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Spooky Action at a Distance

VICTOR CIURA



Cppcon
The C++ Conference

20
21



Spooky Action at a Distance

CppCon 2021

October 26th



@ciura_victor

Victor Ciura
Principal Engineer



Abstract

I hate the term “Design Patterns”. It implies there are universally applicable solutions to some common code scenarios. Just codifying existing practice into some rules and blindly following them is a comfortable path, but not the optimal one. It turns out it’s not as easy as following recipes. Each situation and best associated solution is unique.

However there is value in having uniform code structure throughout a project. So this topic is not to be discarded just yet, rather it needs more careful examination.

In terms of inspectable properties of objects, what have we learned from years of OO influence from other languages and frameworks? How can we leverage these borrowed techniques in a value-oriented context? Does C++ benefit from special considerations?

I think it’s time to revisit our old friend, the Observer pattern - from “theory” to practice. I’m not going to offer The Solution, rather we’re going to examine tradeoffs for several possible implementations, in various usage scenarios from a real project.

About me



Advanced Installer



Clang Power Tools

 [@ciura_victor](https://twitter.com/ciura_victor)

Use the Q&A tab in Zoom

Q & A

Spooky What ?

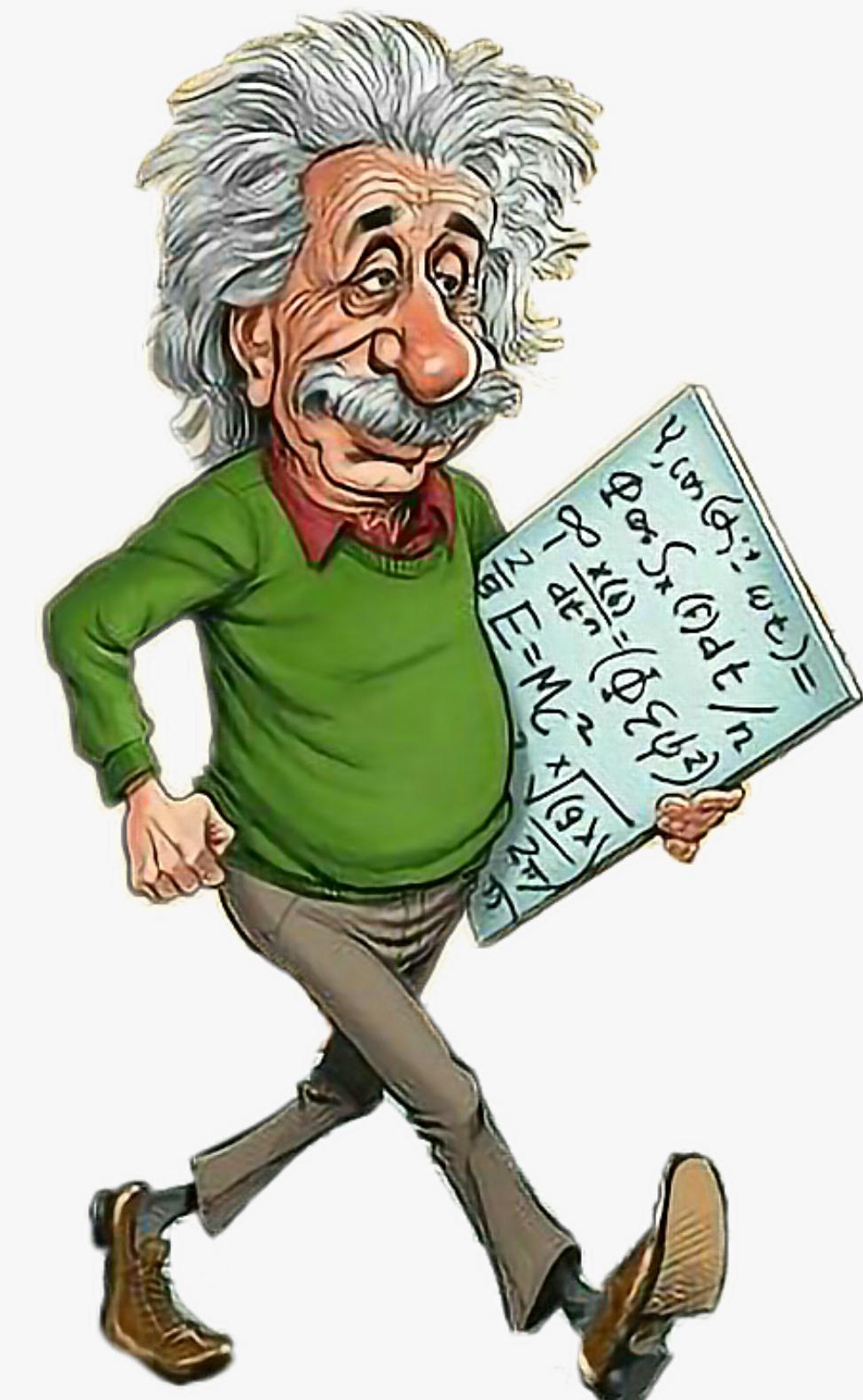
Spooky Action at a Distance

Spooky What ?

Entangled particles

Quantum entanglement or "*spooky action at a distance*"

as Albert Einstein famously called it, is the idea that the fates of tiny particles are linked to each other even if they're separated by long distances.



Revisiting Observers

Subscribe(Observer)

I hate the term “Design Patterns”

Design Patterns

It implies there are **universally** applicable solutions to some common code scenarios.

Just **codifying** existing practice into some **rules** and blindly following them is a comfortable path, but not the optimal one.

It turns out it's not as easy as following **recipes**.

Each situation and best associated solution is **unique**.

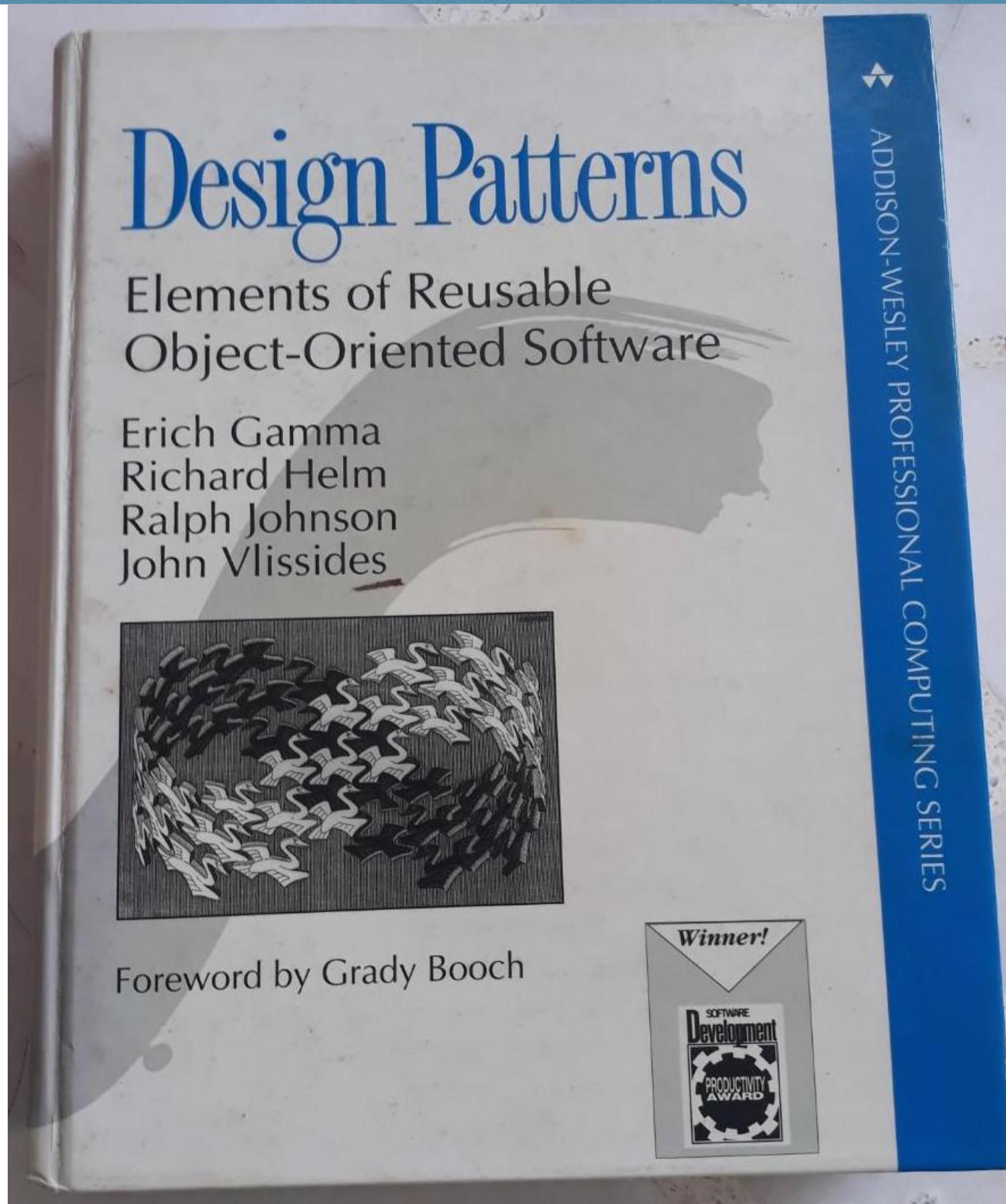
Design Patterns

However there is value in having **uniform** code structure throughout a project.

So this topic is not to be discarded just yet, rather it needs more **careful examination**.

GoF Book

A classic
Too formal & dry



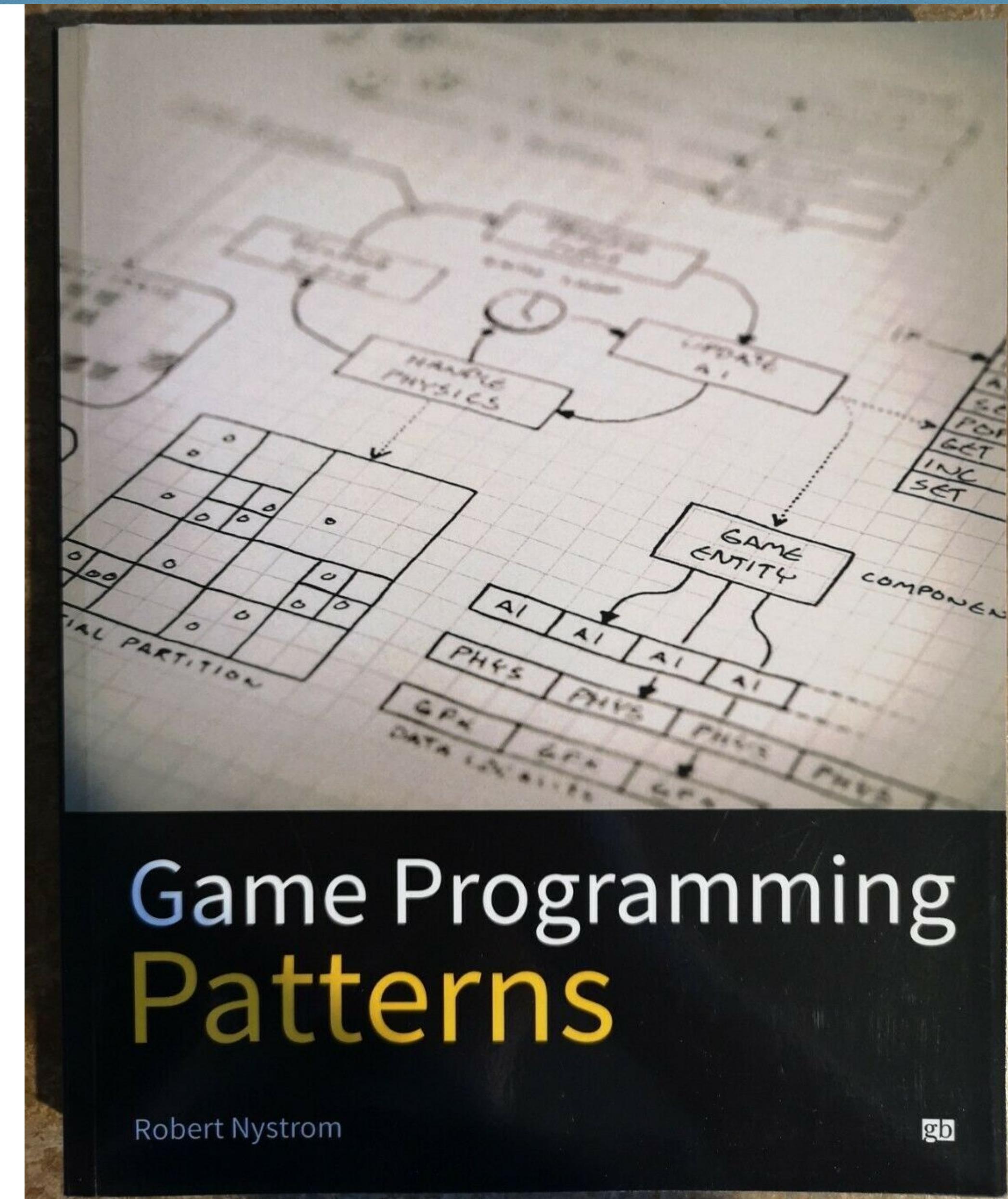
Game Programming Patterns



Bob Nystrom

gameprogrammingpatterns.com

amazon.com/Game-Programming-Patterns-Robert-Nystrom/dp/0990582906/



Related Session - CppCon 2021

Klaus Iglberger - Design Patterns: Facts and Misconceptions

Design Patterns have proven to be useful over several decades and knowledge about them is still very important to design robust, decoupled systems. However, in recent decades a lot of misconceptions have piled up, many based on **misunderstandings** about software design in general and Design Patterns in particular.

The purpose of this talk is to help to separate **facts** from **misconceptions**. It explains what software design is, how Design Patterns fit in, and what an **idiom** is.

<https://sched.co/nv3J>

Tuesday, October 26

7:45am MDT

Design Patterns: Facts and Misconceptions

Klaus Iglberger



Related Session - CppCon 2021

Klaus Iglberger - Design Patterns: Facts and Misconceptions

Addresses the following *misconceptions* about Design Patterns:

- Design Patterns are **outdated** and have become irrelevant
- The GoF Design Patterns are nothing but **idioms**
- The GoF Design Patterns are limited to **object-oriented programming**
- **std::make_unique** is a Design Pattern and helps to adhere to **SRP**

<https://sched.co/nv3J>

Tuesday, October 26

7:45am MDT

Design Patterns: Facts and Misconceptions

Klaus Iglberger



Observer Pattern

In terms of **inspectable properties** of objects:

- What have we learned from years of **OO influence** from other languages and frameworks?
- How can we leverage these borrowed techniques in a **value-oriented** context?
- Does **C++** benefit from special considerations?

Observer Pattern

Let's revisit our old friend, the [Observer](#) pattern - from theory to practice.

I'm not going to offer [The Solution™](#)

We're going to examine [tradeoffs](#) for several possible implementations, in various usage scenarios from a real project.

Observer Pattern

Observers are everywhere...

Think:

- MVC
- MVVM
- Qt signal-slot mechanism
- not just GUI \leftrightarrow model, also model \leftrightarrow model



Observer Pattern

It's a show with **Actors** and **Actions**

Subject/Actor doesn't know what (type) the **Observers** are.

It just knows that they exist and **how to notify** them when certain **actions** occur.

Low Coupling

Subscription Model

Tune-in to a particular radio station



Remote Objects

Inspectable properties and remote objects

"spooky action at a distance"

```
class Widget
{
    Data mData;

public:

    void Set(const Data & d) {
        if (d != mData) {
            mData = d;
            NotifyObservers();
        }
    }
};
```

Subscription Order

Observers added in a certain order.

Do they respond in the same order?

```
class Widget
{
    ... Salient Data

    std::vector<I0bserver *> m0bservers;
};
```

Subscribing

```
void Widget::AddObserver(IObserver & aObserver)
{
    // too simple, right?
    mObservers.push_back(&aObserver);
}
```

Over-subscribing

Adding an observer more than once?

```
void Widget::AddObserver(I0bserver & a0bserver)
{
    auto found = std::find(m0bservers.begin(), m0bservers.end(), &a0bserver);

    if (found == m0bservers.end())
        m0bservers.push_back(&a0bserver);
}
```

Do you want to allow an observer to subscribe more than once?

Do you expect the observer to be called twice for the same event?

Over-subscribing

What about **local** reasoning?

```
void Func()
{
    obj->AddObserver(*this);

    ... // do something important

    obj->RemoveObserver(*this); // what if this obs was already added before?
}
```

Over-subscribing

What about **local** reasoning?

```
void Func()
{
    RegisterObserver obs(*this, actor); // RAII remember if we added
    ... // do something important
    // ~RegisterObserver() removes *this from observers if we added in C-ctor
}
```

Over-subscribing

Signal the caller if the registration was "successful"

```
bool Widget::AddObserver(I0bserver & a0bserver)
{
    auto found = std::find(m0bservers.begin(), m0bservers.end(), &a0bserver);
    if (found != m0bservers.end())
        return false; // observer was already registered

    m0bservers.push_back(&a0bserver);
    return true;
}
```

Over-subscribing

Adding an observer more than once?

```
void Widget::AddObserver(I0bserver & a0bserver)
{
    m0bservers.push_back(&a0bserver);
}
```

We expect the observer to be called twice for the same event.

Local reasoning - restricted lifetime.



Unsubscribe

Removing an observer not in the list (already removed?)

```
void Widget::RemoveObserver(I0bserver & a0bserver)
{
    auto found = std::find(m0bservers.begin(), m0bservers.end(), &a0bserver);

    if (found != m0bservers.end())
        m0bservers.erase(found);
}
```

For **multiple** registration scenario, what if we remove the **wrong instance**?
(sensitive to **order** of notification)

Unsubscribe

Removing **all** instances of this observer (multiple registration)

```
void Widget::RemoveObserver(I0bserver & a0bserver)
{
    m0bservers.erase(
        std::remove(m0bservers.begin(), m0bservers.end(), &a0bserver),
        m0bservers.end() );
}
```

Unsubscribe

Removing **all** instances of this observer (multiple registration)

```
void Widget::RemoveObserver(I0bserver & a0bserver)
{
    std::erase(m0bservers, &a0bserver); // C++20 safer than erase-remove idiom
}
```

Priority

Who should be notified first?

```
void Widget::AddObserver(I0bserver & a0bserver)
{
    auto found = std::find(m0bservers.begin(), m0bservers.end(), &a0bserver);

    if (found == m0bservers.end())
        m0bservers.insert(m0bservers.begin(), &a0bserver);
}
```

Priority

Do we need priority buckets?

```
class Widget
{
    ... mSalientData;

    std::vector<I0bserver *> m0bserversRing0;
    std::vector<I0bserver *> m0bserversRing1;
    std::vector<I0bserver *> m0bserversRing2;
    ...
};
```



Priority

Do we need priority buckets?

```
void Widget::AddObserver(I0bserver & a0bserver, Priority p)
{
    ...
    // what happens if an observer is registered (by mistake)
    // with different priorities?
}
```

Broadcast

Notify all registered observers, in order:

```
void Widget::NotifyObservers()  
{  
    for (auto & observer : mObservers)  
        observer->WidgetChanged(this);  
}
```



Tune-in

Tune-in and react to the event triggered by the actor:

```
void SomeObserver::WidgetChanged(Actor * sender)
{
    // react in some way to the changed object (actor)

    ...
}
```



Unsubscribe

Safe to deregister at any time?

What if an observer wants to **remove itself** after receiving a **notification**?

```
void SomeObserver::WidgetChanged(Actor * sender)
{
    ... // react in some way to the changed object (actor)

    sender->RemoveObserver(*this); // WHAT?! don't care about future events
}
```



Unsubscribe

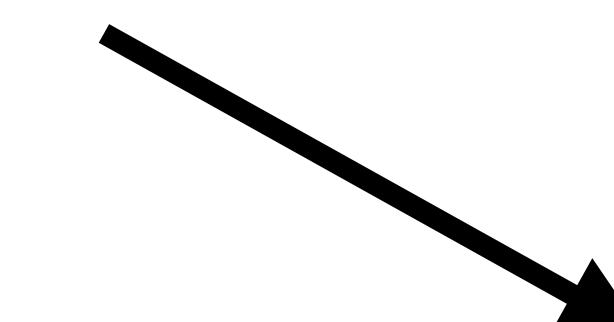
Safe to deregister at any time?

What if an observer wants to **remove itself** after receiving a **notification**?

```
for (auto & observer : mObservers)  
    observer->WidgetChanged(this);
```



```
void SomeObserver::WidgetChanged(Actor * sender)  
{  
    ... // react in some way to the changed object (actor)  
  
    sender->RemoveObserver(*this); // WHAT?! don't care about future events  
}
```



```
std::erase(mObservers, &aObserver);
```



Unsubscribe

How can we make *recursive remove* more **resilient**?

```
bool Widget::RemoveObserver(I0bserver & a0bserver)
{
    for(auto it = m0bservers.begin(); it != m0bservers.end(); ++it)
    {
        if (*it == &a0bserver)
        {
            *it = nullptr; // replace observer with a sentinel
            return true;
        }
    }

    return false;
}
```

Broadcast

Notify all registered observers:

```
void Widget::NotifyObservers()
{
    for (auto & observer : mObservers)
    {
        if (observer)
            observer->WidgetChanged(this);
    }

    std::erase(mObservers, nullptr); // deferred cleanup of removed observers
}
```



Register

Recursive add observer has the same problem, but it's more rare in practice.

Small Objects

Can small objects afford to have observers?

```
class SmallObject
{
    ... mSalientData;

    std::vector<I0bserver *> m0bservers;
};
```

Small Objects

Can small objects afford to have observers?

```
class SmallObject
{
    ... mSalientData;

    std::vector<I0bserver *> m0bservers;
};
```

What if some instances will never have a registered observer?

An **empty** `std::vector` is not tiny.

Small Objects

Small objects can be register observers lazily

```
class SmallObject
{
    ... mSalientData;

    LazyVector<I0server *> mObservers;
};
```

We can use an indirection to "fault-in" the `std::vector` creation when first needed:

```
operator*()
operator->()
{
    if (mPtr == nullptr)
        mPtr = new std::vector<Type>();
    return mPtr;
}
```

Lots of Objects

What if we have lots of these small objects?

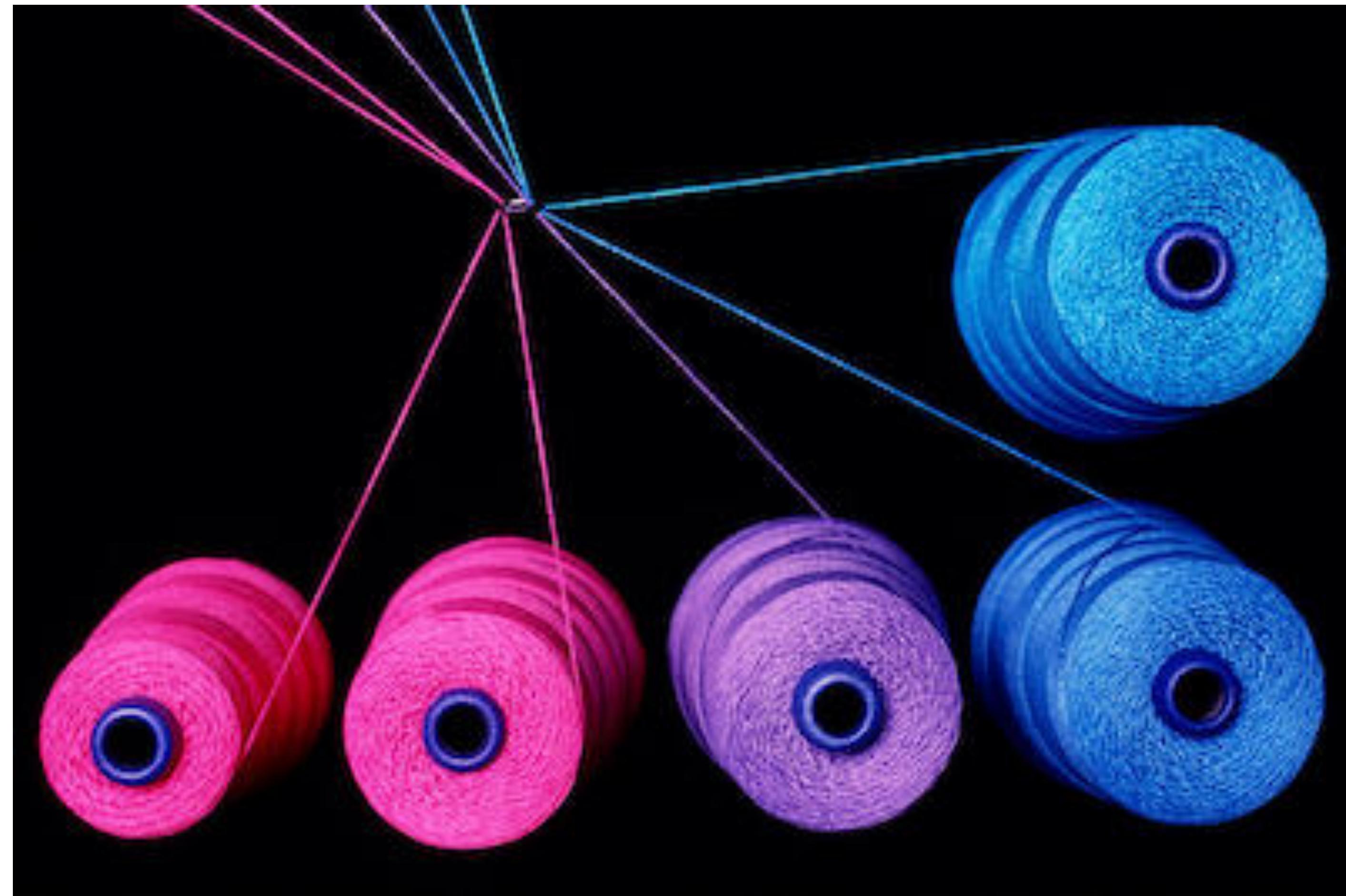
We need to use some additional **aside structure** to keep a record of all observers for each object.

```
class GlobalBottleneck
{
    // (Un)RegisterObserverFor(const Actor *, IObserver *);

    std::unordered_map<const Actor*, std::vector<IObserver *>> mObservers;
};
```

Threads

Multi-lane highway to... crashes



Threads

Put a ~~mutex~~ bottleneck on it !

Guard each function with a **mutex**:

- `Widget::Set()`
- `Widget::AddObserver()`
- `Widget::RemoveObserver()`
- `Widget::NotifyObservers()`

Recursive add/remove observers, bites again!

recursive_mutex ? 😊

Threads

```
class Widget
{
    Data mData;
    std::recursive_mutex mMtx;

public:

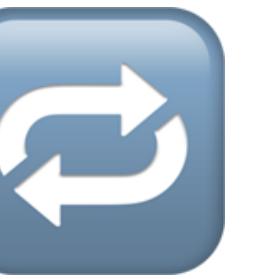
    void Set(const Data & d)
    {
        std::lock_guard<recursive_mutex> lock(mMtx);

        if (d != mData) {
            mData = d;
            NotifyObservers();
        }
    }
};
```

Threads

Not bulletproof!

You can get in a dead-lock situation.



recursive_mutex 😔

Our Values

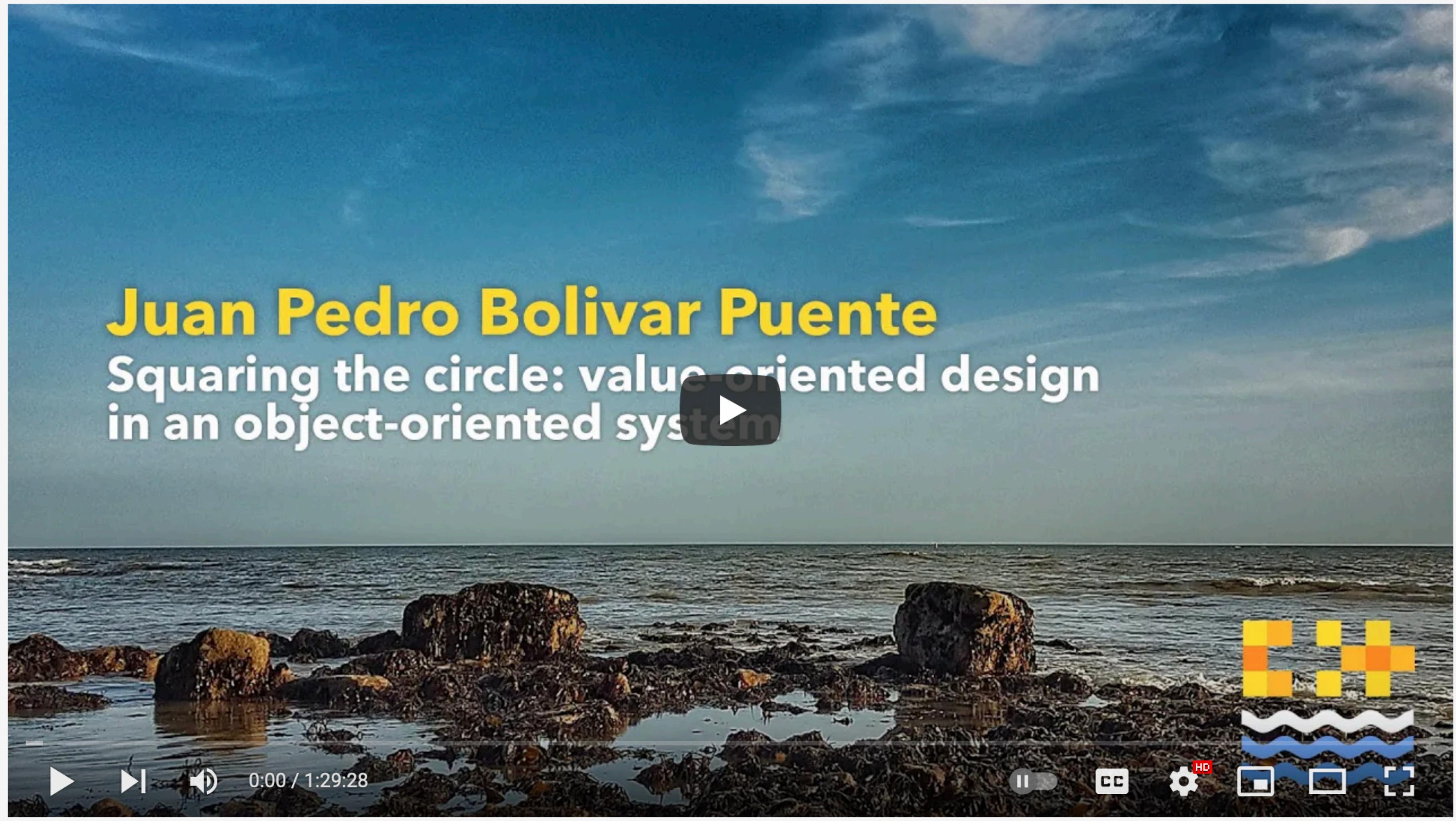
What about Squaring the Circle ?

Our Values

What about Squaring the Circle ?

Value-oriented design in an **Object**-oriented system

Our Values



Value-oriented design in an object-oriented system - Juan Pedro Bolivar Puente [C++ on Sea 2020]

Friday, October 29

9:00am MDT



Squaring the Circle: Value-oriented Design in an Object-oriented System

Juan Pedro Bolivar Puente



youtube.com/watch?v=SAMR5GJ_GqA

Threads

When in doubt, always make **copies.**



Threads

```
void Widget::NotifyObservers()
{
    std::vector<I0bserver *> cpy;
{
    std::lock_guard<mutex> lock(mMtx);
    cpy = m0bservers;
}

size_t count = cpy.size();
for (size_t i = 0; i < count; ++i) // avoid the issues with iter invalidation
{
    if (m0bservers[i])
        cpy[i]->WidgetChanged(this);
}

{
    std::lock_guard<mutex> lock(mMtx);
    std::erase(m0bservers, nullptr); // deferred cleanup of removed observers
}
}
```



Threads

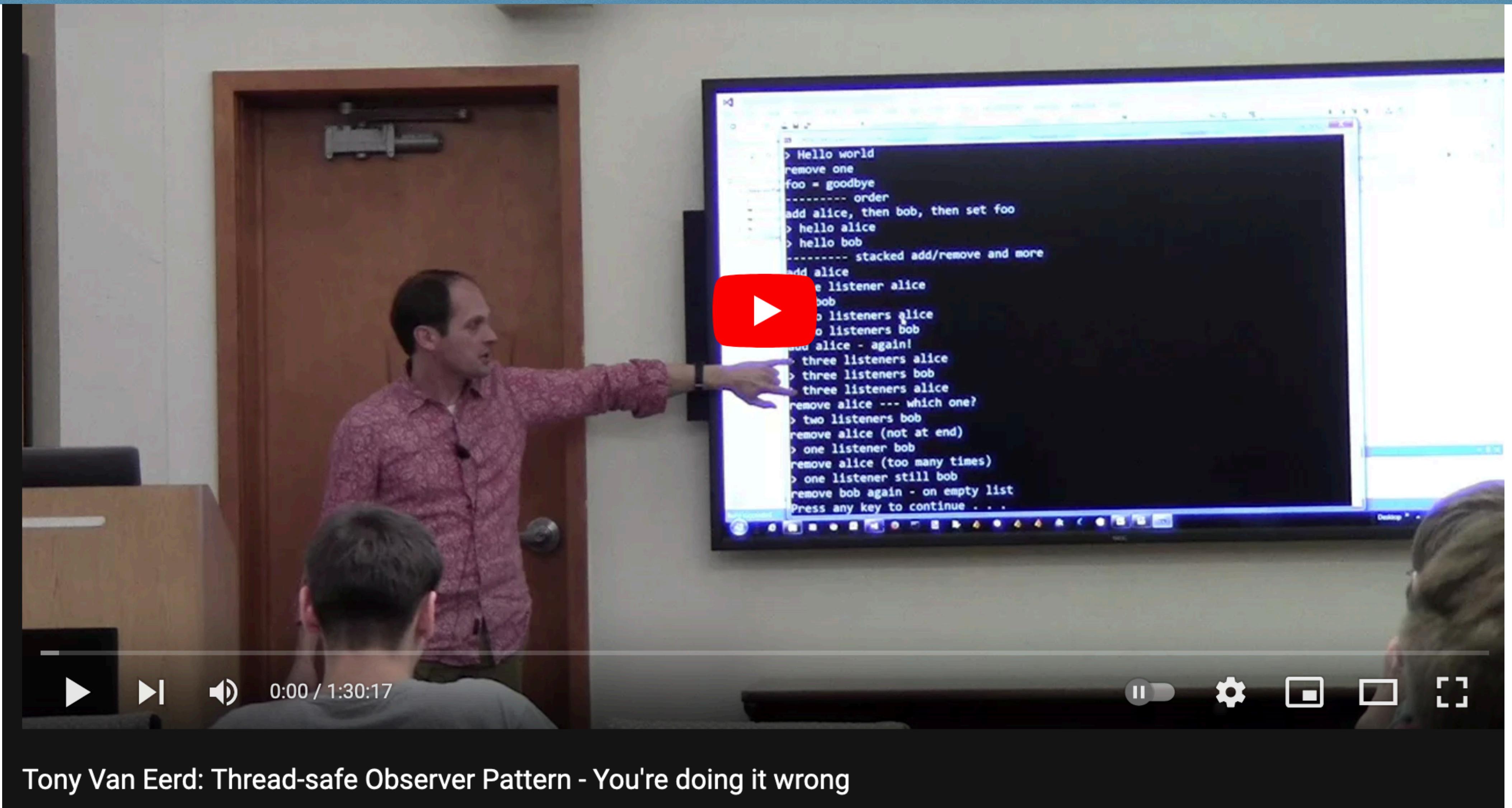
We probably need something like:

`QObject::deleteLater()`

In general, even if you're not using **Qt**,

I think it's very instructive to learn how UI observers are designed to work in Qt.

C++ Now 2016



www.youtube.com/watch?v=RVvVQply6zc

Threads

Basically, in a multi-threaded context, it's almost impossible to implement a solid Observer pattern

In real code you can't see the **deadlocks**... until they happen.

Rule of thumb

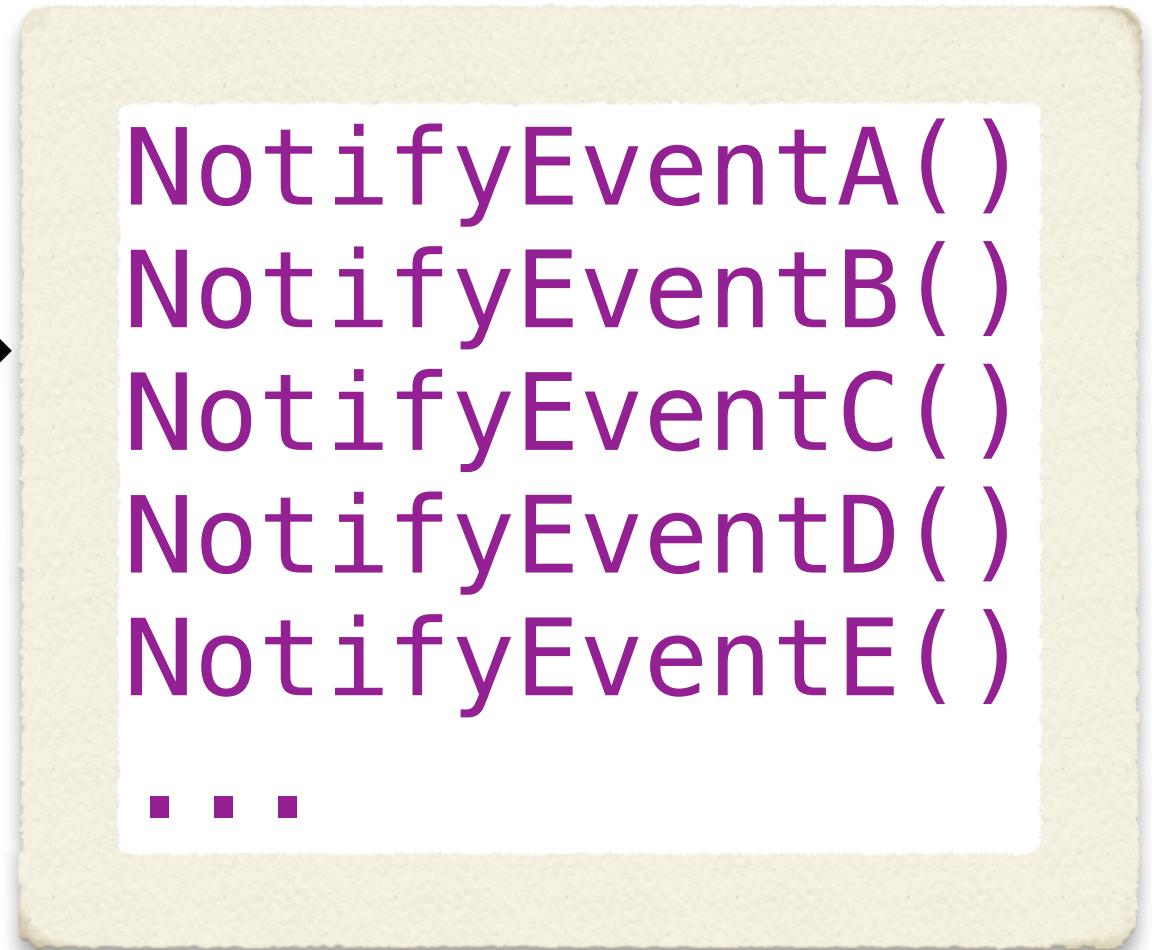
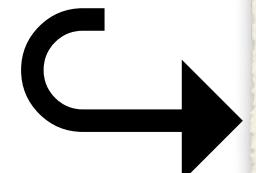
Don't hold a lock
while calling *unknown* code.



Intrusive

Anyway, we don't all this mess inside our type:

- `Widget::AddObserver()`
- `Widget::RemoveObserver()`
- `Widget::NotifyObservers(.)`
- ...



NotifyEventA()
NotifyEventB()
NotifyEventC()
NotifyEventD()
NotifyEventE()
...

And we want a generic/reusable template as a base.

```
class Widget : public Actor<Widget>
{
```

Remote Objects

Inspectable properties and remote objects

```
class Widget : public Actor<Widget>
{
    Data mData;

public:

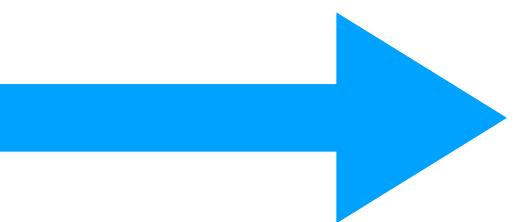
    void Set(const Data & d) {
        if (d != mData) {
            mData = d;
            NotifyObservers();
        }
    }
};
```



"spooky action at a distance"

Remote Observer

```
class RemoteObserver : public IObserver  
{  
    RemoteObserver() {  
        mWidget->AddObserver(*this);  
    }  
  
    ~RemoteObserver(){  
        mWidget->RemoveObserver(*this);  
    }  
  
    void WidgetChanged(Actor * sender) override  
    {  
        // react in some way to the changed object (actor)  
        sender->Query???();  
    }  
    ...  
    Actor * mWidget;  
};
```



Dangling

```
class RemoteObserver : public IObserver  
{  
    RemoteObserver() {  
        mWidget->AddObserver(*this);  
    }  
  
    ~RemoteObserver(){  
        mWidget->RemoveObserver(*this);  
    }  
  
...  
    Actor * mWidget;  
};
```



Don't forget to cancel...

```
// RAII  
RegisterObserver obs(*this, mWidget);
```

Global State

Observer networks form a global state.



The same reason I dislike `std::shared_ptr<>`

Pushing up the daisies

Memory management issues:

- dead subjects
- missing observers

Blissfully dangling...

Pushing up the daisies



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@ciura_victor

Victor Ciura
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