

On the Loewner framework, the Kolmogorov superposition theorem, and the curse of dimensionality

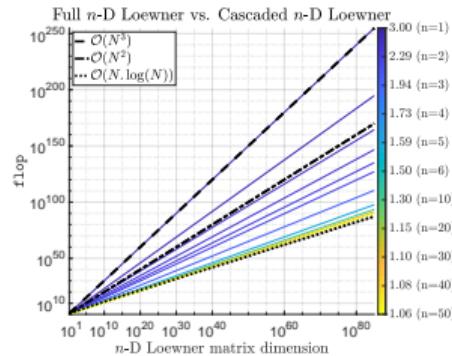
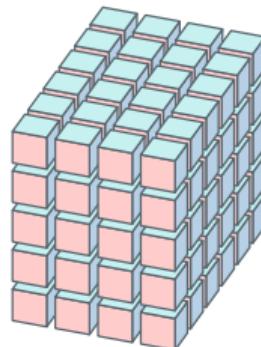
... from tensor to multivariate model and realization

C. Poussot-Vassal, in coll. with A.C. Antoulas [Rice Univ.] and I.V. Goșea [MPI]

September 22, 2025

<https://arxiv.org/abs/2405.00495> (to appear in SIAM Review - Research Spotlight)

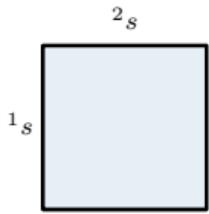
<https://github.com/cpoussot/mLF> (GitHub code)



Forewords

Starting (motivating) examples - toy case

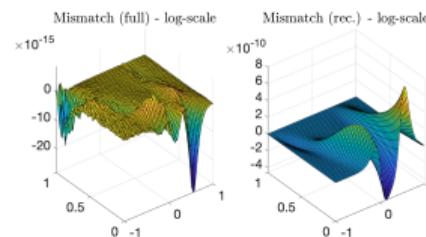
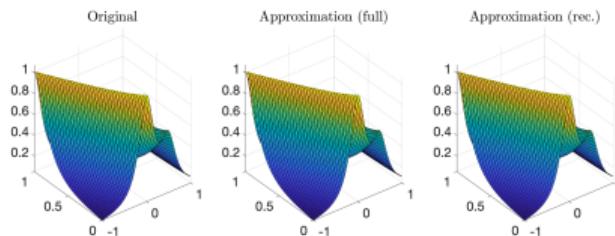
$$\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, p) = \frac{1}{1 + 25(s + p)^2} + \frac{0.5}{1 + 25(s - 0.5)^2} + \frac{0.1}{p + 25}$$



$$\begin{matrix} 1s & \times & 2s \\ [-1, 1] & \times & [0, 1] \end{matrix}$$

$$\mathbf{tab}_2 \in \mathbb{R}^{21 \times 21}$$

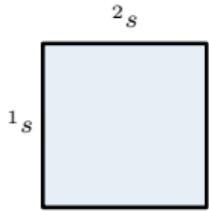
≈ 3.45 Ko ('real')



Forewords

Starting (motivating) examples - ReLU

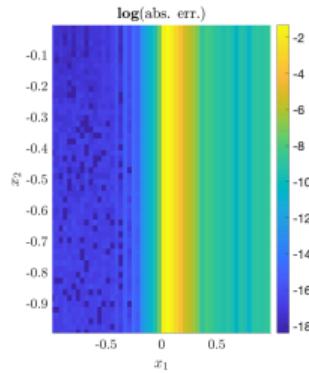
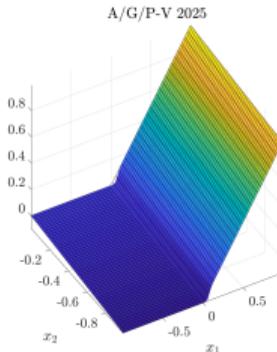
$$\mathbf{H}(^1s, ^2s) = \mathbf{ReLU}(^1s) + \frac{1}{100} {}^2s$$



$${}^1s \quad \times \quad {}^2s \\ [-1, 1] \quad \times \quad [0, 1]$$

$$\mathbf{tab}_2 \in \mathbb{R}^{20 \times 20}$$

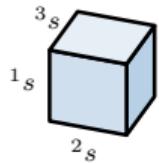
≈ 3.45 Ko ('real')



Forewords

Starting (motivating) examples - Airbus flutter case

$$\Sigma(^1s, ^2s, ^3s) = \Sigma(s, m, v) : s^2 M(m) x(s) + s B(m) x(s) + K(m) x(s) - G(s, v) = u(s), \mathbf{y}(s) = C \mathbf{x}(s)$$



$${}^1s \quad \times \quad {}^2s \quad \times \quad {}^3s \\ i[10, 35] \quad \times \quad [\underline{m}, \overline{m}] \quad \times \quad [\underline{v}, \overline{v}]$$

$$\mathbf{tab}_3 \in \mathbb{C}^{300 \times 10 \times 10}$$

≈ 468.75 Ko ('complex')



A. dos Reis de Souza et al., "Aircraft flutter suppression: from a parametric model to robust control", ECC, 2023.

Forewords

Starting (motivating) examples - Borehole function

$$\mathbf{H}(^1s, \dots, {}^8s) = \mathbf{H}(r_w, r, T_u, H_u, T_l, H_l, L, K_w) = \frac{2\pi T_u (H_u - H_l)}{\ln\left(\frac{r}{r_w}\right) \left(1 + \frac{2LT_u}{\ln(r/r_w)r_w^2K_w}\right) + \frac{T_u}{T_l}}$$



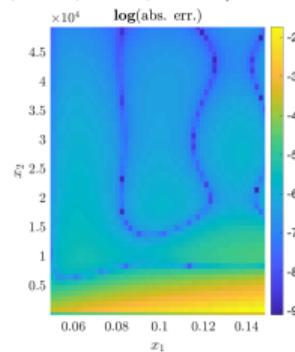
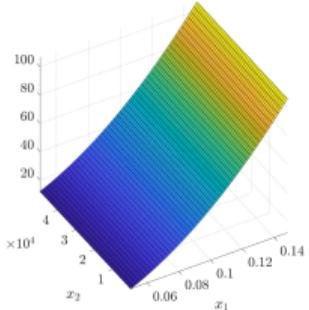
$${}^1s \quad \times \quad \cdots \quad \times \quad {}^8s \\ [r_w, \overline{r_w}] \quad \times \quad \cdots \quad \times \quad [\underline{K_w}, \overline{K_w}]$$

$\mathbf{tab}_8 \in \mathbb{C}^{8 \times 8 \times \cdots \times 8}$

$\approx 130 \text{ Mo ('real')}$

#	Alg.	Parameters	Dim.	CPU [s]	RMSE	min err.	max err.
30	A1	1e-09,1	$1.02e + 04$	19.3	0.00455	2e-09	0.061
	A2	1e-15,2	$1.02e+04$	39.1	0.00456	2.93e-09	0.0611

$$x_{3..8} = [93221.3376; 996.0245; 105.854; 765.3085; 1619.2701; 10834.7051] \\ A/G/P-V 2025$$



S. Surjanovic, "Borehole function", <https://www.sfu.ca/~ssurjano/borehole.html>.

Forewords

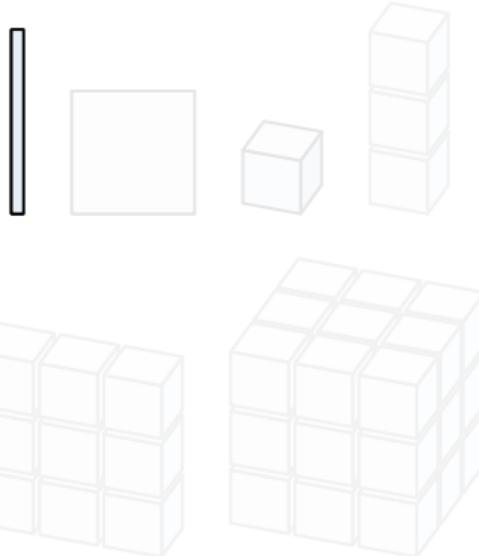
Data (and tensors)

Column / Row data

$$\left. \begin{array}{c} {}^1\lambda_{j_1}, {}^1\mu_{i_1} \end{array} \right\} \xrightarrow{\mathbf{H}(^1s)} \left\{ \begin{array}{c} \mathbf{w}_{j_1}, \mathbf{v}_{i_1} \end{array} \right.$$

1s	
${}^1\lambda_{1,\dots,k_1}$	\mathbf{W}_{k_1}
${}^1\mu_{1,\dots,q_1}$	\mathbf{V}_{q_1}

Tensors (1-D) tab₁



Forewords

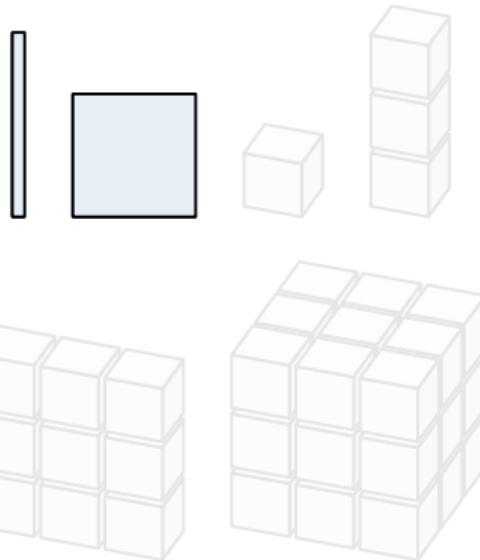
Data (and tensors)

Column / Row data

$$\left. \begin{array}{l} {}^1\lambda_{j_1}, {}^1\mu_{i_1} \\ {}^2\lambda_{j_2}, {}^2\mu_{i_2} \end{array} \right\} \xrightarrow{\mathbf{H}({}^1s, {}^2s)} \left\{ \begin{array}{l} {}^2\lambda_{j_1, \dots, k_2} \\ {}^2\mu_{1, \dots, q_2} \end{array} \right.$$

1s	2s	
${}^1\lambda_{1, \dots, k_1}$	\mathbf{W}_{k_1, k_2}	ϕ_{cr}
${}^1\mu_{1, \dots, q_1}$	ϕ_{rc}	\mathbf{V}_{q_1, q_2}

Tensors (2-D) tab₂



Forewords

Data (and tensors)

Column / Row data

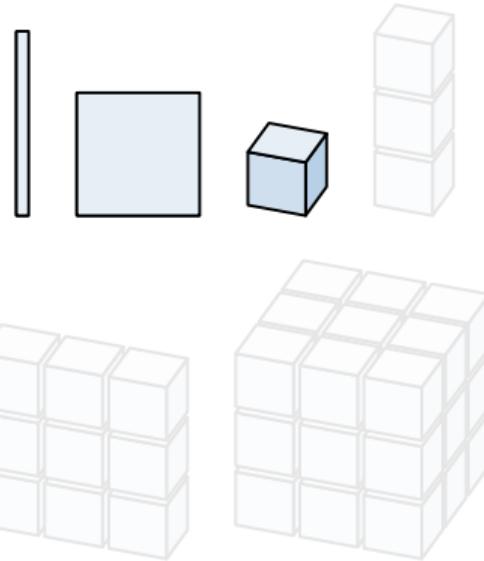
$$\left. \begin{array}{l} {}^1\lambda_{j_1}, {}^1\mu_{i_1} \\ {}^2\lambda_{j_2}, {}^2\mu_{i_2} \\ {}^3\lambda_{j_3}, {}^3\mu_{i_3} \end{array} \right\} \xrightarrow{\mathbf{H}({}^1s, {}^2s, {}^3s)} \left\{ \begin{array}{l} \mathbf{w}_{j_1, j_2, j_3}, \mathbf{v}_{i_1, i_2, i_3} \end{array} \right.$$

${}^3s = {}^3\lambda_{1, \dots, k_3}$		
1s	2s	${}^2\lambda_{1, \dots, k_2}$
${}^1\lambda_{1, \dots, k_1}$	$\mathbf{W}_{k_1, k_2, k_3}$	ϕ_{crc}
${}^1\mu_{1, \dots, q_1}$	ϕ_{rcc}	ϕ_{rrc}

$${}^3s = {}^3\mu_{1, \dots, q_3}$$

${}^3s = {}^3\mu_{1, \dots, q_3}$		
1s	2s	${}^2\mu_{1, \dots, q_2}$
${}^1\lambda_{1, \dots, k_1}$	ϕ_{crr}	ϕ_{crr}
${}^1\mu_{1, \dots, q_1}$	ϕ_{rcr}	$\mathbf{V}_{q_1, q_2, q_3}$

Tensors (3-D) tab_3



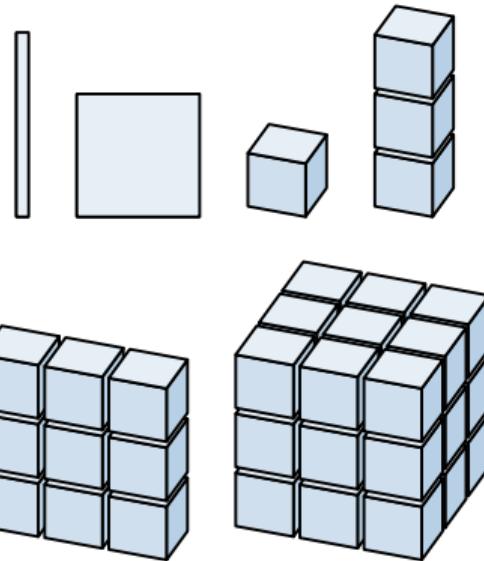
Forewords

Data (and tensors)

Column / Row data

$$\left. \begin{array}{l} {}^1\lambda_{j_1}, {}^1\mu_{i_1} \\ {}^2\lambda_{j_2}, {}^2\mu_{i_2} \\ {}^3\lambda_{j_3}, {}^3\mu_{i_3} \\ \vdots \\ {}^n\lambda_{j_n}, {}^n\mu_{i_n} \end{array} \right\} \xrightarrow{\mathbf{H}(^{1_s, \dots, n_s})} \left\{ \begin{array}{l} \mathbf{w}_{j_1, \dots, j_n}, \mathbf{v}_{i_1, \dots, i_n} \end{array} \right.$$

Tensors (n -D) tab_n



Forewords

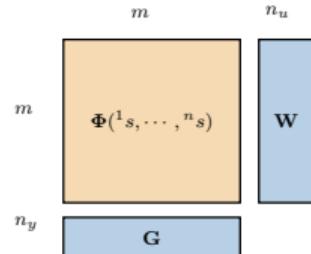
Problem description

Data-driven model approximation

Being given a n -dimensional tensor (data), we seek a multi-variate rational function $\hat{\mathbf{H}}$ and realization $(\mathbf{G}, \Phi, \mathbf{W})$

$$\hat{\mathbf{H}}({}^1s, {}^2s, \dots, {}^n s) = \mathbf{G}\Phi({}^1s, {}^2s, \dots, {}^n s)^{-1}\mathbf{W} \in \mathbb{C}$$

that interpolates the data.



Connection to standard dynamical system realization

A linear-in-state dynamical system parameterized in terms of parameters included in $\mathcal{S} = [{}^2s, \dots, {}^n s]^T \subset \mathbb{C}^{n-1}$

$$\begin{aligned} \mathbf{E}(\mathcal{S})\dot{\mathbf{x}}(t; \mathcal{S}) &= \mathbf{A}(\mathcal{S})\mathbf{x}(t; \mathcal{S}) + \mathbf{B}\mathbf{u}(t) \\ \mathbf{y}(t; \mathcal{S}) &= \mathbf{C}\mathbf{x}(t; \mathcal{S}) \end{aligned}$$

equivalently

$$\hat{\mathbf{H}}({}^1s, {}^2s, \dots, {}^n s) = \mathbf{C}(\mathcal{S}) \left[{}^1s \mathbf{E}(\mathcal{S}) - \mathbf{A}(\mathcal{S}) \right]^{-1} \mathbf{B} \in \mathbb{C}.$$

Forewords

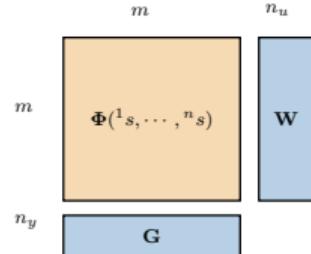
Problem description

Data-driven model approximation

Being given a n -dimensional tensor (data), we seek a multi-variate rational function $\hat{\mathbf{H}}$ and realization $(\mathbf{G}, \Phi, \mathbf{W})$

$$\hat{\mathbf{H}}({}^1s, {}^2s, \dots, {}^n s) = \mathbf{G}\Phi({}^1s, {}^2s, \dots, {}^n s)^{-1}\mathbf{W} \in \mathbb{C}$$

that interpolates the data.



Connection to standard dynamical system realization

A linear-in-state dynamical system parameterized in terms of parameters included in $\mathcal{S} = [{}^2s, \dots, {}^n s]^T \subset \mathbb{C}^{n-1}$

$$\begin{aligned} \mathbf{E}(\mathcal{S})\dot{\mathbf{x}}(t; \mathcal{S}) &= \mathbf{A}(\mathcal{S})\mathbf{x}(t; \mathcal{S}) + \mathbf{B}\mathbf{u}(t) \\ \mathbf{y}(t; \mathcal{S}) &= \mathbf{C}\mathbf{x}(t; \mathcal{S}) \end{aligned}$$

equivalently

$$\hat{\mathbf{H}}({}^1s, {}^2s, \dots, {}^n s) = \mathbf{C}(\mathcal{S}) \left[{}^1s \mathbf{E}(\mathcal{S}) - \mathbf{A}(\mathcal{S}) \right]^{-1} \mathbf{B} \in \mathbb{C}.$$

Forewords

Where we stand (some references)

1-D Two-sided Loewner

- ⇒ (interpolation) barycentric form
- ⇒ realization minimality
- ⇒ direct algorithm

1-D One-sided Loewner

- ⇒ (interpolation) barycentric form
- ⇒ direct algorithm

1-D AAA (Adaptive Anderson Antoulas - one-sided)

- ⇒ (mixed interpolation LS) barycentric form
- ⇒ iterative algorithm

2-D Parametric one-sided Loewner

- ⇒ (interpolation) barycentric form
- ⇒ realization (non-minimal)
- ⇒ direct algorithm

3-D Parametric AAA

- ⇒ (mixed interpolation LS) barycentric form
- ⇒ iterative algorithm

>3-D few results

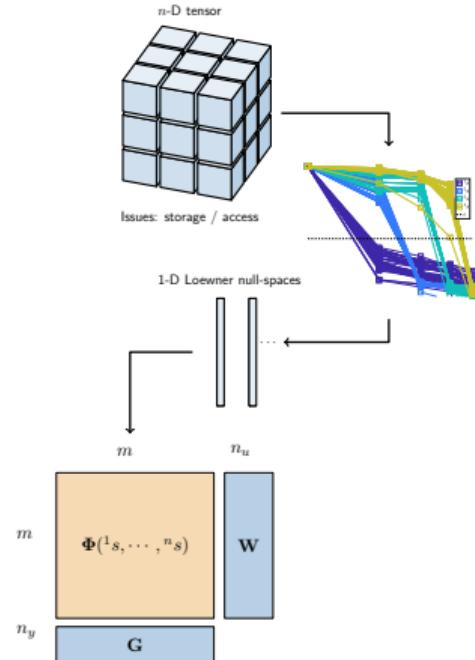
-
-  J-P. Berrut and N. Trefethen, "*Barycentric Lagrange Interpolation*", SIAM Review, 46(3), 2004.
 -  A.J. Mayo and A.C. Antoulas, "*A framework for the solution of the generalized realisation problem*", LAA, 425(2-3), 2007.
 -  A.C. Ionita and A.C. Antoulas, "*Data-Driven Parametrized Model Reduction in the Loewner Framework*", SIAM Journal on Scientific Computing, 36(3), 2014.
 -  T. Vojkovic, D. Quero, C. P-V and P. Vuillemin, "*Low-Order Parametric State-Space Modeling of MIMO Systems in the Loewner Framework*", SIAM Journal on Applied Dynamical Systems, 22(4), 2023.
 -  A.C. Rodriguez, L. Balicki and S. Gugercin, "*The p-AAA algorithm for data driven modeling of parametric dynamical systems*", SIAM Journal on Scientific Computing, 45(3), 2023.

Forewords

Contributions claim

List of contributions

- ▶ n -D tensor data to n -D Loewner matrix \mathbb{L}_n
- ▶ n -D recursive Sylvester equations
- ▶ n -variable transfer functions
- ▶ n -variable generalized realization
- ▶ Taming the curse of dimensionality
 - » in computation effort (flop)
 - » in storage needs (Bytes)
 - » in accuracy
- ▶ n -variable **decoupling**
 - » **KST** formulation for rational functions
 - » connection with **KAN**



Content

Forewords

Multi-variate data, function & Loewner matrix

Multi-variate realization

Taming the curse of dimensionality

Variables decoupling, KST and KANs

Comparison with Tensor Flow

Conclusion

Multi-variate data, function & Loewner matrix

1-D case

$$\begin{cases} P_c^{(1)} &:= \left\{ \left({}^1\lambda_{j_1}; \mathbf{w}_{j_1} \right), j_1 = 1, \dots, k_1 \right\} \\ P_r^{(1)} &:= \left\{ \left({}^1\mu_{i_1}; \mathbf{v}_{i_1} \right), i_1 = 1, \dots, q_1 \right\} \end{cases}$$

Loewner matrix

$$\mathbb{L}_1 \in \mathbb{C}^{q_1 \times k_1}$$

$$(\mathbb{L}_1)_{i_1, j_1} = \frac{\mathbf{v}_{i_1} - \mathbf{w}_{j_1}}{}^1\mu_{i_1} - {}^1\lambda_{j_1}$$

$$\mathbf{M}_1 \mathbb{L}_1 - \mathbb{L}_1 \boldsymbol{\Lambda}_1 = \mathbb{V}_1 \mathbf{R}_1 - \mathbf{L}_1 \mathbb{W}_1$$

Lagrangian form

$$\mathbf{g}({}^1s) = \frac{\sum_{j_1=1}^{k_1} \frac{c_{j_1} \mathbf{w}_{j_1}}{}^1s - {}^1\lambda_{j_1}}{\sum_{j_1=1}^{k_1} \frac{c_{j_1}}{}^1s - {}^1\lambda_{j_1}}$$

Null space

$$\text{span } (\mathbf{c}_1) = \mathcal{N}(\mathbb{L}_1)$$

$$\mathbf{c}_1 = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_{k_1} \end{bmatrix} \in \mathbb{C}^{k_1}$$

Multi-variate data, function & Loewner matrix

1-D case (example)

Data generated from $\mathbf{H}(^1s) = \mathbf{H}(s) = (s^2 + 4)/(s + 1)$ of complexity (2)

$$\begin{array}{rcl} {}^1\lambda_{j_1} & = & [1, 3, 5] \\ {}^1\mu_{i_1} & = & [2, 4, 6, 8] \end{array} \left. \right\} \xrightarrow{\mathbf{H}} \begin{array}{rcl} \mathbf{w}_{j_1} & = & [5/2, 13/4, 29/6] \\ \mathbf{v}_{i_1} & = & [8/3, 4, 40/7, 68/9] \end{array}$$

Loewner matrix

$$\mathbb{L}_1 = \begin{bmatrix} \frac{1}{6} & \frac{7}{12} & \frac{13}{18} \\ \frac{1}{2} & \frac{3}{4} & \frac{5}{6} \\ \frac{9}{14} & \frac{23}{28} & \frac{37}{42} \\ \frac{13}{18} & \frac{31}{36} & \frac{49}{54} \end{bmatrix}$$

Null space

$$\mathbf{c}_1 = \begin{bmatrix} \frac{1}{3} \\ -\frac{4}{3} \\ 1 \end{bmatrix}$$

Lagrangian form

$$\mathbf{g}(s) = \frac{\frac{5}{6(s-1)} - \frac{13}{3(s-3)} + \frac{29}{6(s-5)}}{\frac{1}{3(s-1)} - \frac{4}{3(s-3)} + \frac{1}{s-5}} = \mathbf{H}(s)$$

Multi-variate data, function & Loewner matrix

2-D case

$$\begin{cases} P_c^{(2)} &:= \left\{ (^1\lambda_{j_1}, ^2\lambda_{j_2}; \mathbf{w}_{j_1, j_2}), \ j_1 = 1, \dots, k_1 \quad j_2 = 1, \dots, k_2 \right\} \\ P_r^{(2)} &:= \left\{ (^1\mu_{i_1}, ^2\mu_{i_2}; \mathbf{v}_{i_1, i_2}), \ i_1 = 1, \dots, q_1 \quad i_2 = 1, \dots, q_2 \right\} \end{cases}$$

Loewner matrix

$$\mathbb{L}_2 \in \mathbb{C}^{q_1 q_2 \times k_1 k_2}$$

$$\ell_{j_1, j_2}^{i_1, i_2} = \frac{\mathbf{v}_{i_1, i_2} - \mathbf{w}_{j_1, j_2}}{(^1\mu_{i_1} - ^1\lambda_{j_1})(^2\mu_{i_2} - ^2\lambda_{j_2})}$$

$$\begin{cases} \mathbf{M}_2 \mathbb{X} - \mathbb{X} \boldsymbol{\Lambda}_2 &= \mathbb{V}_2 \mathbf{R}_2 - \mathbf{L}_2 \mathbb{W}_2 \\ \mathbf{M}_1 \mathbb{L}_2 - \mathbb{L}_2 \boldsymbol{\Lambda}_1 &= \mathbb{X} \end{cases}$$

Lagrangian form

$$\mathbf{g}(^1s, ^2s) = \frac{\sum_{j_1=1}^{k_1} \sum_{j_2=1}^{k_2} \frac{c_{j_1, j_2} \mathbf{w}_{j_1, j_2}}{(^1s - ^1\lambda_{j_1})(^2s - ^2\lambda_{j_2})}}{\sum_{j_1=1}^{k_1} \sum_{j_2=1}^{k_2} \frac{c_{j_1, j_2}}{(^1s - ^1\lambda_{j_1})(^2s - ^2\lambda_{j_2})}}$$

Null space

$$\text{span } (\mathbf{c}_2) = \mathcal{N}(\mathbb{L}_2)$$

$$\mathbf{c}_2 = \begin{bmatrix} c_{1,1} \\ \vdots \\ \hline c_{1,k_2} \\ \vdots \\ \hline c_{k_1,1} \\ \vdots \\ c_{k_1,k_2} \end{bmatrix} \in \mathbb{C}^{k_1 k_2}$$

Multi-variate data, function & Loewner matrix

2-D case (example)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

$$\left. \begin{array}{l} {}^1\lambda_{j_1} = [1, 3, 5] \\ {}^1\mu_{i_1} = [0, 2, 4] \\ {}^2\lambda_{j_2} = [-1, -3] \\ {}^2\mu_{i_2} = [-2, -4] \end{array} \right\} \xrightarrow{\mathbf{H}} \left[\begin{array}{ccc|cc} -\frac{1}{3} & -\frac{3}{5} & -\frac{1}{2} & -\frac{2}{3} \\ -\frac{9}{5} & -\frac{27}{7} & -3 & -\frac{9}{2} \\ -\frac{25}{7} & -\frac{25}{3} & -\frac{25}{4} & -10 \\ \hline 0 & 0 & 0 & 0 \\ -1 & -2 & -\frac{8}{5} & -\frac{16}{7} \\ -\frac{8}{3} & -6 & -\frac{32}{7} & -\frac{64}{9} \end{array} \right]$$

Loewner matrix

$$\mathbb{L}_2 = \left[\begin{array}{cc|cc|cc} \frac{1}{3} & -\frac{3}{5} & \frac{3}{5} & -\frac{9}{7} & \frac{5}{7} & -\frac{5}{3} \\ \frac{1}{9} & \frac{3}{5} & \frac{1}{5} & \frac{9}{7} & \frac{5}{21} & \frac{5}{3} \\ \hline \frac{19}{15} & -1 & \frac{1}{5} & -\frac{79}{35} & \frac{23}{35} & -\frac{101}{45} \\ \hline \frac{41}{63} & \frac{59}{35} & -\frac{17}{105} & \frac{11}{7} & \frac{1}{7} & \frac{127}{63} \\ \frac{89}{63} & -\frac{139}{105} & \frac{97}{35} & -\frac{5}{7} & -1 & -\frac{79}{21} \\ \hline \frac{61}{81} & \frac{293}{135} & \frac{239}{135} & \frac{205}{63} & -\frac{223}{189} & \frac{11}{9} \end{array} \right]$$

Null space

$$\mathbf{c}_2 = \left[\begin{array}{c} -\frac{1}{3} \\ \frac{5}{9} \\ \hline \frac{10}{9} \\ -\frac{14}{9} \\ \hline -\frac{7}{9} \\ 1 \end{array} \right]$$

Multi-variate data, function & Loewner matrix

2-D case (example)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

$$\left. \begin{array}{lcl} {}^1\lambda_{j_1} & = & [1, 3, 5] \\ {}^1\mu_{i_1} & = & [0, 2, 4] \\ {}^2\lambda_{j_2} & = & [-1, -3] \\ {}^2\mu_{i_2} & = & [-2, -4] \end{array} \right\} \xrightarrow{\mathbf{H}} \left[\begin{array}{ccc|cc} -\frac{1}{3} & -\frac{3}{5} & -\frac{1}{2} & -\frac{2}{3} \\ -\frac{9}{5} & -\frac{27}{7} & -3 & -\frac{9}{2} \\ -\frac{25}{7} & -\frac{25}{3} & -\frac{25}{4} & -10 \\ \hline 0 & 0 & 0 & 0 \\ -1 & -2 & -\frac{8}{5} & -\frac{16}{7} \\ -\frac{8}{3} & -6 & -\frac{32}{7} & -\frac{64}{9} \end{array} \right]$$

Lagrangian form

$$\mathbf{g}(s, t) = -\frac{\frac{1}{9(s-1)(t+1)} - \frac{1}{3(s-1)(t+3)} - \frac{2}{(s-3)(t+1)} + \frac{6}{(s-3)(t+3)} + \frac{25}{9(s-5)(t+1)} - \frac{25}{3(s-5)(t+3)}}{\frac{1}{3(s-1)(t+1)} - \frac{5}{9(s-1)(t+3)} - \frac{10}{9(s-3)(t+1)} + \frac{14}{9(s-3)(t+3)} + \frac{7}{9(s-5)(t+1)} - \frac{1}{(s-5)(t+3)}} = \mathbf{H}(s, t)$$

Multi-variate data, function & Loewner matrix

n-D case

$$\begin{cases} P_c^{(n)} := \left\{ (^1\lambda_{j_1}, ^2\lambda_{j_2}, \dots, ^n\lambda_{j_n}; \mathbf{w}_{j_1, j_2, \dots, j_n}), j_l = 1, \dots, k_l, l = 1, \dots, n \right\} \\ P_r^{(n)} := \left\{ (^1\mu_{i_1}, ^2\mu_{i_2}, \dots, ^n\mu_{i_n}; \mathbf{v}_{i_1, i_2, \dots, i_n}), i_l = 1, \dots, q_l, l = 1, \dots, n \right\} \end{cases}$$

Loewner matrix

$$\mathbb{L}_n \in \mathbb{C}^{q_1 q_2 \cdots q_n \times k_1 k_2 \cdots k_n}$$

$$\ell_{j_1, j_2, \dots, j_n}^{i_1, i_2, \dots, i_n} = \frac{\mathbf{v}_{i_1, i_2, \dots, i_n} - \mathbf{w}_{j_1, j_2, \dots, j_n}}{(^1\mu_{i_1} - ^1\lambda_{j_1}) \cdots (^n\mu_{i_n} - ^n\lambda_{j_n})}$$

$$\begin{cases} \mathbf{M}_n \mathbb{X}_1 - \mathbb{X}_1 \boldsymbol{\Lambda}_n &= \mathbb{V}_n \mathbf{R}_n - \mathbf{L}_n \mathbb{W}_n, \\ \mathbf{M}_{n-1} \mathbb{X}_2 - \mathbb{X}_2 \boldsymbol{\Lambda}_{n-1} &= \mathbb{X}_1, \\ &\dots \\ \mathbf{M}_1 \mathbb{L}_n - \mathbb{L}_n \boldsymbol{\Lambda}_1 &= \mathbb{X}_{n-1}. \end{cases}$$

Lagrangian form

$$\mathbf{g}(^1s, \dots, ^ns) = \frac{\sum_{j_1=1}^{k_1} \cdots \sum_{j_n=1}^{k_n} \frac{c_{j_1, \dots, j_n} \mathbf{w}_{j_1, \dots, j_n}}{(^1s - ^1\lambda_{j_1}) \cdots (^n s - ^n\lambda_{j_n})}}{\sum_{j_1=1}^{k_1} \cdots \sum_{j_n=1}^{k_n} \frac{c_{j_1, \dots, j_n}}{(^1s - ^1\lambda_{j_1}) \cdots (^n s - ^n\lambda_{j_n})}}$$

Null space

$$\text{span } (\mathbf{c}_n) = \mathcal{N}(\mathbb{L}_n)$$

$$\mathbf{c}_n = \begin{bmatrix} c_{1, \dots, 1} \\ \vdots \\ \hline c_{1, \dots, k_n} \\ \vdots \\ \hline c_{k_1, \dots, 1} \\ \vdots \\ c_{k_1, \dots, k_n} \end{bmatrix} \in \mathbb{C}^{k_1 \cdots k_n}$$

Content

Forewords

Multi-variate data, function & Loewner matrix

Multi-variate realization

Taming the curse of dimensionality

Variables decoupling, KST and KANs

Comparison with Tensor Flow

Conclusion

Multi-variate realization

1-D case (example cont'd)

Data generated from $\mathbf{H}(^1s) = \mathbf{H}(s) = (s^2 + 4)/(s + 1)$ of complexity (2)

$$\mathbf{g}(s) = \frac{\frac{5}{6(s-1)} - \frac{13}{3(s-3)} + \frac{29}{6(s-5)}}{\frac{1}{3(s-1)} - \frac{4}{3(s-3)} + \frac{1}{s-5}}$$

Lagrangian realization $\hat{\mathbf{H}}(s) = \mathbf{W}\Phi(s)^{-1}\mathbf{G}$

$$\Phi(s) = \begin{bmatrix} s-1 & 3-s & 0 \\ s-1 & 0 & 5-s \\ -\frac{1}{3} & \frac{4}{3} & -1 \end{bmatrix}$$

$$\mathbf{W} = \begin{bmatrix} \frac{5}{6} & -\frac{13}{3} & \frac{29}{6} \end{bmatrix}$$

$$\mathbf{G}^\top = \begin{bmatrix} 0 & 0 & -1 \end{bmatrix}$$

Multi-variate realization

2-D case (example cont'd)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

$$\mathbf{g}(s, t) = -\frac{\frac{1}{9(s-1)(t+1)} - \frac{1}{3(s-1)(t+3)} - \frac{2}{(s-3)(t+1)} + \frac{6}{(s-3)(t+3)} + \frac{25}{9(s-5)(t+1)} - \frac{25}{3(s-5)(t+3)}}{\frac{1}{3(s-1)(t+1)} - \frac{5}{9(s-1)(t+3)} - \frac{10}{9(s-3)(t+1)} + \frac{14}{9(s-3)(t+3)} + \frac{7}{9(s-5)(t+1)} - \frac{1}{(s-5)(t+3)}}$$

Lagrangian realization $\hat{\mathbf{H}}(s, t) = \mathbf{W}\Phi(s, t)^{-1}\mathbf{G}$

$$\Phi(s, t) = \begin{bmatrix} s-1 & 3-s & 0 & | & 0 & | & 0 & | & 0 \\ s-1 & 0 & 5-s & | & 0 & | & 0 & | & 0 \\ -\frac{1}{3} & -\frac{10}{9} & -\frac{7}{9} & | & t+1 & | & 0 & | & 0 \\ \frac{5}{9} & -\frac{14}{9} & 1 & | & -t-3 & | & 0 & | & 0 \\ -\frac{1}{9} & -2 & -\frac{25}{9} & | & 0 & | & t+1 & | & -\frac{1}{2} \\ -\frac{1}{3} & 6 & -\frac{25}{3} & | & 0 & | & -t-3 & | & -\frac{1}{2} \end{bmatrix}$$

$$\mathbf{W} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & | & -1 \end{bmatrix}$$

$$\mathbf{G}^\top = \begin{bmatrix} 0 & 0 & | & 1/2 & -1/2 & | & 0 & 0 \end{bmatrix}$$

→ (3,3) block is unimodular !

Multi-variate realization

2-D case (example cont'd)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

$$\mathbf{g}(s, t) = -\frac{\frac{1}{9(s-1)(t+1)} - \frac{1}{3(s-1)(t+3)} - \frac{2}{(s-3)(t+1)} + \frac{6}{(s-3)(t+3)} + \frac{25}{9(s-5)(t+1)} - \frac{25}{3(s-5)(t+3)}}{\frac{1}{3(s-1)(t+1)} - \frac{5}{9(s-1)(t+3)} - \frac{10}{9(s-3)(t+1)} + \frac{14}{9(s-3)(t+3)} + \frac{7}{9(s-5)(t+1)} - \frac{1}{(s-5)(t+3)}}$$

Lagrangian realization $\hat{\mathbf{H}}_{\mathbf{c}}(s, t) = \mathbf{W}_{\mathbf{c}}(t)\Phi_{\mathbf{c}}(s, t)^{-1}\mathbf{G}_{\mathbf{c}}$

$$\Phi_{\mathbf{c}}(s, t) = \left[\begin{array}{ccc|c} s-1 & 3-s & 0 & 0 \\ s-1 & 0 & 5-s & 0 \\ -\frac{1}{3} & \frac{10}{9} & -\frac{7}{9} & t+1 \\ \frac{5}{9} & -\frac{14}{9} & 1 & -t-3 \end{array} \right]$$

$$\mathbf{W}_{\mathbf{c}}(t) = \left[\begin{array}{ccc|c} -\frac{2t}{9} & 4t & -\frac{50t}{9} & 0 \end{array} \right]$$

$$\mathbf{G}_{\mathbf{c}}^T = \left[\begin{array}{cc|cc} 0 & 0 & \frac{1}{2} & -\frac{1}{2} \end{array} \right]$$

Multi-variate realization

Generalized n -D Lagrangian realization

$$\mathbf{g}(^1s, ^2s, \dots, ^ns) = \frac{\sum_{j_1=1}^{k_1} \sum_{j_2=1}^{k_2} \cdots \sum_{j_n=1}^{k_n} \frac{c_{j_1, j_2, \dots, j_n} \mathbf{w}_{j_1, j_2, \dots, j_n}}{(^1s - \textcolor{brown}{1}\lambda_{j_1})(^2s - \textcolor{brown}{2}\lambda_{j_2}) \cdots (^ns - \textcolor{brown}{n}\lambda_{j_n})}}{\sum_{j_1=1}^{k_1} \sum_{j_2=1}^{k_2} \cdots \sum_{j_n=1}^{k_n} \frac{c_{j_1, j_2, \dots, j_n}}{(^1s - \textcolor{brown}{1}\lambda_{j_1})(^2s - \textcolor{brown}{2}\lambda_{j_2}) \cdots (^ns - \textcolor{brown}{n}\lambda_{j_n})}},$$

Theorem: n -D Lagrangian realization

A $2\ell + \kappa - 1 = m$ -th order realization $(\mathbf{G}, \Phi, \mathbf{W})$ of the multi-variate function $\hat{\mathbf{H}}$ in barycentric form, satisfying $\hat{\mathbf{H}}(^1s, \dots, ^ns) = \mathbf{W}\Phi(^1s, ^2s, \dots, ^ns)^{-1}\mathbf{G}$, is given by,

$$\begin{aligned} \Phi(^1s, \dots, ^ns) &= \begin{bmatrix} \Gamma(1 : \kappa - 1, :) & | & \mathbf{0}_{\kappa-1, \ell-1} & | & \mathbf{0}_{\kappa-1, \ell} \\ \bar{\mathbb{A}}^{\text{Lag}} & | & \bar{\Delta}(1 : \ell - 1, :)^\top & | & \mathbf{0}_{\ell, \ell} \\ \bar{\mathbb{B}}^{\text{Lag}} & | & \mathbf{0}_{\ell, \ell-1} & | & \Delta^\top \end{bmatrix} \in \mathbb{C}^{m \times m} \\ \mathbf{G} &= \begin{bmatrix} \mathbf{0}_{\kappa-1, 1} \\ \bar{\Delta}(\ell, :)^\top \\ \mathbf{0}_{\ell, 1} \end{bmatrix} \in \mathbb{C}^{m \times 1} \\ \mathbf{W} &= \begin{bmatrix} \mathbf{0}_{1, \kappa} & | & \mathbf{0}_{1, \ell-1} & | & -\mathbf{e}_\ell^\top \end{bmatrix} \in \mathbb{C}^{1 \times m} \end{aligned}$$

where $\mathbb{A}^{\text{Lag}}, \mathbb{B}^{\text{Lag}} \in \mathbb{C}^{\ell \times \kappa}$ are appropriately chosen, according to the chosen pseudo-companion basis.

Multi-variate realization

Generalized n -D Lagrangian realization (focus on left / right variable sets)

$$\Phi(^1s, \dots, ^n s) = \begin{bmatrix} \Gamma(1 : \kappa - 1, :) & | & \mathbf{0}_{\kappa-1, \ell-1} & | & \mathbf{0}_{\kappa-1, \ell} \\ \bar{\mathbb{A}}^{\text{Lag}} & | & \Delta(1 : \ell - 1, :)^\top & | & \mathbf{0}_{\ell, \ell} \\ \bar{\mathbb{B}}^{\text{Lag}} & | & \mathbf{0}_{\ell, \ell-1} & | & \Delta^\top \end{bmatrix} \in \mathbb{C}^{m \times m}$$

$$\Gamma = {}^1\mathbb{X}^{\text{Lag}} \otimes {}^2\mathbb{X}^{\text{Lag}} \otimes \dots \otimes {}^k\mathbb{X}^{\text{Lag}} \in \mathbb{C}^{\kappa \times \kappa}[{}^1s, \dots, {}^k s]$$

$$\Delta = {}^{k+1}\mathbb{X}^{\text{Lag}} \otimes {}^{k+2}\mathbb{X}^{\text{Lag}} \otimes \dots \otimes {}^n\mathbb{X}^{\text{Lag}} \in \mathbb{C}^{\ell \times \ell}[{}^{k+1}s, \dots, {}^n s]$$

$$\begin{aligned} {}^j\mathbb{X}^{\text{Lag}} &= \begin{bmatrix} {}^j\mathbf{x}_1 & -{}^j\mathbf{x}_2 & 0 & \cdots & 0 \\ {}^j\mathbf{x}_1 & 0 & -{}^j\mathbf{x}_3 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ {}^j\mathbf{x}_1 & 0 & \cdots & 0 & -{}^j\mathbf{x}_{n_j} \\ {}^j q_1 & {}^j q_2 & \cdots & {}^j q_{n_j-1} & {}^j q_{n_j} \end{bmatrix} \in \mathbb{C}^{n_j \times n_j} \\ {}^j\mathbf{x}_i &= {}^j s - {}^j \lambda_i \end{aligned}$$

Facts

- Left / right variables splitting

Γ and Δ

- ${}^j\mathbb{X}^{\text{Lag}}$ is unimodular, i.e.

$$\det({}^j\mathbb{X}^{\text{Lag}}) = 1$$

- ... so are Γ and Δ

Multi-variate realization

Generalized n -D Lagrangian realization (focus on barycentric weights \mathbb{A}^{Lag} and \mathbb{B}^{Lag})

$$\Phi(^1s, \dots, ^ns) = \begin{bmatrix} \Gamma(1 : \kappa - 1, :) & \mathbf{0}_{\kappa-1, \ell-1} & \mathbf{0}_{\kappa-1, \ell} \\ \bar{\mathbb{A}}^{\text{Lag}} & \Delta(1 : \ell - 1, :)^\top & \mathbf{0}_{\ell, \ell} \\ \bar{\mathbb{B}}^{\text{Lag}} & \mathbf{0}_{\ell, \ell-1} & \Delta^\top \end{bmatrix} \in \mathbb{C}^{m \times m}$$

$$\begin{aligned}\mathbb{A}^{\text{Lag}} &= \begin{bmatrix} \alpha_{1,1} & \alpha_{1,2} & \cdots & \alpha_{1,m+1} \\ \alpha_{2,1} & \alpha_{2,2} & \cdots & \alpha_{2,m+1} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{n+1,1} & \alpha_{n+1,2} & \cdots & \alpha_{n+1,m+1} \end{bmatrix} \\ \mathbf{c}_n &= \text{vec}(\mathbb{A}^{\text{Lag}})\end{aligned}$$

Facts

- \mathbb{A}^{Lag} is simply some rearrangement of $\mathcal{N}(\mathbb{L}_n) = \mathbf{c}_n$
- \mathbb{B}^{Lag} follows

Multi-variate realization

Generalized n -D Lagrangian realization (control the complexity)

$$\Phi(^1s, \dots, ^ns) = \begin{bmatrix} \Gamma(1 : \kappa - 1, :) & \mathbf{0}_{\kappa-1, \ell-1} & \mathbf{0}_{\kappa-1, \ell} \\ \bar{\mathbb{A}}^{\text{Lag}} & \Delta(1 : \ell - 1, :)^\top & \mathbf{0}_{\ell, \ell} \\ \bar{\mathbb{B}}^{\text{Lag}} & \mathbf{0}_{\ell, \ell-1} & \Delta^\top \end{bmatrix} \in \mathbb{C}^{m \times m}$$

$$m = 2\ell + \kappa - 1$$

$$\begin{aligned} \kappa &= \prod_{j=1}^k n_j \\ \ell &= \prod_{j=k+1}^n n_j \end{aligned}$$

Facts

- ▶ Γ gathers the first group of parameters $^1s, \dots, ^k_s$
- ▶ Δ gathers the second group of parameters $^{k+1}s, \dots, ^n_s$

Complexity

Re-ordering allows complexity control, e.g.
according to the order of each variable ${}^j s$

Multi-variate realization

3-D case (example)

Data generated from $\mathbf{H}(^1s, ^2s, ^3s) = \mathbf{H}(s, t, p) = (s + pt)/(p^2 + s + t)$ of complexity (1, 1, 2)

$$\begin{aligned} \mathbf{c}_3^\top &= \left[\frac{1}{2} \quad -\frac{39}{28} \quad \frac{13}{14} \mid -\frac{15}{28} \quad \frac{41}{28} \quad -\frac{27}{28} \mid -\frac{15}{28} \quad \frac{41}{28} \quad -\frac{27}{28} \mid \frac{4}{7} \quad -\frac{43}{28} \quad 1 \right] \\ \mathbb{W}_3 &= \left[\frac{1}{4} \quad \frac{8}{39} \quad \frac{9}{52} \mid \frac{17}{30} \quad \frac{20}{41} \quad \frac{23}{54} \mid \frac{3}{10} \quad \frac{10}{41} \quad \frac{11}{54} \mid \frac{19}{32} \quad \frac{22}{43} \quad \frac{25}{56} \right] \end{aligned}$$

Arrangement #1

$(s) - (t, p)$, one obtains a realization of dimension $m = 13$:

$$\kappa = 2 \text{ and } \ell = 2 \times 3$$

$$\Delta(s) = {}^1\mathbb{X}^{\text{Lag}}(s)$$

$$\Gamma(t, p) = {}^2\mathbb{X}^{\text{Lag}}(t) \otimes {}^3\mathbb{X}^{\text{Lag}}(p)$$

Arrangement #2

$(s, t) - (p)$, one obtains a realization of dimension $m = 9$:

$$\kappa = 2 \times 2 \text{ and } \ell = 3$$

$$\Delta(s, t) = {}^1\mathbb{X}^{\text{Lag}}(s) \otimes {}^2\mathbb{X}^{\text{Lag}}(t)$$

$$\Gamma(p) = {}^3\mathbb{X}^{\text{Lag}}(p)$$

Multi-variate realization

3-D case (example)

Data generated from $\mathbf{H}(^1s, ^2s, ^3s) = \mathbf{H}(s, t, p) = (s + pt)/(p^2 + s + t)$ of complexity (1, 1, 2)

$$\begin{array}{lcl} \mathbf{c}_3^\top & = & \left[\begin{array}{ccc|ccc|ccc|cc} \frac{1}{2} & -\frac{39}{28} & \frac{13}{14} & | & -\frac{15}{28} & \frac{41}{28} & -\frac{27}{28} & | & -\frac{15}{28} & \frac{41}{28} & -\frac{27}{28} & | & \frac{4}{7} & -\frac{43}{28} \\ \frac{1}{4} & \frac{8}{39} & \frac{9}{52} & | & \frac{17}{30} & \frac{20}{41} & \frac{23}{54} & | & \frac{3}{10} & \frac{10}{41} & \frac{11}{54} & | & \frac{19}{32} & \frac{22}{43} & \frac{25}{56} \end{array} \right] \\ \mathbf{W}_3 & = & \left[\begin{array}{ccc|ccc|ccc|cc} \frac{1}{2} & -\frac{39}{28} & \frac{13}{14} & | & -\frac{15}{28} & \frac{41}{28} & -\frac{27}{28} & | & -\frac{15}{28} & \frac{41}{28} & -\frac{27}{28} & | & \frac{4}{7} & -\frac{43}{28} \\ \frac{1}{4} & \frac{8}{39} & \frac{9}{52} & | & \frac{17}{30} & \frac{20}{41} & \frac{23}{54} & | & \frac{3}{10} & \frac{10}{41} & \frac{11}{54} & | & \frac{19}{32} & \frac{22}{43} & \frac{25}{56} \end{array} \right] \end{array}$$

$$\Phi = \left[\begin{array}{cccc|cccc|cccc} (s-2)(t-1) & -(s-2)(t-3) & -(t-1)(s-4) & (s-4)(t-3) & | & 0 & 0 & | & 0 & 0 & 0 & 0 \\ 1 - \frac{s}{2} & \frac{s}{2} - 1 & \frac{s}{2} - 2 & 2 - \frac{s}{2} & | & 0 & 0 & | & 0 & 0 & 0 & 0 \\ \frac{1}{2} - \frac{t}{2} & \frac{t}{2} - \frac{3}{2} & \frac{t}{2} - \frac{1}{2} & \frac{3}{2} - \frac{t}{2} & | & 0 & 0 & | & 0 & 0 & 0 & 0 \\ \hline -\frac{1}{2} & -\frac{15}{28} & -\frac{15}{28} & \frac{4}{7} & | & p-5 & p-5 & | & 0 & 0 & 0 & 0 \\ -\frac{39}{28} & \frac{41}{28} & \frac{41}{28} & -\frac{43}{28} & | & 6-p & 0 & | & 0 & 0 & 0 & 0 \\ \frac{13}{14} & -\frac{27}{28} & -\frac{27}{28} & 1 & | & 0 & 7-p & | & 0 & 0 & 0 & 0 \\ \hline -\frac{1}{8} & -\frac{17}{56} & -\frac{9}{56} & \frac{19}{56} & | & 0 & 0 & | & p-5 & p-5 & \frac{1}{2} \\ -\frac{2}{7} & \frac{5}{7} & \frac{5}{14} & -\frac{11}{14} & | & 0 & 0 & | & 6-p & 0 & -1 \\ \frac{9}{56} & -\frac{23}{56} & -\frac{11}{56} & \frac{25}{56} & | & 0 & 0 & | & 0 & 7-p & \frac{1}{2} \end{array} \right]$$

$$\mathbf{W} = -\mathbf{e}_9^\top \text{ and } \mathbf{G}^\top = \left[\begin{array}{ccccc} \mathbf{0}_{1,3} & | & 1/2 & -1 & 1/2 & | & \mathbf{0}_{1,3} \end{array} \right]$$

Multi-variate realization

3-D case (example)

Data generated from $\mathbf{H}(^1s, ^2s, ^3s) = \mathbf{H}(s, t, p) = (s + pt)/(p^2 + s + t)$ of complexity (1, 1, 2)

$$\begin{array}{lcl} \mathbf{c}_3^\top & = & \left[\begin{array}{ccc|ccccc|ccccc} \frac{1}{2} & -\frac{39}{28} & \frac{13}{14} & | & -\frac{15}{28} & \frac{41}{28} & -\frac{27}{28} & | & -\frac{15}{28} & \frac{41}{28} & -\frac{27}{28} & | & \frac{4}{7} & -\frac{43}{28} & 1 \\ \frac{1}{4} & \frac{8}{39} & \frac{9}{52} & | & \frac{17}{30} & \frac{20}{41} & \frac{23}{54} & | & \frac{3}{10} & \frac{10}{41} & \frac{11}{54} & | & \frac{19}{32} & \frac{22}{43} & \frac{25}{56} \end{array} \right] \\ \mathbb{W}_3 & = & \left[\begin{array}{cccc|cc} (s-2)(t-1) & -(s-2)(t-3) & -(t-1)(s-4) & (s-4)(t-3) & 0 & 0 \\ 1-\frac{s}{2} & \frac{s}{2}-1 & \frac{s}{2}-2 & 2-\frac{s}{2} & 0 & 0 \\ \frac{1}{2}-\frac{t}{2} & \frac{t}{2}-\frac{3}{2} & \frac{t}{2}-\frac{1}{2} & \frac{3}{2}-\frac{t}{2} & 0 & 0 \\ -\frac{1}{2} & -\frac{15}{28} & -\frac{15}{28} & \frac{4}{7} & p-5 & p-5 \\ -\frac{39}{28} & \frac{41}{28} & \frac{41}{28} & -\frac{43}{28} & 6-p & 0 \\ \frac{13}{14} & -\frac{27}{28} & -\frac{27}{28} & 1 & 0 & 7-p \end{array} \right] \end{array}$$

$$\Phi_c = \left[\begin{array}{cccc|cc} (s-2)(t-1) & -(s-2)(t-3) & -(t-1)(s-4) & (s-4)(t-3) & 0 & 0 \\ 1-\frac{s}{2} & \frac{s}{2}-1 & \frac{s}{2}-2 & 2-\frac{s}{2} & 0 & 0 \\ \frac{1}{2}-\frac{t}{2} & \frac{t}{2}-\frac{3}{2} & \frac{t}{2}-\frac{1}{2} & \frac{3}{2}-\frac{t}{2} & 0 & 0 \\ -\frac{1}{2} & -\frac{15}{28} & -\frac{15}{28} & \frac{4}{7} & p-5 & p-5 \\ -\frac{39}{28} & \frac{41}{28} & \frac{41}{28} & -\frac{43}{28} & 6-p & 0 \\ \frac{13}{14} & -\frac{27}{28} & -\frac{27}{28} & 1 & 0 & 7-p \end{array} \right]$$

$$\mathbf{W}_c(p) = \left[\begin{array}{ccccc} \frac{p}{28} + \frac{1}{14} & -\frac{3p}{28} - \frac{1}{14} & -\frac{p}{28} - \frac{1}{7} & \frac{3p}{28} + \frac{1}{7} & 0 & 0 \end{array} \right] \text{ and } \mathbf{G}_c^\top = \left[\begin{array}{ccccc} \mathbf{0}_{1,3} & 1/2 & -1 & 1/2 \end{array} \right]$$

Multi-variate realization

(Compressed) generalized n -D Lagrangian realization

$$\mathbf{g}(^1s, ^2s, \dots, ^ns) = \frac{\sum_{j_1=1}^{k_1} \sum_{j_2=1}^{k_2} \cdots \sum_{j_n=1}^{k_n} \frac{c_{j_1, j_2, \dots, j_n} \mathbf{w}_{j_1, j_2, \dots, j_n}}{(^1s - \textcolor{orange}{1}\lambda_{j_1})(^2s - \textcolor{orange}{2}\lambda_{j_2}) \cdots (^ns - \textcolor{orange}{n}\lambda_{j_n})}}{\sum_{j_1=1}^{k_1} \sum_{j_2=1}^{k_2} \cdots \sum_{j_n=1}^{k_n} \frac{c_{j_1, j_2, \dots, j_n}}{(^1s - \textcolor{orange}{1}\lambda_{j_1})(^2s - \textcolor{orange}{2}\lambda_{j_2}) \cdots (^ns - \textcolor{orange}{n}\lambda_{j_n})}},$$

Theorem: n -D Lagrangian compressed realization

A $\ell + \kappa - 1 = m$ -th order realization $(\hat{\mathbf{G}}_c, \hat{\Phi}_c, \hat{\mathbf{W}}_c)$ of the multi-variate function $\hat{\mathbf{H}}$ in barycentric form, satisfying $\mathbf{H}(^1s, \dots, ^ns) = \hat{\mathbf{W}}_c \hat{\Phi}_c(^1s, ^2s, \dots, ^ns)^{-1} \hat{\mathbf{G}}_c(^{k+1}s, \dots, ^ns)$, is given by,

$$\begin{aligned} \hat{\Phi}_c(^1s, \dots, ^ns) &= \begin{bmatrix} \Gamma(1 : \kappa - 1, :) \\ \vdots \\ \mathbb{A}^{\text{Lag}} \end{bmatrix}^\top \begin{bmatrix} \mathbf{0}_{\kappa-1, \ell-1} \\ \Delta(\bar{1} : \bar{\ell} - 1, :)^\top \end{bmatrix} \in \mathbb{C}^{m \times m} \\ \hat{\mathbf{G}}_c(^{k+1}s, \dots, ^ns) &= \begin{bmatrix} \mathbf{0}_{\kappa-1, 1} \\ \Delta(\bar{\ell}, :)^\top \end{bmatrix} \in \mathbb{C}^{m \times 1} \\ \hat{\mathbf{W}}_c &= \mathbf{e}_\ell^\top \Delta^{-\top} \begin{bmatrix} \mathbb{B}^{\text{Lag}} & \mathbf{0}_{\ell, \ell-1} \end{bmatrix} \in \mathbb{C}^{1 \times m} \end{aligned}$$

where $\mathbb{A}^{\text{Lag}}, \mathbb{B}^{\text{Lag}} \in \mathbb{C}^{\ell \times \kappa}$ are appropriately chosen, according to the chosen pseudo-companion basis.

Content

Forewords

Multi-variate data, function & Loewner matrix

Multi-variate realization

Taming the curse of dimensionality

Variables decoupling, KST and KANs

Comparison with Tensor Flow

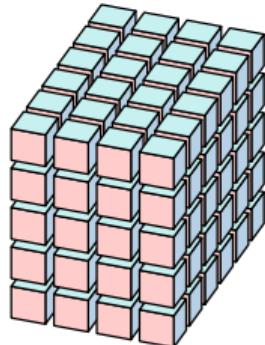
Conclusion

Taming the curse of dimensionality

Loewner matrix operator

$$\begin{aligned} \mathbb{C}^{k_1} \times \mathbb{C}^{q_1} \times \dots \times \mathbb{C}^{k_n} \times \mathbb{C}^{q_n} \times \mathbb{C}^{(k_1+q_1) \times \dots \times (k_n+q_n)} &\longrightarrow \mathbb{C}^{Q \times K} \\ (\overset{1}{\lambda}_{j_1}, \overset{1}{\mu}_{i_1}, \dots, \overset{n}{\lambda}_{j_n}, \overset{n}{\mu}_{i_n}, \mathbf{tab}_n) &\longmapsto \mathbb{L}_n \end{aligned}$$

n -D tensor \mathbf{tab}_n

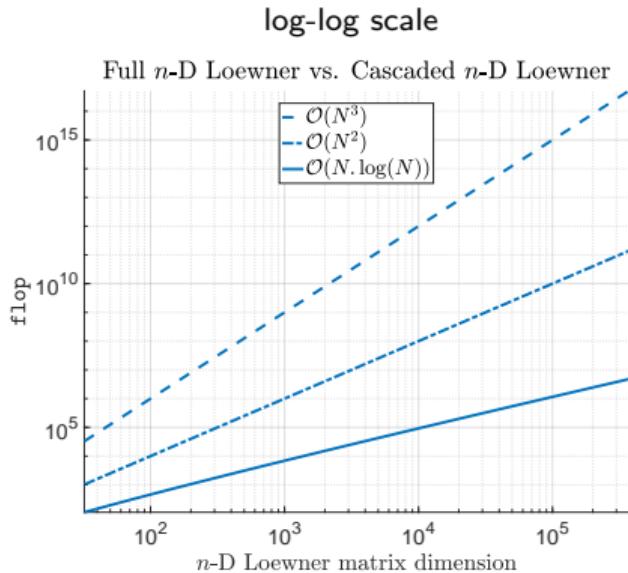


matrix \mathbb{L}_n



Taming the curse of dimensionality

Null space flop and memory issues



Let (rows) $Q = q_1 q_2 \dots q_n$ and (columns)
 $K = k_1 k_2 \dots k_n$

$$\mathbb{L}_n \in \mathbb{C}^{Q \times K}$$

Computational issue

Note that $Q \times K$ matrix SVD flop estimation is

- ▶ QK^2 (if $Q > K$)
- ▶ N^3 (if $Q = K = N$)

Storage issue

Note that $Q \times K$ matrix storage estimation is

- ▶ in real double
- ▶ in complex double

Taming the curse of dimensionality

2-D case (example cont'd, to get the idea)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

2s	${}^2\lambda_1 = -1$	${}^2\lambda_2 = -3$	${}^2\mu_1 = -2$	${}^2\mu_2 = -4$
1s				
${}^1\lambda_1 = 1$	$h_{1,1} = -\frac{1}{3}$	$h_{1,2} = -\frac{3}{5}$	$h_{1,3} = -\frac{1}{2}$	$h_{1,4} = -\frac{2}{3}$
${}^1\lambda_2 = 3$	$h_{2,1} = -\frac{9}{5}$	$h_{2,2} = -\frac{27}{7}$	$h_{2,3} = -3$	$h_{2,4} = -\frac{9}{2}$
${}^1\lambda_3 = 5$	$h_{3,1} = -\frac{25}{7}$	$h_{3,2} = -\frac{25}{3}$	$h_{3,3} = -\frac{25}{4}$	$h_{3,4} = -10$
${}^1\mu_1 = 0$	$h_{4,1} = 0$	$h_{4,2} = 0$	$h_{4,3} = 0$	$h_{4,4} = 0$
${}^1\mu_2 = 2$	$h_{5,1} = -1$	$h_{5,2} = -2$	$h_{5,3} = -\frac{8}{5}$	$h_{5,4} = -\frac{16}{7}$
${}^1\mu_3 = 4$	$h_{6,1} = -\frac{8}{3}$	$h_{6,2} = -6$	$h_{6,3} = -\frac{32}{7}$	$h_{6,4} = -\frac{64}{9}$

$$\xrightarrow{\mathcal{N}(\mathbb{L}_2)} \mathbf{c}_2 = \begin{bmatrix} -\frac{1}{3} \\ \frac{5}{9} \\ \hline \frac{10}{9} \\ -\frac{14}{9} \\ \hline -\frac{7}{9} \\ 1 \end{bmatrix}$$

- 1 \mathbb{L}_1 along 1s , for
 ${}^2s = {}^2\lambda_2 = -3$
- 3 \mathbb{L}_1 along 2s for
 ${}^2s = \{{}^1\lambda_1, {}^1\lambda_2, {}^1\lambda_3\}$
- Scaled null space $\mathbf{c}_2^\top =$

$$[\mathbf{c}_1 \cdot [{}^2\lambda_2]_1 \quad \mathbf{c}_1 \cdot [{}^2\lambda_2]_2 \quad \mathbf{c}_1 \cdot [{}^2\lambda_2]_3]^\top$$

Taming the curse of dimensionality

2-D case (example cont'd, to get the idea)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

2s	${}^2\lambda_1 = -1$	${}^2\lambda_2 = -3$	${}^2\mu_1 = -2$	${}^2\mu_2 = -4$
1s				
${}^1\lambda_1 = 1$	$h_{1,1} = -\frac{1}{3}$	$h_{1,2} = -\frac{3}{5}$	$h_{1,3} = -\frac{1}{2}$	$h_{1,4} = -\frac{2}{3}$
${}^1\lambda_2 = 3$	$h_{2,1} = -\frac{9}{5}$	$h_{2,2} = -\frac{27}{7}$	$h_{2,3} = -3$	$h_{2,4} = -\frac{9}{2}$
${}^1\lambda_3 = 5$	$h_{3,1} = -\frac{25}{7}$	$h_{3,2} = -\frac{25}{3}$	$h_{3,3} = -\frac{25}{4}$	$h_{3,4} = -10$
${}^1\mu_1 = 0$	$h_{4,1} = 0$	$h_{4,2} = 0$	$h_{4,3} = 0$	$h_{4,4} = 0$
${}^1\mu_2 = 2$	$h_{5,1} = -1$	$h_{5,2} = -2$	$h_{5,3} = -\frac{8}{5}$	$h_{5,4} = -\frac{16}{7}$
${}^1\mu_3 = 4$	$h_{6,1} = -\frac{8}{3}$	$h_{6,2} = -6$	$h_{6,3} = -\frac{32}{7}$	$h_{6,4} = -\frac{64}{9}$

$$\xrightarrow{\mathcal{N}(\mathbb{L}_2)} \mathbf{c}_2 = \begin{bmatrix} -\frac{1}{3} \\ \frac{5}{9} \\ \hline \frac{10}{9} \\ -\frac{14}{9} \\ \hline -\frac{7}{9} \\ 1 \end{bmatrix}$$

- 1 \mathbb{L}_1 along 1s , for

$${}^2s = {}^2\lambda_2 = -3$$

- 3 \mathbb{L}_1 along 2s for

$${}^1s = \{{}^1\lambda_1, {}^1\lambda_2, {}^1\lambda_3\}$$

- Scaled null space $\mathbf{c}_2^\top =$

$$\left[\mathbf{c}_1^{{}^1\lambda_1} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_1 \quad \mathbf{c}_1^{{}^1\lambda_2} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_2 \quad \mathbf{c}_1^{{}^1\lambda_3} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_3 \right]^\top$$

$$\mathbf{c}_1^{{}^2\lambda_2} = \begin{bmatrix} \frac{5}{9} \\ -\frac{14}{9} \\ 1 \end{bmatrix}$$

Taming the curse of dimensionality

2-D case (example cont'd, to get the idea)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

2s	${}^2\lambda_1 = -1$	${}^2\lambda_2 = -3$	${}^2\mu_1 = -2$	${}^2\mu_2 = -4$
1s				
${}^1\lambda_1 = 1$	$h_{1,1} = -\frac{1}{3}$	$h_{1,2} = -\frac{3}{5}$	$h_{1,3} = -\frac{1}{2}$	$h_{1,4} = -\frac{2}{3}$
${}^1\lambda_2 = 3$	$h_{2,1} = -\frac{9}{5}$	$h_{2,2} = -\frac{27}{7}$	$h_{2,3} = -3$	$h_{2,4} = -\frac{9}{2}$
${}^1\lambda_3 = 5$	$h_{3,1} = -\frac{25}{7}$	$h_{3,2} = -\frac{25}{3}$	$h_{3,3} = -\frac{25}{4}$	$h_{3,4} = -10$
${}^1\mu_1 = 0$	$h_{4,1} = 0$	$h_{4,2} = 0$	$h_{4,3} = 0$	$h_{4,4} = 0$
${}^1\mu_2 = 2$	$h_{5,1} = -1$	$h_{5,2} = -2$	$h_{5,3} = -\frac{8}{5}$	$h_{5,4} = -\frac{16}{7}$
${}^1\mu_3 = 4$	$h_{6,1} = -\frac{8}{3}$	$h_{6,2} = -6$	$h_{6,3} = -\frac{32}{7}$	$h_{6,4} = -\frac{64}{9}$

$$\xrightarrow{\mathcal{N}(\mathbb{L}_2)} \mathbf{c}_2 = \begin{bmatrix} -\frac{1}{3} \\ \frac{5}{9} \\ \hline \frac{10}{9} \\ -\frac{14}{9} \\ \hline -\frac{7}{9} \\ 1 \end{bmatrix}$$

- 1 \mathbb{L}_1 along 1s , for

$${}^2s = {}^2\lambda_2 = -3$$

- 3 \mathbb{L}_1 along 2s for

$${}^1s = \{{}^1\lambda_1, {}^1\lambda_2, {}^1\lambda_3\}$$

- Scaled null space $\mathbf{c}_2^\top =$

$$\left[\mathbf{c}_1^{{}^1\lambda_1} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_1 \quad \mathbf{c}_1^{{}^1\lambda_2} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_2 \quad \mathbf{c}_1^{{}^1\lambda_3} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_3 \right]^\top$$

$$\mathbf{c}_1^{{}^2\lambda_2} = \begin{bmatrix} \frac{5}{9} \\ -\frac{14}{9} \\ 1 \end{bmatrix} \text{ and } \mathbf{c}_1^{{}^1\lambda_1} = \begin{bmatrix} -\frac{3}{5} \\ 1 \end{bmatrix}, \mathbf{c}_1^{{}^1\lambda_2} = \begin{bmatrix} -\frac{5}{7} \\ 1 \end{bmatrix}, \mathbf{c}_1^{{}^1\lambda_3} = \begin{bmatrix} -\frac{7}{9} \\ 1 \end{bmatrix}$$

Taming the curse of dimensionality

2-D case (example cont'd, to get the idea)

Data generated from $\mathbf{H}(^1s, ^2s) = \mathbf{H}(s, t) = (s^2t)/(s - t + 1)$ of complexity (2, 1)

2s	${}^2\lambda_1 = -1$	${}^2\lambda_2 = -3$	${}^2\mu_1 = -2$	${}^2\mu_2 = -4$
1s				
${}^1\lambda_1 = 1$	$h_{1,1} = -\frac{1}{3}$	$h_{1,2} = -\frac{3}{5}$	$h_{1,3} = -\frac{1}{2}$	$h_{1,4} = -\frac{2}{3}$
${}^1\lambda_2 = 3$	$h_{2,1} = -\frac{9}{5}$	$h_{2,2} = -\frac{27}{7}$	$h_{2,3} = -3$	$h_{2,4} = -\frac{9}{2}$
${}^1\lambda_3 = 5$	$h_{3,1} = -\frac{25}{7}$	$h_{3,2} = -\frac{25}{3}$	$h_{3,3} = -\frac{25}{4}$	$h_{3,4} = -10$
${}^1\mu_1 = 0$	$h_{4,1} = 0$	$h_{4,2} = 0$	$h_{4,3} = 0$	$h_{4,4} = 0$
${}^1\mu_2 = 2$	$h_{5,1} = -1$	$h_{5,2} = -2$	$h_{5,3} = -\frac{8}{5}$	$h_{5,4} = -\frac{16}{7}$
${}^1\mu_3 = 4$	$h_{6,1} = -\frac{8}{3}$	$h_{6,2} = -6$	$h_{6,3} = -\frac{32}{7}$	$h_{6,4} = -\frac{64}{9}$

$$\xrightarrow{\mathcal{N}(\mathbb{L}_2)} \mathbf{c}_2 = \begin{bmatrix} -\frac{1}{3} \\ \frac{5}{9} \\ \hline \frac{10}{9} \\ -\frac{14}{9} \\ \hline -\frac{7}{9} \\ 1 \end{bmatrix}$$

- 1 \mathbb{L}_1 along 1s , for

$${}^2s = {}^2\lambda_2 = -3$$

- 3 \mathbb{L}_1 along 2s for

$${}^1s = \{{}^1\lambda_1, {}^1\lambda_2, {}^1\lambda_3\}$$

- Scaled null space $\mathbf{c}_2^\top =$

$$\left[\mathbf{c}_1^{{}^1\lambda_1} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_1 \quad \mathbf{c}_1^{{}^1\lambda_2} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_2 \quad \mathbf{c}_1^{{}^1\lambda_3} \cdot [\mathbf{c}_1^{{}^2\lambda_2}]_3 \right]^\top$$

$$\mathbf{c}_1^{{}^2\lambda_2} = \begin{bmatrix} \frac{5}{9} \\ -\frac{14}{9} \\ 1 \end{bmatrix} \text{ and } \mathbf{c}_1^{{}^1\lambda_1} = \begin{bmatrix} -\frac{3}{5} \\ 1 \end{bmatrix}, \mathbf{c}_1^{{}^1\lambda_2} = \begin{bmatrix} -\frac{5}{7} \\ 1 \end{bmatrix}, \mathbf{c}_1^{{}^1\lambda_3} = \begin{bmatrix} -\frac{7}{9} \\ 1 \end{bmatrix}$$

Taming the curse of dimensionality

2-D case

Theorem: 2-D to 1-D

Being given the tableau tab_2 tensor in response of the 2-variables $\mathbf{H}(^1s, ^2s)$ function, the null space of the corresponding 2-D Loewner matrix \mathbb{L}_2 , is spanned by

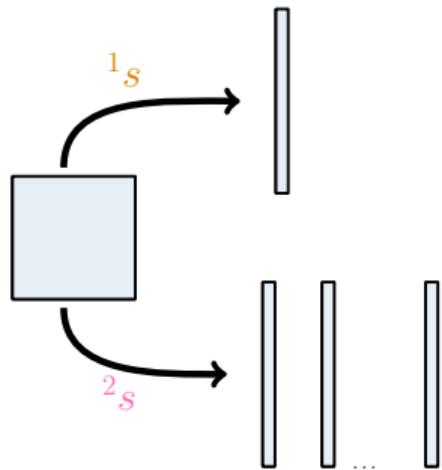
$$\mathcal{N}(\mathbb{L}_2) = \text{vec} \left[\mathbf{c}_1^{^2\lambda_1} \cdot \begin{bmatrix} ^1\lambda_{k_1} \\ \mathbf{c}_1 \end{bmatrix}_1, \dots, \mathbf{c}_1^{^2\lambda_{k_2}} \cdot \begin{bmatrix} ^1\lambda_{k_1} \\ \mathbf{c}_1 \end{bmatrix}_{k_2} \right],$$

where

- ▶ $\mathbf{c}_1^{^1\lambda_{k_1}} = \mathcal{N}(\mathbb{L}_1^{^1\lambda_{k_1}})$,
i.e. the null space of the **1-D Loewner matrix** for frozen $^1s = ^1\lambda_{k_1}$, and
- ▶ $\mathbf{c}_1^{^2\lambda_{j_2}} = \mathcal{N}(\mathbb{L}_1^{^2\lambda_{j_2}})$,
i.e. the j_1 -th null space of the **1-D Loewner matrices** for frozen $^2s = \{^2\lambda_1, \dots, ^2\lambda_{k_2}\}$.

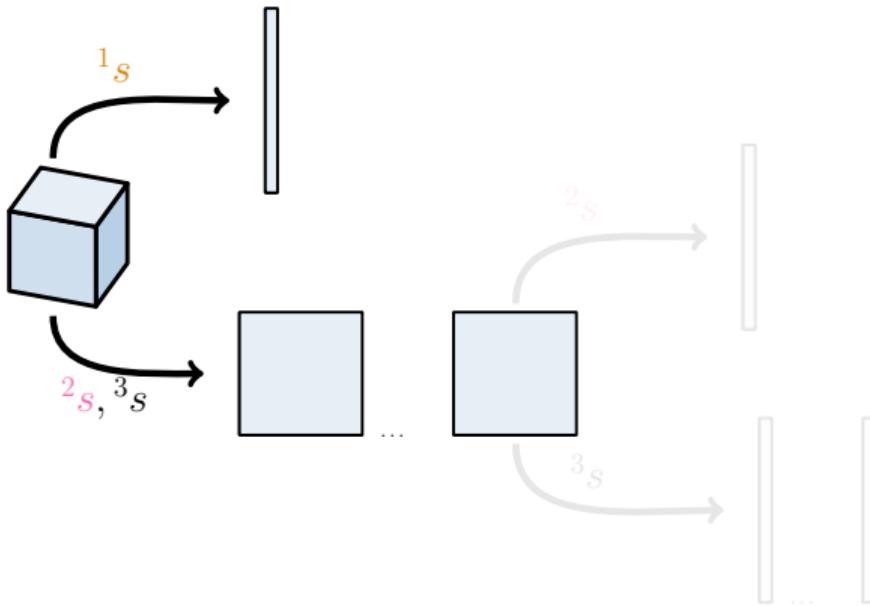
Taming the curse of dimensionality

2-D case



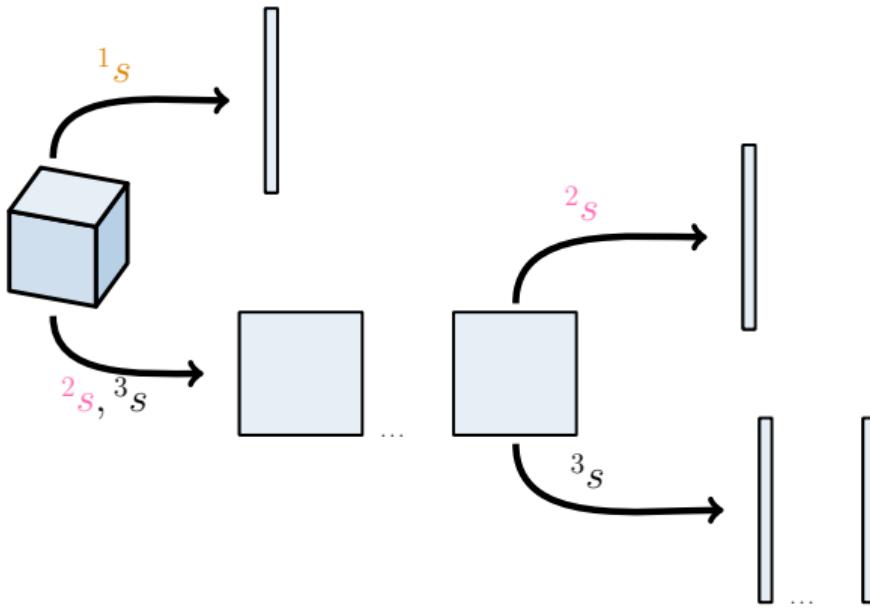
Taming the curse of dimensionality

3-D case



Taming the curse of dimensionality

3-D case



Taming the curse of dimensionality

n-D case

Theorem: *n*-D to (*n* − 1)-D

Being given the tableau tab_n tensor in response of the n -variables $\mathbf{H}({}^1s, \dots, {}^ns)$ function, the null space of the corresponding *n*-D Loewner matrix \mathbb{L}_n , is spanned by

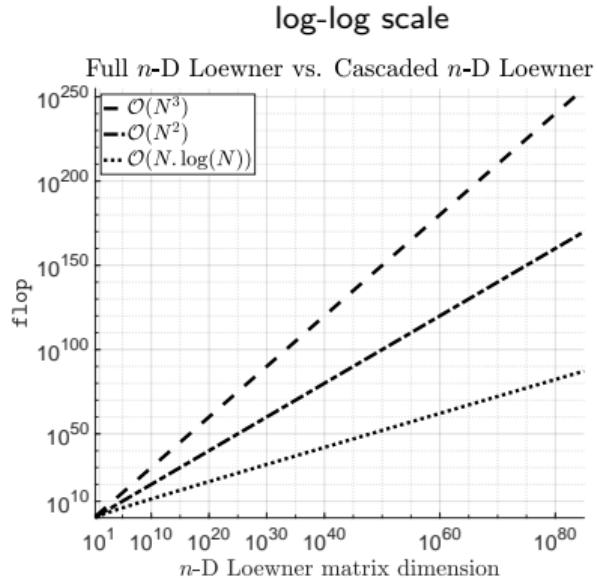
$$\mathcal{N}(\mathbb{L}_n) = \text{vec} \left[\mathbf{c}_{n-1}^{{}^1\lambda_1} \cdot \left[\mathbf{c}_1^{({}^2\lambda_{k_2}, {}^3\lambda_{k_3}, \dots, {}^n\lambda_{k_n})} \right]_1, \dots, \mathbf{c}_{n-1}^{{}^1\lambda_{k_1}} \cdot \left[\mathbf{c}_1^{({}^2\lambda_{k_2}, {}^3\lambda_{k_3}, \dots, {}^n\lambda_{k_n})} \right]_{k_1} \right],$$

where

- ▶ $\mathbf{c}_1^{({}^2\lambda_{k_2}, {}^3\lambda_{k_3}, \dots, {}^n\lambda_{k_n})}$ spans $\mathcal{N}(\mathbb{L}_1^{({}^2\lambda_{k_2}, {}^3\lambda_{k_3}, \dots, {}^n\lambda_{k_n})})$,
i.e. the null space of the **1-D Loewner matrix** for frozen $\{{}^2\lambda_{k_2}, {}^3\lambda_{k_3}, \dots, {}^n\lambda_{k_n}\}$, and
- ▶ $\mathbf{c}_{n-1}^{{}^1\lambda_{j_1}}$ spans $\mathcal{N}(\mathbb{L}_{n-1}^{{}^1\lambda_{j_1}})$,
i.e. the j_1 -th null space of the **(*n* − 1)-D Loewner matrix** for frozen ${}^1s_{j_1} = \{{}^1\lambda_1, \dots, {}^1\lambda_{k_1}\}$.

Taming the curse of dimensionality

Null space - flop complexity



Null space underlying problem

Let (rows) $Q = q_1 q_2 \dots q_n$ and (columns) $K = k_1 k_2 \dots k_n$
 $\mathbb{L}_n \in \mathbb{C}^{Q \times K}$

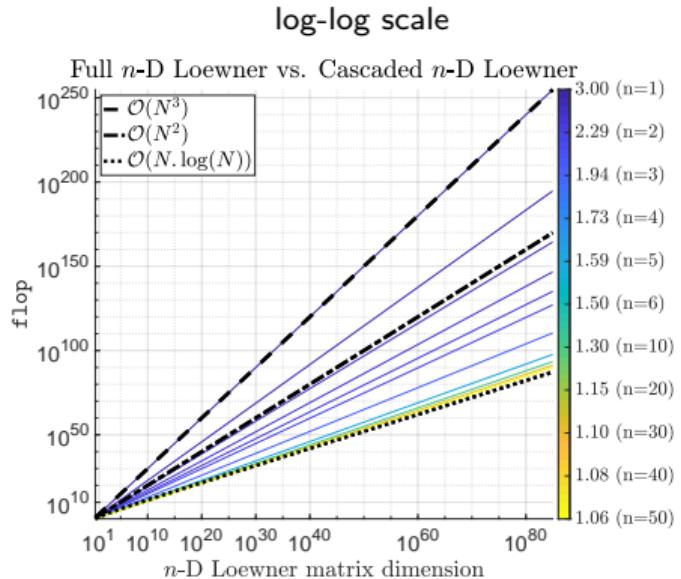
Note that $Q \times K$ matrix SVD flop estimation is

- ▶ QK^2 (if $Q > K$)
- ▶ N^3 (if $Q = K = N$)

⇒ The CURSE of dimensionality

Taming the curse of dimensionality

Null space - flop complexity



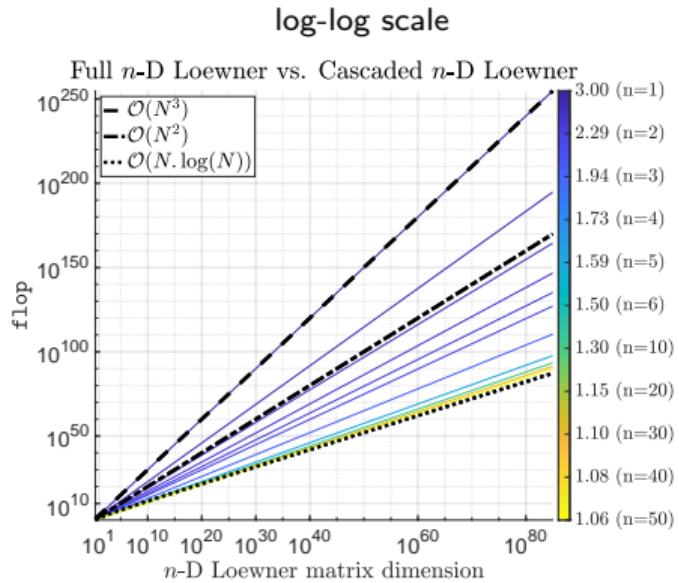
Theorem: Recursive complexity

$$\text{flop}_1(n) = \sum_{j=1}^n \left(k_j^3 \prod_{l=1}^j k_{l-1} \right) \text{ where } k_0 = 1.$$

⇒ The CURSE of dimensionality is TAMED

Taming the curse of dimensionality

Null space - flop complexity



Corollary: Worst case complexity

k interpolation points per variables.

$$\overline{\text{flop}_1} = k^3 \frac{1 - k^n}{1 - k} = k^3 \frac{1 - N}{1 - k},$$

which is a (n finite) geometric series of ratio k .

⇒ The CURSE of dimensionality is TAMED

$$\begin{aligned} \mathcal{O}(N^3) &\rightarrow \mathcal{O}(N^{2.29}) && \text{for } n = 2 \\ &\rightarrow \mathcal{O}(N^{1.94}) && \text{for } n = 3 \\ &\vdots && \\ &\rightarrow \mathcal{O}(N^{1.5}) && \text{for } n = 6 \\ &\vdots && \\ &\rightarrow \mathcal{O}(N^{1.06}) && \text{for } n = 50 \end{aligned}$$

Taming the curse of dimensionality

Null space - memory

With similar importance, the **data storage is a key element** in the curse of dimensionality. The data (tableau) storage is (complex and double precision)

$$\frac{8}{2^{20}} \prod_l^n q_l + k_l \text{ MB} \text{ (example tableau } 2 \cdot [20, 6, 4, 6, 8, 2] = 2 \cdot [k_1, k_2, k_3, k_4, k_5, k_6] \text{ needs 45 MB)}$$

Full n -D Loewner

Construction of

$$\mathbb{L}_n \in \mathbb{C}^{N \times N}$$

where $N = k_1 k_2 \cdots k_n$, needs

$$\frac{8}{2^{20}} N^2 \text{ MB}$$

Example: $N = 46,080$

Memory: **31.64 GB**

flop: $9.78 \cdot 10^{13}$

Taming the curse of dimensionality

Null space - memory

With similar importance, the **data storage** is a key element in the curse of dimensionality. The data (tableau) storage is (complex and double precision)

$$\frac{8}{2^{20}} \prod_l^n q_l + k_l \text{ MB} \text{ (example tableau } 2 \cdot [20, 6, 4, 6, 8, 2] = 2 \cdot [k_1, k_2, k_3, k_4, k_5, k_6] \text{ needs 45 MB})$$

Full n -D Loewner

Construction of

$$\mathbb{L}_n \in \mathbb{C}^{N \times N}$$

where $N = k_1 k_2 \cdots k_n$, needs

$$\frac{8}{2^{20}} N^2 \text{ MB}$$

Example: $N = 46,080$

Memory: **31.64 GB**

flop: $9.78 \cdot 10^{13}$

Cascaded n -D Loewner

Construction of

$$\mathbb{L}_1 \in \mathbb{C}^{\bar{k} \times \bar{k}}$$

where $\bar{k} = \max_j k_j$, needs

$$\frac{8}{2^{20}} \bar{k}^2 \text{ MB}$$

Example: $\bar{k} = 20$

Memory: **6.25 KB**

flop: $8.13 \cdot 10^5$

Taming the curse of dimensionality

Numerical examples, 20-D example

$$\mathbf{H}(^1s, ^2s, \dots, ^{20}s) =$$

$$\frac{3 \cdot {}^1s^3 + 4 \cdot {}^8s + {}^{12}s + {}^{13}s \cdot {}^{14}s + {}^{15}s}{{}^1s + {}^2s^2 \cdot {}^3s + {}^4s + {}^5s + {}^6s + {}^7s \cdot {}^8s + {}^9s \cdot {}^{10}s \cdot {}^{11}s + {}^{13}s + {}^{13}s^3 \cdot \pi + {}^{17}s + {}^{18}s \cdot {}^{19}s - {}^{20}s}$$

Statistics

- ▶ 20-D tensor of dimension (≥ 48 TB in real double precision)
- ▶ Complexity: (3, 2, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 3, 1, 1, 1, 1)
- ▶ n -D Loewner matrix $6,291,456^2 \rightarrow 288$ TB of storage in real double precision
- ▶ Full SVD: $2.49 \cdot 10^{20}$ flop
Recursive SVD: $5.43 \cdot 10^7$ flop
- ▶ error $\approx 10^{-11}$

Taming the curse of dimensionality

Numerical examples, 20-D example

$$\mathbf{H}(^1s, ^2s, \dots, ^{20}s) =$$

$$\frac{3 \cdot {}^1s^3 + 4 \cdot {}^8s + {}^{12}s + {}^{13}s \cdot {}^{14}s + {}^{15}s}{{}^1s + {}^2s^2 \cdot {}^3s + {}^4s + {}^5s + {}^6s + {}^7s \cdot {}^8s + {}^9s \cdot {}^{10}s \cdot {}^{11}s + {}^{13}s + {}^{13}s^3 \cdot \pi + {}^{17}s + {}^{18}s \cdot {}^{19}s - {}^{20}s}$$

Statistics

- ▶ 20-D tensor of dimension (≥ 48 TB in real double precision)
- ▶ Complexity: (3, 3, 2, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1)
- ▶ n -D Loewner matrix $6,291,456^2 \rightarrow 288$ TB of storage in real double precision
- ▶ Full SVD: $2.49 \cdot 10^{20}$ flop
Recursive SVD: $5.43 \cdot 10^7$ flop $\rightarrow 5.03 \cdot 10^7$ flop
- ▶ error $\approx 10^{-11}$

Taming the curse of dimensionality

Numerical examples (from 2 to 20 variables)

#4 Rational function

$$s_4^3 + \frac{s_1 s_3}{s_3^2 + s_1 + s_2 + 1}$$

#5 Rational function

$$\frac{s_3^2 + s_1 s_3 s_5^3}{s_1^3 + s_4 + s_2 s_3}$$

#6 Rational function

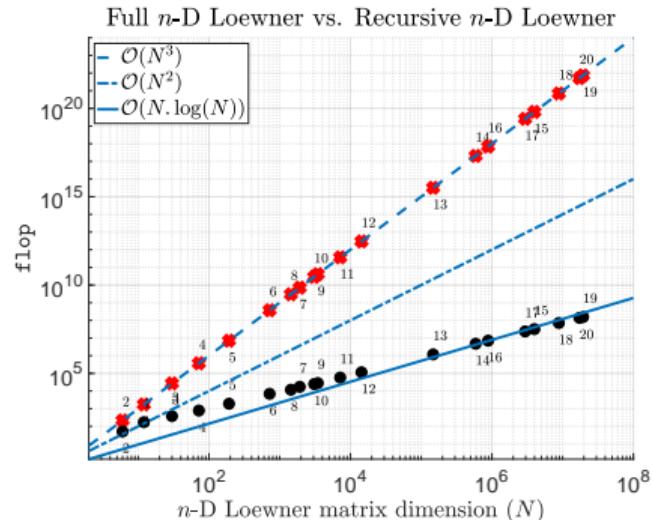
$$\frac{-\sqrt{2} s_6^2 + s_1 + s_3}{s_1^2 + s_4^3 + s_5^2 + s_6 + s_2 s_3}$$

#7 Rational function

$$\frac{s_3 s_2^3 + 1}{s_3 s_2^2 + s_4^2 + s_6^3 + s_1 + s_5 + s_7}$$

#19 Rational function

$$\frac{3 s_1^3 + s_{18}^2 + 4 s_8 + s_{12} + s_{15} + s_{13} s_{14}}{s_3 s_2^2 + \pi s_{16}^3 + s_{17}^2 + s_1 + s_4 + s_5 + s_6 + s_{13} + s_{19} + s_7 s_8 + s_9 s_{10} s_{11}}$$



Taming the curse of dimensionality

Numerical examples (rational and irrational)

#16 Arc-tangent function

$$\frac{\operatorname{atan}(x_1) + \operatorname{atan}(x_2) + \operatorname{atan}(x_3) + \operatorname{atan}(x_4)}{x_1^2 x_2^2 - x_1^2 - x_2^2 + 1}$$

#17 Exponential function

$$\frac{e^{x_1 x_2 x_3 x_4}}{x_1^2 + x_2^2 - x_3 x_4 + 3}$$

#18 Sinc function

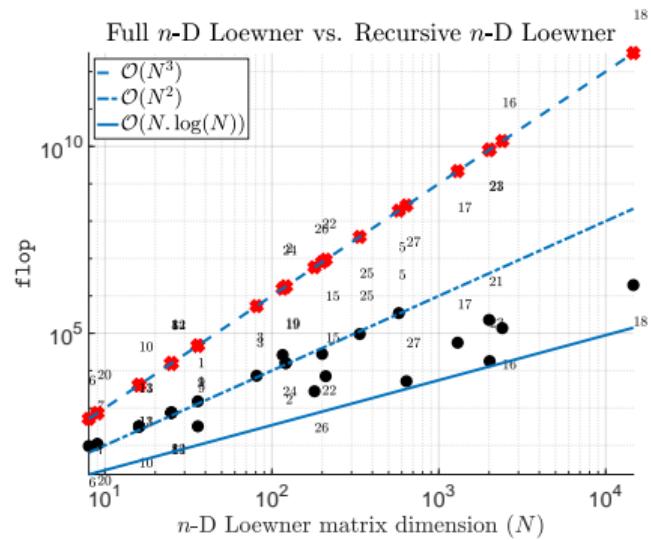
$$\frac{10 \sin(x_1) \sin(x_2) \sin(x_3) \sin(x_4)}{x_1 x_2 x_3 x_4}$$

#19 Sinc function

$$\frac{10 \sin(x_1) \sin(x_2)}{x_1 x_2}$$

#20 Polynomial function

$$x_1^2 + x_1 x_2 + x_2^2 - x_2 + 1$$



Content

Forewords

Multi-variate data, function & Loewner matrix

Multi-variate realization

Taming the curse of dimensionality

Variables decoupling, KST and KANs

Comparison with Tensor Flow

Conclusion

Variables decoupling, KST and KANs

Variables decoupling

Variable decoupling

Given data tab_n , the (recursive) theorem achieves variables decoupling, and the null space can be equivalently written as:

$$\mathbf{c}_n = \underbrace{\mathbf{c}^{n_s}}_{\text{Bary}^{(n_s)}} \odot \underbrace{(\mathbf{c}^{n-1_s} \otimes \mathbf{1}_{k_n})}_{\text{Bary}^{(n-1_s)}} \odot \underbrace{(\mathbf{c}^{n-2_s} \otimes \mathbf{1}_{k_n k_{n-1}})}_{\text{Bary}^{(n-2_s)}} \odot \cdots \odot \underbrace{(\mathbf{c}^1_s \otimes \mathbf{1}_{k_n \dots k_2})}_{\text{Bary}^{(1_s)}}.$$

where \mathbf{c}^j_s denotes the vectorized barycentric coefficients related to the j -th variable.

Variables decoupling, KST and KANs

Variables decoupling (example)

Variables decoupling, KST and KANs

Kolmogorov Superposition Theorem



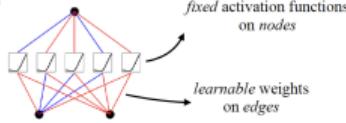
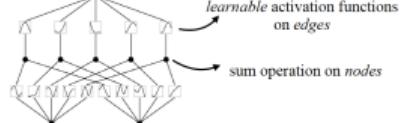
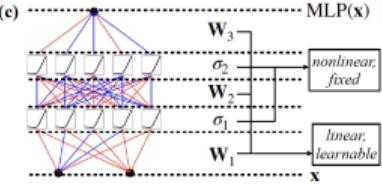
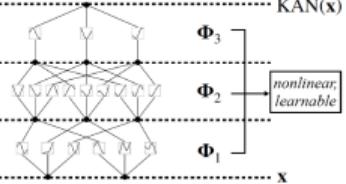
A.G. Vitushkin, "*On Hilbert's thirteenth problem and related questions*", Russian Math. Surveys 59:1, pp. 11–25.

Variables decoupling, KST and KANs

About KANs

KANs features

- ▶ Inspired by the Kolmogorov-Arnold representation theorem
- ▶ The model output is a composition of **sums** and **learnable activation functions** (e.g. splines)
- ▶ Alternate to Multi-Layer Perceptrons (MLP), having fixed activation functions (e.g. ReLU), **inspired by the universal approximation theorem**

Model	Multi-Layer Perceptron (MLP)	Kolmogorov-Arnold Network (KAN)
Theorem	Universal Approximation Theorem	Kolmogorov-Arnold Representation Theorem
Formula (Shallow)	$f(\mathbf{x}) \approx \sum_{i=1}^{N(c)} a_i \sigma(\mathbf{w}_i \cdot \mathbf{x} + b_i)$	$f(\mathbf{x}) = \sum_{q=1}^{2n+1} \Phi_q \left(\sum_{p=1}^n \phi_{q,p}(x_p) \right)$
Model (Shallow)	(a) 	(b) 
Formula (Deep)	$\text{MLP}(\mathbf{x}) = (\mathbf{W}_3 \circ \sigma_2 \circ \mathbf{W}_2 \circ \sigma_1 \circ \mathbf{W}_1)(\mathbf{x})$	$\text{KAN}(\mathbf{x}) = (\Phi_3 \circ \Phi_2 \circ \Phi_1)(\mathbf{x})$
Model (Deep)	(c) 	(d) 

Comparison between MLP and KAN (figure from Z. Liu et al.)



Variables decoupling, KST and KANs

KANs with splines

Building the Kolmogorov-Arnold model as follows

$$F(^1s, ^2s, \dots, ^ns) = \sum_{k=1}^{2m+1} \Phi_k \left(\sum_{j=1}^m f_{kj}(^js) \right)$$

$f_{kj} : [0, 1] \mapsto \mathbb{R}$ and $\Phi_k : \mathbb{R} \mapsto \mathbb{R}$ are continuous functions.

The relation is approximated by $k = 1, \dots, d = 2m + 1$ as

$$\hat{F}(^1s, ^2s, \dots, ^ns) = \sum_{k=1}^d \Phi_k \underbrace{\left(\sum_{j=1}^m f_{kj}(^js_i) \right)}_{\theta_{ik}}$$

where θ_{ik} denotes the k-th component of θ_i vector (interpreted as a hidden variable between two layers), which describes splines

Variables decoupling, KST and KANs

KANs with splines

Building the Kolmogorov-Arnold model as follows

$$F(^1s, ^2s, \dots, ^ns) = \sum_{k=1}^{2m+1} \Phi_k \left(\sum_{j=1}^m f_{kj}(^js) \right)$$

$f_{kj} : [0, 1] \mapsto \mathbb{R}$ and $\Phi_k : \mathbb{R} \mapsto \mathbb{R}$ are continuous functions.

The relation is approximated by $k = 1, \dots, d = 2m + 1$ as

$$\hat{F}(^1s, ^2s, \dots, ^ns) = \sum_{k=1}^d \Phi_k \underbrace{\left(\sum_{j=1}^m f_{kj}(^js_i) \right)}_{\theta_{ik}}$$

where θ_{ik} denotes the k-th component of θ_i vector (interpreted as a hidden variable between two layers), which describes **splines**

Variables decoupling, KST and KANs

KANs (via Loewner) with rational activation functions

$$\mathbf{H} = {}^1s \cdot {}^2s$$

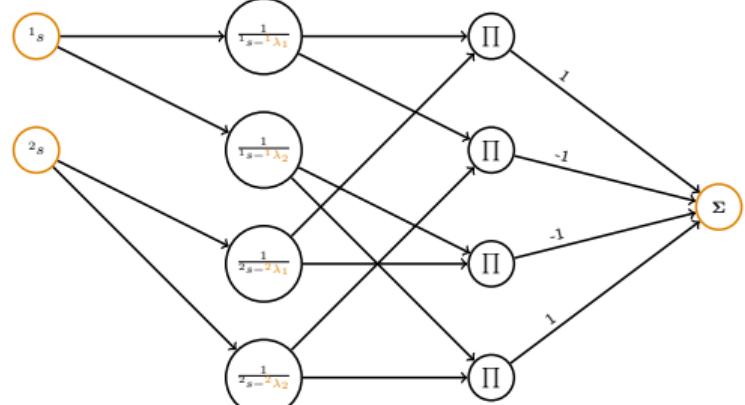
$$\begin{aligned} {}^1\lambda_{j_1} &= \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \\ {}^2\lambda_{j_2} &= \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \end{aligned}$$

$$\mathbf{D} = \begin{pmatrix} {}^1s \cdot \mathbf{Lag}({}^1s) & {}^2s \cdot \mathbf{Lag}({}^2s) \\ -\frac{1.0}{{}^1s+1.0} & -\frac{1.0}{{}^2s+1.0} \\ -\frac{1.0}{{}^1s+1.0} & \frac{1}{{}^2s-1.0} \\ \frac{1}{{}^1s-1.0} & -\frac{1.0}{{}^2s+1.0} \\ \frac{1}{{}^1s-1.0} & \frac{1}{{}^2s-1.0} \end{pmatrix}$$

Equivalent denominator and numerator read:

$$\sum_{i\text{-th row}} \prod_{j\text{-th col}} [\mathbf{D}]_{i,j} \text{ and } \sum_{i\text{-th row}} \mathbf{w} \cdot \prod_{j\text{-th col}} [\mathbf{D}]_{i,j}$$

Equivalent KAN-like with rational activation functions (just \mathbf{D})



Content

Forewords

Multi-variate data, function & Loewner matrix

Multi-variate realization

Taming the curse of dimensionality

Variables decoupling, KST and KANs

Comparison with Tensor Flow

Conclusion

Comparison with Tensor Flow

About Keras via Tensor Flow (<https://www.tensorflow.org/guide/keras?hl=en>)

Some key figures

- ▶ Keras is the high-level API of the TensorFlow (by Google) platform.
- ▶ Multi Layer Perceptron
- ▶ Dense connected network
- ▶ ReLU activation functions
- ▶ Optim.: ADAM (Adaptive Moment Estimation)
- ▶ Random init. (with fixed seed)
- ▶ 1000 iterations

Python code

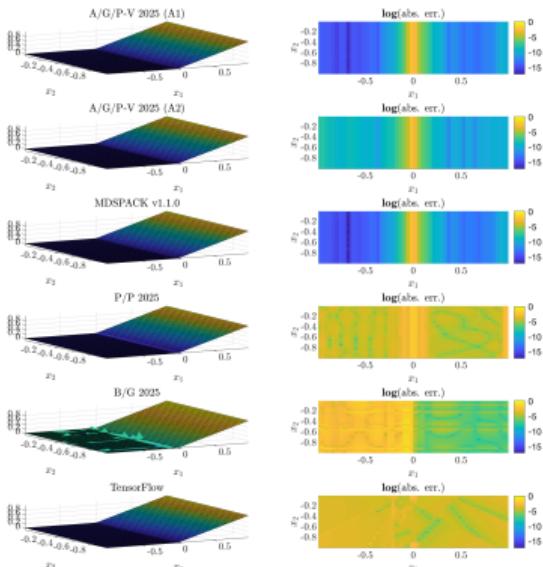
```
1 import numpy as np
2 import math
3 import matplotlib.pyplot as plt
4 import tensorflow as tf
5 from keras.models import Sequential
6 from matplotlib import cm
7
8 # Data
9 def H(x):
10     xy = pow(x[:,0],2)*x[:,1]
11     #y = 1/2*x[:,0] + np.abs(x[:,0])) + 1/10*x[:,1] #1
12     #y = x[:,0]*x[:,1] #3
13     #y = np.exp((x[:,0]*x[:,1])/((pow(x[:,0],2)-1.44)*(pow(x[:,1],2)-1.44))) #6
14     #y = np.tanh(4*(x[:,0]-x[:,1])) #8
15     #y = pow(np.abs((x[:,0]-x[:,1])),3) #10
16     y = (pow(x[:,0],2) + pow(x[:,1],2) + x[:,0] - x[:,1] + 1) / (pow(x[:,0],3) + pow(x[:,1],2) + 4) #15
17     return np.transpose(np.array([y]))
```

18
19 p = 2
20 N1 = 40
21 N2 = 40
22 x1 = np.linspace(-1, 1, N1)
23 x2 = np.linspace(-1, 1, N2)
24 |
25 # IP
26 N = N1*N2
27 tab = np.zeros([N,1])

Comparison with Tensor Flow

Comparison (example #1)

#	Alg.	Parameters	Dim.	CPU [s]	RMSE	min err.	max err.
1	A/G/P-V 2025 (A1)	1e-11,3	144	0.0171	0.000699	1.39e - 17	0.00841
	A/G/P-V 2025 (A2)	1e-15,3	160	0.0823	0.000389	4.49e-13	0.00434
	MDSPACK v1.1.0	1e-11,1e-06	144	0.0108	0.000699	2.43e-17	0.00841
	P/P 2025	1,0.95,50,0.01,4,6,9	130	0.282	0.0017	3.08e-07	0.0152
	B/G 2025	0.001,10	320	0.0753	0.0742	1.13e-09	1.58
	TensorFlow		257	25.3	0.000707	7.77e-08	0.0102



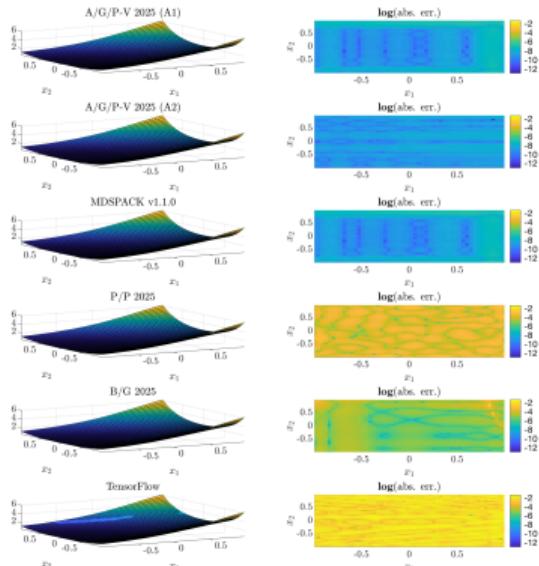
$$\text{ReLU}({}^1s) + \frac{1}{100} {}^2s$$

- ▶ Reference: Personal communication, [none]
- ▶ Domain: \mathbb{R}
- ▶ Tensor size: 12.5 KB (40^2 points)
- ▶ Bounds: $(-1 \quad 1) \times (-1 \quad -\frac{1}{10000000000})$

Comparison with Tensor Flow

Comparison (example #2)

#	Alg.	Parameters	Dim.	CPU [s]	RMSE	min err.	max err.
1	A/G/P-V 2025 (A1)	1e-11,3	144	0.0171	0.000699	1.39e - 17	0.00841
	A/G/P-V 2025 (A2)	1e-15,3	160	0.0823	0.000389	4.49e-13	0.00434
	MDSPACK v1.1.0	1e-11,1e-06	144	0.0108	0.000699	2.43e-17	0.00841
	P/P 2025	1,0.95,50,0.01,4,6,9	130	0.282	0.0017	3.08e-07	0.0152
	B/G 2025	0.001,10	320	0.0753	0.0742	1.13e-09	1.58
	TensorFlow		257	25.3	0.000707	7.77e-08	0.0102



$$\exp(\sin^1 s) + ^2 s^2$$

- ▶ Reference: Personal communication, [none]
- ▶ Domain: \mathbb{R}
- ▶ Tensor size: 12.5 KB (40² points)
- ▶ Bounds:

$$\begin{pmatrix} -1 & 1 \end{pmatrix} \times \begin{pmatrix} -1 & 1 \end{pmatrix}$$

Content

Forewords

Multi-variate data, function & Loewner matrix

Multi-variate realization

Taming the curse of dimensionality

Variables decoupling, KST and KANs

Comparison with Tensor Flow

Conclusion

Conclusion

Take home message

Main contributions

From any n -th order multi-variate transfer function / data tensor

- ▶ Construct a transfer function in barycentric form
- ▶ **Construct a realization with controlled complexity**
- ▶ **Tame the computational complexity**
 $\mathcal{O}(N^3) \rightarrow \approx \mathcal{O}(N^{2.29, 1.94, \dots})$
- ▶ Two algorithms (direct & iterative)
- ▶ Connection with Kolmogorov theorem

Side effects

[Theo.] Tame COD in KST

[Sci. con.] Tensor rank approximation

[Sci. con.] Achieve multi-linearization of NEVP

[Sci. con.] Exact (Loewner) matrix null space computation

[Dyn. sys.] Multi-variate / parametric realization

Collaboration with

A.C. Antoulas [Rice Univ.]

I.V. Goșea [MPI]

<https://arxiv.org/abs/2405.00495>

<https://github.com/cpoussot/mLF>



Conclusion

Big picture

