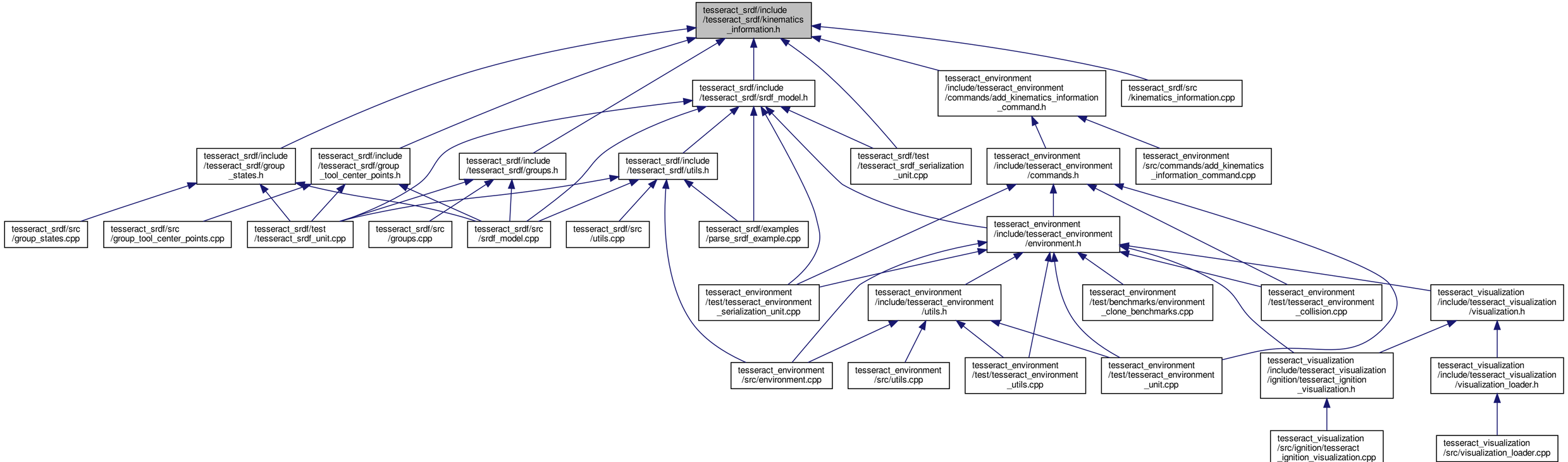
tesseract_srdf/include /tesseract_srdf/kinematics _information.h
tesseract_srdf/include /tesseract_srdf/srdf_model.h
tesseract_environment /include/tesseract_environment /commands/add_kinematics_information _command.h
tesseract_srdf/src /kinematics_information.cpp
tesseract_srdf/include /tesseract_srdf/group _states.h
tesseract_srdf/include /tesseract_srdf/group _tool_center_points.h
tesseract_srdf/include /tesseract_srdf/groups.h
tesseract_srdf/include /tesseract_srdf/utils.h
tesseract_srdf/test /tesseract_srdf_serialization _unit.cpp
tesseract_environment /include/tesseract_environment /commands.h
tesseract_environment /src/commands/add_kinematics _information_command.cpp
tesseract_srdf/src /group_states.cpp
tesseract_srdf/src /group_tool_center_points.cpp
tesseract_srdf/test /tesseract_srdf_unit.cpp
tesseract_srdf/src /groups.cpp
tesseract_srdf/src /srdf_model.cpp
tesseract_srdf/src /utils.cpp
tesseract_srdf/examples /parse_srdf_example.cpp
tesseract_environment /include/tesseract_environment /environment.h
tesseract_environment /test/tesseract_environment _serialization_unit.cpp
tesseract_environment /include/tesseract_environment /utils.h
tesseract_environment /test/benchmarks/environment _clone_benchmarks.cpp
tesseract_environment /test/tesseract_environment _collision.cpp
tesseract_visualization /include/tesseract_visualization /visualization.h
tesseract_environment /src/environment.cpp
tesseract_environment /src/utils.cpp
tesseract_environment /test/tesseract_environment _utils.cpp
tesseract_environment /test/tesseract_environment _unit.cpp
tesseract_visualization /include/tesseract_visualization /ignition/tesseract_ignition _visualization.h
tesseract_visualization /include/tesseract_visualization /visualization_loader.h
tesseract_visualization /src/ignition/tesseract _ignition_visualization.cpp
tesseract_visualization /src/visualization_loader.cpp