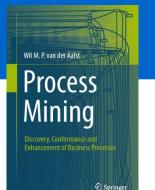
Process Mining: Data Science in Action

**Learning Transition Systems** 



prof.dr.ir. Wil van der Aalst www.processmining.org



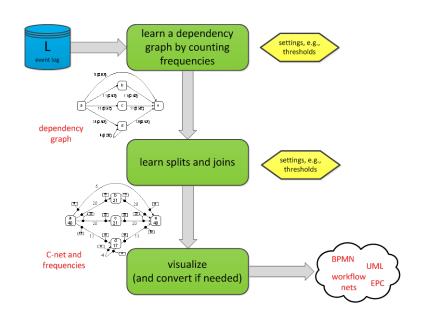
Where innovation starts



Alpha algorithm

```
Let L be an event log over T. \alpha(L) is defined as follows.
1.T_1 = \{ t \in T \mid \exists_{\sigma \in L} t \in \sigma \},
2. T_1 = \{ t \in T \mid \exists_{\sigma \in L} t = first(\sigma) \},
\exists T_0 = \{ t \in T \mid \exists_{\sigma \in I} t = last(\sigma) \},
4. X_1 = \{ (A,B) \mid A \subseteq T_1 \land A \neq \emptyset \land B \subseteq T_1 \land B \neq \emptyset \land A \in A \}
    \forall_{a \in A} \forall_{b \in B} a \rightarrow_{L} b \wedge \forall_{a1,a2 \in A} a_{1} \#_{L} a_{2} \wedge \forall_{b1,b2 \in B} b_{1} \#_{L} b_{2} \},
5.\,Y_L^- = \{\; (A,B) \in X_L \; \mid \; \forall_{(A',B') \;\in\; X_L} \; A \subseteq A' \; \land B \subseteq B' \Longrightarrow (A,B) = (A',B') \; \},
6.P_{L} = \{ p_{(A,B)} \mid (A,B) \in Y_{L} \} \cup \{i_{L},o_{L}\},
7.F_{L} = \{ (a,p_{(A,B)}) \mid (A,B) \in Y_{L} \land a \in A \} \cup \{ (p_{(A,B)},b) \mid \overline{(A,B)} \in A \} 
8. \alpha(L) = (P_1, T_1, F_1).
```

- Alpha algorithm
- Heuristic mining
  - -dependency graph
  - -C-net

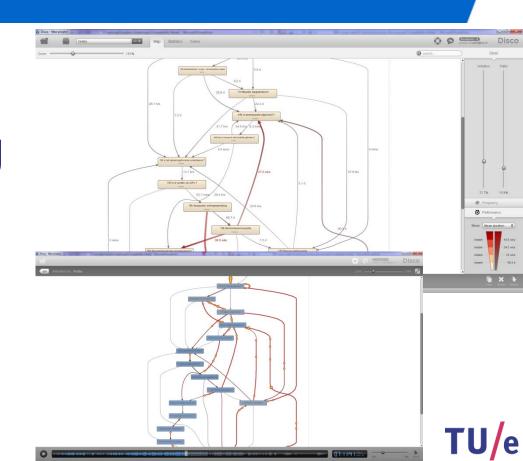




- Alpha algorithm
- Heuristic mining
- Fuzzy miner (tool only)

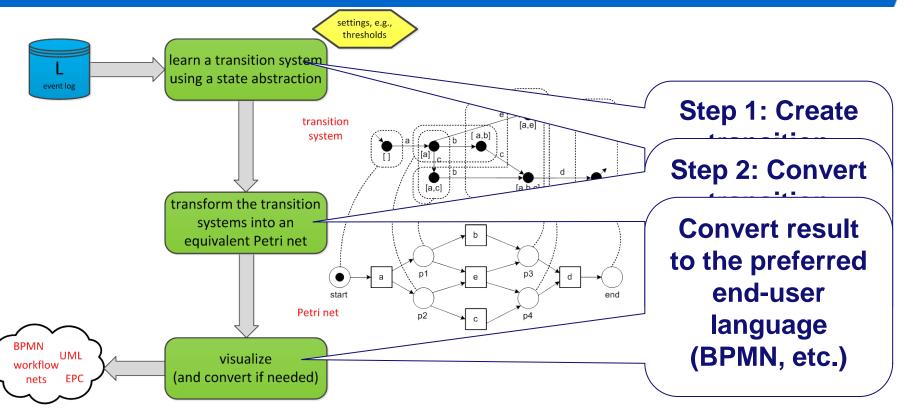


- Alpha algorithm
- Heuristic mining
- Fuzzy miner (tool only)
- Disco (tool only)



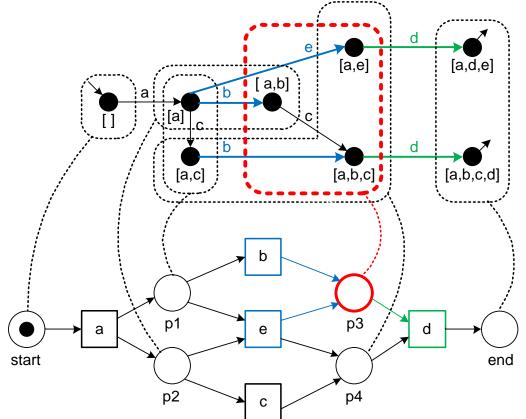
### **Another two-phase approach**

(using state-based regions)



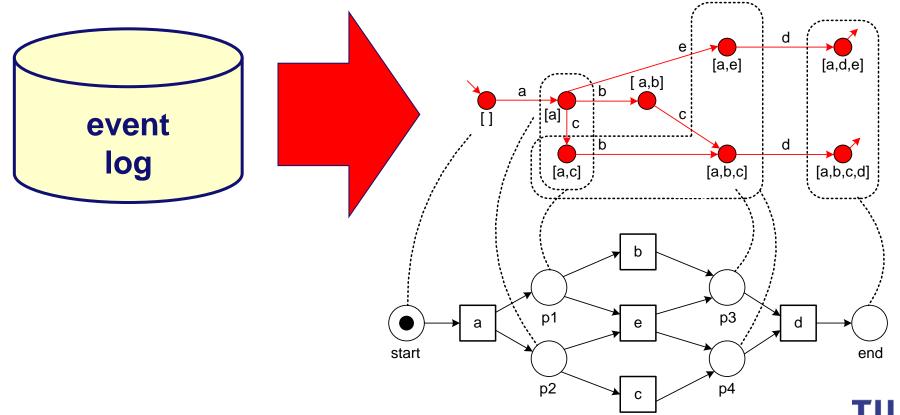
## Second step: State-based regions

It is all about discovering concurrency ...

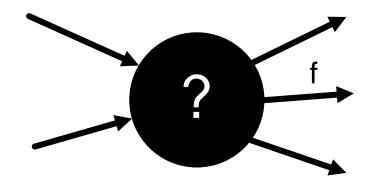




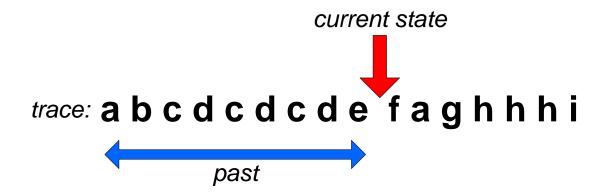
## Today's focus

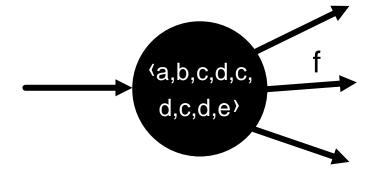


trace: a b c d c d c d e f a g h h h i

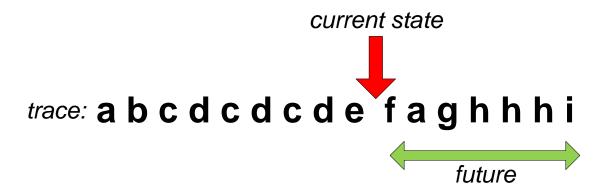


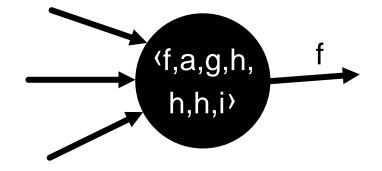




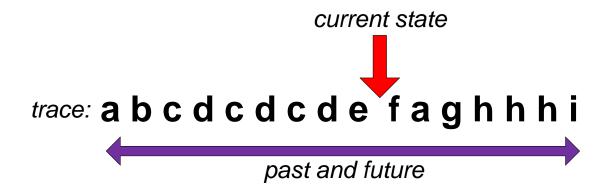


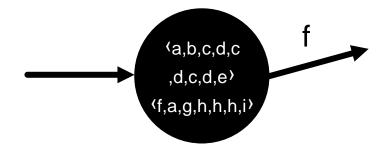




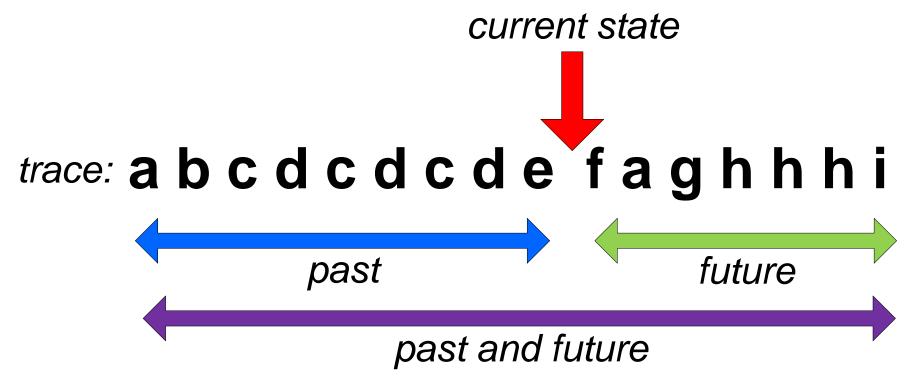














## ction based on past

Sequence tion stion based on current state

resulting transition as current state

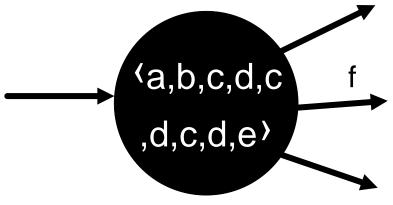
resulting transition as current state

system also known to current state

system also known as the current state

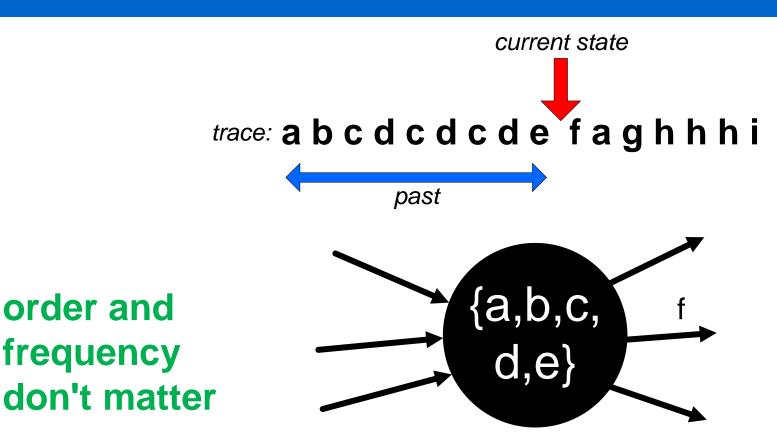
system as the current state stat

order and frequency matter





## Set abstraction based on past

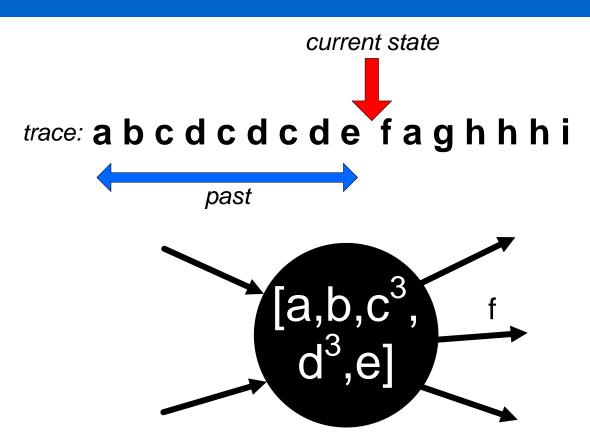




order and

frequency

## Multiset abstraction based on past





only

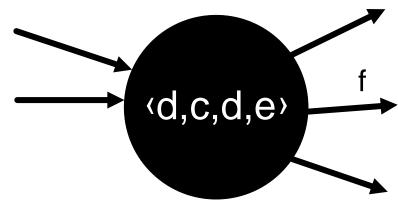
frequency

matters

## Sequence abstraction based on last 4 events



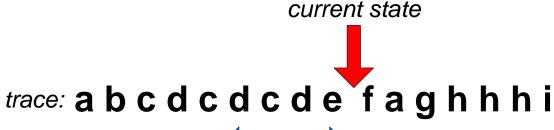




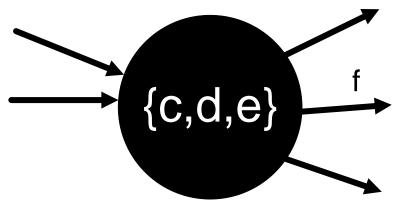




## Set abstraction based on last 4 events

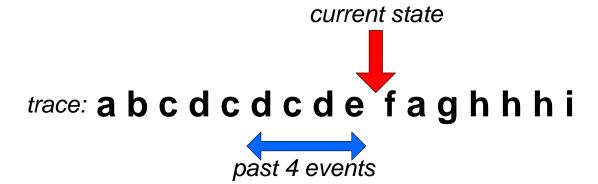


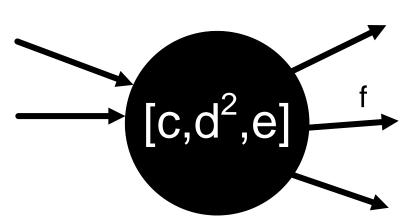






## Multiset abstraction based on last 4 events

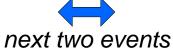


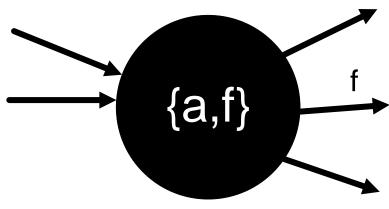




## Set abstraction based on the next 2 events

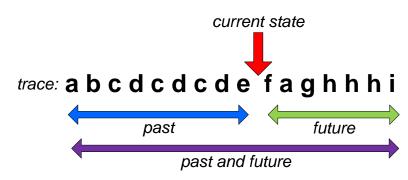








## **Summary**



- Position in trace determines the current state.
- State based on past, future, or past+future.
- Sequence, multiset, set abstraction.
- Limited horizon to abstract further (e.g., k-tail).

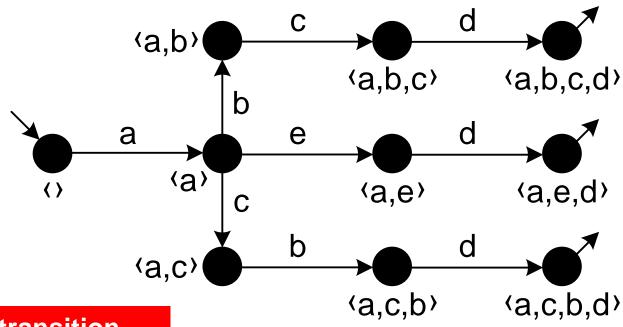


## **Example**

$$L_1 = [\langle a, b, c, d \rangle^3, \langle a, c, b, d \rangle^2, \langle a, e, d \rangle]$$



#### Past without abstraction

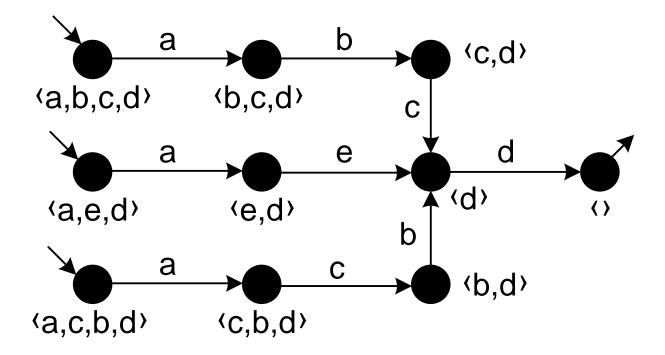


resulting transition system also known as the "prefix automaton"

 $L_1 = [\langle a,b,c,d \rangle^3, \langle a,c,b,d \rangle^2, \langle a,e,d \rangle]$  TU/e

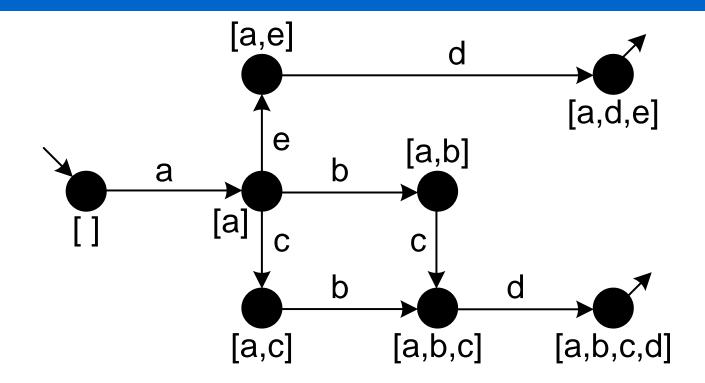


#### **Future without abstraction**



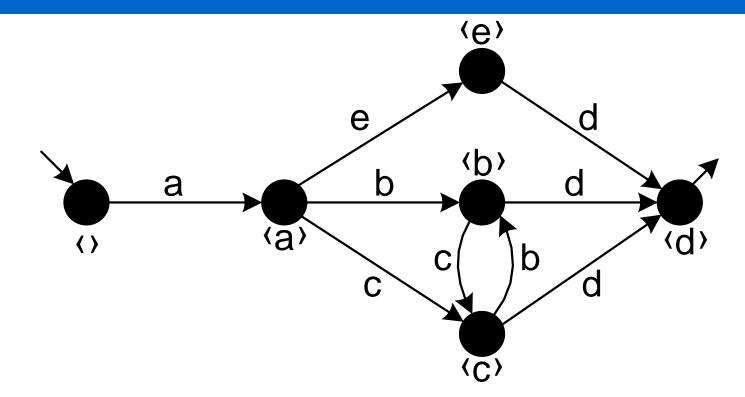


#### Past with multiset abstraction



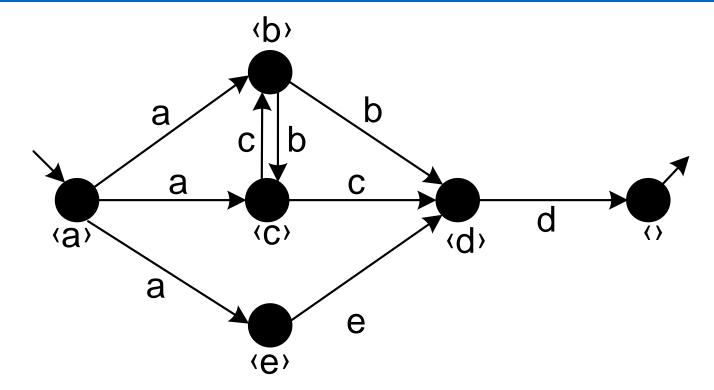


### Only last event matters for state





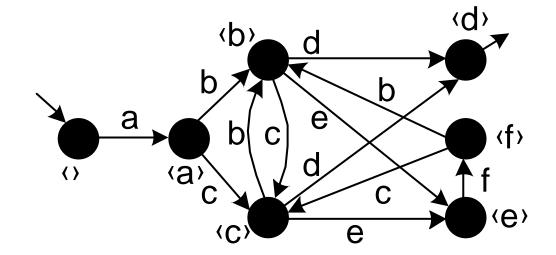
### Only next event matters for state





## Question: What kind of abstraction was used?

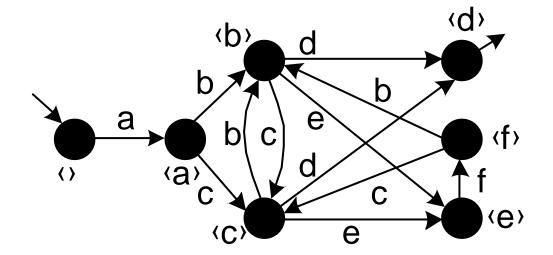
$$L_2 = [\langle a, b, c, d \rangle^3, \langle a, c, b, d \rangle^4, \langle a, b, c, e, f, b, c, d \rangle^2, \langle a, b, c, e, f, c, b, d \rangle, \langle a, c, b, e, f, b, c, d \rangle^2, \langle a, c, b, e, f, b, c, e, f, c, b, d \rangle]$$





## **Answer:**Only last event matters

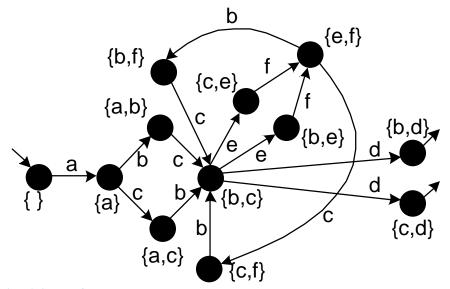
$$L_2 = [\langle a, b, c, d \rangle^3, \langle a, c, b, d \rangle^4, \langle a, b, c, e, f, b, c, d \rangle^2, \langle a, b, c, e, f, c, b, d \rangle, \langle a, c, b, e, f, b, c, d \rangle^2, \langle a, c, b, e, f, b, c, e, f, c, b, d \rangle]$$





## Question: What kind of abstraction was used?

$$L_2 = [\langle a, b, c, d \rangle^3, \langle a, c, b, d \rangle^4, \langle a, b, c, e, f, b, c, d \rangle^2, \langle a, b, c, e, f, c, b, d \rangle, \langle a, c, b, e, f, b, c, d \rangle^2, \langle a, c, b, e, f, b, c, e, f, c, b, d \rangle]$$

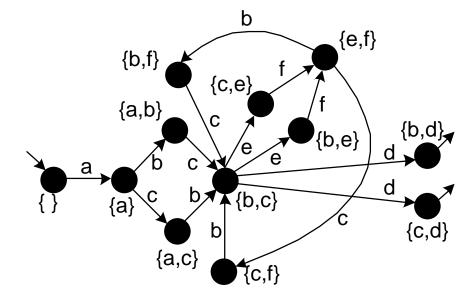




## Answer: Only last two events matters (set abstraction)

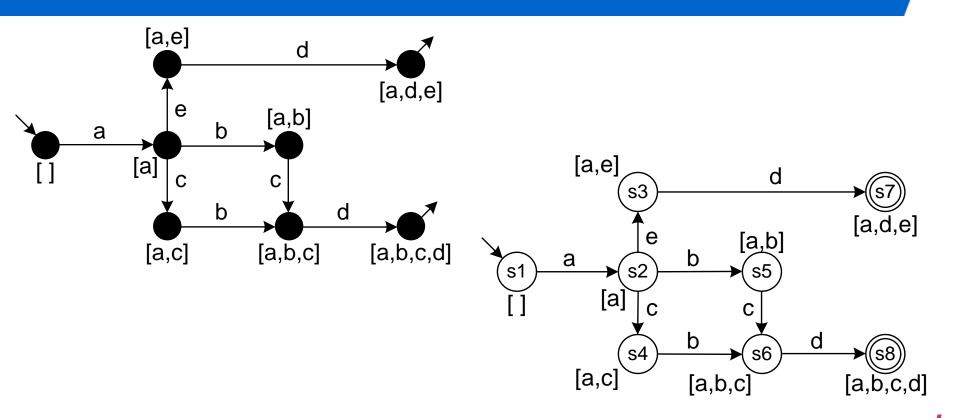
$$L_2 = [\langle a, b, c, d \rangle^3, \langle a, c, b, d \rangle^4, \langle a, b, c, e, f, b, c, d \rangle^2, \langle a, b, c, e, f, c, b, d \rangle, \langle a, c, b, e, f, b, c, d \rangle^2, \langle a, c, b, e, f, b, c, e, f, c, b, d \rangle]$$

Last two events are considered without looking at the order.





### Remark about notation



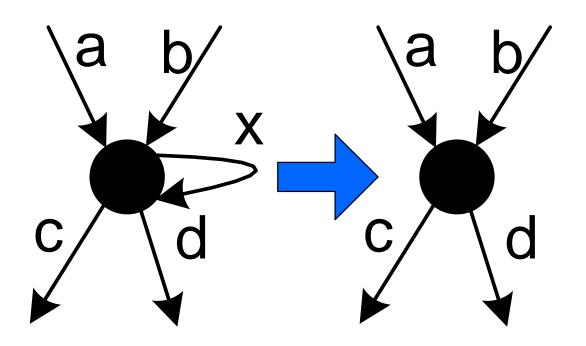


#### **Extensions and variations**

- Events may have other attributes that can be used:
  - States based on resources or data elements rather than activities.
  - Transition names based on resources.
- Filtering of infrequent paths.
- Filtering of infrequent activities.



### Postprocessing of transition system

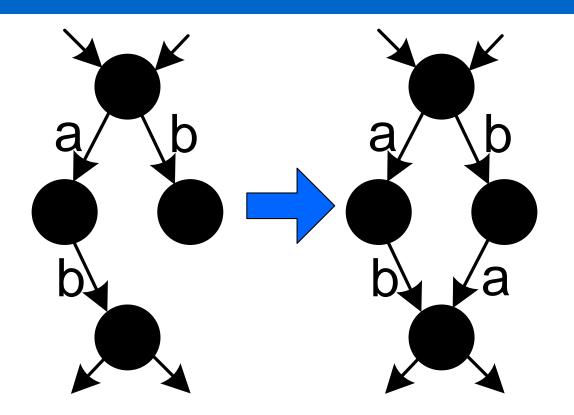


# removing self loops

(will jeopardize fitness)



## Postprocessing of transition system

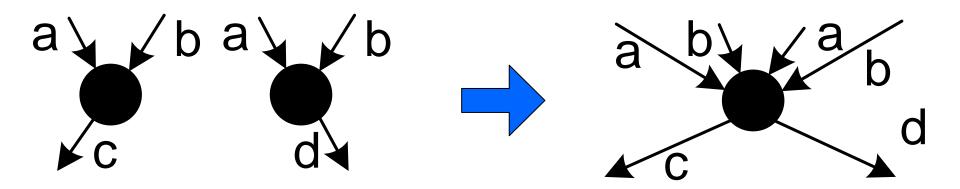


improve diamond structure

(for missing interleavings)



## Postprocessing of transition system

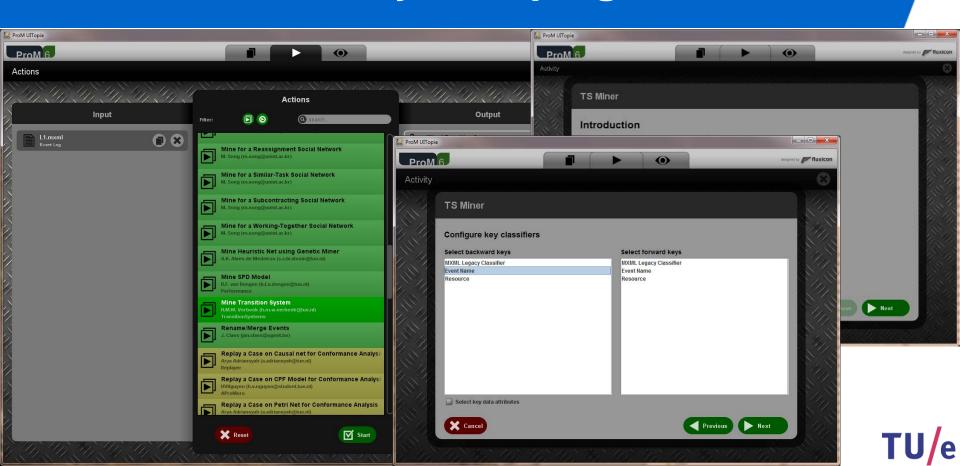


## merge similar states

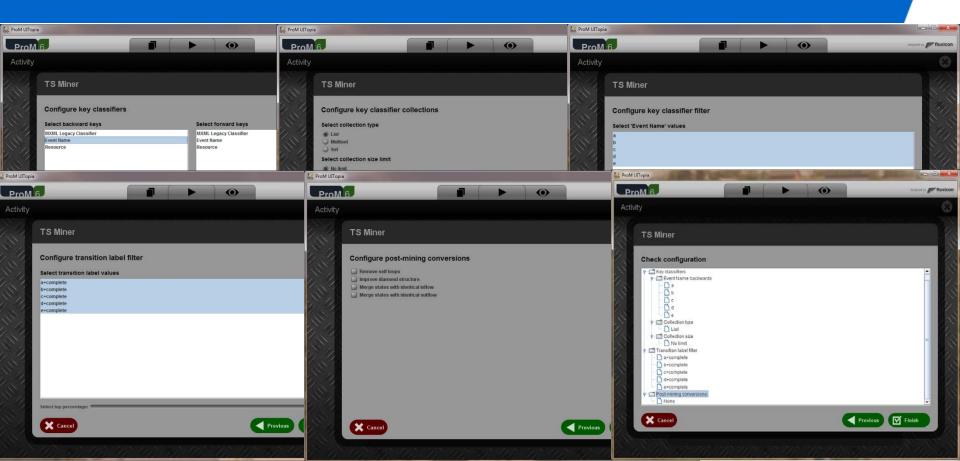
(e.g., based on inputs)



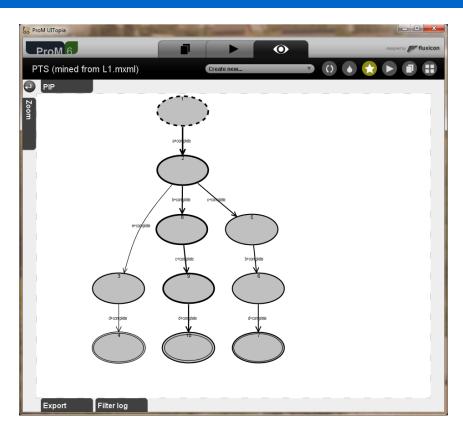
## Mine Transition System plug-in of ProM

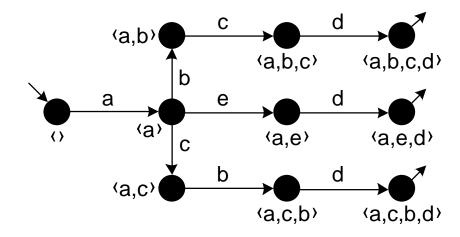


## Highly configurable



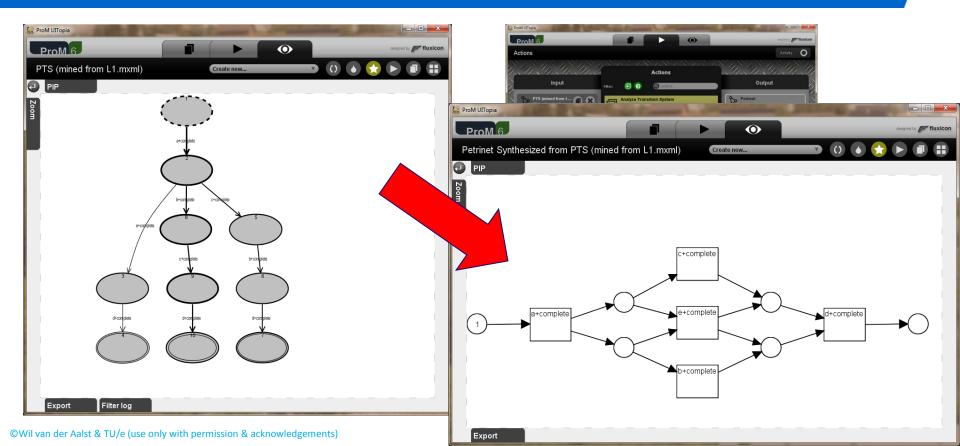
## **Output**







## **Next:** state-based regions



#### Part I: Preliminaries Part III: Beyond Process Discovery Chapter 2 Chapter 3 Chapter 7 Chapter 8 Chapter 1 Chapter 9 Process Modeling and Data Mining Introduction Conformance Mining Additional **Operational Support** Analysis Checking Perspectives Part II: From Event Logs to Process Models Part IV: Putting Process Mining to Work Chapter 10 Chapter 11 Chapter 4 Chapter 5 Chapter 6 Chapter 12 Process Discovery: An Getting the Data Advanced Drags **Tool Support** Analyzing "Lasagna Analyzing "Spaghetti Introduction gues Processes" Processes" Discovery Part V: Reflection Chapter 14 Chapter 13 Cartography and **Epilogue Navigation** Wil M. P. van der Aalst Process Mining

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