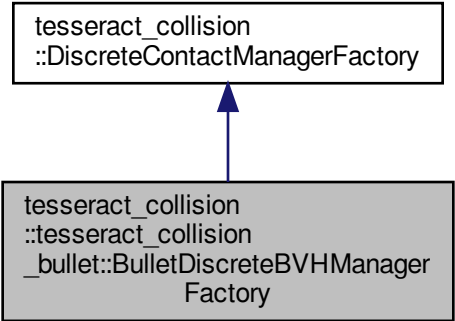


tesseract\_collision  
::DiscreteContactManagerFactory



```
graph BT; A["tesseract_collision_bullet::BulletDiscreteBVHManagerFactory"] --> B["tesseract_collision::DiscreteContactManagerFactory"]
```

tesseract\_collision  
::tesseract\_collision  
\_bullet::BulletDiscreteBVHManager  
Factory