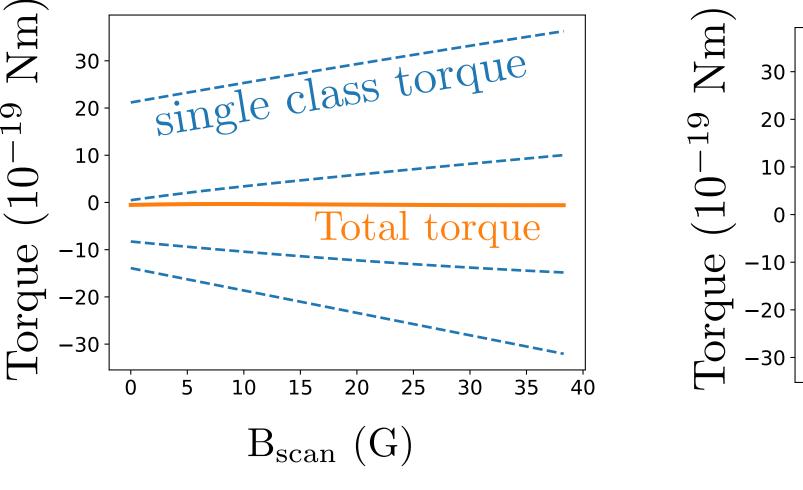
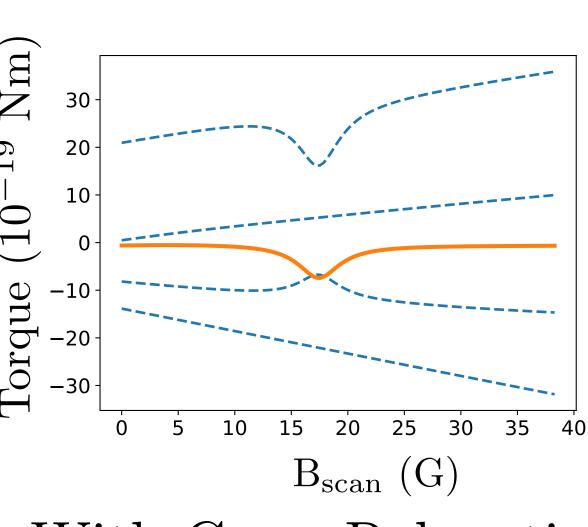
10 10 Total torque

• Solve the master equation to get  $\rho$  (With or without modified  $T_1$ )

• Derive  $\vec{S} = \text{Tr}(\rho \hat{\vec{S}})$  for all four classes • Derive  $\Gamma_t = \sum_i \gamma_e \vec{S}_i \times \vec{B}$ 





Without Cross-Relaxations

With Cross-Relaxations