



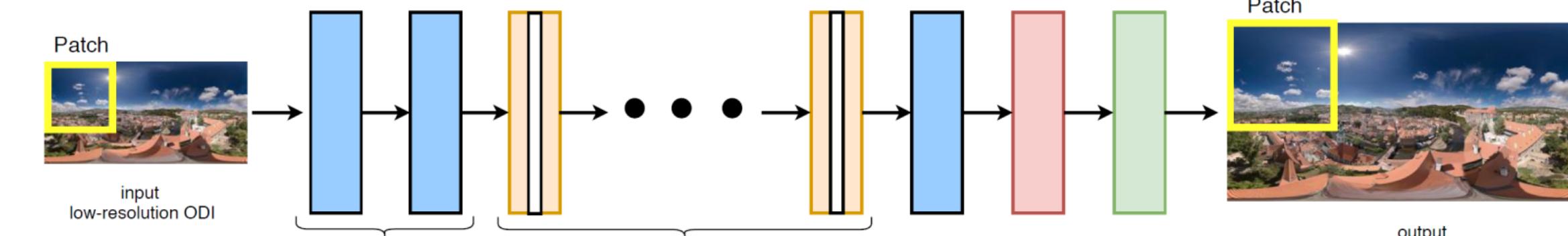
Super-resolution of Omnidirectional Images Using Adversarial Learning

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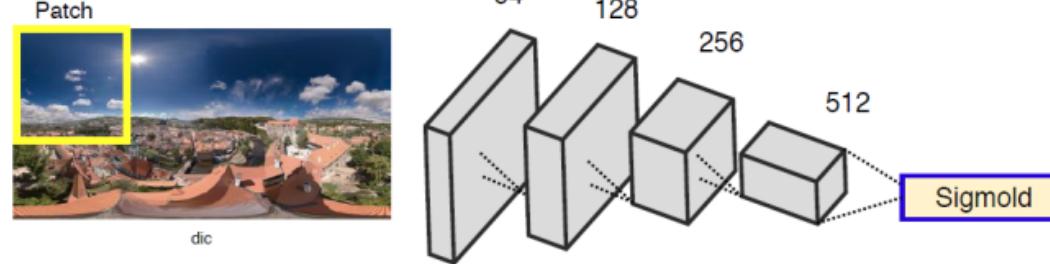
Problem and Objective

- Designing immersive virtual reality systems with ODIs is challenging as they require high resolution content.
- Proposing improved generative adversarial network (GAN) based model for super-resolution of ODIs.
- Handling artefacts obtained in the spherical observational space.

Proposed Model



Architecture of Generator Network with corresponding block labels [14].



Architecture of the used Discriminator Network, PatchGAN [17].

Loss functions

The objective function:

$$\mathbf{G}^* = \arg \min_G \max_D [\mathcal{L}_{adv}(\mathbf{G}, \mathbf{D})] + \beta \mathcal{L}_{feat}(\mathbf{G}) + \gamma \mathcal{L}_{360-SS}(\mathbf{G})$$

360-SS Loss:

$$\mathcal{L}_{360-SS} = \frac{1}{K} \sum_{i=1}^K d_{360-SS}^i, \quad q_r^{x,y} = \cos \frac{(y + 0.5 - (H/2r)\pi)}{(H/r)}.$$

Feature Loss: $\mathcal{L}_{feat} = \frac{1}{K} \sum_{i=1}^K (\mathcal{F}^i(I_{360-sr}) - \mathcal{F}^i(\hat{I}_{360-sr})),$

Adversarial Loss: $\mathcal{L}_{adv} = \sum_{i=1}^K (-\log \mathbf{D}(\mathbf{G}(I_{360-lr}^i))).$

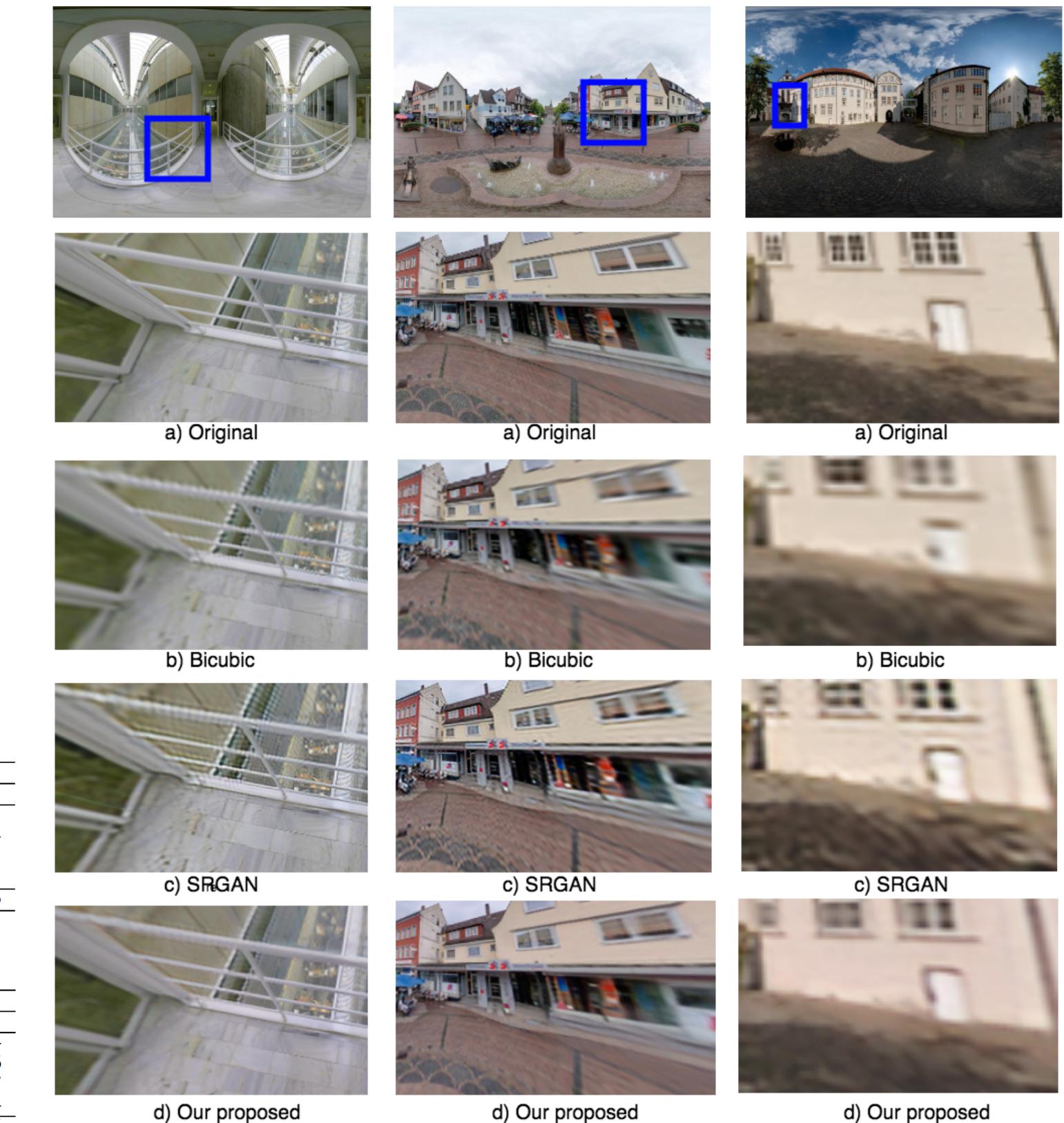
Training

- 3500 ODIs.
- Random crops of size 512×512.
- Data augmentation techniques such as rotation and flipping.
- 2hr training time with 12 GB NVIDIA Titan-X GPU on an Intel Xeon E7 core i7 machine.
- Inference time is 0.030 milliseconds for each ODI.

Quantitative Results

By a factor of 2 on 500 ODIs

Method	r = 2			
	SSIM	PSNR	WS-SSIM	WS-PSNR
NN	0.92 ± .06	29.38 ± .04	0.86 ± .03	34.34 ± .05
Bicubic	0.93 ± .05	30.64 ± .06	0.88 ± .04	35.54 ± .07
SRGAN [14]	0.94 ± .05	32.56 ± .06	0.90 ± .06	36.35 ± .06
Ours	0.95 ± .04	33.20 ± .04	0.92 ± .04	37.68 ± .05
Ours+ 360-SS loss	0.95 ± .03	33.56 ± .04	0.93 ± .06	37.96 ± .03



By a factor of 4 on 500

Method	r = 4			
	SSIM	PSNR	WS-SSIM	WS-PSNR
NN	0.83 ± .07	25.77 ± .05	0.71 ± .03	32.44 ± .05
Bicubic	0.85 ± .07	26.71 ± .03	0.74 ± .04	32.76 ± .04
SRGAN [14]	0.86 ± .02	27.11 ± .09	0.75 ± .06	34.76 ± .03
Ours	0.87 ± .05	27.19 ± .08	0.76 ± .05	35.89 ± .05
Ours+ 360-SS loss	0.87 ± .04	27.70 ± .03	0.77 ± .08	36.98 ± .06

By a factor of 8 on 500

Method	r = 8			
	SSIM	PSNR	WS-SSIM	WS-PSNR
NN	0.83 ± .07	23.47 ± .05	0.64 ± .06	31.12 ± .04
Bicubic	0.85 ± .07	24.26 ± .03	0.66 ± .07	31.83 ± .06
SRGAN [14]	0.86 ± .02	25.10 ± .09	0.70 ± .06	33.00 ± .07
Ours	0.87 ± .05	26.24 ± .08	0.73 ± .07	34.68 ± .04
Ours+ 360-SS loss	0.87 ± .04	26.56 ± .03	0.75 ± .06	35.54 ± .06

References

- [14] C. Ledig, et al., "Photo-realistic single image super-resolution using a generative adversarial network," CVPR, 2017.
[17] P. Isola, et al., "Image-to image translation with conditional adversarial networks," CVPR, 2017.

