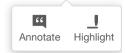
Unit 4.7: Transfer Functions for Circuit Analysis



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The preparatory reading for this section is <u>Chapter 4.4 [Karris, 2012]</u> which discusses transfer function models of electrical circuits. We have also adapted content from <u>3.6 The System Function</u> from [<u>Hsu, 2020</u>].

Follow along at cpjobling.github.io/eg-150-textbook/laplace transform/7/tf for circuits



Agenda

In this unit, we will explore how transfer functions introduced in <u>Unit 4.6: Transfer Functions</u> can be applied to the analysis of circuits.

- Transfer Functions for Circuits
- examples14

```
% Initialize MATLAB
clearvars
cd ../matlab
pwd
format compact
```

ans =

'/Users/eechris/code/src/github.com/cpjobling/eg-150-textbook/laplace_transform/matlab'

Transfer Functions for Circuits

When doing circuit analysis with components defined in the complex frequency domain, the ratio of the output voltage $V_{\rm out}(s)$ to the input voltage $V_{\rm in}(s)$ under zero initial conditions is of great interest.

This ratio is known as the *voltage transfer function* denoted $G_v(s)$:

$$G_v(s) = rac{V_{ ext{out}}(s)}{V_{ ext{in}}(s)}$$

Similarly, the ratio of the output current $I_{\text{out}}(s)$ to the input current $I_{\text{in}}(s)$ under zero initial conditions, is called the current transfer function denoted $G_i(s)$:

$$G_i(s) = rac{I_{ ext{out}}(s)}{I_{ ext{in}}(s)}$$

In practice, the current transfer function is rarely used, so we will use the voltage transfer function denoted:

$$G(s) = rac{V_{ ext{out}}(s)}{V_{ ext{in}}(s)}$$

(examples14)=

Examples 14

We will work through these and demonstrate the MATLAB solutions in class.

Example 14.1

Derive an expression for the transfer function G(s) for the circuit shown in Fig. 67.

In this circuit R_g represents the internal resistance of the applied (voltage) source v_s , and R_L represents the resistance of the load that consists of R_L , L and C.

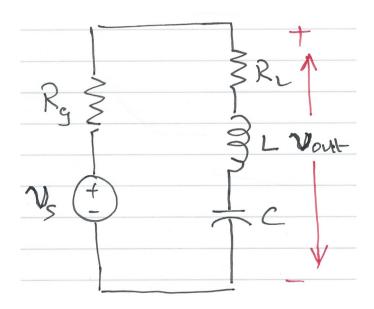


Fig. 67 Circuit for Example 14.1

Sketch of Solution for Example 14.1

- Replace $v_s(t)$, R_g , R_L , L and C by their transformed (complex frequency) equivalents: $V_s(s)$, R_g , R_L , sL and 1/(sC)
- ullet Use the *Voltage Divider Rule* to determine $V_{
 m out}(s)$ as a function of $V_s(s)$
- ullet Form G(s) by writing down the ratio $V_{
 m out}(s)/V_s(s)$

Switch to virtual whiteboard in OneNote.

Solve in OneNote

Worked solution for Example 14.1

Pencast: ex6.pdf - open in Adobe Acrobat Reader.

Answer for Example 14.1

$$G(s) = rac{V_{ ext{out}}(s)}{V_s(s)} = rac{R_L + sL + 1/sC}{R_g + R_L + sL + 1/sC}.$$

Example 14.2

Compute the transfer function for the op-amp circuit shown in Fig. 68 in terms of the circuit constants R_1 , R_2 , R_3 , C_1 and C_2 .

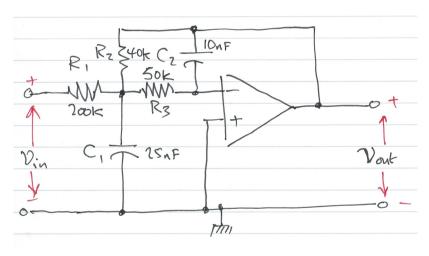


Fig. 68 OpAmp circuit for Example 14.2

Then replace the complex variable s with $j\omega$, and the circuit constants with their numerical values and plot the magnitude

$$|G(j\omega)| = rac{|V_{
m out}(j\omega)|}{|V_{
m in}(j\omega)|}$$

versus radian frequency ω rad/s.

Sketch of Solution for Example 14.2

- Replace the components and voltages in the circuit diagram with their complex frequency equivalents
- Use nodal analysis to determine the voltages at the nodes either side of the 50K resistor $R_{
 m 3}$

Sketch of Solution for Example 14.2 (continued)

- Note that the voltage at the input to the op-amp is a virtual ground
- Solve for $V_{
 m out}(s)$ as a function of $V_{
 m in}(s)$
- ullet Form the reciprocal $G(s) = V_{
 m out}(s)/V_{
 m in}(s)$

Switch to virtual whiteboard in OneNote.



Answer for Example 14.2

$$G(s) = rac{V_{
m out}(s)}{V_{
m in}(s)} = rac{-1}{R_1 \left((1/R_1 + 1/R_2 + 1/R_3 + sC_1) \left(sC_2R_3
ight) + 1/R_2
ight)}.$$
 (41)

Worked solution for Example 14.2

Pencast: <u>ex7.pdf</u> - open in Adobe Acrobat Reader.

Sketch of Solution for Example 14.2 (continued)

- Use MATLAB to calculate the component values, then replace s by $j\omega.$
- Compute $|G(j\omega)|$ and plot on log-linear "paper".

The Matlab Bit

Set up the symbols we will be using. In this case just the Laplace complex frequency s.

```
syms s
```

Now define the values of the components

```
R1 = 200*10^3;

R2 = 40*10^3;

R3 = 50*10^3;

C1 = 25*10^(-9);

C2 = 10*10^(-9);
```

Define the transfer function derived from analysis (Eq. eg:ex14.2)

```
den = R1*((1/R1+ 1/R2 + 1/R3 + s*C1)*(s*R3*C2) + 1/R2)

den =

100*s*((7555786372591433*s)/302231454903657293676544 + 1/20000) + 5
```

Simplify coefficients of s in the denominator. Note sym2poly converts a symbolic polynomial with numerical coefficients into a MATLAB polynomial.

```
format long
denG = sym2poly(den)
```

Now define the denominator

Plot the frequency response

For convenience, define coefficients a and b:

```
a = denG(1);
b = denG(2);
```

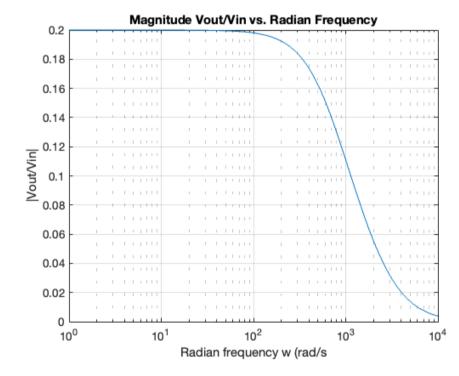
$$G(j\omega) = rac{-1}{a\omega^2 - jb\omega + 5}$$

```
w = 1:10:10000;

Gw = -1./(a*w.^2 - j.*b.*w + denG(3));
```

Plot $|G(j\omega)|$ against ω on log-lin "graph paper".

```
semilogx(w, abs(Gw))
xlabel('Radian frequency w (rad/s')
ylabel('|Vout/Vin|')
title('Magnitude Vout/Vin vs. Radian Frequency')
grid
```



Note that this is a low-pass filter. Sinusoids at low frequencies are passed with a gain of 0.2. For frequencies above around 100 ra/s, the filter starts to reduce the attenuation of the passed signal. At 10,000 rad/s, the attenuation is 1/10 of the attenuation at 1 rad/s.

Summary

In this unit, we will explored how transfer functions introduced in <u>Unit 4.6: Transfer Functions</u> can be applied to the analysis of circuits.

- Transfer Functions for Circuits
- examples14

Take Away

The ratio of the output voltage $V_{\rm out}(s)$ to the input voltage $V_{\rm in}(s)$ under zero initial conditions is of great interest. We call this ratio the *voltage transfer function*

$$G_v(s) = rac{V_{
m out}(s)}{V_{
m in}(s)}$$

We can consider other ratios such as the current transfer function

$$G_i(s) = rac{I_{ ext{out}}(s)}{I_{ ext{in}}(s)}$$

but in practice this is rarely used.

Next time

We explore the facilties provided by other toolboxes in MATLAB, most notably the *Control Systems Toolbox* and the simulation tool Simulink in <u>Unit 4.8: Computer-Aided Systems Analysis and Simulation</u>. We will also look at some of the problems you have studied in **EG-152 Analogue Design** hopefully confirming some of the results you have obbserved in the lab.

• Unit 4.8: Computer-Aided Systems Analysis and Simulation

References

[Hsu20] Hwei P. Hsu. Schaums outlines signals and systems. McGraw-Hill, New York, NY, 2020. ISBN 9780071634724. Available as an eBook. URL: https://www.accessengineeringlibrary.com/content/book/9781260454246.

[Kar12] Steven T. Karris. Signals and systems with MATLAB computing and Simulink modeling.

Orchard Publishing, Fremont, CA., 2012. ISBN 9781934404232. Library call number: TK5102.9

K37 2012. URL: https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action?docID=3384197.

Matlab Solutions

For convenience, single script MATLAB solutions to the examples are provided and can be downloaded from the accompanying MATLAB folder.

• ex:14.2 [<u>example 14.2.mlx</u>]

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