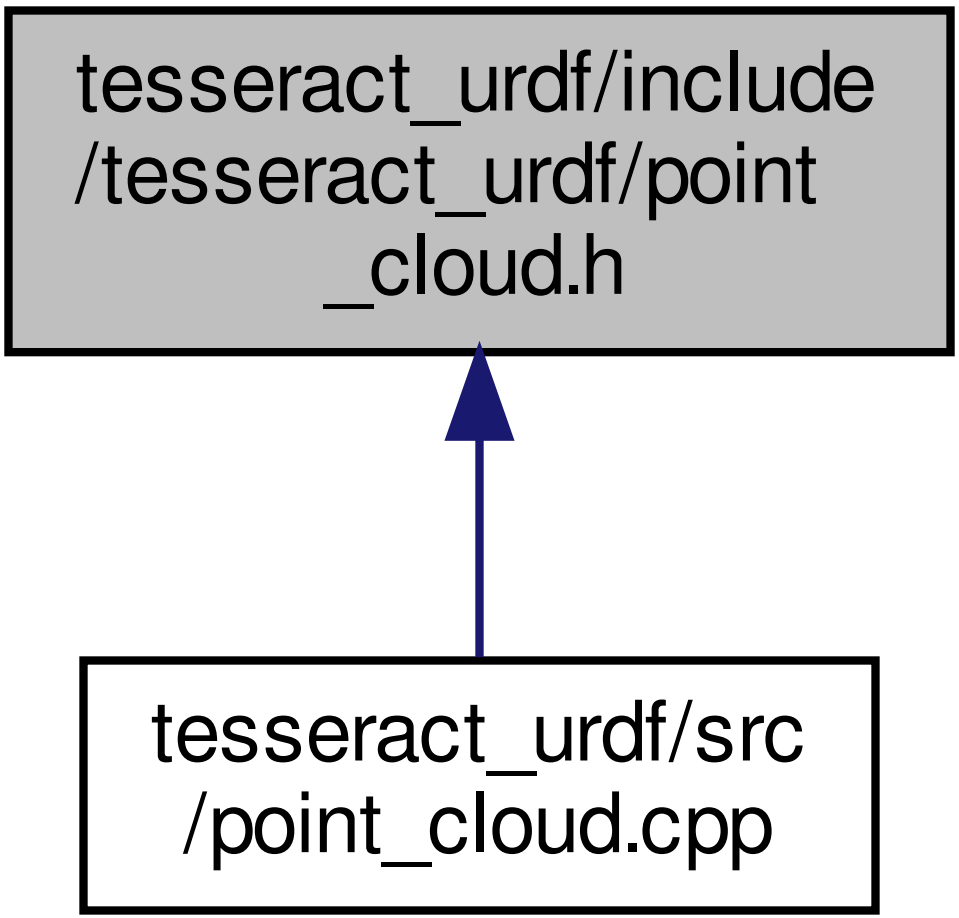
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tesseract_urdf/src/point_cloud.cpp