# **Chris Gravel**

## **EDUCATION**

BASc Mechatronics Engineering with Al Option, University of Waterloo

2014 - 2019

#### SKILLS

Software Languages Python, C, C++, Bash, SQL, Matlab, Javascript Software Tools Microcontrollers, Linux, ROS, Git, OpenCV

#### EXPERIENCE

## Senior Software Engineer (Nest), Google LLC

Sept 2019 - Present

- Lead a team of 5 engineers to design and build infrastructure for supporting Google's Matter launch. The infra we built supports creating dynamic topologies of real devices with a complex configuration matrix of more than 100 params and served as a release gate for millions of devices. (Python)
- Designed and implemented pipelines for continuous delivery and continuous integration testing. Integrated pipelines across multiple ecosystems (Google internal, Github, Gerrit, Jenkins). (Python, Bash, Docker, Jenkins)
- Scoped infrastructure work for supporting new hardware in our test automation. Took ownership of design, and implementation while leading and providing guidance for junior SWEs. Infrastructure supported 20+ hardware devices, 1000+ automation tests, and impacts millions of users. (Python)
- Ideated and implemented a novel solution that applies statistical tools for detecting software regressions involving latency which reduced engineering effort to root cause from 4 hours to 1 min. (Python, SQL, Jenkins, Two sample T-test, DataStudio)
- Used optimization and ML techniques to create a flicker detection algorithm with a 96% recall rate. (Python, numpy, scipy, skimage)
- Mentored engineers to help them advance in their career and adapt to the professional environment. Arranged quarterly team gatherings for 15+ people. Took advice from those willing to teach me. (Soft skills)

## Perception Team Engineer, Avidbots Corp.

May 2018 - Aug 2018

- Developed mathematical model for optimal sensor layout for cliff detection using 1D sensors. (Python, Geometry, Numerical Methods)
- Automated collection and labelling of vision data using localization information and camera feeds on the robot. (OpenCV, Python, C++)

#### IoT & AI Developer, IBM

Sept 2017 - Dec 2017

 Created real-time object recognition solution with 95% accuracy for POC contract using supervised learning on a FasterRCNN network. (Python, FasterRCNN)

## Robotics Software Developer, Avidbots Corp.

Jan 2017 - April 2017

- Developed numerical model in C++ and Matlab for simulating trajectory to determine traversal time. (C++, Python, ROS, Matlab, Numerical Methods)
- Improved performance by 10% by minimizing kinematic accelerations on robot caused by trajectory jaggedness. (C++, ROS, OpenCV)
- Wrote unit tests for a robotics system on the ROS platform in C++ using the Google test framework. (C++, ROS)

## Junior Hardware Designer, Imagine Communications

May 2016 - Aug 2016

- Wrote VHDL code to optimize FPGA implementation of an Ethernet receiver which reduced read clock cycles by 8x. (VHDL)
- Designed and implemented a FPGA component which captures and records ethernet packets for debugging. (VHDL)
- Automated hardware testing using electrical instrumentation and Python APIs. (Python)

#### Mechatronics Prototyper, Engineering Ideas Clinic

Sept 2015 - Dec 2015

- Created schematics, layouts, and soldered PCBs to create proof of concept prototypes
- Salvaged parts from E-waste bins for use in prototypes to save over \$1,000 in resources
- Designed and built an AM Radio to be used as a teaching aid for 4th year electrical students.

## Web App Developer, Computer Science Computing Facility

Jan 2015 - April 2015

- Improved performance of a core web app by 2,000%, reducing page load time by 13 seconds.
- Indexed database by cardinality to improve lookup time in relational database.

## ENGINEERING PROJECTS

Optimization of Vehicle Suspension using Enhanced Hillclimbing — Python, Matlab  • Created a novel search algorithm that outperforms other state-of-the-art search algorithms in the field.	2018
Git Status Tool (gst) — Python  • Commandline tool for improving my own Git workflow. Compatible with Mac and Linux.	2018
Asteroids Game built on ARM Cortex-M microcontroller — C  • Re-created the game of Asteroids on an ARM Cortex-M microcontroller with RTOS.	2016
<ul> <li>Used semaphores and mutexes to enable synchronous multitasking operations.</li> </ul>	

## ACHIEVEMENTS

• Runner-up in an international IBM internal coding competition (CodeBlue 2017).

• Created physics engine to model the original game physics.

- Received multiple awards (4 spot bonuses, 2 peer bonuses) at Google due to impact of contributions.
- Received Python readability status at Google which allows me to approve Python changes for their style.