

T02

DT unit impulse and unit step

CT unit impulse

Sampling property and Sifting property

CT complex exponential (Damped oscillation) and complex sinusoid

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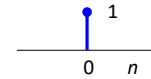
Input-Output relationship

- Memoryless
- Invertibility
- Causality
- Stability
- Time-invariant
- Linearity

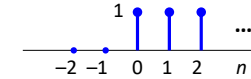
1

DT Unit Impulse and Unit Step

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$



$$u[n] = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$

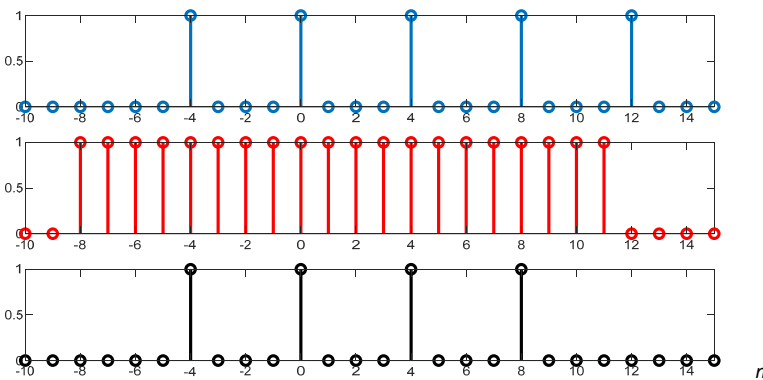


$$\delta[n] = u[n] - u[n-1]$$

$$u[n] = \sum_{k=0}^{\infty} \delta[n-k] = \sum_{m=-\infty}^n \delta[m]$$

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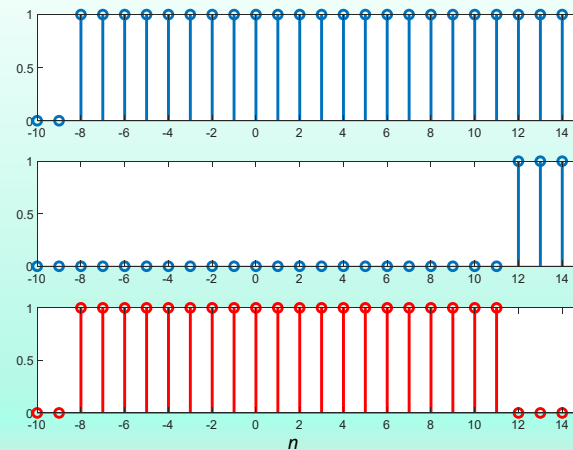
e.g. Sketch $x[n] = \left(\sum_{k=-1}^3 \delta[n-4k] \right) (u[n+8] - u[n-12])$



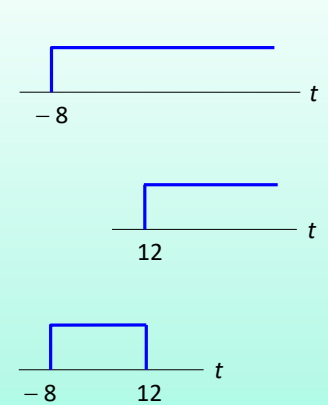
Question : Represent $x[n]$ as a sum of impulses ?

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DT
 $u[n+8] - u[n-12]$



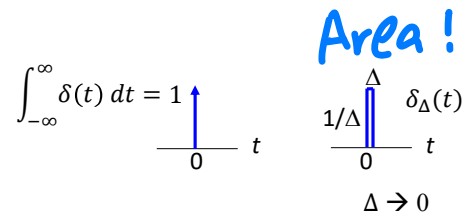
CT
 $u(t+8) - u(t-12)$



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CT Unit Impulse

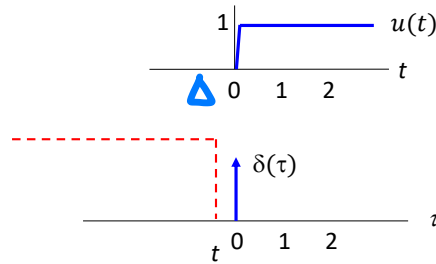
$$\delta(t) = 0 \text{ for } t \neq 0$$



Relationship between $u(t)$ and $\delta(t)$

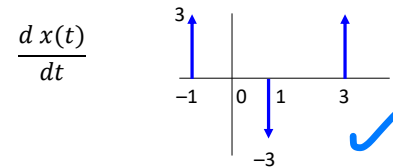
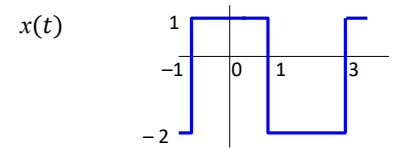
$$\delta(t) = \frac{d}{dt} u(t)$$

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau$$



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e.g.



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e.g. $x(t) = \int_t^\infty 3\delta(\tau - 2) d\tau$

a) Plot $x(t)$

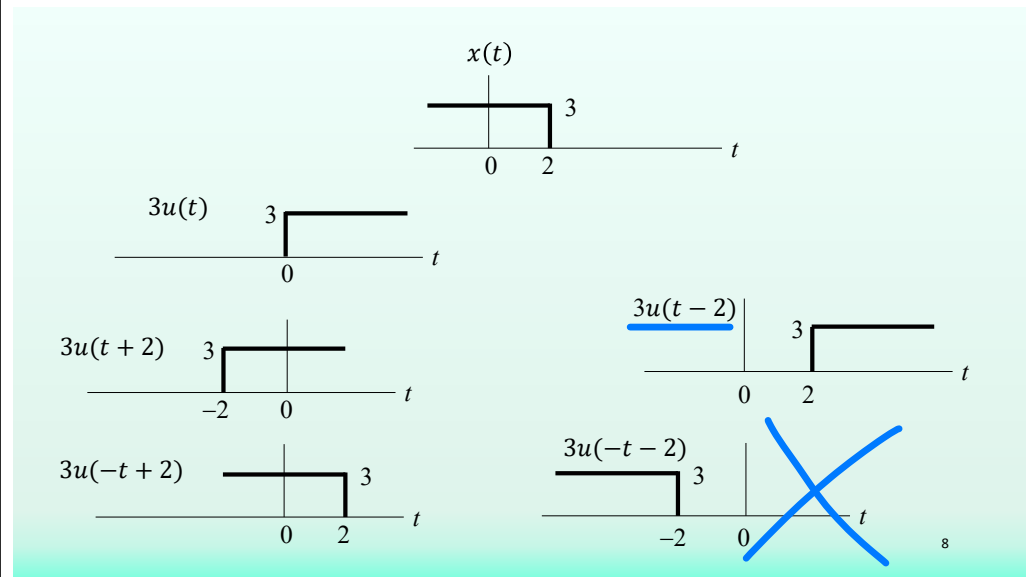


b) Which of the following expressions is correct ?

$$x(t) = 3u(-t + 2)$$

$$x(t) = 3u(-t - 2)$$

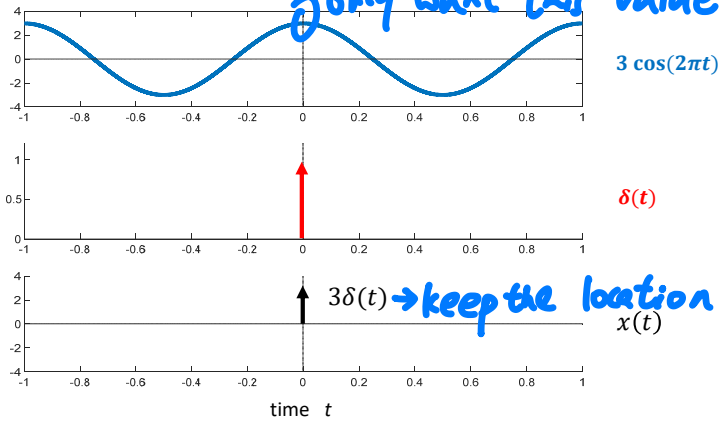
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Sampling Property

e.g. Plot $x(t) = 3 \cos(2\pi t) \delta(t)$

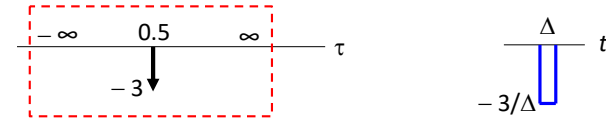


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Sifting Property

e.g. Find $\int_{-\infty}^{\infty} 3 \cos(2\pi\tau) \delta(\tau - 0.5) d\tau$

$$\int_{-\infty}^{\infty} 3 \cos(2\pi\tau) \delta(\tau - 0.5) d\tau = \int_{-\infty}^{\infty} -3 \delta(\tau - 0.5) d\tau = -3$$



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CT Complex Exponential

$$e^{st} \quad s = \sigma + j\omega$$

$$e^{(\sigma+j\omega)t} = e^{\sigma t} e^{j\omega t} = e^{\sigma t} \cos(\omega t) + j e^{\sigma t} \sin(\omega t)$$

Exponential form

Rectangular form

$$|e^{(\sigma+j\omega)t}| = e^{\sigma t}$$

$$\text{Re}\{e^{(\sigma+j\omega)t}\} = e^{\sigma t} \cos(\omega t)$$

$$\angle e^{(\sigma+j\omega)t} = \omega t$$

$$\text{Im}\{e^{(\sigma+j\omega)t}\} = e^{\sigma t} \sin(\omega t)$$

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e.g. $e^{st} \quad s = \sigma + j\omega$

$$x_1(t) = e^{(-0.2+j)t}$$

$$x_2(t) = e^{(0.2-j)t + j\frac{\pi}{2}}$$

st initial phase shift!

Question : What is the complex frequency s ?

$$e^{-0.2t} e^{j\frac{\pi}{2}}$$

$$e^{0.2t} e^{j(-t + \frac{\pi}{2})}$$

e.g. Sketch the following signals.

$$x_3(t) = \text{Re}\{x_1(t)\} u(t)$$

$$x_4(t) = \text{Im}\{x_2(t)\} u(-t)$$

$$= e^{-0.2t} \cos(t) u(t)$$

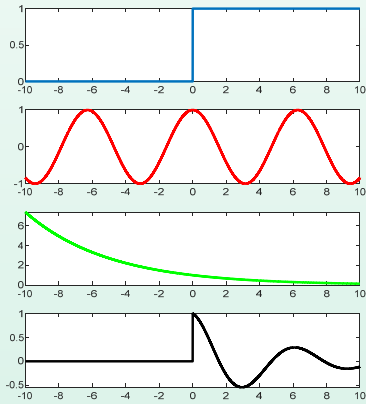
$$= e^{0.2t} \sin\left(-t + \frac{\pi}{2}\right) u(-t)$$

Question :

- Decaying or growing damped oscillation?
- Left-sided or right-sided ?

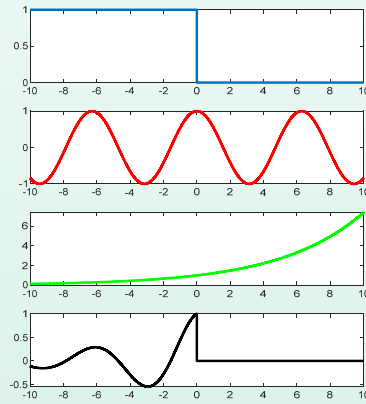
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$$x_3(t) = e^{-0.2t} \cos(t) u(t)$$



Time (sec)

$$x_4(t) = e^{0.2t} \sin\left(-t + \frac{\pi}{2}\right) u(-t)$$



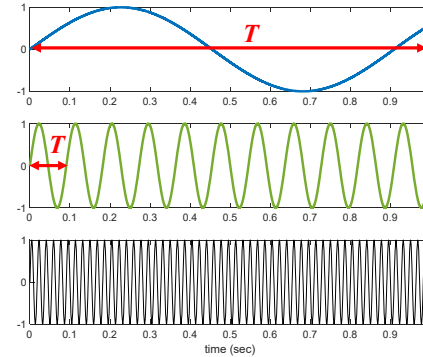
Time (sec)

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CT Complex Sinusoid

$e^{j\omega t} = \cos(\omega t) + j \sin(\omega t)$
 - Different ω
 → Different waveform

The imaginary part of $e^{j\omega_0 t}$ is plotted below



Question : How many distinct CT complex sinusoids ?

$0 \sim \infty$

$$\omega = \frac{2\pi}{T}$$

$$\omega = \frac{22\pi}{10} = \frac{2\pi}{10/11}$$

$$\omega = 22\pi = \frac{2\pi}{1/11}$$

$$\omega = 110\pi = \frac{2\pi}{1/55}$$

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Difference between complex exponential and complex sinusoid ?

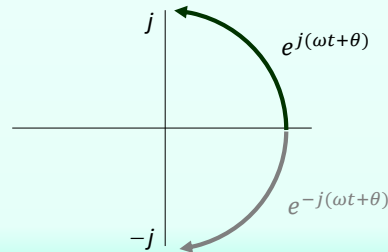
$$e^{\sigma t} e^{j\omega t} = e^{\sigma t} \cos(\omega t) + j e^{\sigma t} \sin(\omega t)$$

$$A e^{j\omega t} = A \cos(\omega t) + j A \sin(\omega t)$$

$$A e^{j(\omega t + \theta)} = A \cos(\omega t + \theta) + j A \sin(\omega t + \theta)$$

$$A \sin(\omega t + \theta) = \frac{A}{2} e^{j(\omega t + \theta)} + \frac{A}{2} e^{-j(\omega t + \theta)}$$

$$A \sin(\omega t + \theta) = \frac{A}{2j} e^{j(\omega t + \theta)} - \frac{A}{2j} e^{-j(\omega t + \theta)}$$



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DT Complex Exponential

$$z^n = e^s = e^{\sigma + j\omega} = e^{\sigma} e^{j\omega} = |z| e^{j\angle z}$$

$$\text{e.g. } x_1[n] = 0.8^n e^{j\frac{2\pi}{5}n}$$

$$x_2[n] = 2^n e^{j\frac{2\pi}{5}n}$$

$$a^n b^n = (ab)^n$$

$$= \left(0.8 e^{j\frac{2\pi}{5}}\right)^n$$

$$= \left(2 e^{j\frac{2\pi}{5}}\right)^n$$

Question : What is the complex frequency z ?

e.g. Sketch the following two signals.

$$x_3[n] = \text{Re}\{x_1[n]\} u[n]$$

$$x_4[n] = \text{Im}\{x_2[n]\} u[-n]$$

$$= 0.8^n \cos\left(\frac{2\pi}{5}n\right) u[n]$$

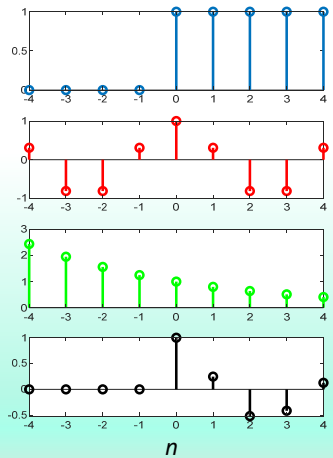
$$= 2^n \sin\left(\frac{2\pi}{5}n\right) u[-n]$$

Question :

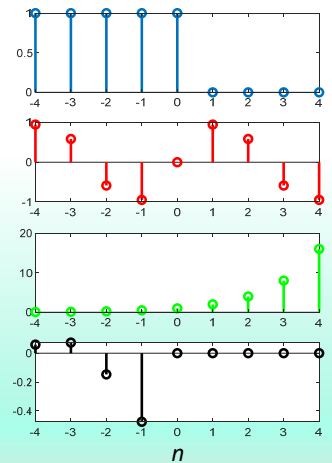
- Decaying or growing damped oscillation?
- Left-sided or right-sided ?

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$$x_1[n] = 0.8^n \cos\left(\frac{2\pi}{5}n\right) u[n]$$



$$x_2[n] = 2^n \sin\left(\frac{2\pi}{5}n\right) u[-n]$$



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DT Complex Sinusoid $e^{j\omega n}$

$$e^{j\omega n} = \cos(\omega n) + j \sin(\omega n)$$

$$\omega = \frac{2\pi m}{N} \quad \text{where } m \text{ and } N \text{ are integers}$$

Question : Difference between CT complex sinusoid and DT complex sinusoid ?

$$e^{j\frac{22\pi}{10}t} = ?$$

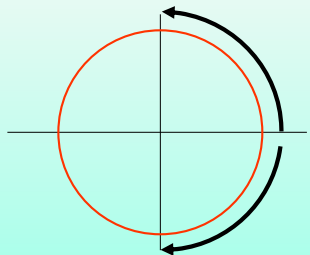
$$e^{j\frac{22\pi}{10}n} = ?$$



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$$e^{j\frac{22\pi}{10}t} = e^{j\frac{20\pi}{10}t} e^{j\frac{2\pi}{10}t} = e^{j2\pi t} e^{j\frac{2\pi}{10}t} = e^{j\frac{22\pi}{10}t}$$

$$e^{j\frac{22\pi}{10}n} = e^{j\frac{20\pi}{10}n} e^{j\frac{2\pi}{10}n} = e^{j2\pi n} e^{j\frac{2\pi}{10}n} = e^{j\frac{2\pi}{10}n}$$



$$e^{j2\pi(0.9)n} = e^{j2\pi(1.9)n} = e^{j2\pi(-0.1)n}$$

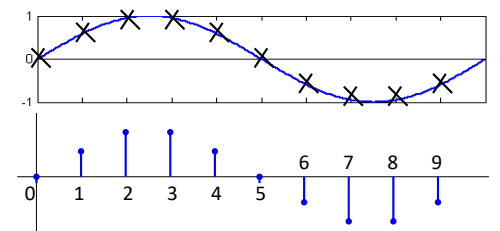
$$e^{j2\pi(1.9)n} = e^{j2\pi(1+0.9)n} = e^{j2\pi n} e^{j2\pi(0.9)n}$$

$$e^{j2\pi(-0.1)n} = e^{j2\pi(0.9-1)n} = e^{-j2\pi n} e^{j2\pi(0.9)n}$$

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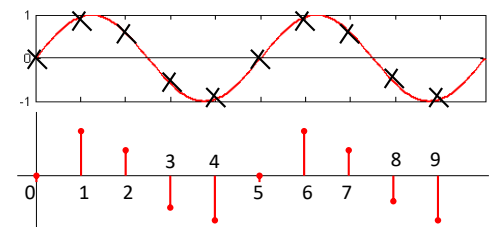
The imaginary part of $e^{j\omega n}$ is plotted below.

CT → DT



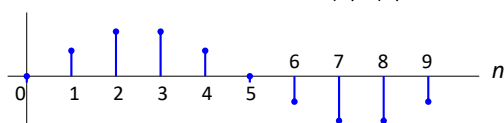
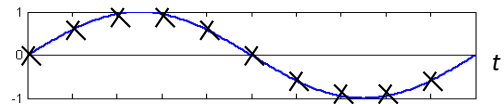
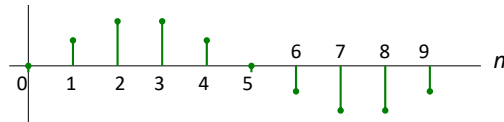
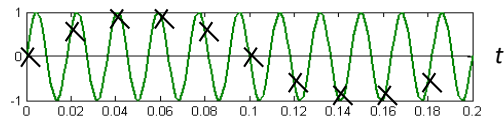
$$\omega = \frac{2\pi(1)}{10}$$

Meaning of m ?



$$\omega = \frac{2\pi(2)}{10}$$

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$$\omega = \frac{2\pi(11)}{10}$$

Same sequence !

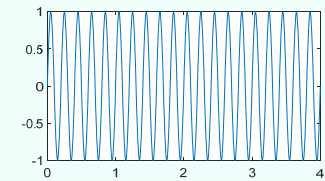
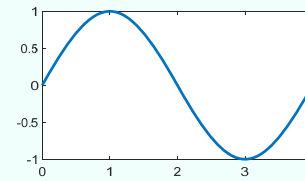
$$e^{j\frac{2\pi}{10}n} = e^{j\frac{2\pi(11)}{10}n}$$

$$\omega = \frac{2\pi}{10}$$

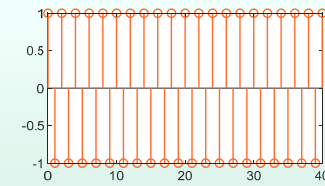
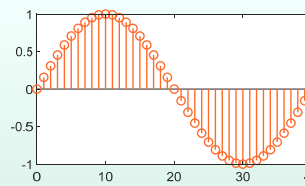
Question : How many distinct DT complex sinusoids if $N = 10$?

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Question : The highest fundamental angular frequency for CT complex sinusoid ?



Question : The highest fundamental angular frequency for DT complex sinusoid ?

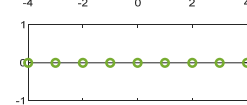
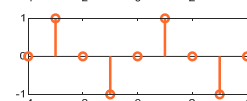
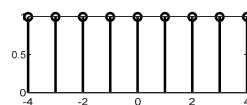
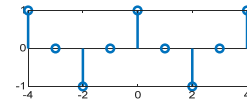
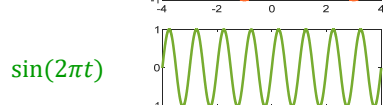
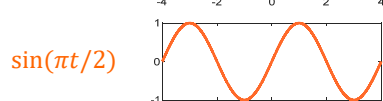
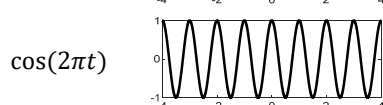
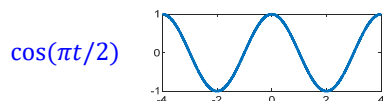


$$\frac{2\pi}{N} \lambda$$

$$N \geq 2(\text{minimum})$$

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e.g. Sketch the following CT and DT signals.



$$\cos(\pi n/2)$$

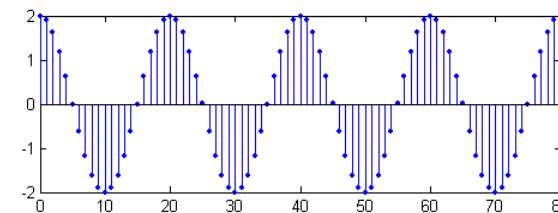
$$\cos(2\pi n)$$

$$\sin(\pi n/2)$$

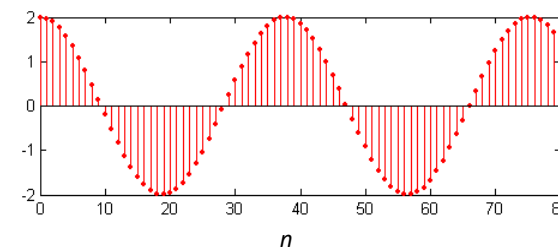
$$\sin(2\pi n)$$

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e.g. Periodic ? Fundamental period N ?



$$x_1[n] = 2 \cos\left(\frac{2\pi}{20}n\right)$$



$$x_2[n] = 2 \cos\left(\frac{\pi}{6}n\right)$$

$$N = 12 \lambda$$

$$\lambda \text{ integer}$$

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e.g. Match the following signals with Figure 1, Figure 2 and Figure 3.

$$x_1[n] = \text{Re} \left\{ (0.8 e^{j\frac{2\pi}{5}})^n \right\}$$

2

$$x_2[n] = \text{Re} \{ e^{j\frac{2\pi}{5}n} \}$$

3

$$x_3[n] = \text{Re} \{ e^{j\frac{2}{5}n} \}$$

1 non-periodic!

Figure 1

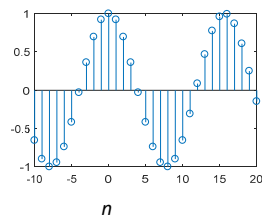


Figure 2

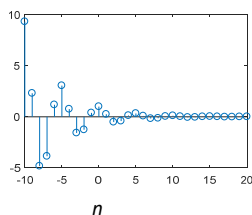
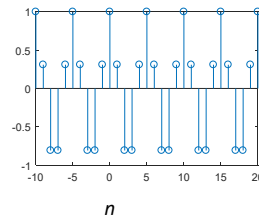


Figure 3



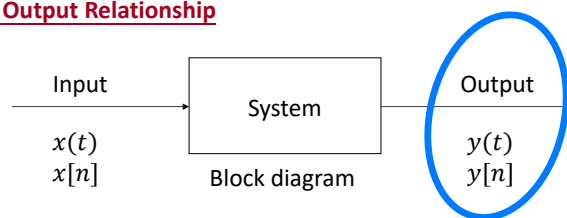
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Input-Output relationship

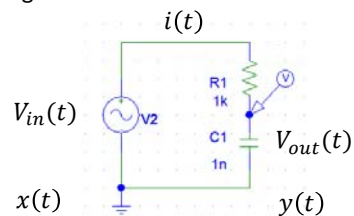
- Memoryless
- Invertibility
- Causality
- Stability
- Time-invariant
- Linearity

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Input and Output Relationship



e.g.



$$i(t) = C \frac{d}{dt} V_{out}(t)$$

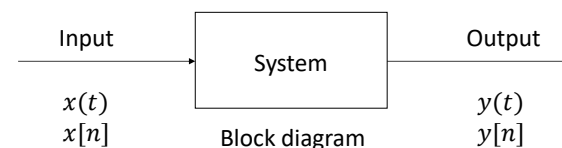
$$V_{in}(t) = V_R(t) + V_{out}(t) = i(t)R + V_{out}(t)$$

$$= RC \frac{d}{dt} V_{out}(t) + V_{out}(t)$$

$$x(t) = RC \frac{d}{dt} y(t) + y(t)$$

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System



System Properties



Input-Output Relationship

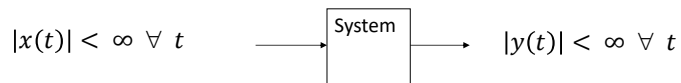
Memoryless The output only depends on the current input

Causality The output does not depend on the future input

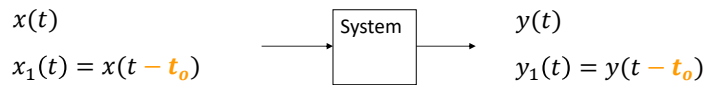
Invertibility Distinct inputs leads to distinct outputs
(i.e. One-to-one mapping)

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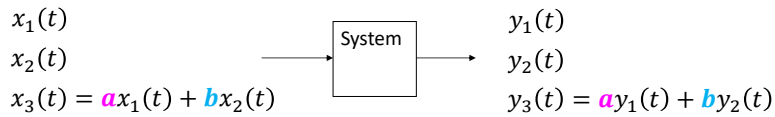
Stability Bounded input results in bounded output (**BIBO**)



Time-invariant The behavior of a system **does not** change over time



Linearity Superposition and Scaling (**zero-input zero-output**)



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Plug a positive and negative

e.g. $y(t) = \cos(x(t)) + 1$

$y(t) = Ev\{x(t)\}$

Memoryless ?

Memoryless ?

Causal ?

Causal ?

Invertible ?

Invertible ?

Stable ?

Stable ?

Time-invariant ?

Time-invariant ?

Linear ?

Linear ?

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e.g. $y(t) = \cos(x(t)) + 1$

Memoryless ? ✓

Causal ? ✓

Stable ? ✓

Time-invariant ? ✓

$$y(1) = \cos(x(1)) + 1$$

$$y(-1) = \cos(x(-1)) + 1$$

What does this system do ?

Linear ?

$$y_3(t) = \cos(x_3(t)) + 1 = \cos(ax_1(t) + bx_2(t)) + 1$$

$$x_3(t) = ax_1(t) + bx_2(t)$$

$$\neq ay_1(t) + by_2(t)$$

If it is true, $y_3(t) = ay_1(t) + by_2(t) = a \cos(x_1(t)) + 1 + b \cos(x_2(t)) + 1$

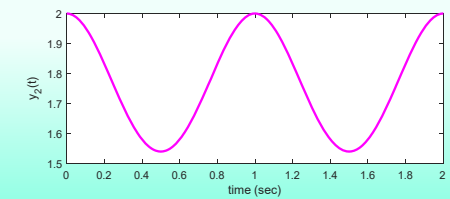
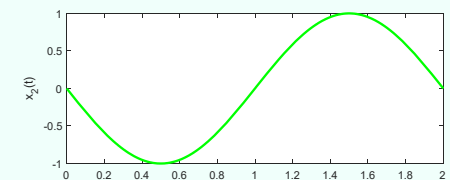
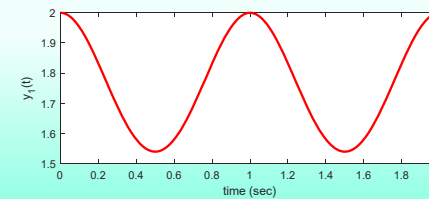
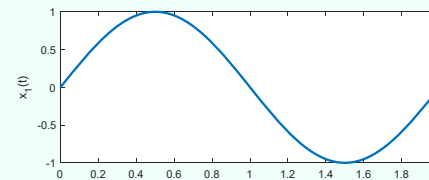
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Invertible ?



$$\cos(-\theta) = \cos(\theta)$$

$$y(t) = \cos(x(t)) + 1$$



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e.g. $y(t) = Ev\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$

Memoryless ? ~~X~~

Causal ? ~~X~~

Invertible ? ~~X~~

Stable ? ✓

Linear ? ✓

$x_3(t) = ax_1(t) + bx_2(t)$

$y(1) = \frac{1}{2}[x(1) + x(-1)]$

$y(-1) = \frac{1}{2}[x(-1) + x(1)]$

What does this system do ?

$y_3(t) = \frac{1}{2}[ax_1(t) + bx_2(t) + ax_1(-t) + bx_2(-t)]$

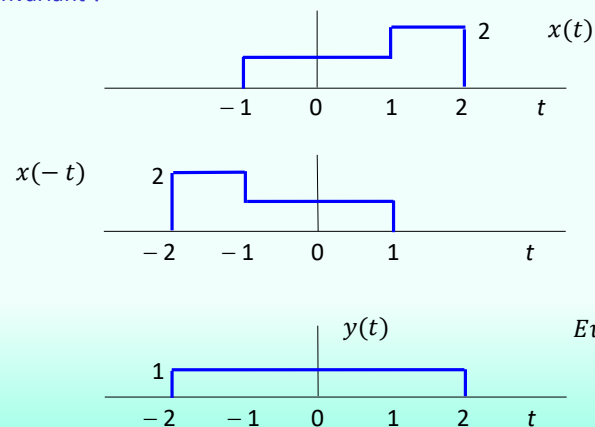
$= ay_1(t) + by_2(t)$

If it is true, $y_3(t) = ay_1(t) + by_2(t) = \frac{a}{2}[x_1(t) + x_1(-t)] + \frac{b}{2}[x_2(t) + x_2(-t)]$

← past input!

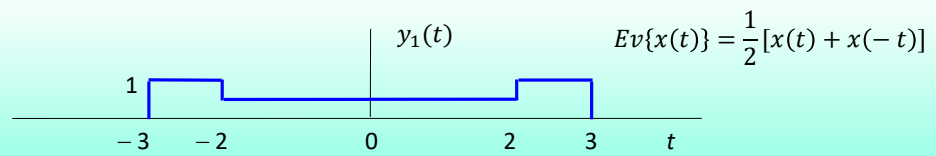
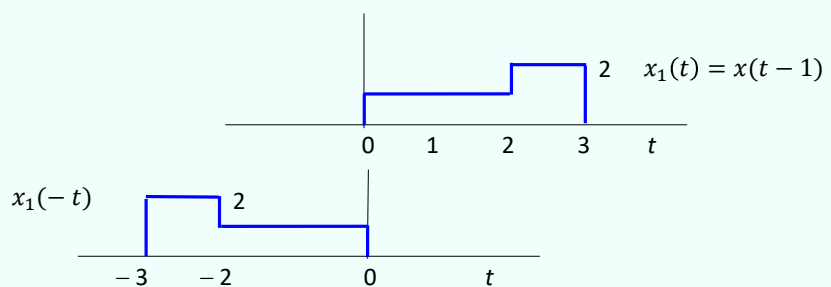
future!

Time-invariant ?



-1 a>1
1 a<1

$Ev\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$



e.g.

$y[n] = \max\{x[n], x[n-1]\}$

Memoryless ? ~~X~~

Causal ? ✓

Invertible ?

Stable ? ✓

Time-invariant ? ✓

Linear ? ~~X~~

$y[n] = \sum_{k=-\infty}^{n+1} x[k]$

Memoryless ? ~~X~~

Causal ? ~~X~~

Invertible ? ~~X~~

Stable ? ~~X~~

Time-invariant ? ~~X~~

Linear ? ✓

e.g. $y[n] = \max\{x[n], x[n-1]\}$

Memoryless ? \times

Causal ? \checkmark

Invertible ? \times

Stable ? \checkmark

Time-invariant ? \checkmark

$$y[1] = \max\{x[1], x[0]\}$$

$$y[-1] = \max\{x[-1], x[-2]\}$$

What does this system do ?

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$$y[n] = \max\{x[n], x[n-1]\}$$

Linear ? \times

$$x_1[n] = [3, 2, 1]$$

$$y_1[n] = [3, 3, 2]$$

$$x_2[n] = [1, 8, 6]$$

$$y_2[n] = [1, 8, 8]$$

$$x_3[n] = x_1[n] + x_2[n] = [4, 10, 7]$$

$$y_3[n] = [4, 10, 10]$$

$$\neq y_1[n] + y_2[n]$$

If it is true,

$$y_3[n] = y_1[n] + y_2[n] = [4, 11, 10]$$

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e.g. $y[n] = \sum_{k=0}^{n+1} x[k]$

Memoryless ? \times

Causal ? \times

Stable ?

Linear ?

$$y[1] = \sum_{k=0}^2 x[k]$$

$$y[-2] = \sum_{k=0}^{-1} x[k]$$

What does this system do ?

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Time-invariant ?

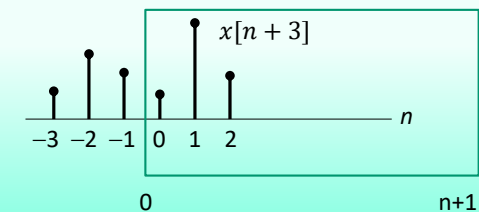
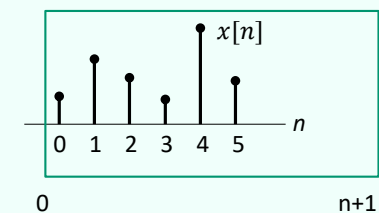
Invertible ?

$$y[-1] = x[0]$$

$$y[0] = x[0] + x[1]$$

$$y[1] = x[0] + x[1] + x[2]$$

$$y[n] = \sum_{k=0}^{n+1} x[k]$$



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