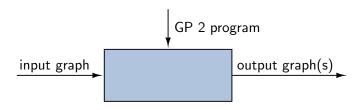
Hoare-Style Verification for GP 2

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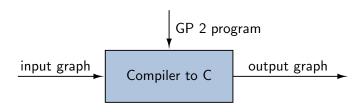
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Graph Programming Language GP 2



- Experimental DSL for graphs and graph-like structures
- Rule-based, visual manipulation of graphs
- Non-deterministic
- Simple syntax and semantics to facilitate formal reasoning

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Program for transitive closure

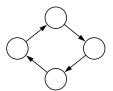
A graph is *transitive* if for every directed path $v \rightsquigarrow v'$ with $v \neq v'$, there is an edge $v \rightarrow v'$

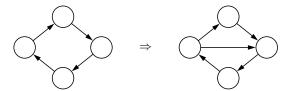
Main = link!

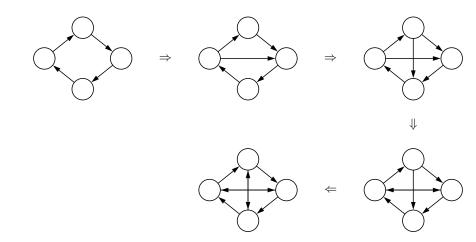
link(a, b, x, y, z: list)

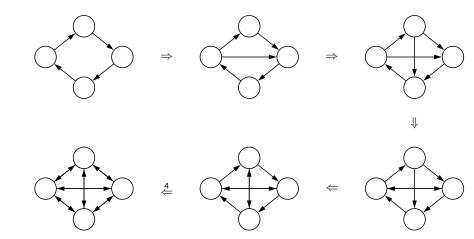


where not edge(1,3)









Rule schemata ("attributed rules")

bridge(n: int; s,t: string; a: atom; x,y: list)

$$\begin{array}{ccc}
 & s \\
\hline
 & a:x \\
\hline
 & t
\end{array}$$

$$\begin{array}{cccc}
 & y \\
\hline
 & x:y \\
\hline
 & 1
\end{array}$$

$$\Rightarrow \qquad \begin{array}{ccccc}
 & x:y \\
\hline
 & 1
\end{array}$$

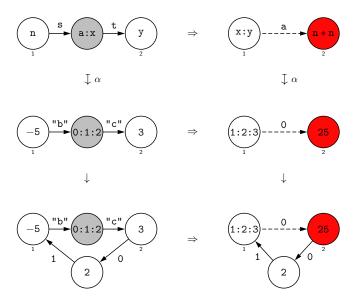
where n < 0 and not edge(1, 3)

- ':' is list concatenation
- ► LHS expressions are *simple*
- Variables in RHS and condition occur in LHS
- Host graph expressions are constants (integers, strings and lists)
- ▶ Marked nodes and edges: red, green, blue, shaded, dashed

Subtype hierarchy for labels

```
\begin{array}{c} \text{list} \\ & \cup \text{I} \\ \text{atom} \\ & \swarrow & \searrow \\ \text{int} & \text{string} \\ & \cup \text{I} \\ & \text{char} \end{array}
```

Rule-schema application



Program for vertex colouring

Main = init!; inc! init(x: atom) inc(x, y: atom; i: int; a: list)

Program for vertex colouring

Main = init!; inc!

init(x: atom)

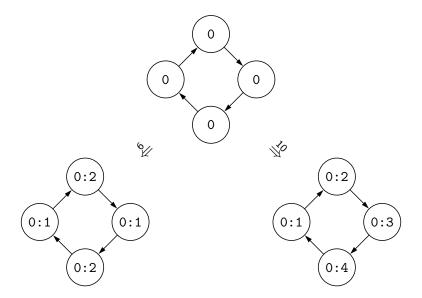
$$x$$
 \Rightarrow $x:1$

inc(x, y: atom; i: int; a: list)

 $x:i$ \Rightarrow $x:i$ \Rightarrow $x:i$ \Rightarrow $x:i$

Assumption: node labels in host graph are atoms

Program for vertex colouring (cont'd)



Programs: abstract syntax

```
Program ::= Decl {Decl}
MainDecl ::= Main '=' ComSeq
ComSeq ::= Com \{';' Com\}
       ::= Ruleld
Com
               | '{' [Ruleld {',' Ruleld}] '}'
               | if ComSeq then ComSeq [else ComSeq]
               try ComSeq [then ComSeq [else ComSeq]]
               | ComSeq '!'
```

Transition relation defined by SOS

```
Main = \{r1, r2\}; \{r1, r2\}; r1!

r1: (1) \Rightarrow (1) r2: (1) \Rightarrow (2)
```

$$\begin{array}{cccc} \langle \mathtt{Main}, \textcircled{1} \rangle & \rightarrow & \langle P, \textcircled{2} \rangle & \rightarrow & \mathsf{fail} \\ \downarrow & & & \\ \langle P, \textcircled{1} \rangle & \rightarrow & \langle \mathtt{r1!}, \textcircled{1} \rangle & \rightarrow & \langle \mathtt{r1!}, \textcircled{1} \rangle & \rightarrow & \dots \\ \downarrow & & & \\ \langle \mathtt{r1!}, \textcircled{2} \rangle & & \downarrow & \\ & & & & \\ & & & & \\ \end{matrix}$$

where $P = \{r1, r2\}; r1!$

Verification: Motivation

Motivated by applications of graph programs to defining semantics and analyses of languages and systems, e.g.

- Visual modelling/specification languages
- Model transformations
- Shape safety of pointer operations
- Concurrent asynchronous programming abstractions

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Can existing "classical" verification tools help us?

- ▶ Yes, but blow up in inherently symmetric & dynamic problems
- ► Alternatively: lift and tailor classical verification techniques to the domain of graphs and graph transformation

Verification: Our Approach

In particular: we are developing a theory to underpin assertional graph-based reasoning

- Graph/morphism-based assertion logic
- ► Hoare logics for programs
- ▶ Effective weakest precondition constructions for rules
- Exploits an algebraic characterisation of graph rewriting

$$\vdash \{pre\} \ P \ \{post\}$$

We combine ideas from:

- Nested conditions (finite)
 - Express local graph structure via morphisms
- Classical FO logic; attributed graph constraints
 - Express properties of attributes
- MSO logic on graphs (in the presentation of Courcelle)
 - ► Express non-local properties (paths, cycles, ...)

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Example: local graph structure and attributes

"for all pairs of nodes, if their labels are distinct, then they are adjacent"



Example: non-local property

"the graph is 2-colourable (bipartite)"

Example: non-local property

$$\exists_{V}X,Y. \quad \forall \quad \bullet_{v} \quad [\ (v \in X \lor v \in Y) \land \neg (v \in X \land v \in Y) \]$$

$$\land \forall \quad \bullet_{v} \quad \bullet_{w} \quad [\ \exists \quad \bullet_{v} \rightarrow \bullet_{w} \Rightarrow \neg (v \in X \land w \in X) \land \neg (v \in Y \land w \in Y) \]$$

"the graph is 2-colourable (bipartite)"

Example: attributes and non-local property

$$\exists \bigcirc_{v} [\neg \exists \bigcirc_{v} \bigcirc_{w}] \land \forall_{I} x. \ \forall \ \bigotimes_{v} [x > 0 \Rightarrow \exists \ \bigotimes_{v} \bigcirc_{w} [path(v, w)]]$$

"there is an (arbitrary-length) path from every positive integer-labelled node to a unique red node"



Hoare-Style Proof Calculi

Proof rules for (partial/total) correctness of GP 2 constructs, e.g.

$$[\mathsf{comp}] \ \frac{\{c\} \ P \ \{e\} \ \{e\} \ Q \ \{d\}}{\{c\} \ P; \ Q \ \{d\}} \qquad [!] \ \frac{\{\mathit{inv}\} \ \mathcal{R} \ \{\mathit{inv}\}}{\{\mathit{inv}\} \ \mathcal{R}! \ \{\mathit{inv} \land \neg \mathsf{App}(\mathcal{R})\}}$$

Core of the calculi:

$$\vdash \{\mathsf{Pre}(r, post)\} \ r \ \{post\}$$

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 Extended from Habel/Pennemann's construction to handle attributes, MSO logic, and path predicates



Example: Colouring

```
Main = init!; inc!
inc(x,y: atom; i: int; a: list)
```

$$c = \forall_{L} a. \forall \textcircled{a}_{v} [atom(a)]$$

$$d \land \neg App(\{inc\}) = \forall_{L} a. \forall \textcircled{a}_{v} [\exists_{A} b. \exists_{I} c. a = b : c \land c >= 1]$$

$$\land \neg \exists_{L} k. \exists_{A} x, y. \exists_{I} i. \exists \underbrace{x : i}_{v} \xrightarrow{k} \underbrace{y : i}_{w}$$

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$$\begin{aligned} \operatorname{Pre}(\operatorname{inc}, d) &= \forall_{\mathsf{L}} \mathsf{k}. \forall_{\mathsf{A}} \mathsf{x}, \mathsf{y}. \forall_{\mathsf{I}} \mathsf{i}. \ \forall \underbrace{\left(\mathsf{x} : \mathsf{i} \right)_{\mathsf{v}}^{\mathsf{k}} - \left(\mathsf{y} : \mathsf{i} \right)_{\mathsf{w}}^{\mathsf{k}}}_{\mathsf{W}} = \\ & [\ \mathsf{i} > = 1 \land \forall_{\mathsf{L}} \mathsf{a}. \ \forall \underbrace{\left(\mathsf{x} : \mathsf{i} \right)_{\mathsf{v}}^{\mathsf{k}} - \left(\mathsf{y} : \mathsf{i} \right)_{\mathsf{w}}^{\mathsf{k}}}_{\mathsf{w}} \mathsf{a} \\ & [\ \exists_{\mathsf{A}} \mathsf{b}. \exists_{\mathsf{T}} \mathsf{c}. \ \mathsf{a} = \mathsf{b} : \mathsf{c} \land \mathsf{c} > = 1 \] \ \end{aligned}$$

Open problems

Our calculi are sound with respect to the GP 2 semantics

But: assertion logic is not expressive

- Are there expressive extensions?
- Relative completeness (despite not expressive)?
- Proof rules for programs with composite tests / loop bodies?

Future Work

- Implementation for user-guided proofs
- Incorporating tracking information
- Automatic confluence and termination checking
- Applying to GROOVE's control programs; CEGAR