fuel train

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Description

Six young health participants were asked to perform one set of 10 repetitions of the Unilateral Dumbbell Biceps Curl in five different fashions: exactly according to the specification (Class A), throwing the elbows to the front (Class B), lifting the dumbbell only halfway (Class C), lowering the dumbbell only halfway (Class D) and throwing the hips to the front (Class E). More information is available from the website here: http://groupware.les.inf.puc-rio.br/har (http://groupware.les.inf.puc-rio.br/har) (see the section on the Weight Lifting Exercise Dataset). The data for this project come from this source: http://groupware.les.inf.puc-rio.br/har).

The goal of this project is to create an algorithm to identify how well participants performed the dumbbbell bicep curls.

Load the data

Load the training and test data sets

```
filetrain<-"https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv"
filetest<-"https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv"
traindata <- read.csv(file=filetrain, header=TRUE, sep=",")
testdata <- read.csv(file=filetest, header=TRUE, sep=",")</pre>
```

clean the data

After viewing the data, it was evident that many fields contained blanks and NAs for the majority of the measurements (19,216 out of 19.622 observations). These fields were eliminated from the data we use since they can't be used in the prediction algorithm and to help speed up the calculations on the data set.

```
##convert blanks to NA
traindatana <- read.csv(file=filetrain, header=TRUE, sep=",",na.strings=c(""," ","NA"
))
na count <-sapply(traindatana, function(y) sum(length(which(is.na(y)))))</pre>
na count <- data.frame(na count)</pre>
##na count
##we see 19,216 NAs for many of the variables out of the 19,622 observations so we re
move these columns to reduce the number of variables for our model fitting. Statisti
cs not shown to conserve space in the report.
traindataclean<-traindatana[ , ! apply( traindatana , 2 , function(x) any(is.na(x)) )</pre>
]
##remove the first 7 columns which aren't part of the measurements taken by the monit
or
traindataclean<-traindataclean[,c(8:60)]
##we can see there are no more variables that are blank or NA
head(traindataclean)
```

```
##
     roll belt pitch belt yaw belt total accel belt gyros belt x gyros belt y
                                -94.4
## 1
           1.41
                                                       3
                                                                  0.00
                       8.07
                                                                                 0.00
## 2
           1.41
                       8.07
                                -94.4
                                                       3
                                                                   0.02
                                                                                 0.00
## 3
           1.42
                       8.07
                                -94.4
                                                       3
                                                                   0.00
                                                                                 0.00
## 4
           1.48
                       8.05
                                -94.4
                                                       3
                                                                   0.02
                                                                                 0.00
## 5
           1.48
                       8.07
                                -94.4
                                                       3
                                                                   0.02
                                                                                 0.02
## 6
                                                       3
           1.45
                       8.06
                                -94.4
                                                                   0.02
                                                                                 0.00
##
     gyros_belt_z accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## 1
             -0.02
                              -21
                                               4
                                                            22
                                                                           -3
## 2
             -0.02
                              -22
                                              4
                                                            22
                                                                            -7
## 3
                              -20
                                              5
                                                            23
             -0.02
                                                                           -2
## 4
             -0.03
                              -22
                                              3
                                                            21
                                                                           -6
                              -21
                                              2
                                                            24
## 5
             -0.02
                                                                           -6
## 6
             -0.02
                              -21
                                                            21
##
     magnet_belt_y magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm
                599
## 1
                               -313
                                         -128
                                                    22.5
                                                             -161
                                                                                 34
## 2
                608
                                         -128
                               -311
                                                    22.5
                                                             -161
                                                                                 34
## 3
                600
                               -305
                                         -128
                                                    22.5
                                                             -161
                                                                                 34
## 4
                604
                               -310
                                         -128
                                                    22.1
                                                                                 34
                                                             -161
## 5
                600
                               -302
                                         -128
                                                    22.1
                                                             -161
                                                                                 34
## 6
                603
                               -312
                                         -128
                                                    22.0
                                                             -161
     gyros_arm_x gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z
##
                                                                                -123
## 1
             0.00
                          0.00
                                       -0.02
                                                     -288
                                                                    109
## 2
             0.02
                         -0.02
                                       -0.02
                                                     -290
                                                                    110
                                                                                -125
## 3
             0.02
                         -0.02
                                       -0.02
                                                     -289
                                                                    110
                                                                                -126
## 4
             0.02
                         -0.03
                                        0.02
                                                     -289
                                                                    111
                                                                                -123
## 5
             0.00
                         -0.03
                                        0.00
                                                     -289
                                                                    111
                                                                                -123
                                                                                -122
## 6
                                                                    111
             0.02
                         -0.03
                                        0.00
                                                     -289
##
     magnet arm x magnet arm y magnet arm z roll dumbbell pitch dumbbell
```

## 1	-368	337	516 13	.05217	-70.49400
## 2		337		.13074	-70.63751
## 3	-368	344		.85075	-70.27812
## 4	- 372	344		.43120	-70.39379
## 5	-374	337		.37872	-70.42856
## 6		342		.38246	-70.81759
##	yaw_dumbbell total_accel_dumbbell gyros_dumbbell_x gyros_dumbbell_y				
## 1	_		57 <u> </u>	0	-0.02
## 2	-84.71065	3	37	0	-0.02
## 3	-85.14078	-85.14078		0	-0.02
## 4	-84.87363 37		37	0 -0.02	
## 5	-84.85306	-84.85306 37		0 -0.02	
## 6	-84.46500	3	37	0	-0.02
##	<pre>gyros_dumbbell_z accel_dumbbell_x accel_dumbbell_z</pre>				
## 1	0.00 -234		4	47 –271	
## 2	0.00	–2 3	-233 47		-269
## 3	0.00 -232		2	46 –27	
## 4	-0.02	2 –23	2	48	
## 5	0.00 -233		3	48 –270	
## 6	0.00	– 23	34	48	-269
##	<pre>magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm</pre>				
## 1	- 55		293	- 65	28.4
## 2			296	-64	28.3
## 3	-56		298 –63		28.3
## 4			303	-60	28.1
## 5	- 55		292 –68		28.0
## 6			294	- 66	27.9
##	- - -	aw_forearm total_ -153	_accel_forearm 36	<u>-</u>	rm_x 0.03
## 1 ## 2		-153 -153	36		0.03
## 3		-153 -152	36		0.03
## 4		-152 -152	36		0.02
## 5		-152 -152		36 0.02	
## 6		-152	36		0.02
##		gyros forearm z			
## 1		-0.02	 19	_	203
## 2		-0.02	19		203
## 3	-0.02	0.00	19	6	204
## 4	-0.02	0.00	18	9	206
## 5	0.00	-0.02	18	9	206
## 6	-0.02	-0.03	19	3	203
##	accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z				
## 1	-215	-17	,	654	476
## 2	-216	-18	:	661	473
## 3	-213	-18	•	658	469
## 4	-214	-16		658	469
## 5	-214	-17	,	655	473
## 6	-215	- 9		660	478
##	classe				
## 1					

```
## 2 A
## 3 A
## 4 A
## 5 A
## 6 A
```

Split the training data into a training set and a test set

We split the training data into a training subset and a test subset so that we can do a cross-validation of the model prior to applying it to the 20 samples in the test data

```
library(caret)

## Loading required package: lattice
## Loading required package: ggplot2

trainIndex <- createDataPartition(traindataclean$classe, p=0.7, list=FALSE)
data_train_train_subset <- traindataclean[ trainIndex, ]
data_train_test_subset <- traindataclean[-trainIndex,]</pre>
```

Create various models for prediction

Try rpart model for prediction

```
install.packages("rattle")

## package 'rattle' successfully unpacked and MD5 sums checked

##

## The downloaded binary packages are in

## C:\Users\cpeck\AppData\Local\Temp\RtmpYnjBKK\downloaded_packages
```

```
library(rattle)
```

```
## Rattle: A free graphical interface for data mining with R.
## Version 3.4.1 Copyright (c) 2006-2014 Togaware Pty Ltd.
## Type 'rattle()' to shake, rattle, and roll your data.
```

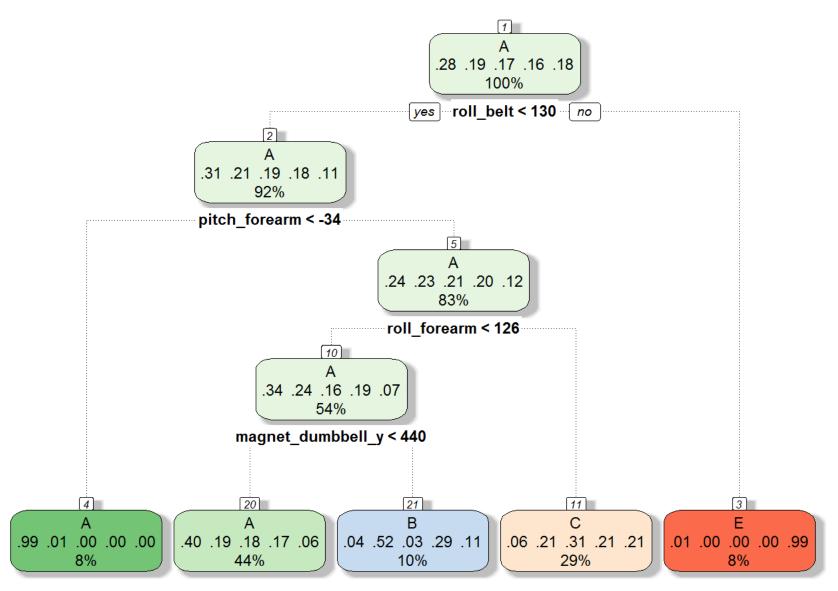
```
modelfittree<-train(classe~.,method="rpart", data=data_train_train_subset, control =
rpart.control(maxdepth = 5))</pre>
```

Loading required package: rpart

print(modelfittree\$finalModel)

```
## n= 13737
##
## node), split, n, loss, yval, (yprob)
         * denotes terminal node
##
##
    1) root 13737 9831 A (0.28 0.19 0.17 0.16 0.18)
##
      2) roll belt< 130.5 12570 8672 A (0.31 0.21 0.19 0.18 0.11)
##
        4) pitch forearm< -33.95 1123
                                          7 A (0.99 0.0062 0 0 0) *
##
        5) pitch forearm>=-33.95 11447 8665 A (0.24 0.23 0.21 0.2 0.12)
##
         10) roll_forearm< 126.5 7410 4882 A (0.34 0.24 0.16 0.19 0.067)
##
           20) magnet_dumbbell_y< 439.5 6103 3633 A (0.4 0.19 0.18 0.17 0.058) *
##
           21) magnet dumbbell y>=439.5 1307 630 B (0.044 0.52 0.033 0.29 0.11) *
##
         11) roll_forearm>=126.5 4037 2801 C (0.063 0.21 0.31 0.21 0.21) *
##
      3) roll belt>=130.5 1167
                                  8 E (0.0069 0 0 0 0.99) *
##
```

fancyRpartPlot(modelfittree\$finalModel)



Rattle 2016-Dec-31 15:23:06 cpeck

Try predicting with the rpart model. We can see it doesn't work very well based on the table, which contains many misclassifications in the predtree variable compared to the actual classe.

```
predtree<-predict(modelfittree,data_train_test_subset)
table(predtree,data_train_test_subset$classe)</pre>
```

```
##
## predtree
                 Α
                       В
                             C
                                   D
                                         Ε
           A 1507
                     490
                           498
##
                                431
                                      174
##
           В
                22
                     282
                            10
                                161
                                       62
              139
##
           C
                     367
                           518
                                372
                                      374
##
                 0
                       0
                             0
                                   0
                                         0
           D
                                      472
##
           Ε
```

Try random forest model. We can see that this works well based on the confusion matrix, which has very low class errors. The variable importance plot shows that the yaw belt, roll belt, magnet dumbbell z and pitch belt are the most important variables in predicting the classe.

```
library(randomForest)
```

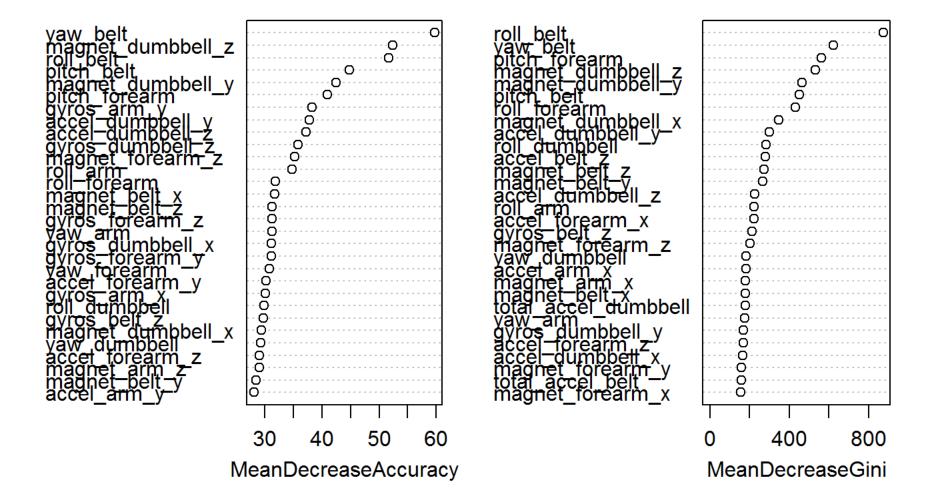
```
## randomForest 4.6-10
## Type rfNews() to see new features/changes/bug fixes.
```

```
modelfitrf <- randomForest(classe ~ ., data=data_train_train_subset, importance=TRUE)
modelfitrf</pre>
```

```
##
## Call:
    randomForest(formula = classe ~ ., data = data train train subset,
                                                                                 importanc
e = TRUE)
##
                   Type of random forest: classification
                         Number of trees: 500
##
## No. of variables tried at each split: 7
##
           OOB estimate of error rate: 0.5%
##
## Confusion matrix:
##
             В
                             E class.error
## A 3901
                   1
                        0
                             0 0.001280082
             4
## B
       13 2639
                   6
                        0
                             0 0.007148232
            10 2383
                        3
## C
        0
                             0 0.005425710
## D
        0
             0
                  22 2228
                             2 0.010657194
## E
             0
                   2
                        5 2518 0.002772277
```

```
varImpPlot(modelfitrf)
```

modelfitrf



Try predicting with the random forest on the training test data. We can see it works well as there are very few predictions that don't match the actual classe.

```
predrf<-predict(modelfitrf,data_train_test_subset)
predtab<-table(predrf,data_train_test_subset$classe)
confusionMatrix(predtab)</pre>
```

```
## Confusion Matrix and Statistics
##
##
## predrf
                         C
                                    \mathbf{E}
              Α
                    R
                              D
##
        A 1672
##
        В
              0 1134
        C
              2
##
                    2 1024
##
        D
              0
                    0
                         1
                            949
                                    0
##
                    0
                         0
        \mathbf{E}
              0
                               1 1080
##
## Overall Statistics
##
##
                    Accuracy: 0.9956
##
                      95% CI: (0.9935, 0.9971)
##
       No Information Rate: 0.2845
##
       P-Value [Acc > NIR] : < 2.2e-16
##
##
                       Kappa : 0.9944
##
    Mcnemar's Test P-Value: NA
##
## Statistics by Class:
##
##
                          Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                            0.9988
                                      0.9956
                                                0.9981
                                                          0.9844
                                                                    0.9982
## Specificity
                            0.9993
                                      0.9998
                                                0.9959
                                                          0.9998
                                                                    0.9998
## Pos Pred Value
                            0.9982
                                      0.9991
                                                0.9808
                                                          0.9989
                                                                    0.9991
## Neg Pred Value
                                                0.9996
                            0.9995
                                      0.9989
                                                          0.9970
                                                                    0.9996
## Prevalence
                            0.2845
                                      0.1935
                                                0.1743
                                                          0.1638
                                                                    0.1839
## Detection Rate
                            0.2841
                                      0.1927
                                                0.1740
                                                          0.1613
                                                                    0.1835
## Detection Prevalence
                            0.2846
                                      0.1929
                                                0.1774
                                                          0.1614
                                                                    0.1837
                            0.9990
                                      0.9977
                                                0.9970
                                                          0.9921
                                                                    0.9990
## Balanced Accuracy
```

Expected out of sample error

From the confusion matrix above, we can see that the out of sample error is very low based on the accuracy of 99.5%. Out of sample error is calculated as 1 - accuracy.

Predict on the test data

We apply the random forest model to predict the classe of the 20 test observations

```
predrftest<-predict(modelfitrf,testdata)
predrftest</pre>
```

```
## 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20
## B A B A A E D B A A B C B A E E A B B B
## Levels: A B C D E
```

table(predrftest)

```
## predrftest
## A B C D E
## 7 8 1 1 3
```