



Eval Kit Manual

AS5048

Adapter Board

AS5048-EK-AB

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Revision History

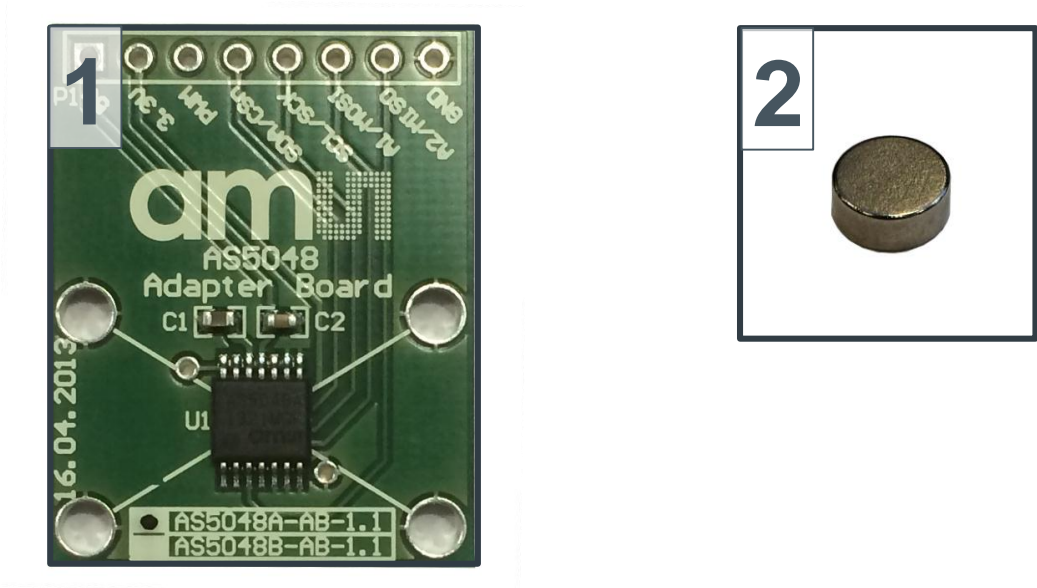
| Revision | Date | Owner | Description |
|----------|------------|-------|---|
| 1.0 | 01.10.2009 | | Initial version |
| 1.1 | 18.10.2013 | azen | Updated to new template |
| 1.2 | 14.01.2013 | rph | Minor corrections in section 4.1 |
| 1.3 | 01.07.2014 | mzie | Updated ordering code, added section 1.1, updated figure 2-9, updated source code |

1 Introduction

The AS5048 adapter board is a small PCB allowing simple and quick testing or evaluation of the AS5048 magnetic position sensor without the need to build a test fixture or design an own PCB.

1.1 Kit Content

Figure 1: Kit Content



| Pos. | Item | Comment |
|------|----------------------|---|
| 1 | AS5048 adapter board | P1 unpopulated |
| 2 | Magnet AS5000-MD6H-2 | Diametric Magnet, D6x2.5mm, NdFeB, Bometec AG |

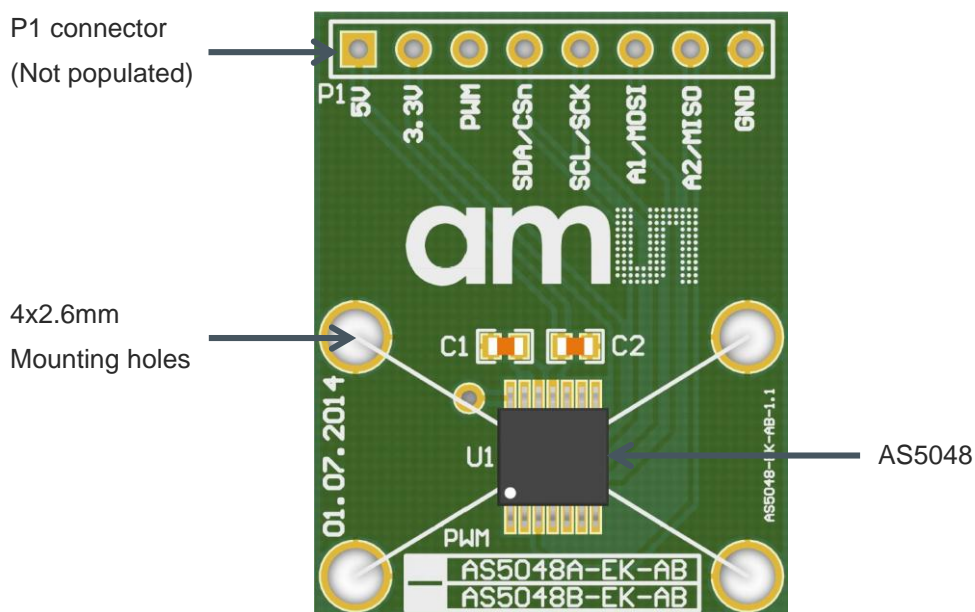
2 Board Description

The PCB can either be connected to an external microcontroller or to the Universal Connector Board (AS5xxx-UCB) in combination with a NI USB-8451 box and a provided LabVIEW software.

P1 has to be populated with a 1x8 pin header and is required for power supply as well as SPI/I2C and PWM interfaces.

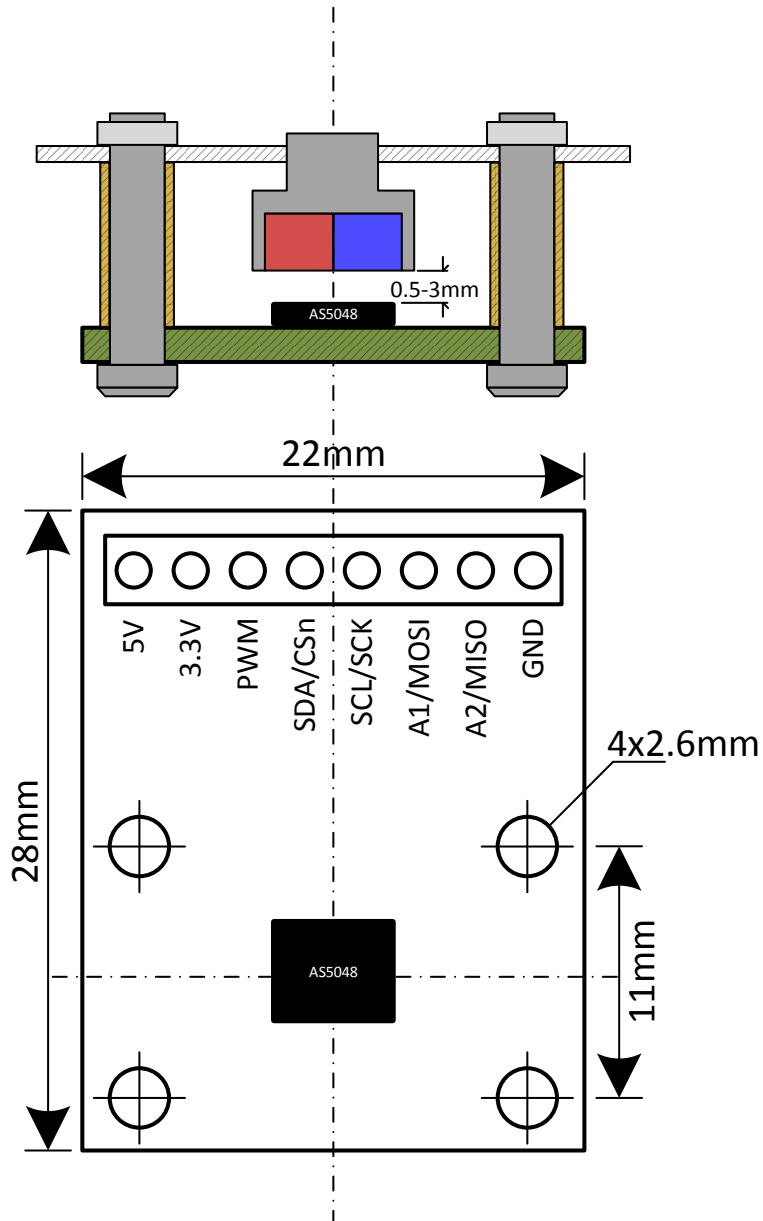
The PCB is available in two versions. Either populated with an AS5048A with SPI or AS5048B with I2C interface.

Figure 2: AS5048 adapter board



2.1 Mounting the AS5048 adapter board

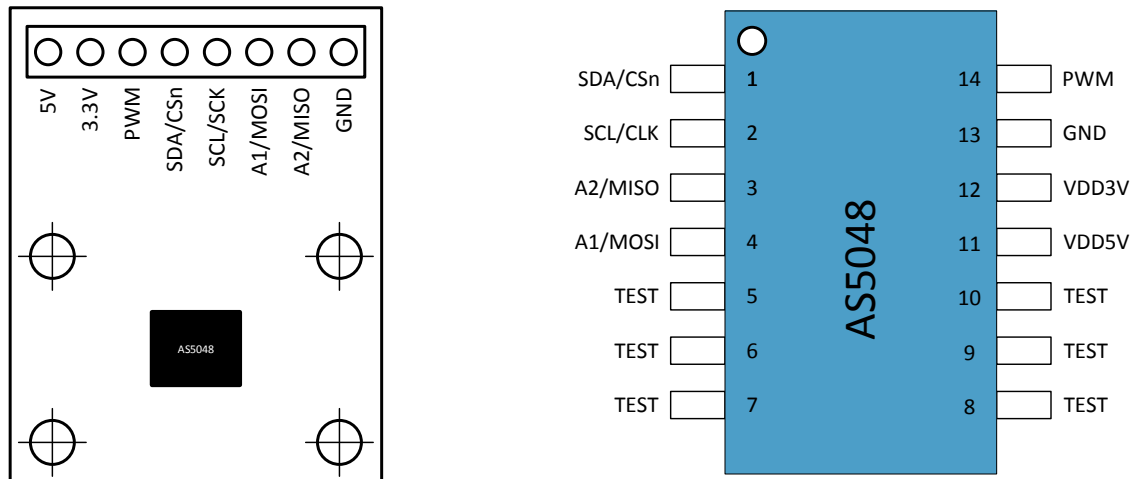
Figure 3: Mounting and dimensions



A 6x2.5mm diametric magnet must be placed over or under the AS5048 sensor, and should be centered on the middle of the package with a tolerance of 0.5mm. The airgap between the magnet surface and the package should be maintained in the range 0.5mm to 3mm. The magnet holder must not be ferromagnetic. Materials as brass, copper, aluminum, stainless steel are the best choices to make this part.

3 AS5048 adapter board and pinout

Figure 4: AS5048 adapter board connectors and encoder pinout



| Pin# Board | Pin# AS5048 | Symbol Board | Description |
|------------|-------------|--------------|--|
| P1 – 1 | 11 | 5V | Supply voltage |
| P1 – 2 | 12 | 3.3V | 3V-Regulator output; internally regulated from VDD. Connect to VDD for 3V supply voltage |
| P1 – 3 | 14 | PWM | Pulse width modulation output |
| P1 – 4 | 1 | SDA/CSn | SPI chip select-active low; shared with I2C data pin |
| P1 – 5 | 2 | SCL/SCK | SPI clock input; shared with I2C clock input |
| P1 – 6 | 4 | A1/MOSI | SPI master out/slave in; shared with I2C address selection pin 1 |
| P1 – 7 | 3 | A2/MISO | SPI master in/slave out; shared with I2C address selection pin 2 |
| P1 – 8 | 13 | GND | Supply ground |

4 Operation cases

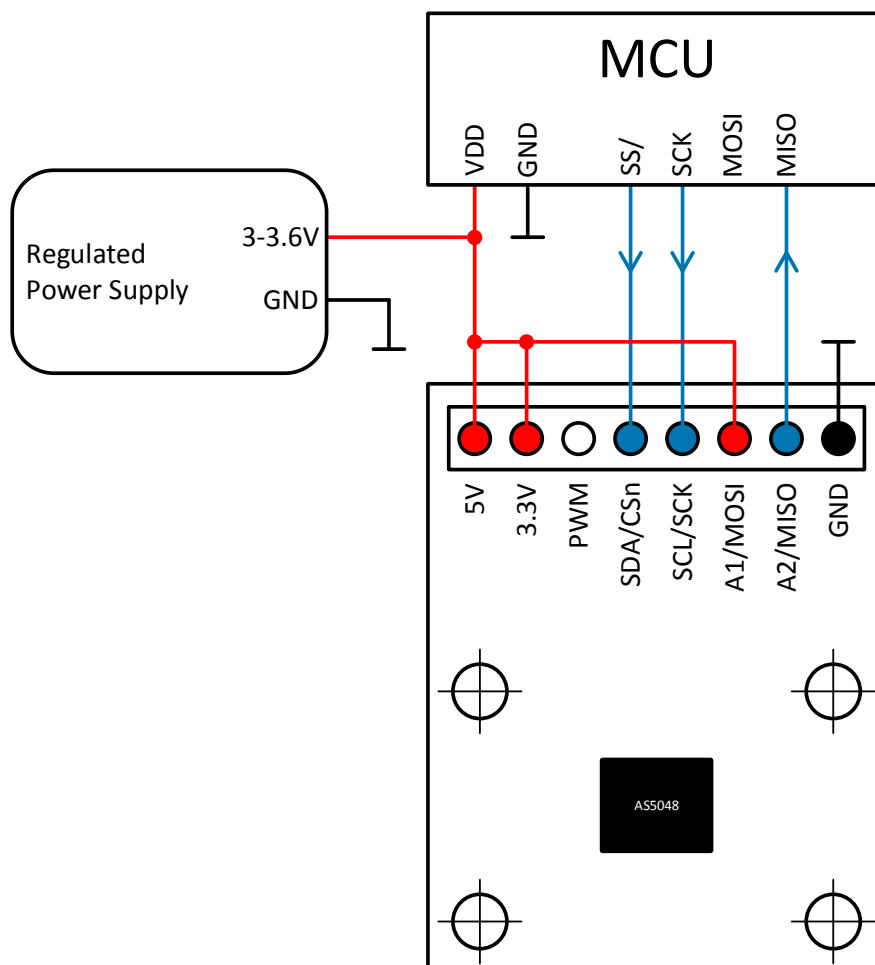
The most complete and accurate solution for a MCU to read the angle of a magnet is the SPI interface.

4.1 One Device SPI mode, unidirectional – 3 wire

The AS5048-EK-AB can be directly connected to an industry standard SPI port of a microcontroller. The minimum connection requirement for unidirectional communication (angle + alarm values reading) between the microcontroller and the AS5048 are MISO, SCK, SS/.

The angle will be read at each 16-bit SPI transfer. See AS5048 datasheet register table, register 3FFFh.

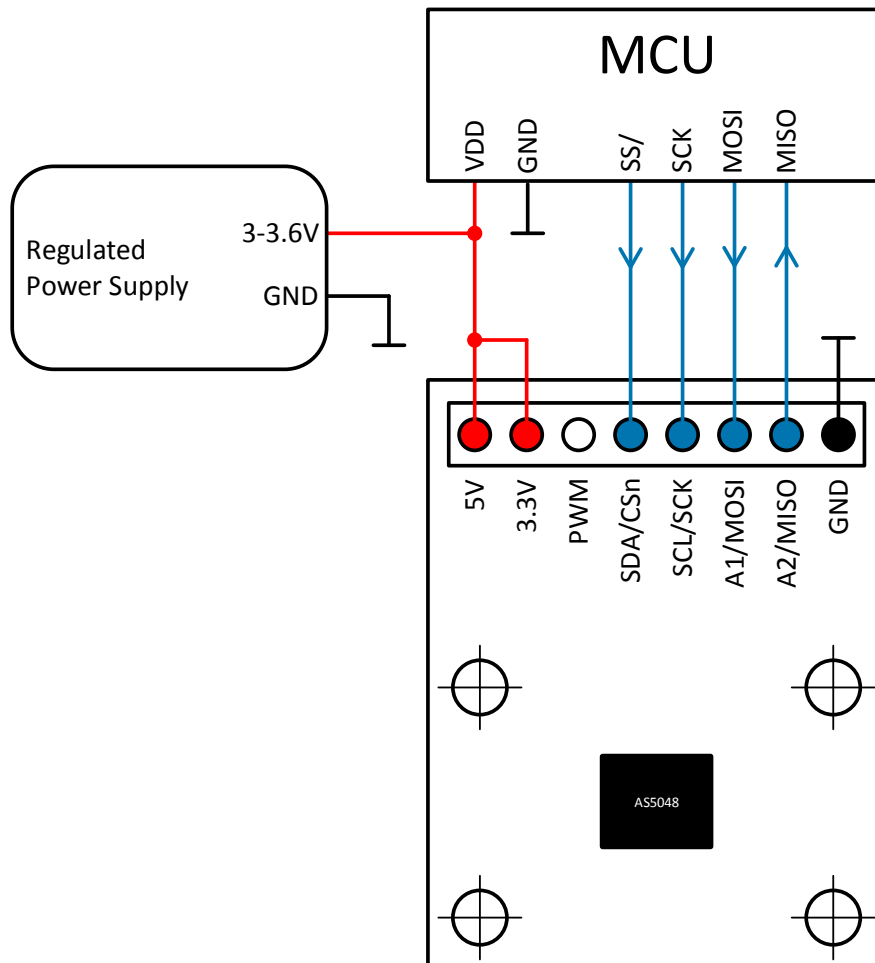
Figure 5: Using the SPI Interface unidirectional with a microcontroller



4.2 One device SPI mode, bidirectional – 4 wire

If other registers than only angle values have to be read, or in order to write registers into the AS5048, the signal MOSI is necessary.

Figure 6: Using the SPI Interface biidirectional with a microcontroller



4.3 Multi devices SPI Daisy chain mode

The AS5048 can be daisy chained, using 4 wires only for SPI communication.

In this configuration with n x encoders, the sequence will be processed as follow:

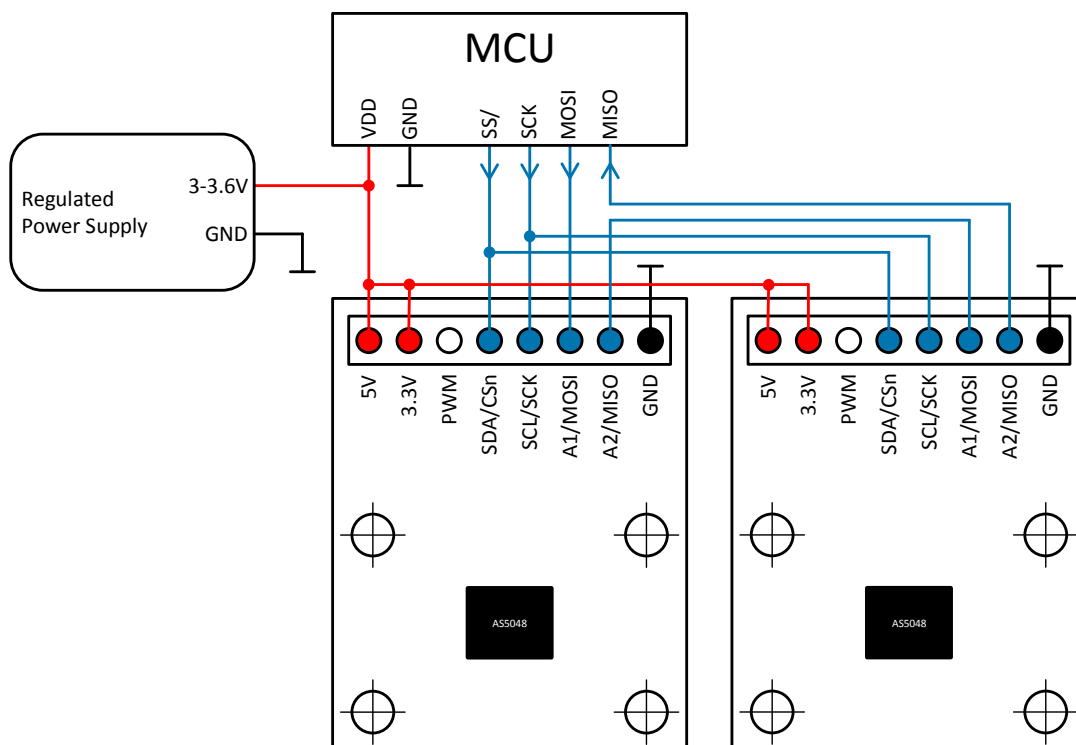
- MCU sets SS/ = 0
- MCU shifts n x 16-bit (e.g. READ command FFFFh) through the chain
- MCU sets SS/=1

At that point all the n x encoders have received the READ command FFFFh.

- MCU sets SS/=0
- MCU shifts n x 16-bit (e.g. NOP command 0000h)
- MCU sets SS/=1

At that point the n x 16-bit received on MISO are the n x angle values.

Figure 7: Multi Devices in Daisy chain mode



5 Software example source code

The following source code shows a 4-wire SPI application case.

```

/*!
*****
* \brief Reads out chip data via SPI interface
*
* This function is used to read out cordic value from chips supporting SPI
* interface.
* After calling this function the data can be displayed using #displayData.
*
* \param[in] die : index of the die to read out.
* \param[out] dd : Buffer of type #t_displayData where the read out data
*                  will be written to.
*
*****
*/

static void spiReadData(u8 die, t_displayData * dd)
{
    umword i;
    u16 dat;
    u16 agcreg;
#ifdef AS5048_CHIPDESCRIPTION
    u16 magreg;
#endif
    PARAMETER_UNUSED(die);

    dd->angleprec = 0;
    /* read agc value */
    for (i = 0; i < 2; i++)
    {
        /* the result is available only just in the second transfer.
           transfers must be separated by chip selects */
        dat = SPI_CMD_READ | SPI_REG_AGC;
        dat |= spiCalcEvenParity(dat);
        spiTransfer((u8*)&dat, sizeof(u16));
    }
    agcreg = dat;

#ifdef AS5048_CHIPDESCRIPTION
    for (i = 0; i < 2; i++)
    {
        /* the result is available only just in the second transfer.
           transfers must be separated by chip selects */
        dat = SPI_CMD_READ | SPI_REG_MAG;

```

```

        dat |= spiCalcEvenParity(dat) << 15;
        spiTransfer((u8*)&dat, sizeof(u16));
    }
    magreg = dat;
#endif
    for (i = 0; i < 2; i++)
    {
        /* the result is available only just in the second transfer.
           transfers must be separated by chip selects */
        dat = SPI_CMD_READ | SPI_REG_DATA;
        dat |= spiCalcEvenParity(dat);
        spiTransfer((u8*)&dat, sizeof(u16));
    }

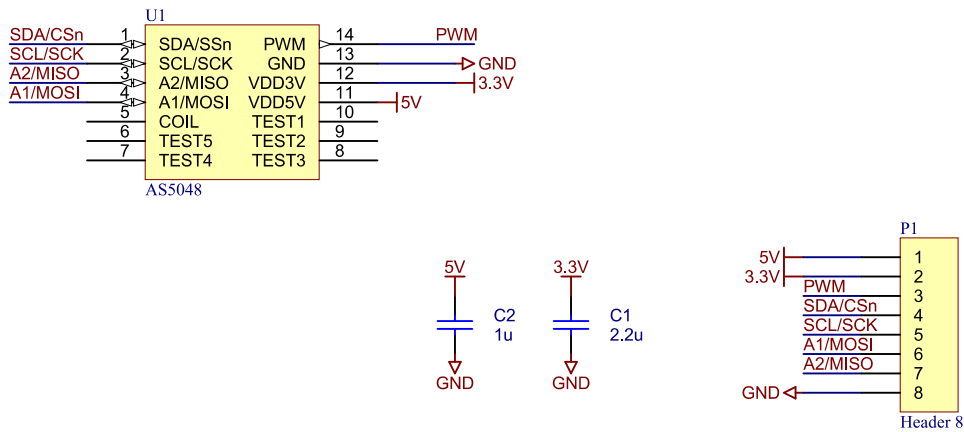
#ifdef AS5048_CHIPDESCRIPTION
    if ((dat & 0x4000) || (agcreg & 0x4000) || (magreg & 0x4000))
#else
    if (((dat >> 1) & 0x1) || ((agcreg >> 1) & 0x1))
#endif
    {
        /* error flag set - need to reset it */
        dat = SPI_CMD_READ | SPI_REG_CLRRERR;
        dat |= spiCalcEvenParity(dat);
        spiTransfer((u8*)&dat, sizeof(u16));
    }
    else
    {
#ifdef AS5048_CHIPDESCRIPTION
        dd->agc = agcreg & 0xff;
        dd->value = dat & (currentChipDescription->positions - 1);
        dd->angle = (dd->value * 360) / currentChipDescription->positions;
        dd->magnitude = magreg & (currentChipDescription->positions - 1);
        dd->alarmLo = (agcreg >> 10) & 0x1;
        dd->alarmHi = (agcreg >> 11) & 0x1;
#else
        dd->agc = (agcreg >> 2) & 0x3F;
        dd->value = (dat >> 2) & (currentChipDescription->positions - 1);
        dd->angle = (dd->value * 360) / currentChipDescription->positions;
        dd->alarmLo = (dat >> 14) & 0x1;
        dd->alarmHi = (dat >> 15) & 0x1;
#endif
    }
}

```

6 AS5048-EK-AB Hardware

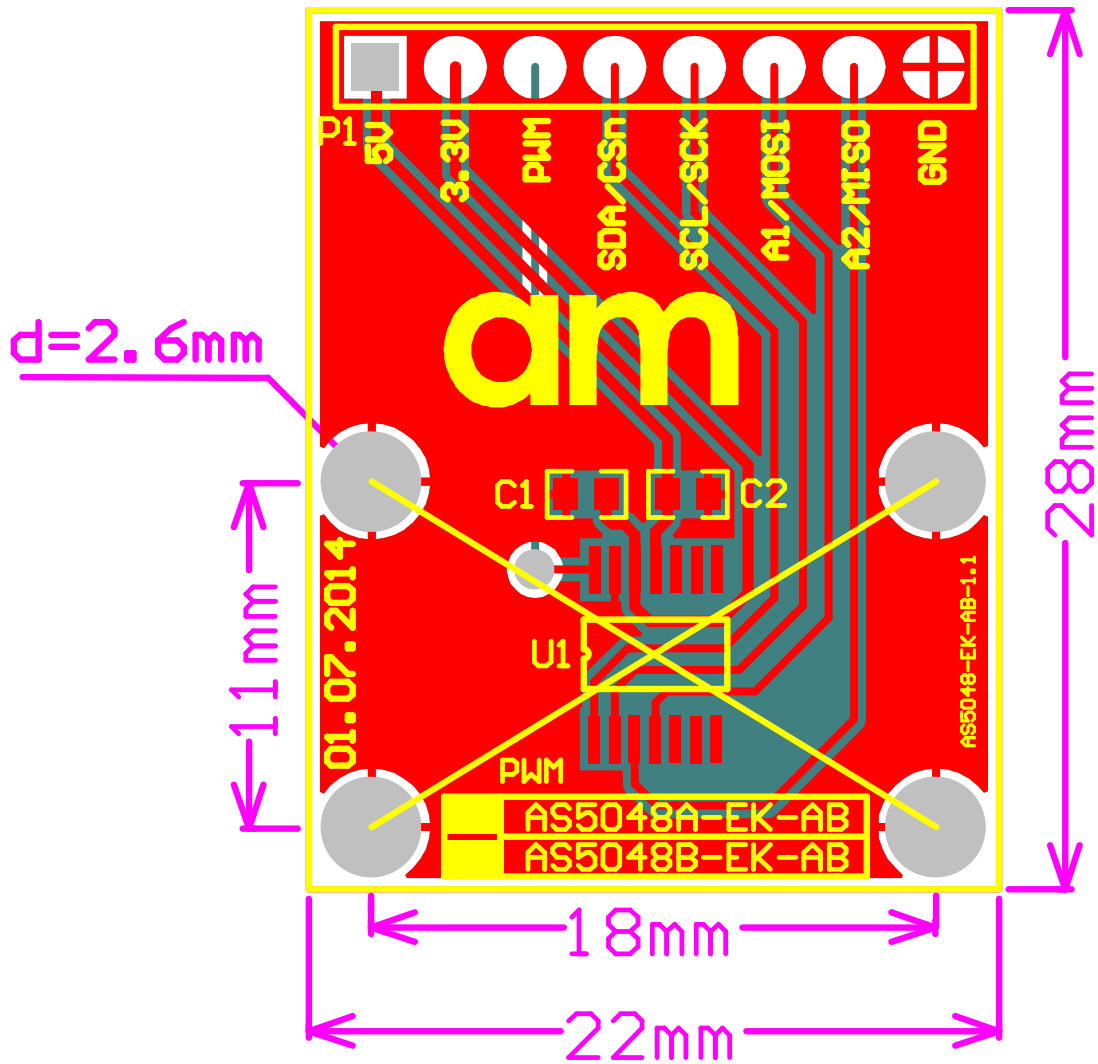
6.1 AS5048-EK-AB schematics

Figure 8: AS5048-EK-AB schematics



6.2 AS5048-EK-AB PCB layout

Figure 9: AS5048-EK-AB PCB layout



7 Ordering & Contact Information

| Ordering Code | Description |
|---------------|-------------------------------|
| AS5048-EK-AB | AS5048 Eval Kit Adapter Board |

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