C++ Review DUNE

Una organización donde compartir notas acerca de C++ con PDFs escritos en LATEX. 8 de mayo del 2022

Pad de apuntes

Sesión grabada en diode.zone

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CMake as a build system

Documentación de CMake

- cmake_minimum_required
- project
- find_package
- list
- include
- add_executable
- target_link_libraries

Documentación de Dune build system

- dune_project
- dune_enable_all_packages
- finalize_dune_project
- target_link_dune_default_libraries

```
macro(target_link_dune_default_libraries _target)
foreach(_lib ${DUNE_LIBS}}
    target_link_libraries(${_target} PUBLIC ${_lib})
endforeach()
endmacro(target link dune default libraries)
```

```
cmake_minimum_required(VERSION 3.13)
project(dune-vector-learn CXX)
#find dune-common and set the module path
find package(dune-common REQUIRED)
list(APPEND CMAKE MODULE PATH ${dune-common MODULE PATH})
#include the dune macros
include(DuneMacros)
# start a dune project with information from dune.module
dune project()
dune enable all packages()
add executable("dune-vector-learn" dune-vector-learn.cc)
target_link_dune_default_libraries("dune-vector-learn")
add executable("identity" identity.cc)
target link dune default libraries("identity")
# finalize the dune project, e.g. generating config.h etc.
finalize_dune_project(GENERATE_CONFIG H CMAKE)
```

Dune :: TestSuite

A Simple helper class to organize your test suite.

Dune::ArrayList A dynamically growing random access list.

```
template <class T,
    int N = 100,
    class A = std::allocator<T>>
class Dune::ArrayList<T, N, A>
```

```
#ifdef HAVE_CONFIG_H
#include "config.h"
#endif
#include <iostream>
#include <dune/common/test/testsuite.hh>
#include <dune/common/arraylist.hh>
int main(int argc, char **argv)
 Dune::TestSuite test;
 Dune::ArrayList<double, 10> alist;
 for (int i = 0; i < 100; i++)
   alist.push back(i);
 for (auto &e : alist)
   std::cout << e << std::endl;
 return test.exit():
```

#incl

Code snippet

```
[[maybe_unused]] Suppresses warnings on unused entities.
```

Dune :: FieldVector vector space out of a tensor product of fields.

```
template <class K, int SIZE>
class Dune::FieldVector<K, SIZE>
```

Dune :: printvector Print an ISTL vector.

DUNE_THROW Macro to throw an exception.

```
#define DUNE_THROW (E, m)
```

Dune :: Exception Base class for Dune-Exceptions.

```
#include <dune/common/fvector.hh>
#include <dune/istl/io.hh>
#include <iostream>
int main()
  [[maybe_unused]] int p = 0;
  constexpr int dim = 3;
  Dune::FieldVector<double, dim> x(0);
  Dune::printvector(std::cout, x, "x", "row");
  trv
    if (x.dimension \neq 2)
      DUNE_THROW(Dune:: Exception,
                  "DUNE ASSERT AND RETURN returned incorrect dimension")
  catch (Dune:: Exception &e)
    std::cerr << "Dune reported error: " << e << std::endl;
    return 1:
  catch ( ... )
    std::cerr << "Unknown exception thrown!" << std::endl;</pre>
    return 1;
```

 $v\in\mathbb{Z}^{100}.$

```
#include <fmt/ranges.h>
#include <iostream>
#include <vector>
int main()
  std::vector<int> v{};
  for (int i = 0; i < 100; i++)
    v.push back(i);
  fmt::print("Primera forma sin iterador:\n{}\n", v);
  for (int i = 0; i < v.size(); i++)</pre>
    v[i] *= 2;
  fmt::print("Segunda forma con iterador:\n");
  std::vector<int>::iterator iter = v.begin();
  while (iter \neq v.end())
    std::cout << *iter << std::endl;</pre>
    iter++;
```

Dune :: Matrix A generic dynamic dense matrix.

template <class T, class A = std::allocator<T>>
class Dune::Matrix<T, A>

Dune :: printmatrix Print a generic block matrix.

Die Maximumsnorm, Tschebyschew-Norm oder ∞ -Norm (Unendlich-Norm) eines Vektors ist definiert als

$$\|x\|_{\infty} = \max_{i=1,\dots,n} |x_i|$$

Die euklidische Norm oder 2-Norm eines Vektors ist definiert als

$$\|x\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$$

Die Summennorm, (genauer) Betragssummennorm, oder 1-Norm (lies: "Einsnorm") eines Vektors ist definiert als

$$\left\|x\right\|_1 = \sum_{i=1}^n \left|x_i\right|$$

```
#include <dune/common/fmatrix.hh>
#include <dune/istl/io.hh>
#include <dune/istl/matrix.hh>
#include <fmt/core.h>
#include <fmt/ranges.h>
int main()
 constexpr int dim = 2;
 Dune::FieldVector<double, dim> x(0);
 Dune::printvector(std::cout, x, "x", "row");
  fmt::print("x = {}\n", x);
  fmt::print("Size of x: {}\n". x.size()):
  fmt::print("|x|, = {}\n", x.two norm());
  fmt::print("\|x\|_{\infty}: {}\n", x.infinity norm());
  fmt::print("Dimension of x: {}\n", x.dimension);
 Dune::Matrix<double> matrix(3, 5);
 matrix = 0:
 Dune::printmatrix(std::cout, matrix, "Matrix<double>", "--");
  fmt::print("matrix has {} rows.\n", matrix.N());
  fmt::print("matrix has {} columns.\n". matrix.M()):
  return 0;
```

Die Frobeniusnorm $\|\cdot\|_F$ einer Komplexe Zahl $(m \times n)$ -Matrix $A \in \mathbb{K}^{m \times n}$ mit \mathbb{K} aus dem Körper der reellen oder komplexen Zahlen ist definiert als

$$\|A\|_F := \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2}.$$

Dune :: Functions :: Polynomial A scalar polynomial implementation.

```
template <class K>
class Dune::Functions::Polynomial<K>
```

```
#include <iostream>
#include <dune/functions/analyticfunctions/polynomial.hh>
int main(int argc, char **argv)
 auto p = Dune::Functions::Polynomial<int>({1, 2, 3});
 auto a_i = p.coefficients();
 std::cout << "P[x] = "
            << a i[0] << "* x ^{\circ} " << 0 << " + "
            << a_i[1] << "* x ^ " << 1 << " + "
            << a i[2] << "* x ^ " << 2 << "\n"
            << "P[x = 0]: " << p(0) << "\n"
            << "P[x = 1]: " << p(1) << "\n"
            \ll "P[x = 2]: " \ll p(2) \ll "\n":
 return 0:
```

```
#include <fmt/ranges.h>
#include <iostream>
#include <vector>

std::vector<double> range(double min, double max, std::size_t N)
{
    std::vector<double> range;
    double delta = (max - min) / double(N - 1);
    for (int i = 0; i < N; i++)
    {
        range.push_back(min + i * delta);
    }
    return range;
}</pre>
```

```
int main()
  using MyDVector = std::vector<double>;
  std::vector<int> v1 = {1, 2, 3, 4};
  fmt::print("{}\n", v1);
  std::vector<int> v2;
 v2 = std::vector<int>(v1.begin() + 1, v1.end() - 1);
  fmt::print("{}\n", v2);
  MyDVector u1 = range(1, 2, 100);
  fmt::print("{}\n", u1);
  MyDVector u2 = range(1., 21., 20);
  fmt::print("{}\n", u2);
  return 0;
```