

T02

DT unit impulse and unit step

CT unit impulse

Sampling property and Sifting property

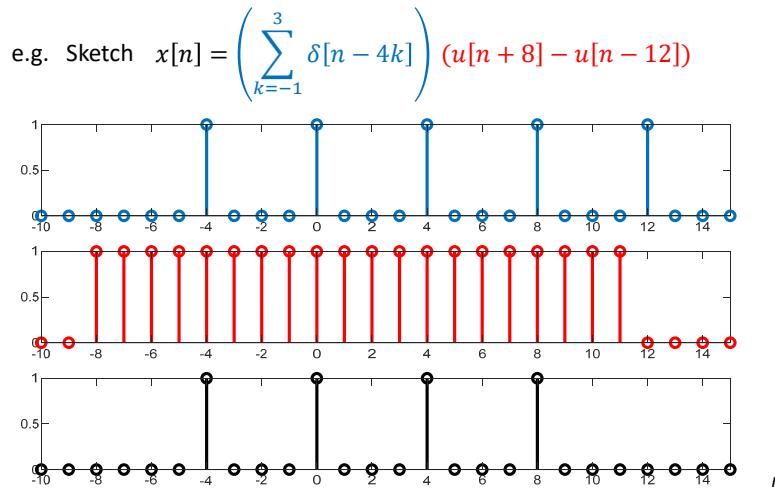
CT complex exponential (Damped oscillation) and complex sinusoid

DT complex exponential (Damped oscillation) and complex sinusoid

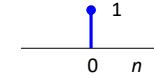
Input-Output relationship

- Memoryless
- Invertibility
- Causality
- Stability
- Time-invariant
- Linearity

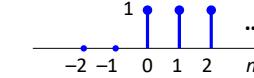
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Question : Represent $x[n]$ as a sum of impulses ?**DT Unit Impulse and Unit Step**

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$



$$u[n] = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$



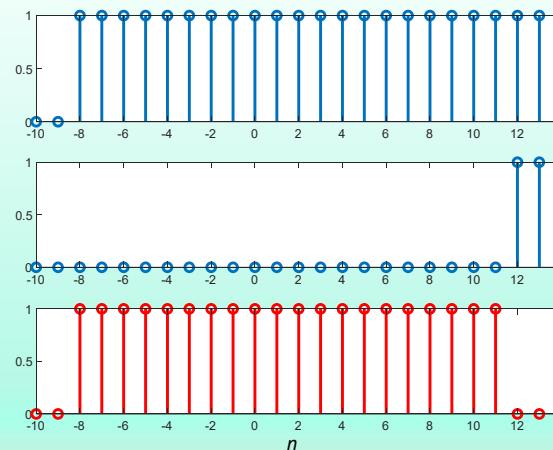
$$\delta[n] = u[n] - u[n-1]$$

$$u[n] = \sum_{k=0}^{\infty} \delta[n-k] = \sum_{m=-\infty}^n \delta[m]$$

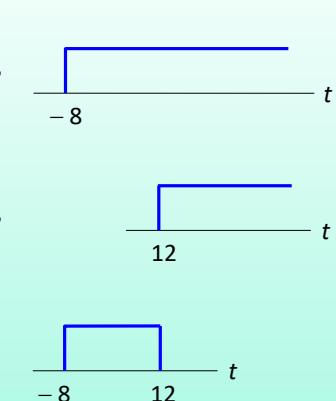
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DT
 $u[n+8] - u[n-12]$



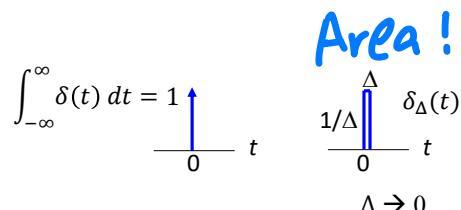
CT
 $u(t+8) - u(t-12)$



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CT Unit Impulse

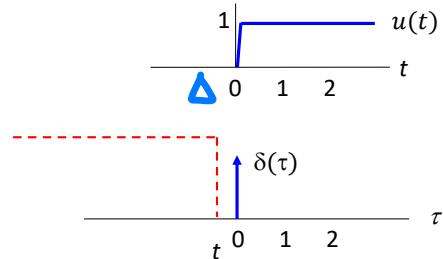
$$\delta(t) = 0 \text{ for } t \neq 0$$



Relationship between $u(t)$ and $\delta(t)$

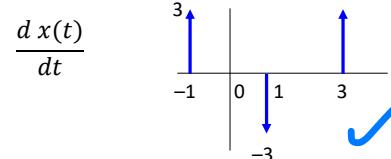
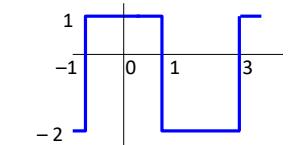
$$\delta(t) = \frac{d}{dt} u(t)$$

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau$$



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e.g.



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$$\text{e.g. } x(t) = \int_t^{\infty} 3\delta(\tau - 2) d\tau$$

a) Plot $x(t)$

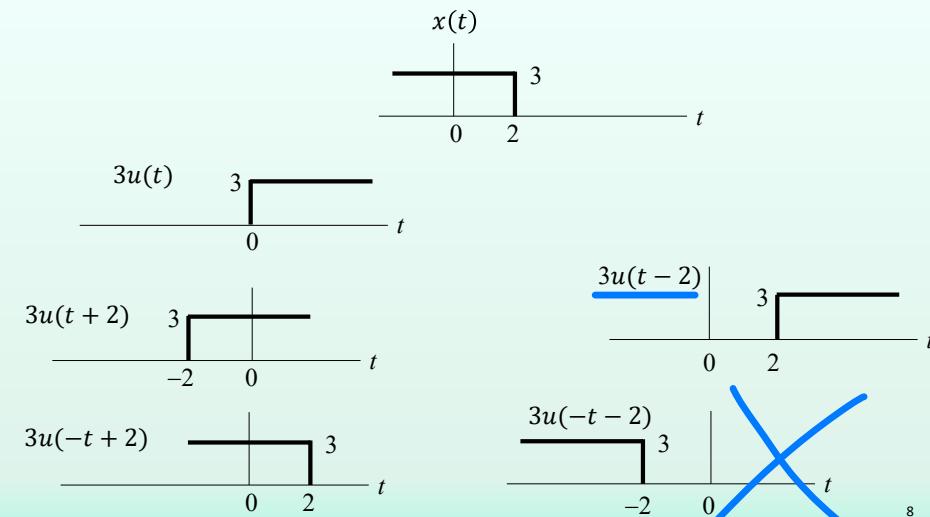


b) Which of the following expressions is correct?

$$x(t) = 3u(-t + 2) \quad \checkmark$$

$$x(t) = 3u(-t - 2) \quad \times$$

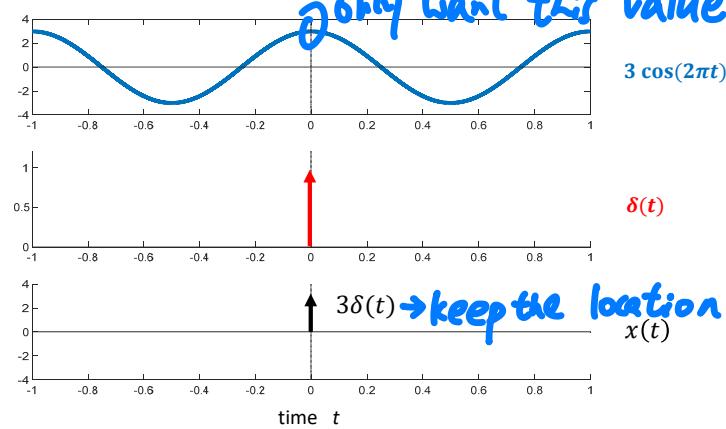
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Sampling Property

e.g. Plot $x(t) = 3 \cos(2\pi t) \delta(t)$

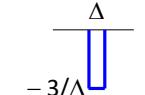
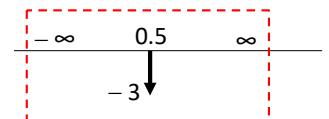


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Sifting Property

e.g. Find $\int_{-\infty}^{\infty} 3 \cos(2\pi\tau) \delta(\tau - 0.5) d\tau$

$$\int_{-\infty}^{\infty} 3 \cos(2\pi\tau) \delta(\tau - 0.5) d\tau = \int_{-\infty}^{\infty} -3 \delta(\tau - 0.5) d\tau = -3$$



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CT Complex Exponential

$$e^{st}$$

$$s = \sigma + j\omega$$

$$e^{(\sigma+j\omega)t} = e^{\sigma t} e^{j\omega t} = e^{\sigma t} \cos(\omega t) + j e^{\sigma t} \sin(\omega t)$$

Exponential form

Rectangular form

$$|e^{(\sigma+j\omega)t}| = e^{\sigma t}$$

$$\operatorname{Re}\{e^{(\sigma+j\omega)t}\} = e^{\sigma t} \cos(\omega t)$$

$$\Im e^{(\sigma+j\omega)t} = \omega t$$

$$\operatorname{Im}\{e^{(\sigma+j\omega)t}\} = e^{\sigma t} \sin(\omega t)$$

e.g.

$$e^{st}$$

$$s = \sigma + j\omega$$

$$x_1(t) = e^{(-0.2+j)t}$$

$$x_2(t) = e^{(0.2-j)t+j\frac{\pi}{2}}$$

Question : What is the complex frequency s ?

$$e^{-0.2t} e^{jt}$$

$$e^{0.2t} e^{j(-t + \frac{\pi}{2})}$$

e.g. Sketch the following signals.

$$x_3(t) = \operatorname{Re}\{x_1(t)\} u(t)$$

$$x_4(t) = \operatorname{Im}\{x_2(t)\} u(-t)$$

$$= e^{-0.2t} \cos(t) u(t)$$

$$= e^{0.2t} \sin\left(-t + \frac{\pi}{2}\right) u(-t)$$

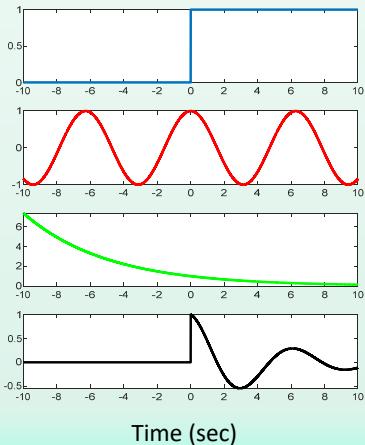
Question :

- Decaying or growing damped oscillation?
- Left-sided or right-sided ?

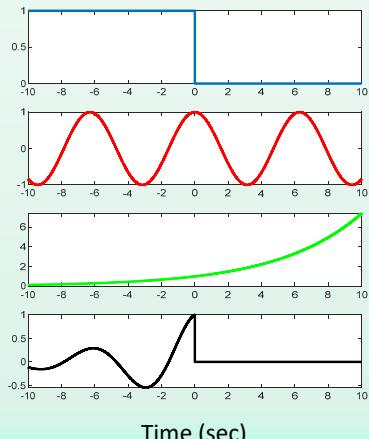
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$$x_3(t) = e^{-0.2t} \cos(t) u(t)$$



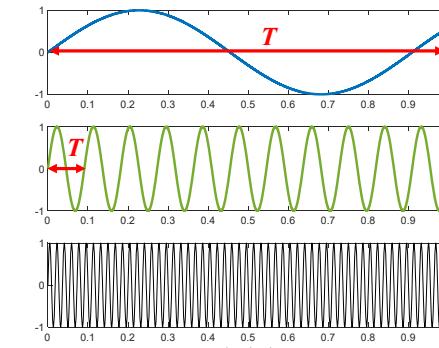
$$x_4(t) = e^{0.2t} \sin\left(-t + \frac{\pi}{2}\right) u(-t)$$



CT Complex Sinusoid

$$e^{j\omega t} = \cos(\omega t) + j \sin(\omega t)$$

The **imaginary part** of $e^{j\omega_0 t}$ is plotted below.



$\omega \sim \omega$

$$\omega = \frac{2\pi}{T}$$

$$\omega = \frac{22\pi}{10} = \frac{2\pi}{10/11}$$

$$\omega = 22\pi = \frac{2\pi}{1/11}$$

$$\omega = 110\pi = \frac{2\pi}{1/55}$$

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Question : How many distinct CT complex sinusoids ?

Difference between complex exponential and complex sinusoid ?

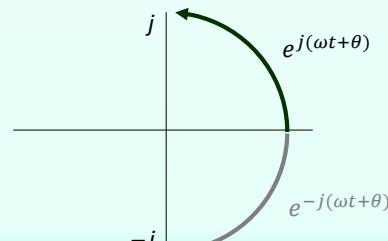
$$e^{\sigma t} e^{j\omega t} = e^{\sigma t} \cos(\omega t) + j e^{\sigma t} \sin(\omega t)$$

$$Ae^{j\omega t} = A \cos(\omega t) + j A \sin(\omega t)$$

$$Ae^{j(\omega t + \theta)} = A \cos(\omega t + \theta) + j A \sin(\omega t + \theta)$$

$$A \sin(\omega t + \theta) = \frac{A}{2} e^{j(\omega t + \theta)} + \frac{A}{2} e^{-j(\omega t + \theta)}$$

$$A \sin(\omega t + \theta) = \frac{A}{2j} e^{j(\omega t + \theta)} - \frac{A}{2j} e^{-j(\omega t + \theta)}$$



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$S = \sigma + j\omega$

DT Complex Exponential

$$z^n$$

$$z = e^s = e^{\sigma+j\omega} = e^{\sigma} e^{j\omega} = |z| e^{j\angle z}$$

$$\text{e.g. } x_1[n] = 0.8^n e^{j\frac{2\pi}{5}n}$$

$$= (0.8 e^{j\frac{2\pi}{5}})^n$$

$$x_2[n] = 2^n e^{j\frac{2\pi}{5}n}$$

$$a^n b^n = (ab)^n$$

$$= (2 e^{j\frac{2\pi}{5}})^n$$

complex frequency

Question : What is the complex frequency z ?

e.g. Sketch the following two signals.

$$x_3[n] = \text{Re}\{x_1[n]\} u[n]$$

$$= 0.8^n \cos\left(\frac{2\pi}{5}n\right) u[n]$$

$$x_4[n] = \text{Im}\{x_2[n]\} u[-n]$$

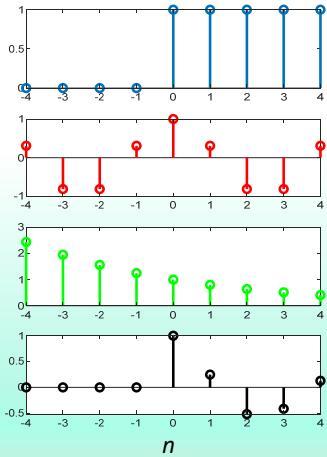
$$= 2^n \sin\left(\frac{2\pi}{5}n\right) u[-n]$$

Question :

- Decaying or growing damped oscillation?
- Left-sided or right-sided ?

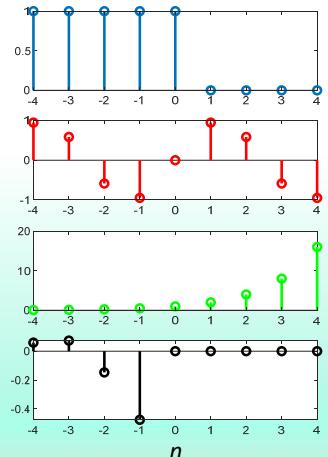
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$$x_1[n] = 0.8^n \cos\left(\frac{2\pi}{5}n\right) u[n]$$



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$$x_2[n] = 2^n \sin\left(\frac{2\pi}{5}n\right) u[-n]$$



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DT Complex Sinusoid

$$e^{j\omega n}$$

$$e^{j\omega n} = \cos(\omega n) + j \sin(\omega n)$$

$$\omega = \frac{2\pi m}{N}$$

where m and N are integers

Question : Difference between CT complex sinusoid and DT complex sinusoid ?

$$e^{j\frac{22\pi}{10}t} = ?$$

$$e^{j\frac{22\pi}{10}n} = ?$$



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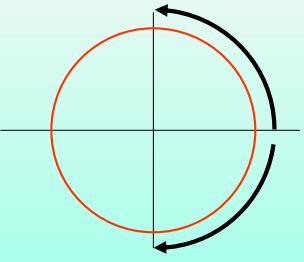
$$e^{j\frac{22\pi}{10}t} = e^{j\frac{20\pi}{10}t} e^{j\frac{2\pi}{10}t} = e^{j2\pi t} e^{j\frac{2\pi}{10}t} = e^{j\frac{22\pi}{10}t}$$

$$e^{j\frac{22\pi}{10}n} = e^{j\frac{20\pi}{10}n} e^{j\frac{2\pi}{10}n} = e^{j2\pi n} e^{j\frac{2\pi}{10}n} = e^{j\frac{2\pi}{10}n}$$

$$e^{j2\pi(0.9)n} = e^{j2\pi(1.9)n} = e^{j2\pi(-0.1)n}$$

$$e^{j2\pi(1.9)n} = e^{j2\pi(1+0.9)n} = e^{j2\pi n} e^{j2\pi(0.9)n}$$

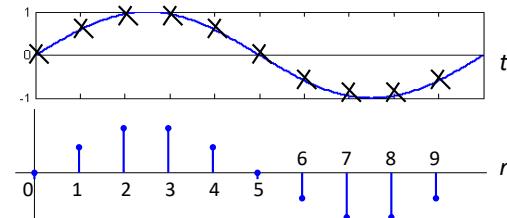
$$e^{j2\pi(-0.1)n} = e^{j2\pi(0.9-1)n} = e^{-j2\pi n} e^{j2\pi(0.9)n}$$



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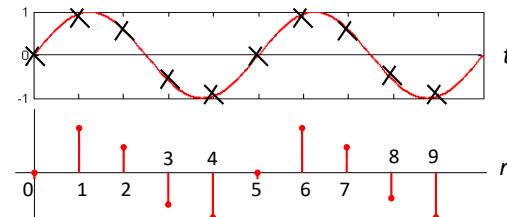
The **imaginary part** of $e^{j\omega n}$ is plotted below.

CT \rightarrow DT



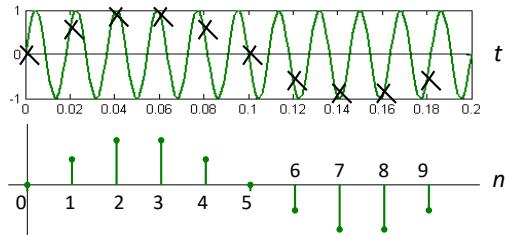
$$\omega = \frac{2\pi (1)}{10}$$

Meaning of m ?



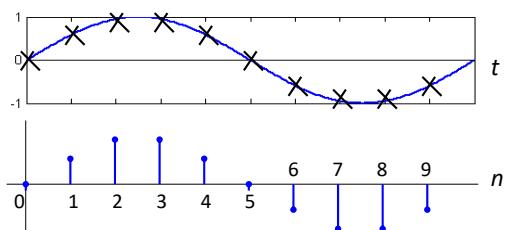
$$\omega = \frac{2\pi (2)}{10}$$

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$$\omega = \frac{2\pi(11)}{10}$$

Same sequence !

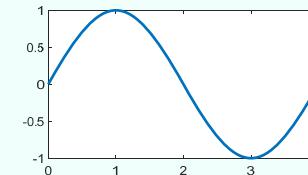


$$\omega = \frac{2\pi}{10}$$

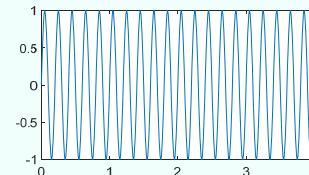
Question : How many distinct DT complex sinusoids if $N = 10$?

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Question : The highest fundamental angular frequency for CT complex sinusoid ?

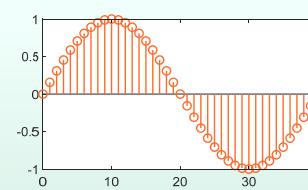


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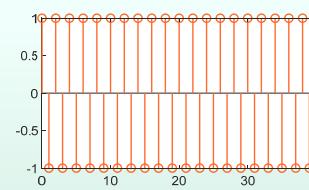


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Question : The highest fundamental angular frequency for DT complex sinusoid ?



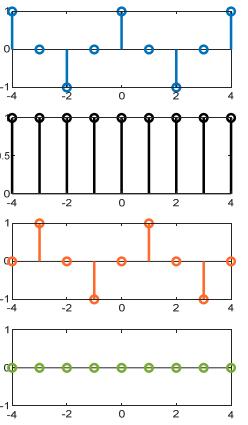
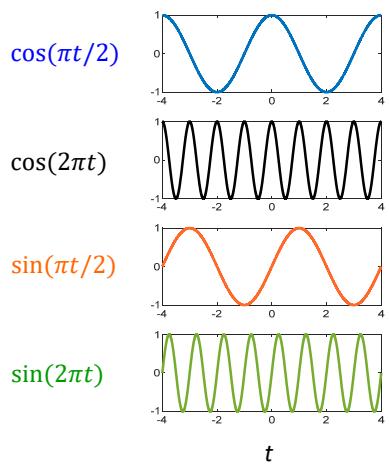
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$$\frac{2\pi}{N} \quad N = 2(\text{minimum})$$

e.g. Sketch the following CT and DT signals.



$$\cos(\pi n/2)$$

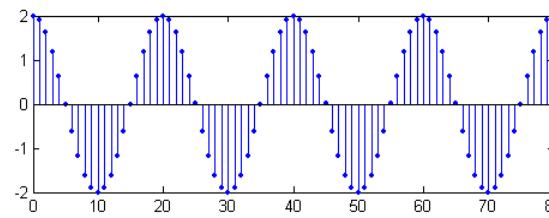
$$\cos(2\pi n)$$

$$\sin(\pi n/2)$$

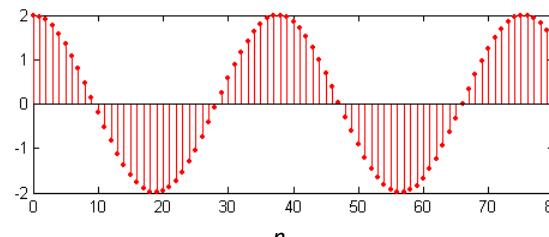
$$\sin(2\pi n)$$

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e.g. Periodic ? Fundamental period N ?



$$x_1[n] = 2 \cos\left(\frac{2\pi}{20}n\right)$$



$$x_2[n] = 2 \cos\left(\frac{n}{6}\right)$$

$N = 12\pi$
f integer

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e.g. Match the following signals with Figure 1, Figure 2 and Figure 3.

$$x_1[n] = \operatorname{Re}\left\{(0.8 e^{j\frac{2\pi}{5}})^n\right\}$$

2

$$x_2[n] = \operatorname{Re}\left\{e^{j\frac{2\pi}{5}n}\right\}$$

3

$$x_3[n] = \operatorname{Re}\left\{e^{j\frac{2}{5}n}\right\}$$

1
non-periodic!

Figure 1

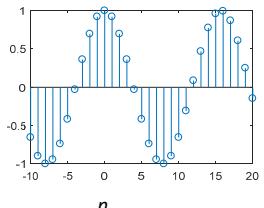


Figure 2

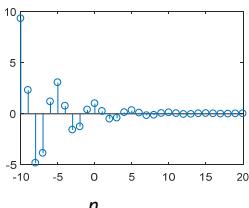
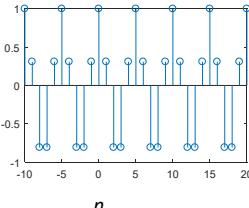


Figure 3

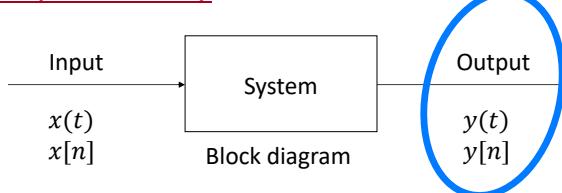


Input-Output relationship

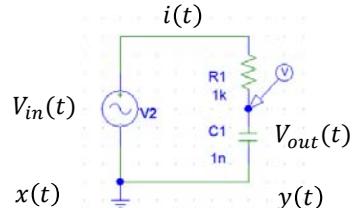
- Memoryless
- Invertibility
- Causality
- Stability
- Time-invariant
- Linearity

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Input and Output Relationship



e.g.



$$i(t) = C \frac{d}{dt} V_{out}(t)$$

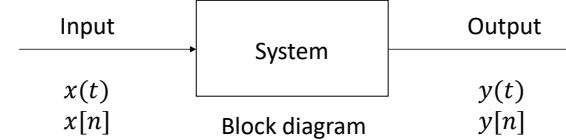
$$V_{in}(t) = V_R(t) + V_{out}(t) = i(t)R + V_{out}(t)$$

$$= RC \frac{d}{dt} V_{out}(t) + V_{out}(t)$$

$$x(t) = RC \frac{d}{dt} y(t) + y(t)$$

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System



System Properties

Memoryless The output only depends on the current input

Causality The output does not depend on the future input

Invertibility Distinct inputs leads to distinct outputs
(i.e. One-to-one mapping)

Input-Output Relationship

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Stability Bounded input results in bounded output (**BIBO**)

$$|x(t)| < \infty \forall t \quad \text{System} \quad |y(t)| < \infty \forall t$$

Time-invariant The behavior of a system does not change over time

$$x(t) \quad \text{System} \quad y(t)$$

$$x_1(t) = x(t - t_o) \quad y_1(t) = y(t - t_o)$$

Linearity Superposition and Scaling (zero-input zero-output)

$$x_1(t) \quad \text{System} \quad y_1(t)$$

$$x_2(t) \quad \text{System} \quad y_2(t)$$

$$x_3(t) = ax_1(t) + bx_2(t) \quad y_3(t) = ay_1(t) + by_2(t)$$

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e.g. $y(t) = \cos(x(t)) + 1$

Memoryless ? ✓

Causal ? ✓

Stable ? ✓

Time-invariant ? ✓

$$y(1) = \cos(x(1)) + 1$$

$$y(-1) = \cos(x(-1)) + 1$$

What does this system do ?

Linear ?

$$y_3(t) = \cos(x_3(t)) + 1 = \cos(ax_1(t) + bx_2(t)) + 1$$

$$x_3(t) = ax_1(t) + bx_2(t) \quad \neq ay_1(t) + by_2(t)$$

If it is true, $y_3(t) = ay_1(t) + by_2(t) = a\cos(x_1(t)) + 1 + b\cos(x_2(t)) + 1$

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Plug a positive and negative

e.g. $y(t) = \cos(x(t)) + 1$ $y(t) = Ev\{x(t)\}$

Memoryless ?

Memoryless ?

Causal ?

Causal ?

Invertible ?

Invertible ?

Stable ?

Stable ?

Time-invariant ?

Time-invariant ?

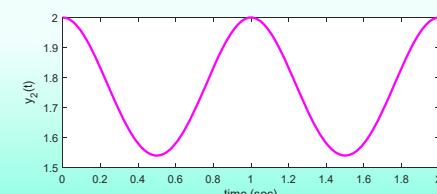
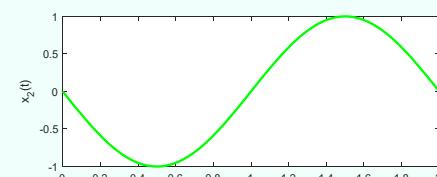
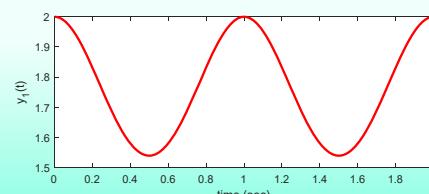
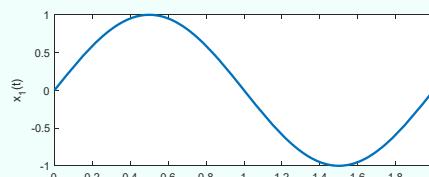
Linear ?

Linear ?

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Invertible ? ✗ $\cos(-\theta) = \cos(\theta)$

$$y(t) = \cos(x(t)) + 1$$



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e.g. $y(t) = Ev\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$

Memoryless? \times

Causal? \times

Invertible? \times

Stable? \checkmark

Linear? \checkmark

$$x_3(t) = ax_1(t) + bx_2(t)$$

$$y(1) = \frac{1}{2}[x(1) + x(-1)]$$

$$y(-1) = \frac{1}{2}[x(-1) + x(1)]$$

future!

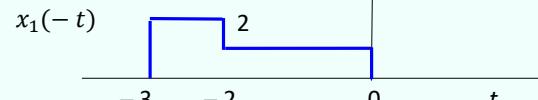
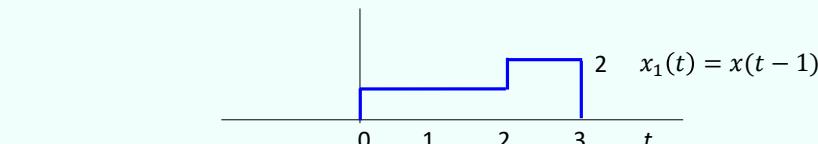
What does this system do?

$$\begin{aligned} y_3(t) &= \frac{1}{2}[ax_1(t) + bx_2(t) + ax_1(-t) + bx_2(-t)] \\ &= ay_1(t) + by_2(t) \end{aligned}$$

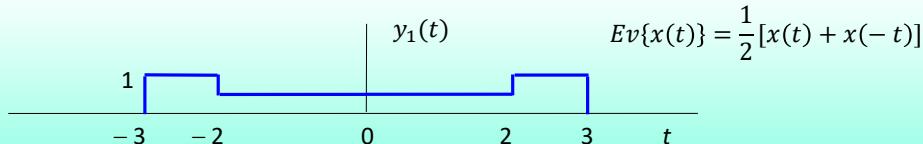
If it is true, $y_3(t) = ay_1(t) + by_2(t) = \frac{a}{2}[x_1(t) + x_1(-t)] + \frac{b}{2}[x_2(t) + x_2(-t)]$

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$x_1(t)$



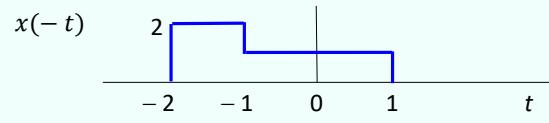
$y_1(t)$



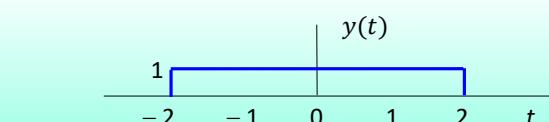
$$Ev\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$$

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Time-invariant?



-1
1
 $\frac{Q>1}{Q<1}$



$$Ev\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$$

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e.g.

$$y[n] = \max\{x[n], x[n-1]\}$$

$$y[n] = \sum_{k=-\infty}^{n+1} x[k]$$

Memoryless? \times

Causal? \checkmark

Invertible?

Stable? \checkmark

Time-invariant? \checkmark

Linear? \times

Memoryless? \times

Causal? \checkmark

Invertible? \times

Stable? \times

Time-invariant? \times

Linear? \checkmark

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e.g. $y[n] = \max\{x[n], x[n - 1]\}$

Memoryless ?

Causal ?

Invertible ?

Stable ?

Time-invariant ?

$$y[1] = \max\{x[1], x[0]\}$$

$$y[-1] = \max\{x[-1], x[-2]\}$$

What does this system do ?

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$y[n] = \max\{x[n], x[n - 1]\}$

Linear ?

$$x_1[n] = [3, 2, 1]$$

$$y_1[n] = [3, 3, 2]$$

$$x_2[n] = [1, 8, 6]$$

$$y_2[n] = [1, 8, 8]$$

$$x_3[n] = x_1[n] + x_2[n] = [4, 10, 7]$$

$$y_3[n] = [4, 10, 10]$$

$$\neq y_1[n] + y_2[n]$$

If it is true,

$$y_3[n] = y_1[n] + y_2[n] = [4, 11, 10]$$

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e.g. $y[n] = \sum_{k=0}^{n+1} x[k]$

Memoryless ?

Causal ?

Stable ?

Linear ?

$$y[1] = \sum_{k=0}^2 x[k] \quad y[-2] = \sum_{k=0}^{-1} x[k]$$

What does this system do ?

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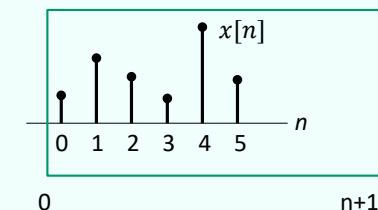
Time-invariant ?

Invertible ?

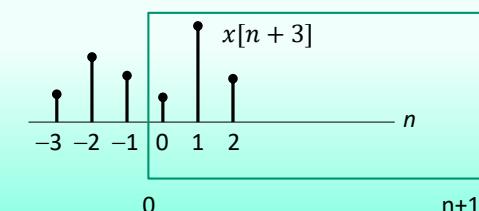
$$y[-1] = x[0]$$

$$y[0] = x[0] + x[1]$$

$$y[1] = x[0] + x[1] + x[2]$$



$$y[n] = \sum_{k=0}^{n+1} x[k]$$



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