

Phonons in 3D

$$\bar{R}_e = \bar{R}_{n,\alpha} = \bar{R}_n^0 + \bar{R}_\alpha^0 + \bar{u}_{n,\alpha}$$

Instantaneous position of atom $\mathbf{L} = (n, \alpha)$
 unit cell
 basis atom

equilibrium position of unit cell
 equilibrium position of basis pt.
 displacement of atom from equilibrium

Harmonic Approximation:

$$\mathcal{H} = \sum_{n,\alpha} \frac{\bar{P}(n,\alpha)}{2M_\alpha} + \sum_{n,n'} \sum_{\alpha,\alpha'} \sum_{\mu,\mu'} \left(\psi_{n,n'}^{m,m'}(\alpha,\alpha') u^n(n) u^{m'}_{\alpha'}(n') \right)$$

sum over unit cells
 $n=0, \dots, N$
 sum over basis atoms
 $\alpha=1, \dots, N_b$

sum over dimensions
 $\mu=x, y, z$

$\psi_{n,n'}^{m,m'}(\alpha,\alpha')$ → force induced on the (n, α) atom in the m -direction, due to a unit displacement of the (n', α') atom in the m' -direction

→ We can follow the same procedure as before

Once again, we obtain coupled differential equations. Solutions for displacement take the form:

$$u_{\alpha}^M(n,t) = u_{\alpha}^M(n) \frac{1}{\sqrt{M_{\alpha}}} e^{-i\omega t}$$

$$= \frac{E_{\alpha}^M}{\sqrt{M_{\alpha}}} e^{ik \cdot \bar{R}_n} e^{ik \cdot \bar{R}_{\alpha}^o} e^{-i\omega t}$$

geometric phase factor
(depends on position
in lattice)

oscillatory term

- the result is a characteristic eqn defining the Dynamical Matrix:

$$\omega^2 E_{\alpha}^M = \sum_{\alpha', \mu'} D_{\alpha, \alpha'}^{\mu, \mu'} E_{\alpha'}^M \Rightarrow \omega^2 E(k) = D(k) E(k)$$

Dynamical Matrix elements:

$$D_{\alpha, \alpha'}^{\mu, \mu'}(k) = \frac{1}{\sqrt{M_{\alpha} M_{\alpha'}^T}} \sum_{n'} \psi_{\alpha, \alpha'}^{\mu, \mu'}(n, n') e^{i k \cdot (\bar{R}_n^o - \bar{R}_{n'}^o)}$$

$$m = n - n'$$

$$D_{\alpha, \alpha'}^{\mu, \mu'}(k) = \frac{1}{\sqrt{M_{\alpha} M_{\alpha'}^T}} \sum_m \psi_{\alpha, \alpha'}^{\mu, \mu'}(m) e^{i k \cdot \bar{R}_m^o}$$

- Notice now that $\hat{D}(k)$ is a $3N_b \times 3N_b$ matrix
 $\Rightarrow N_b = \# \text{ of atoms in unit cell (in basis)}$
- Evidently, we will have $3N_b$ independent solutions for $\omega^2(k)$, i.e. $3N_b$ phonon branches.
- the terms E_α^m represent the amplitude normalization of the vibration.
- in our general equation: $\omega^2 E(k) = \hat{D}(k) E(k)$:

$$E(k) = (E_1^x, E_1^y, E_1^z, E_2^x, E_2^y, E_2^z, \dots, E_{N_b}^x, E_{N_b}^y, E_{N_b}^z)$$

- For each atom type, α , we can write:

$$\bar{E}_\alpha(k) = (E_\alpha^x, E_\alpha^y, E_\alpha^z)$$

and

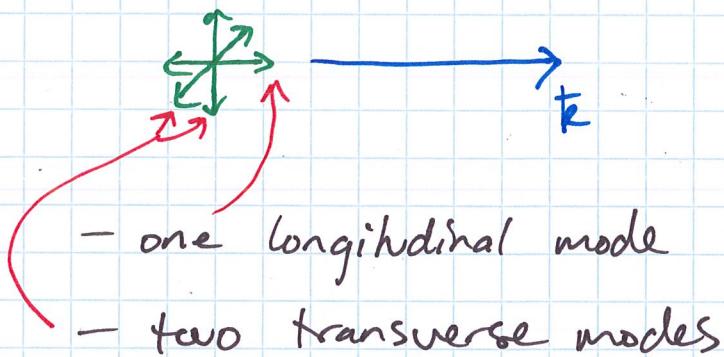
$$\bar{u}_\alpha(n, t) = \frac{\bar{E}_\alpha(k)}{\sqrt{M_\alpha}} e^{i k \cdot (\bar{R}_n + \bar{R}_\alpha) - i \omega t}$$

\hookrightarrow displacement vector

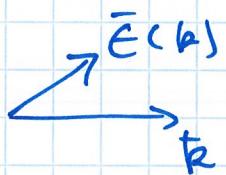
- We see here that $\bar{E}_\alpha(k)$ represents the "direction" of oscillation, i.e. polarization of the vibrational mode

$\bar{E}_\alpha(k) \rightarrow$ polarization vector

In general, in 3D, oscillations can be \parallel or \perp to \vec{k} :



- Polarization vector $\vec{E}(k)$ determines the type of mode
- Although, $\vec{E}(k)$ need not be exclusively transverse or longitudinal:



($2 \cdot T \in L$ form
l.m. indep. basis for solutions.
l.m. comb. of solutions are
also solutions)

- If there are 2 or more atoms in the unit cell, there will be both optical & acoustic modes:

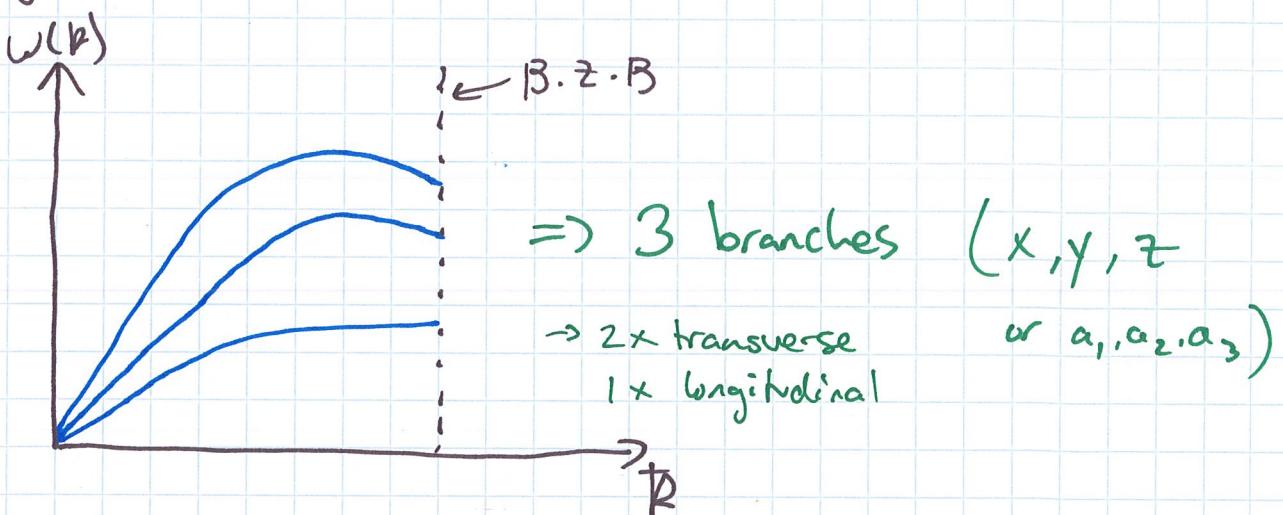
TO : transverse optical

TA : transverse acoustic

LO : longitudinal optical

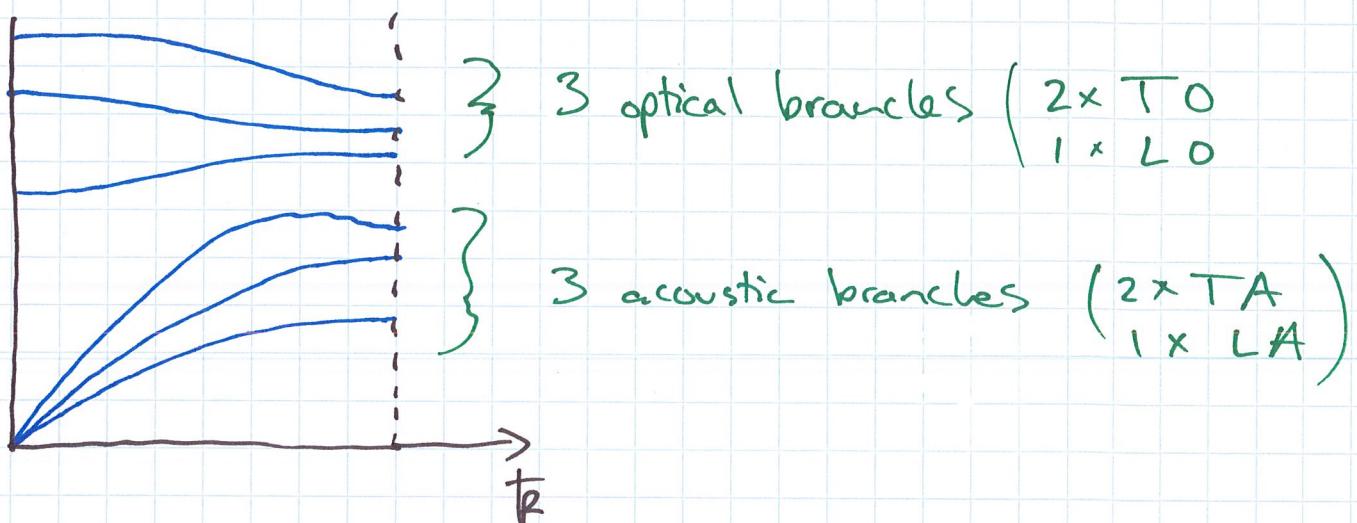
LA : longitudinal acoustic

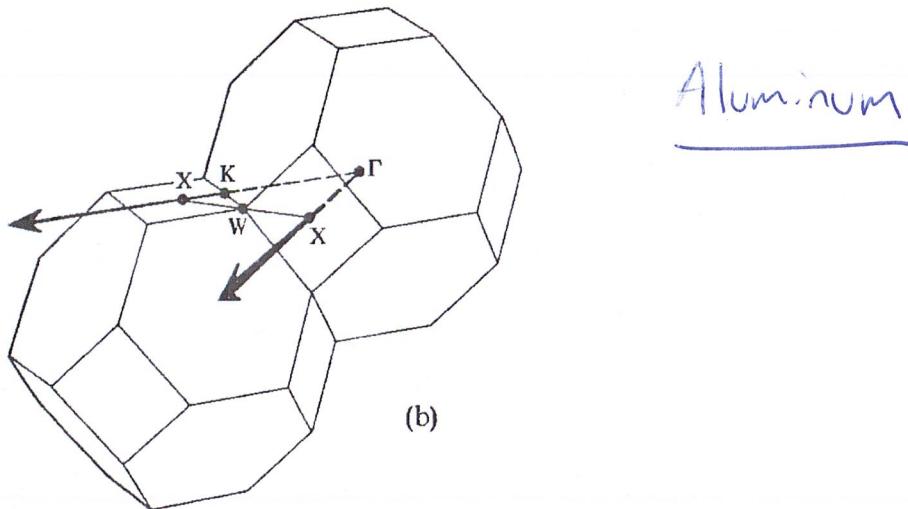
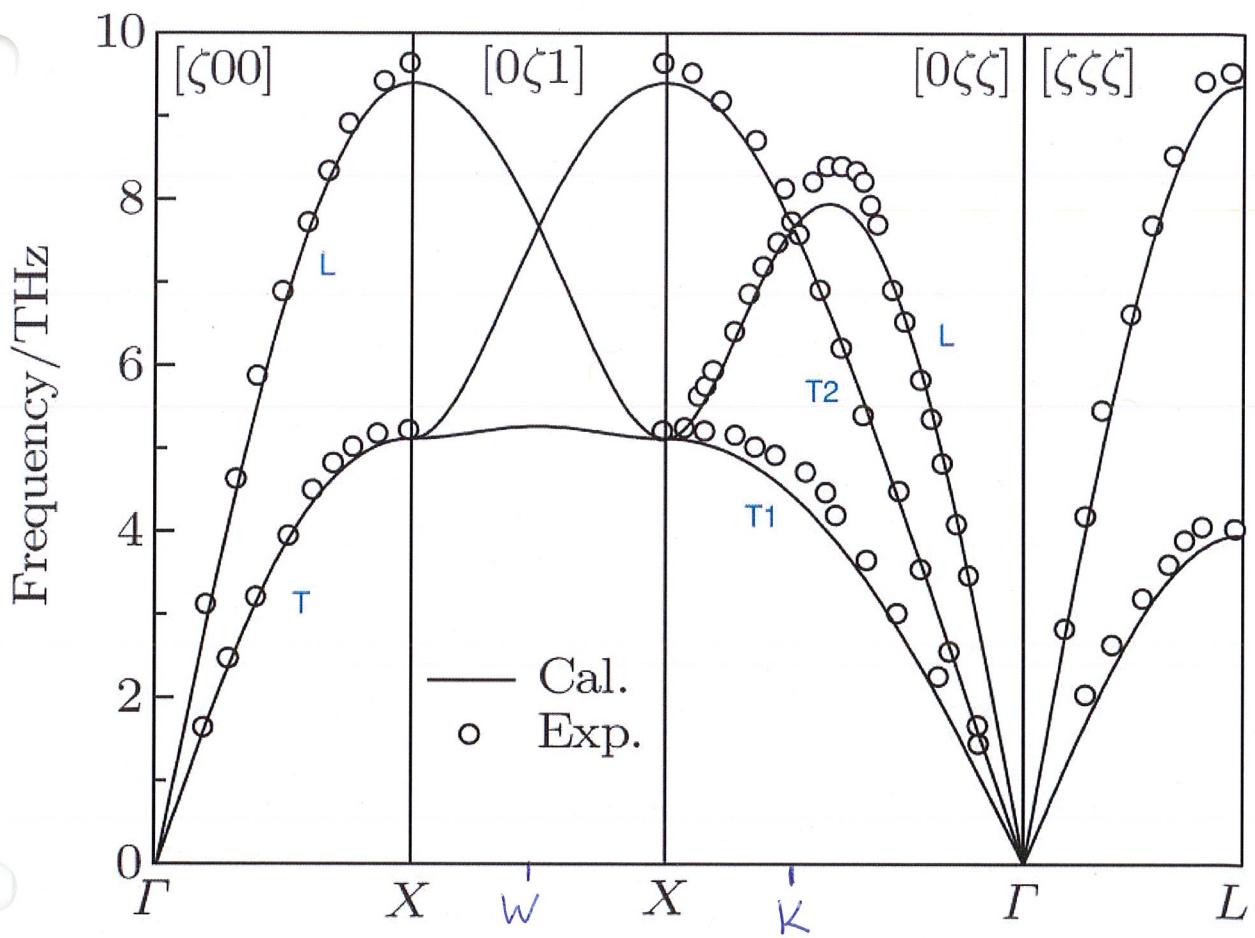
e.g. Monatomic 3D solid

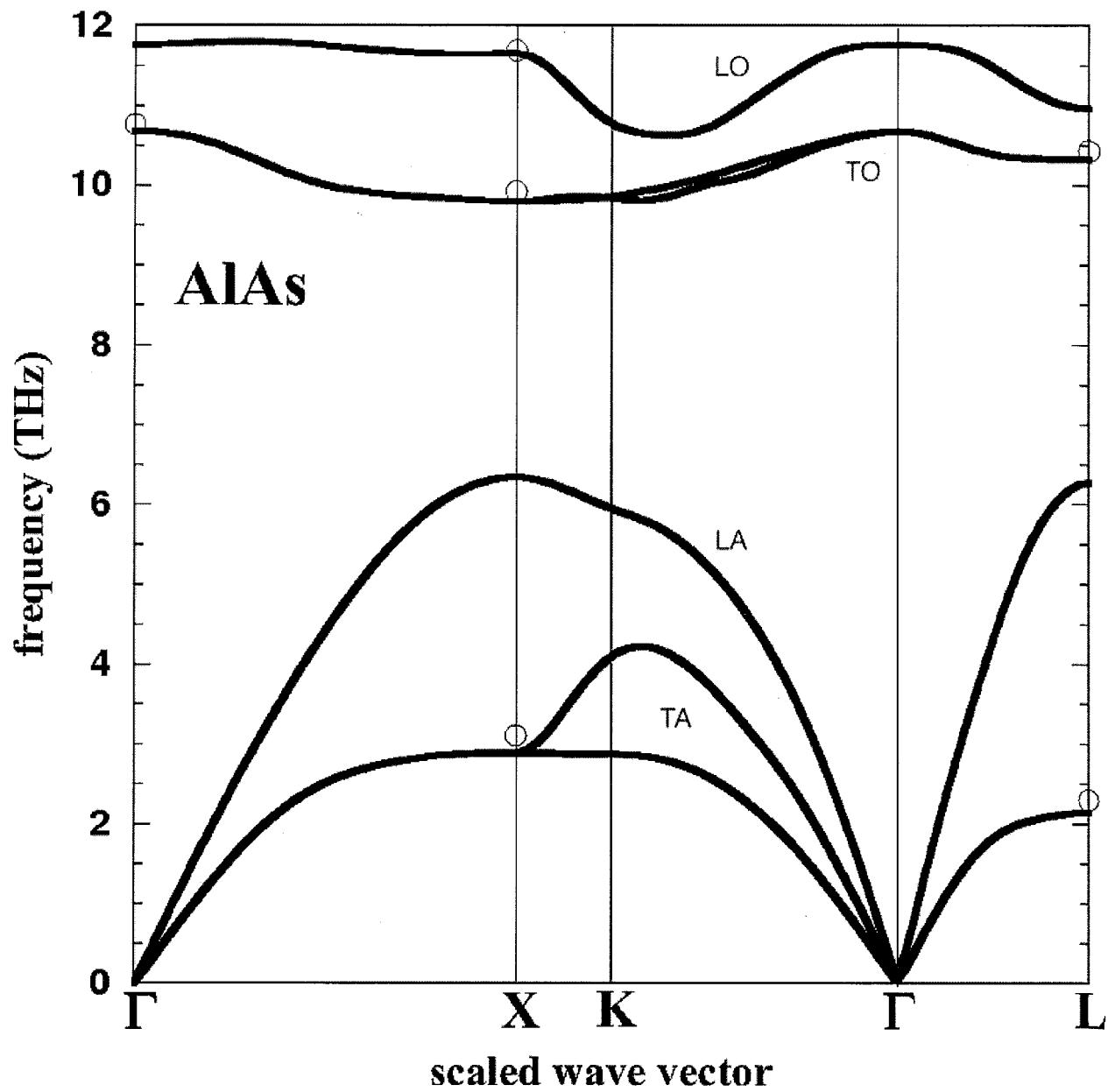


→ of course, depending on the symmetry of the solid, some dispersion curves may be degenerate!

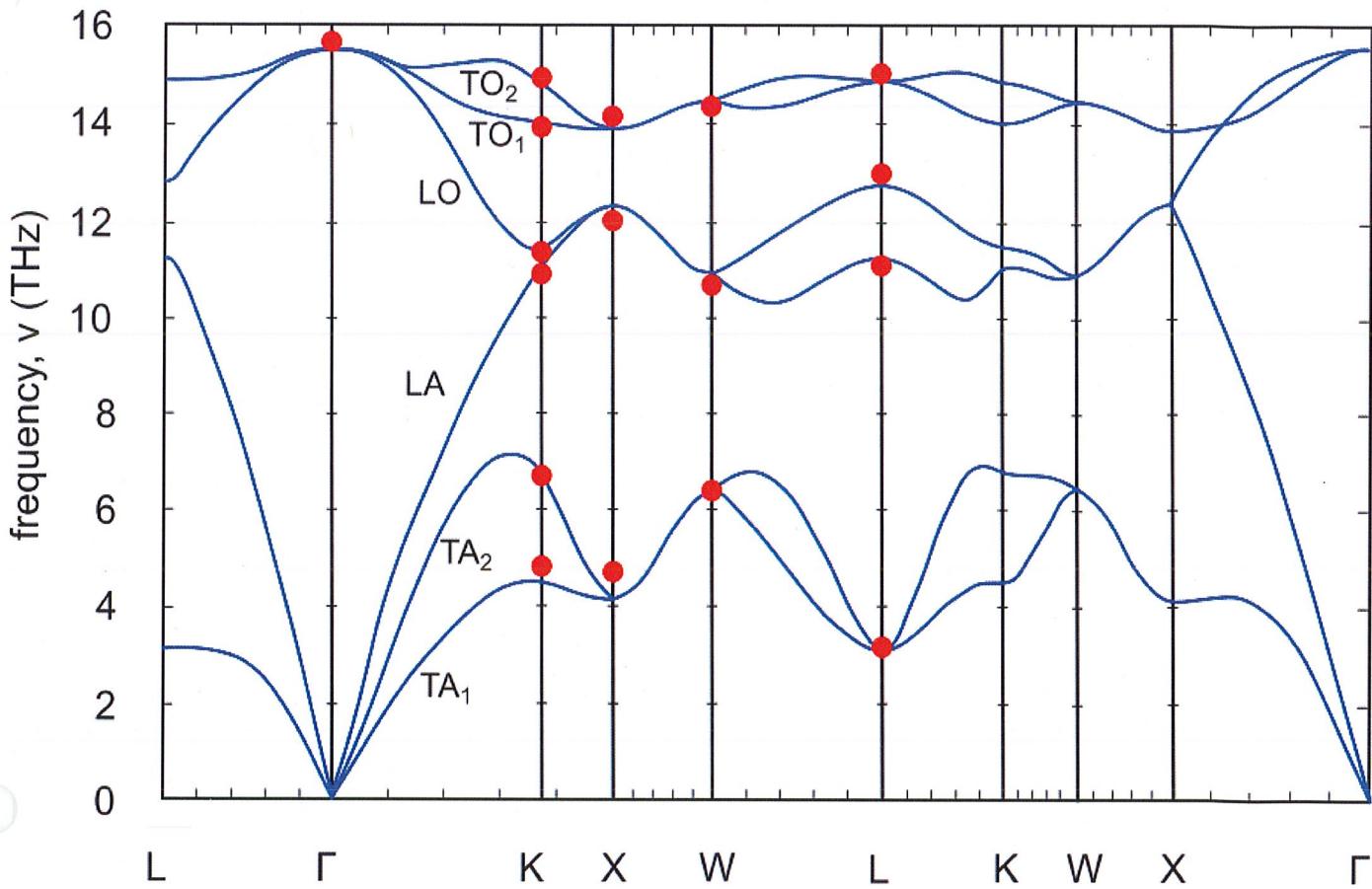
e.g. Diatomic 3D solid



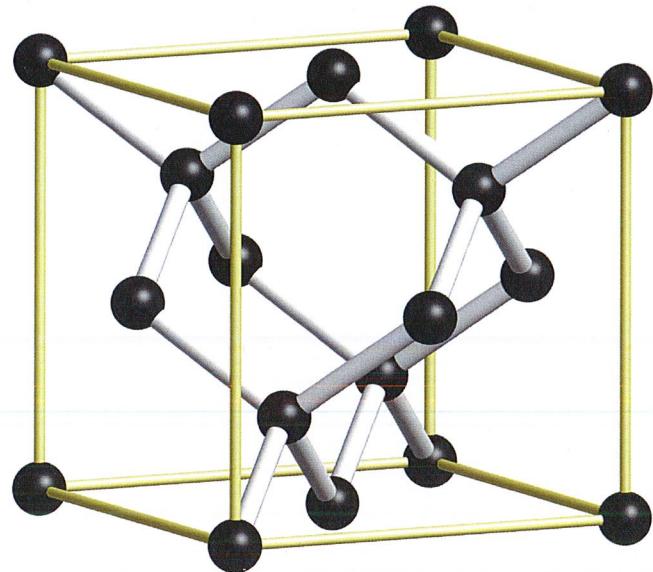




Silicon (crystalline)



FCC structure, 2-atom basis



2-atom basis

→ Masses equal
 $(M_1 = M_2)$

→ Interaction (Force constants)
not equal

