down the equation of a circle of radius a lying in the (x,y)-plane centred at the origin in (a) parametric form and (b) constraint form.

Solution: Circle equation: $x^2 + y^2 = a^2$

Parametric form:
$$\begin{cases} x = t \\ y = \pm \sqrt{a^2 - t^2} \end{cases}$$

Constraint form: $y = \pm \sqrt{a^2 - x^2}$

(ii) Write down the equation of a hypersurface consisting of a sphere of radius a centred at the origin in (a) parametric form and (b) constraint form. Eliminate the parameters in form (a) to obtain form (b).

Solution:

Sphere equation: $x^2 + y^2 + z^2 = a^2$

Parametric form:
$$\begin{cases} x = t \\ y = u \\ z = \pm \sqrt{a^2 - t^2 - u^2} \end{cases}$$

Constraint form: $z = \pm \sqrt{a^2 - x^2 - y^2}$

2. Write down the change of coordinates from Cartesian coordinates $(x^a) = (x, y, z)$ to spherical polar coordinates $(x'^a) = (r, \theta, \phi)$ in \mathbb{R}^3 . Obtain the transformation matrices $[\partial x^a/\partial x'^b]$ and $[\partial x'^a/\partial x^b]$ expressing them both in terms of the primed coordinates. Obtain the Jacobians J and J'. Where is J' zero or infinite?

Solution:

The spherical polar coordinates in terms of Cartesian ones:

$$\mathbf{r}\left(x,y,z\right):=\sqrt{x^{2}+y^{2}+z^{2}}$$

$$\theta\left(x,y,z\right):=\operatorname{atan}\left(\frac{\sqrt{x^{2}+y^{2}}}{z}\right)$$

$$\phi(x, y, z) := \operatorname{atan}\left(\frac{y}{x}\right)$$

Producing the transformation matrix:

$$\begin{bmatrix} \frac{\partial x'^a}{\partial x^b} \end{bmatrix} = \begin{pmatrix} \frac{\frac{x}{\sqrt{z^2 + y^2 + x^2}}}{\frac{xz}{\sqrt{y^2 + x^2}}} & \frac{\frac{y}{\sqrt{z^2 + y^2 + x^2}}}{\frac{yz}{\sqrt{y^2 + x^2}}} & \frac{\frac{z}{\sqrt{z^2 + y^2 + x^2}}}{\frac{yz}{\sqrt{y^2 + x^2}}} & -\frac{\sqrt{y^2 + x^2}}{\frac{z^2 + y^2 + x^2}} \\ -\frac{y}{y^2 + x^2} & \frac{x}{y^2 + x^2} & 0 \end{pmatrix}$$

and the Jacobian of the transformation is

$$J' = \left| \frac{\partial x'^a}{\partial x^b} \right| = \frac{1}{\sqrt{y^2 + x^2}} \frac{1}{\sqrt{z^2 + y^2 + x^2}} = \frac{1}{r^2 \sin(\theta)}$$

And the Cartesian coordinates in terms of spherical polar ones:

$$x(r, \theta, \phi) := r \sin(\theta) \cos(\phi)$$

$$y(r, \theta, \phi) := r \sin(\theta) \sin(\phi)$$

$$z(r, \theta, \phi) := r \cos(\theta)$$

Producing the transformation matrix:

$$\begin{bmatrix} \frac{\partial x^a}{\partial x'^b} \end{bmatrix} = \begin{pmatrix} \cos(\phi) \sin(\theta) & \cos(\phi) r \cos(\theta) & -\sin(\phi) r \sin(\theta) \\ \sin(\phi) \sin(\theta) & \sin(\phi) r \cos(\theta) & \cos(\phi) r \sin(\theta) \\ \cos(\theta) & -r \sin(\theta) & 0 \end{pmatrix}$$

and the Jacobian of the transformation is

$$J = \left| \frac{\partial x^a}{\partial x'^b} \right| = r^2 \sin\left(\theta\right)$$

Observe that $J' \to 0$ when $r \to \infty$ and it diverges when $r \to 0$. But when $\theta \to 0$ or $\theta \to n\pi$, that is, on the poles, J' also diverges.

As we see, we confirm the product rule for the determinants that the Jacobian of the inverse transformation where J = 1/J'

3. Show by manipulating the dummy indices that

$$(Z_{abc} + Z_{cab} + Z_{bca}) X^a X^b X^c = 3Z_{abc} X^a X^b X^c.$$

Solution:

$$(Z_{abc} + Z_{cab} + Z_{bca}) X^{a} X^{b} X^{c} = Z_{abc} X^{a} X^{b} X^{c} + Z_{cab} X^{a} X^{b} X^{c} + Z_{bca} X^{a} X^{b} X^{c}$$
(1)

$$= Z_{abc} X^{a} X^{b} X^{c} + Z_{cab} X^{a} X^{b} X^{c} + Z_{bca} X^{a} X^{b} X^{c}$$
(2)

$$= Z_{abc} X^{a} X^{b} X^{c} + Z_{abc} X^{a} X^{b} X^{c} + Z_{abc} X^{a} X^{b} X^{c}$$
(3)

$$= 3Z_{abc} X^{a} X^{b} X^{c}$$
(4)

PS: From line 2 to 3 we switch in the second term $c \to a$, $a \to b$ and $b \to c$, in the third term $b \to a$, $c \to b$ and $a \to c$.

- 4. Show that:
 - (i) $\delta_a^b X^a = X^b$,

$$\delta_a^b X^a = \frac{\partial x^b}{\partial x^a} X^a = \sum_{a=1}^n \frac{\partial x^b}{\partial x^a} X^a = X^b$$

because

$$\sum_{a=1}^{n} \frac{\partial x^{b}}{\partial x^{a}} = \begin{cases} 0 & \text{when } a \neq b \\ 1 & \text{when } a = b \end{cases}$$

(ii) $\delta_a^b X_b = X_a$ Solution:

$$\delta_a^b X_b = \frac{\partial x^b}{\partial x^a} X_b = \sum_{b=1}^n \frac{\partial x^b}{\partial x^a} X_b = X_a$$

because

$$\sum_{b=1}^{n} \frac{\partial x^{b}}{\partial x^{a}} = \begin{cases} 0 & \text{when } b \neq a \\ 1 & \text{when } b = a \end{cases}$$

(iii) $\delta^b_a \delta^c_b \delta^d_c = \delta^d_a$. Solution:

$$\delta^b_a \delta^c_b \delta^d_c = \frac{\partial x^b}{\partial x^a} \frac{\partial x^c}{\partial x^b} \frac{\partial x^d}{\partial x^c} = \sum_{b=1}^n \sum_{c=1}^n \frac{\partial x^b}{\partial x^a} \frac{\partial x^c}{\partial x^b} \frac{\partial x^d}{\partial x^c} = \sum_{b=1}^n \frac{\partial x^b}{\partial x^a} \frac{\partial x^d}{\partial x^b} = \frac{\partial x^d}{\partial x^a} = \delta^d_a$$

because

$$\sum_{c=1}^{n} \frac{\partial x^{c}}{\partial x^{b}} = \begin{cases} 0 & \text{when } c \neq b \\ 1 & \text{when } c = b \end{cases}$$

and

$$\sum_{b=1}^{n} \frac{\partial x^{b}}{\partial x^{a}} = \begin{cases} 0 & \text{when } b \neq a \\ 1 & \text{when } b = a \end{cases}$$

5. If Y^a and Z^a are contravariant vectors, then show that Y^aZ^b is a contravariant vector of rank 2.

Solution:

$$Y^{'a}Z^{'b} = \frac{\partial x^{'a}}{\partial x^c}Y^c \frac{\partial x^{'b}}{\partial x^d}Z^d = \left(\frac{\partial x^{'a}}{\partial x^c}\frac{\partial x^{'b}}{\partial x^d}\right)Y^cZ^d$$

then, as we see above, Y^aZ^b transform according to a contravariant tensor of rank 2.

PS: In term of components, we had have,

$$Y^{a}Z^{b} = \begin{pmatrix} Y^{1}Z^{1} & Y^{1}Z^{2} & \cdots & Y^{1}Z^{n} \\ Y^{2}Z^{1} & Y^{2}Z^{2} & \cdots & Y^{2}Z^{n} \\ \vdots & \vdots & \ddots & \vdots \\ Y^{n}Z^{1} & Y^{n}Z^{2} & \cdots & Y^{n}Z^{n} \end{pmatrix}$$

with n^2 components, as expected.

6. Write down the change of coordinates from Cartesian coordinates $(x^a) = (x, y)$ to plane polar coordinates $(x^{'a}) = (R, \phi)$ in \mathbb{R}^2 and obtain the transformation matrix $\left[\partial x^{'a}/\partial x^b\right]$ expressed as a function of the primed coordinates. Find the components of the tangent vector to the curve consisting of a circle of radius a centred at origin with the standard parametrization (see exercise 5.1(i)) and use $X^{'a} = \partial x^{'a}/\partial x^b$ X^b to find its components in the primed coordinate system.

Solution:

The change of coordinates are:

$$R = \sqrt{x^2 + y^2} \tag{5}$$

$$\phi = \operatorname{atan}\left(\frac{y}{x}\right) \tag{6}$$

The transformation matrix is

$$\begin{bmatrix} \frac{\partial x^{'a}}{\partial x^b} \end{bmatrix} = \begin{pmatrix} \frac{x}{\sqrt{y^2 + x^2}} & \frac{y}{\sqrt{y^2 + x^2}} \\ -\frac{y}{y^2 + x^2} & \frac{x}{y^2 + x^2} \end{pmatrix} = \begin{pmatrix} \cos \phi & \sin \phi \\ -\frac{\sin \phi}{R} & \frac{\cos \phi}{R} \end{pmatrix}$$
(7)

as a function of the primed coordinates.

To find the components of the tangent vector to the curve:

Circle equation: $x^2 + y^2 = a^2$

Parametric form:
$$\begin{cases} x = t \\ y = \pm \sqrt{a^2 - t^2} \end{cases}$$

thus $x^1 = x$ and $x^2 = y$ we represent the curve as $x^a(t)$. So, the tangent vector,

$$\frac{dx^a}{dt} = \begin{pmatrix} \frac{dx^1}{dt} \\ \frac{dx^2}{dt} \end{pmatrix} = \begin{pmatrix} 1 \\ \mp \frac{t}{\sqrt{a^2 - t^2}} \end{pmatrix} = \begin{pmatrix} 1 \\ -\frac{x}{y} \end{pmatrix}$$

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Using $X^{'a} = (\partial x^{'a}/\partial x^b) X^b$:

$$X^{'a} = \begin{pmatrix} \frac{x}{\sqrt{y^2 + x^2}} & \frac{y}{\sqrt{y^2 + x^2}} \\ -\frac{y}{y^2 + x^2} & \frac{x}{y^2 + x^2} \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -\frac{x}{y} \end{pmatrix}$$

$$= \begin{pmatrix} \frac{x}{\sqrt{y^2 + x^2}} - \frac{x}{\sqrt{y^2 + x^2}} \\ -\frac{y}{y^2 + x^2} - \frac{x^2}{y(y^2 + x^2)} \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ -\frac{y^2}{y(y^2 + x^2)} - \frac{x^2}{y(y^2 + x^2)} \end{pmatrix}$$
(10)

$$= \begin{pmatrix} \frac{x}{\sqrt{y^2 + x^2}} - \frac{x}{\sqrt{y^2 + x^2}} \\ -\frac{y}{y^2 + x^2} - \frac{x^2}{y(y^2 + x^2)} \end{pmatrix}$$
(9)

$$= \begin{pmatrix} 0 \\ -\frac{y^2}{y(y^2+x^2)} - \frac{x^2}{y(y^2+x^2)} \end{pmatrix} \tag{10}$$

$$= \begin{pmatrix} 0 \\ -\frac{1}{y} \end{pmatrix} \tag{11}$$

$$= \begin{pmatrix} 0 \\ -\frac{1}{a \sin \phi} \end{pmatrix} \tag{12}$$

that are the components of the tangent vector in primed coordinate system.