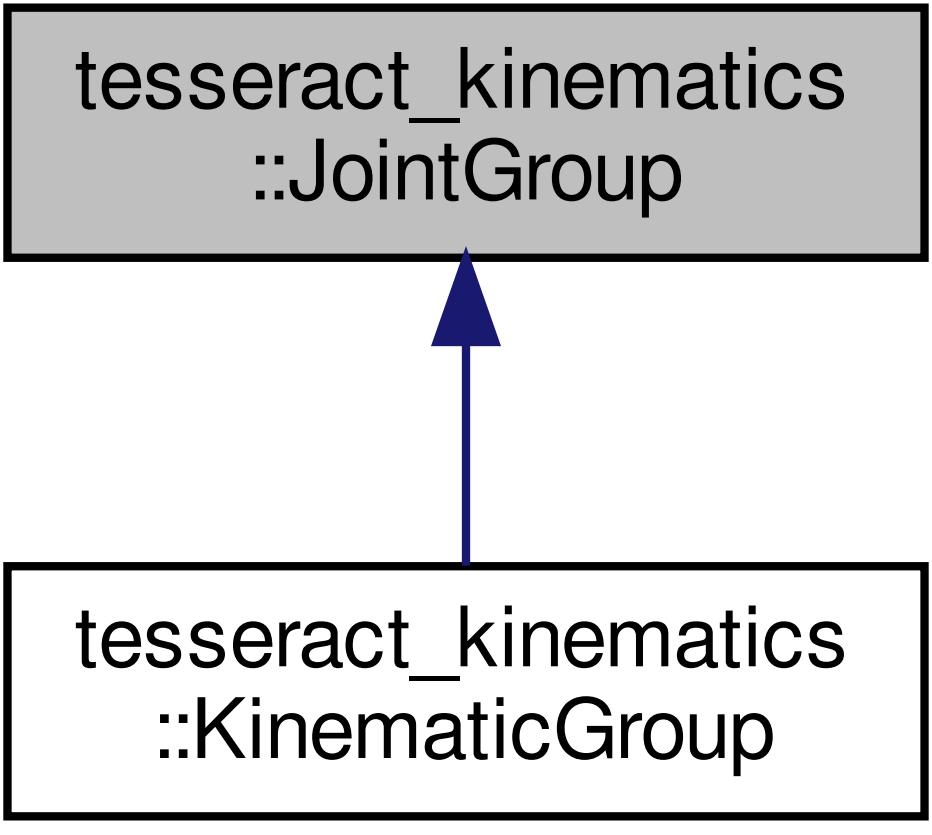
tesseract_kinematics
::JointGroup
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::KinematicGroup