



# Stochastic inference

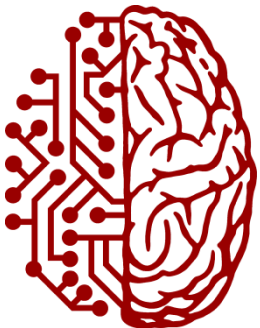
with deterministic

spiking neurons

Mihai A. Petrovici

Luziwei Leng, David Stöckel, Oliver Breitwieser, Ilja Bytschok, Jakob Jordan

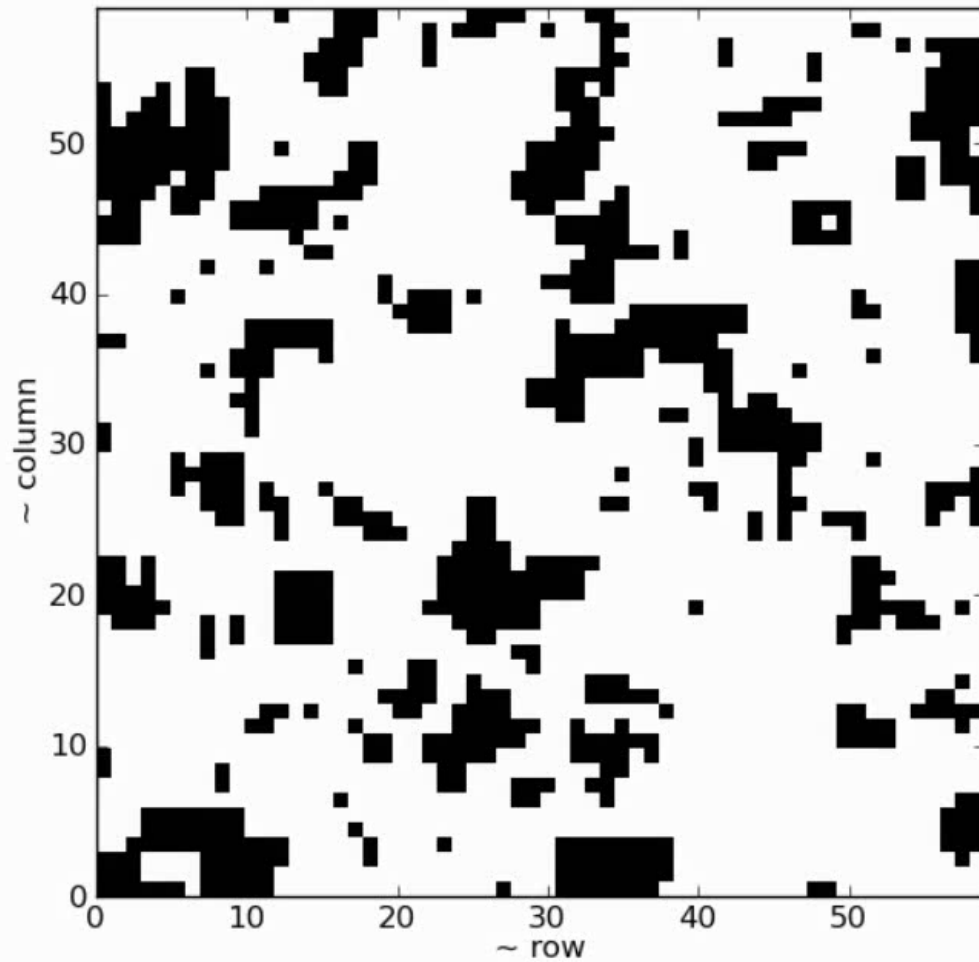
Roman Martel, Johannes Bill, Johannes Schemmel, Karlheinz Meier



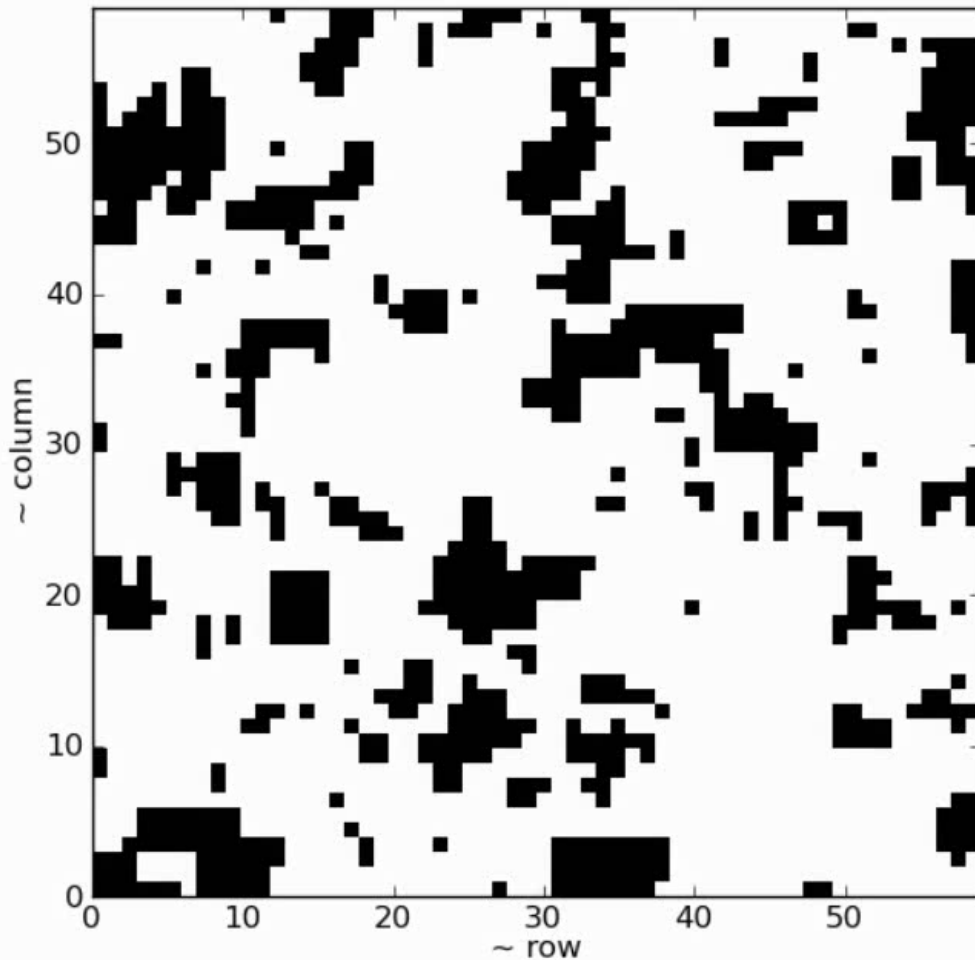
Electronic Vision(s)  
Kirchhoff Institute for Physics  
University of Heidelberg



## Ensemble dynamics



## Ensemble dynamics



Ising model

$$H(\sigma) = - \sum_{ij} J_{ij} \sigma_i \sigma_j - \sum_i b_i \sigma_i$$

$$p_{\beta}(\sigma) = \frac{e^{-H(\sigma)/k_B T}}{Z_{\beta}}$$

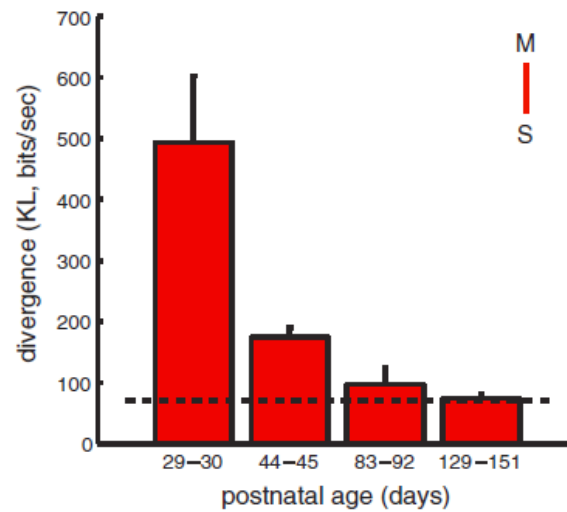
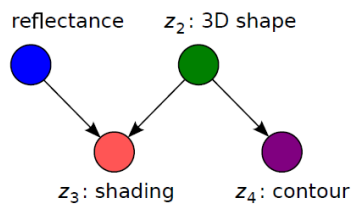
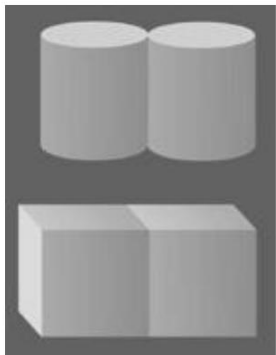
Glauber dynamics

→ sampling !

# Bayesian inference & learning

decision problem  $\leftrightarrow$  inference problem

$p(\text{reality} \mid \text{observations})$



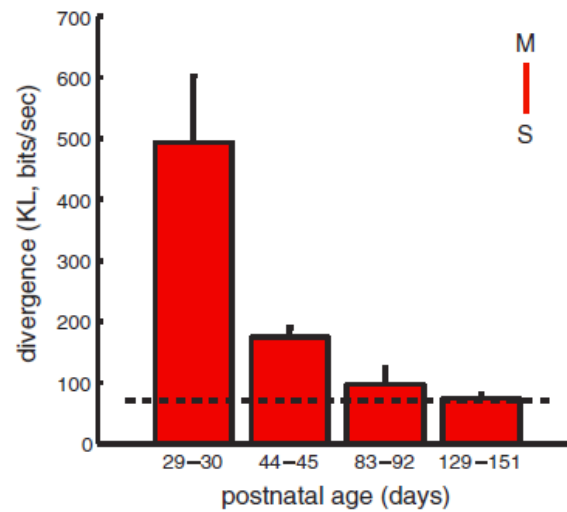
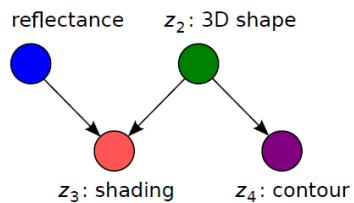
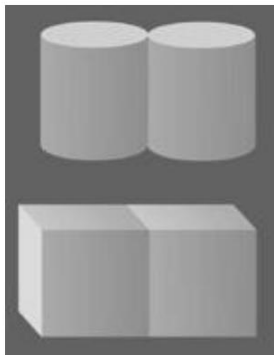
Berkes et al. (2011)

Knill & Kersten (1991)

# Bayesian inference & learning

decision problem  $\leftrightarrow$  inference problem

$p(\text{reality} \mid \text{observations})$



Berkes et al. (2011)



Matthew et al. (ca. 85)

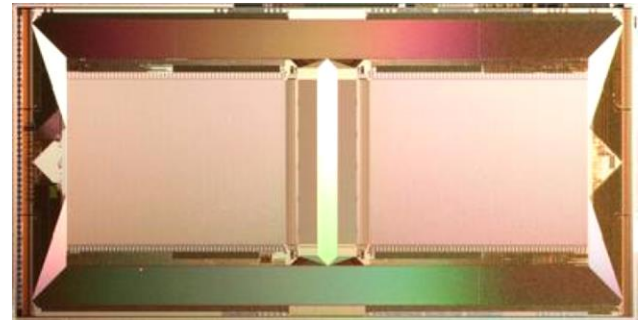
Knill & Kersten (1991)

## Why spikes ?

understand biology



exploit efficient hardware

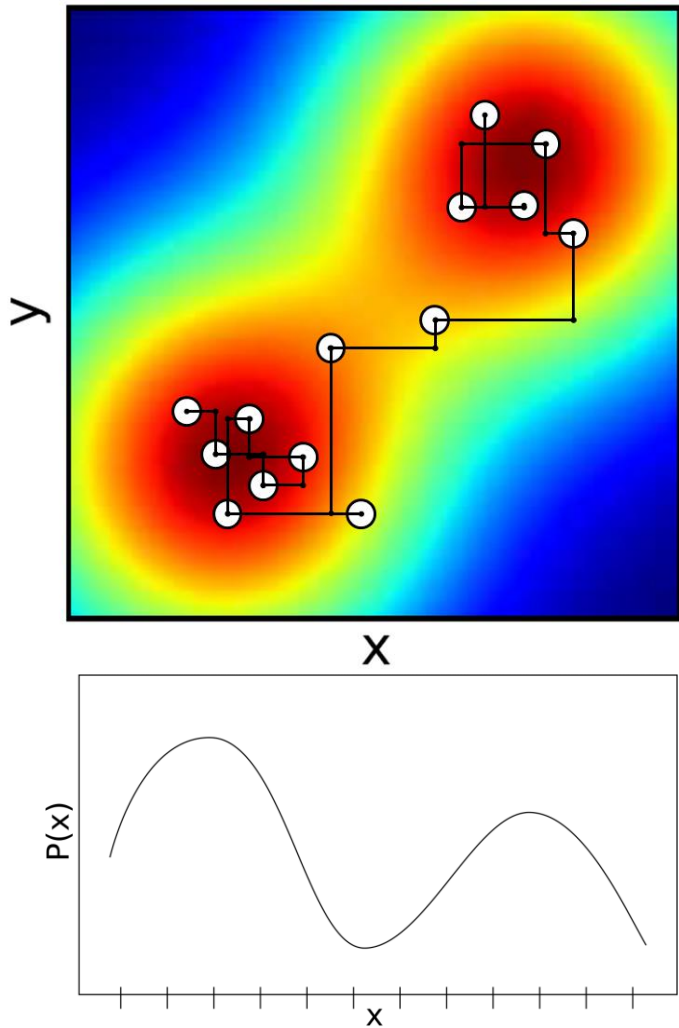


low power, high speed, ...

... and maybe also gain a **computational advantage**

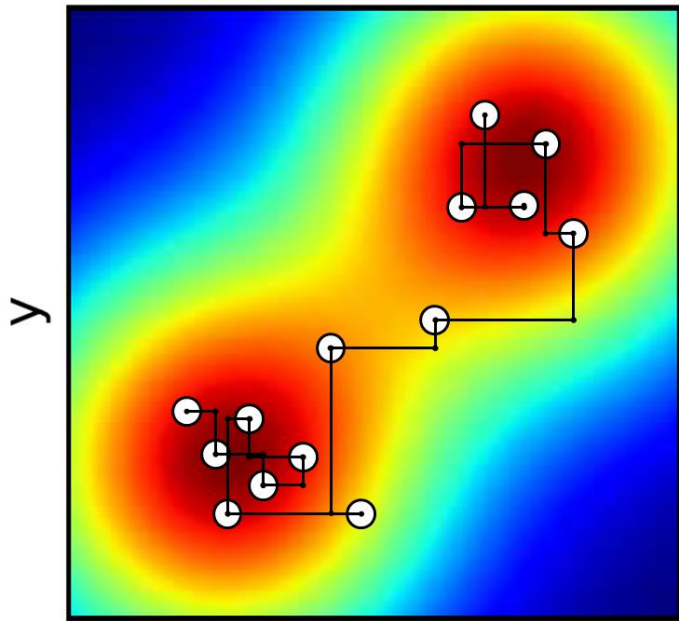
# Neural sampling

(Gibbs) sampling

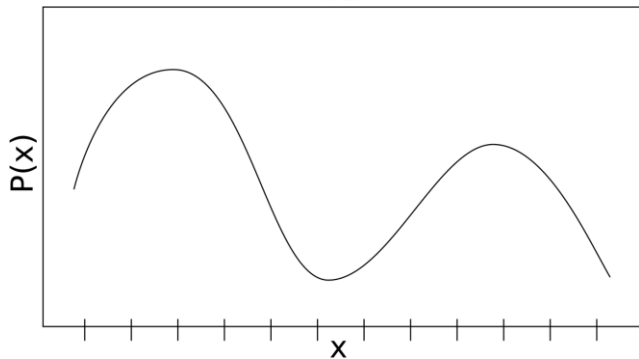


# Neural sampling

(Gibbs) sampling

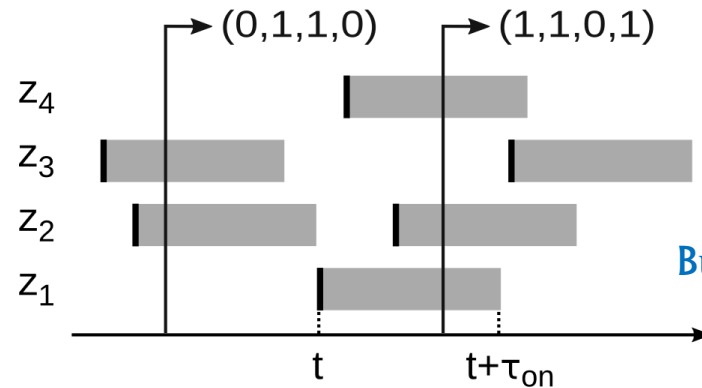


x



assumptions:  $z_k \in \{0,1\}$

$z_k = 1 \Leftrightarrow$  neuron has spiked in  $[t - \tau, t)$



Büsing et al. (2011)

information transfer between neurons:

$$u_k = \log \frac{p(z_k = 1 | \mathbf{z}_{\setminus k})}{p(z_k = 0 | \mathbf{z}_{\setminus k})}$$

$$\Leftrightarrow v_k = p(z_k = 1) = \frac{1}{1 + \exp(-u_k)}$$

response/activation function



# The LIF activation function

noise source: Poisson spike trains  $\Rightarrow$  membrane as Ornstein-Uhlenbeck process

$$du(t) = -\Theta \cdot [\mu - u(t)]dt + \sigma dW(t)$$

Brunel & Sergi (1998)

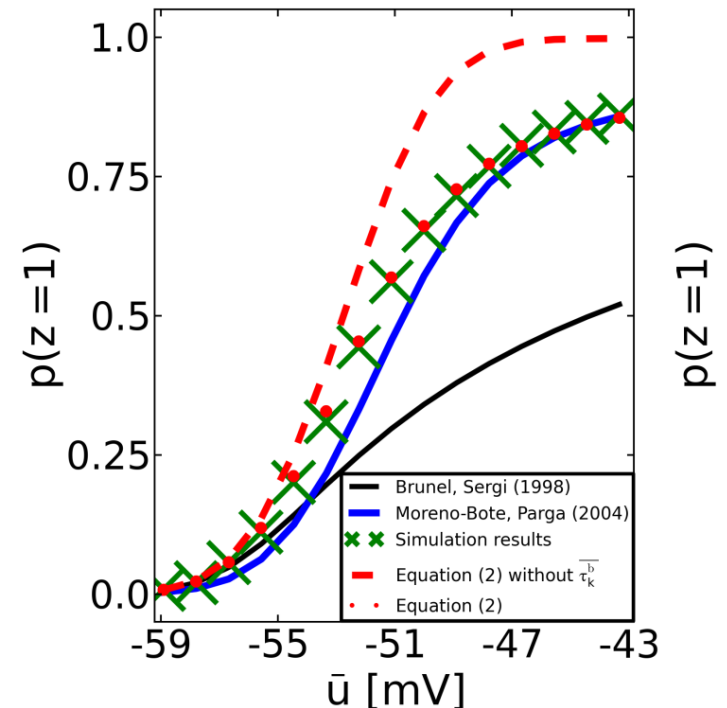
assumption:  $\tau_{\text{syn}} \ll \tau_m$

$$\langle T \rangle = \tau \sqrt{\pi} \int_{\rho - \mu/\sigma}^{\vartheta_{\text{eff}} - \mu/\sigma} [1 + \operatorname{erf} x] \exp(x^2) dx$$

Moreno-Bote & Parga (2004)

assumption:  $\tau_{\text{ref}} \approx \tau_{\text{syn}} \gg \tau_m$

$$v = \int_{\vartheta}^{\infty} \left( \tau_m \frac{\varrho - \tilde{u}}{\vartheta - \tilde{u}} \right)^{-1} p(\tilde{u}) d\tilde{u}$$



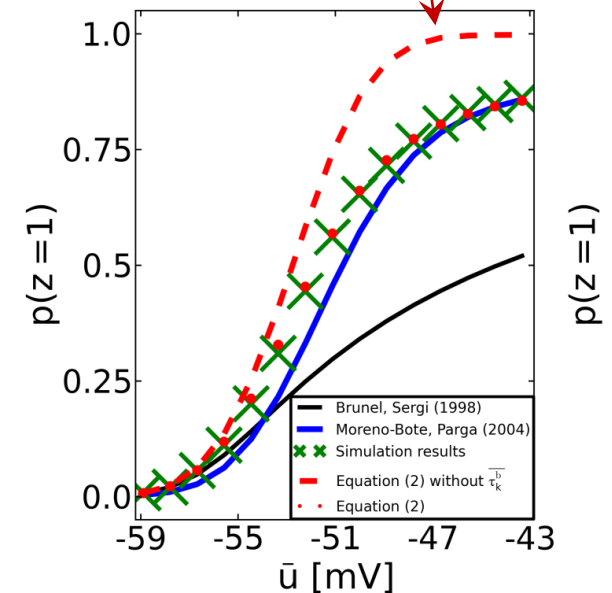
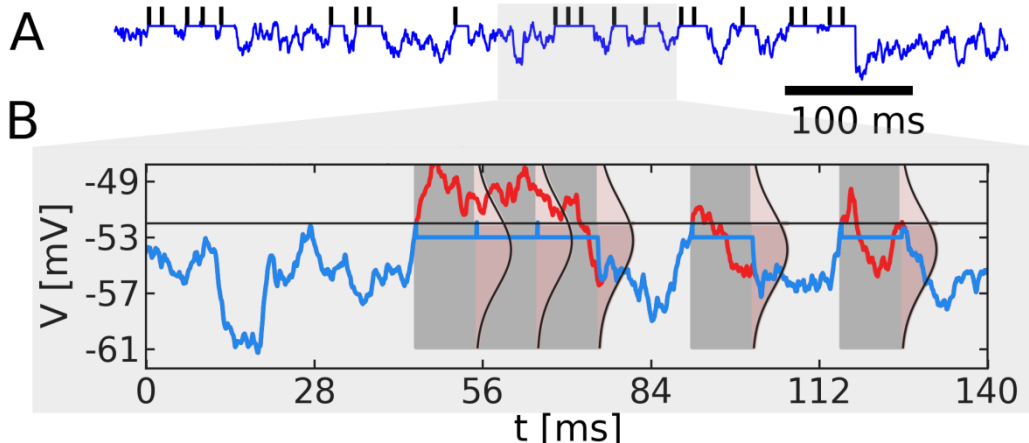
# The membrane autocorrelation propagation

$$p(z_k = 1) = \frac{t_{k, \text{refractory}}}{t_{\text{total}}} = \frac{\sum_n P_n n \tau_{\text{ref}}}{\sum_n P_n \cdot \left( n \tau_{\text{ref}} + \sum_{k=1}^{n-1} \overline{\tau_k^b} + T_n \right)}$$

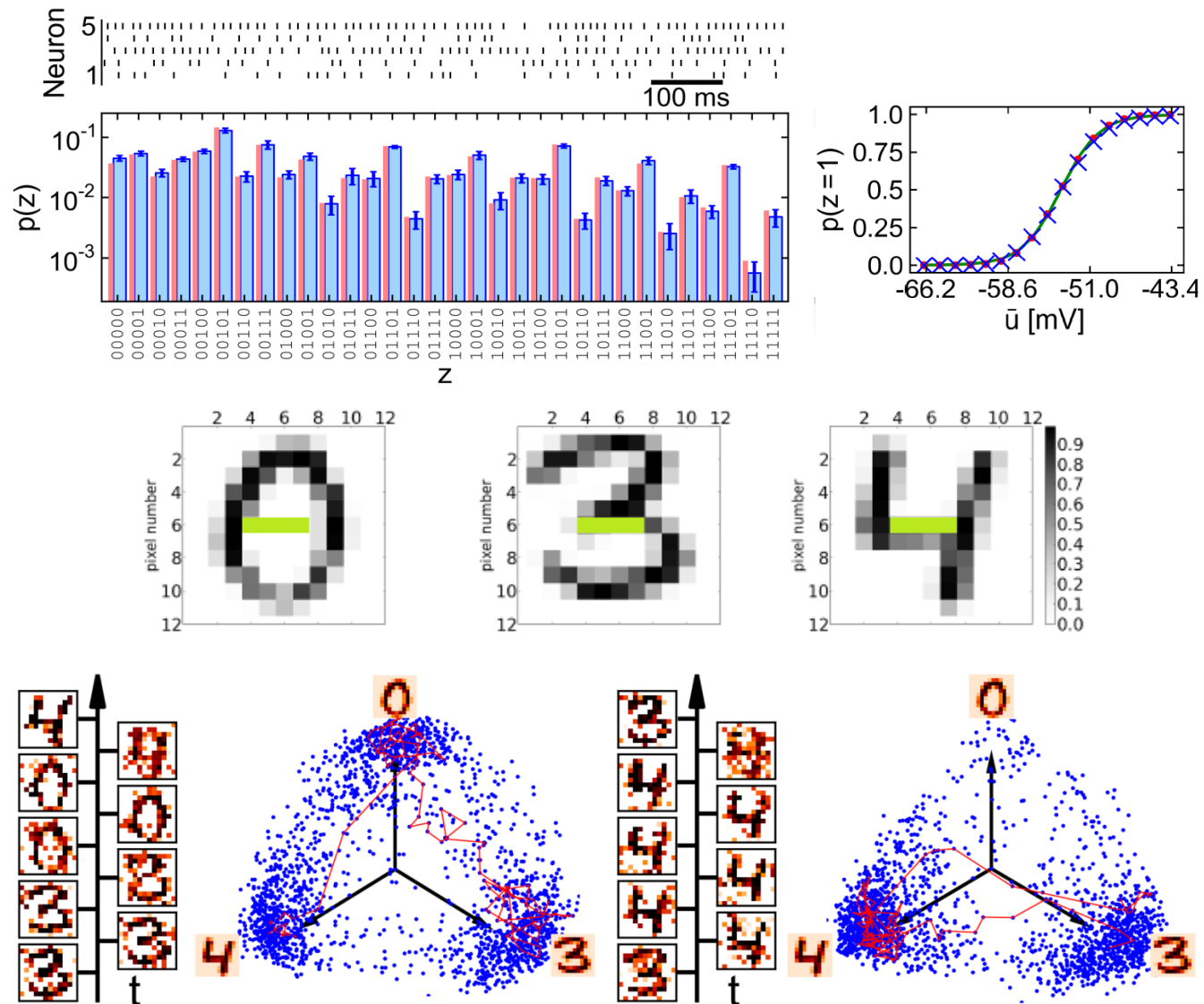
$$P_n = \left( 1 - \sum_{i=1}^{n-1} P_i \right) \cdot \int_{V_{\text{thr}}}^{\infty} dV_{n-1} p(V_{n-1} | V_{n-1} > V_{\text{thr}}) \left[ \int_{-\infty}^{V_{\text{thr}}} dV_n p(V_n | V_{n-1}) \right]$$

$$T_n = \int_{V_{\text{thr}}}^{\infty} dV_{n-1} p(V_{n-1} | V_{n-1} > V_{\text{thr}}) \left[ \int_{-\infty}^{V_{\text{thr}}} dV_n p(V_n | V_{n-1}) \langle FPT(V_{\text{thr}}, V_n) \rangle \right]$$

$$\overline{\tau_k^b} = \int_{\vartheta}^{\infty} du_k \tau_{\text{eff}} \ln \left( \frac{\varrho - u_k}{\vartheta - u_k} \right) p(u_k | u_k > \vartheta, u_{k-1})$$



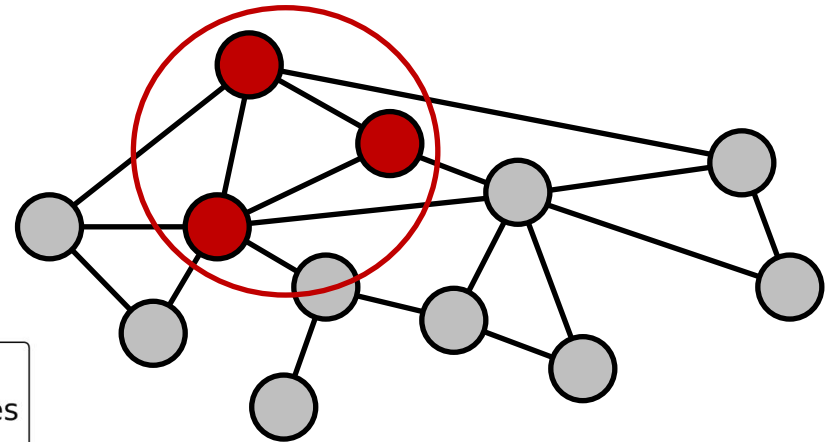
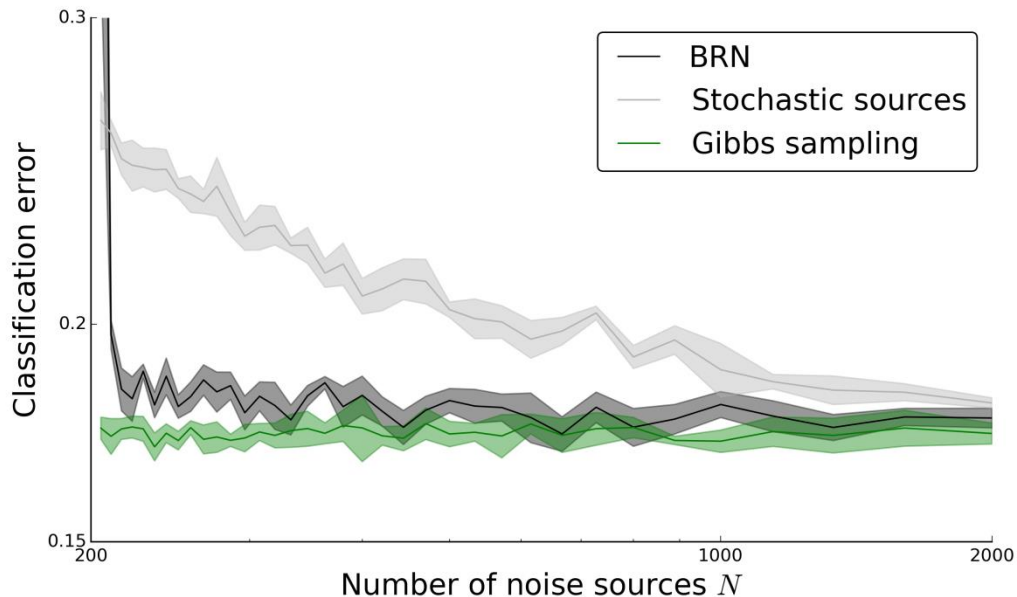
# (Fully visible) LIF-based Boltzmann machines



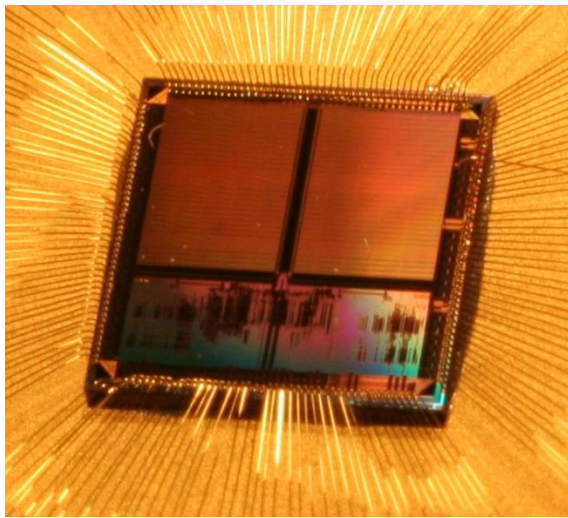
## ... so where does the noise come from ?

- in simulations: from independent Poisson sources
- more realistic: from being embedded in larger networks
- but: **noise correlations hurt !**

→ decorrelation by lateral inhibition



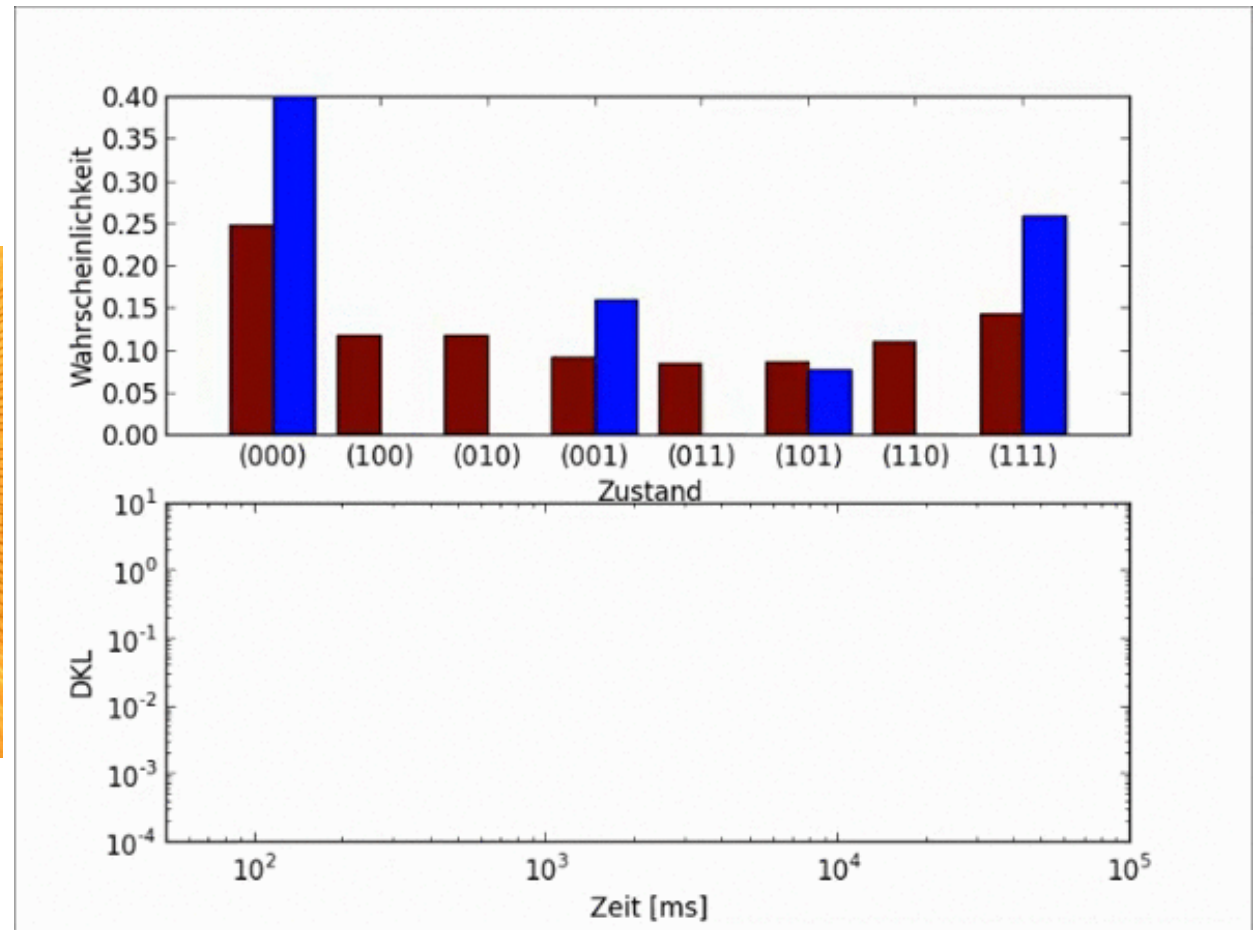
# LIF sampling on accelerated neuromorphic hardware



„Spikey“ chip

Schemmel et al. (2006)

Pfeil et al. (2013)



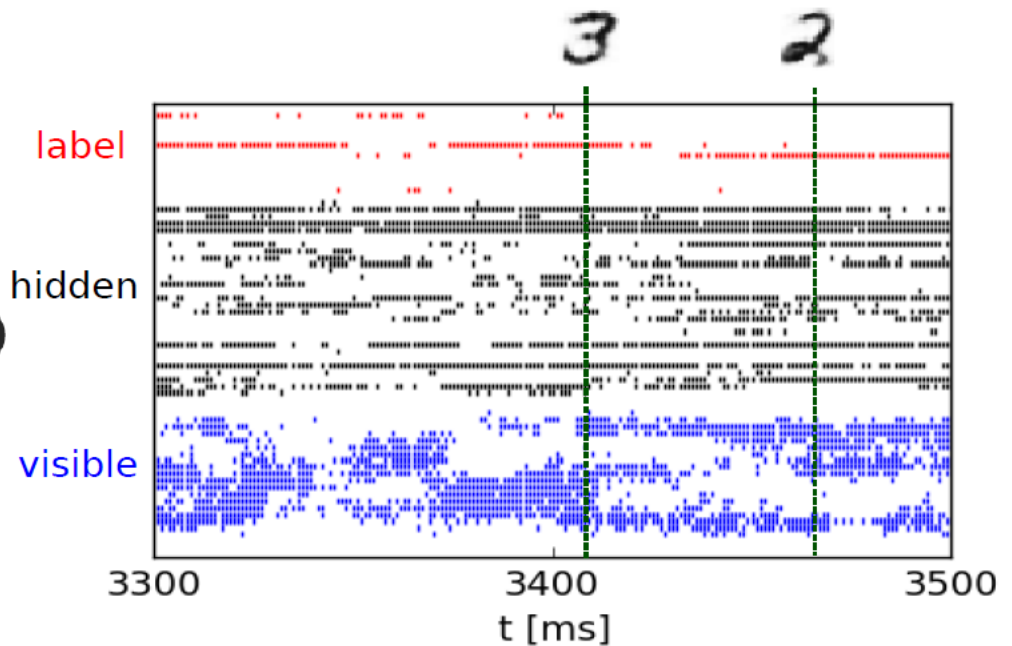
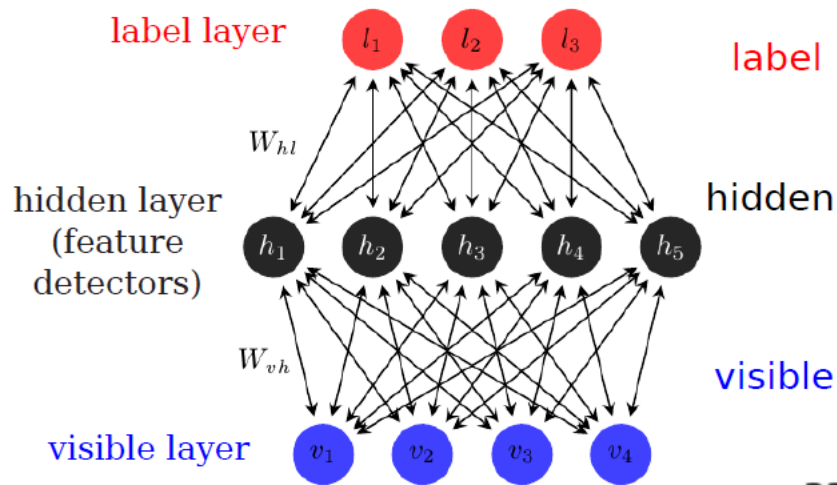
bio: 100 s

software simulation: 10 s

neuromorphic emulation: 10 ms

Petrovici & Stöckel et al. (2015)

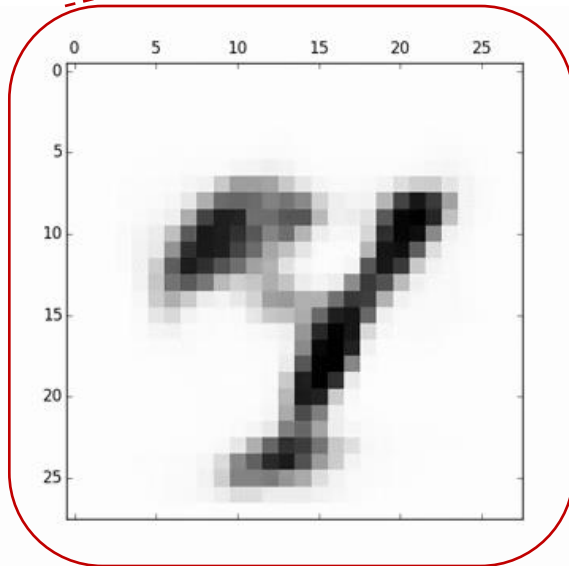
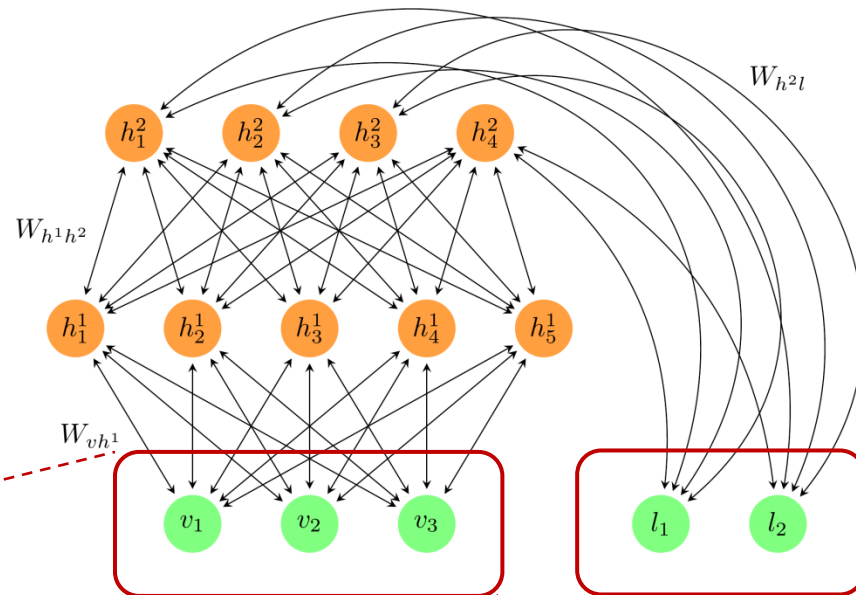
# Deep learning architectures



# Deep learning architectures

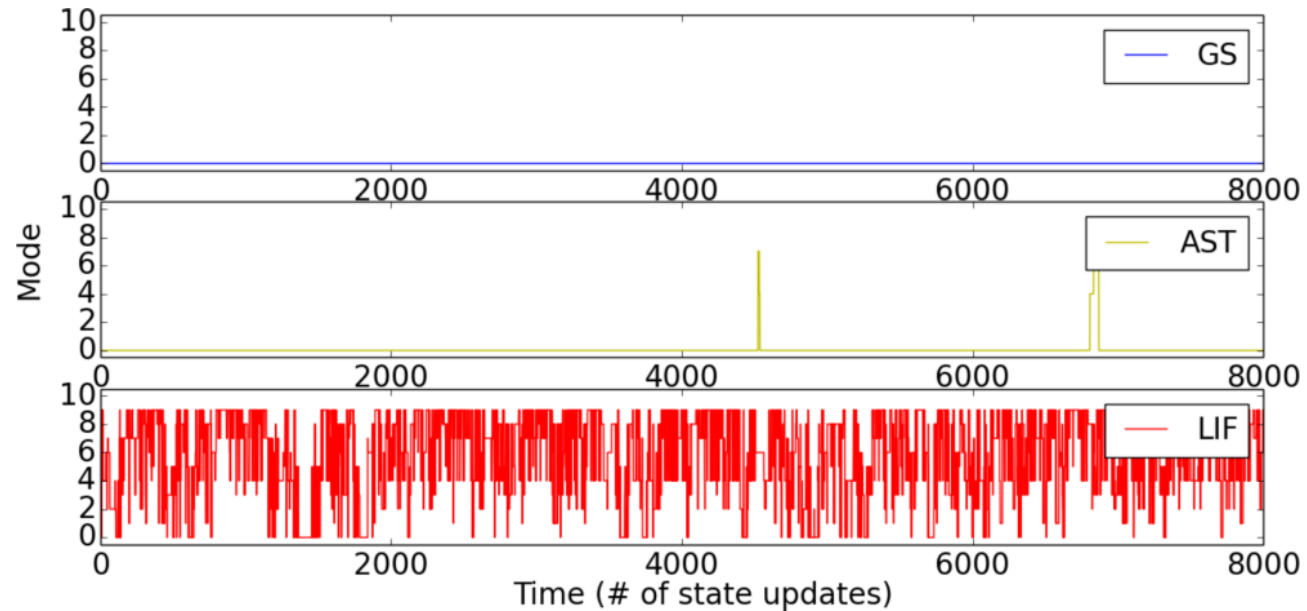
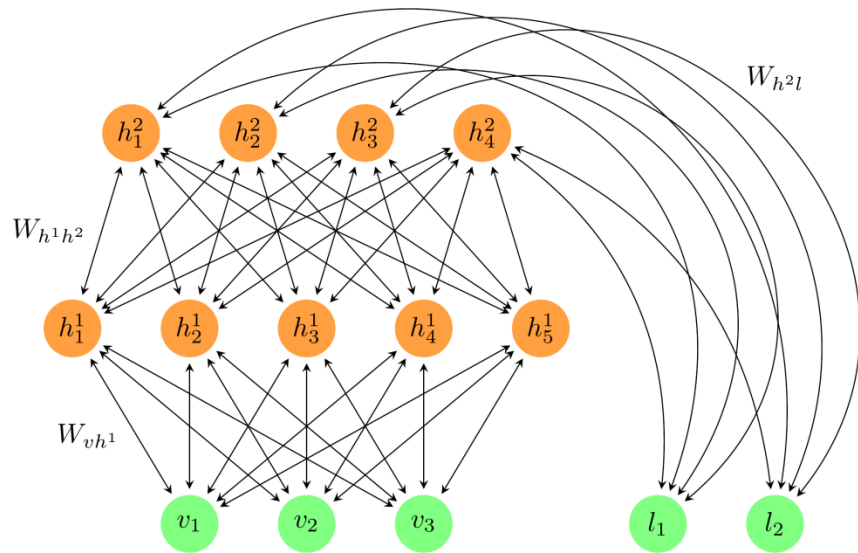
Training of RBMs/DBMs on MNIST:

- contrastive divergence
- coupled adaptive tempering



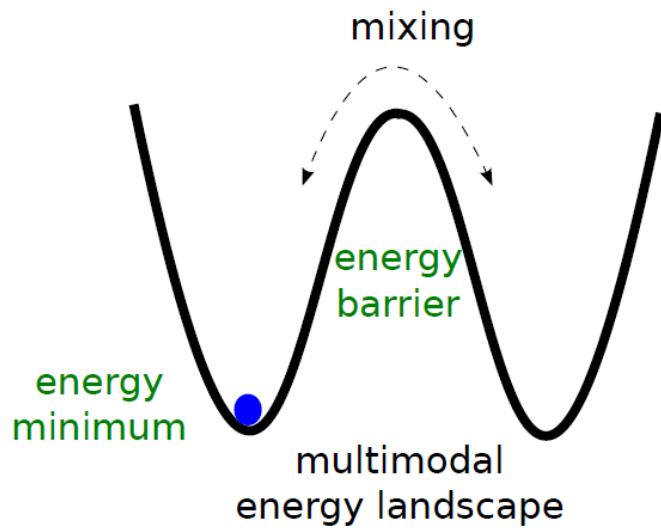
96.9 % correct classification

## Mixing in deep spiking networks

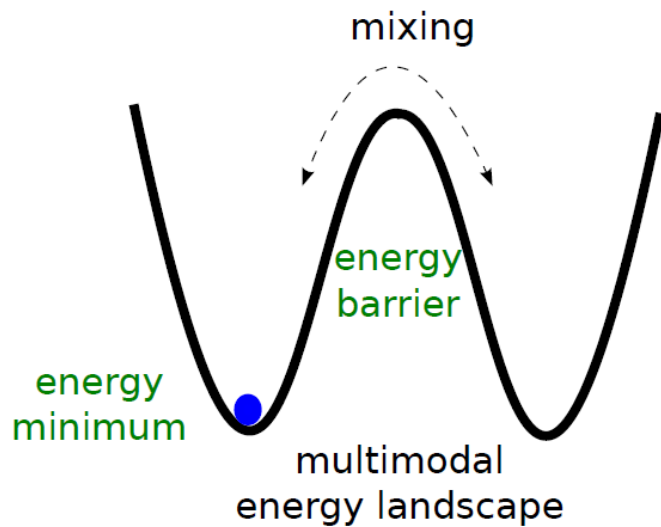




## Mixing in deep spiking networks



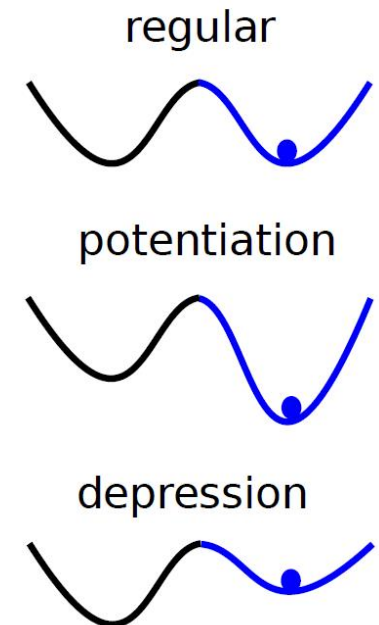
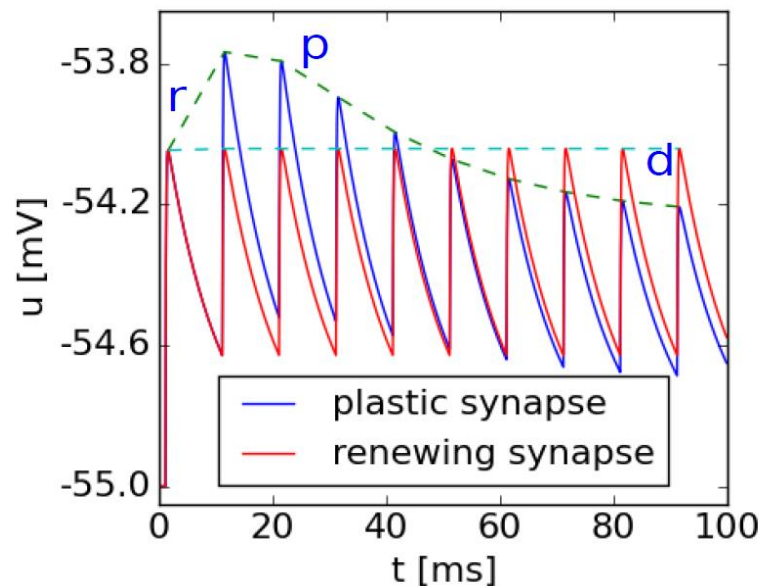
# Mixing in deep spiking networks



Tsodyks-Markram short-term plasticity

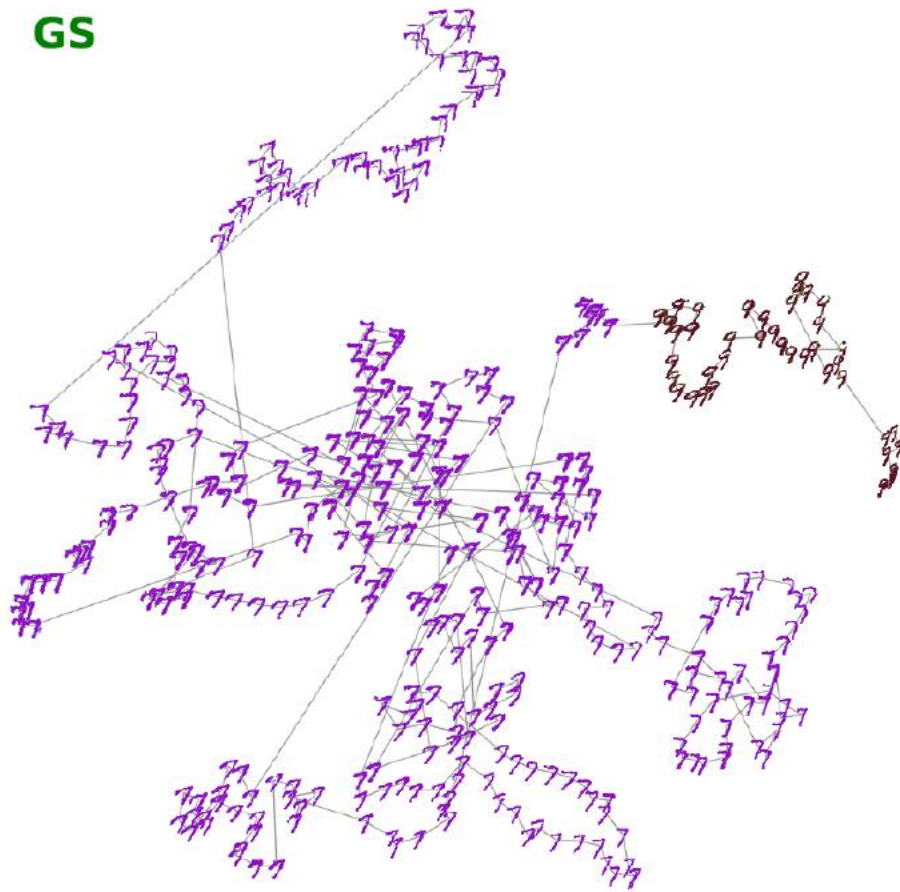
$$\frac{dR}{dt} = \frac{1 - R}{\tau_{rec}} - U_{SE}R\delta(t - t_{sp})$$

$$\frac{dU_{SE}}{dt} = -\frac{U_{SE}}{\tau_{facil}} + U_0(1 - U_{SE})\delta(t - t_{sp})$$

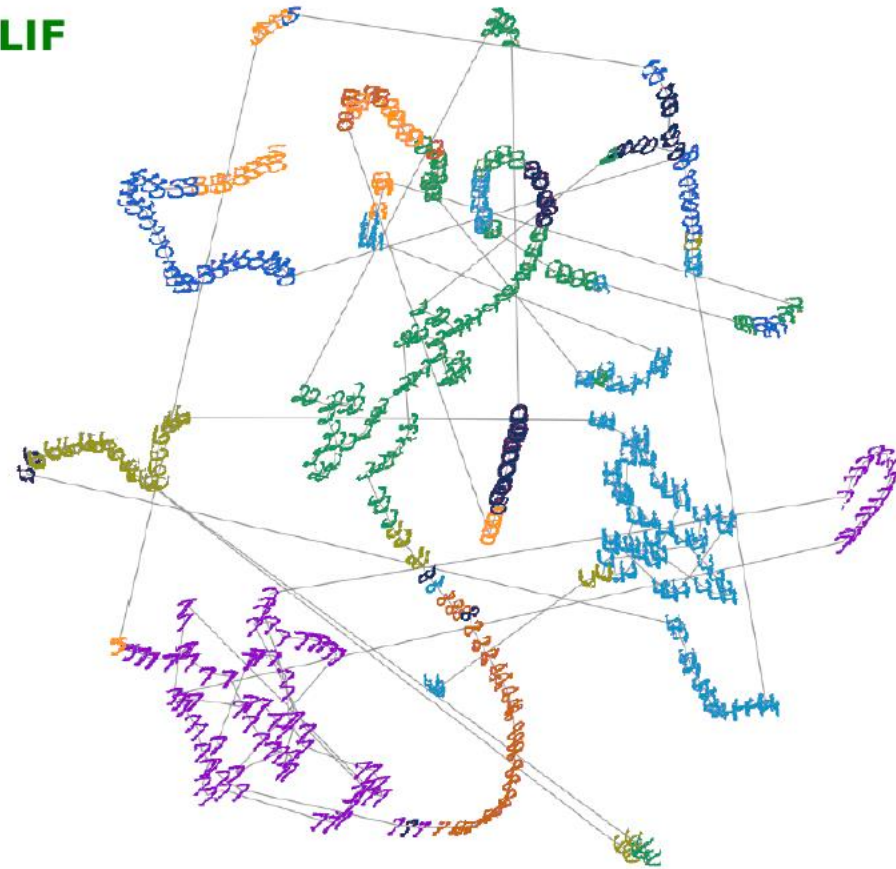


# Spiking networks as superior generative and discriminative models

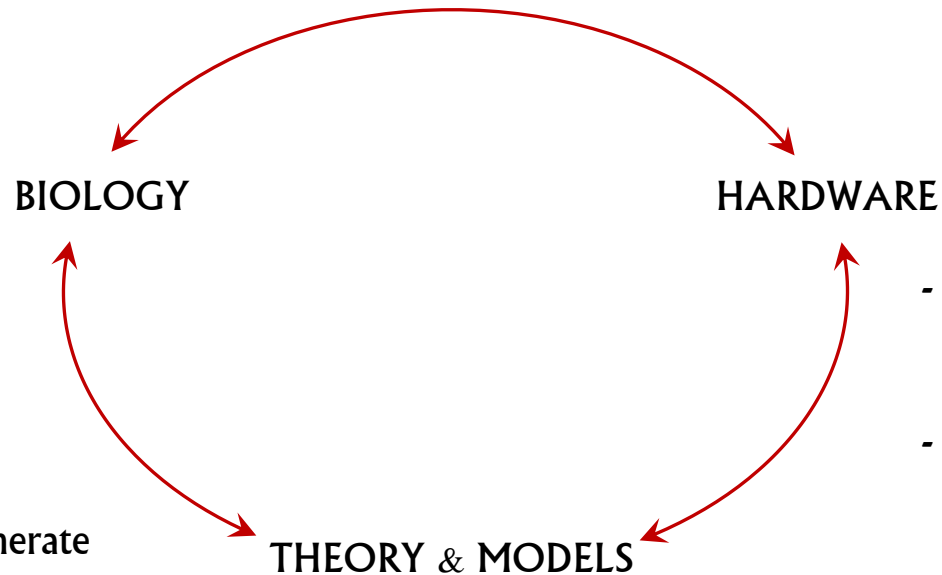
GS



LIF



## Summary



- functional role of HCS
- functional role of STP
- uncorrelated noise is surprisingly easy to generate

- design of a robust spike-based sampling model
- extremely fast convergence to target distribution

- model of LIF sampling
- analytical description of LIF activation function
- deep spiking networks as simultaneous discriminative and generative models