

# Senior Design Project

Christopher Waschenko, Yohan Gamboa

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# 1 Project Overview

The Goal of this project is to design a Quadcopter search and report extension module (SREM) that will be an add on to a generic FPV quadcopter drone. The **SREM** will handle the guidance navigation and control of the quadcopter, with the capability of navigation in extreme remote environments using mainly dead reckoning to perceive its state

## 1.1 Requirements

- SREM-1 SREM **SHALL** determine estimate position without the need of GPS
- SREM-2 SREM **SHALL** detect an possible crash site or camp