

Tout ce qui peut mal aller doit être entraîné:
une approche antagoniste à la sensibilité au
risque en apprentissage par renforcement

Séminaire départemental
14 mars 2025

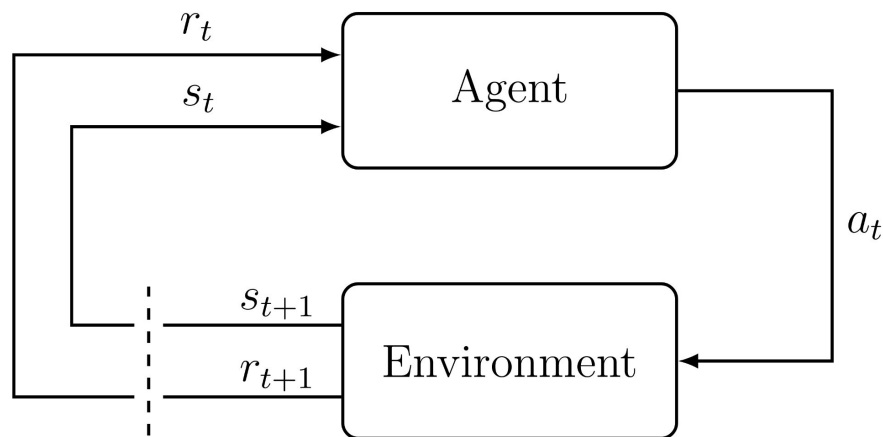
About Me

4th year PhD Student

- Subject: Trustworthy Machine Learning
 - Risk-Sensitive Reinforcement Learning
 - Today's talk!
 - Fairness in Machine Learning
 - Not on today's menu :(!
- Advisor: Audrey Durand



RL 101: Markov Decision Process (MDP)

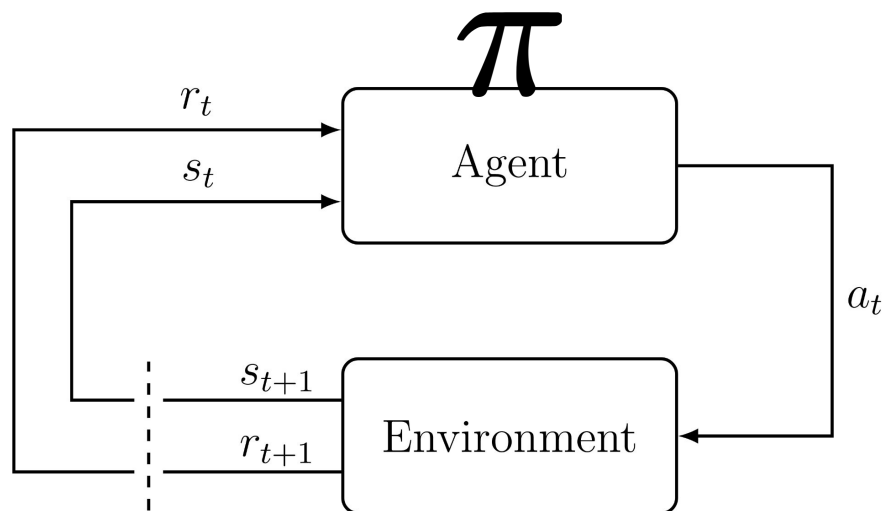


$$\langle \mathcal{S}, \mathcal{A}, P, R, \gamma \rangle$$

**Andrew Barto and
Richard Sutton Receive
A.M. Turing Award**



RL 101: Markov Decision Process (MDP)

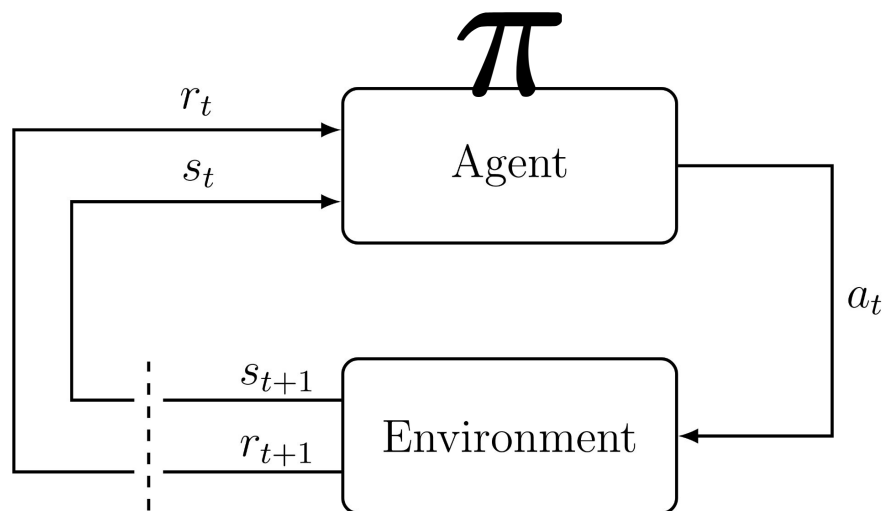


- Action $a_t \sim \pi(h_t)$
- Next state $s_{t+1} \sim P(\cdot \mid s_t, a_t)$
- Reward $r_t = R(s_t, a_t)$
- History $h_t = (s_0, a_0, r_0, \dots, s_t)$

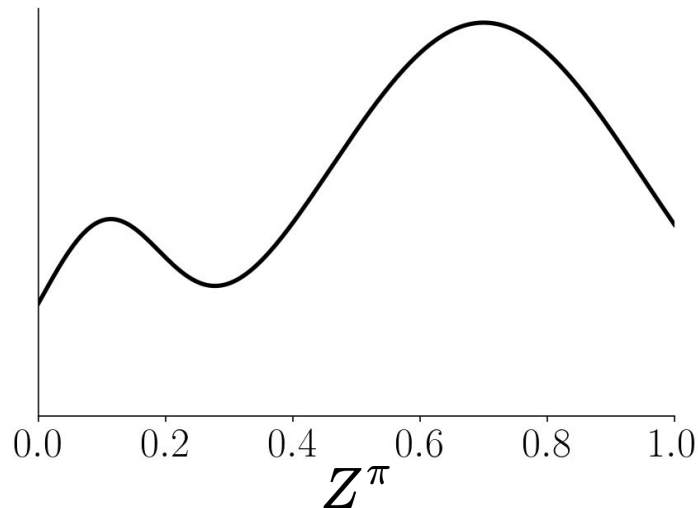
$$\langle \mathcal{S}, \mathcal{A}, P, R, \gamma \rangle$$

Discount Factor

RL 101: Random Total Discounted Return



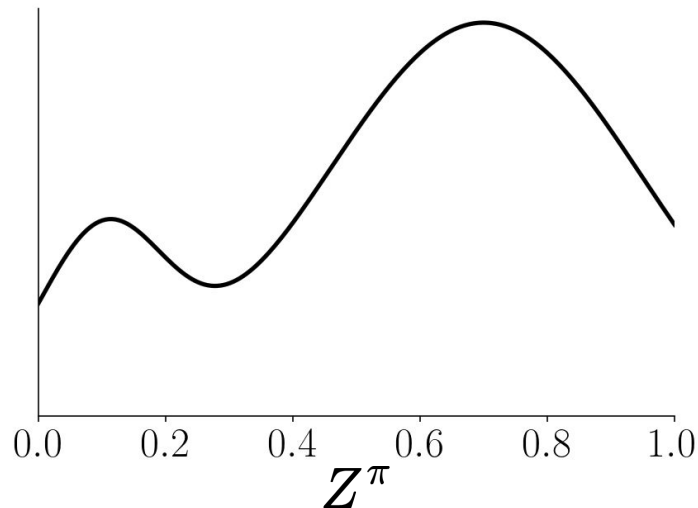
$$Z^\pi := \sum_{t=0}^{\infty} \gamma^t r_t$$



Classical RL objective: Expectation Maximization

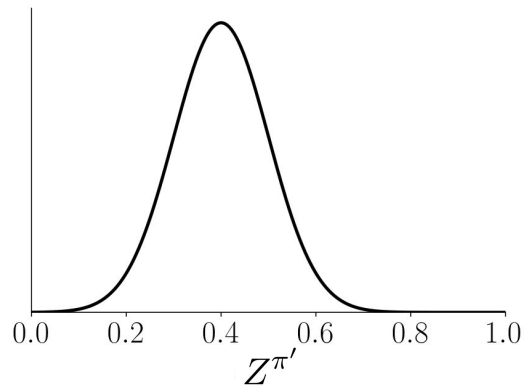
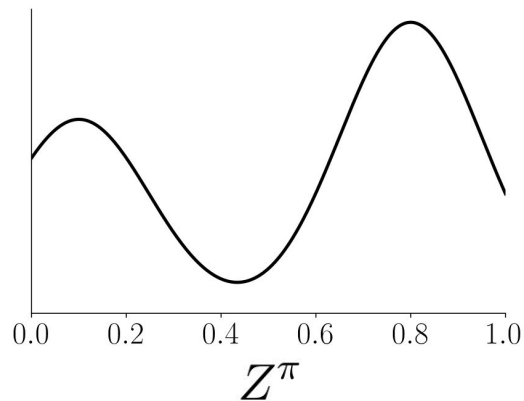
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$$\pi^\star = \arg \max_{\pi} \mathbb{E}[Z^\pi]$$



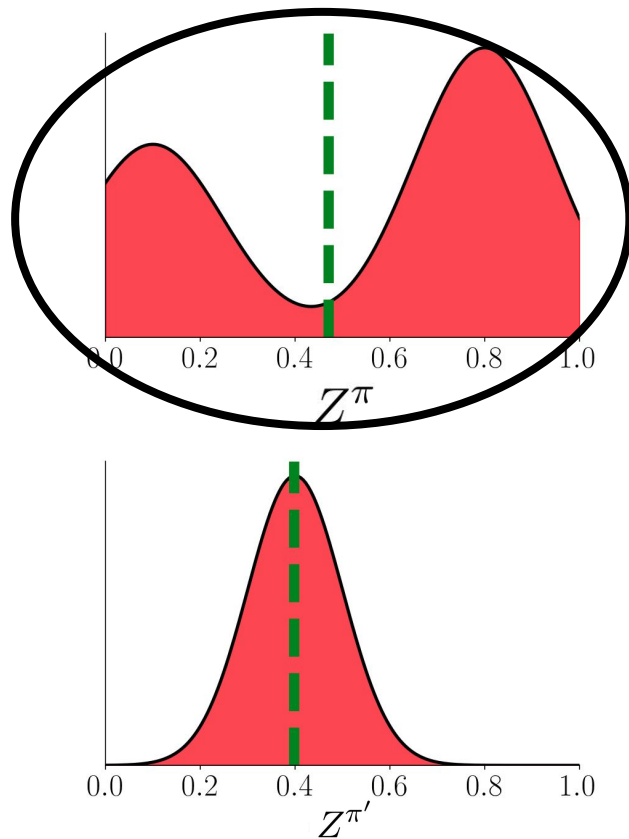
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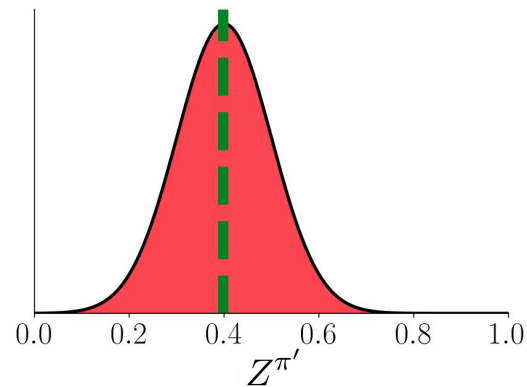
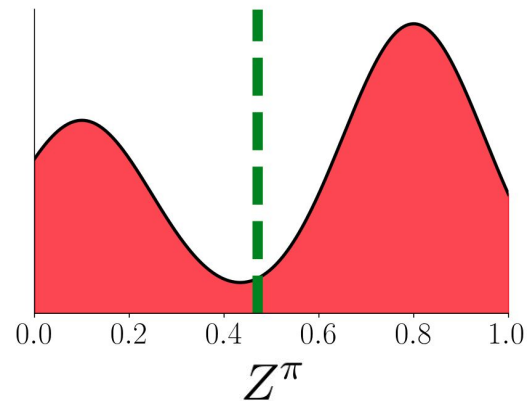
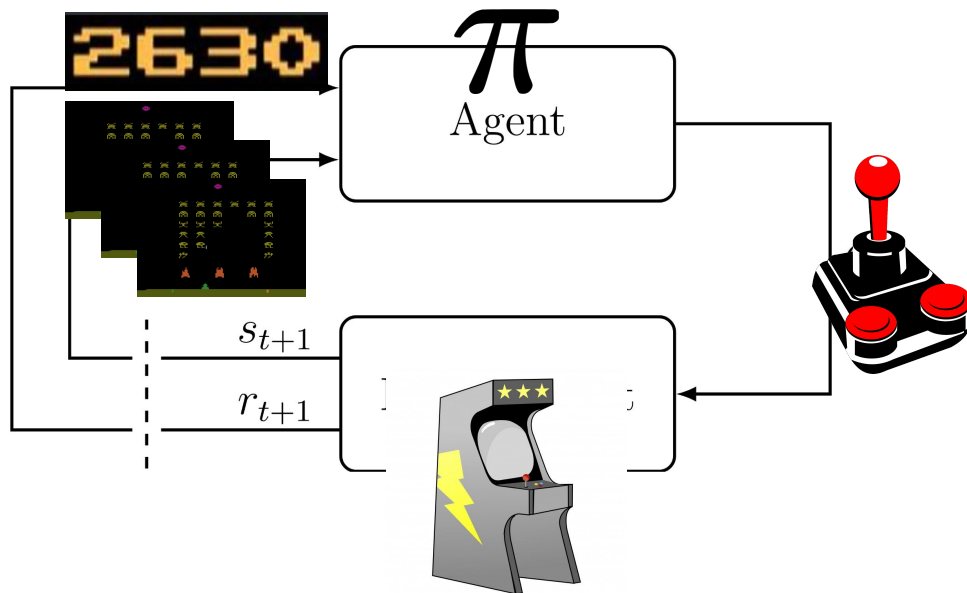
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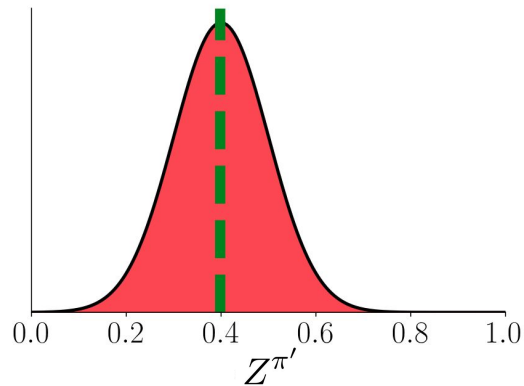
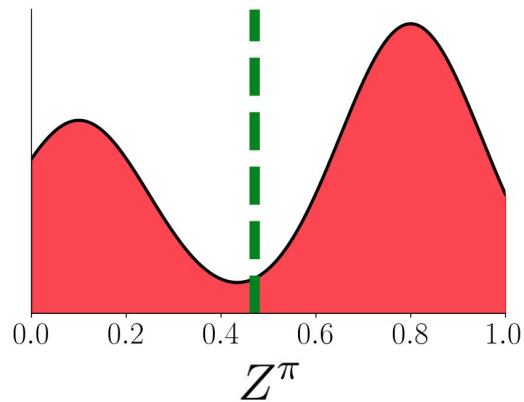
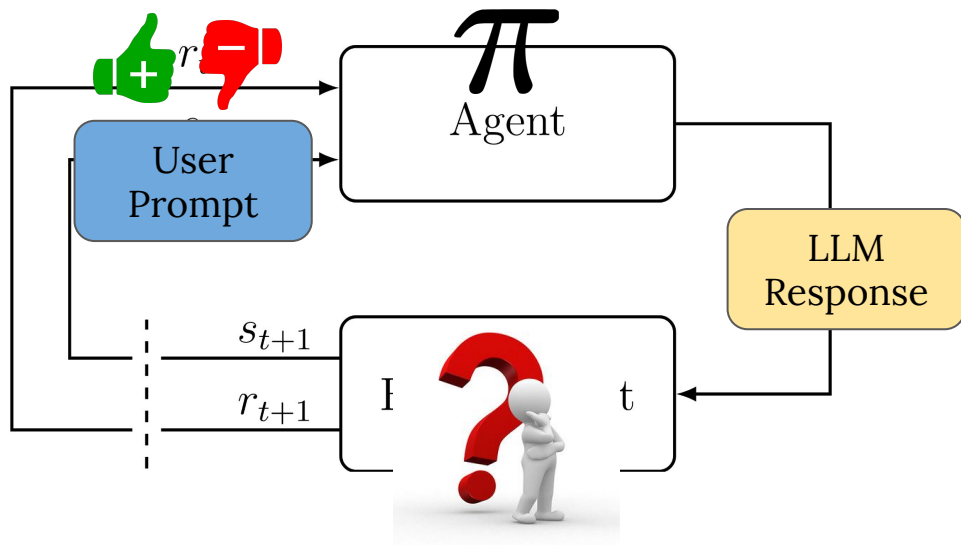
Arcade Learning Environment

[Bellemare et al., 2013]

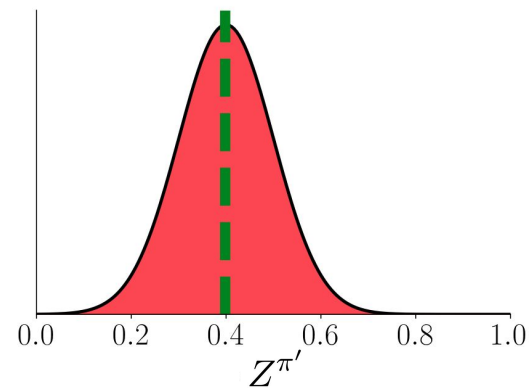
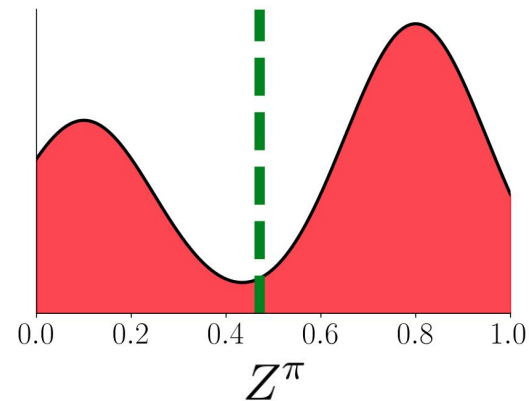
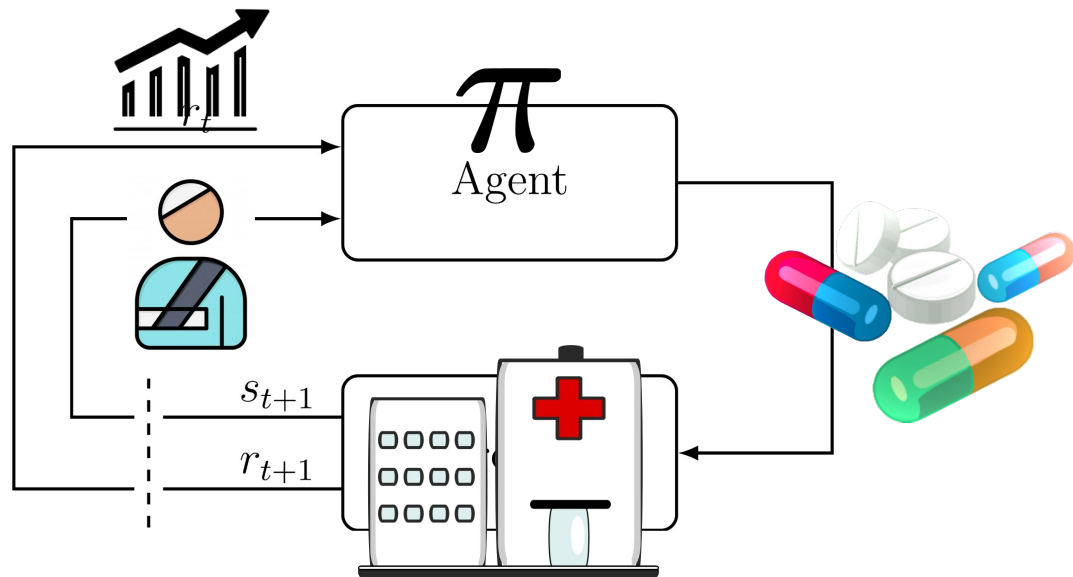


Reinforcement Learning from Human Feedback (RLHF)

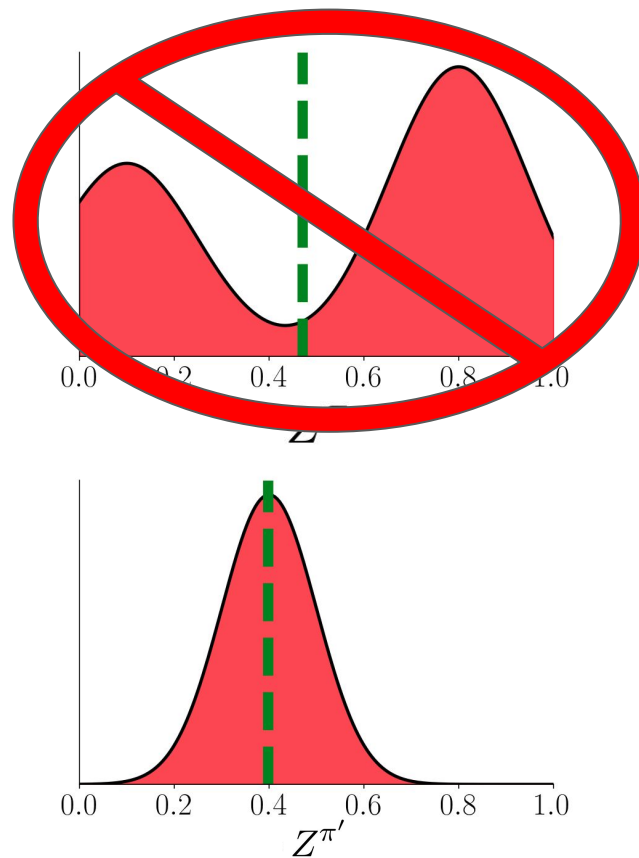
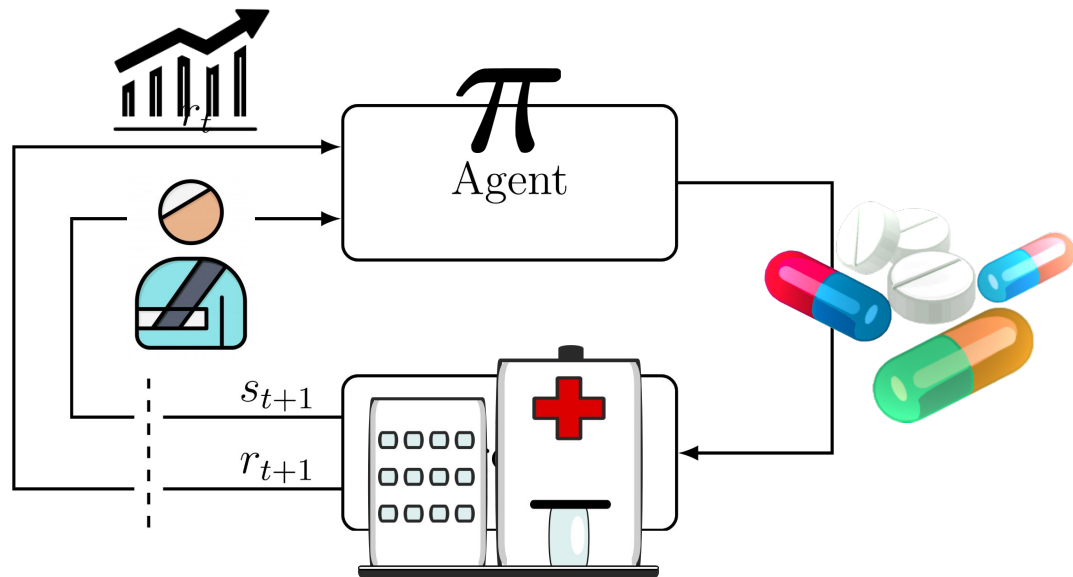
[Ouyang et al., 2022]



Clinical Treatment Design

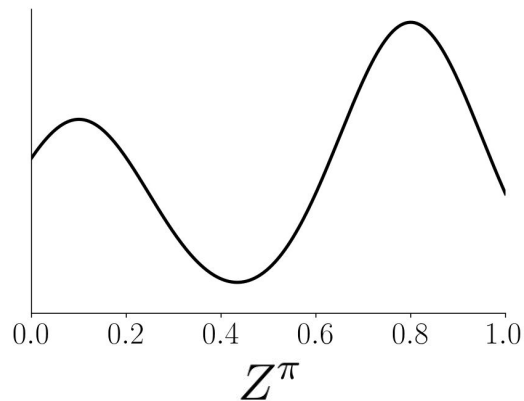


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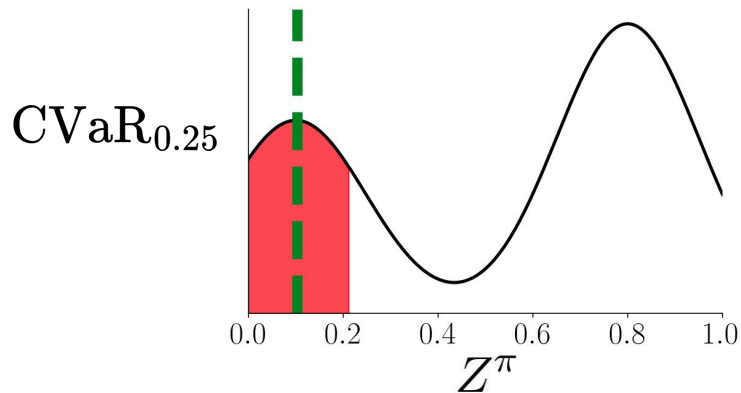
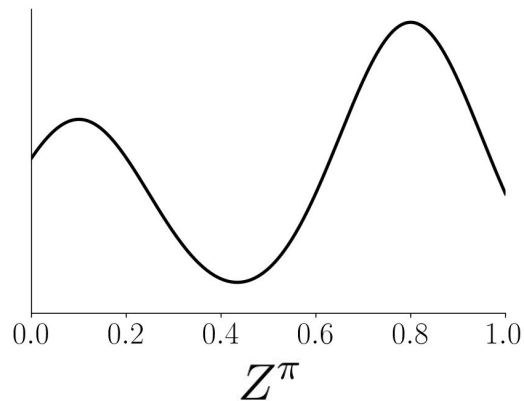
Measuring Risk: Conditional-Value-at-Risk (CVaR)

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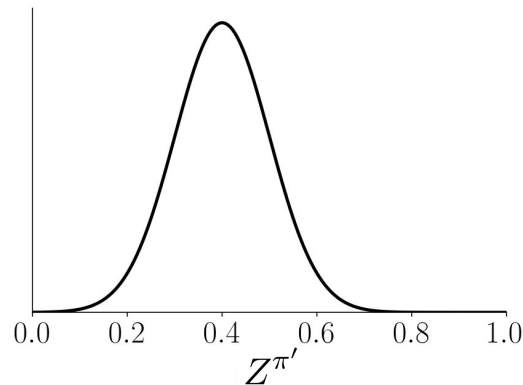
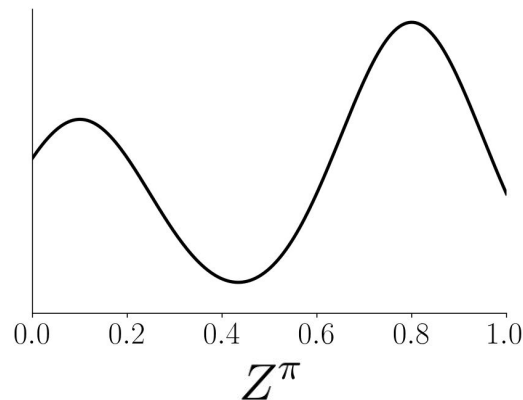
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CVaR RL: Risk-Sensitive Objective

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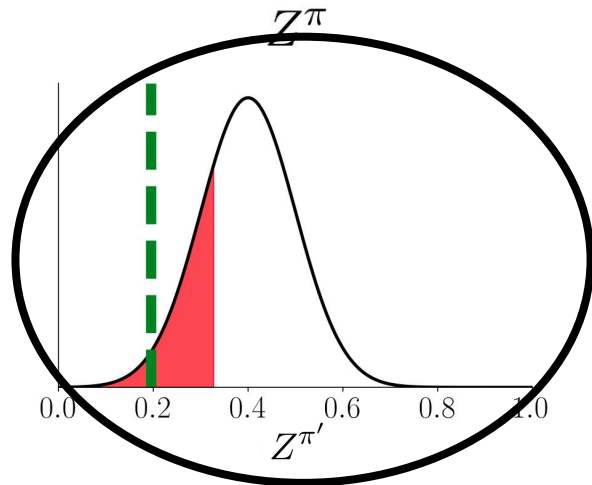
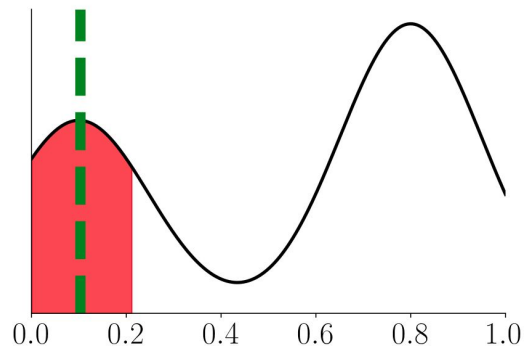
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Why Use CVaR RL for Safe RL?

Other alternatives exist:

- Reward shaping
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- Constrained RL

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Other alternatives exist:

- Reward shaping
- Adversarial training
- Constrained RL

But CVaR RL is:

- Meaning preserving
- More interpretable
- Assumption-free

CVaR: Actually Used in Practice!

[Basel Committee on Banking Supervision, 2019]

3. Quantitative standards

181. Banks will have flexibility in devising the precise nature of their models, but the following minimum standards will apply for the purpose of calculating their **capital charge**. Individual banks or their supervisory authorities will have discretion to apply stricter standards.

- (a) **"Expected shortfall"** must be computed on a daily basis for the bank-wide internal model for regulatory capital purposes. Expected shortfall must also be computed on a daily basis for each trading desk that a bank wishes to include within the scope for the internal model for regulatory capital purposes.
- (b) In calculating the expected shortfall, a **97.5th percentile**, one-tailed confidence level is to be used.

The Million Dollar Question:
What difference does it make to change the
RL objective to CVaR?

Classical RL: The Fundamental Theorem

The classical RL optimization problem

$$\pi^{\star} = \arg \max_{\pi} \mathbb{E}[Z^{\pi}]$$

can be solved by repeatedly applying the *Bellman Optimality Operator*

$$V_{k+1}^{\star}(s) = T[V_k^{\star}](s) = \max_a \left[R(s, a) + \gamma \sum_{s'} P(s' | s, a) V_k^{\star}(s') \right]$$

which can be cast as a Dynamic Programming (DP).

Classical RL: The Fundamental Theorem

Proof components:

1. A Markovian policy is optimal.

$$\exists \pi_m : \boxed{S} \rightarrow \Delta(A) \text{ with } \mathbb{E}[Z^{\pi_m}] = \max_{\pi} \mathbb{E}[Z^{\pi}]$$

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2. A deterministic policy is optimal.

$$\exists \pi_d : S \rightarrow \boxed{A} \text{ with } \mathbb{E}[Z^{\pi_d}] = \max_{\pi} \mathbb{E}[Z^{\pi}]$$

Classical RL: The Fundamental Theorem

3. *Fixed Policy Bellman Operator* performs **Policy Evaluation**.

Define the average discounted returned at state s :

$$V^{\pi}(s) := \mathbb{E} \left[\sum_{t=0}^{\infty} \gamma^t r_t \mid s_0 = s, \pi \right]$$

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and it follows that

$$\|V^\pi - V_k^\pi\|_\infty \leq \gamma^k \|V^\pi - V_0^\pi\|_\infty \quad \lim_{k \rightarrow \infty} V_k^\pi(s) = V^\pi(s)$$

Classical RL: The Fundamental Theorem

4. *Optimality Bellman Operator* finds **optimal policy**.

Define the average discounted returned at state s of the **optimal policy**:

$$V^*(s) := \max_{\pi} \mathbb{E} \left[\sum_{t=0}^{\infty} \gamma^t r_t \mid s_0 = s, \pi \right]$$

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$$\|V^* - V_k^*\|_{\infty} \leq \gamma^k \|V^* - V_0^*\|_{\infty}$$

$$\lim_{k \rightarrow \infty} V_k^*(s) = V^*(s)$$

Classical RL: The Fundamental Theorem

Recap:

1. A deterministic Markovian policy is optimal.
2. *Fixed Policy Bellman Operator* performs **Policy Evaluation**.
3. *Optimality Bellman Operator* finds **optimal policy**.



We can compute optimal policy *efficiently* using DP!

A Fundamental Theorem for CVaR RL?

Can we cast the CVaR RL problem

$$\pi^{\star} = \arg \max_{\pi} \text{CVaR}_{\alpha}[Z^{\pi}]$$

as a Dynamic Program that can be solved efficiently?

A Fundamental Theorem for CVaR RL?

Proof components:

1. A deterministic Markovian policy is optimal.

Classical RL: $\exists \pi_m : S \rightarrow A$ with $\mathbb{E}[Z^{\pi_m}] = \max_{\pi} \mathbb{E}[Z^{\pi}]$

CVaR RL: This does not hold in general! [Artzner et al., 1999]

- Intuition: Are you betting yesterday's profit or today's lunch money?

A Fundamental Theorem for CVaR RL?

Can augment the MDP with enough info to have Markovian optimality!

Two options (based on CVaR reformulations):

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Two options (based on CVaR reformulations):

- [Bäuerle and Ott, 2011]: Leverage *primal* formulation of CVaR
 - Add reward *floor* “c” to state.
 - “c” is **unbounded real**
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- [Chow et al., 2015]: Leverage *dual* formulation of CVaR
 - Add confidence level “y” to state.
 - “y” is **bounded between 0 and 1!**
 - Requires **optimizing dual variables**.

Dual Time Decomposition of CVaR

[Pflug and Pichler, 2016]

CVaR at time t can be decomposed as a function of CVaR at time $t + 1$:

$$\boxed{\text{CVaR}_\alpha \left[\sum_{t=0}^{\infty} \gamma^t r_t \mid s_0 = s, \pi \right]} = R(s, a) + \gamma \min_{\xi \in \Xi_\alpha(P, s, a)} \sum_{s'} P(s' \mid s, a) \xi(s') \boxed{\text{CVaR}_{\alpha \xi(s')} \left[\sum_{t=1}^{\infty} \gamma^{t-1} r_t \mid s_1 = s', \pi \right]}$$
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- Involves an **inner minimization problem** on worst next states

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- Involves an **inner minimization problem** on worst next states
- Dual variables change **next state** and **next confidence level**
- Our interpretation: dual variables are *calibrated* Murphy's Law!
 - Increases likelihood of adverse events

A Fundamental Theorem for CVaR RL?

Can augment the MDP with enough info to have Markovian optimality!

- [Chow et al., 2015]: Leverage *dual* formulation of CVaR

- Add confidence level “y” to state.
- “y” is **bounded between 0 and 1!**
- Requires **optimizing dual variables**.

$$\begin{aligned} a_t &= \pi(s_t, y_t) \\ s_{t+1} &\sim P(\cdot \mid s_t, a_t) \xi(\cdot \mid s_t, a_t, y_t) \\ y_{t+1} &= y_t \xi(s_{t+1} \mid s_t, a_t, y_t) \end{aligned}$$

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$$\underbrace{\text{CVaR}_\alpha \left[\sum_{t=0}^{\infty} \gamma^t r_t \mid s_0 = s, \pi \right]}_{V^\pi(s, \alpha)} = R(s, a) + \gamma \min_{\xi \in \Xi_\alpha(P, s, a)} \sum_{s'} P(s') \xi(s') \underbrace{\text{CVaR}_{\alpha \xi(s')} \left[\sum_{t=1}^{\infty} \gamma^{t-1} r_t \mid s_1 = s', \pi \right]}_{V^\pi(s', \alpha \xi(s'))}$$

We can define

$$\boxed{V_{k+1}^\pi(s, y)} = T^\pi[V_k^\pi](s, y) = R(s, a) + \gamma \min_{\xi \in \Xi_\alpha(P, s, a)} \sum_{s'} P(s') \xi(s') \boxed{V_k^\pi(s', y \xi(s'))}$$

and it follows that

$$\|V^\pi - V_k^\pi\|_\infty \leq \gamma^k \|V^\pi - V_0^\pi\|_\infty \quad \lim_{k \rightarrow \infty} V_k^\pi(s) = V^\pi(s)$$

A Fundamental Theorem for CVaR RL?

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3. *Optimality Bellman Operator* finds **optimal policy**.

Taking the maximum on both sides of CVaR Decomposition gives:

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We want to show that we have

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Only lower bound in general! [Hau et al., 2024]

Impact of Hau et al.'s result

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- The Optimality bellman operator does not hold for dual CVaR:
 - Chow et al. and numerous works building on it are refuted.
 - Convergence does occur, but to an overestimation of the CVaR of the policy found.
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 - Chow et al. and numerous works building on it are refuted.
 - Convergence does occur, but to an overestimation of the CVaR of the policy found.
 - Suboptimality gap can be made arbitrarily large: no quick fix!
- All other properties remain:
 - Optimal policy is deterministic and Markovian on augmented MDP
 - CVaR evaluation can be cast as a Dynamic Program

Our Proposal: CVaR RL as a Game

Consider dual variables to yield an **adversarial** MDP:

- Motivated by antagonist objective (max-min structure)
- When the adversary is optimal for the policy, expected return = CVaR
- Notation abuse: adversary is set of dual variables for all (s, a, y)

Our Proposal: CVaR RL as a Game

Define the expected value of a (policy, adversary) pair:

$$V_{\xi}^{\pi}(s, y) := \mathbb{E} \left[\sum_{t=0}^{\infty} \gamma^t r_t \mid s_0 = s, \pi, \xi \right]$$

Our Proposal: CVaR RL as a Game

Define the expected value of a (policy, adversary) pair:

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We propose to alternate between policy and adversary optimization:

Improve policy

$$\pi_{k+1}(s, y) = \arg \max_a \left[R(s, a) + \gamma \sum_{s'} P(s' \mid s, a) \xi(s' \mid s, a, y) V_{\xi_k}^{\pi_k}(s', y \xi_k(s' \mid s, a, y)) \right]$$

Propagate new policy

$$V_{\xi_k}^{\pi_{k+1}}(s, y) = R(s, \pi_{k+1}(s, y)) + \gamma \sum_{s'} P(s' \mid s, \pi_{k+1}(s, y)) \xi_k(s' \mid s, \pi_{k+1}(s, y), y) V_{\xi_k}^{\pi_{k+1}}(s', y \xi_k(s'))$$

Compute CVaR

$$V_{\xi_{k+1}}^{\pi_{k+1}}(s, y) = R(s, \pi_{k+1}(s, y)) + \gamma \min_{\xi \in \Xi_y(P, s, \pi_{k+1})} \sum_{s'} P(s' \mid s, \pi_{k+1}(s, y)) \xi(s') V_{\xi_{k+1}}^{\pi_{k+1}}(s', y \xi(s'))$$

Compute adversary

$$\xi_{k+1}(s' \mid s, a, y) = \arg \min_{\xi \in \Xi_y(P, s, a)} \sum_{s'} P(s' \mid s, \pi_{k+1}(s, y)) \xi(s') V_{\xi_{k+1}}^{\pi_{k+1}}(s', y \xi(s'))$$

Convergence Analysis: Work In Progress

Intuition: next policy selects best greedy action wrt previous CVaR

- *What can go wrong should be trained on*
- Early empirical results are encouraging

Not being able to rely on simultaneous optimization complicates analysis.

- Hard to quantify if next policy has higher CVaR
- Current idea: try to prove (policy, adversary) pairs converge to equilibrium

Conclusion

The CVaR RL formulation offers an **attractive** pathway to safe RL

Finding a **CVaR** equivalent of the **Fundamental Theorem** still an open question

Proposal: **separately optimizing the policy and adversary as a game** could be a good foundation for CVaR Fundamental Theorem

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