

T09

From Continuous-time to Discrete-time

Interpolation

Sampling theorem

Aliasing

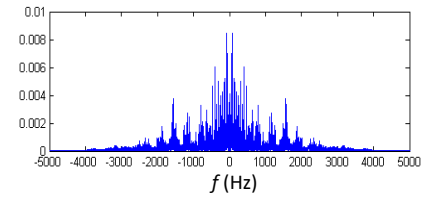
Sampling by gating

Anti-Aliasing Filter

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From Continuous-Time to Discrete-Time

Frequency spectrum of real signal $x(t)$



$$x(t) \rightarrow \left(\sum_{n=-\infty}^{\infty} \delta(t - nT) \right) \rightarrow x_p(t)$$

$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

Question :

- Band-limited signal ?
- Application of sampling ?

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Question : Why is it important to know the sampling frequency ?

reverse know original frequency!

e.g. $x(t) = \cos(2\pi t)$ $\xrightarrow{\text{C/D conversion}}$ $x[n] = \cos\left(\frac{2\pi}{4}n\right) = \cos\left(\frac{\pi}{2}n\right)$

$T = 1 \text{ sec}$

$f_s = 4 \text{ Hz}$

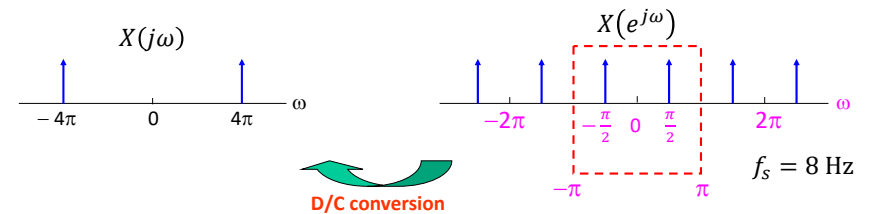
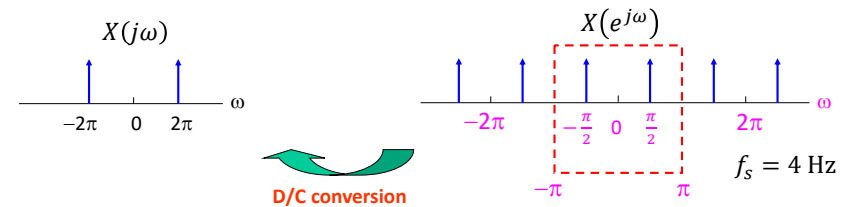
How to tell the difference ?

e.g. $x(t) = \cos(4\pi t)$ $\xrightarrow{\text{C/D conversion}}$ $x[n] = \cos\left(\frac{4\pi}{8}n\right) = \cos\left(\frac{\pi}{2}n\right)$

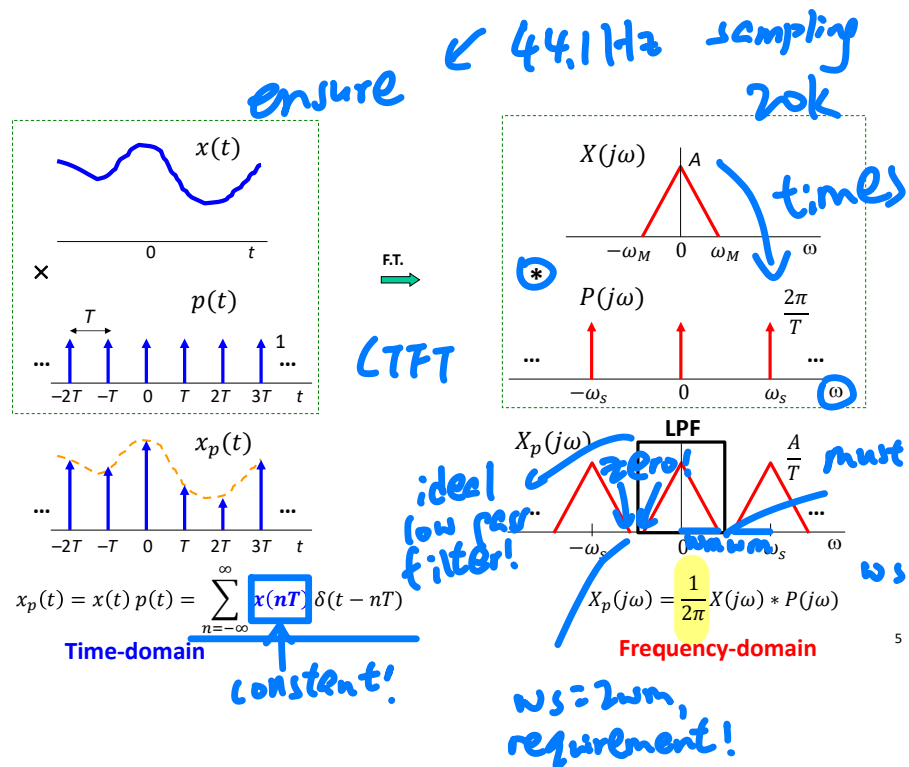
$T = 0.5 \text{ sec}$

$f_s = 8 \text{ Hz}$

3



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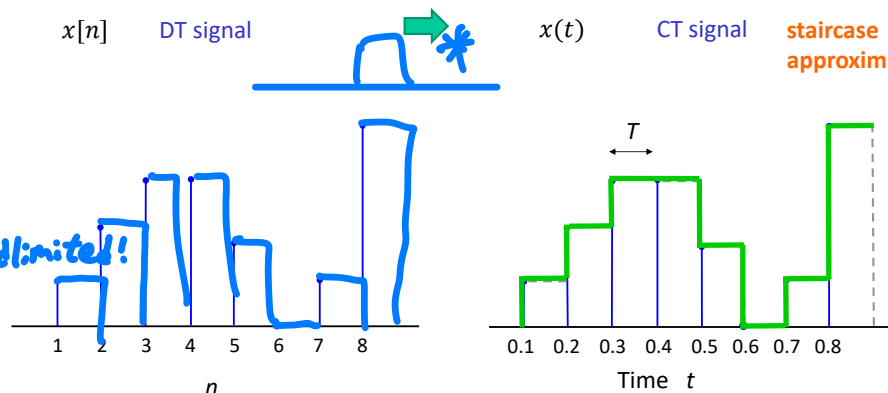
OK, no ideal LPF
sinc function

Interpolation

$x[n]$ DT signal

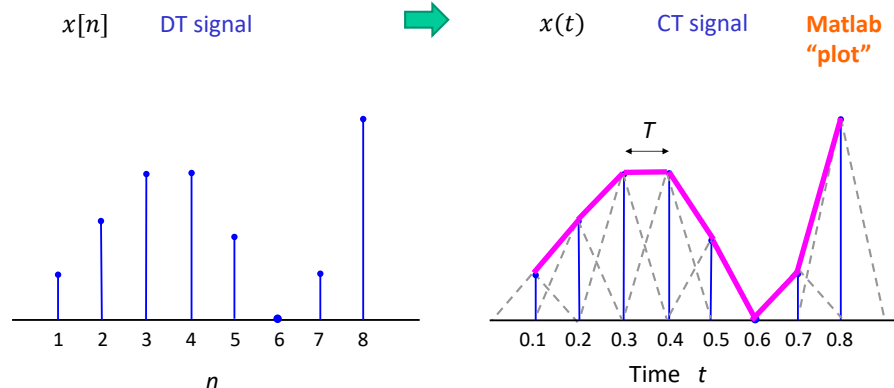
$x(t)$ CT signal

staircase approximation



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choose appropriate fs



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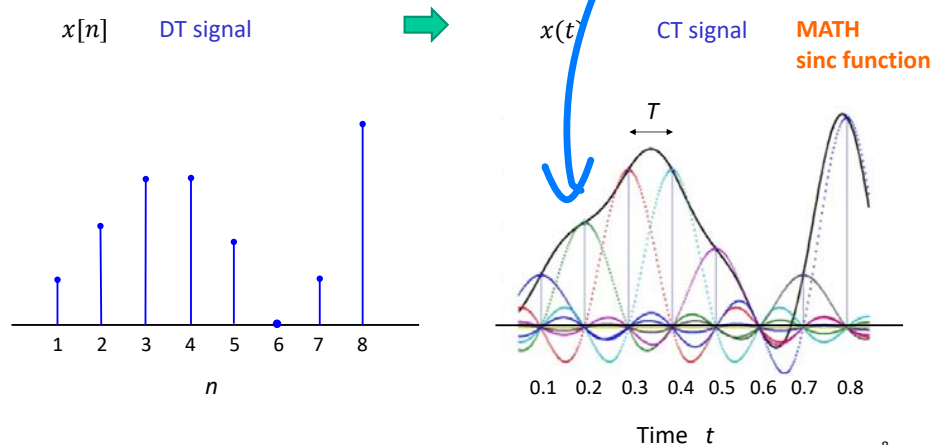
just perfect smooth curve

Question: What is the meaning of using ideal LPF for reconstruction?

$x[n]$ DT signal

$x(t)$ CT signal

MATH sinc function



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Sampling Theorem

The minimum sampling frequency

$$\omega_s > 2\omega_M$$

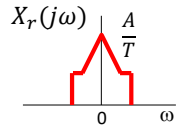
Nyquist rate :

?

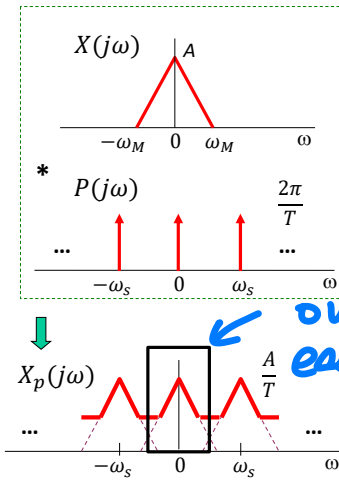
Aliasing

- Distortion

- $\omega_s < 2\omega_M$



LPF



Aliasing

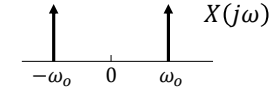
$\omega_s \downarrow$, time duration \uparrow

Question : Actually meaning?

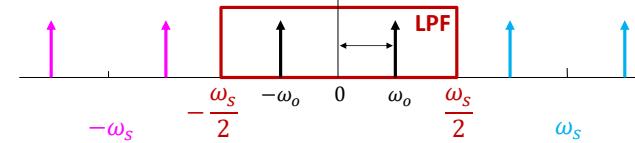
e.g.

$$x(t) = \cos(\omega_o t)$$

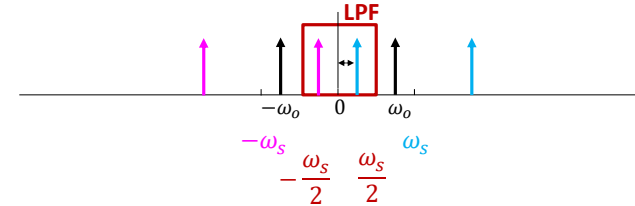
F.T.



a) What is the perceived output frequency if $\omega_s > 2\omega_o$?



b) What is the perceived output frequency if $\omega_s < 2\omega_o$?



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Different CT signals with different actual signal frequencies shown below

2.2	3.8	4.2	5.8	-1.8	(Hz)
4.4\pi	7.6\pi	8.4\pi	11.6\pi	-3.6\pi	(rad/s)

CT

If the sampling frequency = 2 Hz

DT angular frequency = CT actual angular frequency (in rad/s) / sampling frequency (in Hz)

$$2\pi + 0.2\pi \quad 4\pi - 0.2\pi \quad 4\pi + 0.2\pi \quad 6\pi - 0.2\pi \quad -2\pi + 0.2\pi$$

$$\begin{aligned} \cos(2\pi n + 0.2\pi n) &= \cos(0.2\pi n) \\ \cos(4\pi n - 0.2\pi n) &= \cos(0.2\pi n) \\ \cos(4\pi n + 0.2\pi n) &= \cos(0.2\pi n) \\ \cos(6\pi n - 0.2\pi n) &= \cos(0.2\pi n) \\ \cos(-2\pi n + 0.2\pi n) &= \cos(0.2\pi n) \end{aligned}$$

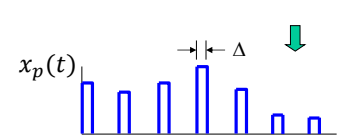
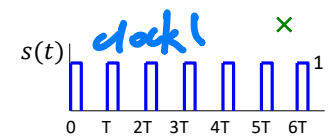
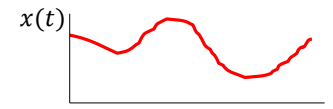
$$\cos(A + B) = \cos(A)\cos(B) - \sin(A)\sin(B)$$

D/C conversion \rightarrow $\cos(0.4\pi t)$

wrong!

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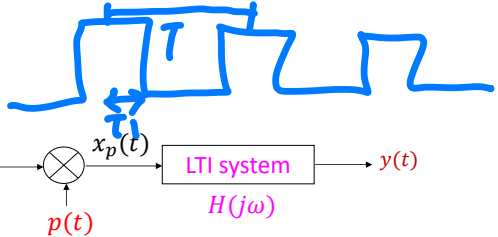
Sampling by Gating



pulse train!
因为 delta function 高度 \infty, 不可 model!

Question : The spectrum of the sampled signal $x_p(t)$?

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e.g.
Bandlimited signal
with unilateral bandwidth of
10 kHz

Period square wave with
 $T_1 = 5 \mu s$ and $T = 20 \mu s$

modulation!

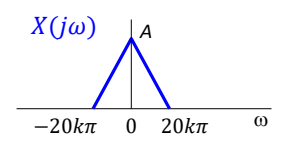
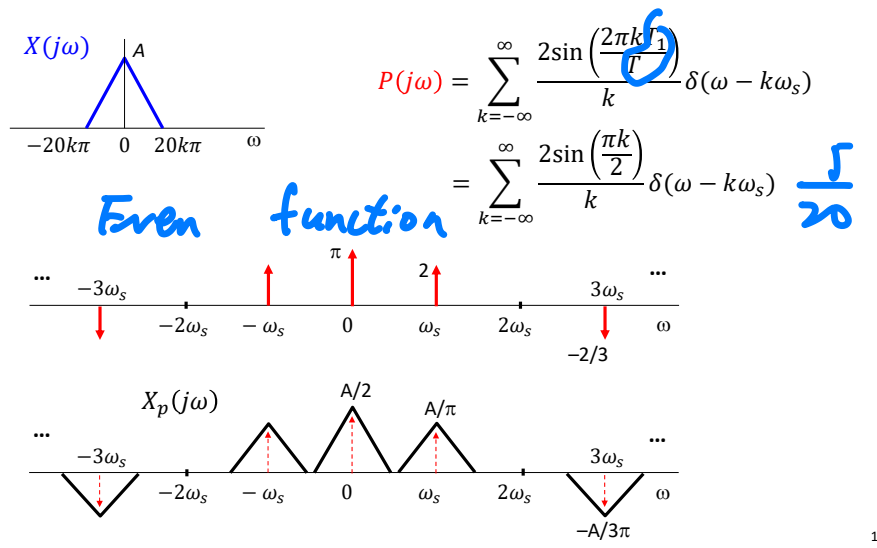
- a) Sketch the spectrum of $x_p(t)$.
- b) Specify this LTI system if $y(t) = 2 x(t) \cos(1 \times 10^5 \pi t)$.
- c) Design a system to reconstruct $x(t)$ using $y(t)$.

$$x_p(t) = x(t) p(t)$$

$$X_p(j\omega) = \frac{1}{2\pi} X(j\omega) * P(j\omega)$$

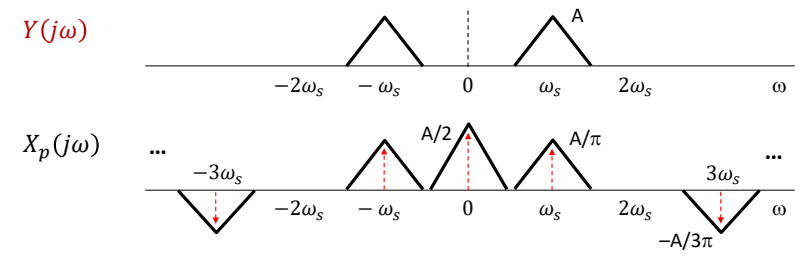
$$\omega_s = \frac{2\pi}{20 \times 10^{-6}} = 10^5 \pi$$

$$Y(j\omega) = X_p(j\omega) H(j\omega)$$

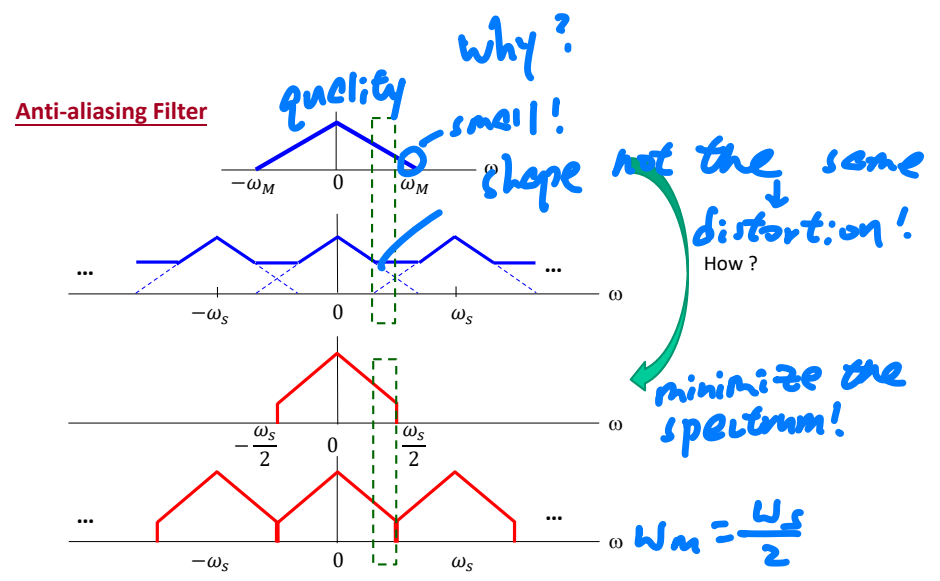


$$y(t) = 2 x(t) \cos(1 \times 10^5 \pi t)$$

$$Y(j\omega) = X(j(\omega - \omega_s)) + X(j(\omega + \omega_s))$$



**?
bandpass, gain = π!**



Question : How to minimize aliasing (e.g. moire effect) if $\omega_s < 2\omega_M$?