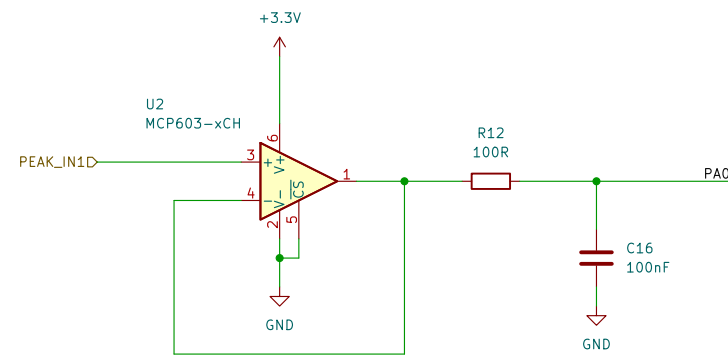
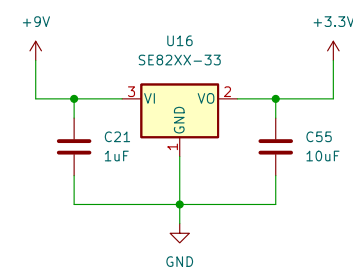


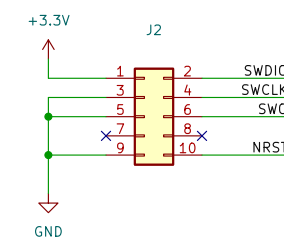
Peak Detector Input Buffer for ADC



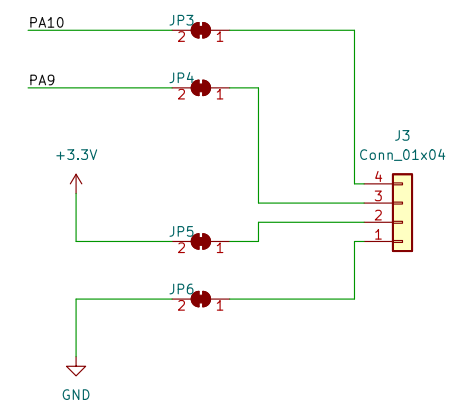
- Dedicated Voltage Regulator



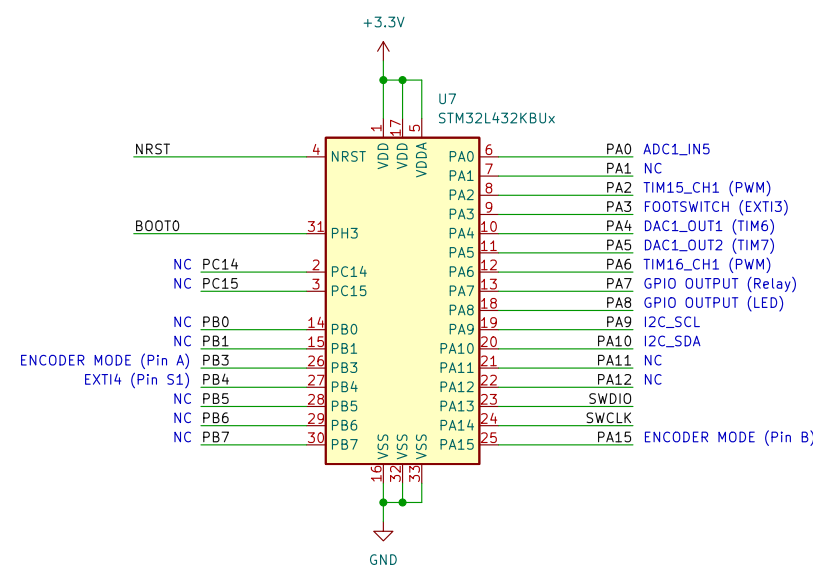
## 10-Pin ARM Programming Header



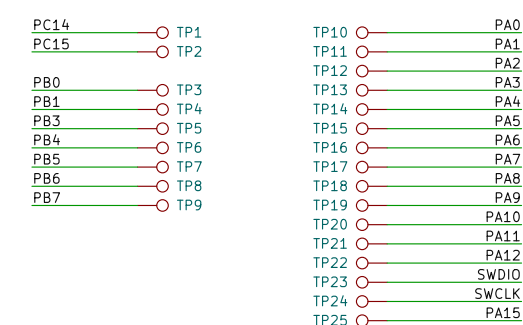
|| OLED Display Connector



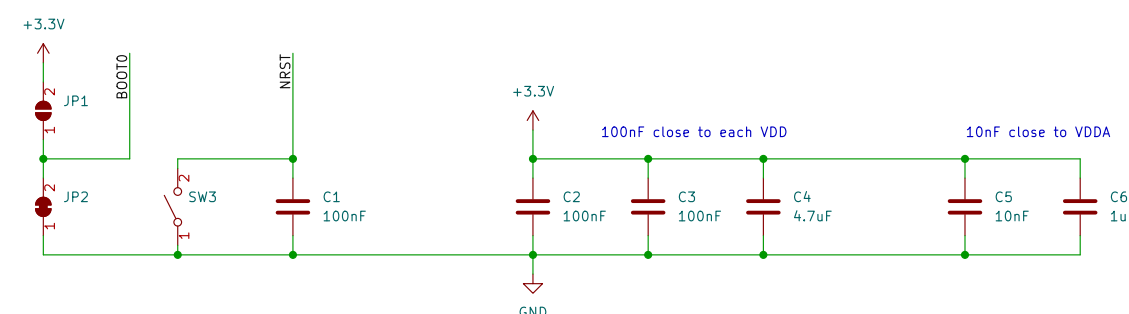
Microcontroller



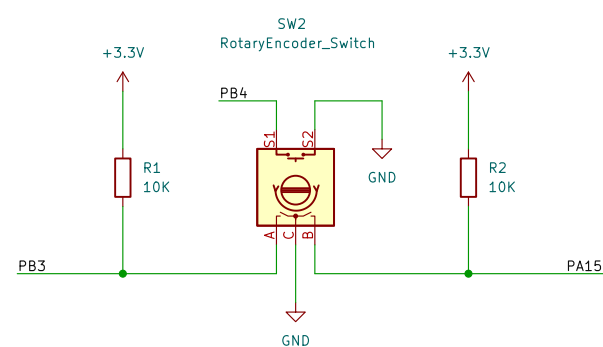
## Testpoints



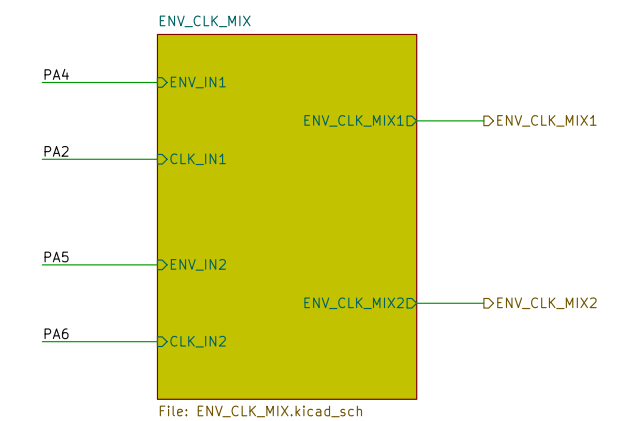
## Decoupling Capacitors



## Rotary Encoder



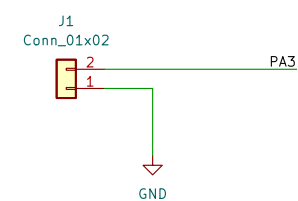
## Envelope/Clock Mixer Output Stage



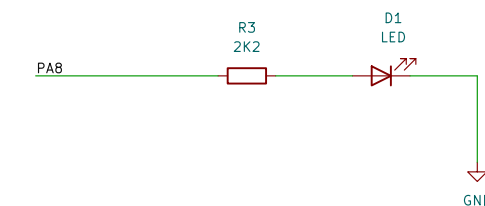
Signal Path Relay



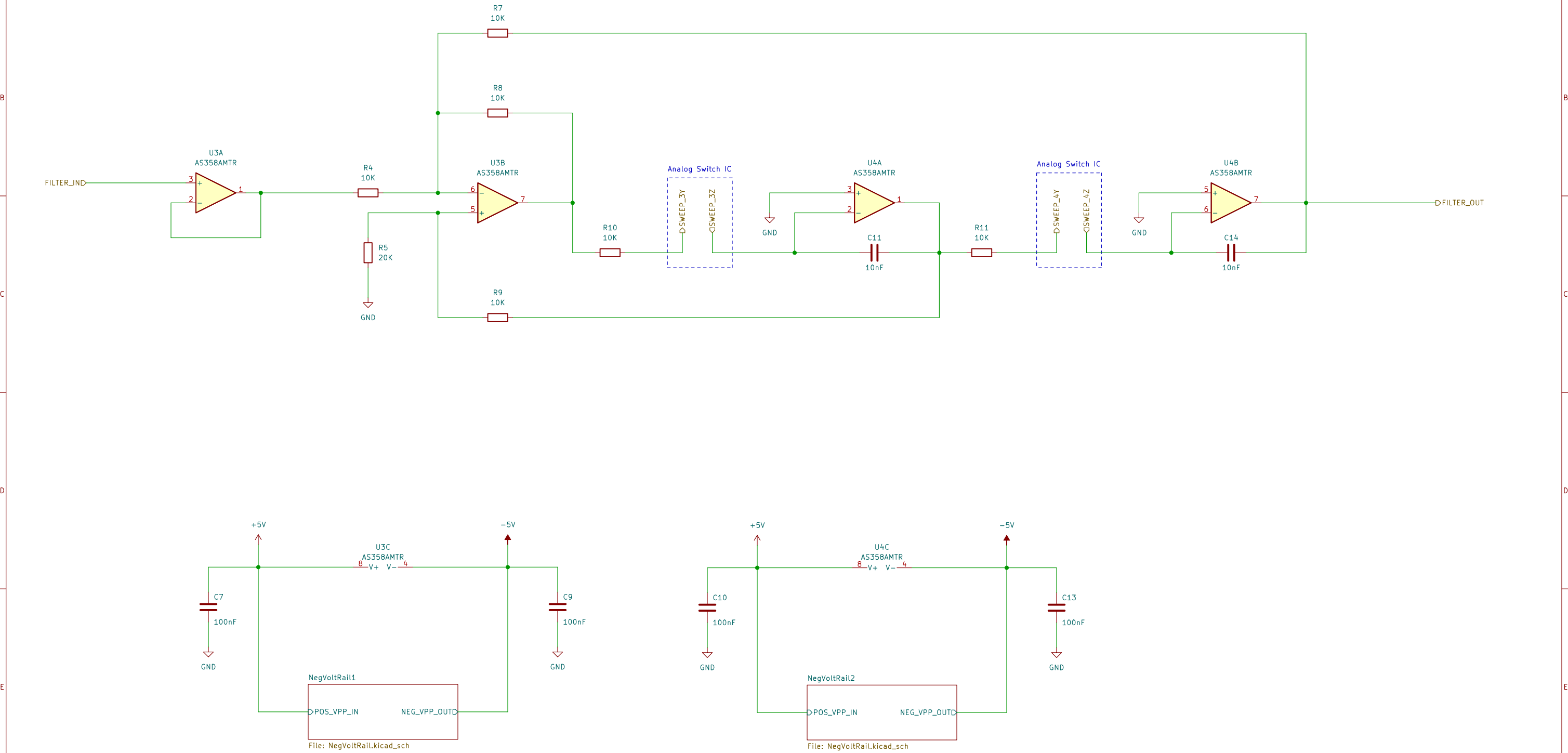
Signal Path Footswitch Connector



Signal Path LED



This is based on a traditional 2nd order, state-variable filter.  
More information can be found here: <https://sound-au.com/articles/state-variable.htm>



This is an experimental "bit crusher" circuit. The signal is switched on/off at high frequency using the analog switch IC. This will reduce the resolution of the input signal in the time domain (as opposed to the normal bit crushing effect of reducing the amplitude resolution)

The addition of capacitors after the analog switch IC, allows the block to function as a kind of Sample and Hold circuit. This should cause a smoothing effect on the output signal, which may or may not be desirable.

#### Capacitor Position:

Only one capacitor should be used, with the other footprint bridged. When using the lower capacitor, droop rate (during hold mode) will be directly related by the input voltage. When using the upper capacitor, the capacitor is connected to opamp virtual ground and the droop rate is constant. This is the recommended option.

#### Feedback Loop:

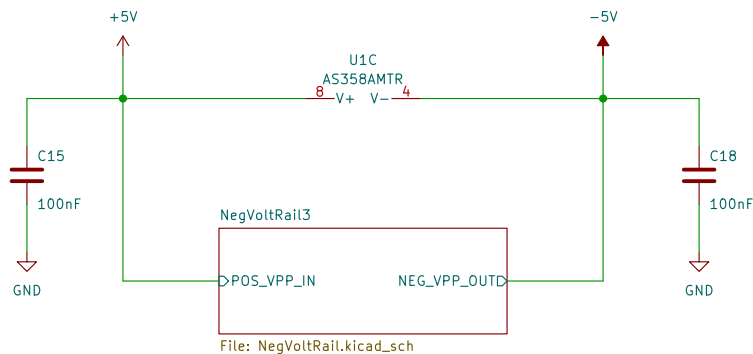
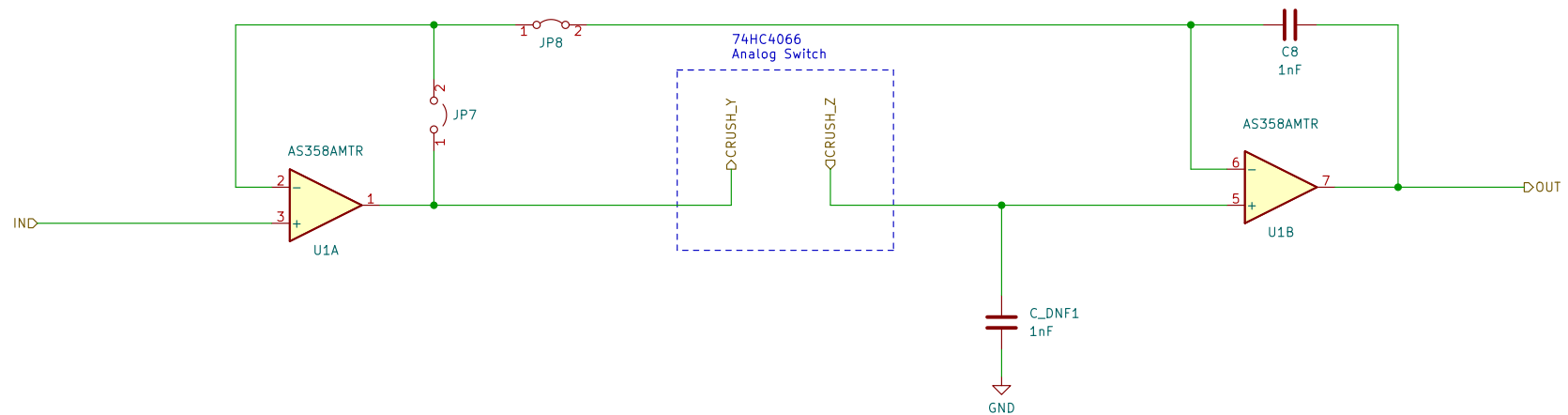
"The feedback significantly improves the accuracy of the S/H relative to the open-loop configuration, although the speed is somewhat less". Closed Loop is recommended option.

#### Capacitor Value:

"The acquisition time can be reduced by choosing a smaller hold capacitance; however, this will increase the hold step and droop rate." Default to 1nF but try other values: 1pF, 100nF, 1uF.

<https://www.ti.com/lit/an/snoa223/snoa223.pdf>

DNF if using other cap. Bridge the pins.



Sheet: /InputBuffer/  
File: Buffer.kicad\_sch

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Size: A4

Date:

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#### Feedback Loop:

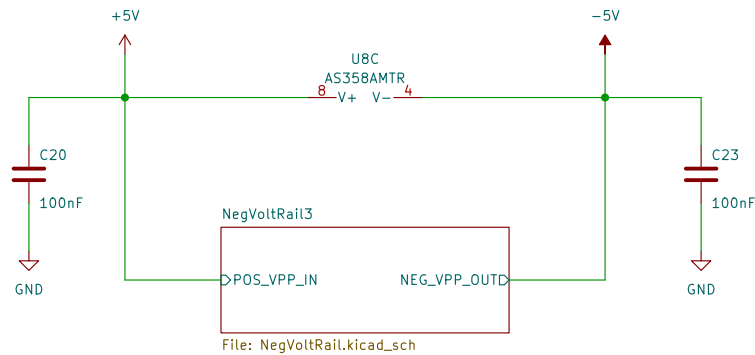
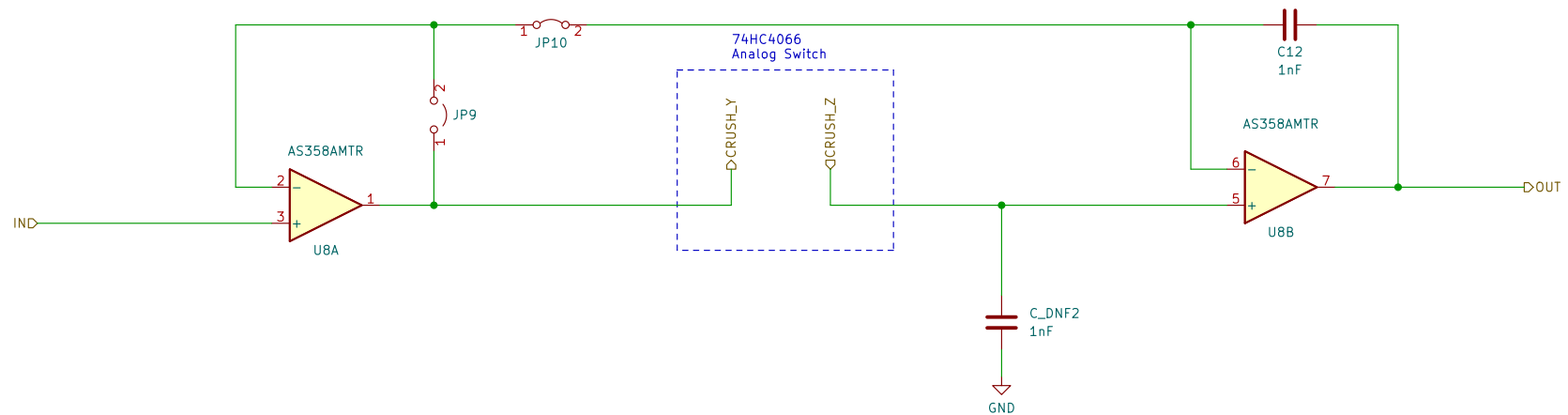
"The feedback significantly improves the accuracy of the S/H relative to the open-loop configuration, although the speed is somewhat less". Closed Loop is recommended option.

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<https://www.ti.com/lit/an/snoa223/snoa223.pdf>

DNF if using other cap. Bridge the pins.



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#### Title:

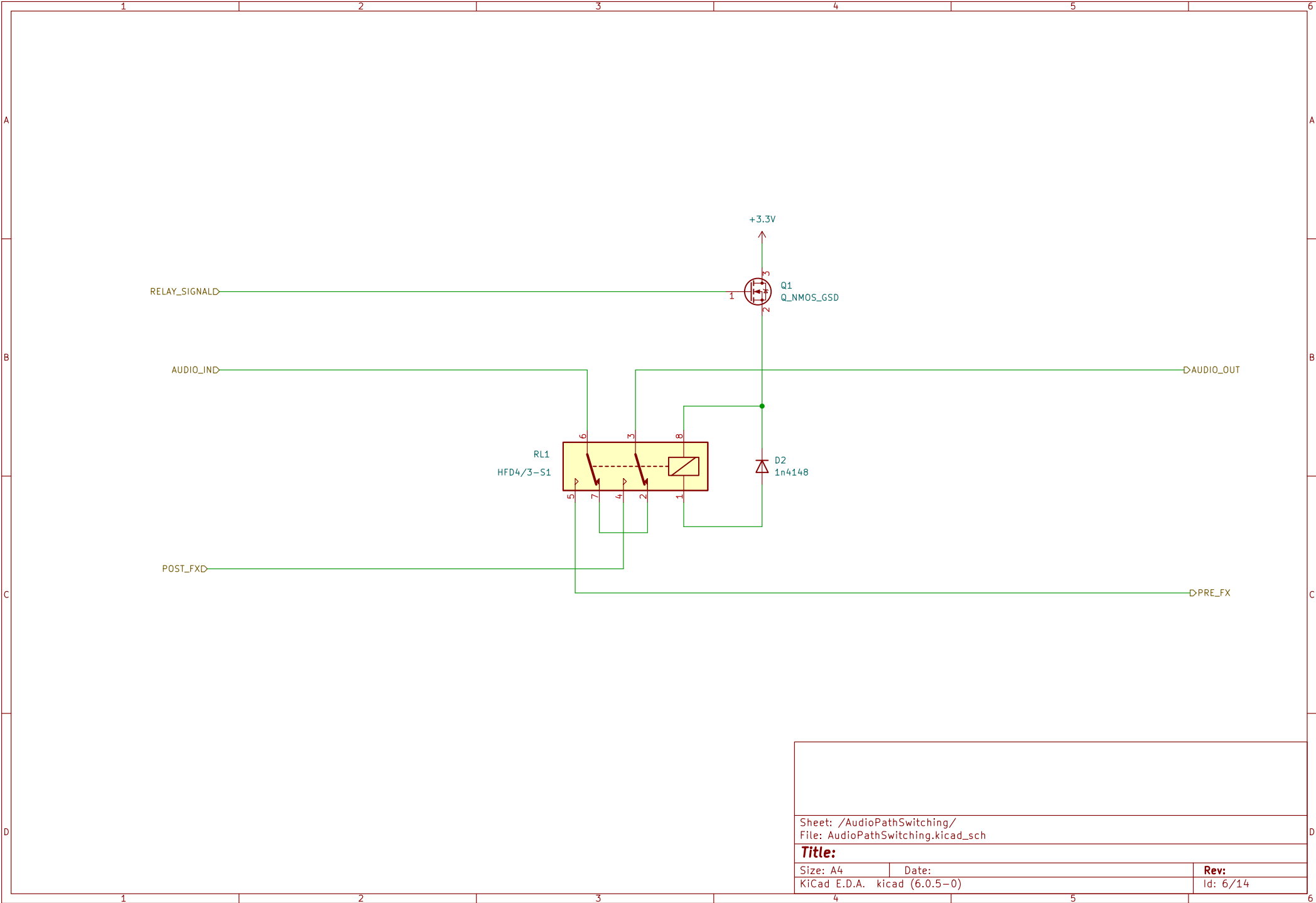
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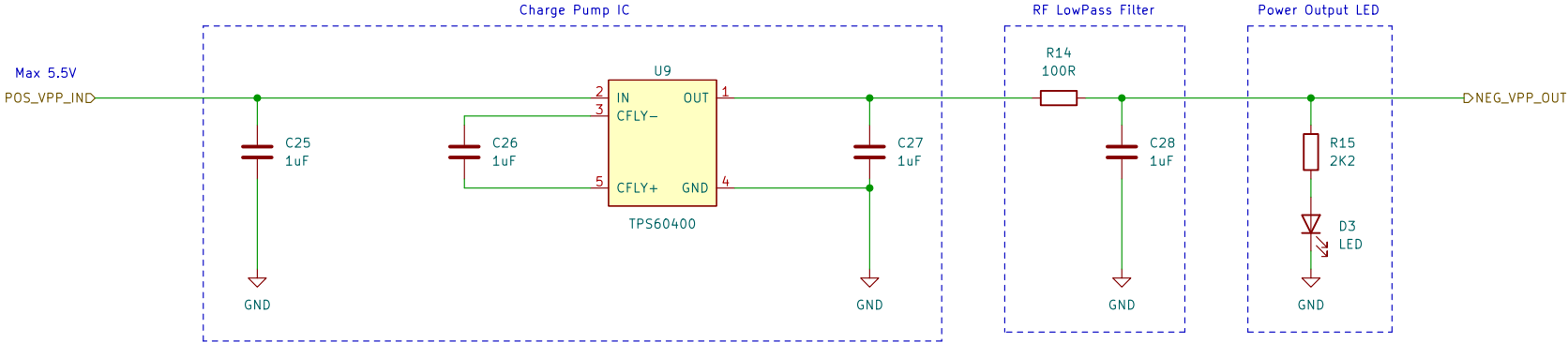
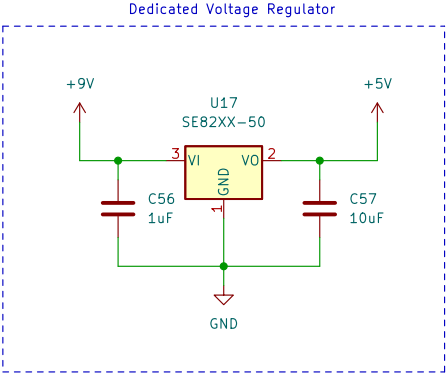
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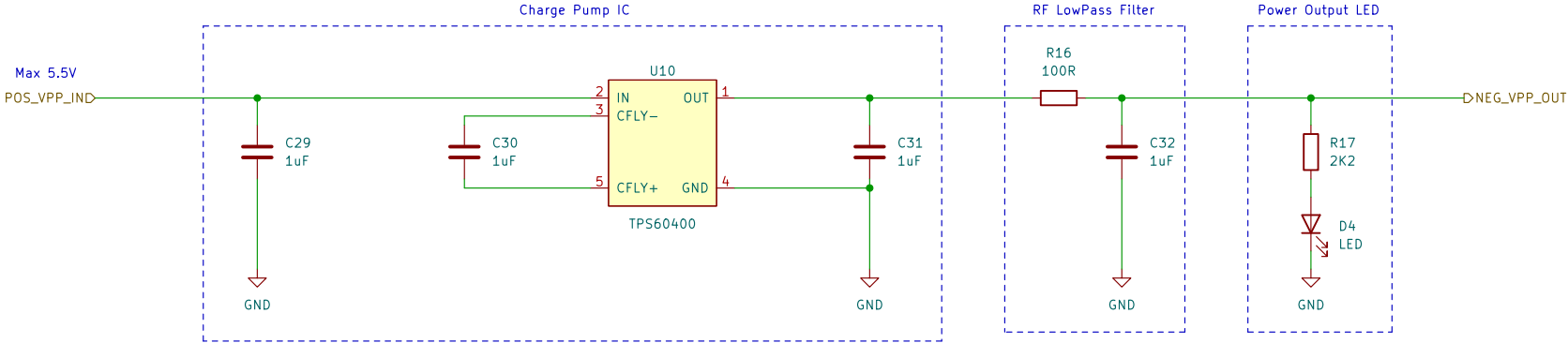
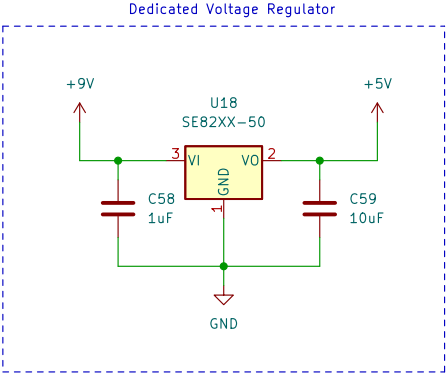
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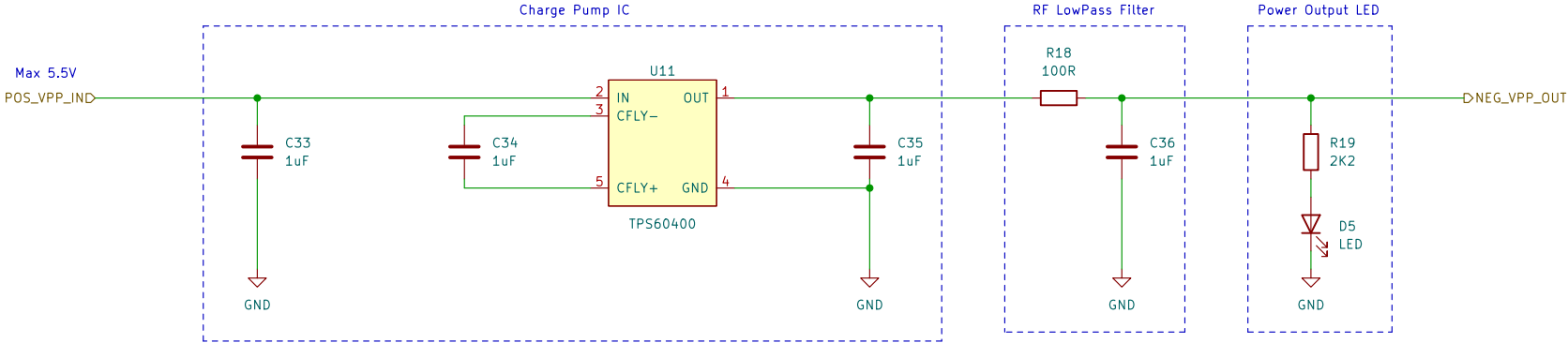
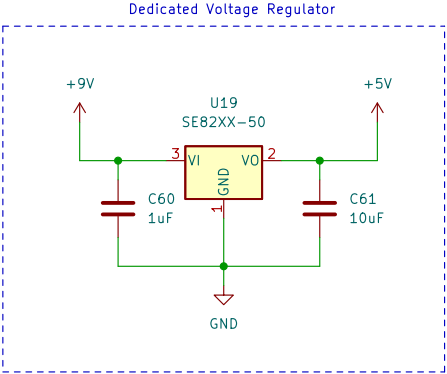
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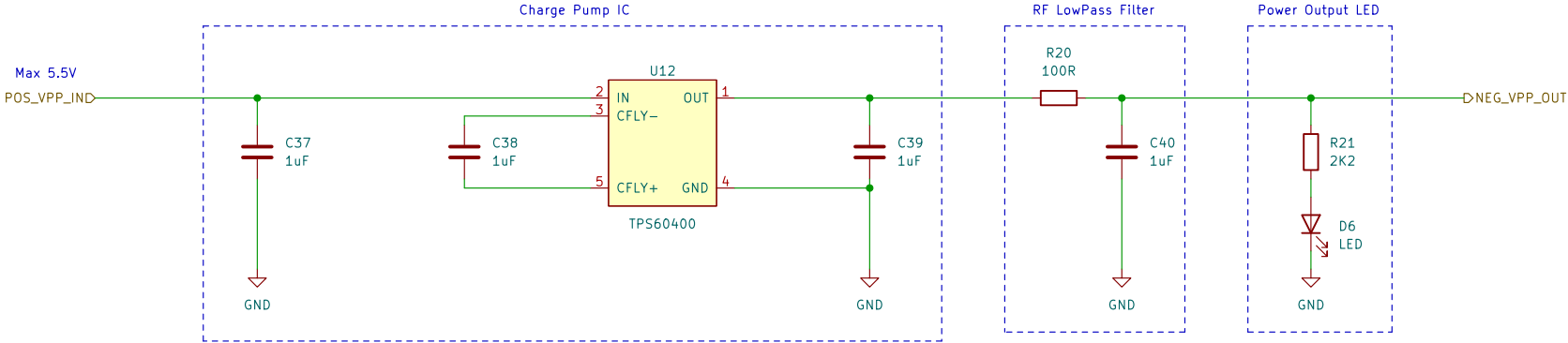
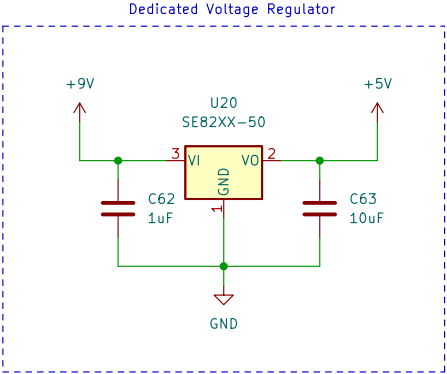
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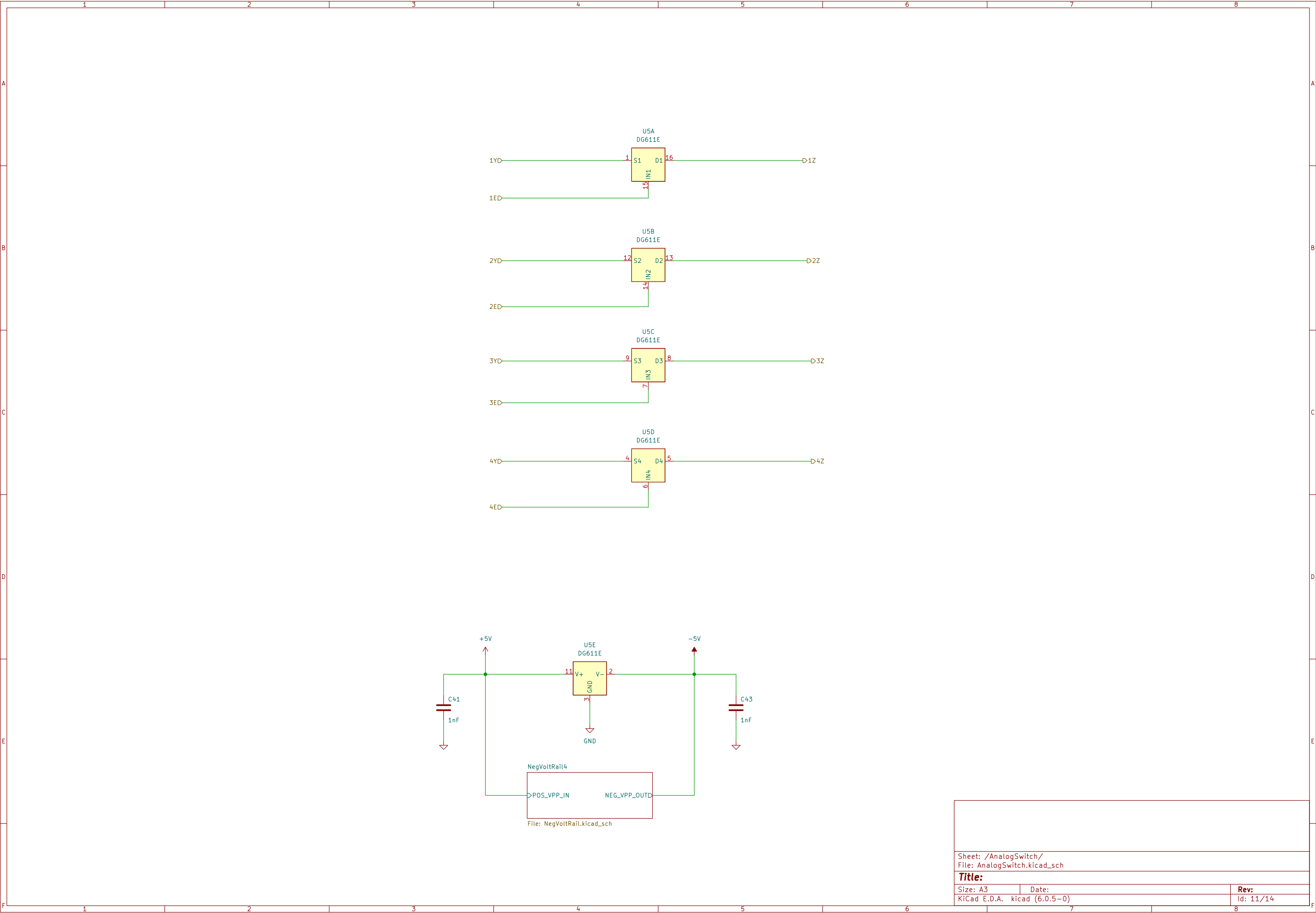
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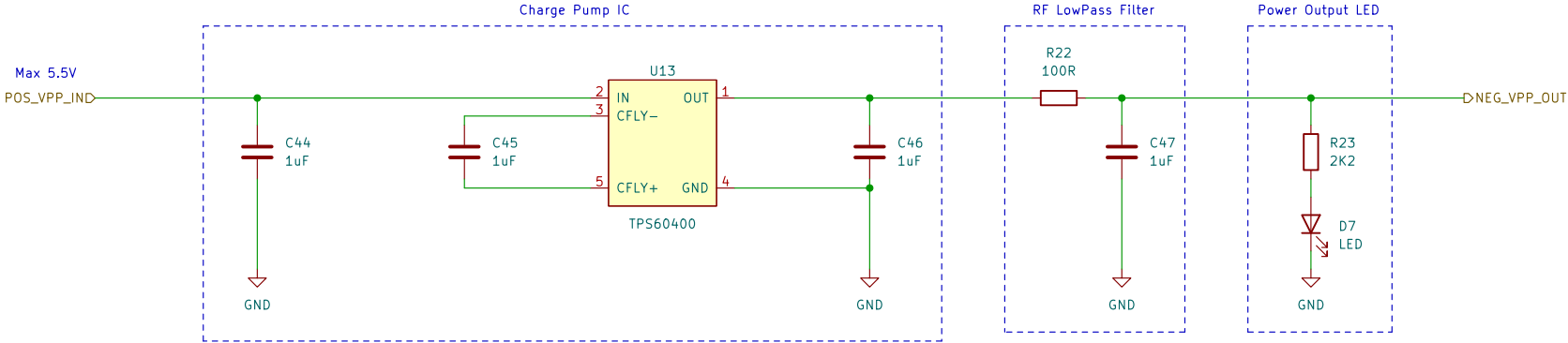
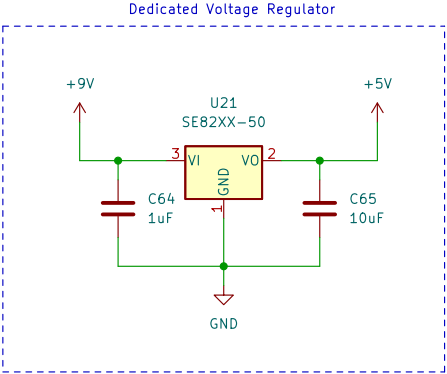
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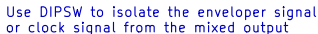
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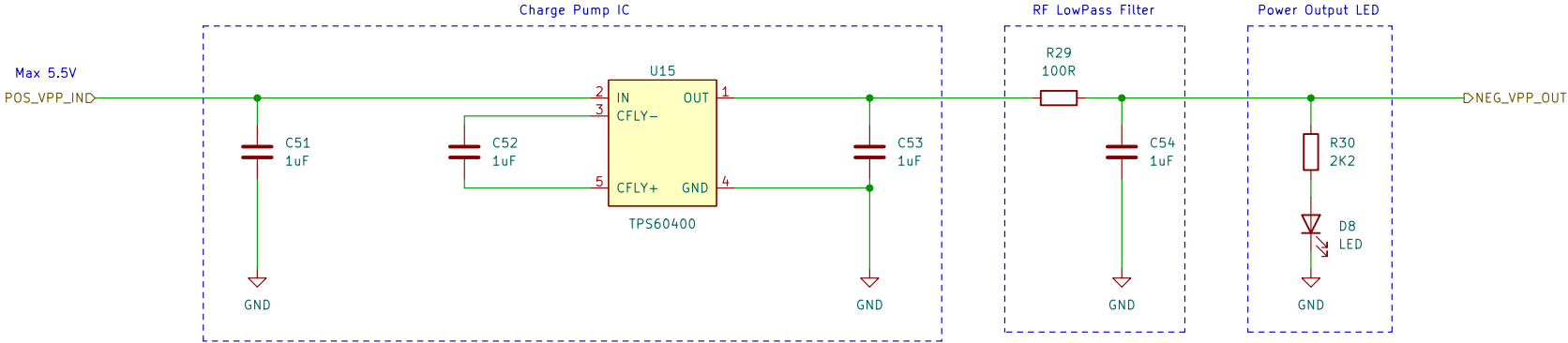
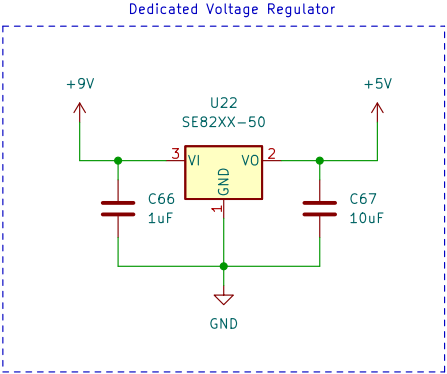






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