Chris Gravel

EDUCATION

BASc Mechatronics Engineering with Al Option, University of Waterloo

2014 - 2019

SKILLS

Software Languages Python, C, C++, Bash, SQL, Matlab, Javascript Software Tools Microcontrollers, Linux, ROS, Git, OpenCV

EXPERIENCE

Software Engineer (Nest), Google LLC

Sept 2019 - Present

- Scoped infrastructure work for supporting test automation for new hardware products. Took ownership of design, and implementation while leading and providing guidance for junior SWEs. Infrastructure supported 20+ hardware devices, 1000+ automation tests, and impacts millions of users. (Python)
- Ideated and implemented a novel solution that applies statistical tools for detecting software regressions which reduced engineering effort to root cause latency issues from 4 hours to 1 min. (Python, SQL, Jenkins, Two sample T-test, DataStudio)
- Used optimization and ML techniques to create a flicker detection algorithm with a 96% recall rate. (Python, numpy, scipy, skimage)
- Worked with cross functional teams to design and implement infrastructure that analyzed power measurements and generated software regression signals. Test became the most productive test at Nest with over 50 actionable signals that drove product decisions. (Python, numpy)

Perception Team Engineer, Avidbots Corp.

May 2018 - Aug 2018

- Developed mathematical model for optimal sensor layout for cliff detection using 1D sensors. (Python, Geometry, Numerical Methods)
- Automated collection and labelling of vision data using localization information and camera feeds on the robot. (OpenCV, Python, C++)

IoT & AI Developer, IBM

Sept 2017 - Dec 2017

 Created real-time object recognition solution with 95% accuracy for POC contract using supervised learning on a FasterRCNN network. (Python, FasterRCNN)

Robotics Software Developer, Avidbots Corp.

Jan 2017 - April 2017

- Developed numerical model in C++ and Matlab for simulating trajectory to determine traversal time. (C++, Python, ROS, Matlab, Numerical Methods)
- Improved performance by 10% by applying low pass filters to trajectory coordinates using OpenCV. (C++, ROS, OpenCV)
- Wrote unit tests for a robotics system on the ROS platform in C++ using the Google test framework. (C++, ROS)

Junior Hardware Designer, Imagine Communications

May 2016 - Aug 2016

- Wrote VHDL code to optimize FPGA implementation of an Ethernet receiver which reduced read clock cycles by 8x.
 (VHDL)
- Designed and implemented a FPGA component which captures and records ethernet packets for debugging. (VHDL)
- Automated hardware testing using electrical instrumentation and Python APIs. (Python)

Mechatronics Prototyper, Engineering Ideas Clinic

Sept 2015 - Dec 2015

- Created schematics, layouts, and soldered PCBs to create proof of concept prototypes
- Salvaged parts from E-waste bins for use in prototypes to save over \$1,000 in resources
- Designed and built an AM Radio to be used as a teaching aid for 4th year electrical students.

Web App Developer, Computer Science Computing Facility

Jan 2015 - April 2015

- Improved performance of a core web app by 2,000%, reducing page load time by 13 seconds.
- Indexed database by cardinality to improve lookup time in relational database.

ENGINEERING PROJECTS

Optimization of Vehicle Suspension using Enhanced Hillclimbing — Python, Matlab • Created a novel search algorithm that outperforms other state-of-the-art search algorithms in the field.	2018
Git Status Tool (gst) — Python • Commandline tool for improving my own Git workflow. Compatible with Mac and Linux.	2018
Asteroids Game built on ARM Cortex-M microcontroller — C • Re-created the game of Asteroids on an ARM Cortex-M microcontroller with RTOS.	2016
 Used semaphores and mutexes to enable synchronous multitasking operations. 	

ACHIEVEMENTS

• Runner-up in an international IBM internal coding competition (CodeBlue 2017).

• Created physics engine to model the original game physics.

- Received multiple awards (4 spot bonuses, 2 peer bonuses) at Google due to impact of contributions.
- Received Python readability status at Google which allows me to approve Python changes for their style.