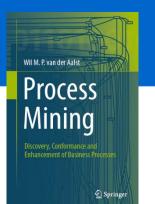
Process Mining: Data Science in Action

Transition Systems and Petri Net Properties

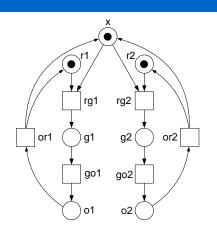


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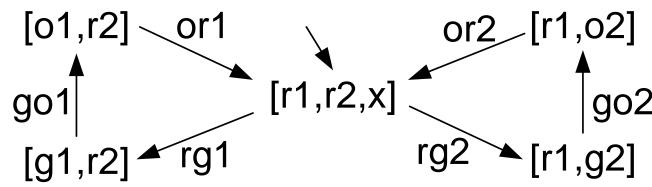


Where innovation starts

Reachability graph of a Petri net

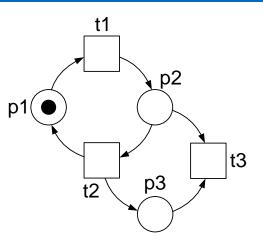


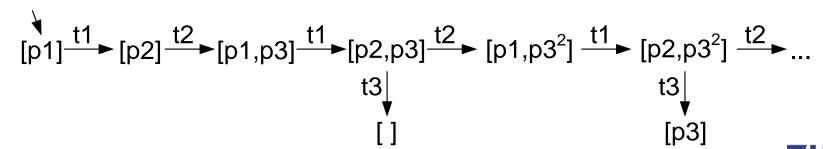
The reachability graph is a transition system with one initial state (initial marking) and no explicit final marking.





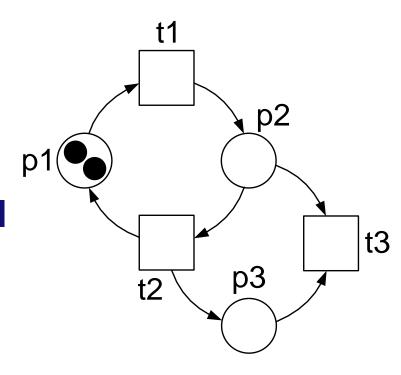
Reachability graph may be infinite





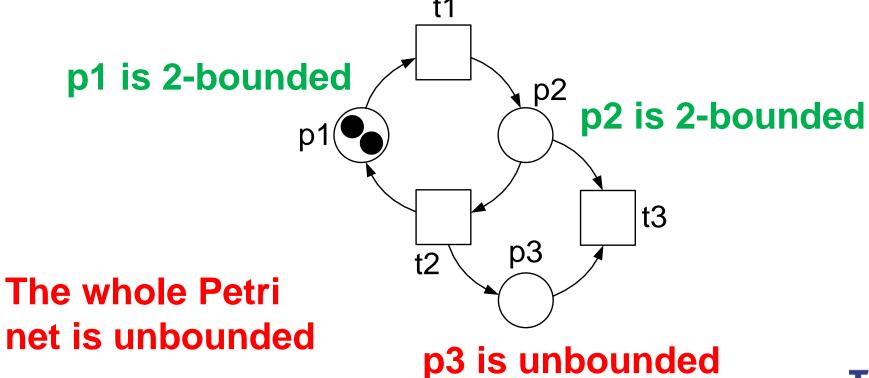
Boundedness

- A place p is k-bounded if there is no reachable marking with more than k tokens in p.
- A Petri net is k-bounded if all places are k-bounded.
- A place/Petri net is bounded if there exists such a k.

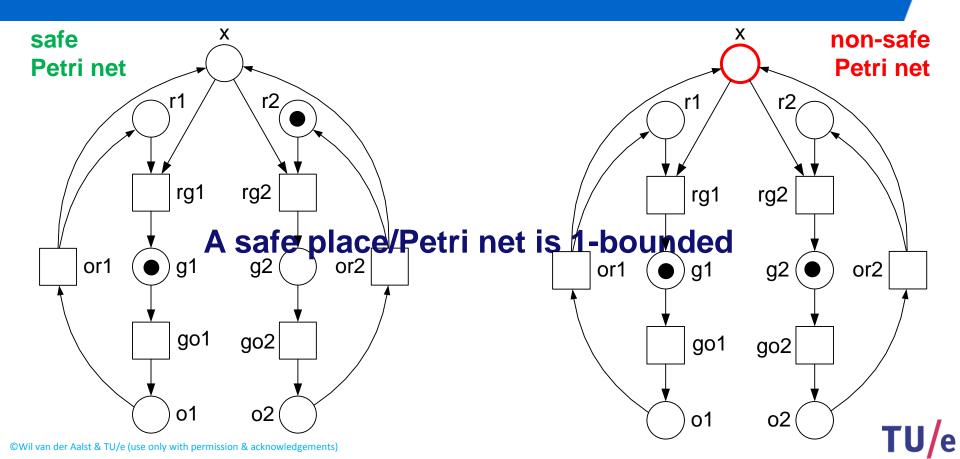




Boundedness

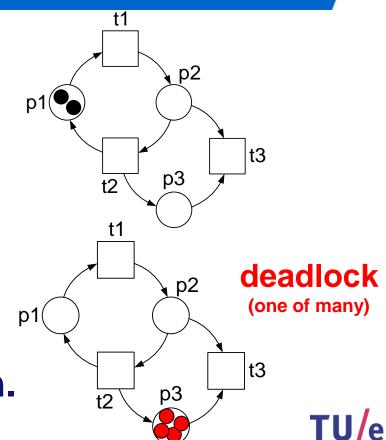


Safeness (= 1-boundedness)



Deadlock

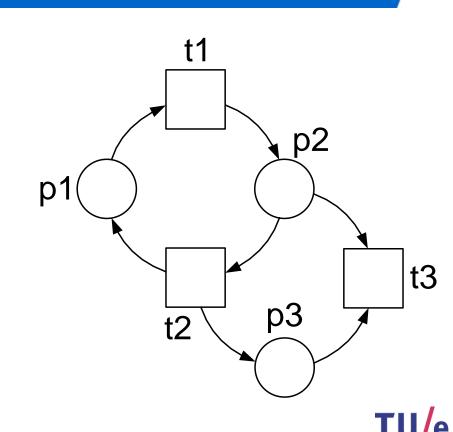
- A marking is dead if no transition is enabled in it.
- A Petri net has a potential deadlock if there is a reachable dead marking.
- A Petri net is deadlock-free if each reachable marking enables at least one transition.



Question

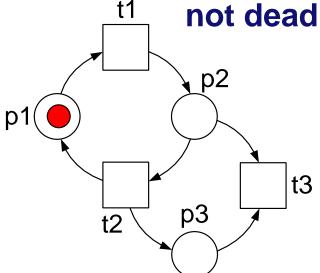
Provide (if possible) an initial making such that

- the Petri net is unbounded and not deadlock-free,
- the Petri net is bounded and not deadlock-free,
- the Petri net is unbounded and deadlock-free, and
- the Petri net is bounded and deadlock-free.

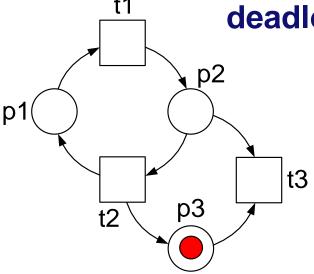


Answer

unbounded and not deadlock-free



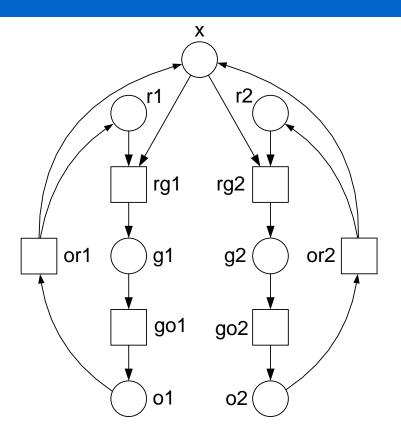
bounded but not deadlock-free



The net will always have a deadlock independent of the initial marking!



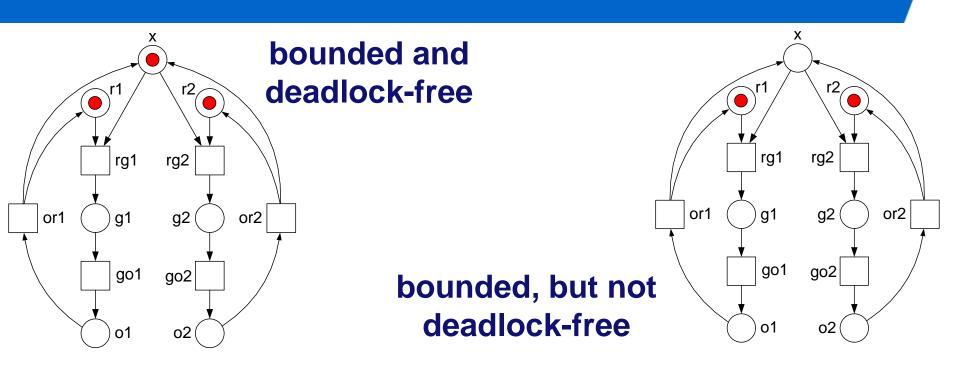
Question



Provide (if possible) an initial making such that

- the Petri net is unbounded and not deadlock-free,
- the Petri net is bounded and not deadlock-free,
- the Petri net is unbounded and deadlock-free, and
- the Petri net is bounded and deadlock-free.

Answer

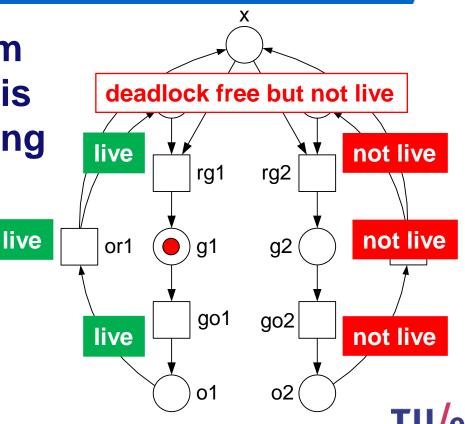


The net will always be bounded independent of the initial marking!

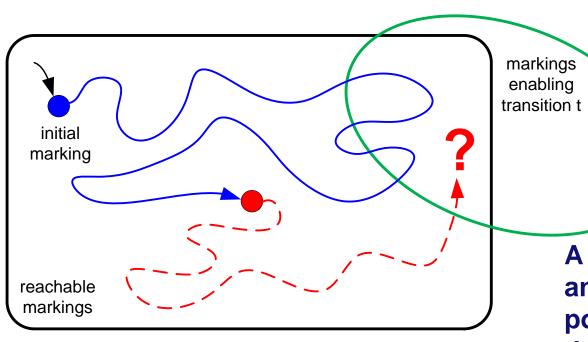


Liveness

- A transition t is live if from any reachable marking it is possible to reach a marking that enables t.
- A Petri net is live if all transitions are live.
- A Petri net that is live is deadlock-free.



Understanding liveness



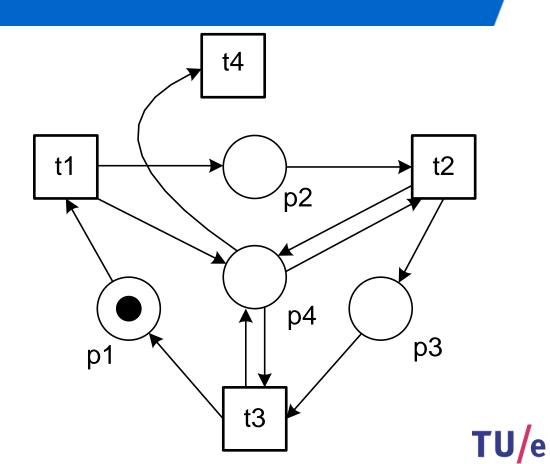
A transition *t* is live if from any reachable marking it is possible to reach a marking that enables *t*.

A Petri net is live if all transitions are live.



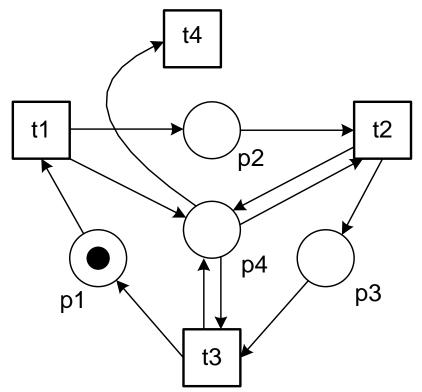
Question

- Is the Petri net bounded?
- Is the Petri net safe?
- Is the Petri net deadlock free?
- Is the Petri net live?



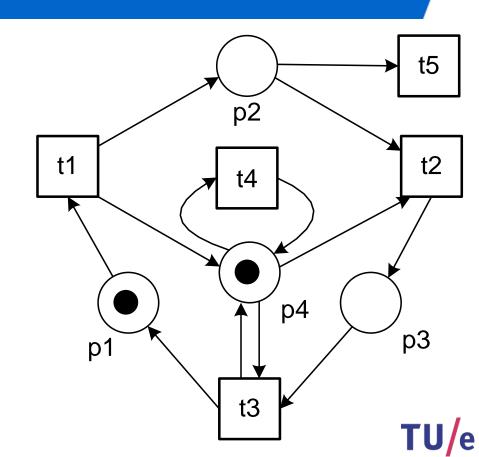
Answer

- The Petri net is not bounded because any number of tokens can be put in p4.
- Hence, also not safe (= 1-bounded).
- The Petri net is not deadlock free, e.g., [p2] is reachable.
- Hence, also not live.



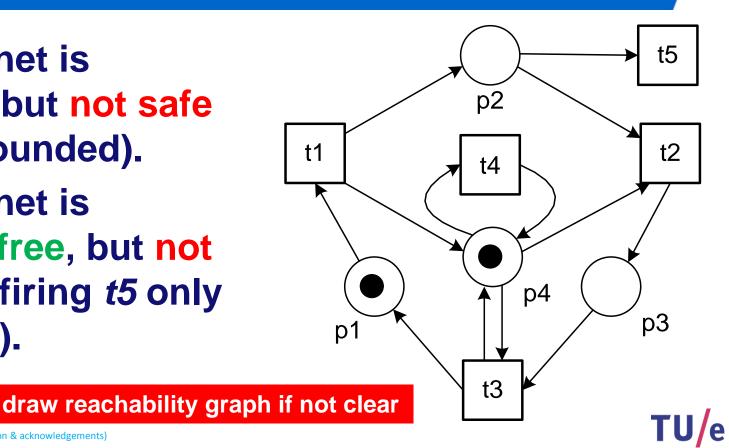
Question

- Is the Petri net bounded?
- Is the Petri net safe?
- Is the Petri net deadlock free?
- Is the Petri net live?



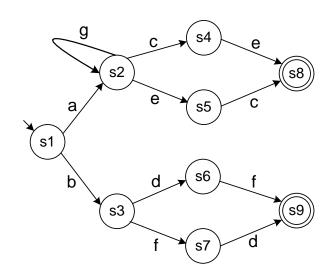
Answer

- The Petri net is bounded, but not safe (p4 is 2-bounded).
- The Petri net is deadlock-free, but not live (after firing t5 only t4 can fire).



Transition systems

- A reachability graph is a special kind of transition system.
- Firing sequences correspond to paths in the transition system.
- A transition system is composed of states and transitions.
- There may be 1 or more initial states and 0 or more final states (more general than Petri nets).



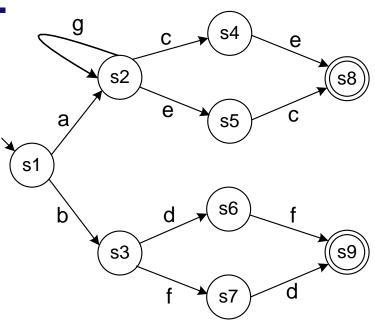
One initial state: s1

Two final states: s8 and s9



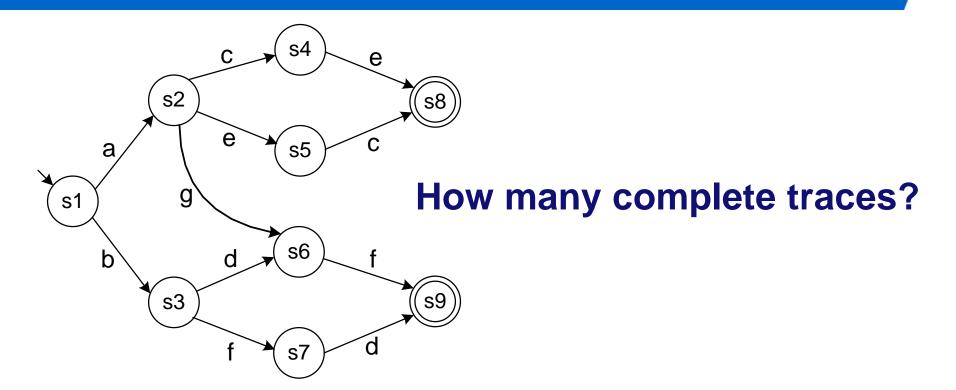
Complete traces

- (a,g,g,c,e) is a complete trace.
- (b,d,f) is a complete trace.
- (a,g,g,g,g) is an incomplete trace.
- \(\bar{b}, \f \) is an incomplete trace.
- The transition system has infinitely many (in)complete traces.





Question

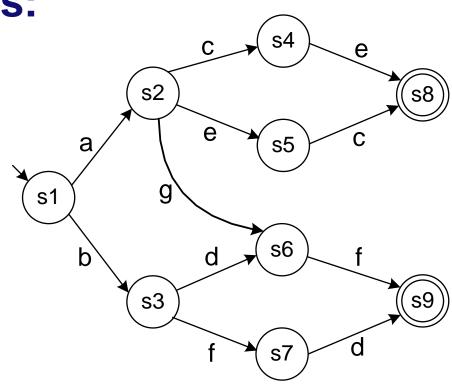




Answer

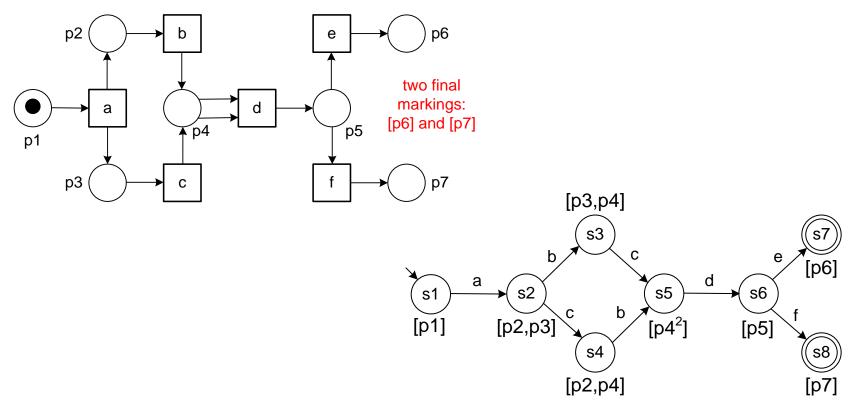
Five complete traces:

- ⟨a,c,e⟩
- ⟨a,e,c⟩
- ⟨a,g,f⟩
- **(b,d,f)**
- ⟨b,f,d⟩



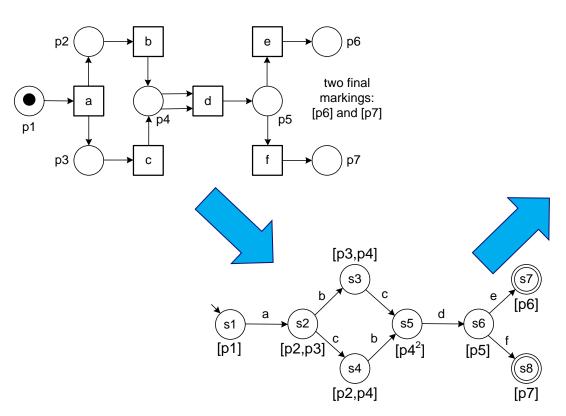


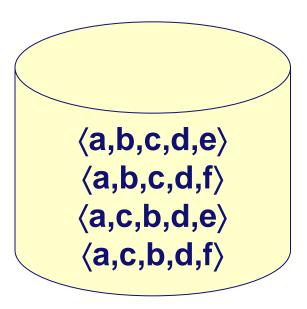
A Petri net may also have a designated set of final markings





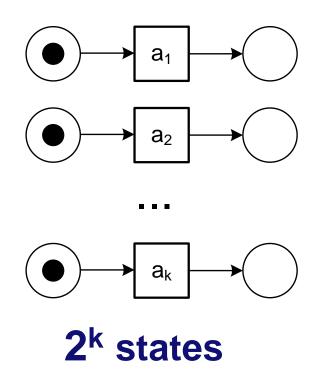
Play-out

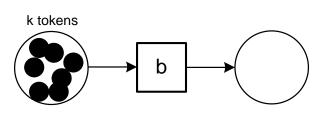




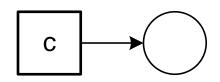


Transition system may be exponential in size of Petri net (or even infinite)





(k+1) states

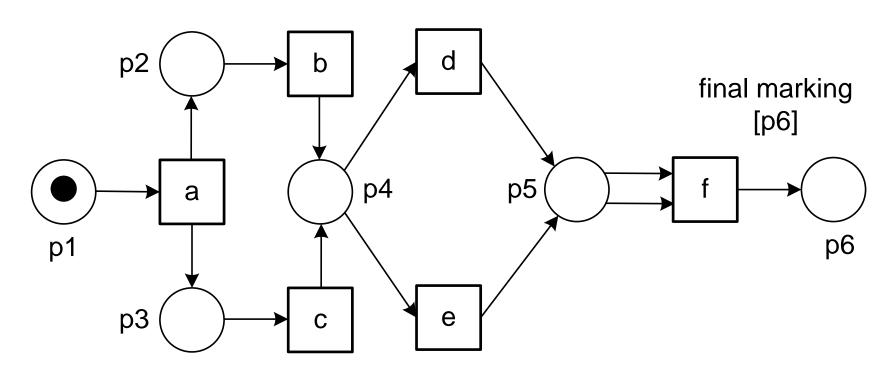


infinitely many states



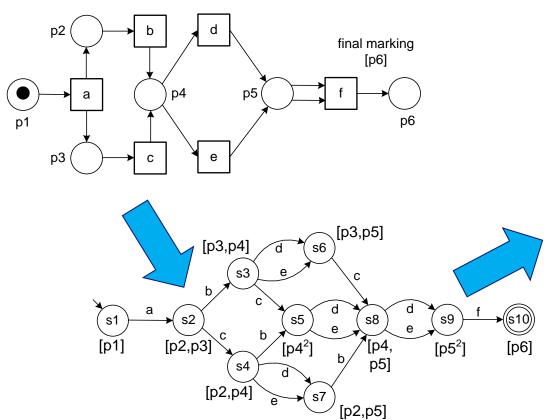
Play-out model:

Give the transition system and all complete traces that are possible





Resulting transition system and set of complete traces

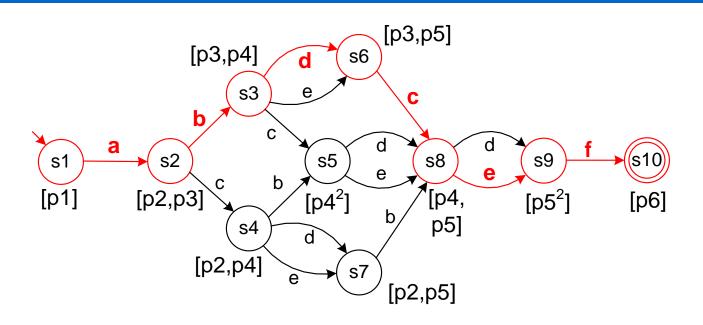


16 possible traces

 $\langle a,b,c,d,d,f \rangle$ $\langle a,b,c,d,e,f \rangle$ $\langle a,b,c,e,d,f \rangle$ $\langle a,b,c,e,e,f \rangle$ $\langle a,c,b,d,d,f \rangle$ ⟨a,c,b,d,e,f⟩ $\langle a,c,b,e,d,f \rangle$ $\langle a,c,b,e,e,f \rangle$ $\langle a,b,d,c,d,f \rangle$ $\langle a,b,d,c,e,f \rangle$ $\langle a,b,e,c,d,f \rangle$ ⟨a,b,e,c,e,f⟩ $\langle a,c,d,b,d,f \rangle$ $\langle a,c,d,b,e,f \rangle$ ⟨a,c,e,b,d,f⟩ $\langle a,c,e,b,e,f \rangle$



Example path



```
\langle a,b,c,d,d,f \rangle
  \langle a,b,c,d,e,f \rangle
  \langle a,b,c,e,d,f \rangle
  \langle a,b,c,e,e,f \rangle
  \langle a,c,b,d,d,f \rangle
  \langle a,c,b,d,e,f \rangle
  \langle a,c,b,e,d,f \rangle
  \langle a,c,b,e,e,f \rangle
  \langle a,b,d,c,d,f \rangle
\langle a,b,d,c,e,f \rangle
  \langle a,b,e,c,d,f \rangle
  \langle a,b,e,c,e,f \rangle
  \langle a,c,d,b,d,f \rangle
  \langle a,c,d,b,e,f \rangle
  \langle a,c,e,b,d,f \rangle
  \langle a,c,e,b,e,f \rangle
```

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Chapter 2

Process Modeling and Analysis

Chapter 3
Data Mining

Part III: Beyond Process Discovery

Chapter 7

Conformance Checking Chapter 8
Mining Additional
Perspectives

Chapter 9
Operational Support

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Chapter 4
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Chapter 5

Process Discovery: An Introduction

Models

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Advanced Process
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Tool Support

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Analyzing "Lasagna
Processes"

Chapter 12
Analyzing "Spaghetti Processes"

Part V: Reflection

Chapter 13
Cartography and
Navigation

Chapter 14
Epilogue



Wil M. P. van der Aalst

Process Mining

Discovery, Conformance and Enhancement of Business Proce



