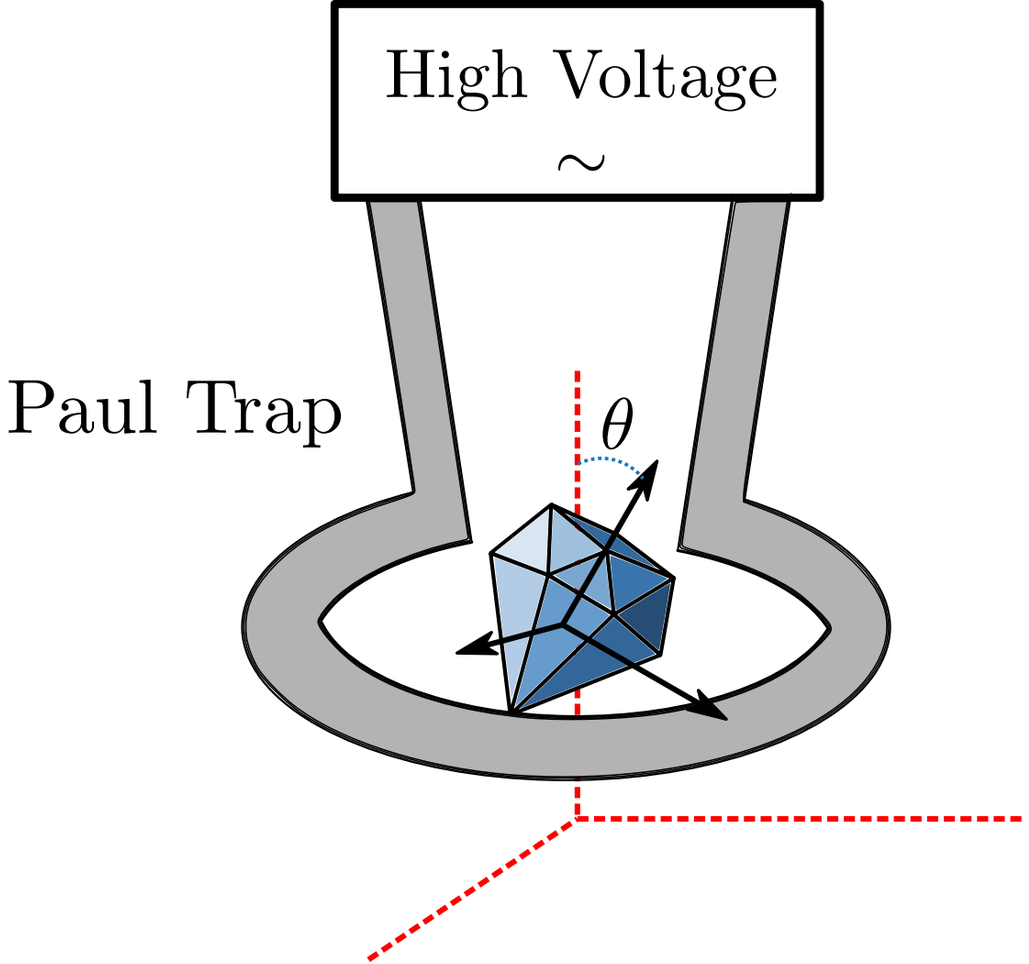

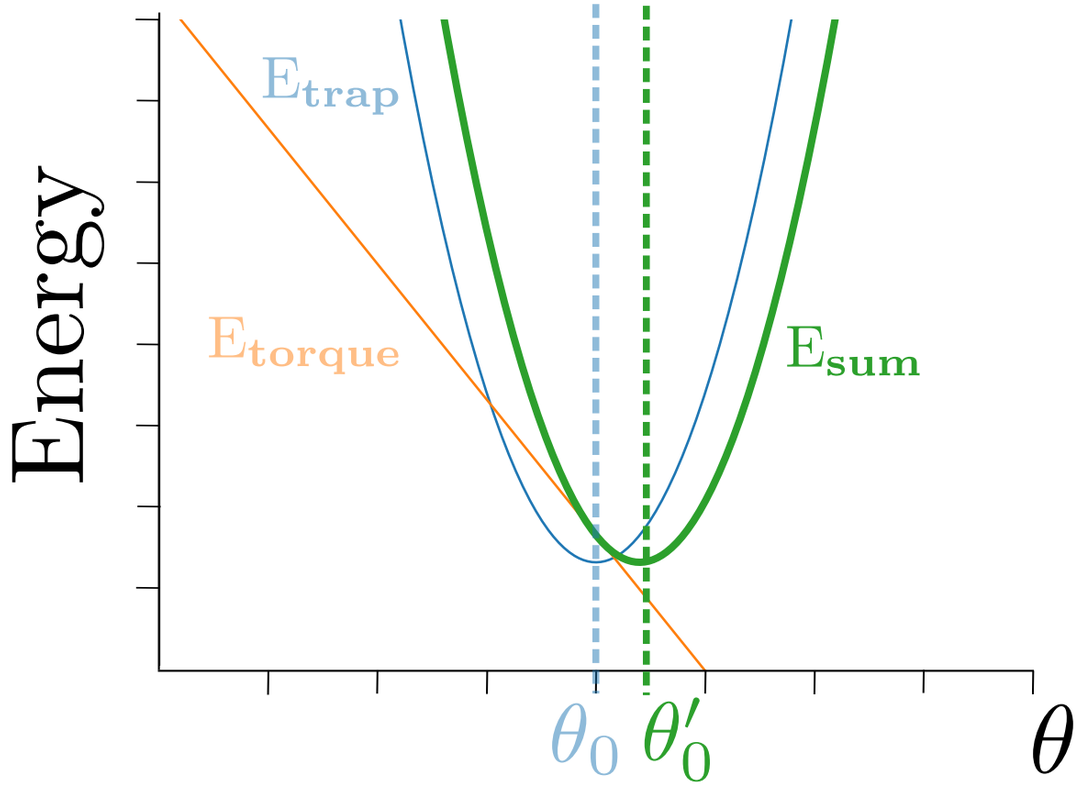

Torque + Trap = shifted Trap

$\rightarrow$ Displacement of the equilibrium angle

Center of mass trapping : (x_0, y_0, z_0)

Angular trapping : $(\phi_0, \theta_0, \psi_0)$