Contents

1	Task 1	
	1.1 Subtask 1	
	1.1.1 Proving associativity	
	1.1.1 Proving associativity	
	1.2 Subtask 2	
2	Task 2 2.1 Speedups	
3	Task 3	
4	Task 4	,
1	Tools 1	

1 Task 1

1.1 Subtask 1

For subtask 1 we look at the following list homomorphism:

```
h [] = e
h [a] = f a
h (x ++ y) = (h x) o (h y)
```

1.1.1 Proving associativity

I aim to prove that for any [a,b,c] in Img(h) the following holds: (a o b) o c = a o (b o c)

I pick (x,y,z) and such that (h x) = a, (h y) = b, (h z) = c I look at the third statement and state:

$$h((h (x ... y) ... h(z)) = (h(x) o (h y)) o (h z) = (a o b) o c$$

Then i calculate it in "reverse" and say

$$h \times ... (h (y ... z)) = h(x) o (h(y) o h(z)) = a o (b o c)$$

Furthermore we know that however we split our input lists $(x ... (y ... x) \text{ or } ((x ... y) ... z, \text{ our program gives the same result (e.g. it is a well-defined homomorphism). Therefore it is valid to say$

1.1.2 Proving the neutral element

I then want to prove that for all b in Img(h), b o e = e o b = b

For every b in Img(h) there exists an a in A s.t. h(a) = b We have from the assignment text(and the definition of a LH) that

```
h([a]) = h([] ++ [a]) = h([a] ++ [])
=>
h (a) = h ([]) o h (a) = h(a) o h ([])
=>(knowing h [] = e)
b = b o e = e o b
```

1.2 Subtask 2

I want to prove the following invariant:

```
reduce (..) [] distr_p x == x
```

And we can use this on the lhs of the invariant, and draw the following conclusion

```
(reduce (+) 0) . (map f)
=>
  (reduce (+) 0) . (map f) . (reduce (..) []) distr_p
=> (3rd promotion lemma)
  (reduce (+) 0) . (map(reduce(+)0)) . map(map f)) . distr_p
=> (1st promotion lemma)
  (reduce (+) 0) . (map ( (reduce (+) 0) . (map f) ) ) . distr_p
```

$2 \quad \text{Task } 2$

We write the parallel version of the longest segment by implementing according to the lecture notes. More in-depth; We calculate the LSS and the following extra baggage:

1. LSS: The current longest segment, which is defined as max(max(lssx, lssy), connecting_length) where the connecting length is (lcsx + lisy) if and only if there is a connection across boundaries

- 2. LIS: Longest initial segment, which differs from MIS by only being applicable if lisx spans the whole x segment. This is the expanded expression: if connect && lisx ==tlx then tlx + lisy else lisx
- 3. LCS: Longest Concluding segment, which differs in the same way, and is computed much the same (with the exception of checking against thy instead)
- 4. TL: The total length is the sum of the subsegments total length, e.g. tlx + tly
- 5. First: First is firstx(unless x is the neutral element, in which case we get firsty)
- 6. Last: Much like first, last is lasty unless y is the neutral element.

2.1 Speedups

I now test the runtime difference between a sequential c compilation, and an opencl compilation:

```
[wbr220@a00333 lssp]$ futhark dataset --i32-bounds=-10:10 -b -g [10000000]i32 > data.i:
[wbr220@a00333 lssp]$ futhark c -o lssp-sorted-c lssp-sorted.fut
[wbr220@a00333 lssp]$ futhark opencl -o lssp-sorted-opencl lssp-sorted.fut
[wbr220@a00333 lssp]$ ./lssp-sorted-c -t /dev/stderr -r 10 <data.in > /dev/null
26101
25264
24472
24481
24607
24504
24471
24475
24472
25291
-- Avg: 24813
[wbr220@a00333 lssp]$ ./lssp-sorted-opencl -t /dev/stderr -r 10 <data.in > /dev/null
741
739
735
737
738
```

```
737
735
736
743
737
-- Avg: 737
```

And we see a 97% speedup on average

3 Task 3

I wrote the code, included in wa1-task3.cu, in Cuda c++. The code includes the requested GPU parallel in the gpu_run(float* inp, float* out, int N) function, that takes two allocated arrays of memory, designed for the input and output. It's sequential equivalent seq_run(float* inp, float* out, int N) has the same signature.

When running, the functions output their runtime in microseconds. Compiling the program with nvcc -O3 -DN_ELEMS=753411 wal-task3.cu i get the following output:

```
[wbr220@a00333 t3]$ ./a.out
CPU Run took 53609 microseconds (53.61ms)
GPU Run took 33 microseconds (0.03ms)
Passed: 753411, Invalid: 000000
```

Which clearly demonstrates the effectiveness of parallel programming. The GPU Runs 99.9% faster than the CPU, outside of the time it takes to move the data to and from the device. This speedup is mostly explained by the GPU computing the results in blocks of 256 at a time.

We are interested in locating the spot where the GPU computes faster than the CPU. To help us, the compiler takes a directive: $N_{\rm ELEMS}$, which defines amount of elements. To find the point i continually recompile the program while changing this amount, and log the time values

```
[wbr220@a00333 t3]$ ./test.sh

Compiling test 1

TEST 1

CPU Run took 7 microseconds (0.01ms)

GPU Run took 29 microseconds (0.03ms)

Passed: 000001, Invalid: 000000

Compiling test 10
```

```
TEST 10
CPU Run took 8 microseconds (0.01ms)
GPU Run took 31 microseconds (0.03ms)
Passed: 000010, Invalid: 000000
Compiling test 100
TEST 100
CPU Run took 16 microseconds (0.02ms)
GPU Run took 30 microseconds (0.03ms)
Passed: 000100, Invalid: 000000
Compiling test 250
TEST 250
CPU Run took 26 microseconds (0.03ms)
GPU Run took 28 microseconds (0.03ms)
Passed: 000250, Invalid: 000000
Compiling test 500
TEST 500
CPU Run took 49 microseconds (0.05ms)
GPU Run took 30 microseconds (0.03ms)
Passed: 000500, Invalid: 000000
Compiling test 1000
TEST 1000
CPU Run took 93 microseconds (0.09ms)
GPU Run took 30 microseconds (0.03ms)
Passed: 001000, Invalid: 000000
```

We now clearly see that for an array of a size around 250 the CPU starts being slower than the GPU, and by n=1000 the GPU is more than 3 times as fast as the CPU

4 Task 4

We need to flatten the following function:

I wrote the following futhark function:

```
let spMatVctMult [num_elms] [vct_len] [num_rows]
 (mat_val : [num_elms](i32,f32))
 (mat_shp : [num_rows]i32)
 (vct : [vct_len]f32) : [num_rows]f32 =
  -- Calculates the index of the start of each sub-array(1-indexed)
  let shp_sc = scan (+) 0 mat_shp
  -- Shift the shape array right
  let shp\_rot = map (\i -> if i == 0 then 0 else <math>shp\_sc[i-1]) (iota num\_rows)
  -- Distribute the flags to their calculated places
  let row_flg = scatter (replicate num_elms 0) shp_rot (replicate num_rows 1)
  -- Perform the actual matrix-vector multiplication
  let muls = map ((i, x) \rightarrow x*vct[i]) mat_val
  -- Sum up each row using the flags calculated above
  let row_sums = sgmSumF32 row_flg muls
  -- Extract the last element of each row
  in map (\i -> row_sums[i-1]) shp_sc
   I test with the following information:
$ futhark dataset --i32-bounds=0:9999 -g [1000000]i32 --f32-bounds=-7.0:7.0 -g [1000000]
And the test cases:
-- compiled input @ data.in auto output
in both spMVmult-flat and spMVmult-seq, and let the futhark bench run
20 rounds each and i get the following output:
[wbr220@a00333 w1-code-handin] futhark bench --backend=opencl --runs=20 spMVmult-seq.:
t.fut < data.in</pre>
Compiling spMVmult-seq.fut...
Compiling spMVmult-flat.fut...
Reporting average runtime of 20 runs for each dataset.
Results for spMVmult-flat.fut:
#0 ("[0i32, 1i32, 0i32, 1i32, 2i32, 1i32, 2i32, 3i32, 2..."):
                                                                        93s (RSD: 0.076;
data.in:
                                                                        255s (RSD: 0.027;
Results for spMVmult-seq.fut:
#0 ("[0i32, 1i32, 0i32, 1i32, 2i32, 1i32, 2i32, 3i32, 2..."):
                                                                        430s (RSD: 0.037;
data.in:
                                                                   32370819s (RSD: 0.182;
```

And we see an average speedup of 99.999%.