

# Tools for data analyses in Cosmology

- Aula 8 -

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Observatório Nacional

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Healpy

Previously on `healpy` class ...

```
In [123]: theta = 30.          # Colatitude
...: lat = 90. - theta        # Latitude
...: phi = 25.                # Longitude
...: lon = phi
...:

In [124]: vec0 = hp.ang2vec(np.deg2rad(theta), np.deg2rad(phi))
...: vec0
...:
Out[124]: array([ 0.45315389,  0.21130913,  0.8660254 ])
```

```
In [125]: vec1 = hp.dir2vec(lon, phi=lat, lonlat = True)
...: vec1
...:
Out[125]: array([ 0.45315389,  0.21130913,  0.8660254 ])
```

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In [124]: vec0 = hp.ang2vec(np.deg2rad(theta), np.deg2rad(phi))
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Out[124]: array([ 0.45315389,  0.21130913,  0.8660254 ])
```

```
In [125]: vec1 = hp.dir2vec(lon, phi=lat, lonlat = True)
...: vec1
...:
Out[125]: array([ 0.45315389,  0.21130913,  0.8660254 ])
```

**Exercise:** Which is the vector corresponding to the position of the Virgo cluster?

$\ell, b = 283.8^\circ, 74.4^\circ \Rightarrow$

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Out[124]: array([ 0.45315389,  0.21130913,  0.8660254 ])
```

```
In [125]: vec1 = hp.dir2vec(lon, phi=lat, lonlat = True)
...: vec1
...:
Out[125]: array([ 0.45315389,  0.21130913,  0.8660254 ])
```

**Exercise:** Which is the vector corresponding to the position of the Virgo cluster?

$$\ell, b = 283.8^\circ, 74.4^\circ \Rightarrow$$

$$x, y, z = [0.06414637, -0.26115726, 0.96316257]$$

## Rotation and geometry functions

### healpy.rotator.angdist

**healpy.rotator.angdist**(*dir1*, *dir2*, *lonlat=False*)

Returns the angular distance between *dir1* and *dir2*.

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Virgo:  $\ell, b = 283.8^\circ, 74.4^\circ$

Coma:  $\ell, b = 235.1^\circ, 73.0^\circ$

## Rotation and geometry functions

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Returns the angular distance between *dir1* and *dir2*.

**Exercise:** Which is the angular distance between Virgo and Coma clusters?

Virgo:  $\ell, b = 283.8^\circ, 74.4^\circ$

Coma:  $\ell, b = 235.1^\circ, 73.0^\circ$

**Result:** Distance = 0.23 rad = 13.35 deg



Rotation and geometry functions

## healpy.pixelfunc.get\_all\_neighbours

```
healpy.pixelfunc.get_all_neighbours(nside, theta, phi=None, nest=False)
```

Return the 8 nearest pixels.

**Sequence:** SW, W, NW, N, NE, E, SE and S  
neighbours

## Rotation and geometry functions

### How to use:

```
In [94]: nside = 128  
...: theta = np.pi/2.  
...: phi = np.pi  
...:
```

```
In [95]: pix = hp.get_all_neighbours(nside, theta, phi)
```

```
In [96]: pix
```

```
Out[96]: array([98816, 98303, 97792, 97280, 97793, 98305, 98817, 99328])
```

```
In [96]:
```

```
In [97]: pix = hp.get_all_neighbours(nside,100)
```

```
In [98]: pix
```

```
Out[98]: array([130, 99, 73, 51, 74, 101, 131, 165])
```

Neighbours of pixel 5432 at Nside=1024?

## Rotation and geometry functions

### How to use:

```
In [94]: nside = 128  
...: theta = np.pi/2.  
...: phi = np.pi  
...:
```

```
In [95]: pix = hp.get_all_neighbours(nside, theta, phi)
```

```
In [96]: pix  
Out[96]: array([98816, 98303, 97792, 97280, 97793, 98305, 98817, 99328])
```

```
In [96]:
```

```
In [97]: pix = hp.get_all_neighbours(nside,100)
```

```
In [98]: pix  
Out[98]: array([130, 99, 73, 51, 74, 101, 131, 165])
```

Neighbours of pixel 5432 at Nside=1024?

```
Out[1]: array([5642, 5431, 5225, 5023, 5226, 5433,  
5643, 5857])
```

## Rotation and geometry functions

How to use:

```
In [94]: nside = 128  
...: theta = np.pi/2.  
...: phi = np.pi  
...:
```

```
In [95]: pix = hp.get_all_neighbours(nside, theta, phi)
```

```
In [96]: pix
```

```
Out[96]: array([98816, 98303, 97792, 97280, 97793, ..., 99328])
```

```
In [96]:
```

```
In [97]: pix = hp.get_all_neighbours(nside, theta, phi, 100)
```

```
In [98]: pix
```

```
Out[98]: array([5432, 5431, 5430, 5429, 5428, ..., 5433, 5432, 5431, 5430, 5429])
```

```
In [99]: hp.get_neighbours(nside, theta, phi, 100, 5432)
```

```
Out[99]: array([5642, 5431, 5225, 5023, 5226, 5433, 5643, 5857])
```

What can it be used for?

## Rotation and geometry functions

<code>Rotator</code> ([rot, coord, inv, deg, eulertype])	Rotation operator, including astronomical coordinate systems.
<code>rotateVector</code> (rotmat, vec[, vy, vz, do_rot])	Rotate a vector (or a list of vectors) using the rotation matrix given by rotmat.
<code>rotateDirection</code> (rotmat, theta[, phi, ...])	Rotate the vector described by angles theta,phi using the rotation matrix given by rotmat.

## Rotation and geometry functions

### healpy.rotator.Rotator

```
class healpy.rotator.Rotator(rot=None, coord=None, inv=None, deg=True, eulertype='ZYX')
```

Rotation operator, including astronomical coordinate systems.

# Rotation and geometry functions

## How to use:

```
In [130]: r = hp.Rotator(coord=['G','E']) # Transforms galactic to ecliptic coordinates
...:
...: theta_gal, phi_gal = np.pi/2., 0.
...: theta_ecl, phi_ecl = r(theta_gal, phi_gal) # Apply the conversion
...: print(theta_ecl, phi_ecl)
...:
1.66742286715 -1.62596400306
```

OR:

```
In [130]:
```

```
In [131]: theta_ecl, phi_ecl = hp.Rotator(coord='ge')(theta_gal, phi_gal) # In one line
...: print(theta_ecl, phi_ecl)
...:
1.66742286715 -1.62596400306
```

```
In [131]:
```

```
In [132]: vec_gal = np.array([1, 0, 0]) #Using vectors
...: vec_ecl = r(vec_gal)
...: print(vec_ecl)
...:
[-0.05488249 -0.99382103 -0.09647625]
```

# Rotation and geometry functions

## Exercise:

- Change the coordinates for the whole sky. Consider the pixels in  $N_{\text{side}} = 1024$ . Steps:
  - [1] Generate an array (pixels) with the pixel indexes corresponding to this resolution (`np.arange`).
  - [2] Calculate the  $\theta, \phi$  coordinates of all the pixels (`hp.pix2ang`).
  - [3] Rotate them to find the new  $\theta_{\text{ec1}}, \phi_{\text{ec1}}$ .
  - [4] Convert these ecliptic coordinates back to pixel indexes (pixels2) (`hp.ang2pix`).
  - [5] Visualize the distribution.



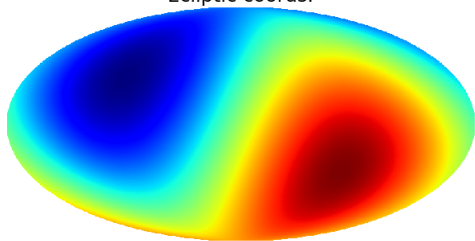
# Rotation and geometry functions

Results:

Galactic coords.



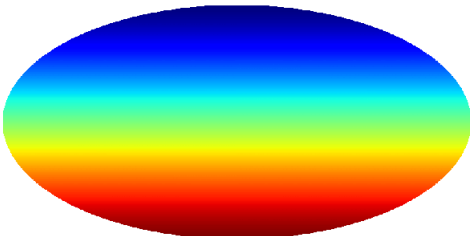
Ecliptic coords.



# Rotation and geometry functions

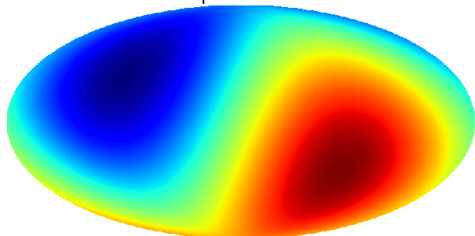
Results:

Galactic coords.



2520 1.25804e+07

Ecliptic coords.

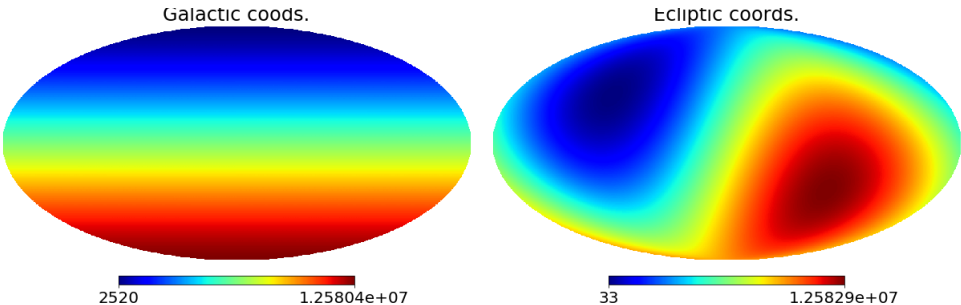


33 1.25829e+07

How to apply this coordinate transform in a map?

# Rotation and geometry functions

Results:

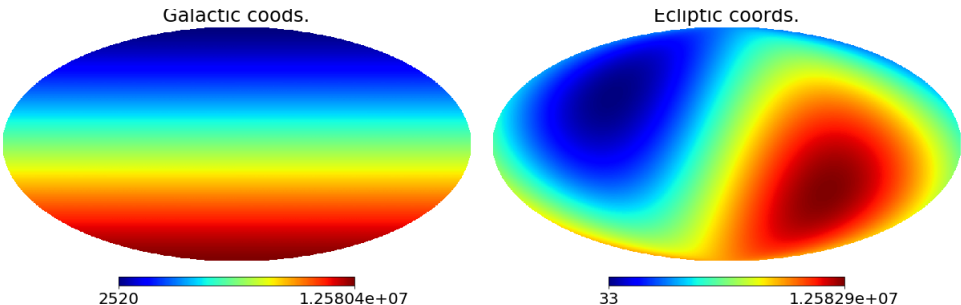


How to apply this coordinate transform in a map?

How to perform a rotation instead of a coordinate transform?

# Rotation and geometry functions

Results:



How to apply this coordinate transform in a map?

How to perform a rotation instead of a coordinate transform?

Lets see ...