

(a) since all rows are a multiple of one, $\sqrt{\text{tr}(AA^T)} = \sqrt{\sum_{i,j} a_{ij}^2}$
 so ALWAYS

Correct answer, but not explanation. 2/3

(b) SOMETIMES

as X could be a non-unique solution we are not guaranteed to retrieve it

Correct answer, but not explanation. 2/3

(c) NEVER, since $L = D - A$ they have a different rank; rank so cannot have exactly same set of eigenvectors

Sometimes. True whenever D is a scaling of identity. 1/3

(d) VV^T is a projection matrix that has a property of norm preservation
 therefore, ALWAYS $\|VV^T x\|_2 = \|x\|_2$

Sometimes. Not true when $k < n$. 1/3

- (a) sp.3 image ~~b~~ c
 sp.2 image a
 sp.1 image b

Correct.

- (b) spectrum 3 will be better approximated in rank 40 as the remaining 60 discarded singular values are smaller and do not contribute as much to an approximation error

Correct.

- (c) Power Method convergence $T = O\left(\frac{\log \frac{d}{\epsilon}}{\gamma}\right)$

in this case: d-same & ϵ is same \Rightarrow higher γ will contribute the most to the fastest convergence

$$\gamma = \frac{\delta_1 - \delta_2}{\delta_1} = \frac{\delta_1}{\delta_1} - \frac{\delta_2}{\delta_1} = 1 - \frac{\delta_2}{\delta_1} \Rightarrow \text{fastest will be the spectrum with } \min\left(\frac{\delta_2}{\delta_1}\right) \Rightarrow \text{spectrum 3}$$

forgot to say slowest, but correct reasoning. 1.5/2

#3 4/8

(a) A is symmetric by definition $\Rightarrow \text{tr}(A) = \sum_{i=1}^n \lambda_i$
and b/c graph is undirected

since diagonal of A is 0 $\Rightarrow \text{tr}(A) = 0$

therefore, $\text{tr}(A) = 0 = \sum_{i=1}^n \lambda_i$

what prevents all eigenvalues from being 0? 3/4

so, there will be $X = \{\lambda_i : \lambda_i > 0\}$ and $Y = \{\lambda_i : \lambda_i < 0\}$

$$\sum_{i \in X} \lambda_i + \sum_{i \in Y} \lambda_i = 0$$

therefore, both sets should be non-empty
to get a sum 0

(b) $L = D - A$

if there is ~~was~~ ~~eq.~~ the same set of eigenvalues

for each λ_i : $Av_i = \lambda_i v_i$

$$Lv_i = \lambda_i v_i$$

$$(D - A)v_i = \lambda_i v_i$$

$$Dv_i - Av_i = \lambda_i v_i \Rightarrow Av_i = Dv_i - \lambda_i v_i$$

$$Av_i = \lambda_i v_i$$

This argument doesn't rule out having same eigenvalues but different eigenvectors. 1/4.

We know that L is PSD so only has non-negative eigenvalues, whereas from part (a), A has a negative one.