

# Computer Vision Systems Programming VO Models vs. Algorithms

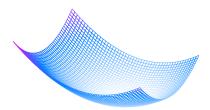
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### **Topics**

Models vs. algorithms

Approaching computer vision problems

Numerical optimization



CV is about infering some world state  $\mathbf{w}$  from measurements  $\mathbf{x}$   $\mathbf{x}$  is a feature vector extracted from images

 $\mathbf{w} \in \mathbb{R}^m$  : **regression** problem (e.g. stereo)

 $\mathbf{w} \in \mathbb{N}^m$  : classification problem (e.g. face recognition)

How Not To Do It

#### Don't think in terms of algorithms

- ▶ First I'll convert my image to grayscale
- ▶ Then I'll threshold it at some value
- ► Then I'll clean up holes via morphology

#### Such solutions

- Rely on many magic numbers that all interact
- ▶ Do not encode uncertainty about w



Think about how your data came into being Use this information to model the relationship between  ${\bf x}$  and  ${\bf w}$  Ideally use probabilistic models as inference is ill-posed

"Say **what** you want to do, not **how** you are going to to it"  $\sim$  A. Fitzgibbon



On this basis, CV is about

- ▶ Defining a **model** that relates **x** and **w**
- **Learning** its parameters  $\theta$  from training samples
- lacktriangle Using an inference algorithm that returns  $\Pr(\mathbf{w}|\mathbf{x},oldsymbol{ heta})$

Example: Background Subtraction

We want to segment images in foreground and background

- Based on the perceived brightness of objects
- In scenes with a constant background
- On a per-pixel basis





Image from Prince 2012

Example: Background Subtraction

Therefore we have  $w \in \{0,1\}$  (classification problem)

Given our problem, we model

$$Pr(x|w = 0) = Norm_{x}(\mu, \sigma^{2})$$

$$Pr(x|w = 1) = Uniform_{x}(0, 255)$$

$$Pr(w) = Bern_{w}(\lambda)$$

Example: Background Subtraction

We assume  $\lambda = 0.5$ 

And learn  $\pmb{\theta} = (\mu, \sigma)$  from training samples  $\{x_i\}_{i=1}^n$ 

- Using the maximum likelihood method
- Assuming that the training samples are independent

We thus learn

$$\hat{\boldsymbol{\theta}} = \underset{\boldsymbol{\theta}}{\operatorname{arg max}} \Pr(x_1, \dots, x_n | \boldsymbol{\theta})$$
$$= \underset{\boldsymbol{\theta}}{\operatorname{arg max}} \prod_{i=1}^n \Pr(x_i | \boldsymbol{\theta})$$

Example: Background Subtraction

#### Continuing from before

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} \prod_{i=1}^{n} \operatorname{Norm}(\mu, \sigma^{2})$$

$$= \arg \max_{\boldsymbol{\theta}} \sum_{i=1}^{n} \log \operatorname{Norm}(\mu, \sigma^{2})$$

$$= \arg \max_{\boldsymbol{\theta}} \left( -0.5n \log \sigma^{2} - 0.5n \log(2\pi) - 0.5 \sum_{i=1}^{n} \frac{(x_{i} - \mu)^{2}}{\sigma^{2}} \right)$$

Example: Background Subtraction

If we differentiate and equate to zero, we obtain

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (x_i - \hat{\mu})^2$$

We have derived algorithms for finding our model parameters



### Models vs. Algorithms

Models describe the relationship between  ${\bf x}$  and  ${\bf w}$  Algorithms are recipes for finding  ${\boldsymbol \theta}$ 

Model	Algorithm
Gaussian Linear models* Structure from motion* Rigid motion between point sets*	Mean & variance Linear least squares Bundle adjustment ICP

<sup>\*</sup> Assuming zero-mean Gaussian noise



#### Inference

In the example case we have modeled  $Pr(\mathbf{x}|\mathbf{w})$ 

- ► Such models are called generative
- ▶ In this case, we perform inference using Bayes' rule

$$Pr(\mathbf{w}|\mathbf{x}) = \frac{Pr(\mathbf{x}|\mathbf{w}) Pr(\mathbf{w})}{Pr(\mathbf{x})}$$

We can also model  $\Pr(\mathbf{w}|\mathbf{x})$  directly

- Such models are called discriminative
- ▶ In this case, we can perform inference directly



Assume 
$$x = 100, \mu = 95, \sigma = 2$$

In this case, we obtain

- $\Pr(w=0) = \Pr(w=1) = 0.5$
- $\Pr(x = 100 | w = 0) = \text{Norm}_{100}(90, 2^2) \approx 0.009$
- $ightharpoonup \Pr(x = 100) = \sum_{i \in \{0,1\}} \Pr(x = 100 | w = i) \Pr(w = i) \approx .007$
- $\Pr(w|x=100) \approx (0.69, 0.31)$

Therefore we classify the pixel as background



### Complex Models



mage from https://www.youtube.com/watch?v=sQegEro5Bfc

### Optimization

#### Learning $\theta$ is an optimization problem

- We seek  $\hat{\boldsymbol{\theta}}$  that maximizes some objective function  $f(\boldsymbol{\theta})$
- ▶ E.g. before we sought  $\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} \Pr(x_1, \dots, x_n | \boldsymbol{\theta})$

There are algorithms available for finding heta of many models

But this is not always the case

Therefore, a brief intro on optimization ...



### Optimization

We seek 
$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} f(\boldsymbol{\theta}) = \arg \min_{\boldsymbol{\theta}} -f(\boldsymbol{\theta})$$

- ightharpoonup Sometimes  $\hat{ heta}$  can be found analytically (like before)
- Often we have to resort to iterative methods

#### Iterative methods

- Start with an estimate  $\boldsymbol{\theta}^{[0]}$
- Improve this estimate iteratively using local information
- Until no more improvement can be made



# Optimization Iterative Methods

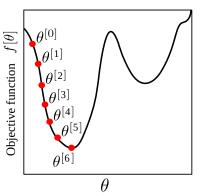
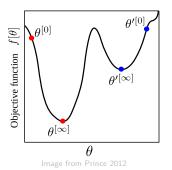


Image adapted from Prince 2012

# Optimization Iterative Methods

This means we need a good initial estimate  $oldsymbol{ heta}^{[0]}$ 

- ▶ Otherwise we might get stuck in a local minimum
- Unless f is convex



# Optimization Iterative Methods

Iterative methods work by alternatively

- ► Choosing a search direction using local information
- ► Searching the minimum along that direction in some interval
- lacktriangle Updating  $oldsymbol{ heta}$  according to the found minimum

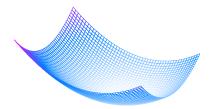
Local information from first and second order derivatives

Many different optimization algorithms

- ► Steepest decent, Newton, Levenberg-Marquardt, BFGS ...
- ► Some can be tested at https://awful.codeplex.com/



We seek the minimum of  $f(\boldsymbol{\theta}) = (\theta_1 - 2)^2 + (\theta_2 - 1)^2$ 



## Optimization Iterative Methods – Simple Example

Finding the minimum with Python and SciPy  $\,$ 

```
def f(x):
    return np.power(x[0]-2,2) + np.power(x[1]-1,2)
scipy.optimize.minimize(f, [5, 5]) # returns [2, 1]
```

## Optimization Iterative Methods – Simple Example

Finding the minimum with Matlab

```
fminunc(@(x)(x(1)-2)^2 + (x(2)-1)^2, [5, 5]) \%  returns [2, 1]
```

### Summary

We have seen how (not) to approach CV problems

▶ See Prince 2012 for more information on CV models

Optimization is fundamental in vision problems

We briefly discussed why, and how optimization works

#### Literature

#### Books for further information on these topics

- ▶ Prince 2012 (http://computervisionmodels.com/)
- ▶ Bishop et al. 2006
- Boyd and Vandenberghe 2009
- ► Wright and Nocedal 1999

### Bibliography

Bishop, Christopher et al. (2006). **Pattern Recognition and Machine Learning**. Springer.

Boyd, Stephen and Lieven Vandenberghe (2009). **Convex Optimization**. Cambridge University Press.

Prince, S.J.D. (2012). **Computer Vision: Models Learning and Inference**. Cambridge University Press.

Wright, SJ and J Nocedal (1999). **Numerical optimization**. Springer.

