



# Workshop

## **Generating detailed 3D Streetspace Models in CityGML 3.0 using the free OpenDRIVE data conversion tool r:trân**

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## Resulting 3D streetspace model



- ▶ r:trân is an
  - open library
  - for road space model transformations (OpenDRIVE to CityGML)
  - steered by parameterizable recipes
  
- ▶ Initial use cases
  - Conversion of OpenDRIVE → CityGML 2.0
  - Conversion of OpenDRIVE → CityGML 3.0

<https://rtron.io>

<https://github.com/tum-gis/rtron>

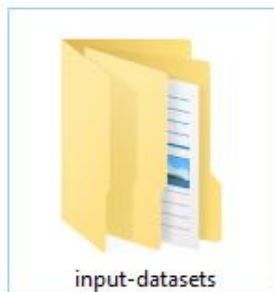
# Hands-on Tutorial

## ► Prerequisite

- Commands are based on Windows OS
- Docker installation
- Data inspector of FME (Safe Software) <https://www.safe.com/fme/trial/>
- (optional) 3DCity Database (3DCityDB) <https://www.3dcitydb.org/3dcitydb/>

## ► Download of sample data and scripts:

<https://syncandshare.lrz.de/getlink/fiCYHWPtetehc1TybqWRpeRy/sample-datasets.zip>



# Practical Application: Conversion

- ▶ Run this command (also provided in scripts\readme.txt)
  - Path to the downloaded sample dataset directory
  - Container internal path to project input & output directory
  - Transformation recipe script

```
docker run -i --name rtron --rm^  
-v C:\adjust\path\to\sample-datasets\input-datasets:/project/input^  
-v C:\adjust\path\to\sample-datasets\output-datasets:/project/output^  
rtron/rtron - < C:\adjust\path\to\sample-datasets\scripts\opendrive-to-citygml3.kts
```