

# CARTER SIFFERMAN

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I am a PhD candidate in Computer Science with expertise in **machine learning, computer vision, imaging, and robotics**, specializing in novel sensing systems. I have extensive research experience (publications in CVPR, ICCV, ICRA, IROS) and practical production-oriented experience from industry internships. I am seeking a full-time **Applied Scientist, Research Scientist, or engineering** role where I can apply my expertise to practical problems.

## Education

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**PhD Computer Science: University of Wisconsin - Madison** **2022 - Present**

Thesis: 3D Imaging with Miniature Time-of-Flight Sensors. Advisors: Michael Gleicher, Mohit Gupta  
Expected Graduation: Fall 2025 – Spring 2026 (Flexible)

**M.S. Computer Science: University of Wisconsin - Madison** **2022**

**B.S. Computer Science: Drury University** **2016**

## Experience

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**University of Wisconsin – Madison | Graduate Research Assistant | Madison, WI** **Aug. 2022 - Present**

- Research areas: 3D computer vision, imaging, and robotics (see publications)
- Lead author of five publications in top vision / robotics venues (CVPR, ICCV, ICRA, IROS)
- Mentored nine total undergraduates to support the lab in research and engineering

**Amazon Robotics | Applied Scientist II Intern | Westborough, MA** **May - August 2025**

- Defined and scoped a novel research problem, ensuring alignment with team mission, business needs
- Created evaluation plan, captured dataset, and developed ML model for imaging problem, demonstrating significantly improved performance over prior standard
- Validated and tested algorithms on production hardware
- Contributed to internal codebases and published internal research paper to ensure efficient handoff

**CyberOptics | Machine Vision Research Intern | Minneapolis, MN** **May - August 2022**

- Created, trained, and evaluated ML model which significantly improved 3D reconstruction in challenging conditions by incorporating product layout priors
- Authored internal whitepaper detailing methodology and results of research
- Contributions were subsequently implemented into production systems

**Cerner | Software Engineering Intern | Kansas City, MO** **May - August 2018**

## Technical Skills

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**Languages:** Python, Java, MATLAB, JavaScript, C/C++ (Arduino)

**Technologies:** PyTorch, ROS, ROS 2, NumPy, OpenCV, ML Deployment (TensorRT), Linux, Git, LaTeX

## Selected First-Author Publications

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Click publication names for web page; for full list, see [Google Scholar](#).

**C. Sifferman\***, Y. Li\*, Y. Li, M. Gleicher, M. Gupta, Y. Li. [Recovering Parametric Scenes from Very Few Time-of-Flight Pixels](#). To Appear: *International Conference on Computer Vision (ICCV) 2025*. [**\* Equal contribution**]

**C. Sifferman**, W. Sun, M. Gupta, M. Gleicher. [Using a Distance Sensor to Detect Deviations in a Planar Surface](#). *Robotics and Automation Letters (RA-L)*. *International Conference on Robotics and Automation (ICRA) 2025*.

F. Mu\*, **C. Sifferman\***, S. Jungerman, Y. Li, M. Han, M. Gleicher, M. Gupta, Y. Li. [Towards 3D Vision with Low-Cost Single-Photon Cameras](#). *Computer Vision and Pattern Recognition (CVPR) 2024*. [**\* Equal contribution**]

**C. Sifferman**, Y. Wang, M. Gupta, M. Gleicher. [Unlocking the Performance of Proximity Sensors by Utilizing Transient Histograms](#). *Robotics and Automation Letters (RA-L)*. In *Proceedings: International Conference on Robotics and Automation (ICRA) 2024*.

**C. Sifferman**, D. Mehrotra, M. Gupta, M. Gleicher. [Geometric Calibration of Single-Pixel Distance Sensors](#). *Robotics and Automation Letters (RA-L)*. In *Proceedings: International Conference on Intelligent Robots and Systems (IROS) 2022*.

Z. Moore\*, **C. Sifferman\***, S. Tullis\*, M. Ma, R. Proffitt, M. Skubic. [Depth Sensor-Based In-Home Daily Activity Recognition and Assessment System for Stroke Rehabilitation](#). *IEEE International Conference on Bioinformatics and Biomedicine (BIBM) 2019*. [**\* Equal contribution**]

## Invited Talks

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**MIT Media Lab**, Camera Culture Group. *Imaging with Miniature Time-of-Flight Sensors*. October 2024.

**NASA Goddard Space Flight Center**, Robotics Lunch Discussion. *3D Robot Sensing with Miniature Time of-Flight Sensors*. August 2024.

**SONY**, Research Award Program. *Novel Applications of Miniature Time-of-Flight SPADs*. April 2024.

## Selected Awards

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<b>NSF Research Traineeship Program “INTEGRATE” Fellowship</b>	2024 - 26
<b>McPherson Eye Research Institute Walsh Travel Award</b>	2024
<b>UW-Madison CS Department Summer Research Assistantship</b>	2021
<b>UW-Madison CS Department First Year Scholarship</b>	2020 - 21