



MAGIC assessment cover sheet

Course:	MAGIC063
Session:	2023-2024
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- ① a) No - If $x_1, x_2 \in X$ s.t. $x_1 = 0$ and $x_2 \neq 0$ then
 the only open set s.t. $x_i \in U_i \subset Y$ is $U_1 = \mathbb{R}$ so
 $x_2 \in U_2 \subset Y$ will have $U_1 \cap U_2 = \mathbb{R} \cap U_2 \neq \emptyset$
- b) No - For open set $U = \{x\}$ where $x \in \mathbb{R} / \{0\}$, if
 T generated by $\mathcal{B} \ni B \in \mathcal{B}$ s.t. $x \in B$ and $x \in B$ and
 $\{x\} \subseteq U = \{x\}$ so $B = \{x\}$ and there are
 \mathbb{R} different such $\{x\}$ and $\mathbb{R} / \{0\}$ not countable
- c) Yes - Open cover $\bigcup_{x \in A} U_x = X$ then must have
 an $x \in A$ s.t. $U_x = \mathbb{R}$ as \mathbb{R} only open set containing
 0 therefore has finite subcover \mathbb{R}
- d) No - For example $\{1\} \in T$ but $f^{-1}(\{1\}) = \{x\}$ and $\{x\} \notin T$
- e) No - as $\mathbb{R} \in T$ but $f^{-1}(\mathbb{R}) = [-1, 1] \notin T$
- f) Yes - If $X_1, X_2 \in T$ s.t. $X = X_1 \cup X_2$ then one
 of X_1 or X_2 is \mathbb{R} as only open set containing 0
 so if $X_1 = \mathbb{R}$ then X_2 cannot be disjoint to X_1 .

② a) $x = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix}$

$$x^T J x = J \Rightarrow \begin{pmatrix} x_1 & x_3 \\ x_2 & x_4 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & x_1 x_4 - x_2 x_3 \\ x_2 x_3 - x_1 x_4 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

which means M matrices s.t. $\det(Jx) = 1$
 The map $\det : N \rightarrow \mathbb{R}$ is smooth and $1 \in \mathbb{R}$ is a
 regular value of \det as for every $a \in f^{-1}(1)$ we
 must have at least one of $x_1, x_2, x_3, x_4 \neq 0$ so
 $\text{rank } d(\det)|_a = (x_4 - x_3, -x_2, x_1)$ has rank 1.
 Therefore by the regular value theorem $M = \det^{-1}(1)$ is
 a submanifold of N of dimension 1. It is of
 dimension 3 since $4 = \dim N = \dim \mathbb{R} + 3$

b) M is not compact as it is not bounded so by
 Heine-Borel cannot be compact

(2) c) Can have open covering $U_1 = \mathbb{R}^4 / \{x \in \mathbb{R}^4 \text{ s.t. } x_4 = 0\}$ and $U_2 = \mathbb{R}^4 / \{x \in \mathbb{R}^4 \text{ s.t. } x_3 = 0\}$

$$\phi_1(x_1, x_2, x_3, x_4) = (x_2, x_3, x_4) \quad \phi_1: U_1 \rightarrow \mathbb{R}^3$$

$$\phi_2(x_1, x_2, x_3, x_4) = (x_1, x_3, x_4) \quad \phi_2: U_2 \rightarrow \mathbb{R}^3$$

$$\phi_1^{-1}(y_1, y_2, y_3) = \left(\frac{1+y_1 y_2}{y_3}, y_1, y_2, y_3 \right)$$

$$\phi_2^{-1}(y_1, y_2, y_3) = \left(y_1, \frac{y_1 y_3 - 1}{y_2}, y_2, y_3 \right)$$

$$U_1 \cap U_2 = \mathbb{R}^4 / \{x \in M \text{ s.t. } x_4 = 0 \text{ or } x_3 = 0\}$$

$$\phi_2 \circ \phi_1^{-1}(y_1, y_2, y_3) = \left(\frac{1+y_1 y_2}{y_3}, y_2, y_3 \right) \text{ smooth on } y_3 \neq 0$$

$\phi_1(U_1 \cap U_2)$ as $x_4 \neq 0 \Rightarrow y_3 \neq 0$

$$\phi_1 \circ \phi_2^{-1}(y_1, y_2, y_3) = \left(\frac{y_1 y_3 - 1}{y_2}, y_2, y_3 \right) \text{ smooth } \phi_2(U_1 \cap U_2)$$

as $x_3 \neq 0 \Rightarrow y_2 \neq 0$

$$T_{1,2} = \phi_1 \circ \phi_2^{-1} \text{ so } dT_{1,2} = \begin{pmatrix} \frac{y_3}{y_2} & -\frac{y_1 y_3 - 1}{y_2^2} & \frac{y_1}{y_2} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$dT_{2,1} = \begin{pmatrix} \frac{y_2}{y_3} & \frac{y_1}{y_3} & -\frac{1+y_1 y_2}{y_3^2} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\det[dT_{1,2}] = \frac{y_3}{y_2} \text{ has rank 1.}$$

$$\det[dT_{2,1}] = \frac{y_2}{y_3}$$

Both negative at for example $(1, 2, -1)$ so not an orientation

$$a) h(x) =$$

$$\textcircled{2} \text{ d)} \quad \text{For } x \in M \quad x = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix}$$

$$h(x) = x^2 = \begin{pmatrix} x_1^2 + x_2 x_3 & x_1 x_2 + x_2 x_4 \\ x_3 x_1 + x_4 x_2 & x_3 x_2 + x_4^2 \end{pmatrix}$$

$$\begin{aligned} \det h(x) &= x_1^2 x_2 x_3 + x_1^2 x_4^2 + x_2^2 x_3^2 + x_2 x_3 x_4^2 \\ &\quad - x_1^2 x_2 x_3 - x_1 x_2 x_3 x_4 - x_3 x_2 x_1 x_4 \\ &\quad - x_2 x_3 x_4^2 \\ &= x_1 x_4 (x_1 x_4 + x_2 x_3) + x_2 x_3 (x_2 x_3 - x_1 x_4) \end{aligned}$$

$$\text{or } p = x \in M \text{ so } x_1 x_4 - x_2 x_3 =$$

$$= x_1 x_4 (1) + x_2 x_3 (-1)$$

$$= x_1 x_4 - x_2 x_3 = 1$$

$$dh_p$$

$$\Rightarrow h(x) \in M$$

\textcircled{2} e) ~~det~~ $f: M \rightarrow \mathbb{R}$ ~~surjection~~

$$\det f(x) \in \mathbb{R}$$

$$f: M \rightarrow \mathbb{R} \quad x = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix} \in M$$

$$f(x) = x_1$$

$$df_x = (1 \ 0 \ 0 0)$$

has maximal rank for all $x \in M$ $\Rightarrow df_x$ surjection

$$② d) h(x) = \begin{pmatrix} x_1^2 + x_2 x_3 & x_1 x_2 + x_2 x_4 & x_3 x_1 + x_3 x_4 & x_3 x_2 + x_4^2 \end{pmatrix}$$

$$dh_p = \begin{pmatrix} 2x_1 & x_3 & x_2 & 0 \\ x_2 & x_1 + x_4 & 0 & x_2 \\ x_3 & 0 & x_1 + x_4 & 0 \\ 0 & x_3 & x_2 & 2x_4 \end{pmatrix}$$

for $p = (0, 1, 1, 0) \in M$

$$dh_p = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

has rank 2, so dh_p not injective
therefore not an immersion
so also can't be an embedding

$$③ a) f^* \gamma = x_1 y dx \otimes dx$$

$$f^* dx = y dx + x dy$$

$$f^* dx^2 = z dx + x dz$$

$$\begin{aligned} \circ f^* \eta &= y^2 dx \otimes dx + xy dx \otimes dy + xy dy \otimes dx \\ &\quad + x^2 dy \otimes dy + z^2 dx \otimes dx + xz dx \otimes dz \\ &\quad + xz dz \otimes dx + x^2 dz \otimes dz \end{aligned}$$

$$b) \text{ Need } \eta(d\{X\}, d\{Y\}) = 0$$

$$d\{X\} = y X' + x X^2$$

$$d\{Y\} = z Y' + x Y^3$$

$$X = x \frac{\partial}{\partial x^2} - y \frac{\partial}{\partial y} - z \frac{\partial}{\partial z}$$

⑦ 1 is a section of the section

~~that~~ e^{x_1} is the function
 $(x_1, x_2, x_3) \mapsto e^{x_1}$

for $(0, x_2, x_3)$, e^{x_1}

on $\{x \in M : x = (0, x_2, x_3)\}$

$$\nabla 1 = dx_3$$

$$\begin{aligned}
 3) c) \quad & X = x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \\
 & \dot{x}(t) = x(t) \\
 & \dot{y}(t) = -y(t) \\
 & \dot{z}(t) = z(t) \\
 & x(0) = x_0 \\
 & y(0) = y_0 \\
 & z(0) = z_0
 \end{aligned}$$

$$5) a) \underset{\text{torsion}}{T(x, y)} = \nabla_x Y - \nabla_y X - [X, Y]$$

$$[\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}] = \frac{\partial}{\partial x^i} \frac{\partial}{\partial x^j} - \frac{\partial}{\partial x^j} \frac{\partial}{\partial x^i} = 0$$

$$3) \Rightarrow T\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} - \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}$$

$$\begin{aligned}
 d) \quad & \text{For } i=1, j=2 \quad T = \nabla_{\frac{\partial}{\partial x^1}} \frac{\partial}{\partial x^2} - \nabla_{\frac{\partial}{\partial x^2}} \frac{\partial}{\partial x^1} \\
 & = x^2 \frac{\partial}{\partial x^1}
 \end{aligned}$$

$$\text{For } i=2, j=2 \quad T = -x^2 \frac{\partial}{\partial x^1}$$

$$\text{For } i=j=1 \text{ or } 2 \quad T = 0$$

For curvature

$$(R_{ij})^a_b = \partial_i T_{jb}^a - \partial_j T_{ib}^a + T_{jb}^c T_{ic}^a - T_{ib}^c T_{jc}^a$$

$$\Rightarrow (R_{12}) = \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix}$$

$$(R_{21}) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$(R_{11}) = (R_{22}) = 0$$

b) From the notes for a closed loop square γ
of length $L > 0$ the holonomy of ∇ around γ is

$$T_\gamma = \prod_{i=1}^4 L^2 (R_{ij}) + O(L^2)$$

where (R_{ij}) is the curvature given above

$$x = x_0 \cos t$$

$$\dot{x}(t) = \dot{x}_0 \sin t$$

$$\ddot{x}(t) = -\dot{x}_0 \cos t$$

$$\dot{y}(t) = -y_0 \sin t$$

$$\ddot{y}(t) = -y_0 \cos t$$

$$\dot{z}(t) = z_0 \sin t$$

$$\ddot{z}(t) = z_0 \cos t$$

$$x(0) = x_0$$

$$y(0) = y_0$$

$$z(0) = z_0$$

⑥ a) $\ddot{x}(t) = [(1-t^2) - 2t^2] (\cos t, \sin t)$
 $+ t(1-t^2) (-\sin t, \cos t)$
 $= (1-3t^2)(\cos t, \sin t) + t(1-t^2)(-\sin t, \cos t)$

From problem set 6 question 1 ~~the~~ α is a geodesic if α a critical point of E where

$$E = \frac{1}{2} \int_0^1 g(\dot{\gamma}(t), \dot{\gamma}(t)) dt$$

Let $\dot{\alpha}(t) = (\dot{x}_1(t), \dot{x}_2(t))$ and $d_s|_{s=0} (x_1^s(t), x_2^s(t)) = (X_1(t), X_2(t))$

$$\begin{aligned} \frac{d}{ds} E[\gamma_s] \Big|_{s=0} &= \frac{1}{2} \int_0^1 2\dot{x}_1(t) X_1(t) + 2\dot{x}_2(t) X_2(t) dt \\ &= \int_0^1 [(1-3t^2)\cos(t) - t(1-t^2)\sin(t)] X_1(t) dt \\ &\quad + \int_0^1 [(1-3t^2)\sin(t) + t(1-t^2)\cos(t)] X_2(t) dt \end{aligned}$$

which is not 0 for all variations so
not a geodesic

b) β geodesic $\Rightarrow \nabla_{\frac{d}{dt}}^\beta \dot{\beta} = 0$

③ c) $X = x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} - z \frac{\partial}{\partial z}$

 $\dot{x}(t) = x(t), \quad x(0) = x_0$
 $\dot{y}(t) = -y(t), \quad y(0) = y_0$
 $\dot{z}(t) = -z(t), \quad z(0) = z_0$
 $x(t) \ln|x(t)| = t + k = t + \ln|x_0|$
 $x(t) = e^{t + \ln|x_0|}$

Hence $\theta_x(t) = e^{t + \ln|x_0|}$

 $y(t) = e^{t - \ln|y_0|}, \quad z(t) = e^{t - \ln|z_0|}$
 $\theta_{(x,y,z)}(t) = (e^{t + \ln|x_0|}, e^{t - \ln|y_0|}, e^{t - \ln|z_0|})$ an embedding
 $\theta_1(x, y, z) = (e^{1 + \ln|x|}, e^{1 - \ln|y|}, e^{1 - \ln|z|})$

d) $bX = a(x, y, z) dx + b(x, y, z) dy + c(x, y, z) dz$

 $a(x, y, z) = bX\left(\frac{\partial}{\partial x}\right) = g(X, \frac{\partial}{\partial x}) = \theta^* g_{\text{Euc}}(x, \frac{\partial}{\partial x})$
 $= g_{\text{Euc}}\left(\frac{\partial}{\partial x}, d\theta^*\frac{\partial}{\partial x}\right)$
 $= g_{\text{Euc}}\left(e^{\frac{\partial}{\partial x}}, \frac{\partial}{\partial x}\right)$

$a(x, y, z) = bX\left(\frac{\partial}{\partial x}\right) = g\theta^* g_{\text{Euc}}(x, \frac{\partial}{\partial x})$

$= g_{\text{Euc}}(\theta, x, d\theta, \frac{\partial}{\partial x})$

⑦ a) $k(x_1 \times x_2, y_1 \times y_2) = g(x_1, y_1) + f(p) h(x_2, y_2)$
 for $x_1, y_1 \in T_p M$ $x_2, y_2 \in T_p N$ $p \in M$

b) Both g and h ~~are~~ symmetric so

~~$$k(x_1 \times x_2, y_1 \times y_2) = g(y_1, x_1) + f(p) h(y_2, x_2)$$~~

$$= g(x_1, y_1) + f(p) h(x_2, y_2)$$

so k symmetric

Both g and h positive definite and $f(p) \in (0, \infty)$

so $k(x_1 \times x_2, y_1 \times y_2) = g(x_1, y_1) + f(p) h(x_2, y_2) \geq 0$

~~$g(x_1, x_1) = 0$ only if $x_1 = 0$~~

~~$$k(x_1 \times x_2, x_1 \times x_2) = g(x_1, x_1) + f(p) h(x_2, x_2)$$~~

~~$g(x_1, x_1) = 0$ only if $x_1 = 0$~~

~~$f(p) \neq 0$ ~~so~~ ~~pos~~~~

$k = 0$ only if $g(x_1, x_1) = 0$ and

$h(x_2, x_2) = 0$ as ~~$f(p) > 0$~~ and both $\overset{g-h}{\checkmark}$ pos. def

so $k(x, x) = 0$ only if $x = 0$

(7c) (M, g) and (N, h) complete so all geodesics exist for all time for connexion $(\nabla_X g)$ $(\nabla_X h)$ and

$$(\nabla_X k)(Y, Z) = X[k(Y, Z)] - k(\nabla_X Y, Z) - k(Y, \nabla_X Z)$$

$$\text{so } \nabla_{\frac{d}{dt}}^X k(\dot{\gamma}) = 0$$

$$\begin{aligned} \nabla_{\frac{d}{dt}}^X k(\dot{\gamma}) &= \frac{d}{dt}[k(\dot{\gamma}, \dot{\gamma})] - k(\nabla_{\frac{d}{dt}}^X \dot{\gamma}, \dot{\gamma}) - k(\dot{\gamma}, \nabla_{\frac{d}{dt}}^X \dot{\gamma}) \\ &= \frac{d}{dt}[(g + fh)(\dot{\gamma}, \dot{\gamma})] - (g + fh)(\nabla_{\frac{d}{dt}}^X \dot{\gamma}, \dot{\gamma}) - k(\dot{\gamma}, \nabla_{\frac{d}{dt}}^X \dot{\gamma}) \\ &= \frac{d}{dt}g(\dot{\gamma}, \dot{\gamma}) + \frac{d}{dt}[fh(\dot{\gamma}, \dot{\gamma})] \text{ so } = 0. \\ &\quad - g(\nabla_{\frac{d}{dt}}^X \dot{\gamma}, \dot{\gamma}) - fh(\nabla_{\frac{d}{dt}}^X \dot{\gamma}, \dot{\gamma}) - g(\nabla_{\frac{d}{dt}}^X \dot{\gamma}, \dot{\gamma}) \\ &\quad - fh(\dot{\gamma}, \nabla_{\frac{d}{dt}}^X \dot{\gamma}) \end{aligned}$$

so since $f(p) \geq c$ we can see that a curve c is a geodesic iff it is a geodesic for g and h since (M, g) and (N, h) complete we then see that the geodesic exist for all time

End of submission.

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